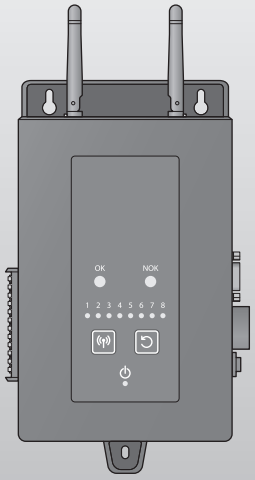
Panasonic

使用说明书
装配控制器

型 号
EYFRW2



重要信息
使用本产品之前,请先详细阅读说明书,并妥加保管,以便日后使用。
请在购买国以外控制使用无线功能。
否则会与各国的法令及规定等发生冲突。

原版说明书:英文
原版说明书译本:其他语言

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使用时

本产品的设置中使用Web浏览器。
请准备支持以下内容的计算机。

运行环境

支持操作系统	Windows 10以上（支持以下浏览器的操作系统）
Web浏览器	Microsoft Edge版本102以上 或Google Chrome版本102以上

- 部分计算机即使满足运行环境也无法使用。
- 根据所用计算机的使用环境不同，本书的说明内容、画面和实际的内容、画面或有差异，敬请谅解。
- 本书的内容如有更改，恕不另行通知。
- 禁止擅自转载本书内容的部分或全部。
- 本书中使用的插图为示意图。

【要求】
请始终更新为最新的固件后再使用。
最新固件数据可从以下使用说明书所载的网站进行确认。
关于固件更新方法，请参见“更新固件”。
参见P95

使用说明书的获取方法

本产品的最新版使用说明书及相关资料请从以下网站下载。

https://panasonic.net/electricworks/ecm/powerelctrictools/download/

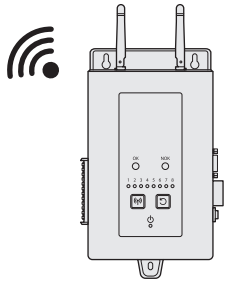
商标

- Microsoft及Windows是美国Microsoft Corporation在美国及其他国家的注册商标或商标。
- 根据Microsoft Corporation的指南使用画面照片。

其他记载的各种名称、公司名称、产品名称等为各公司的商标或注册商标。另外，本文中部分™、®未注明。

本产品

本产品是利用工具和无线进行通信的控制器。
可以接收工具的紧固履历数据或控制工具设置及紧固数量。



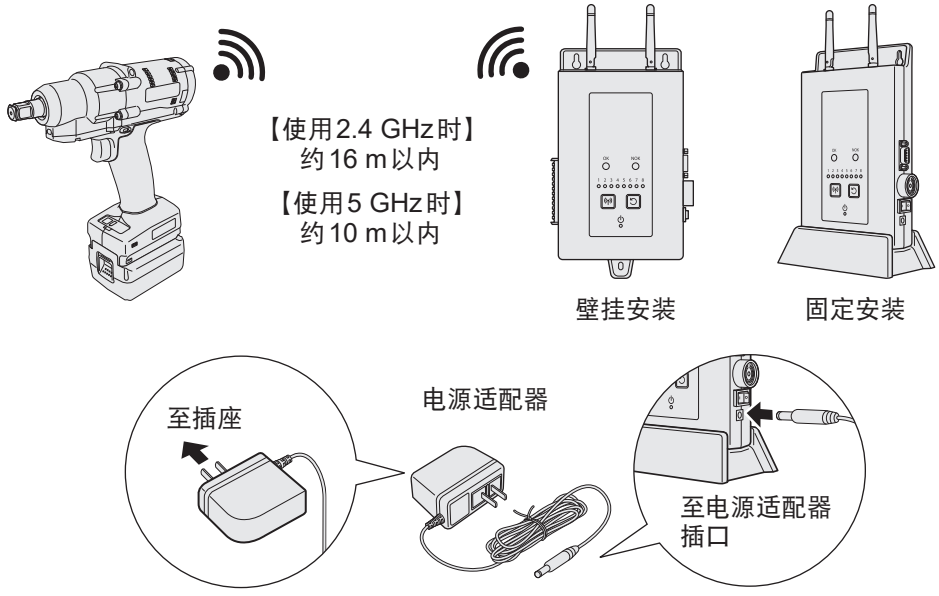
01 最多连接8台工具

02 支持2.4 GHz/5 GHz段

03 紧固控制、履历保存功能

操作

安装在可与工具进行无线通信的范围内使用。
通过AC插座接通电源，并在需要时，利用各类通信IF与外部设备连接。



例：WEYFRW1K7951

- 本产品内置有纽扣电池，用以维持时钟功能（RTC）。
  建议始终打开电源，以控制内置纽扣电池的消耗。
- 无线通信距离因环境而异。

为了防止对人的危害和财产的损害,请必须遵守说明事项。

■针对错误使用时产生的危害和损害程度进行区分并说明。

⚠警告	可能造成死亡或重伤的内容。
⚠注意	可能造成轻伤或发生财产损害危险的内容。

■使用以下图片符号表示必须遵守的内容。(以下是图片符号的示例)

	绝对禁止的内容。
	必须执行的内容。

⚠警告

 必须遵守	● **确认安装位置是否有电线管、自来水管及煤气管等埋设管线。** 一旦接触埋设物可能会导致触电、漏电、煤气泄漏等事故。
	● **确保电源插头插入插座。** 插入不到位,可能引起触电或因发热引起火灾的危险。 请勿使用损坏的插头或松动的插座。
	● **定期清理电源插头上的灰尘等。** 插头上积满灰尘等,可能因湿气等引起绝缘不良,进而引起火灾。 请拔出插头,用干燥的布擦拭插头。
	● **使用指定的电源线。** 如不遵守,会导致触电、短路、火灾。
	● **作业场所需足够明亮。** 因昏暗导致的视线不佳可能引起事故或受伤。

⚠警告

 禁止	● **不得使用超过额定值或交流电100 V-240 V以外的插座或接线器具。** 多脚布线等会超出额定值,导致发热引发火灾。
	● **不得损坏电源线和插头。(不可有损伤、破损、加工、靠近热器具、强行弯曲、强拧、拉伸、放置重物、夹入、捆扎等)** 如果在损伤状态下使用,会造成触电˙短路˙火灾。 请定期检查电线和插头,如有损坏,请立即咨询销售店。
	● **请勿在直流电源及引擎发电机、变压器上使用控制器。** ● **请勿在有可燃性液体或气体的场所使用。** 否则可能会出现发热、冒烟、起火、破裂。
	● **请勿将控制器安装在水泥砂浆墙壁上。** 用螺丝固定时,如有漏电,可能会使水泥砂浆内的板条网发热,导致起火。
	● **不用时,请将电源插头从插座上拔出。** 如果不遵守,有可能因绝缘劣化而导致触电或漏电火灾。
 禁止分解	● **不可改造产品。不可进行拆解或修理。** 有引起火灾、触电或受伤的危险。 修理请咨询购买的销售店或本公司的服务窗口。
 禁止浸水	**请不要对充电工具做以下操作。** ● **不可在雨淋或潮湿的地方使用或放置。** ● **不可浸水使用。** 有冒烟、起火、破裂的危险。
 禁止湿手	● **请勿用湿手将电源插头从插座上拔出。** 有触电的危险。

⚠注意

禁止

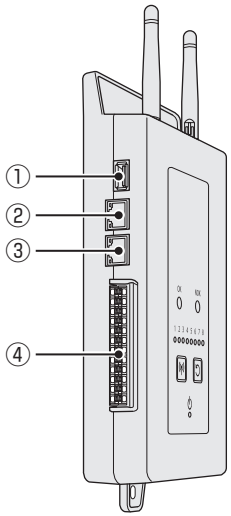
- **请勿用于非指定用途。**
  否则可能会造成人员受伤。
- **不要放在儿童够得着的地方。**
  有造成事故或故障的危险。
- **控制器中沾有油等异物时，请勿使用。**
  如果油等异物进入内部，可能会导致发热、起火、破裂。
- **请勿将本体保存在45 ℃以上环境中。**
  有动作异常的危险。
- **请勿采用不合理的姿势工作。**
  可能因摔倒而受伤。
  始终注意脚下，保持身体平衡。
- **疲惫状态下不要使用。**
  有可能发生事故或受伤。
- **请勿让儿童等非作业人员靠近车间或触碰控制器。**
  有受伤的危险。
- **控制器只可用于适用机型。**
  否则会因误运转而引发事故。

必须遵守

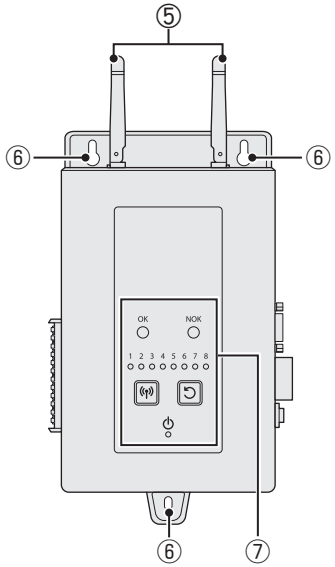
- **壁挂安装控制器时，要用螺丝固定牢固，防止掉落。**
  否则可能会因掉落而导致人员受伤。
- **拔下电源插头时，请勿握住电源线，必须拿着电源插头拔出。**
  握住电线拔出的话，可能导致触电和短路。
- **使用前，请确认控制器及其他零件有无损伤，是否能正常运转。**
  如不遵守，可能会因破损等而造成人员受伤。
- **保持工作场所的干净。**
  散乱的场所和工作台是事故引发的原因。
- **注意操作和作业方法、周围的状况等，运用常识进行作业。**
  如果不按规定操作，可能会发生事故或受伤。

主 体

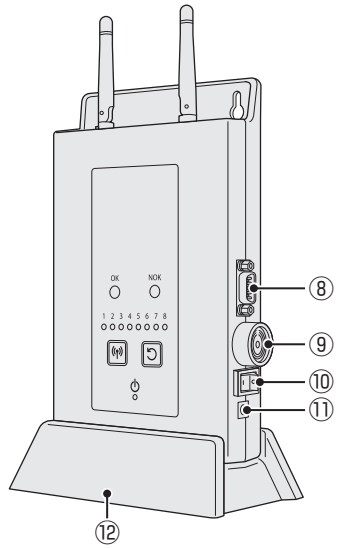
■左侧面



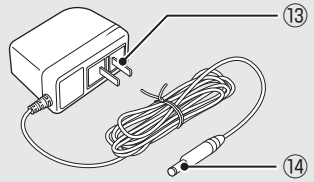
■正面



■右侧面



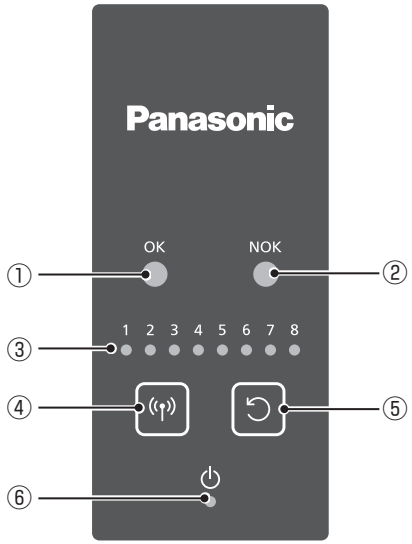
■电源适配器



①	USB端口（USB-A）
②	Ethernet端口（维护用）
③	Ethernet端口（网络用）
④	1～24 I/O端口
⑤	分集天线
⑥	壁挂孔
⑦	控制面板

⑧	串行端口（RS232C）
⑨	蜂鸣器
⑩	电源开关
⑪	电源适配器插口
⑫	控制器支架
⑬	电源插头
⑭	电源端子

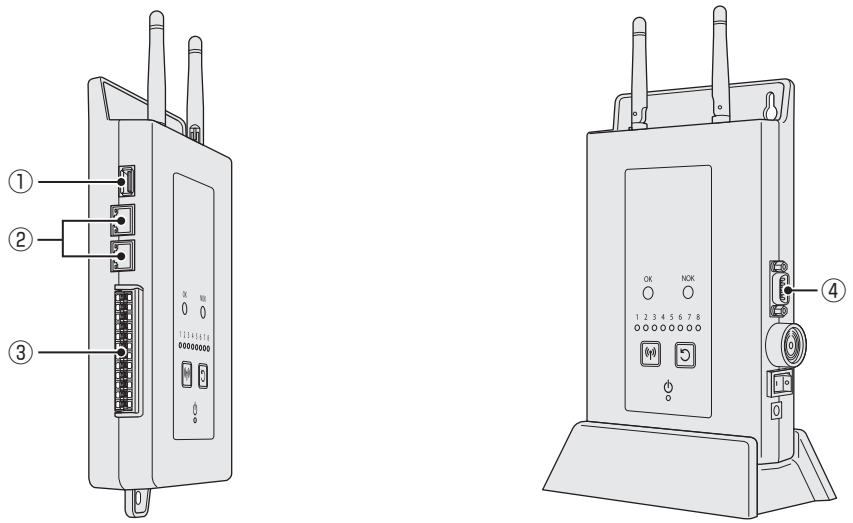
■控制面板



①	紧固OK指示灯 绿灯闪烁：接收条形码读取信息 亮绿灯：接收紧固OK信号 熄灭：未接收紧固OK信号
②	紧固NOK指示灯 亮红灯：接收紧固NOK信号 熄灭：未接收紧固NOK信号
③	通信指示灯（No.1～No.8） 亮蓝灯：工具已注册 蓝灯闪烁：工具注册中或通信范围外 熄灭：工具未注册

④	配对键
⑤	复位键
⑥	电源指示灯 亮黄灯：电源ON（接收模式） 熄灭：电源OFF 黄灯闪烁：发生错误

■通信接口

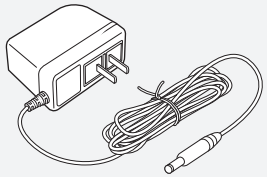


接口		详情
①	USB	使用USB存储器更新固件时使用。 ※ 仅限直接连接USB存储器（不可延长）
②	Ethernet （维护用/网络用）	用于连接无线接收器，通过无线接收器连接条形码阅读器。 ※ 仅可使用无线式条形码阅读器。 • USB2.0　USB-A×1
③	输入输出端子（I/O）	用于连接设备（PLC等）。 ※ Ethernet端口（维护用）请和设置用计算机直接连接。（不使用HUB） • 10Base-T/100Base-TX×2 • 电缆长度30 m以下
④	串口（RS232C）	用于和外部设备（PLC等）连接。 • 输入8点 输出8点 • 电缆长度10 m以下 • 输入端子额定值：DC24 V　50 mA • 输出端子额定值：DC30 V　3 A • RS232C×1 • 电缆长度10 m以下

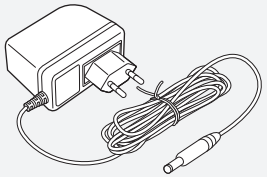
附 带 品

■**电源适配器 ×1**

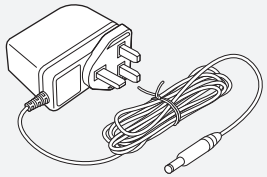
[中国大陆]
（WEYFRW1K7951）



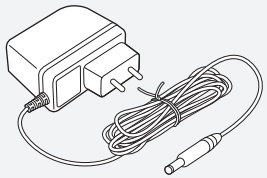
[仅韩国适用]
(WEYFRW1K7051)



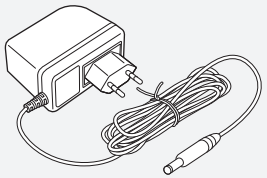
[仅马来西亚适用]
(WEYFRW1K7851)



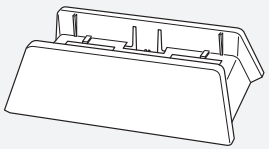
[仅印度适用]
(WEYFRW1K7151)



[仅泰国/印度尼西亚适用]
(WEYFRW1K7751)



■**控制器支架 ×1**
（EYFRW1F7001）

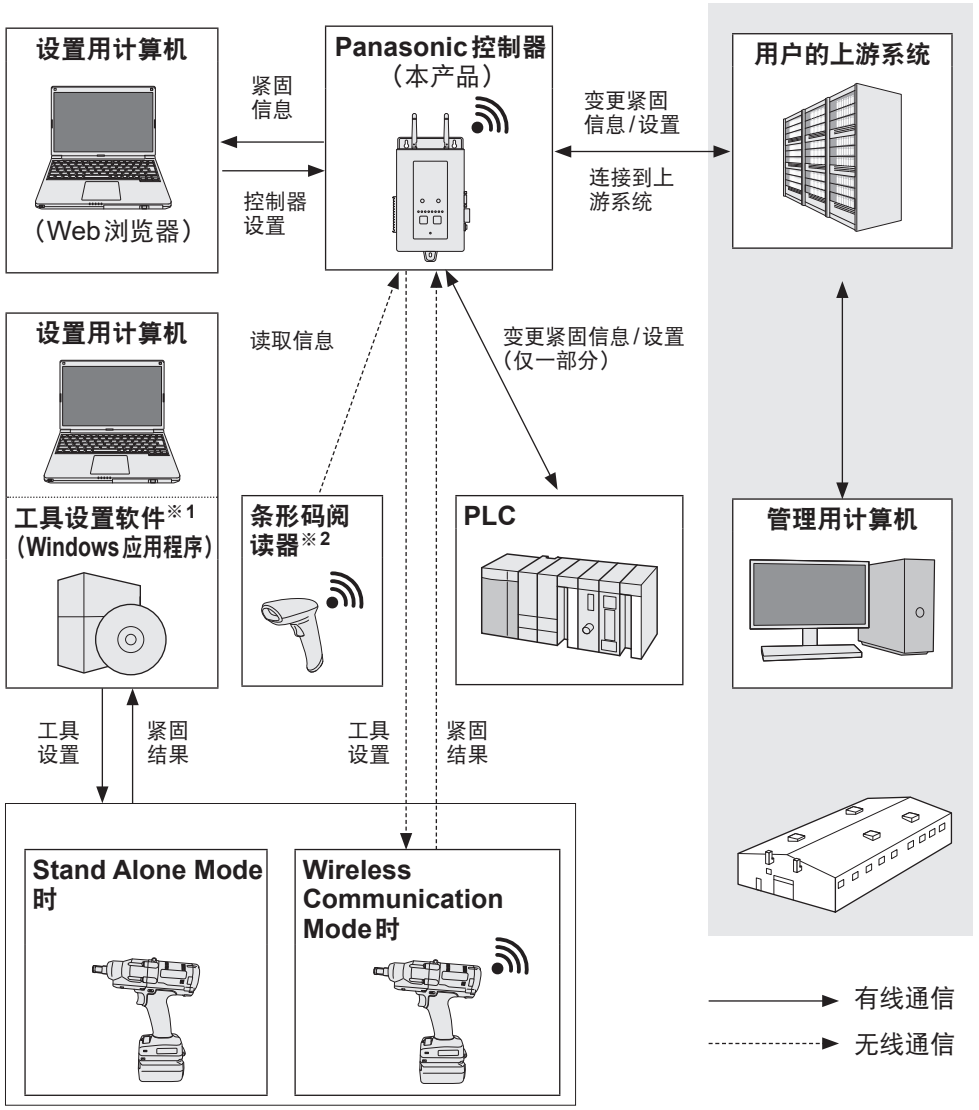


消 耗 品

■**纽扣电池**（CR2450）**×1**
关于更换方法，请参见“更换纽扣电池”。
参见P96



系统相关图

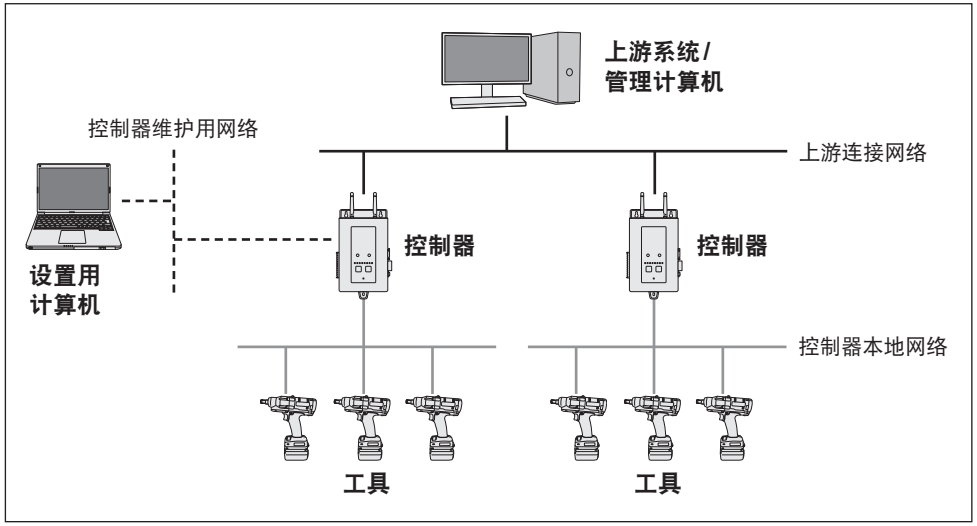


※1“工具设置软件”请从本公司网页下载。 **参见P2**
※2 仅支持固件版本2.03.00以上。

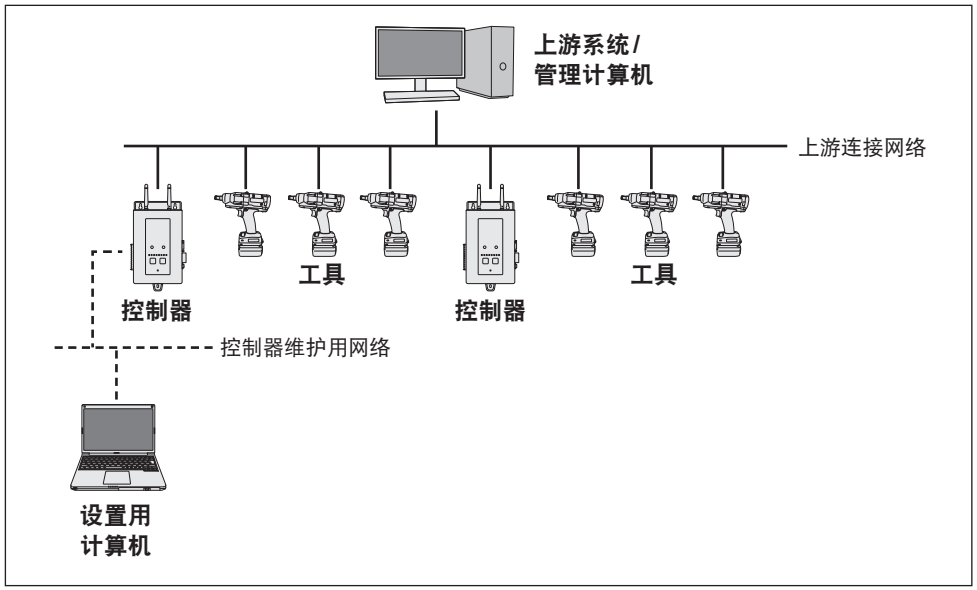
网络构成模式

可在以下4种模式下使用。

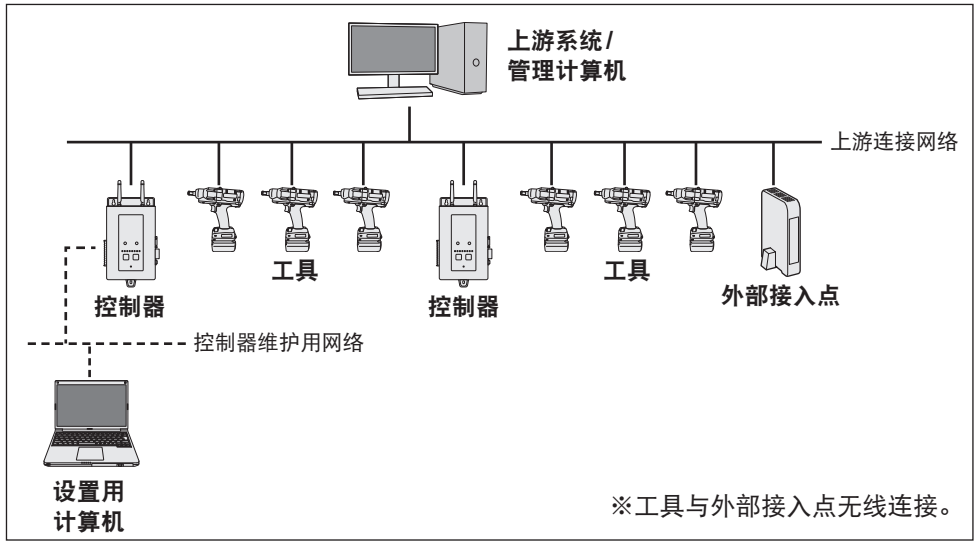
■不管理工具的IP地址
※自动分配（使用控制器内置接入点）



■管理工具的IP地址（使用控制器内置接入点）

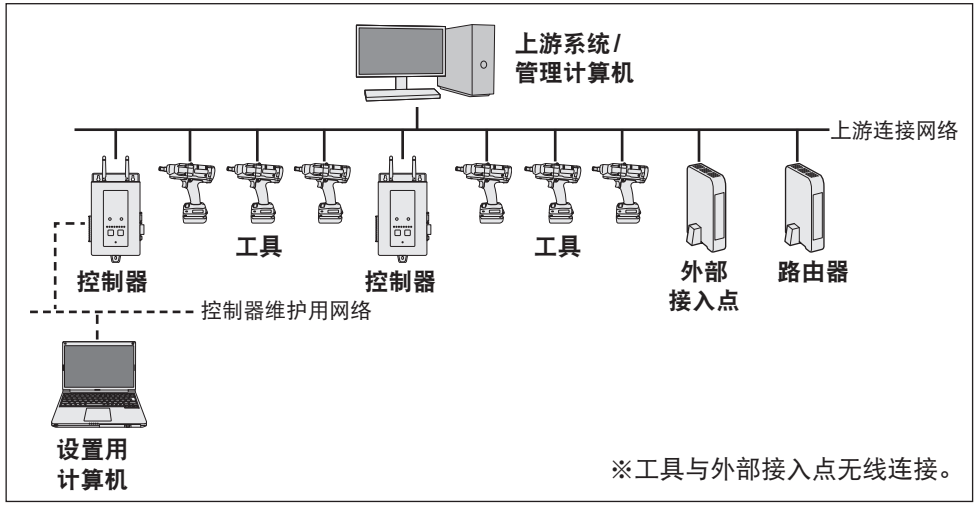


■管理工具的IP地址（使用外部接入点）



※ 本系统请在本地网络环境（无联网）中使用。
※ 在实际开始使用之前，请务必确认控制器的网络用IP地址设置。（需要时请更改默认值）

■不管理工具的IP地址
※自动分配（从上游连接网络内的DHCP服务器）



※ 可能会因网络的防火墙设置而无法使用。
请事先确认。

关于控制器和工具本体的固件版本

关于兼容性

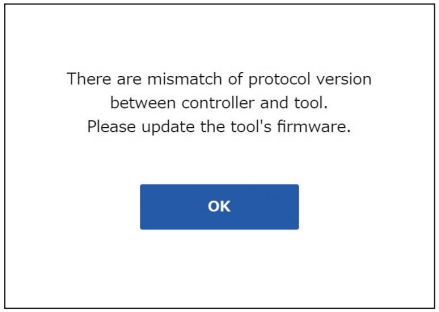
要实现部分网络构成模式，需要将固件更新到最新版本，具体如下所示。
请在确认以下兼容性表后，根据需要进行更新。参见 P95

控制器固件	工具本体固件
Ver2.04.00 以上	Ver2.04.00 以上
Ver2.00.00～2.03.00	Ver2.00.00 以上

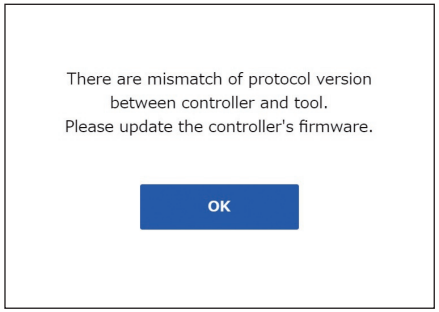
版本不一致时的显示

如果将不能确保上述兼容性的工具配对注册到控制器，会显示如下警告。

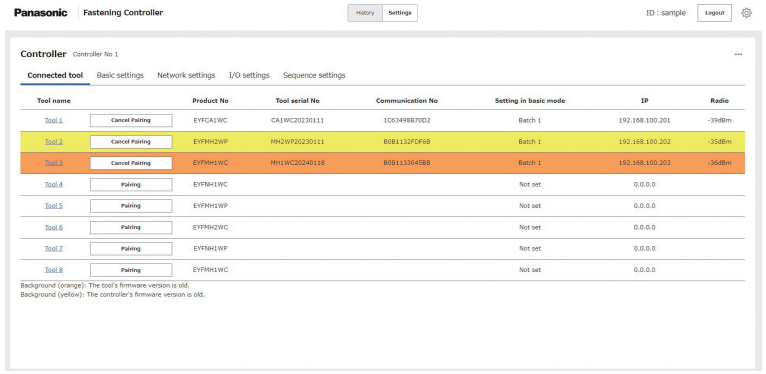
工具的固件版本较低时



控制器的固件版本较低时



橙色背景：工具固件版本较低的状态
黄色背景显示：控制器固件版本较低的状态



连接对象工具　型号一览

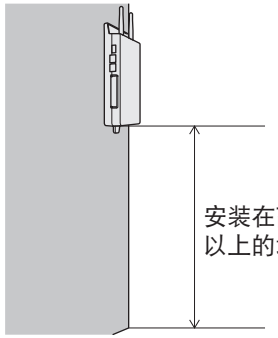
可注册型号	EYFMH1WC、EYFMH2WC EYFNH1WC ※1、EYFCA1WC※2

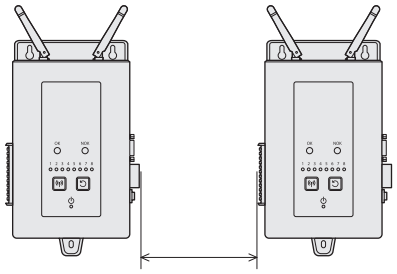
※1 仅支持固件版本2.02.00以上。
※2 仅支持固件版本2.04.00以上。
• 请参阅最新总目录。

安装注意事项

控制器请安装在高度80 cm以上的场所。另外，如有多个控制器相邻，请在安装时至少距离10 cm以上。（建议1 m以上）
安装控制器的天线时，要确保天线周围没有障碍物。
控制器采用分集天线型，有2根天线，在安装时请确保2根天线的周边均没有障碍物。

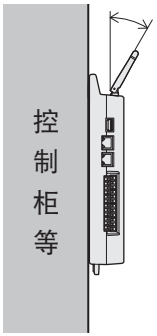
⚠注意
为了保证安装时的安全，请使用公称直径3.5 mm～4.1 mm的木螺钉。



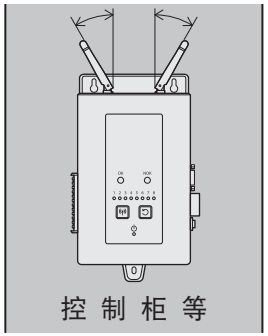

安装多台控制器时，安装时请距离
10 cm以上

通信不稳定时，请调整天线角度。
※安装在金属盘内时，调整天线角度可能会使通信稳定。

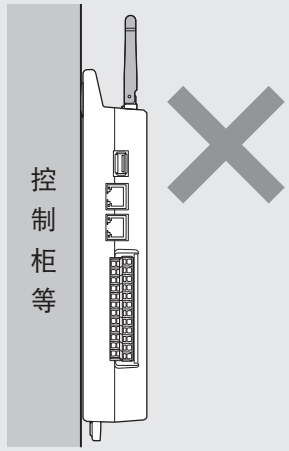
安装时，前倾30～45°
左右



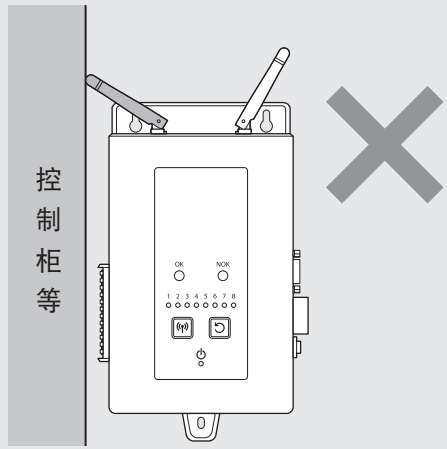
从正面看，安装时朝外伸出
30～45°



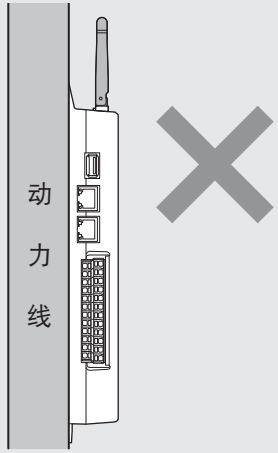
■请勿如下安装。



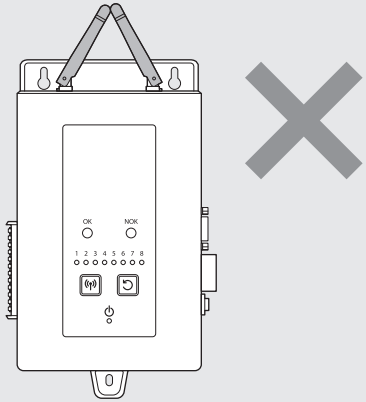
背面的控制柜（金属物）与
天线平行



天线接触到控制柜（金属物）



安装在过于靠近
动力线的位置

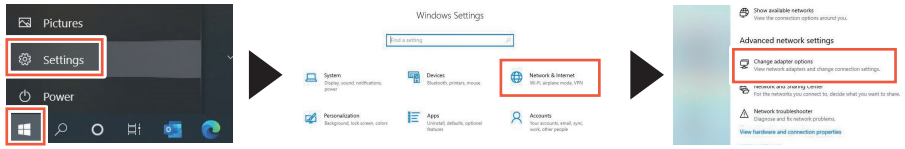

天线之间相接触

使用前

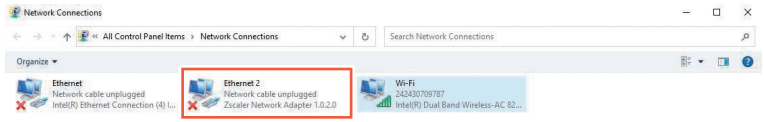
设置用计算机侧的网络设置

首次连接控制器和设置用计算机时，请将设置用计算机的网络设置更改如下。

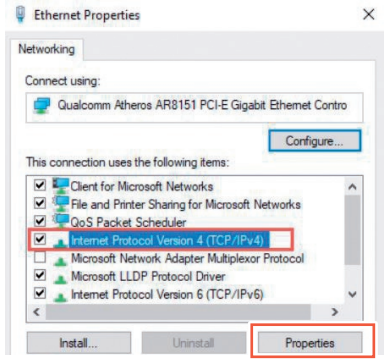
1 单击（单击画面左下方的 ⊞ ）-⚙（Settings）-[Network & Internet]-[Change adapter options]



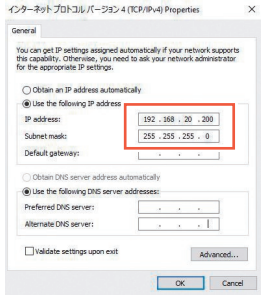
2 右击要连接的设备，然后单击 [Properties]



3 选择“Internet Protocol Version 4”，单击 [Properties]



4 如下设置“IP address”及“Subnet mask”



IP address	192 . 168 . 20 . 200
Subnet mask	255 . 255 . 255 . 0

※首次连接后，如果任意更改了控制器的IP地址，通过将设置用计算机的网络设置（IP address及Subnet mask）恢复到更改前之后可连接。这时，请确保控制器和设置用计算机为同一网络环境后，再设置IP地址。

※请记住更改前的设置用计算机的网络设置（IP address及Subnet mask），以免丢失。

※Default gateway建议不设置（空白）。

显示设置画面

设置控制器时，请用Web浏览器访问控制器进行。
按以下步骤可显示控制器的设置画面。

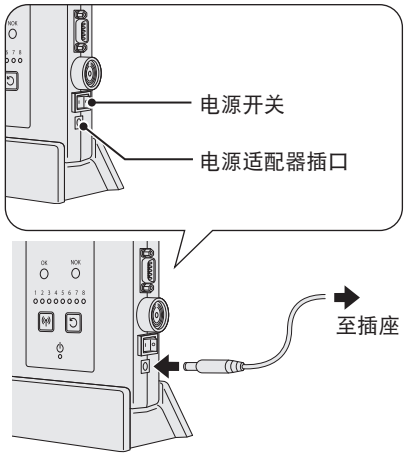
首次使用时，请拔出背面纽扣电池的保护膜后再使用。

1 打开控制器的电源

① 将附带的电源适配器连接到控制器，将电源插头插入插座。

② 打开控制器的电源开关。

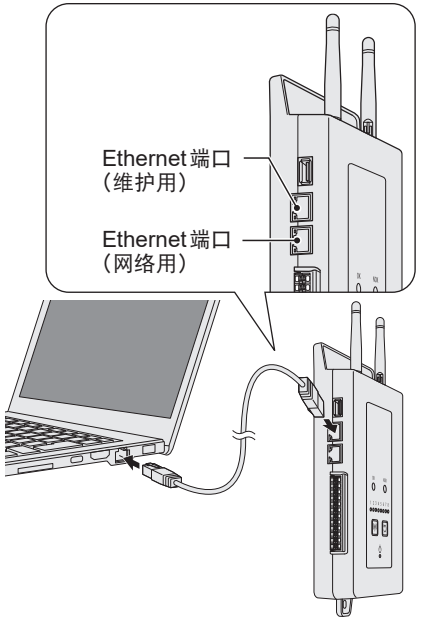
※ 启动需要数十秒。
※ 启动中，紧固OK指示灯、紧固NOK指示灯、通信指示灯（No.1～No.8）全部闪烁。
※ 请勿连接LAN电缆。



2 用LAN电缆连接控制器和设置用计算机

① 将LAN电缆插入控制器的Ethernet端口。
※Ethernet端口有维护用和网络用2个端口。
首次连接时，请使用维护用端口。

② 用LAN电缆和设置用计算机连接。



3 在设置用计算机上启动Web浏览器，访问控制器

① 在设置用计算机上启动Web浏览器。（推荐Microsoft Edge）

② 在Web浏览器的地址栏中输入控制器的IP地址。

※默认的Ethernet端口（维护用）IP地址为“192.168.20.10”。

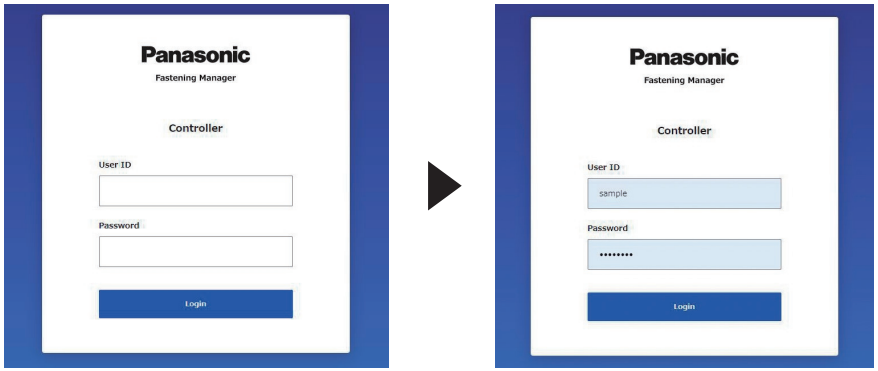
在Web浏览器的地址栏中输入“http://192.168.20.10/controller”后访问。
※仅“192.168.20.10/controller”也可访问。

※关于从Ethernet端口（网络用）访问的方法，请参见“经由网络的连接方法”。 参见P23

※还需要对设置用计算机侧的IP地址进行设置。

③ 显示登录画面后，输入User ID和Password。
※首次登录时的用户ID和密码请参见以下内容。

④ 显示Home画面（设置画面初始页面）。



首次登录时的用户ID和密码

请用以下用户ID和密码登录。

■User ID: **root**

■Password: **abcABC123**

※ 首次登录时的帐户类型为“默认”。
关于帐户的类型，请参见“帐户的类型（权限）”。 参见P21

※ 用上述用户ID和密码登录后，只可创建帐户。实际使用时，请创建新帐户。

※ 为了安全起见，建议在首次登录后修改上述密码。

帐户的类型（权限）

帐户有以下几种。请根据用途使用。

帐户的类型	可使用的功能
默认	• 首次登录用。 参见P20 追加和更改用户帐户。
Administrator	• 确认紧固履历。 • 设置控制器。 • 设置工具。 • 追加和更改用户帐户。 ※至少要创建1个以上的管理员帐户。
General	• 仅确认紧固履历（包括浏览作业显示器）。

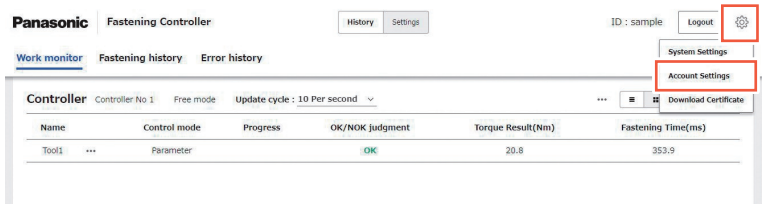
最多可注册10个帐户。
请在多名作业人员同时登录使用等的情况下使用。
※仅可用1个管理员帐户同时访问。
如有多个访问重叠，后发的会话优先。

创建用户帐户

使用前，请创建新的用户帐户。

1 从Home画面（设置画面初始页面）右上方的选项键中选择“Account Settings”

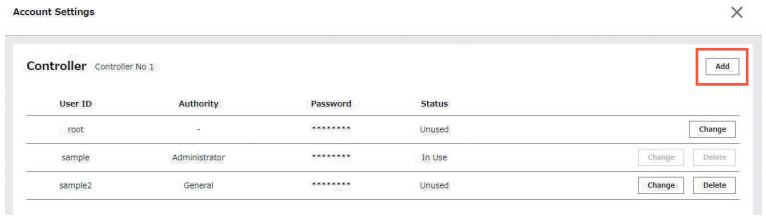
显示“Account Settings”画面。



2 单击“Account Settings”画面中的[Add]

显示“Add account”画面。

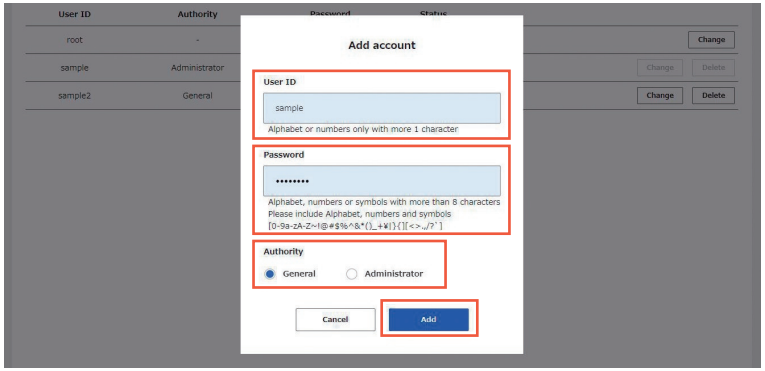
• 更改帐户请单击[Change]，删除帐户请单击[Delete]。



操作

3 输入“User ID”、“Password”，选择“Authority”后单击 [Add]

※进行工具设置时，请创建管理员帐户。
※密码请务必组合大写字母、小写字母、数字、符号中的3种以上。



【参考】用户 ID/密码丢失时的处理方法

■普通帐户

【方法①】 用管理员帐户登录后更改该帐户。
※ 由于普通帐户无法更改用户 ID/密码，需要让管理员帐户持有者进行处理。

【方法②】 用新建的管理员帐户登录后更改该帐户。
※ 请用首次登录时的用户 ID 和密码登录，然后新建管理员帐户。
参见 P20

■管理员帐户时

A) 创建多个管理员帐户时
【方法①】 用其他管理员帐户登录后更改该帐户。
【方法②】 用新建的管理员帐户登录后更改该帐户。
※ 请用首次登录时的用户 ID 和密码登录，然后新建管理员帐户。
参见 P20
【方法③】 如果包括初始 ID 在内的所有管理员帐户的 ID/密码丢失，进行初始化。
参见 P93

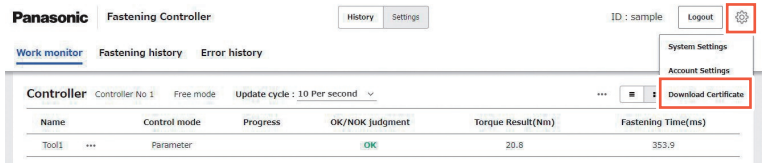
B) 只有 1 个管理员帐户时
【方法①】 用新建的管理员帐户登录后更改该帐户。
※ 请用首次登录时的用户 ID 和密码登录，然后新建管理员帐户。
参见 P20
【方法②】 如果包括初始 ID 在内的所有管理员帐户的 ID/密码丢失，进行初始化。
参见 P93

获取证书

从 Ethernet 端口（网络用）访问控制器时需要证书。
证书可按以下步骤获取。

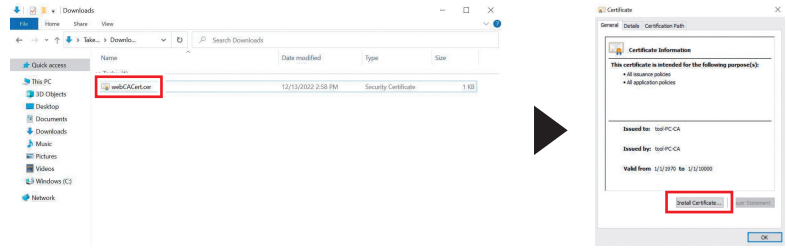
1 通过 Home 画面（设置画面初始页面）右上方的选项键选择“Download Certificate”

证书数据下载到设置用计算机中。

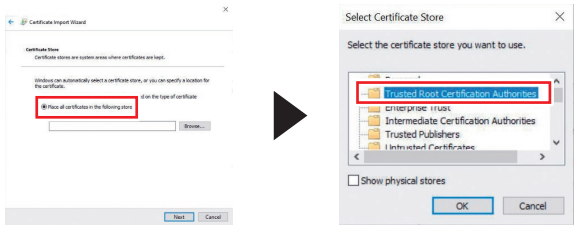


2 在“经由网络访问控制器的设置用计算机”中安装证书

①双击下载的证书数据，选择“Install Certificate”。



②从“Place all certificates in the following store”指定“Trusted Root Certification Authorities”。

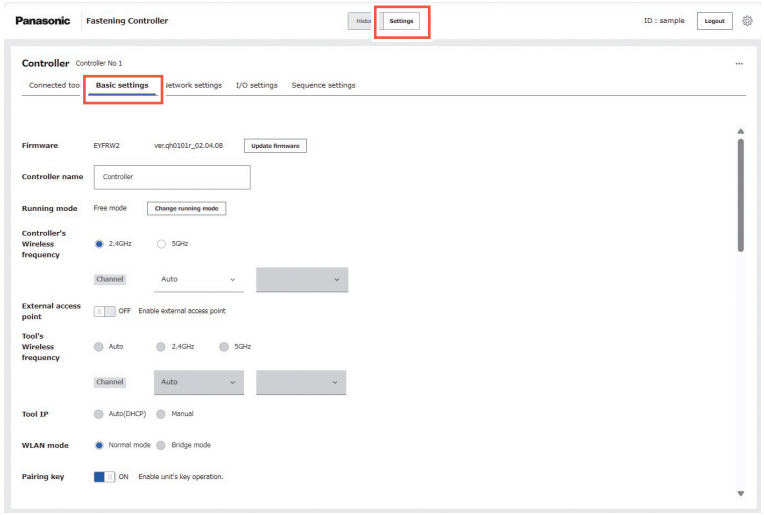


经由网络的连接方法

从 Ethernet 端口（网络用）连接控制器时，请在 Web 浏览器的地址栏中输入“https://XXX.XXX.XXX.XXX/controller”后访问。
※在 XXX.XXX.XXX.XXX 中输入 IP 地址。
※初始设置 IP 地址为“192.168.0.10”。更改初始设置时，请输入更改后的地址。
参见 P30

基本设置（Basic settings）

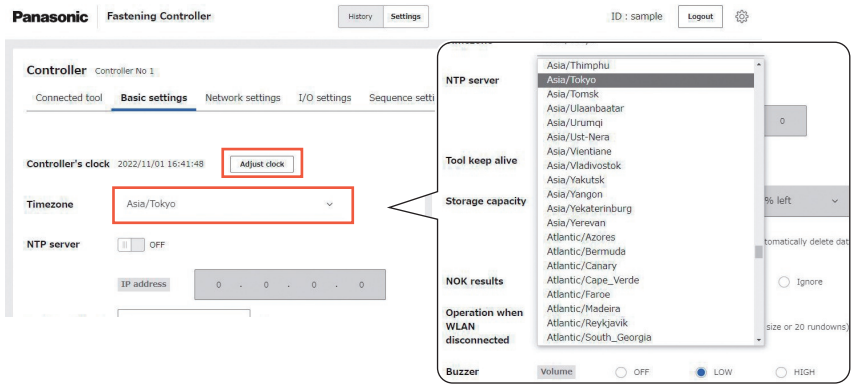
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡。
可以设置控制器主体。



■时间设置

选择“Timezone”后，单击[Adjust clock]。
更新时间。

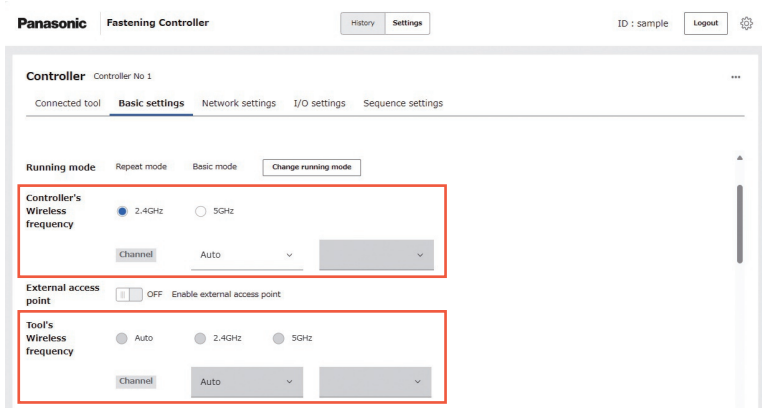
• 出厂时未设置时间。首次使用时请务必设置时间。



※如果使用NTP服务器，请输入IP地址。

■无线频率、通道的设置

可以设置要使用的频率。
选择“2.4GHz”或“5GHz”，然后选择使用通道。
※使用外部AP时的工具频率请通过“Tool's Wireless frequency”进行设置。
※“2.4GHz”和“5GHz”可选择的通道不同。
※如果将“Channel”设置为“Auto”，在电源ON时，将自动选择可在周围环境中使用的通道。
请灵活用于针对电波干扰的措施。
※将多台控制器靠近安装时，请避免设置相邻的通道。



■设置项目一览

Firmware

显示控制器的固件版本。
单击[Update firmware]可更新固件。
更新步骤请参见“更新固件”。 参见P95

Controller name

可注册控制器的名称。
最多32位英文数字。
[默认值] Controller
[设置范围] 最多32个英文数字字符串
※仅可使用“-”（连字符）“_”（下划线）“ ”（半角空格）符号

Running mode

选择控制器的动作模式。
[默认值] Free mode
[设置范围] Free mode / Repeat mode（Basic mode / Sequence mode）/ External control mode

Controller's Wireless frequency

选择用于无线通信的控制器的频率通道。
[默认值] 2.4GHz
[设置范围] 2.4GHz（Auto / Channel 1～13）/ 5GHz（Auto / Channel 36, 40, 44, 48）
※Channel 12和13不可在中国和韩国使用。

External access point

启用使用外部接入点的通信。 参见P73
[默认值] OFF（禁用）
[设置范围] OFF（禁用）/ON（启用）
※ 如果将“Tool IP”设置为“Auto (DHCP)”，可以形成不管理工具IP地址的网络构成。 参见P13

Tool's Wireless frequency

选择使用外部接入点时工具使用的通道。
[默认值] Auto
[设置范围] Auto / 2.4GHz（Auto / Channel 1～13）/ 5GHz（Auto / Channel 36, 40, 44, 48）
※在“Auto”下，将从“2.4GHz”和“5GHz”中自动选择可使用的通道。
※Channel 12和13不可在中国和韩国使用。

Tool IP

可以选择工具的IP地址设置方法。
[默认值] Manual
[设置范围] Auto (DHCP) / Manual
※仅在“External access point”设置为ON时可以设置。

WLAN mode

可以选择使用控制器内置接入点时的工具IP地址的设置方法。
[默认值] Normal mode
[设置范围] Normal mode / Bridge mode
※“Normal mode”：自动分配工具IP地址。
※“Bridge mode”：指定工具IP地址。

Pairing key

启用主体配对键的操作。
[默认值] ON（启用）
[设置范围] OFF（禁用）/ON（启用）

Reset key

启用主体复位键的操作。
[默认值] ON（启用）
[设置范围] OFF（禁用）/ON（启用）

Controller's clock

设置控制器的时间。

单击[Adjust clock]可更新时间。

Timezone

同步控制器时钟时，可设置任意的时区。

NTP server

设置NTP服务器可自动同步时间。

Tool keep alive

设置在无线通信模式中从控制器对工具进行生存确认的时间间隔。
如果工具无反应，会被视为脱机并断开。

[默认值]　30 s

[设置范围] 10 s～3600 s

Storage capacity

设置在存储器剩余空间变少时是否进行通知，以及空间不足时的动作。

[默认值]　（通知）OFF
　　（动作）Automatically delete data

[设置范围]（通知）OFF / ON（剩余空间 10/20/30/40/50%）
　　（动作）Suspend operation / Automatically delete data

默认设置为“Automatically delete data”。
请在考虑数据的处理方法之后，再根据需要更改为“Suspend operation”。

NOK results

选择紧固NOK数据的处理。

[默认值]　Store data only

[设置范围] Report to system / Store data only / Ignore

Operation when WLAN disconnected

选择无线通信暂时切断时的作业处理。

[默认值]　Suspend tool

[设置范围] Suspend tool / Enable fastening（Until batch size or 20 rundowns）

详情请参见“无线通信中断时的工具动作”。 参见P80

Buzzer

选择蜂鸣器的音量及要通知的内容。

[默认值]　（Volume）LOW
　　（Beep）全部ON

[设置范围]（Volume）OFF / LOW / HIGH
　　（Beep）各项目OFF / ON

Barcode reader settings

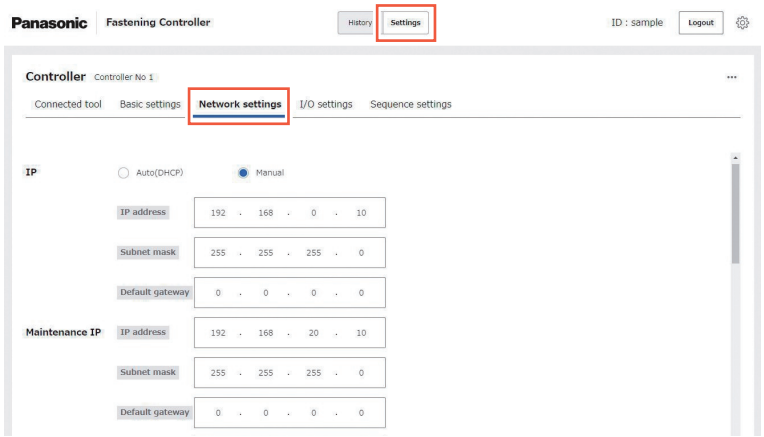
可以连接条形码阅读器，将读取信息添加到紧固履历数据中。

[Reading Test]　显示条形码阅读器读取的信息。

[Bluetooth settings]　使用Bluetooth通信方式的条形码阅读器时的设置。
通过“Search”键显示可以连接的设备。
请通过“Pairing”键选择要连接的设备。
已连接时，显示MAC地址/设备名称。
通过“Cancel registration”键可以断开连接。

网络设置（Network settings）

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Network settings”选项卡。
完成控制器的网络设置。



■设置项目一览

IP

设置Ethernet端口（网络用）的IP地址。
[默认值] Manual
[设置范围] Auto（DHCP）/ Manual
※手动设置时
[默认值] （IP address） 192.168.0.10
（Subnet mask） 255.255.255.0
（Default gateway） 0.0.0.0

Maintenance IP

设置Ethernet端口（维护用）的IP地址。
[默认值] （IP address） 192.168.20.10
（Subnet mask） 255.255.255.0
（Default gateway） 0.0.0.0

WLAN

设置与工具进行无线通信用的IP地址（控制器端）。
[默认值] （IP address） 192.168.100.1
（Subnet mask） 255.255.255.0
（Default gateway） 0.0.0.0

Atlas Open Protocol

设置Atlas Open Protocol相关项目。
详情请参见“通过Open Protocol通信连接”。 参见P61

RS232C

TOYOTA MOTOR CORPORATION专用设置。设置可以从外部设备进行控制。
[默认值] Disable
[设置范围] Disable / Enable

Step flow after tightening NG

设置紧固结果为紧固NG时是否可以执行下一次紧固。
[默认值] Keep
[设置范围] Next（可以执行下一次紧固）/ Keep（不可执行下一次紧固）

Access point

设置用于和工具进行无线通信的内置接入点。
[默认值] （SSID） 控制器型号-MAC地址
（Security） WPA2
[设置范围] （SSID） 最多32个英文数字字符
（Security） WPA2

External access point

设置要使用的外部接入点。
[默认值] （SSID） 无
（Security） 无
（Password） 无
[设置范围] （SSID） 最多32个英文数字字符
（Security） Open/WPA2
（Password） 8-63个英文数字字符
※ 不可使用“"”“¥”“,”“'”（重音符）”符号。
※ 在“Basic settings”中，仅在设置“External access point”“ON”时，启用设置。

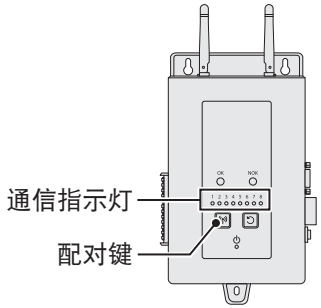
- 请确保“IP”和“Maintenance IP”的IP地址子网不重复。
（“Subnet mask”为默认设置（255.255.255.0）时，请避免“192.168.0”及“192.168.20”的部分不一致）
- 仅可启用“Atlas Open Protocol”与“RS232C”中的一个。
不可同时启用。

控制器的配对操作

利用“主体按键操作”和“设置画面操作”2种方法，可使控制器进入配对模式。
配对模式持续2分钟，如果在此期间在通信范围内使工具进入配对模式，将会自动建立配对。
如果在该时间内未完成配对，则会解除配对模式。
※配对操作后到进入配对模式可能需要较长时间。

■主体按键操作

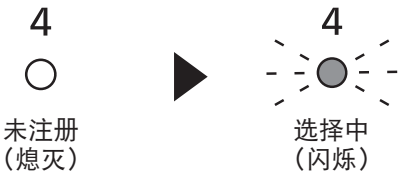
操作控制器主体上的配对键。
选择通信指示灯上的未注册No.（熄灭），长按进入配对模式。
详情请参见以下章节。



（注册工具No.4时）

1 按下控制器主体的配对键4次，选择工具No.4

通信指示灯No.4闪烁。



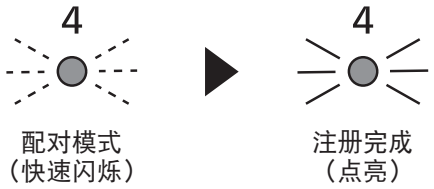
2 在选中No.4的状态下，长按控制器主体上的配对键，进入工具No.4的配对模式

进入配对模式后，通信指示灯No.4的闪烁变成快速闪烁。



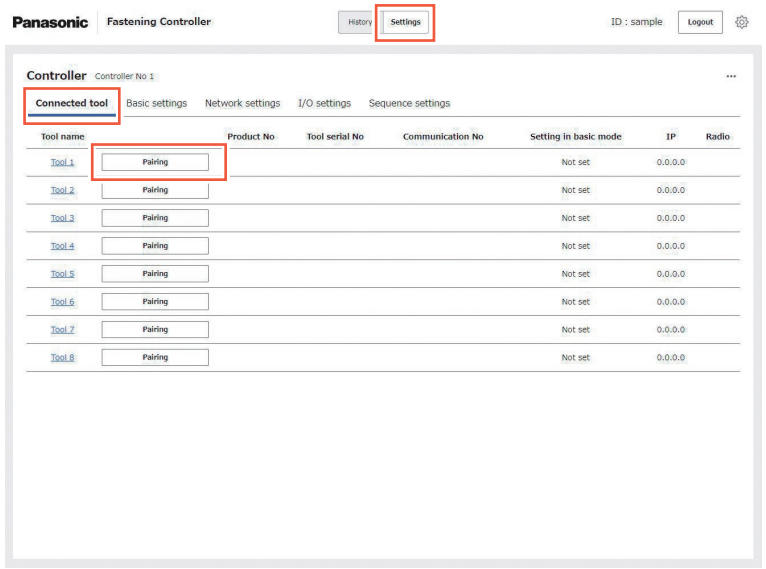
3 操作工具，使工具No.4完成配对

通信指示灯No.4点亮。
有关工具的操作，请确认“工具主体的配对操作”。 参见P34



■设置画面操作

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
在“Connected tool”画面中单击对象工具No.的[Pairing]。
控制器进入配对模式后，进行“工具主体的配对操作”。 参见P34



【参考】与备用工具进行替换

如果由于工具故障等原因，替换为与同一型号的工具进行配对注册时，
按配对解除 参见P34 ▶ 配对操作 参见P32
的顺序对应后，将自动沿用紧固参数等设定值。

※要配对登录其他型号的工具时，请在解除配对后删除注册信息，然后再进行配对注册。 参见P38

配对完成时的显示

配对完成后，如果在设置画面没有显示配对的工具信息，请在设置画面进行画面内更新。

※“Bridge mode”“External access point”请在配对注册前设置工具IP地址。

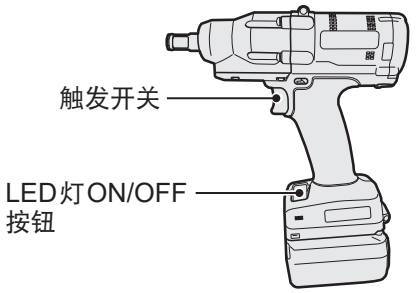
工具主体的配对操作

请在控制器进入配对模式后，再进行工具主体的配对操作。

■操作步骤

1 安装电池组后，按住LED灯ON/OFF按钮，拉出触发开关

进入配对模式。
自动建立无线通信，配对注册完成。
※详细内容请参见工具主体的使用说明书。
※如果配对未建立，请先在控制器端进行配对解除操作，然后重新进行配对操作。

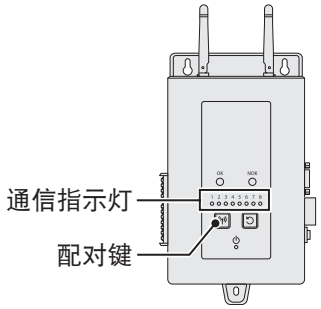


配对解除

可以利用“主体按键操作”和“设置画面操作”2种方法解除控制器的配对注册。

■主体按键操作

操作控制器主体上的配对键。
选择要解除注册的通信指示灯的工具No.（点亮），长按后可解除配对注册。
详情请参见以下章节。



（解除工具No.4时）

1 按下控制器主体的配对键4次，选择工具No.4

通信指示灯No.4闪烁。



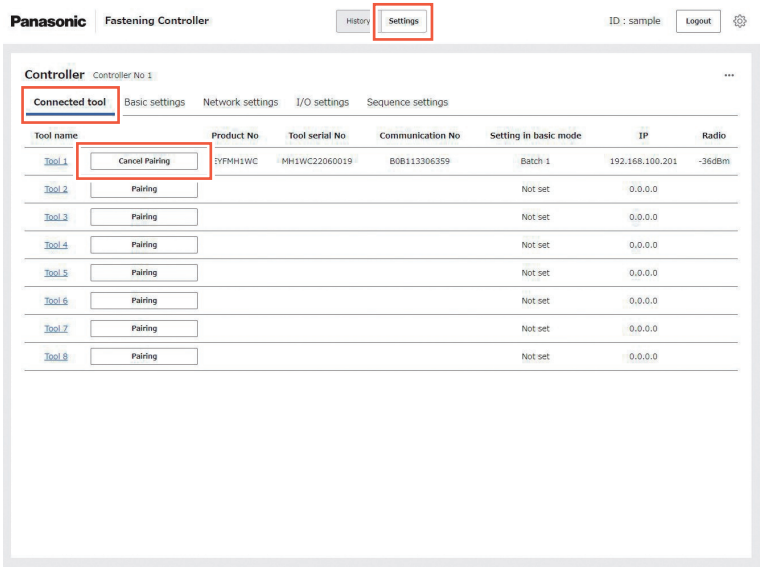
2 在No.4选中状态长按控制器主体上的配对键，解除工具No.4的配对注册

解除配对注册后，通信指示灯No.4的闪烁变为熄灭。



■设置画面操作

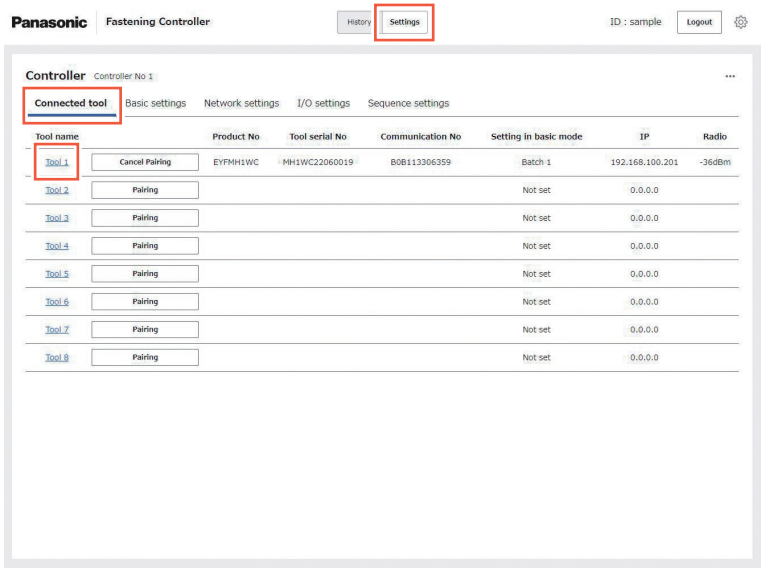
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
在“Connected tool”画面中单击对象工具No.的[Cancel Pairing]。



※ 在工具电源OFF状态等控制器与工具间无法通信时，请勾选配对解除确认对话框中的[Force to unpair]。

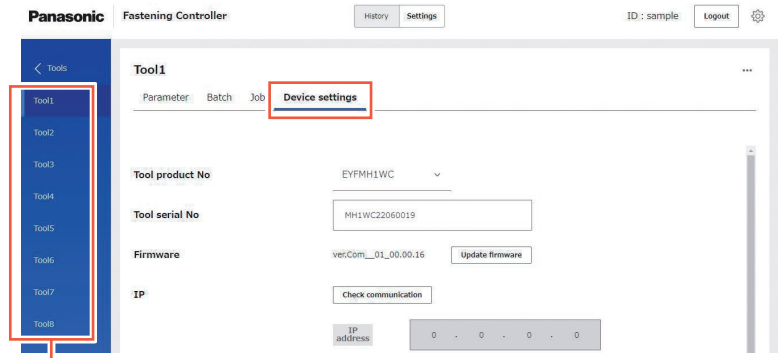
工具画面的显示

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
在“Connected tool”画面中单击对象工具No.。
显示工具No.画面。



工具设置画面的显示

可以从工具No.画面的“Device settings”选项卡选择工具的基本设置及通用参数的设置。
※切换工具时，也可以从工具列表选择。



工具列表

工具设置项目

Tool product No

选择工具型号。
[默认值]　未选择
[设置范围]下拉选择
※先进行配对时自动选择。
※配对后不可更改型号。请先解除配对后再重新设置。

Tool serial No

显示/设置工具的个体识别信息。
[默认值]　型号识别5位＋制造编号8位（制造年份2位＋月份2位＋生产批次4位）
[设置范围]13～16个英文数字字符
※如果更改，可能无法正确识别机型。
　从管理规定上来讲，如非必要，使用时请勿更改。

Firmware

显示工具通信部的固件版本。
单击[Update firmware]，可更新固件。
更新步骤请参见“更新固件”。 参见P95

IP

设置与工具进行无线通信用的IP地址（工具侧）。
[默认值]　（IP address）　192.168.100.201（工具1）～ 208（工具8）
　　（Subnet mask）　255.255.255.0
　　（Default gateway）　0.0.0.0
※ 启用Bridge mode或External access point时，全部为“0.0.0.0”。

Tool's clock

显示工具的时间。单击[Adjust to controller]可同步时间。

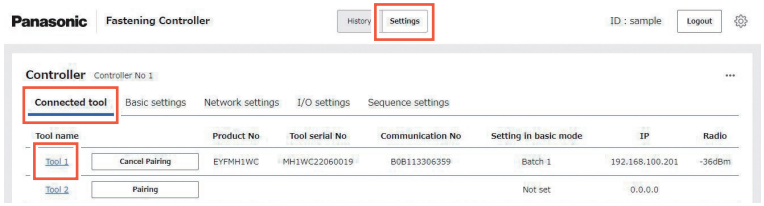
• 有关其他设置项目，请参见工具主体的使用说明书。

删除注册信息

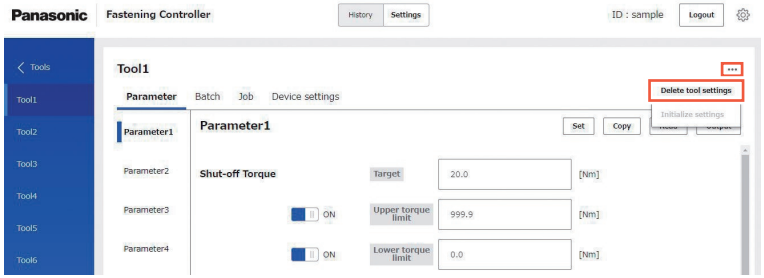
停止使用该No.的工具时，或在配对使用其他型号的工具时，请删除注册信息。
※请解除配对后再进行。

1 **单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡**
显示“Connected tool”画面。

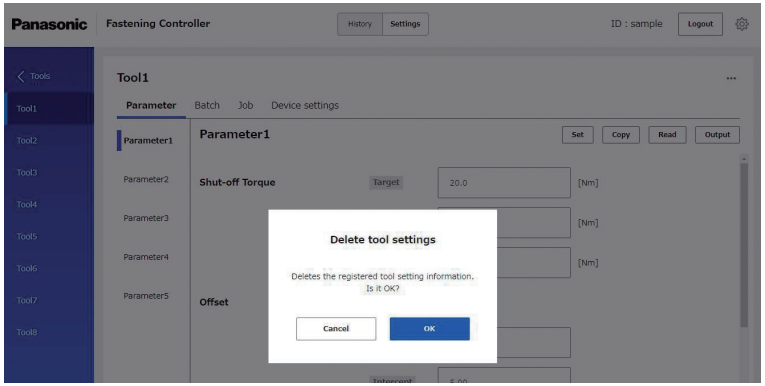
2 **在“Connected tool”画面中单击对象工具No.**
显示工具No.画面。



3 **从 ⋯（工具选项键）单击[Delete tool settings]**
显示“Delete tool settings”画面。



4 **在“Delete tool settings”画面中单击[OK]**

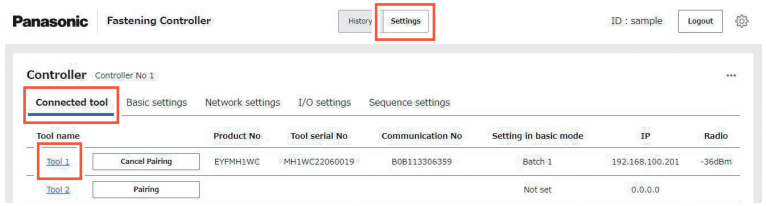


复位到出厂状态

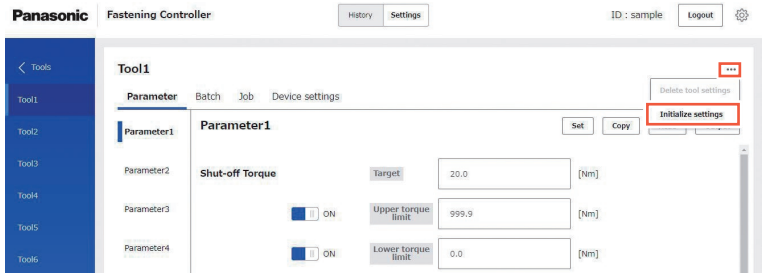
可将工具的设置复位到出厂状态。
※复位后解除配对。

1 **单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡**
显示“Connected tool”画面。

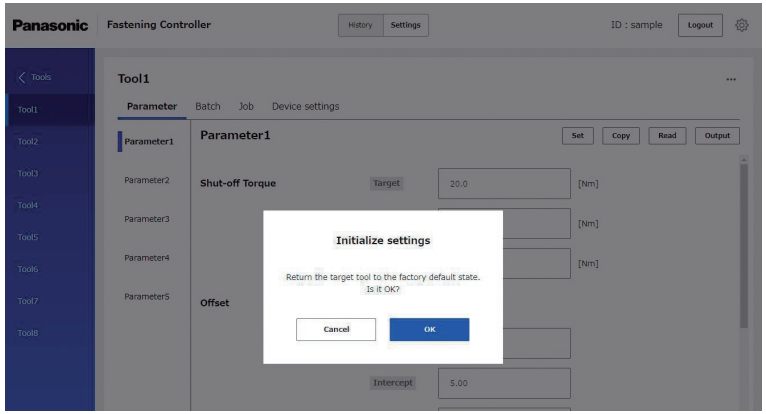
2 **在“Connected tool”画面中单击对象工具No.**
显示工具No.画面。



3 **从 ⋯（工具选项键）单击[Initialize settings]**
显示“Initialize settings”画面。



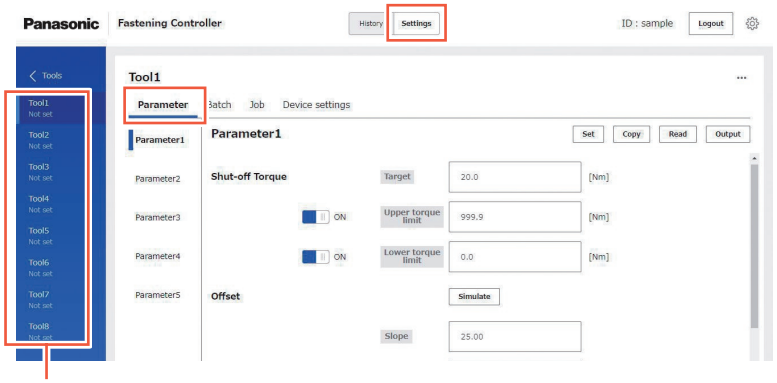
4 **在“Initialize settings”画面中单击[OK]**



设置工具的紧固参数

参数设置

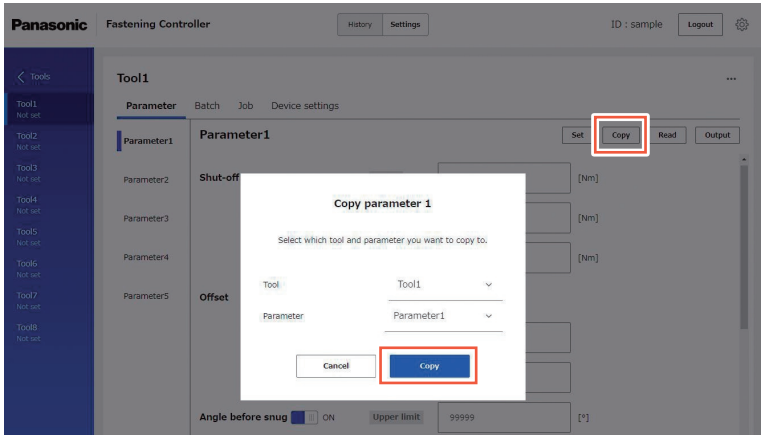
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
在“Connected tool”画面中单击对象工具No.。
可从工具NO.画面中的“Parameter”选项卡进行设置。
每台工具可注册5种参数（参数1～5）。
※切换工具时，也可从工具列表选择。



工具列表

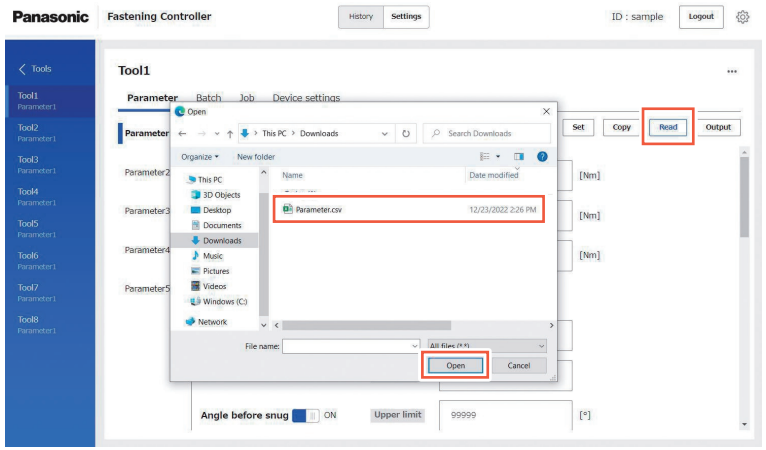
复制参数

要根据已创建完成的参数创建新参数时，或者要在其他工具中使用同一参数时，可进行复制。
从工具NO.画面的“Parameter”选项卡单击[Copy]后，会显示参数的复制画面，请选择复制路径，并单击参数复制画面中的[Copy]。



读取参数

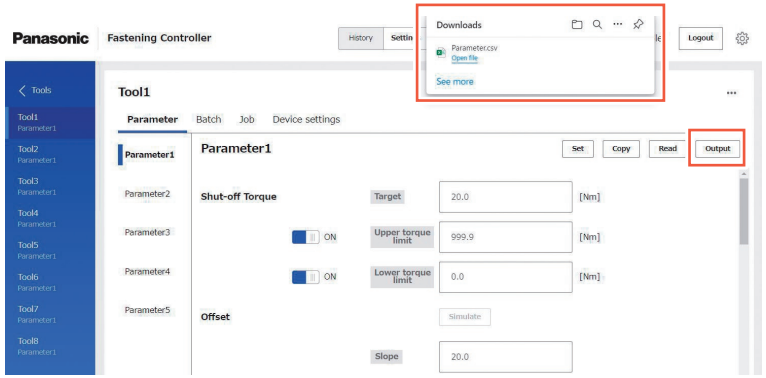
可以将保存在设置用计算机中的参数文件读取到控制器进行注册。
也可以读取用“Tool Manager”创建的参数文件。
请从工具NO.画面的“Parameter”选项卡单击[Read]，打开参数文件。



输出参数

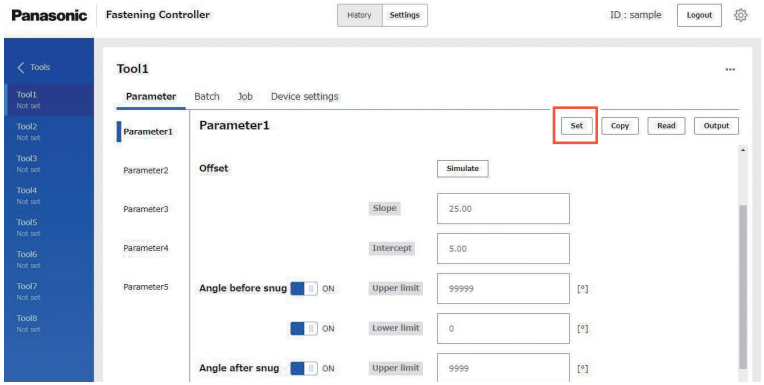
可将创建的参数输出到设置用计算机。
请用于备份用途或复制到其他控制器、移到其他设置用计算机等。
请从工具NO.画面的“Parameter”选项卡单击[Output]，保存参数文件。

请勿对输出的参数文件进行编辑。
否则可能无法正常读取。



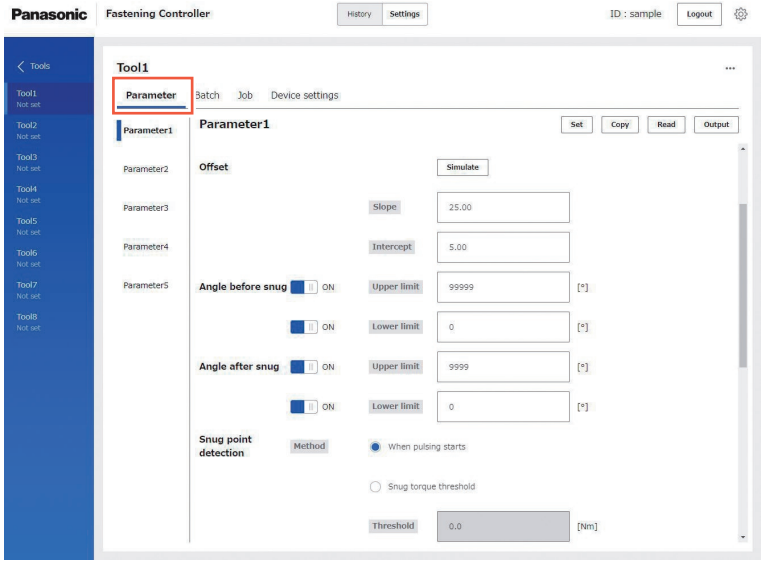
注册参数

利用控制器的动作模式“Free mode”进行控制时，进行注册以指定在工具中使用的参数。
※如果是“Repeat mode”、“External control mode”，则没有影响。
（有关“Free mode”、“Repeat mode”、“External control mode”的详细内容，请确认“设置动作模式” 参见P49）
请从工具NO.画面的“Parameter”选项卡单击[Set]。



参数项目

设置紧固参数的项目。
详细内容请参见工具主体的使用说明书。

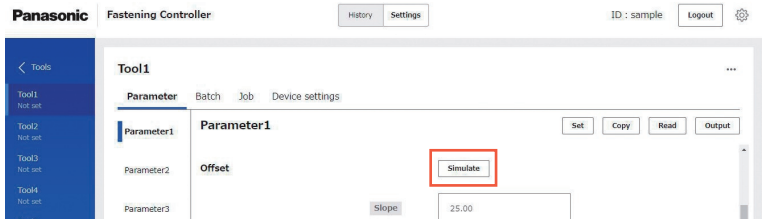


■设置偏移（参数设置 参考①）

请设置偏移，使扭矩输出值与实测值一致。

1 从工具No.画面的“Parameter”选项卡单击“Offset”项目中的[Simulate]

显示“Offset”页。



2 输入设定值后，单击[Apply]

请输入“Socket length”“Shut-off Torque”。
单击[Apply]后，输入的设定值被发送到工具。
工具变为偏移模式（T2标识）。

3 用工具执行实际的作业后，单击[Get data]

紧固履历数据被添加到“Offset”页的履历列表中。
※[Get data]后，工具变为可紧固状态（“C模式”），但在偏移设置完成之前，请勿进行正常的紧固作业。

4 选中已获取的紧固履历数据中的相应行，输入实测扭矩（紧固）值，单击[Calculate]

自动计算修正工具输出扭矩和实测扭矩的偏移值。

5 确认偏移值更新后，单击[Apply]

调整的设定值被发送到工具。

6 重复步骤3～5，直至差值变得极小

※请将95％～105％范围内的％显示作为基准。



【最小输出模式】

勾选偏移设置画面中的[T1 mode]，主体在最小输出模式下动作。
（解除勾选[T1 mode]后，主体将返回到“Offset Mode”）



T1 mode
[功能概要] 目标扭矩接近主体的扭矩控制功能运转范围下限时，可确认是否可进行扭矩控制。该模式下的主体以最低打击数（最小输出）关机。 此时，不会记录作业履历。 在该模式作业后，使用扭矩测量仪或扭力扳手确认主体输出的扭矩是否低于目标扭矩。 对于超过扭矩的作业，在该模式下可能无法使用主体。

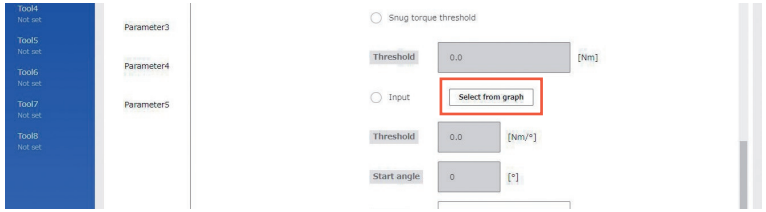
※偏移设置中，其他工具会暂时无法进行紧固动作。

■进行着座设置（参数设置 参考②）

可根据波形数据进行着座设置。

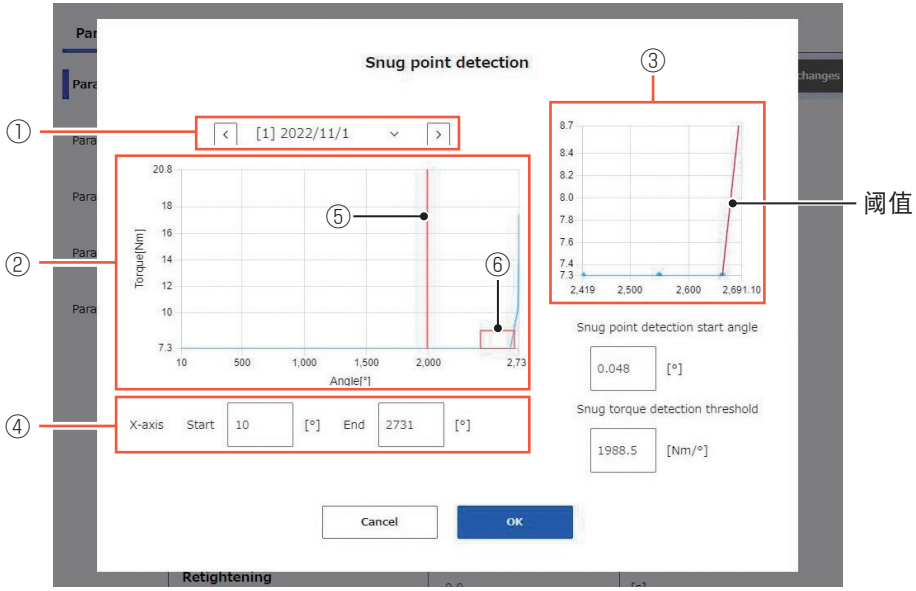
1 从工具No.画面的“Parameter”选项卡单击“Snug point detection”项目的[Select from graph]

- 显示“Snug point detection”画面，在画面上显示对象工具的最新波形数据。
- 需要参照的紧固履历数据。请至少进行1次紧固作业后再设置。
- 用于设置的图表可从图表切换（①）进行更改。



2 从图表选择

- 有一个显示整个图表的主窗口（②）和放大图表任意部分的副窗口（③）。
- 主窗口的显示范围可通过在图表下方的“X-axis”（④）中输入显示开始和结束角度进行更改。
- 移动竖线，可设置着座判定开始角度（⑤）。
- 副窗口的显示范围可通过移动主窗口的选择框（⑥）更改。
- 请从副窗口（③）选择阈值进行设置。

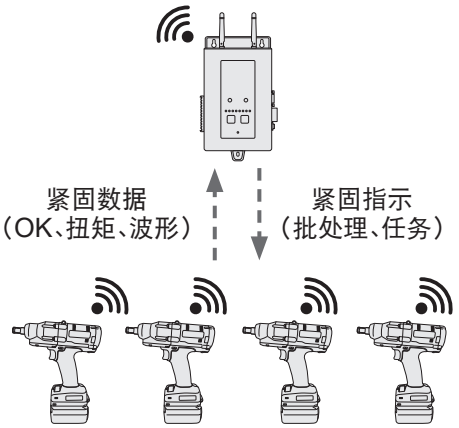


设置紧固控制模式

工具的紧固控制

利用控制器可对最多8台的连接工具进行紧固控制。
另外,还会按每个紧固作业接收紧固数据,对紧固数量进行计数。

连接台数:最多8台



紧固控制模式的概要

紧固控制在多种模式下进行。各模式的概要请参见以下内容。

模式	[Free mode]	[Repeat mode]	
		[Basic mode]	[Sequence mode]
OK判定基准	– (无数量管理)	紧固数量完成	按指定的顺序,多个工具分别完成紧固数量
[Batch] "单一设定值" (相同条件紧固) ※单一工件	A OK 设定值 / 紧固数量 10 Nm / ∞ Parameter	A OK 设定值 / 紧固数量 10 Nm / 10个 Batch	A ① OK ▶ B ② OK 设定值 / 紧固数量 10 Nm / 10个 20 Nm / 5个 Batch×Sequence
[Job] "多个设定值" (不同条件紧固) ※多个工件		A OK 设定值 / 紧固数量 10 Nm / 2个 20 Nm / 3个 30 Nm / 5个 Job	A ① OK ▶ B ② OK 设定值 / 紧固数量 10 Nm / 2个 20 Nm / 3个 30 Nm / 5个 20 Nm / 5个 30 Nm / 10个 Job×Sequence
备注	–	※任务最多到10个步骤	※时序最多可设置10步

操作

可注册件数

控制器中可注册的控制模式数如下所示。

控制器模式		工具动作设置	可注册件数
Free mode		Parameter	○ 每台工具最多可注册5种
Repeat mode	Basic mode（独立控制）	Batch	○ 每台工具最多可注册5种
		Job	○ 每台工具最多可注册5种
	Sequence mode（顺序控制）	Batch/Job	○ 最多可注册5种
External control mode		–	○

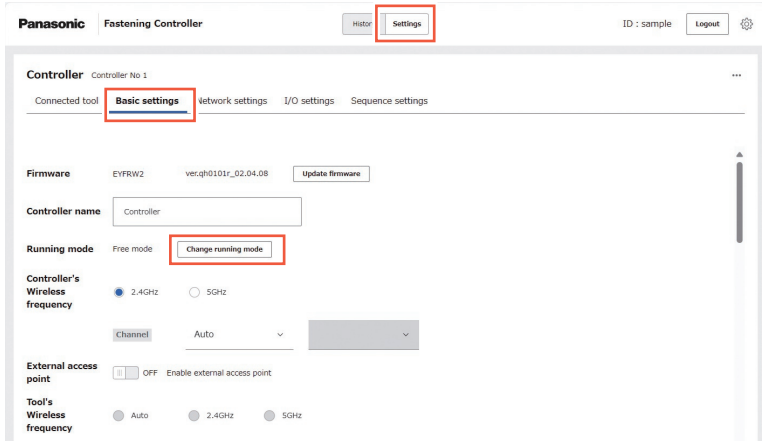
设置动作模式

控制器的动作模式可按以下步骤设置。

1 **单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡**

2 **从“Basic settings”选项卡单击[Change running mode]**

显示“Change running mode”画面。



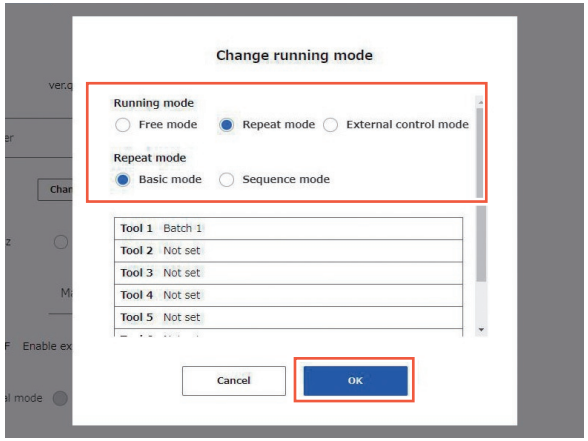
3 **选择“Running mode”，单击[OK]**

设置动作模式。

动作模式可从“Free mode”“Repeat mode”“External control mode”中选择。

另外，可在设置“Repeat mode”时选择“Basic mode”、“Sequence mode”。

参见P50～53

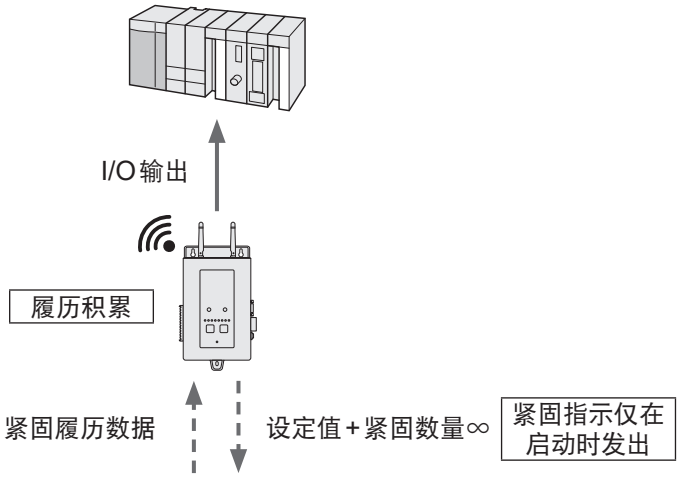


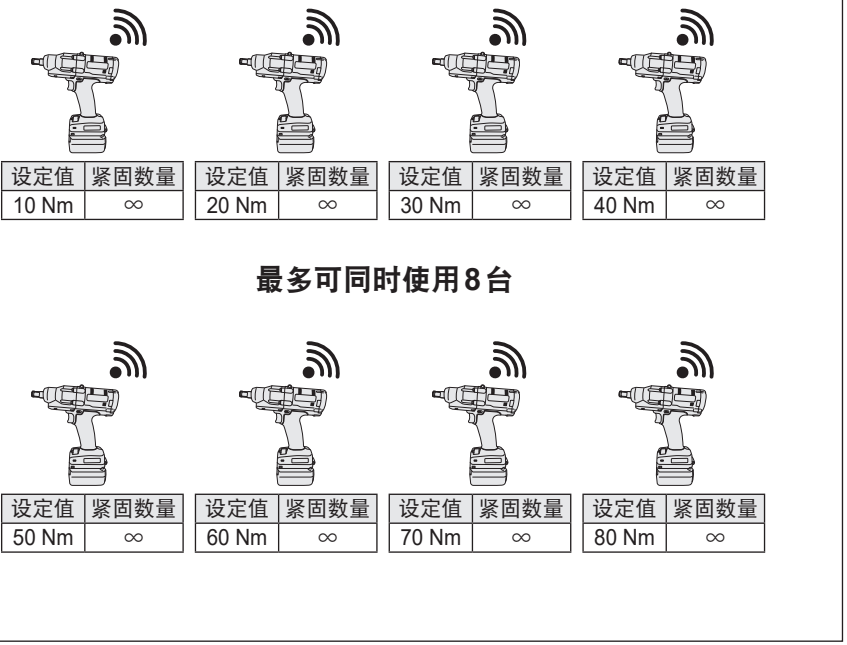
※设置为“Free mode”时，需要事先注册“Parameter”。

※设置为“Repeat mode”时，需要事先注册“Batch/Job”。

■Free mode

无需管理紧固数量，可自由紧固的模式。
各工具按事先注册的“Parameter”进行紧固。
最多8台工具可单独紧固。
基于I/O的输出设置启用。
※可在用外部设备对紧固数量进行计数时使用。





设定值	紧固数量
10 Nm	∞

设定值	紧固数量
20 Nm	∞

设定值	紧固数量
30 Nm	∞

设定值	紧固数量
40 Nm	∞

最多可同时使用8台

设定值	紧固数量
50 Nm	∞

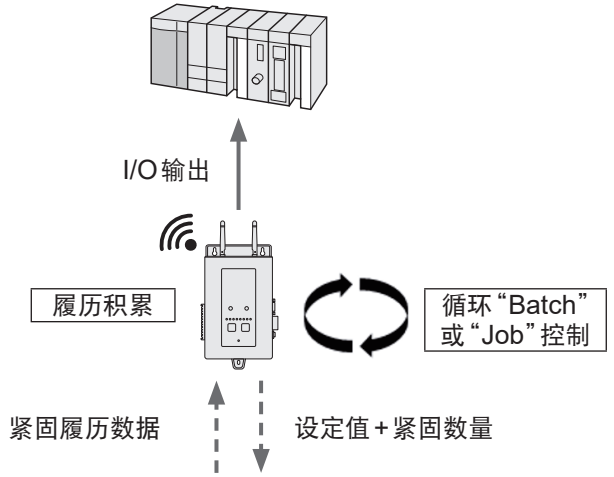
设定值	紧固数量
60 Nm	∞

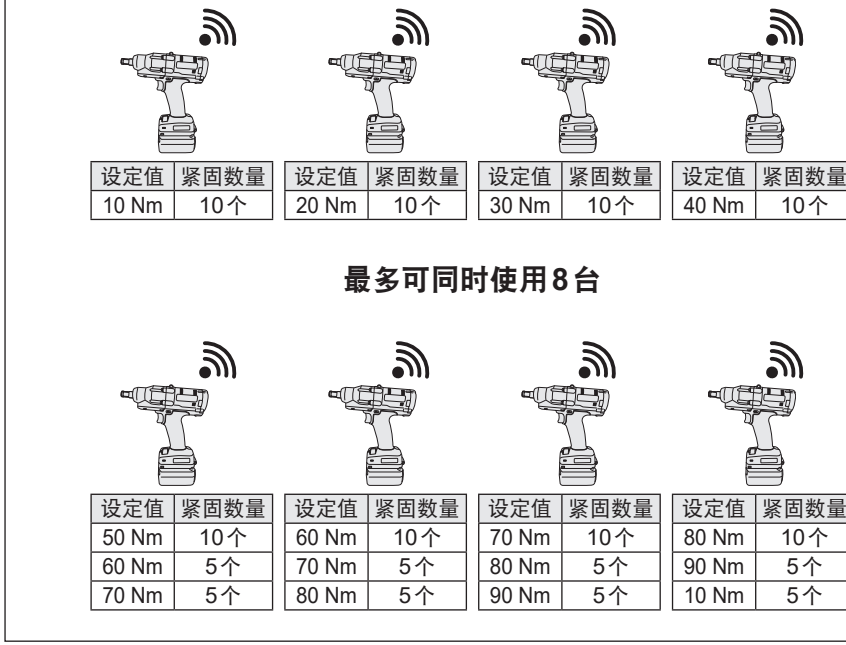
设定值	紧固数量
70 Nm	∞

设定值	紧固数量
80 Nm	∞

■Repeat mode（Basic mode）

重复控制“Batch”“Job”的模式。
各工具按照事先注册的“Batch”或“Job”进行紧固。
最多8台工具可单独紧固。
基于I/O的输出设置启用。





设定值	紧固数量
10 Nm	10个

设定值	紧固数量
20 Nm	10个

设定值	紧固数量
30 Nm	10个

设定值	紧固数量
40 Nm	10个

最多可同时使用8台

设定值	紧固数量
50 Nm	10个
60 Nm	5个
70 Nm	5个

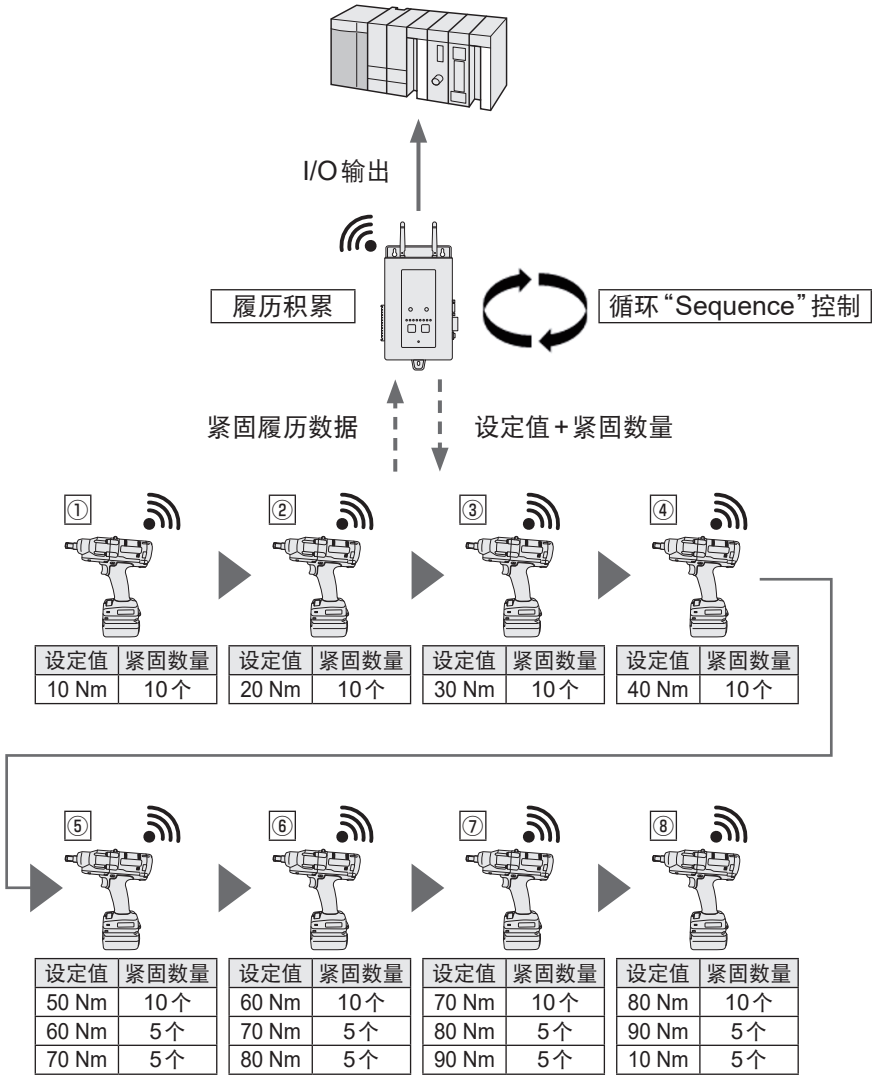
设定值	紧固数量
60 Nm	10个
70 Nm	5个
80 Nm	5个

设定值	紧固数量
70 Nm	10个
80 Nm	5个
90 Nm	5个

设定值	紧固数量
80 Nm	10个
90 Nm	5个
10 Nm	5个

■Repeat mode（Sequence mode）

按顺序控制可使用的工具以重复“Sequence”的模式。
各工具根据事先注册的“Sequence”，按顺序进行紧固。
最多可设置10个步骤。时序内可使用的工具最多为8台，一次只能使用1台。
基于I/O的输出设置启用。



设定值	紧固数量
10 Nm	10个

设定值	紧固数量
20 Nm	10个

设定值	紧固数量
30 Nm	10个

设定值	紧固数量
40 Nm	10个

设定值	紧固数量
50 Nm	10个
60 Nm	5个
70 Nm	5个

设定值	紧固数量
60 Nm	10个
70 Nm	5个
80 Nm	5个

设定值	紧固数量
70 Nm	10个
80 Nm	5个
90 Nm	5个

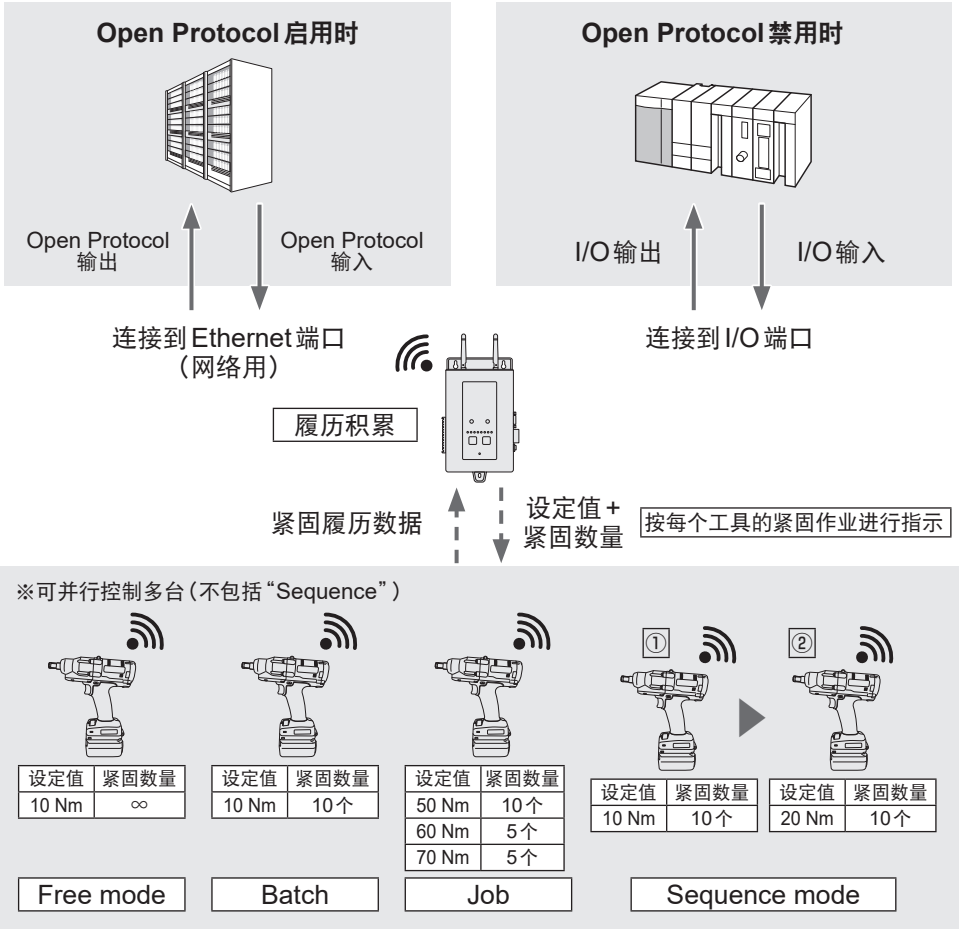
设定值	紧固数量
80 Nm	10个
90 Nm	5个
10 Nm	5个

■External control mode

根据外部设备（上游系统）发出的指示来控制紧固的模式。
可在以下2种模式下控制。

●利用Open Protocol进行控制（Open Protocol启用）
可根据上游系统发出的Open Protocol指示进行紧固控制。
最多可单独控制8台工具。
※不支持任务控制、时序控制。

●通过I/O进行控制（Open Protocol禁用）
可根据来自外部设备的I/O输入指示进行紧固控制。
最多可单独或时序控制8台工具。



设定值	紧固数量
10 Nm	∞

设定值	紧固数量
10 Nm	10个

设定值	紧固数量
50 Nm	10个
60 Nm	5个
70 Nm	5个

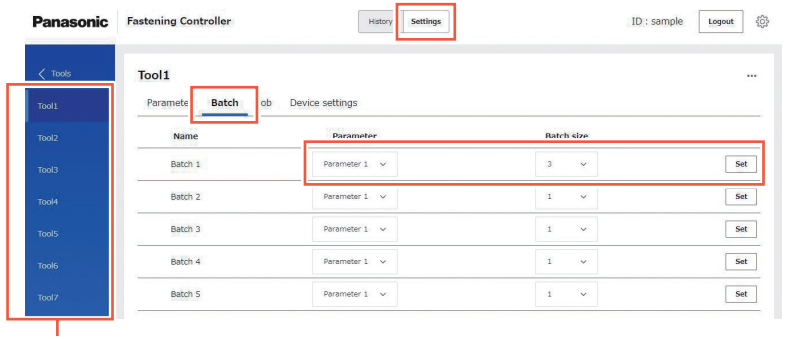
设定值	紧固数量
10 Nm	10个

设定值	紧固数量
20 Nm	10个

※ 如果在紧固作业中控制器电源关闭，重启后不会重新开始紧固。
要重新接受外部设备发出的指示后再开始作业。
※ 基于I/O的输出设置启用。

创建（设置）批处理

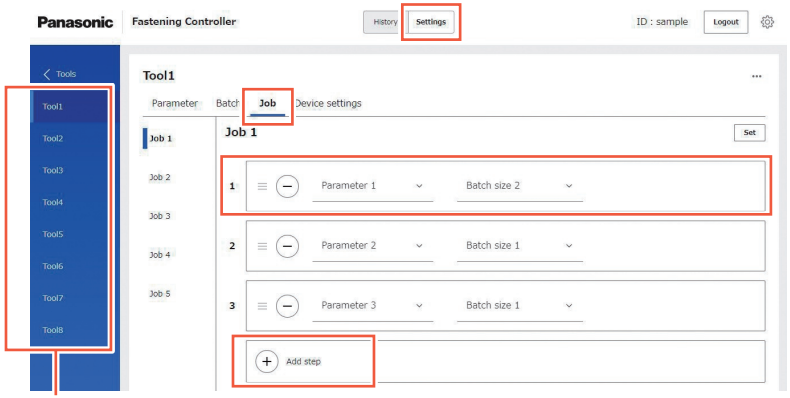
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。在“Connected tool”画面中单击对象工具No.。
可从工具NO.画面中的“Batch”选项卡进行设置。
下拉选择“Parameter”，然后设置“Batch size”（紧固数量。最多99个）。进行[Set]后，即可作为“Repeat mode（Basic mode）”时的动作设置。
※切换工具时，也可从工具列表选择。
※批处理最多可注册5种。



工具列表

创建（设置）任务

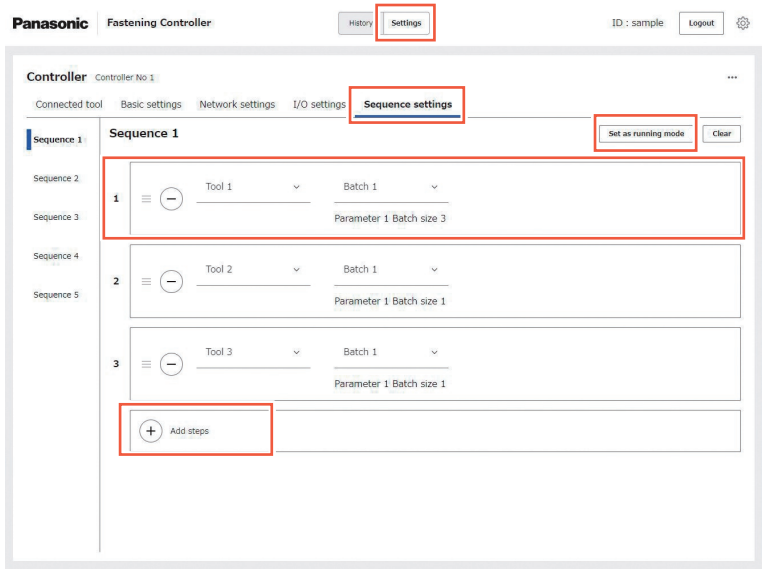
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。在“Connected tool”画面中单击对象工具No.。
可从工具NO.画面中的“Job”选项卡进行设置。
下拉选择“Parameter”，然后设置“Batch size”（紧固数量。最多99个）。进行[Set]后，即可作为“Repeat mode（Basic mode）”时的动作设置。
※最多可注册10步。
※切换工具时，也可从工具列表选择。
※任务最多可注册5种。



工具列表

创建（设置）时序

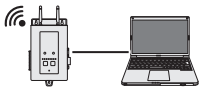
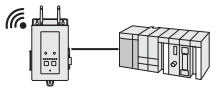
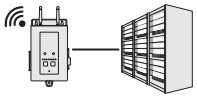
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Sequence settings”选项卡。
在“Sequence settings”画面中，下拉选择“Tool”后，设置“Batch”或“Job”。
设为[Set as running mode]后，即可作为“Repeat mode（Sequence mode）”时的动作设置。
※最多可注册5个时序。
※最多可注册10个步。
※在同一时序内也可设置使用多次工具。



与外部设备连接

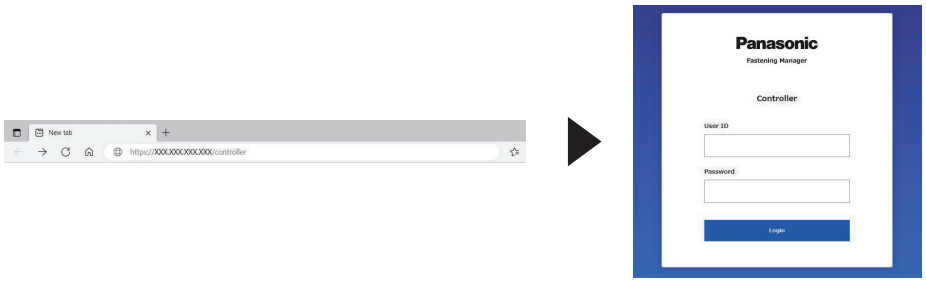
外部设备连接的概要

本产品可与以下外部设备连接。

对象	设置用计算机	PLC	客户上游系统
连接示意图			
通信方式	Ethernet	I/O	Ethernet
通信协议	http/https	－（仅ON/OFF信号）	Open Protocol
主要用途	• 浏览/保存紧固履历 • 更改设置	• 输出OK/NOK信号 • 切换紧固指示	• 输出紧固履历 • 切换紧固指示
可输出数据	• 工具串行 • 时间 • OK/NOK • 扭矩值、角度值、紧固时间 • 波形数据	• OK/NOK • Batch/job/sequence完成 • Batch/job/sequence选择中 • 工具运转中	• 工具串行 • 时间 • OK/NOK • 扭矩值、角度值、紧固时间 • 波形数据
支持紧固指示切换	－	• Batch/job/sequence选择中	• Parameter/batch选择中
其他	显示使用Web浏览器 推荐Microsoft Edge	输入/输出各8端口	关于对应命令，请参见“Open Protocol支持命令一览”。 **参见P65** 控制时序请单独确认。

远程连接设置用计算机

可从安装有证书的设置用计算机经由网络远程连接控制器。
但仅有1个访问可同时访问设置功能。
连接时，请在Web浏览器中输入对象控制器的IP地址。
参见P23



与外部设备通过I/O连接

通过I/O连接

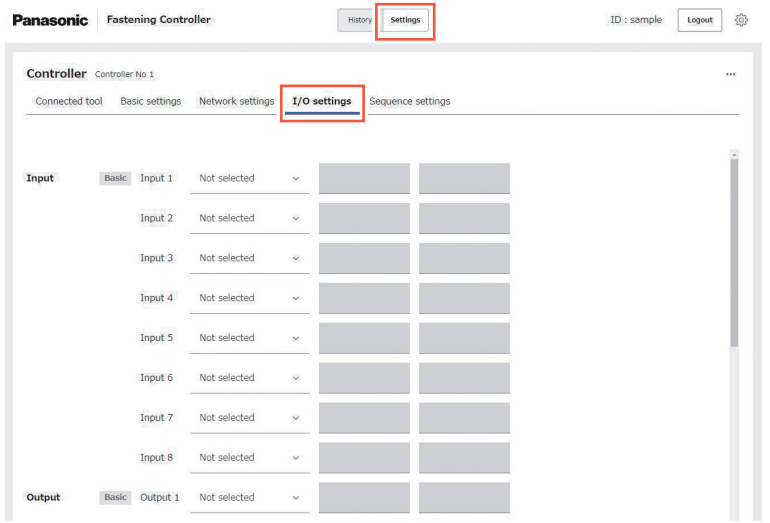
可分别向8个输入端子、8个输出端子自由分配命令。
从“I/O settings”画面进行设置。
可分配到各个端口的命令如下。

输入	可选内容
1	Batch（工具1～5） Job（工具1～5） Sequence（1～5） Batch reset（1～8） Reset Suspend tool（1～8） Suspend controller Emergency stop（1～8）
2	
3	
4	
5	
6	
7	
8	

输出	可选内容
1	OK（工具1～8） NOK（工具1～8） Batch complete（工具1～5） Job complete（工具1～5） Sequence complete（1～5） Tool active（工具1～8） Batch selected（工具1～5） Job selected（工具1～5） Sequence selected（1～5）
2	
3	
4	
5	
6	
7	
8	

设置I/O

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“I/O settings”选项卡。



※ 未设置的动作及现象也可自行分配（不包括任务选择、时序选择）

可分配到输入的命令

可分配到入力（Input端口）的命令如下。
如果外部设备已向各端口输入信号，将根据分配的命令进行紧固控制。

大项目（动作）	中项目（对象工具）	小项目（批处理No.等）
Batch	工具1-8	1-5
Job	工具1-8	1-5
Sequence	—	1-5
Suspend tool ※1	工具1-8	—
Suspend controller ※1	—	—
Batch reset	工具1-8	—
Reset	—	—
Emergency stop ※1	工具1-8	—

※1 仅在输入信号维持中启用。

“Suspend tool”或“Suspend controller”命令输入中的注意事项

- 不接收“Suspend controller”输入中的紧固指示。
- 不接收和“Suspend tool”输入中工具No.相同的工具No.的“Batch”或“Job”的紧固指示。
- 接收和“Suspend tool”输入中工具No.不同的工具No.的“Batch”或“Job”的紧固指示。
- 接收“Suspend tool”输入中的“Sequence”的紧固指示。
  此时，会一直进行控制，直至“Suspend tool”输入中的工具符合为止。
- “Batch reset”和“Reset”也和紧固指示一样处理。

在大项目中选择动作后，选择对象工具，如果还有需要，选择No.（批处理No.等）。



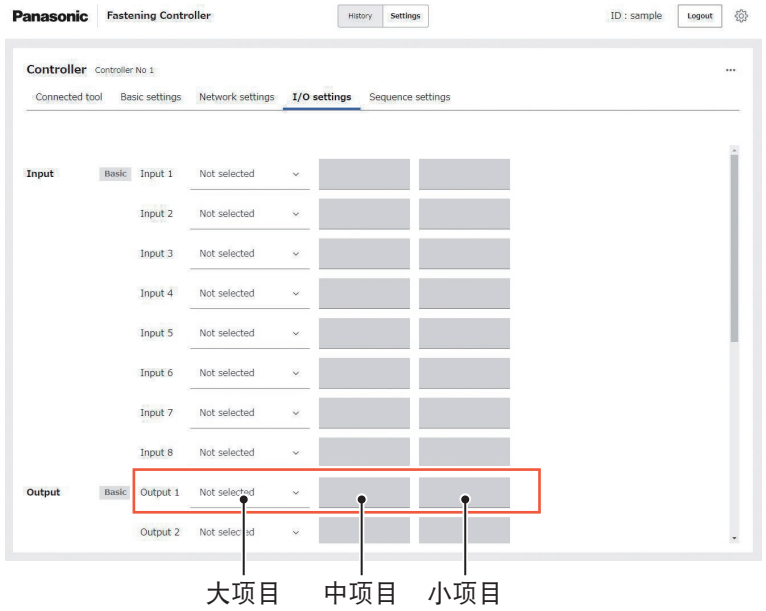
※如果输入未注册的信号，将不反应。（不出现错误）

可分配到输出的命令

可分配到输出（Output端口）的命令如下。
发生对象现象时，按分配的命令，从各端口将输出信号输出到外部设备。

大项目（现象）	中项目（对象工具）	小项目（批处理No.等）
OK	工具1-8	—
NOK	工具1-8	—
Batch complete	工具1-8	1-5
Job complete	工具1-8	1-5
Sequence complete	—	1-5
Tool active	工具1-8	—
Batch selected	工具1-8	1-5
Job selected	工具1-8	1-5
Sequence selected	—	1-5

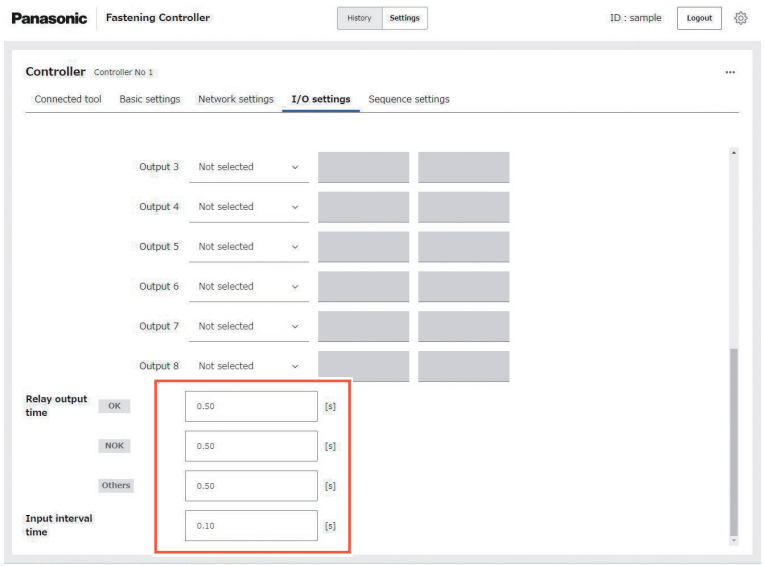
在大项目中选择现象后，选择对象工具，如果还有需要，选择No.（批处理No.等）。



※如果在输出命令中切断控制器的电源，在恢复供电后将不能从中途重新开始。（但会保存紧固履历数据）

其他设置

其他与I/O相关的设置可按以下设置。



Relay output time (OK)

选择从继电器输出紧固OK信号的时间（期间）。
[默认值]　0.5 s
[设置范围]0.01 s～10 s

Relay output time (NOK)

选择从继电器输出紧固NOK信号的时间（期间）。
[默认值]　0.5 s
[设置范围]0.01 s～10 s

Relay output time (Others)

选择从继电器输出紧固OK/NOK以外信号的时间（期间）。
[默认值]　0.5 s
[设置范围]0.01 s～10 s

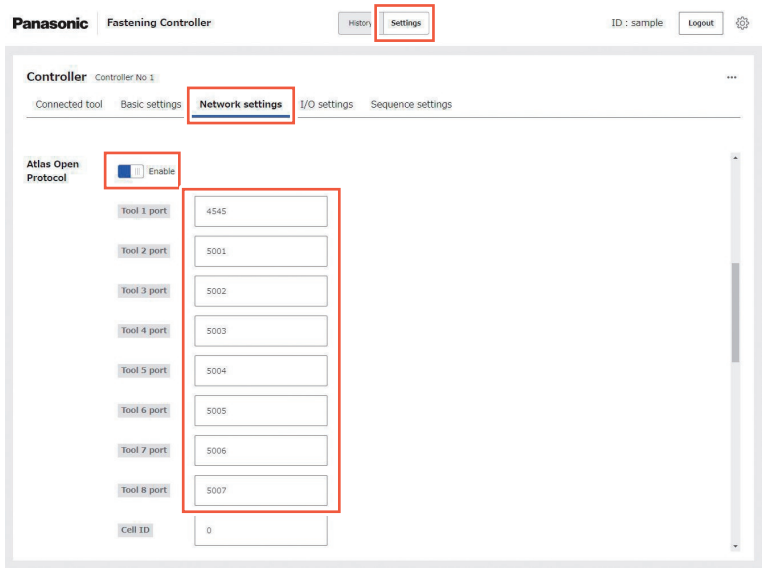
Input interval time

选择不对连续的输入信号进行计数（不受理）的时间。
用于防止因干扰等造成重复计数的设置。
[默认值]　0.1 s
[设置范围]0.01 s～10 s

通过Open Protocol通信连接

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Network settings”选项卡。

将“Atlas Open Protocol”设为“Enable”。
对要使用的工具分别设置端口No.。

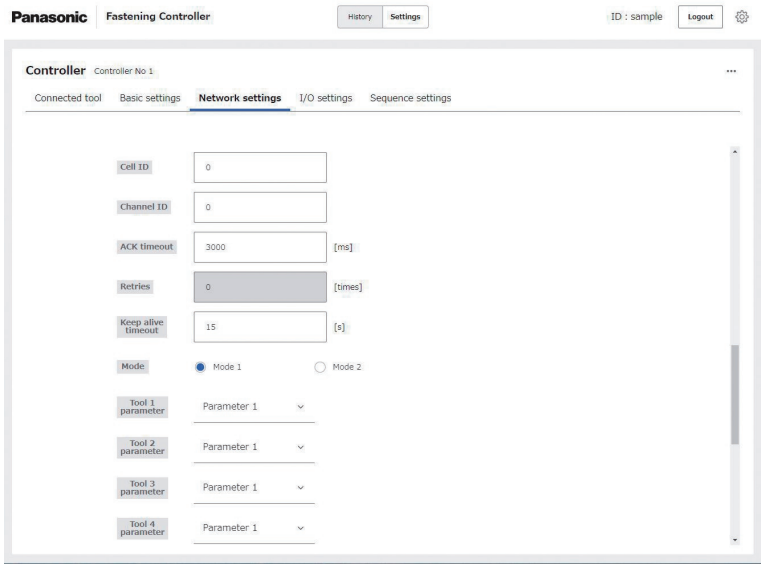


Tool port

将通过Open Protocol进行通信的端口No.按工具进行分配。
[默认值]　（Tool 1）4545
　　（Tool 2-8）5001 – 5007
[设置范围]（Tool 1-8）1024～49151

其他设置项目

根据需要设置其他的设置项目。



Cell ID

设置单元格ID。
[默认值]　0
[设置范围]0～9999

Channel ID

设置通道ID。
[默认值]　0
[设置范围]0～99

ACK timeout

设置对来自控制器发出的请求信息发送的响应等待超时时间。
[默认值]　3000 ms
[设置范围]100 ms～30000 ms

Retries

设置重新发送来自控制器的请求信息的次数。
[默认值]　0 times
[设置范围]不可更改（固定）

Keep alive timeout

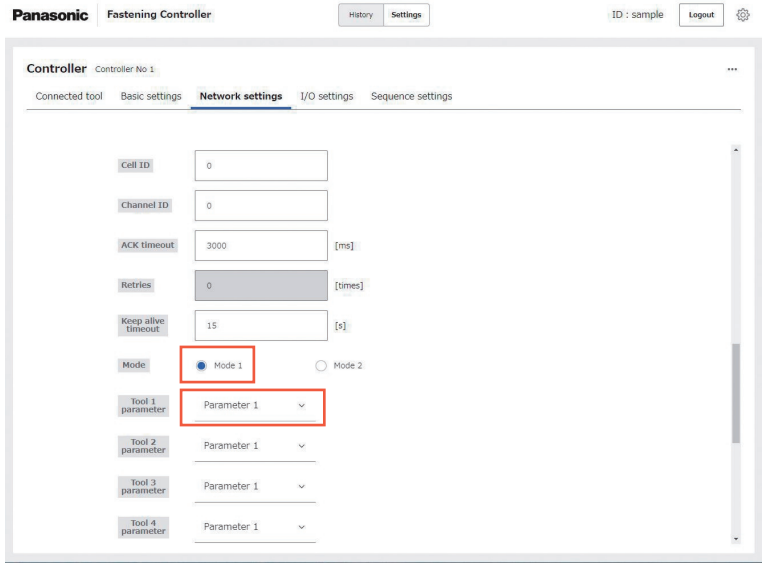
设置与上游系统的最后通信起至判断通信中断的时间。
[默认值]　15 s
[设置范围]1 s～60 s

Mode

设置动作模式。
Mode 1:按照预先注册的紧固参数进行自由紧固的模式
Mode 2:按照上游指示的紧固参数进行紧固的模式
[默认值]　Mode 1
[设置范围]Mode 1 / Mode 2

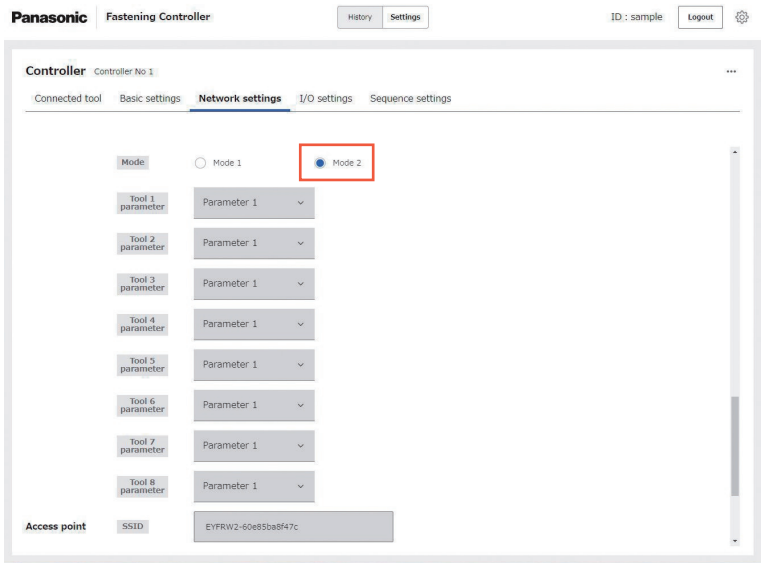
分配紧固参数（Mode 1时）

以“Mode 1”（无参数指示）使用时，需要预先针对各工具注册紧固参数。
请从下方中选择以下拉方式使用的参数。



分配紧固参数（Mode 2时）

可利用MID 0018命令从外部设备进行紧固指示。
紧固指示中可分配“Parameter”或“Batch”。



■在紧固指示中指定“Parameter”时

请将ID的第100位设为0。
10位和1位表示参数编号。

示例：参数1的ID为“001”
　　参数5的ID为“005”

■在紧固指示中指定“Batch”时

请将ID的第100位设为1。
10位和1位表示批处理编号。

示例：批处理1的ID为“101”
　　批处理5的ID为“105”

※“Job”和“Sequence”不可分配。

■Open Protocol支持命令一览

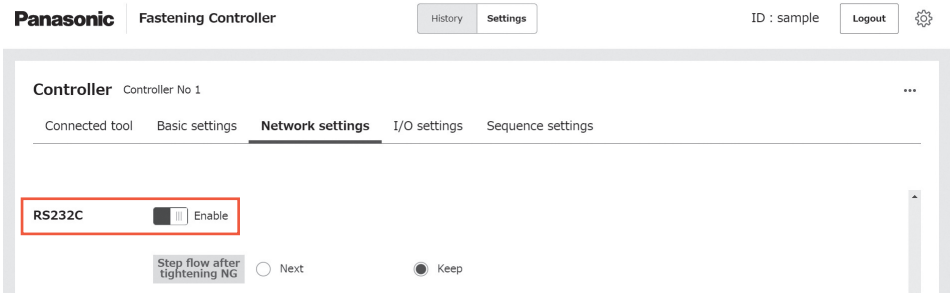
本产品支持以下命令。
有关各命令的详情，请参见Open Protocol规格书（Open Protocol Specification）。

MID 0001 Application communication start
支持Revision1。 [内容]　通信开始
MID 0002 Application communication start acknowledge
支持Revision1。 [内容]　通信响应
MID 0004 Application command error
支持Revision1。 [内容]　命令错误
MID 0005 Application command accepted
支持Revision1。 [内容]　命令接收
MID 0018 Select parameter set, Dynamic Job included
支持Revision1。 分配方法请参见“分配紧固参数（Mode 2时）”。 参见P64 [内容]　参数集指示
MID 0042 Disable tool
支持Revision1。 [内容]　不可使用工具
MID 0043 Enable tool
支持Revision1。 [内容]　可使用工具
MID 0050 Vehicle ID number download request
支持Revision1。 [内容]　车辆ID获取请求

MID 0060 Last tightening result data subscribe
支持Revision1-2。 [内容]　最终紧固结果数据注册
MID 0061 Last tightening result data
支持Revision1-2。 [内容]　紧固结果上传
MID 0062 Last tightening result data acknowledge
支持Revision1-2。 [内容]　紧固结果上传响应
MID 9999 Keep alive message
支持Revision1。 [内容]　生存确认

与外部设备通过TOYOTA MOTOR CORPORATION专用设置连接

支持从外部设备进行控制。
请在[Settings]的“Network Settings”选项卡中启用“RS232C”。

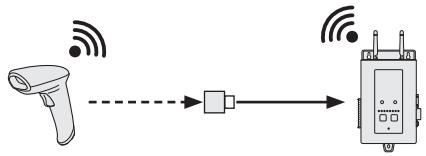


RS232C
TOYOTA MOTOR CORPORATION专用设置。设置可以从外部设备进行控制。 [默认值]　Disable [设置范围]　Disable / Enable
Step flow after tightening NG
设置紧固结果为紧固NG时是否可以执行下一次紧固。 [默认值]　Keep [设置范围]　Next（可以执行下一次紧固）/ Keep（不可执行下一次紧固）

仅支持固件版本2.03.00以上。
关于固件更新方法，请参见“更新固件”。
参见P95

使用方法

可以连接市售的条形码阅读器，将读取信息保存至紧固履历数据中。
可以将产品信息与紧固履历相关联。

连接方法	通信方式	详情
	2.4 GHz无线通信或Bluetooth	• 读取产品信息（生产序列号等），保存为紧固履历数据。

请勿使用有线USB条形码阅读器。

对象设备

可以连接并使用在本产品上的条形码阅读器的规格如下。

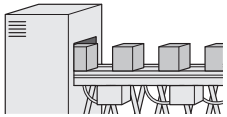
项目	规格
通信接口	USB-HID
键盘布局	US
支持字符	半角英文数字、符号 支持字符：半角数字 0-9；半角字母 A-Z, a-z；符号 !"#$%&'()*+,-./:;<=>?@[¥]^_`{|}~ 字符内容（构想信息）
可读取的一维码	JAN、EAN、UPC、CODE39、ITF
可读取的二维码	二维码模型1/2、微型二维码
可读取的字符数	最大100字符

推荐机型
Bluetooth：　Honeywell产Xenon XP 1952g、ZEBRA产DS2278

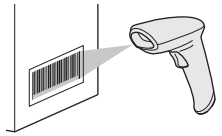
作业流程

按照以下步骤进行作业，可以将产品信息保存至紧固履历数据中。

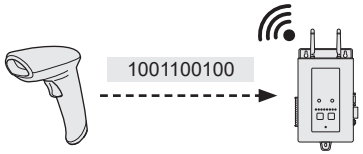
1 **产品流动过来**



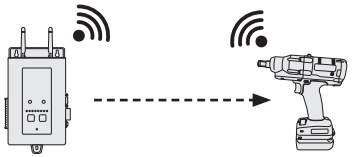
2 **使用条形码阅读器读取产品信息**



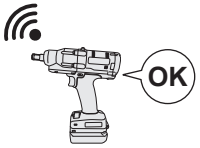
3 **条形码阅读器读取的信息被发送到控制器**



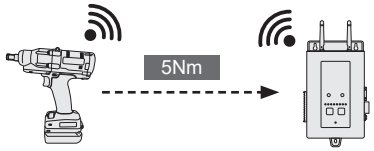
4 **控制器向工具发送紧固指示**
※ 可能会与步骤3调换顺序。



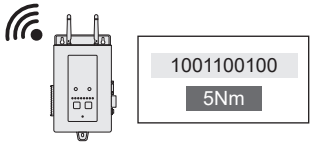
5 **工具进行紧固作业**



6 **紧固结果（扭矩等）被发送到控制器**



7 **控制器中暂存的读取信息与紧固结果关联起来，被保存至存储器中**



8 **重复步骤5～7，直到读取到新的条形码读取信息（或作业结束）**

设置方法

根据条形码阅读器的规格不同，设置方法不同。

■ 2.4 GHz无线通信（有专用无线接收器）

请按照以下步骤进行连接。
（无需执行步骤2～3）

■ Bluetooth通信（无专用无线接收器）

请另行准备Bluetooth无线接收器，按照以下步骤进行连接。

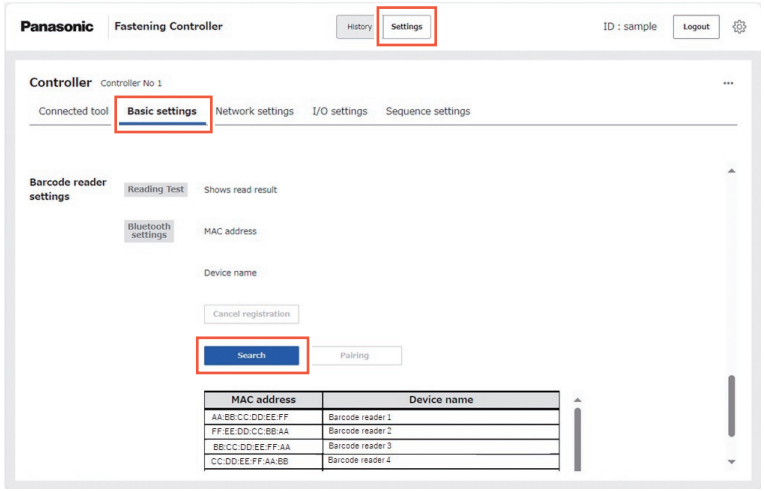
可使用的Bluetooth无线接收器

- 支持Bluetooth版本：Ver4.0
- 支持Linux操作系统（但仅限于不需要专用驱动程序的版本）

推荐机型
EDIMAX BT-8500

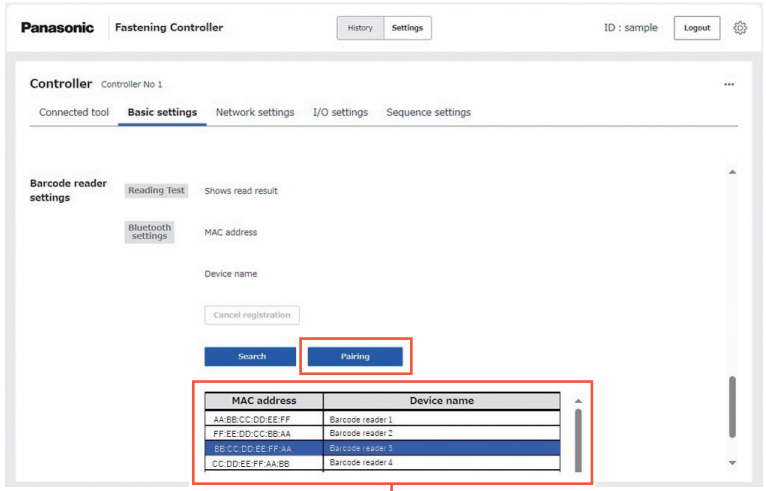
1 **将条形码阅读器的无线接收器连接在控制器的USB-A端口上**

2 **单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡，单击“Barcode reader settings”的[Search]**
※ 请根据条形码阅读器的规格，将之设置为配对模式。



3 在设备名称列表中选择要连接的条形码阅读器，按下 [Pairing]

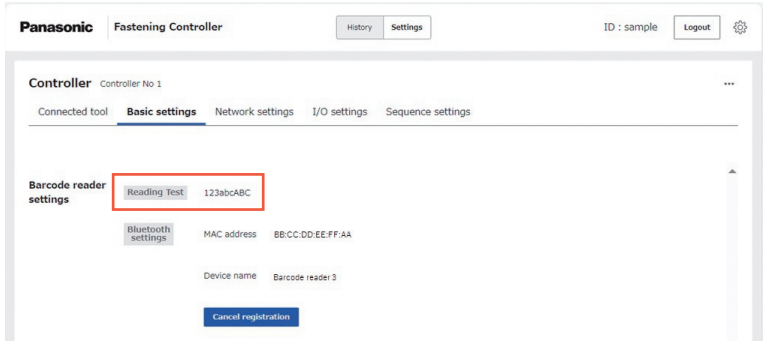
本产品将与条形码阅读器配对。



设备名称列表

- 搜索操作将持续约10秒。
- 配对注册后，下一次使用时将自动连接。
  ※根据条形码阅读器的规格，可能需要重新配对。
  ※如果配对未建立，请先在控制器端进行配对解除操作，然后重新进行配对操作。

4 确认条形码信息被读取，“Reading Test”中显示正确的信息

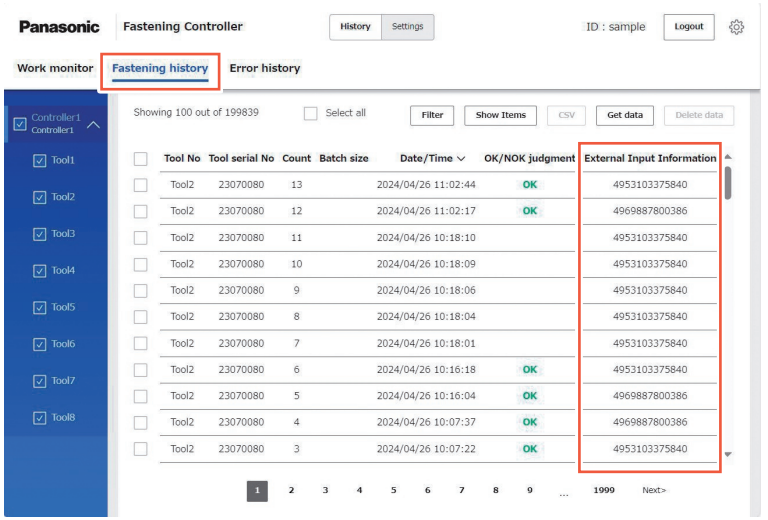


5 条形码阅读器读取到信息后，进行紧固作业

读取信息显示在紧固履历数据的“External Input Information”中。

使用中注意事项

- 接收条形码读取信息状态下，“紧固OK指示灯”闪烁。
  使用中，请随时确认本产品处于接收条形码读取信息状态，进行作业。



关于读取信息的注意点

读取信息

- 将会与读取之后记录在控制器中的所有工具紧固结果相关联。
- 在控制器电源关闭时不会被保存。
- 会被新读取到的信息覆盖。
- 在以下情况时会被暂存。

Running mode	读取信息暂存条件
Free mode	暂存至读取到新的信息。
Repeat mode (Basic mode)	暂存至“Batch”/“Job”完成。 或暂存至读取到新的信息。
Repeat mode (Sequence mode)	暂存至“Sequence”完成。 或暂存至读取到新的信息。
External control mode * 利用Open Protocol进行控制	优先使用VIN信息，不使用读取信息。
External control mode * 通过I/O进行控制	暂存至“Batch”/“Job”/“Sequence”完成。 或暂存至读取到新的信息。

- 根据所使用的条形码阅读器的设备规格，与本产品连接时可能需要进行详细的设置。请充分确认所使用的设备的使用说明书和设置后，使用本功能。
- 0.5秒以内连续读取到信息时，信息会被整合，因此请间隔时间读取信息。
- 本产品上同时可以使用1台条形码阅读器。与多台条形码阅读器相连接时，可能无法正常运行。

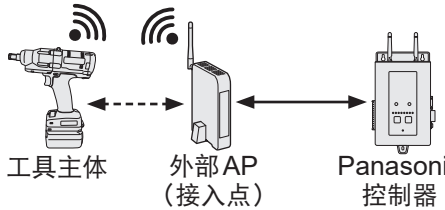
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操作

可不使用控制器内置的接入点，而使用外部接入点和工具进行无线通信。
可不受控制器安装场所的限制使用工具。
接入点和控制器请用有线LAN连接。
※无线通信距离、通信性能根据使用的接入点而异。

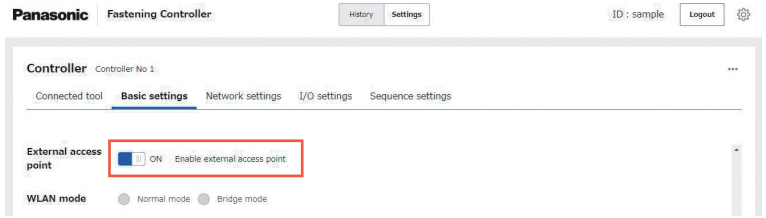
连接方法	通信方式	详情
	Ethernet	• 通过模式切换选择内置AP（接入点）/外部AP（接入点） • 最多可连接8台工具 ※内置AP（接入点）/外部AP（接入点）一样

※如果将“Tool IP”设置为“Auto (DHCP)”，可以形成不管理工具IP地址的网络构成。
参见P13

设置方法

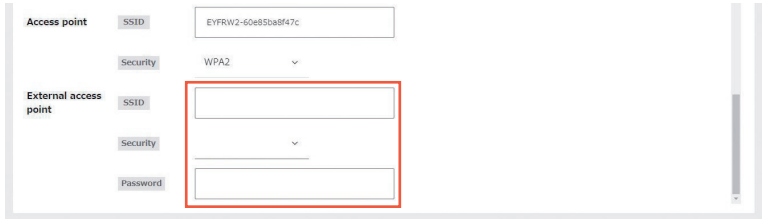
1 单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡，将“External access point”设为“ON”

※“WLAN mode”设置中“External access point”设置为ON时不在范围内。



2 单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Network Settings”选项卡，设置“Network Settings”画面中“External access point”的“SSID”、“Security”、“Password”

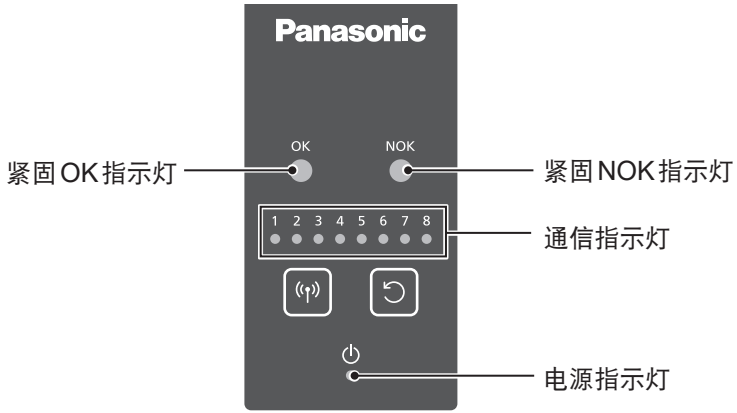
※可在控制器中注册的SSID仅有1种。（无法对每个工具进行设置）
※请参见使用的外部AP（接入点）使用说明书。
※请务必在与工具进行配对注册前设置。
※请在配对注册前设置工具IP地址。



指示灯和蜂鸣器的规格

通过指示灯和蜂鸣器提醒主体的状态。

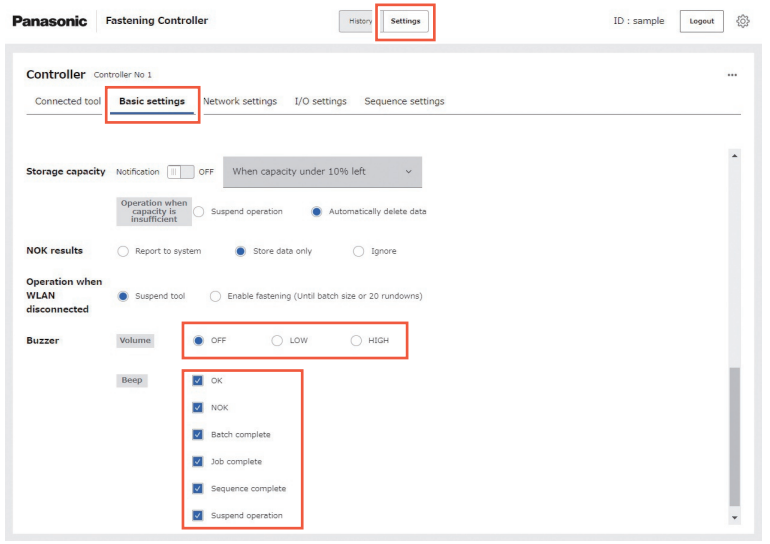
> **⚠注意**
> 开机时指示灯闪烁表示可能需要进行程序初始化，请勿关闭电源开关。



状态	指示灯	蜂鸣器
电源ON	电源（黄色）指示灯 亮灯	–
配对　工具选择中	通信（蓝色）指示灯 慢速闪烁	–
配对　连接中	通信（蓝色）指示灯 快速闪烁	–
配对完成	通信（蓝色）指示灯 亮灯	哔（短音） ■
配对未连接	通信（蓝色）指示灯 极慢速闪烁	–
配对断开	通信（蓝色）指示灯 熄灭	–
紧固OK	OK（绿色）指示灯 亮灯	哔（短音） ■
紧固NOK	NOK（红色）指示灯 亮灯	哔-（长音） ▬
Batch/job完成	OK（绿色）指示灯 闪烁2次	哔哔（短音） ■■
Sequence完成	OK（绿色）指示灯 闪烁3次	哔哔哔（短音） ■■■
发生错误	电源（黄色）指示灯 闪烁	哔-哔-（长音） ▬▬

蜂鸣器设置

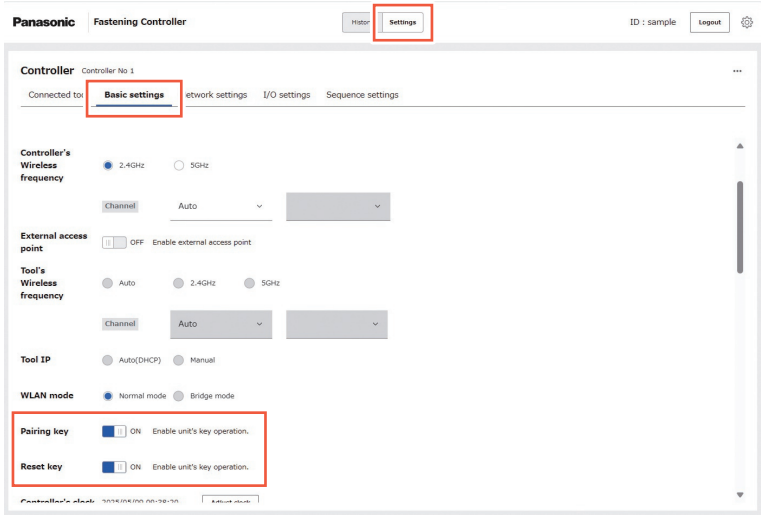
单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡。
可在“Buzzer”中设置“Volume”和“Beep”。



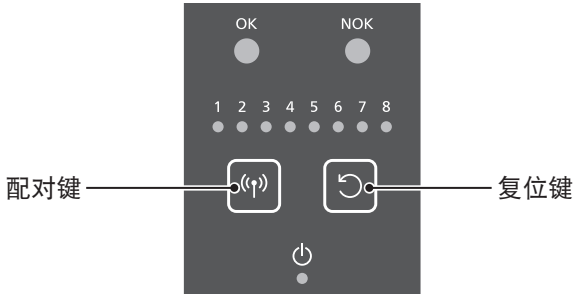
项目	规格
Volume	3档（OFF/LOW/HIGH） （LOW：75 dB、HIGH：85 dB）
Beep	从设置用计算机选择 （OK/NOK/Batch complete/Job complete/Sequence complete/Suspend operation）

操作键设置

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡。
可从“Pairing key”设置和“Reset key”设置禁用控制面板的配对键和复位键。

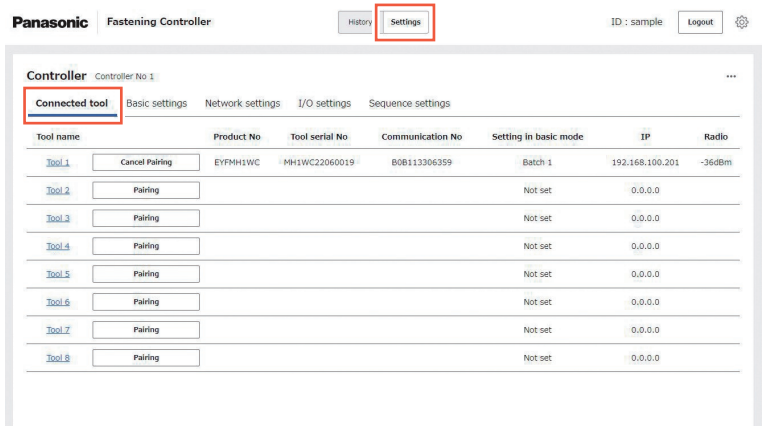


Pairing key
可以切换启用/禁用控制面板的配对键。 [默认值]　ON [设置范围]ON（启用）/OFF（禁用）
Reset key
可以切换启用/禁用控制面板的复位键。 [默认值]　ON [设置范围]ON（启用）/OFF（禁用）



确认连接工具信息

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
可确认连接到控制器的工具信息及状态。



各显示项目如下。

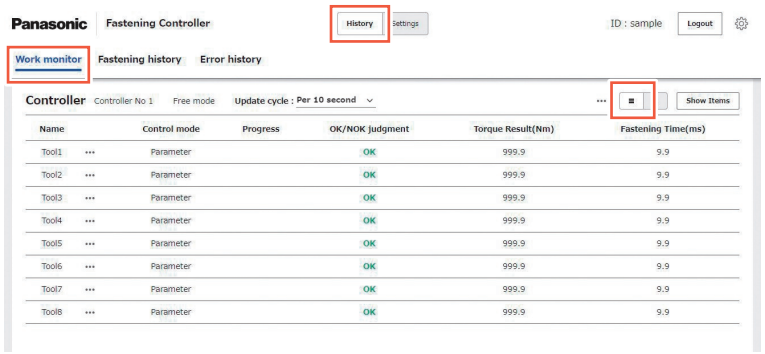
Tool name
显示注册的工具编号（No.1-8）。
Tool serial No
显示/设置工具的个体识别信息。 默认值为型号识别5位＋制造编号8位（制造年份2位＋月份2位＋生产批次4位）。
Product No
显示工具型号。
Communication No
显示工具通信部的个体识别信息（MAC地址）。
Setting in basic mode
显示将动作模式设为“Repeat mode (Basic mode)”时动作的内容。
IP
显示工具的IP地址。
Radio
显示工具发出的电波接受灵敏度（RSSI）。 ※显示最新通信时的数值。 ※由于使用外部AP时无法测量，显示为“0dBm”。

单击Home画面(设置画面初始页面)上部的[History],然后选择“Work monitor”选项卡。
可按每个工具显示最新的紧固履历。请在一边确认作业结果,一边在作业等时使用。
※也可从多台设置用计算机同时显示。(最多接入8台。帐户相同也可)
※用多个帐户登录时,建议使用其他终端。
※用同一终端使用多个帐户时,建议用其他的浏览器软件登录。
※设置更改仅1个接入有效。

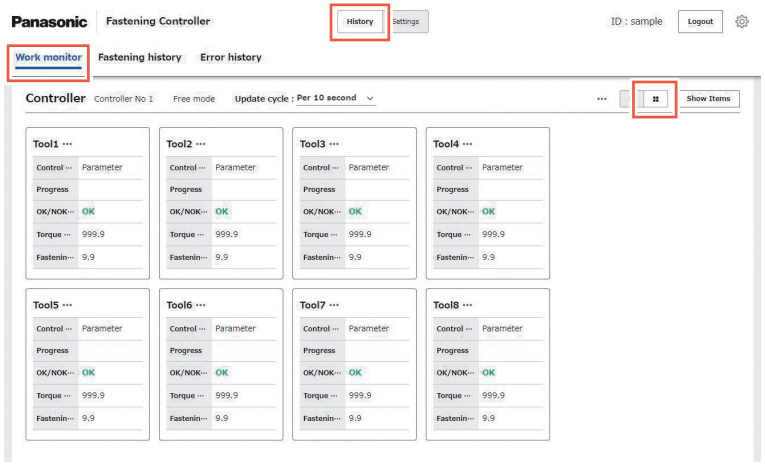
切换显示形式

可选择“列表显示”和“网格显示”。
可通过画面右上方的显示图标切换。

■列表显示

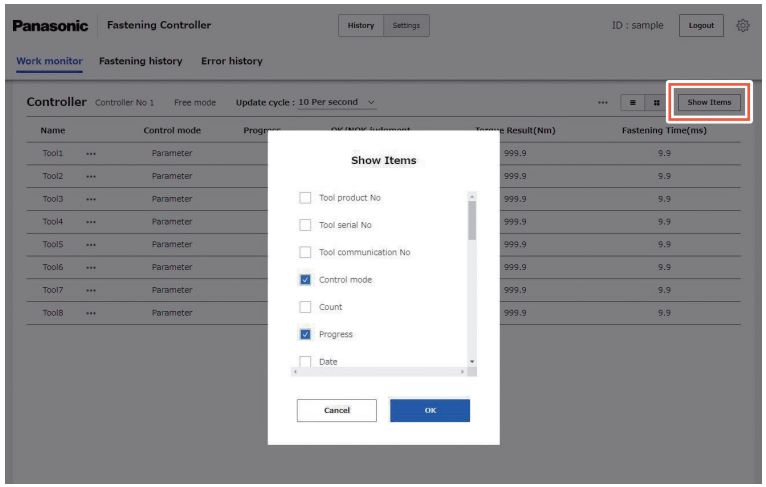


■网格显示



选择显示项目

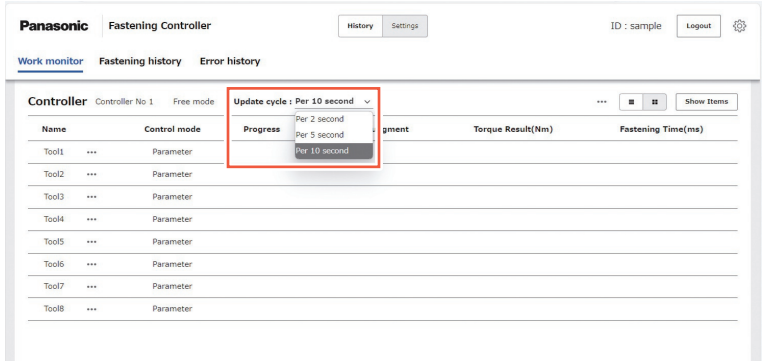
要显示的项目可从“Show Items”选择。



※设置“列表显示”时,如果显示项目较多,需要滚动。
※设置“网格显示”时,最多可显示5个项目。

更改画面更新频次

画面可进行自动更新设置。
请从以下“Per 2 second”“Per 5 second”“Per 10 second”中选择更新频次。



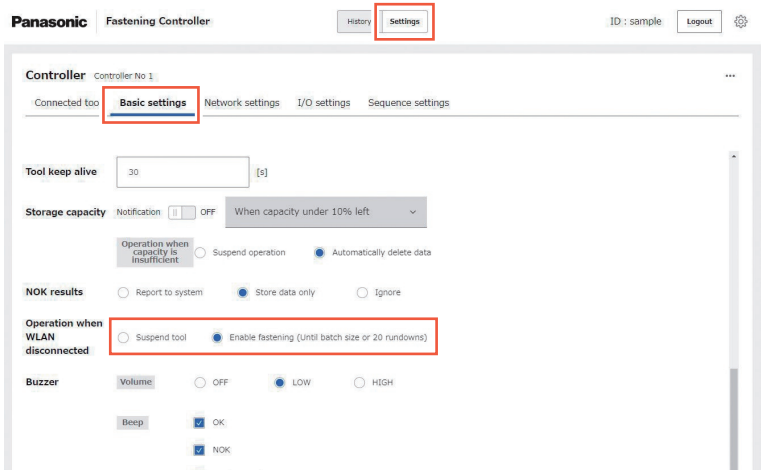
※如果连接工具台数较多,可连接的设置用计算机较多,建议将更新频次设置为“Per 10 second”。(数据处理可能需要较长时间)

无线通信中断时的工具动作

工具和控制器的无线通信暂时断开时，可允许通过同一参数继续进行紧固作业。
无线通信中断时的工具紧固结果将在“再次连接时”或“恢复通信时的作业结束时”发送到控制器。



单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Basic settings”选项卡。
将“Operation when WLAN disconnected”设置为“Suspend tool”时，通信断开后，无法在下一次紧固中进行紧固。
即使设为“Enable fastening”，达到上限紧固后依旧无法进行紧固。



“Enable fastening”时的各模式下的上限紧固数量如下。

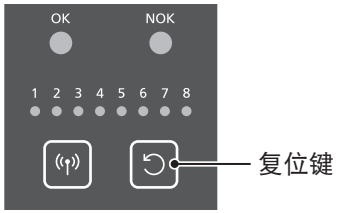
模式		动作
Free mode		最多可继续紧固20个
Repeat mode	Basic mode	可继续紧固至批处理完成，或最多20个
	Sequence mode	可继续紧固至批处理完成，或最多20个 ※非对象工具无影响
External control mode		可继续紧固至批处理完成，或最多20个

运用中的数量计数复位操作

如果在用控制器进行紧固管理中更改设置，需要先停止紧固管理。设置更改时显示确认对话框。
可用“主体按键操作”和“设置画面操作”2种方式复位数量计数。
※不包括在“Free mode”下的应用。

主体按键操作

请长按控制器主体的复位键3秒以上。
※紧固作业中的所有工具计数将被复位

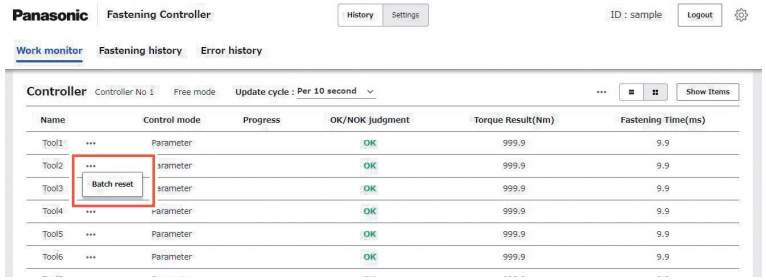


设置画面操作

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Work monitor”选项卡。

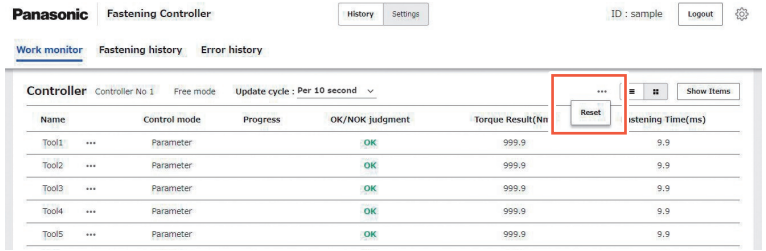
■复位每个工具时

在“Work monitor”画面中，从对象工具No.的 ⋯（工具选项键）单击[Batch reset]。



■一次性复位所有的工具时

请从“Work monitor”画面右上方的 ⋯（控制器选项键）单击[Reset]。



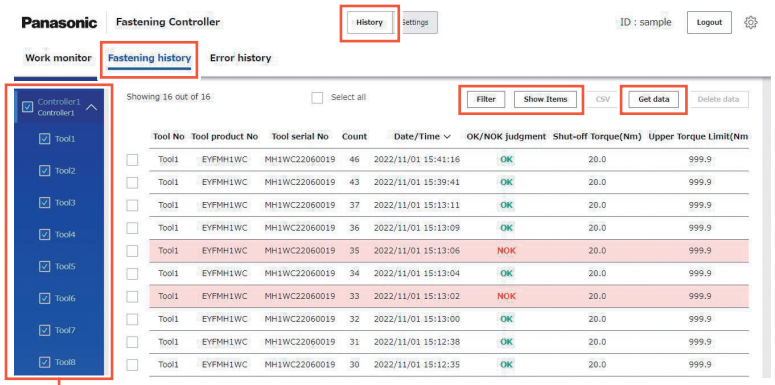
※时序模式时，复位至开头的工具。

显示紧固履历数据

单击Home画面(设置画面初始页面)上部的[History],然后选择“Fastening history”选项卡。
可浏览从工具发送到控制器的紧固履历数据。

要显示数据时,请从左侧的工具列表选择显示对象控制器/工具,然后单击右上方的[Get data]。
按新的顺序显示紧固履历数据。

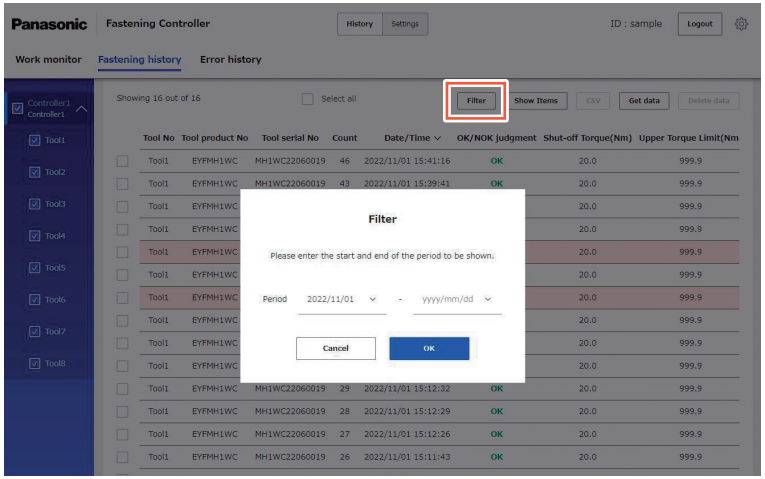
※有关紧固履历项目的内容,请参见工具主体的使用说明书。



工具列表

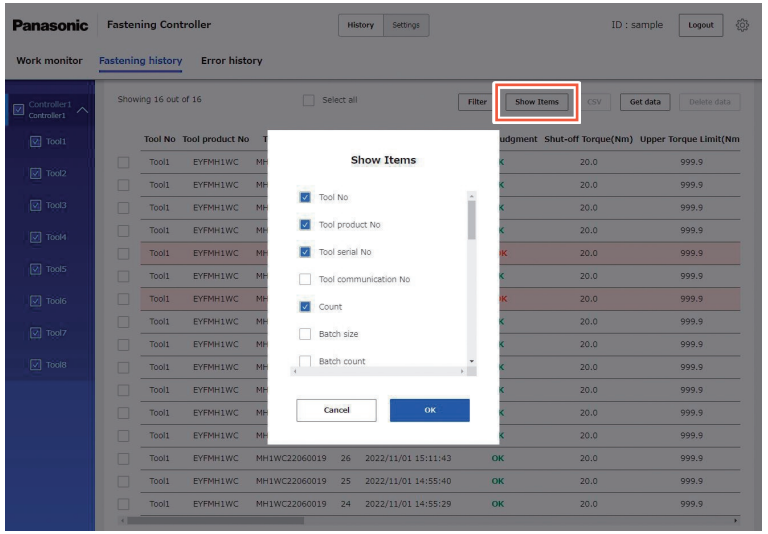
■按照日期时间提取紧固履历

单击[Filter],输入日期时间,可筛选要显示的紧固履历。



■设置显示项目

单击[Show Items],选择项目,可更改要显示的项目。



管理紧固履历数据

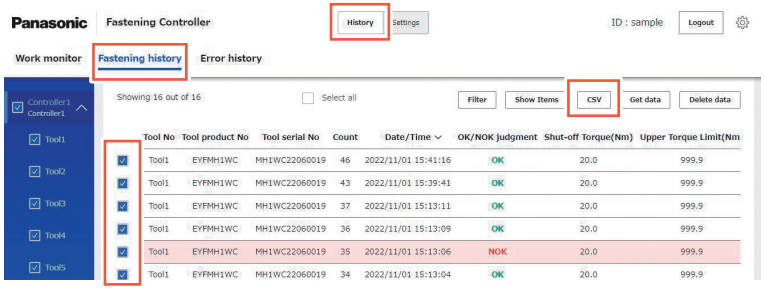
控制器中可保存的紧固履历数据(包括波形数据)大约为20万条。
如果超过该数量,则会根据设置变为“Suspend operation”或“Automatically delete data(覆盖)”。
请根据需要,按以下基准定期输出CSV。

■存储器容量达到上限的基准期限

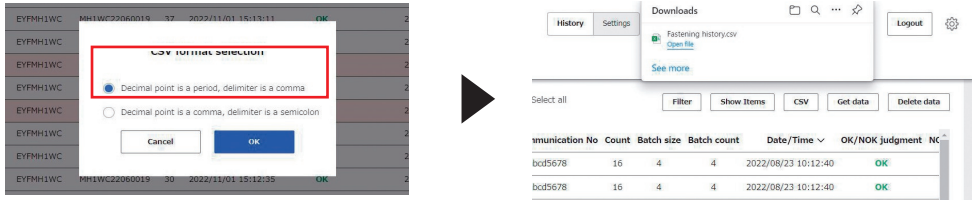
	每台工具的紧固数量/1日		
工具台数	1000条	3000条	5000条
2台	约100日	约33日	约20日
4台	约50日	约16日	约10日
8台	约25日	约8日	约5日

输出CSV紧固履历数据

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Fastening history”选项卡。
请在选择对象数据后，单击[CSV]。
可用CSV格式输出紧固履历数据。
输出的数据内容不取决于“Show Items”的设置，而是输出各工具的所有项目。

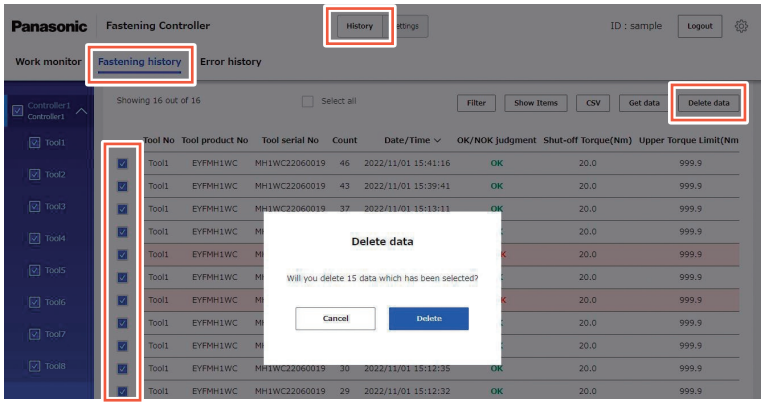


CSV格式可从“Decimal point is a period, delimiter is a comma”、“Decimal point is a comma, delimiter is a semicolon”中选择。



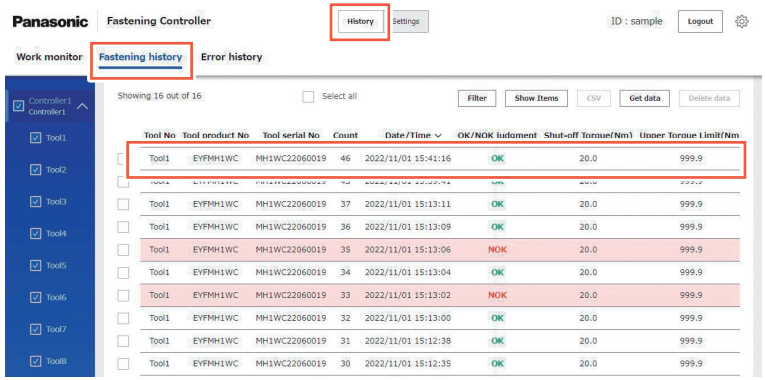
删除紧固履历数据

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Fastening history”选项卡。
请在选择对象数据后，单击[Delete data]。
可删除紧固履历数据。

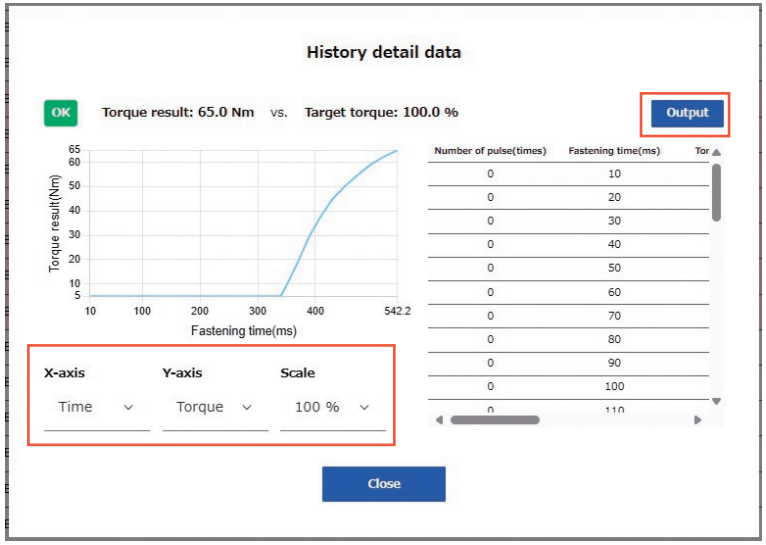


显示波形数据

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Fastening history”选项卡。
如果设置为保存波形数据，单击紧固履历中的对象履历行时，将弹出显示每个紧固的波形数据。



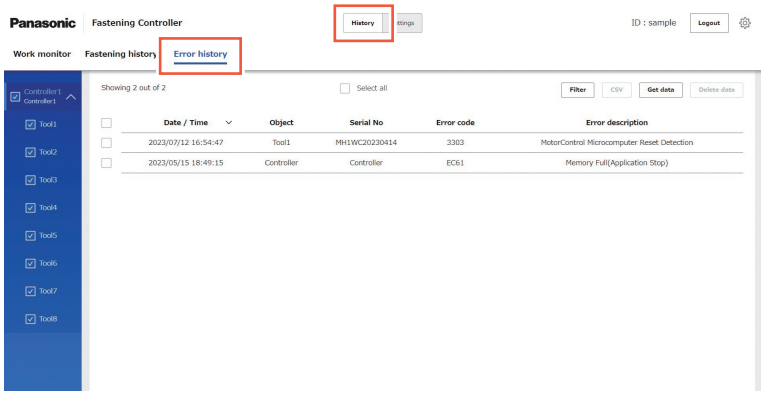
可选择“X-axis”、“Y-axis”、“Scale”进行显示。
另外也可单击[Output]，以CSV格式输出。



※ 请将“Device settings”的“Graph sending timing”设置为“After every fastening”。

显示错误履历

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Error history”选项卡。
可确认已发生错误的履历。

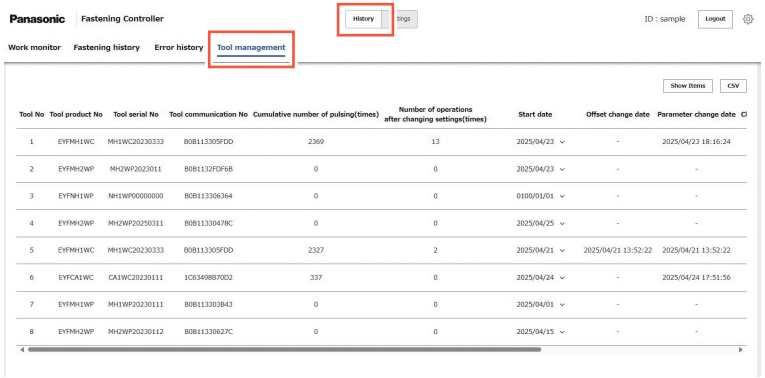


显示项目如下。
※错误代码的内容请参见“错误代码”。 参见P104

Date / Time
显示发生错误的日期/时间。
Object
显示错误的对象（控制器或工具1-8）。
Serial No
显示错误的对象（控制器或工具1-8）识别信息。
Error code
显示发生的错误代码。
Error description
显示发生的错误内容。

管理项目的显示

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Tool management”选项卡。
可以确认每个“Tool No”的管理项目。



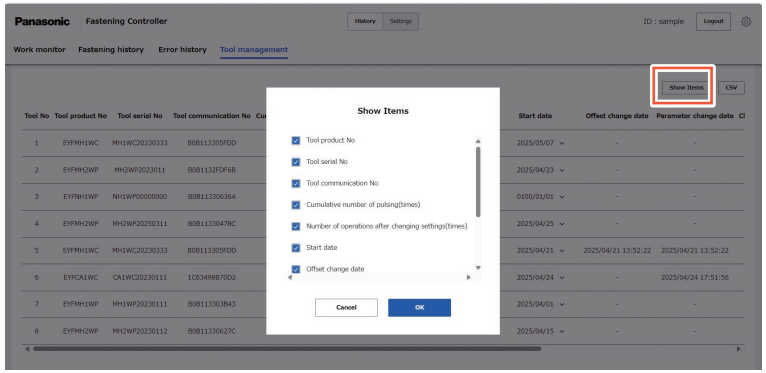
显示项目如下。
可在画面中确认最新信息。
根据工具的作业结果信息显示各项目信息。
更换工具或配对新工具时，各种信息会被清除，请注意。
※解除控制器-工具的配对时，不会被清除。

Tool product No
显示配对注册的工具型号。
Tool serial No
显示工具的个体识别信息。
Tool communication No
显示工具通信部的个体识别信息（MAC地址）。
Cumulative number of pulsing (times)
显示工具实施打击作业的累积作业次数。
Number of operations after changing settings (times)
显示更改工具设置后的累积作业次数。

Start date
设置工具的使用开始日期。仅可通过管理员帐户设置。 [设定值]　0100/01/01～9999/12/31
Offset change date
显示更改包含“Offset”的“Slope”或“Offset”的“Intercept”在内的工具设置时的日期时间。
Parameter change date
显示更改工具设置时的日期时间。
Changed parameter No
显示更改的参数No。 更改“Device settings”时，也会在该项目中显示。
Cumulative fastening time (h)
显示工具的累积作业时间。
Cumulative pulsing time (h)
显示伴有工具打击的作业累积时间。

■设置显示项目

单击[Show Items]，选择项目，可更改要显示的项目。



设置工具的使用开始日期

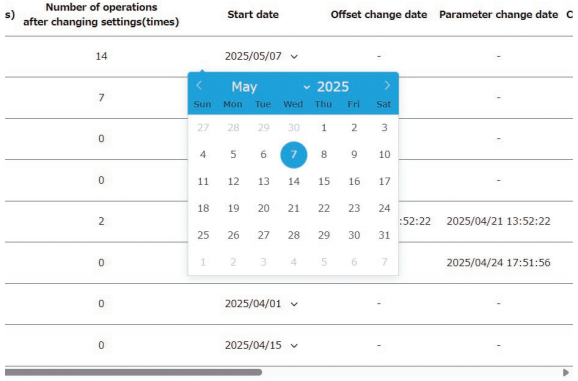
※本操作仅可通过管理员帐户实施。参见P21

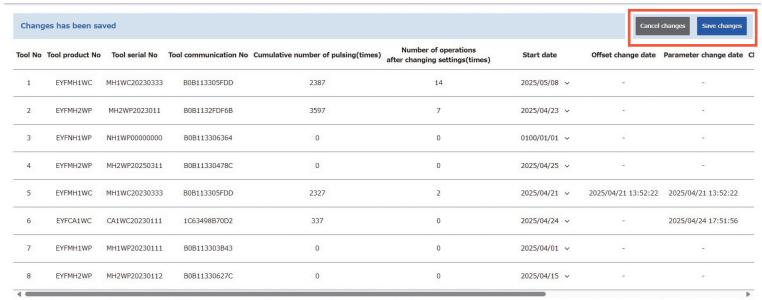
单击Home画面（设置画面初始页面）上部的[History]，然后选择“Tool management”选项卡。

请单击各工具的“Start date”项目。
可从日历格式的UI设置使用开始日期。

选择使用开始日期后，单击“Save changes”将确定更改内容。
也可在确定前修改“Start date”，或更改其他工具的“Start date”。

单击“Cancel changes”，可恢复为更改前的状态。





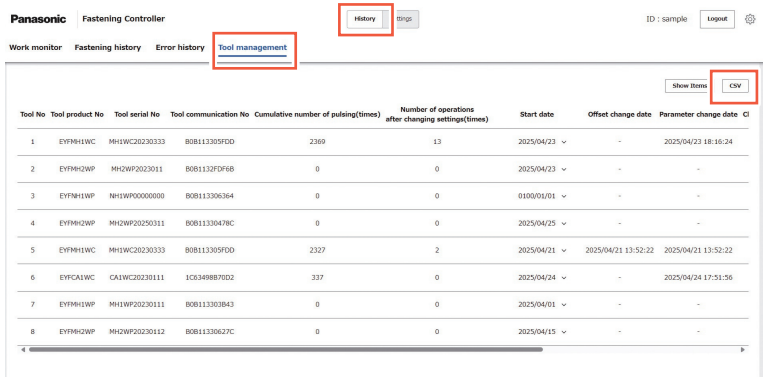
CSV输出工具管理数据

单击Home画面（设置画面初始页面）上部的[History]，然后选择“Tool management”选项卡。

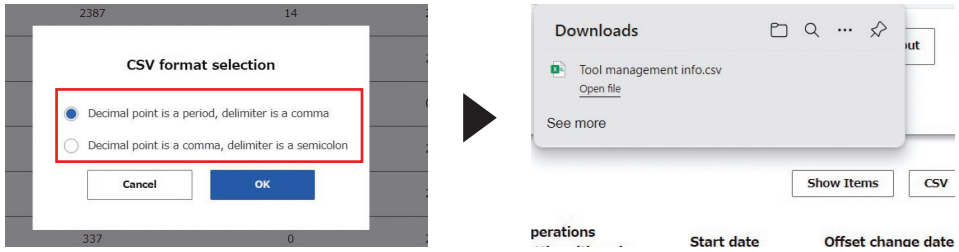
请单击“CSV”。

以CSV格式输出画面显示的数据。

输出的数据内容不取决于“Show Items”的设置，而是输出各工具的所有项目。



CSV格式可从“Decimal point is a period, delimiter is a comma”、“Decimal point is a comma, delimiter is a semicolon”中选择。

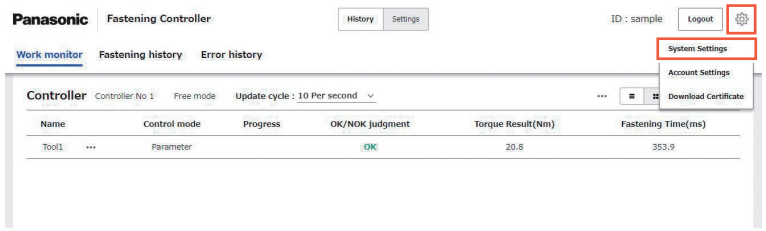


更改显示语言

显示语言可从“Japanese”或“English”中选择。

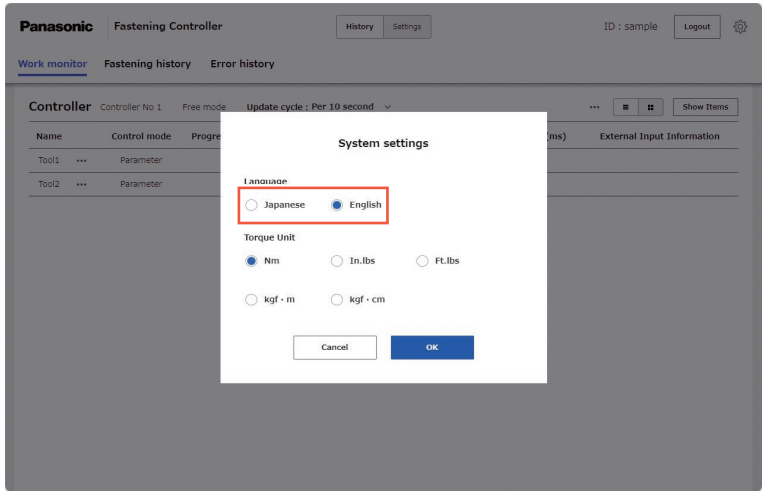
1 从Home画面（设置画面初始页面）右上方的选项键中选择“System Settings”

显示“System Settings”画面。



2 在“System Settings”画面中选择语言

可从“Japanese”或“English”中选择语言。



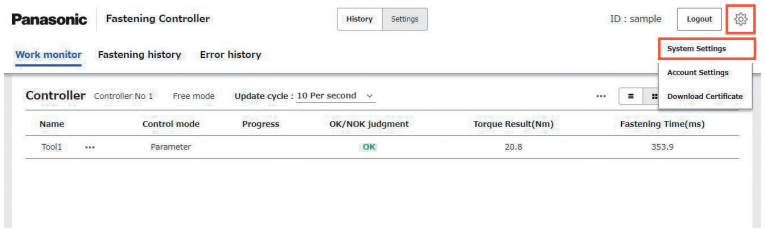
操作

更改显示扭矩单位

可从“Nm”、“In.lbs”、“Ft.lbs”、“kgf·m”、“kgf·cm”中选择显示扭矩单位。

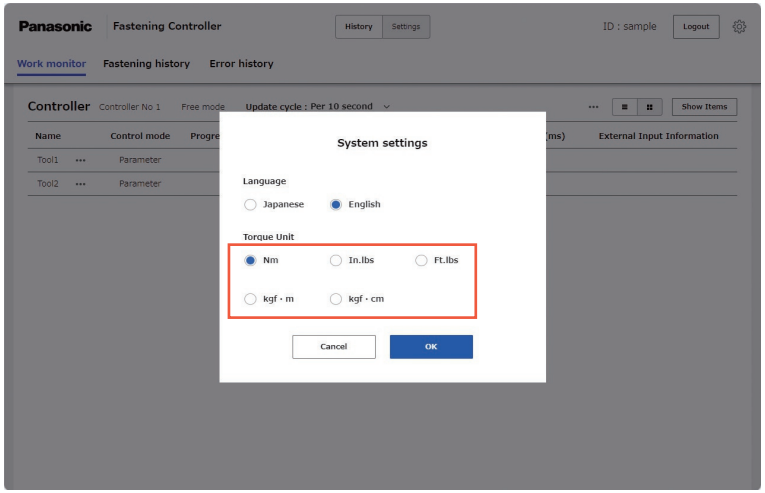
1 从Home画面（设置画面初始页面）右上方的选项键中选择“System Settings”

显示“System Settings”画面。



2 在“System Settings”画面中选择“Torque Unit”

可从“Nm”、“In.lbs”、“Ft.lbs”、“kgf·m”、“kgf·cm”中选择“Torque Unit”。



※部分单位显示下可能会发生数值修正。

维护方法

用软布擦拭

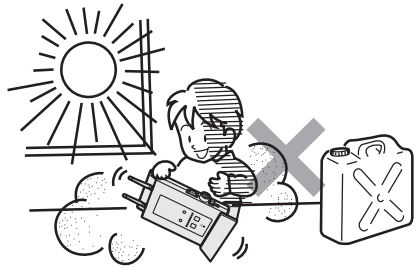
请勿使用湿布、稀释液、酒精或苯等挥发性物品。
（否则会造成变色、变形、开裂）



保管方法

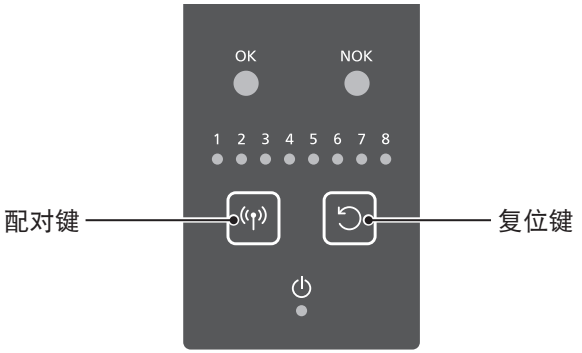
请在保管时避免以下条件。

- 车内等高温场所
- 阳光直射场所
- 水或潮湿等较多的场所
- 垃圾及粉尘较多的场所
- 儿童可触及的场所
- 有汽油等引火物的场所
- 有掉落危险的场所



初始化控制器

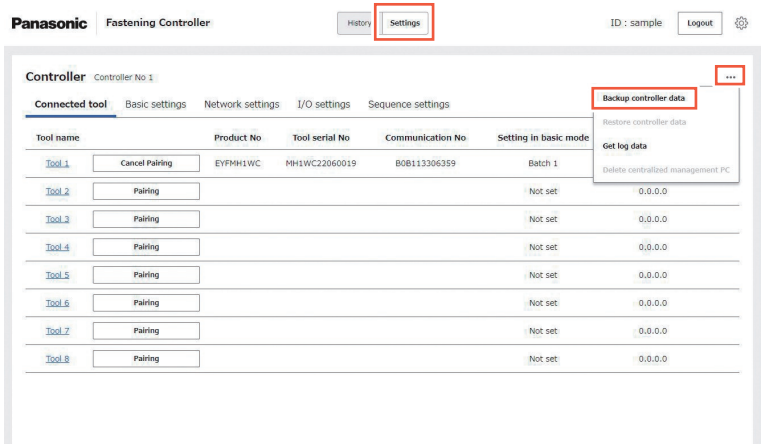
初始化控制器（恢复出厂设置）时，请同时按住配对键和复位键并保持10秒以上。



※根据存储使用容量不同，可能需要5分钟以上。
※将主体按键操作设为禁用时，无法操作。 参见P76

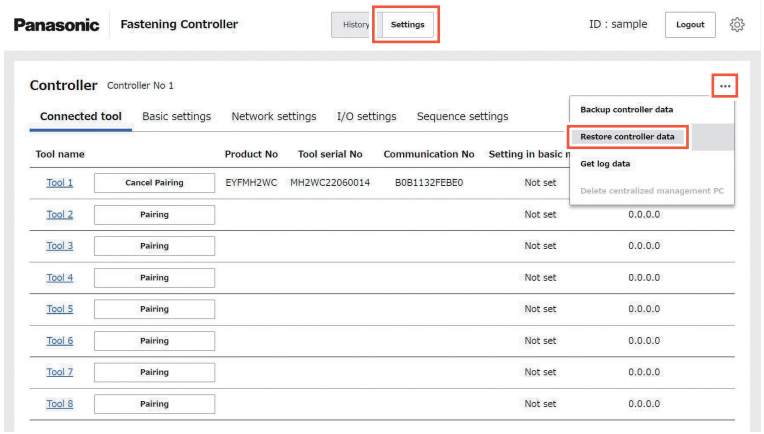
设置备份功能

请单击Home画面（设置画面初始页面）上部的[Settings]。
请从 ⋯（控制器选项键）单击[Backup controller data]。
可备份控制器的设置内容及工具的设置内容。
※紧固履历数据不可备份。需要时请输出CSV。



设置的恢复功能

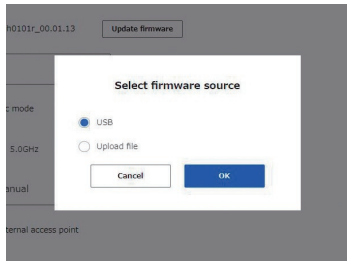
请单击Home画面（设置画面初始页面）上部的[Settings]。
请从 ⋯（控制器选项键）单击[Restore controller data]。
可从备份恢复控制器的设置内容及工具的设置内容。
※ 紧固控制中无法实施。
※ 在配对注册工具的状态下无法实施。请设为未注册状态。



更新固件

可对控制器及工具的通信部进行固件更新。

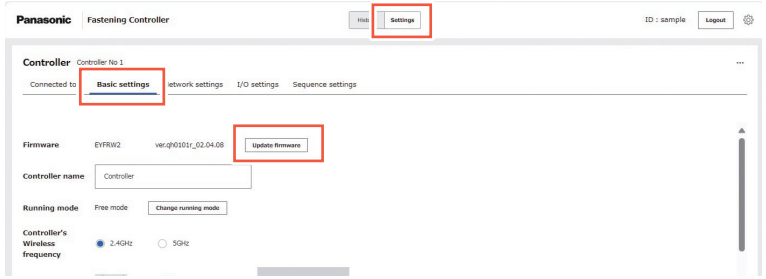
有2种方法可更新固件。
① 使用控制器USB端口
※ 不可使用带密码锁定功能的USB。
※ 请在USB存储器下保存1个固件数据。
② 从设置用计算机写入
※ “Upload file”时，请在选择画面上选择保存在计算机中的固件数据。



最新固件请确认本公司主页。 参见P2
或咨询营业负责人。

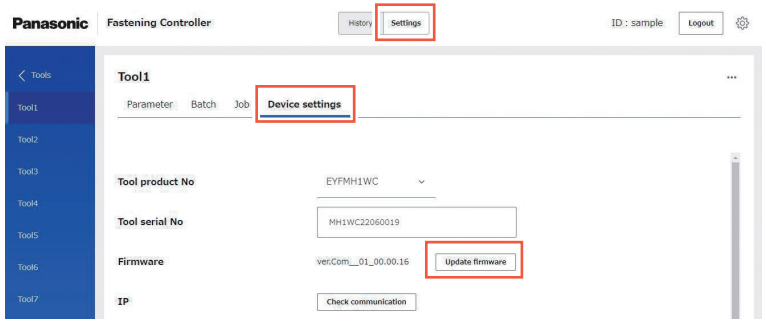
■控制器时

单击Home画面（设置画面初始页面）上部的[Settings]，然后从“Basic settings”选项卡单击[Update firmware]。



■工具通信部时

单击Home画面（设置画面初始页面）上部的[Settings]，然后选择“Connected tool”选项卡。
在“Connected tool”画面中单击对象工具No.。
请从工具No.画面的“Device settings”选项卡单击[Update firmware]。



更换纽扣电池

为维持控制器的时钟功能（RTC），请参考以下更换基准期限更换纽扣电池。

■电池类型



CR2450

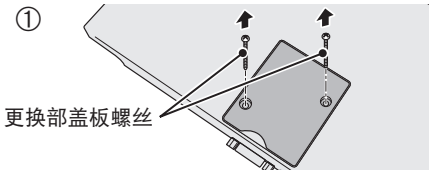
■更换基准期限

纽扣电池在电源关闭时用于维持时钟功能。
为了减少消耗，建议一般情况下不要关闭电源。

电源每天打开12小时（仅平时）	始终打开电源时
约3年	约8年

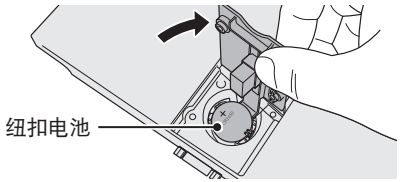
请按以下方法更换，或咨询销售店。
建议安排具备电气知识的人员来进行作业。

1 拆下更换部盖板螺丝（2颗），然后拆下更换部盖板

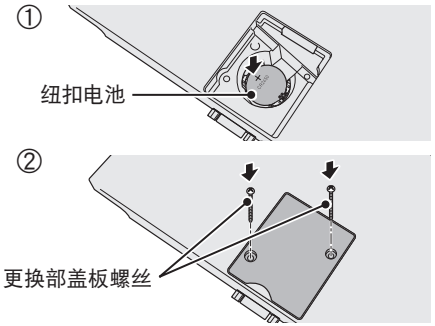


2 使用更换部盖板取出纽扣电池

请在拆下时用更换部盖板的挂钩勾住纽扣电池。

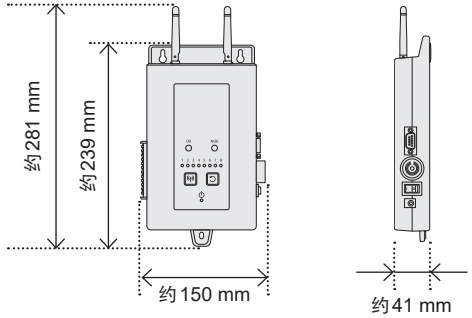


3 安装新纽扣电池，用更换部盖板螺丝（2颗）安装更换部盖板



主体规格

接收室内产品组装作业中的紧固OK/NOK信号

型号	EYFRW2
电源	AC100 V-240 V　50-60 Hz
无线通信标准	无线LAN（IEEE.802.11 a/b/g/n） n：仅限 HT20
频带	2.4 GHz频带：　2.412 GHz～2.472 GHz 5 GHz频带：　5.180 GHz～5.240 GHz [仅中国和韩国适用] 2.4 GHz频带：　2.412 GHz～2.462 GHz 5 GHz频带：　5.180 GHz～5.240 GHz
通道	2.4 GHz频带：　1～13通道 5 GHz频带：　36、40、44、48通道 [仅中国和韩国适用] 2.4 GHz频带：　1～11通道 5 GHz频带：　36、40、44、48通道
通信范围	使用2.4 GHz时：约16 m　使用5 GHz时：约10 m
可注册工具数	最多8台
输入输出端子（I/O）	输入8点　输出8点
I/O输入端子额定值	DC24 V　5 mA
I/O输出端子额定值	DC30 V　3 A
I/O电源额定值	DC24 V　50 mA
功率	约30 W
使用温湿度范围	0 ℃～45 ℃　20%～90%
大小（大概尺寸） 全长×全高×宽度	约150×239×41 mm（含天线高度：约281 mm） 
质量（重量）	约550 g（仅主体）
通信接口	Ethernet×2、RS232C×1、USB-A×1
保存数据条数	紧固履历 约200,000条（包含波形数据）
适用工具机型	EYFMH1WC、EYFMH2WC、EYFNH1WC ※1、EYFCA1WC ※2

※1 仅支持固件版本2.02.00以上。
※2 仅支持固件版本2.04.00以上。

• 请参阅最新总目录。

无线规格

每个通道的频率

频带	通道	频率
2.4 GHz频带	通道 1	2.412 GHz
	通道 2	2.417 GHz
	通道 3	2.422 GHz
	通道 4	2.427 GHz
	通道 5	2.432 GHz
	通道 6	2.437 GHz
	通道 7	2.442 GHz
	通道 8	2.447 GHz
	通道 9	2.452 GHz
	通道 10	2.457 GHz
	通道 11	2.462 GHz
	通道 12	2.467 GHz
	通道 13	2.472 GHz
5 GHz频带	通道 36	5.180 GHz
	通道 40	5.200 GHz
	通道 44	5.220 GHz
	通道 48	5.240 GHz

• 通道12和13不可在中国和韩国使用。

WebUI规格

支持操作系统	Windows10以上（支持以下浏览器的操作系统）
支持浏览器	Microsoft Edge版本102以上 或Google Chrome版本102以上
支持语言	日语/英语
推荐屏幕分辨率	1024×768以上

注意

- 部分计算机即使满足运行环境也无法使用。
- 根据所用计算机的使用环境不同，本书的说明内容、画面和实际的内容、画面或有差异，敬请谅解。
- 本书的内容如有更改，恕不另行通知。
- 禁止擅自转载本书内容的部分或全部。
- 本书中的Windows操作说明使用Windows10中的步骤及画面。
- 除支持操作系统中所列的操作系统之外，不可使用“WebUI功能”。
- 不保证推荐环境中的所有计算机均可正常运行。

■操作（务必阅读）

＜限制事项＞
“WebUI功能”为EYFRW2的设置用软件。

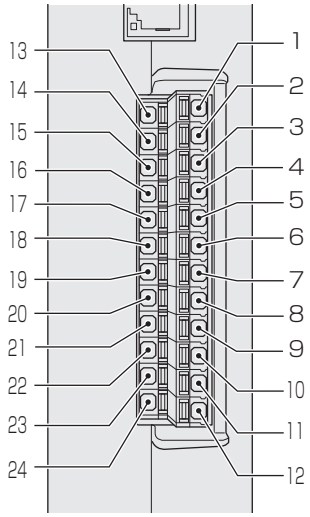
注意

- 使用本功能时，请注意以下几点。
  使用时，视为同意以下【使用条件】。

【使用条件】
本公司不对本功能进行任何保证。
本公司对使用本功能或动作导致的直接损失、间接损失、波及损失、结果损失或特别损失概不负责。
本公司禁止转载及发布本功能。

触点I/O规格

■输出继电器和输入端子的分配



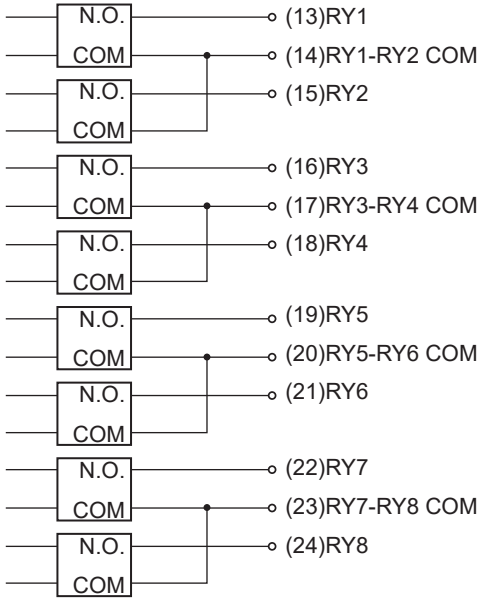
IN:输入　RY:输出

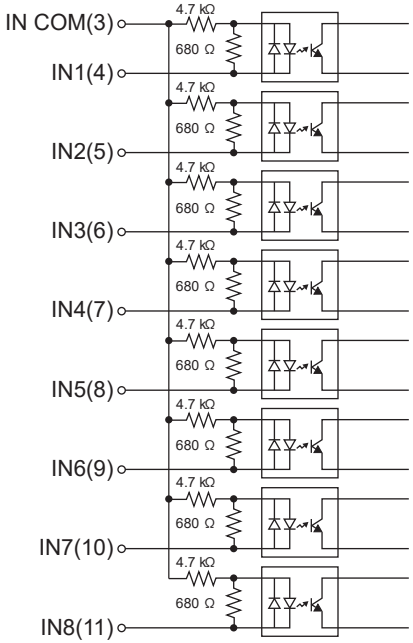
编号	引脚排列
1	24 V输出（+）※
2	24 V输出（+）※
3	IN COM
4	IN 1
5	IN 2
6	IN 3
7	IN 4
8	IN 5
9	IN 6
10	IN 7
11	IN 8
12	24 V输出（-）※

编号	引脚排列
13	RY1
14	RY1-RY2 COM
15	RY2
16	RY3
17	RY3-RY4 COM
18	RY4
19	RY5
20	RY5-RY6 COM
21	RY6
22	RY7
23	RY7-RY8 COM
24	RY8

※ 可向外部设备供应24 V电源。
端子1、2可分别并联使用。

■端子台连接图





[中国大陆]

（一）符合“微功率短距离无线电发射设备目录和技术要求”的具体条款和使用场景，采用的天线类型和性能，控制、调整及开关等使用方法；

（二）不得擅自改变使用场景或使用条件、扩大发射频率范围、加大发射功率（包括额外加装射频功率放大器），不得擅自更改发射天线；

（三）不得对其他合法的无线电台（站）产生有害干扰，也不得提出免受有害干扰保护；

（四）应当承受辐射射频能量的工业、科学及医疗（ISM）应用设备的干扰或其他合法的无线电台（站）干扰；

（五）如对其他合法的无线电台（站）产生有害干扰时，应立即停止使用，并采取措施消除干扰后方可继续使用；

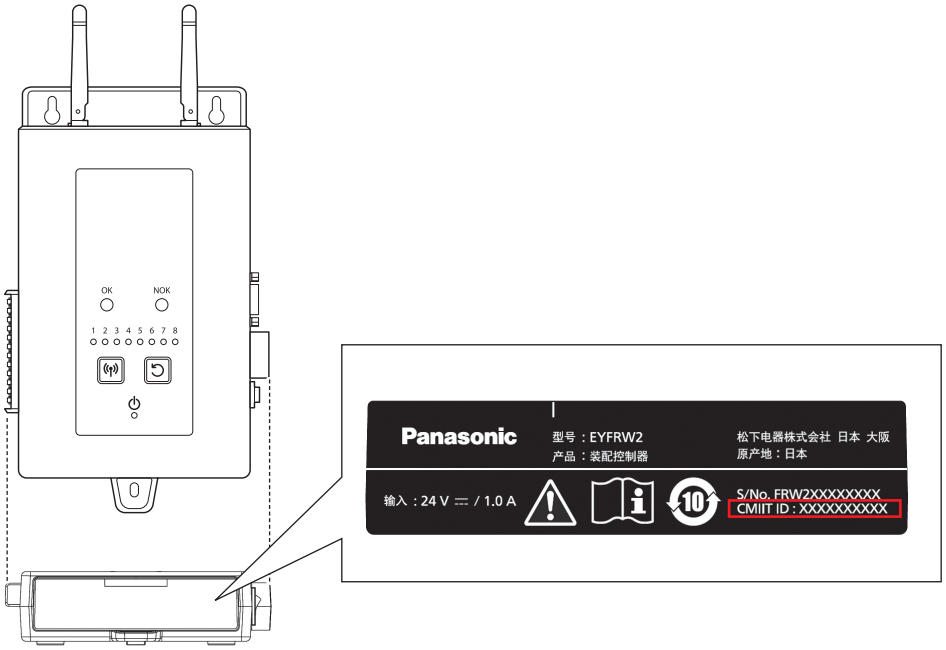
（六）在航空器内和依据法律法规、国家有关规定、标准划设的射电天文台、气象雷达站、卫星地球站（含测控、测距、接收、导航站）等军民用无线电台（站）、机场等的电磁环境保护区域内使用微功率设备，应当遵守电磁环境保护及相关行业主管部门的规定；

（七）禁止在以机场跑道中心点为圆心、半径 5000 米的区域内使用各类模型遥控器；

（八）微功率设备使用时温度和电压的环境条件。

无线认证（续）

■CMIIT ID表显示位置



（底部）

■无线规格

无线通讯标准	无线网络（IEEE 802.11 a/b/g/n） n：仅限 HT20
频带	频带 2.412 GHz - 2.462 GHz / 5.180 GHz – 5.240 GHz
通道数	通道数 2.4 GHz频段：1ch – 11ch 5 GHz频段：36ch, 40ch, 44ch, 48ch

■无线电功能角色：
工具和控制器之间的无线配对
也　双向数据通讯（对刀信息、拧紧工作结果等）

许可规定

软件许可规定

本产品由以下类型的软件构成。

(1) Panasonic（株）（Panasonic）自主开发的软件
(2) 第三方持有并授权给Panasonic的软件
(3) 根据GNU GENERAL PUBLIC LICENSE Version1.0 (GPL V1.0)授权的软件
(4) 根据GNU GENERAL PUBLIC LICENSE Version2.0 (GPL V2.0)授权的软件
(5) 根据GNU GENERAL PUBLIC LICENSE Version3.0 (GPL V3.0)授权的软件
(6) 根据GNU LESSER GENERAL PUBLIC LICENSE Version2.1 (LGPL V2.1)授权的软件
(7) 根据GNU LESSER GENERAL PUBLIC LICENSE Version3.0 (LGPL V3.0)授权的软件
(8) 根据SMAIL GENERAL PUBLIC LICENSE (SMAIL)授权的软件
(9) 根据Mozilla Public License Version 1.1 (MPL V1.1)授权的软件
(10) 根据Mozilla Public License Version 2.0 (MPL V2.0)授权的软件
(11) 根据GPL V1.0 GPL V2.0 GPL V3.0、LGPL V2.1 LGPL V3.0 SMAIL MPL V1.1 MPL V2.0之外的条件授权的开源软件

对于属于上述(3)~(11)的软件，虽基于其可能有用的意图而发布，但本公司不就此作出任何保证，包括关于“商品性”或“针对特定用途的适用性”的默示保证。

关于著作权者的信息及许可详情，请参见P.109以后。

自本产品发售之日起至少3年内，Panasonic将向联系以下咨询窗口的第三方提供依据GPL V1.0 GPL V2.0 GPL V3.0、LGPL V2.1 LGPL V3.0 SMAIL或规定有义务公开源代码的其他条件授权软件相对应的机器可读完整源代码以及各自的著作权者信息，费用按实际情况收取。请联系使用说明书中的“电器设备资材产品咨询窗口”。

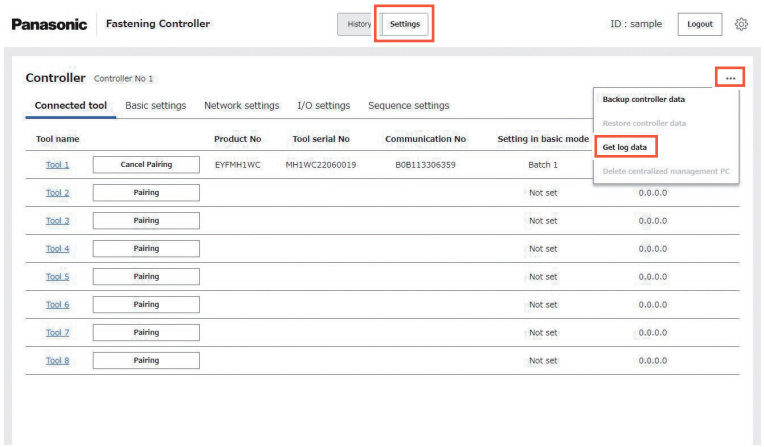
Contact Information: oss-cd-powertools-gl@ml.jp.panasonic.com

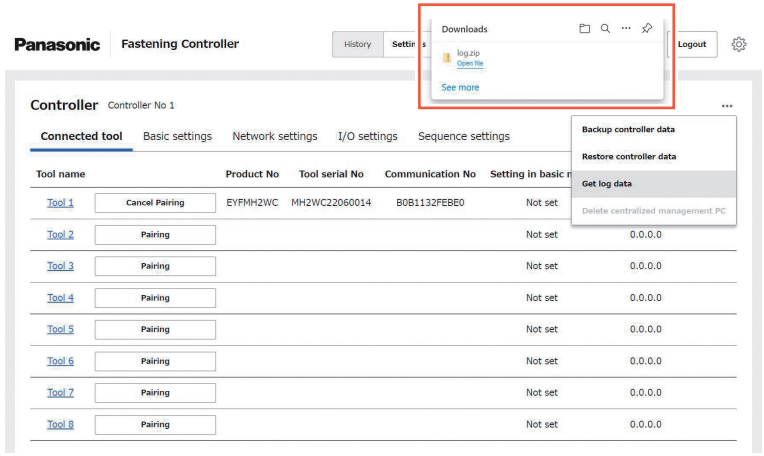
对象	错误代码	区分	分类	发生现象	处理方法
控制器	0xEF21	警告	硬件异常	副CPU异常（故障）	请重启控制器。 如未消除，可能是设备故障，请咨询销售店。
	0xEF51	警告	硬件异常	Ether0异常	可能是设备故障，请咨询销售店。
	0xEF52	警告	硬件异常	Ether1异常	可能是设备故障，请咨询销售店。
	0xEF61	警告	硬件异常	WLAN模块异常（故障）	请重启控制器。 如未消除，可能是设备故障，请咨询销售店。
	0xCE42	错误	软件异常	设置信息异常	请将控制器恢复出厂设置后再进行设置。
	0xCE43	错误	软件异常	保存信息异常	请长按控制器的复位键3秒以上。
	0xEC61	警告	软件异常	紧固履历区域剩余空间用尽（动作停止）	请从紧固履历画面删除紧固履历数据，确认可用空间。 请根据需要，在删除数据前进行备份。
工具	0x4301	注意	软件异常	达到存储上限	请连接到工具设置软件（Tool Manager软件）后删除作业履历。
	0x4302	注意	软件异常	达到未发送结果累积上限	由于工具无法与控制器进行通信， 请移动作业场所。 如未消除，可能是设备故障，请咨询销售店。
	0x3303	错误	软件异常	电机控制微机复位检测	发生错误，已消除。
	0x3304	错误	软件异常	扭矩运算微机复位检测	发生错误，已消除。

对象	错误代码	区分	分类	发生现象	处理方法
工具	0x4305	注意	软件异常	RTC电池余量低	请更换工具主体内部的纽扣电池。
	0x4306	注意	软件异常	FW更新异常	请确认固件文件是否正确。
	0x4315	注意	软件异常	USB通信错误	发生错误，已消除。
	0x4316	注意	软件异常	WLAN模块重启	发生错误，已消除。
	0x1401	警告	硬件异常	WLAN模块异常	发生错误，已消除。
	0x1402	警告	硬件异常	电机控制微机异常	发生错误，已消除。
	0x1403	警告	硬件异常	扭矩运算微机异常	发生错误，已消除。
	0x1404	警告	硬件异常	外置Flash异常	发生错误，已消除。
	0x1405	警告	硬件异常	RTC异常	发生错误，已消除。
	0x1406	警告	硬件异常	电路识别异常	发生错误，已消除。
	0x1407	警告	硬件异常	Swap空间用尽	发生错误，已消除。
	0x1408	警告	硬件异常	参数空间损坏	发生错误，已消除。

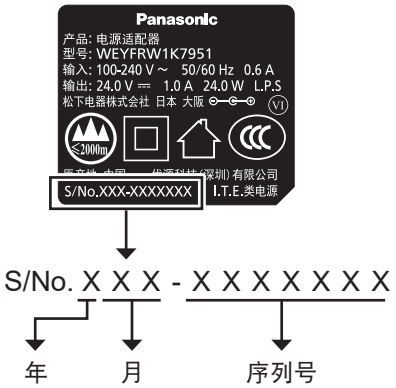
动作日志数据

请单击Home画面(设置画面初始页面)上部的[Settings]。
请从 ⋯(控制器选项键)单击[Get log data]。
可获取控制器的动作日志信息。





交流适配器制造日期说明



自2010年起的序列号,年份标示如下:

例:

2022/11 .....N11-XXXXXXX
2023/06 .....P06-XXXXXXX
2024/01 .....Q01-XXXXXXX
2025/01 .....R01-XXXXXXX
2026/01 .....S01-XXXXXXX

(A、B、C-Z)不使用字母“I”和“O”。
(为了不与数字1和0混淆。)

指导性防护标识

标识	含义
	为了降低受伤的风险,用户必须阅读并理解使用说明书。
	仅供室内使用。

通知

[中国大陆]

产品中有害物质的名称及含有的信息表

部件名称	有害物质									
	Pb	Hg	Cd	Cr (VI)	PBBs	PBDEs	DBP	DIBP	BBP	DEHP
外壳	○	○	○	○	○	○	○	○	○	○
回路基板	×	○	○	○	○	○	○	○	○	○
分集天线	○	○	○	○	○	○	○	○	○	○
蜂鸣器	○	○	○	○	○	○	○	○	○	○
控制器支架	○	○	○	○	○	○	○	○	○	○
纽扣电池	○	○	○	○	○	○	○	○	○	○
电源适配器	○	○	○	○	○	○	○	○	○	○

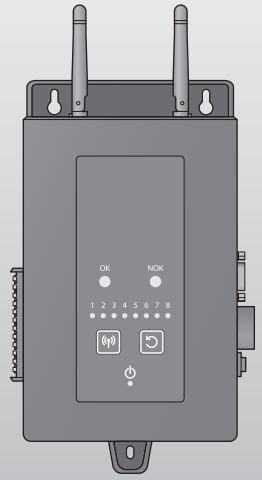
注1）○:表示该有害物质在该部件所有均质材料中的含量均不超出电器电子产品有害物质限制使用国家标准要求。
×:表示该有害物质至少在该部件的某一均质材料中的含量超出电器电子产品有害物质限制使用国家标准要求。
注2）以上未列出的部件,表明其有害物质含量均不超出电器电子产品有害物质限制使用国家标准要求。

执行标准	装配控制器: GB 4343.1 – 2018, GB 17625.1 - 2012
	电源适配器: GB 4943.1 – 2022, GB/T 9254.1 – 2021, GB17625.1 - 2022

Panasonic

사용설명서
어셈블리 컨트롤러

모델 번호:
EYFRW2



중요
이 제품을 사용하기 전에 안전 사용설명서를 읽고 따르십시오.
제품을 구입한 국가 밖에서 무선 기능을 사용해서는 안 됩니다.
사용하면 현지 법률 및 규정을 위반할 수 있습니다.

원문 지침: 영어
원문 지침의 번역: 기타 언어

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작동 환경

컨트롤러를 구성하려면 웹 브라우저를 사용해야 합니다.
다음 요구 사항을 충족하는 PC를 준비하십시오.

작동 환경

호환 OS	Windows 10 이상(아래 웹 브라우저 지원)
웹 브라우저	Microsoft Edge 버전 102 이상 또는 Google Chrome 버전 102 이상

- 일부 PC는 작동 환경을 충족하더라도 사용할 수 없습니다.
- PC의 사용 환경 등에 따라 본 사용설명서의 설명 및 화면이 실제 설명 및 화면과 다를 수 있습니다.
  미리 양해를 구합니다.
- 이 사용설명서의 내용은 사전 통지 없이 변경될 수 있습니다.
- 이 사용설명서의 내용 전체 또는 일부를 무단으로 복제하는 것은 금지되어 있습니다.
- 이 사용설명서의 그림은 참조용입니다.

[중요]
펌웨어를 항상 최신 상태로 유지하십시오.
사용설명서에 대한 액세스를 제공하는 다음 웹사이트에서 최신 펌웨어 데이터를 찾을 수 있습니다.
펌웨어를 업데이트하는 방법은 “펌웨어 업데이트”를 참조하십시오.
P95참조

사용설명서에 액세스하는 방법

컨트롤러의 사용설명서 및 기타 리소스의 현재 버전은 아래 웹 사이트에서 다운로드할 수 있습니다.

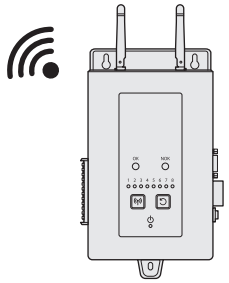
https://panasonic.net/electricworks/ecm/powerelctrictools/download/

상표
- Microsoft 및 Windows는 미국 및/또는 기타 국가에서 Microsoft Corporation 의 등록 상표 또는 상표입니다.
- 스크린샷은 Microsoft Corporation 의 지침에 따라 사용됩니다.

이 사용설명서에 있는 회사 이름 및 제품 이름을 포함한 기타 이름은 해당 회사의 상표 또는 등록 상표입니다.
™ 및 ® 는 이 사용설명서에서 생략될 수 있습니다.

사용 목적

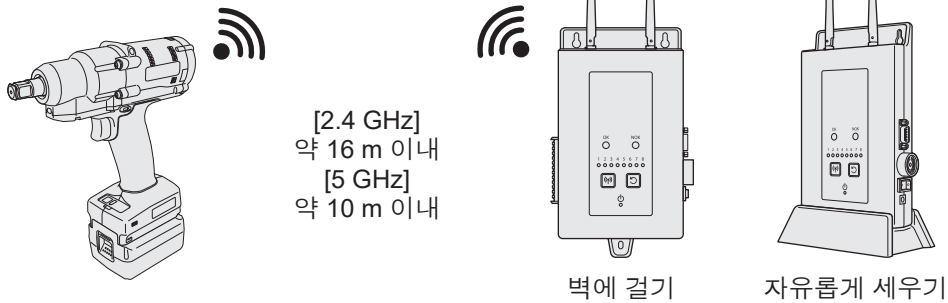
이 제품은 무선으로 도구와 통신하는 컨트롤러입니다.
도구로부터 체결 이력 데이터를 받아 도구 설정 및 체결 수량을 제어할 수 있습니다.

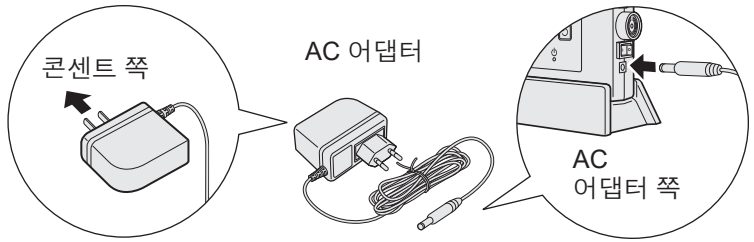


01	최대 8개의 도구에 연결
02	2.4 GHz 및 5 GHz 대역 지원
03	체결 제어 기능 및 이력 저장 기능 지원

설정

도구와의 무선 통신이 가능한 범위에 컨트롤러를 설치하십시오.
AC 콘센트를 통해 전원을 공급하고 필요에 따라 통신 인터페이스를 통해 외부 장치에 연결합니다.





예: WEYFRW1K7951

- 컨트롤러에는 시계 기능(RTC)을 계속 실행하기 위한 코인 셀 배터리가 포함되어 있습니다.
  내부 코인 셀 배터리 소모를 줄이기 위해 전원을 켜두는 것이 좋습니다.
- 무선 범위는 환경에 따라 변경될 수 있습니다.

안전 예방 조치 항상 지침을 따르십시오.

다음은 인명 피해 및 재산 피해를 방지하기 위해 항상 준수해야 하는 지침입니다.

■잘못된 사용으로 인한 피해 및 피해의 심각도는 다음과 같습니다.

⚠ 경고	사망하거나 중상을 입을 수 있습니다.
⚠ 주의	경상을 입거나 재산 피해가 발생할 수 있습니다.

■준수해야 할 내용은 다음 기호로 표시됩니다. (다음은 예시임)

	금지되는 행동입니다.
	따라야 하는 행동입니다.

⚠ 경고

필수	● **설치 장소에 전선관, 수도관, 가스관 등이 매설되지 않았는지 확인하십시오.** 이러한 매설물과 접촉하면 감전이나 누전, 가스 누출의 원인이 됩니다.
	● **전원 플러그를 끝까지 꽂으십시오.** 제대로 삽입하지 않으면 감전이나 발열로 인해 화재가 발생할 수 있습니다. 손상된 플러그나 느슨한 소켓을 사용하지 마십시오.
	● **전원 플러그의 먼지를 정기적으로 청소하십시오.** 플러그에 먼지가 쌓이면 수분을 흡수하므로 절연 불량으로 인해 화재가 발생할 수 있습니다. 전원 플러그를 뽑고 마른 천으로 닦으십시오.
	● **지정된 전원 코드만 사용하십시오.** 다른 플러그를 사용하면 감전, 단락 또는 화재가 발생할 수 있습니다.
	● **작업장을 충분히 밝게 유지하십시오.** 어두운 작업장에서는 시야가 제대로 확보되지 않아 사고나 부상을 입을 수 있습니다.

⚠ 경고

금지	● **정격 값을 초과하는 방식으로 소켓이나 배선 장치를 사용하지 마십시오. 100 V-240 V AC 만 사용하십시오.** 소켓의 과부하로 인해 정격 값을 초과하면 열로 인해 화재가 발생할 수 있습니다.
	● **전원 코드나 플러그를 손상시키지 마십시오. (손상, 파손, 개조, 열원에 접근, 무리한 구부림, 비틀림, 당기기, 무거운 하중, 끼임, 결속 등을 피하십시오.)** 손상된 코드나 플러그를 사용하면 감전, 단락 또는 화재가 발생할 수 있습니다. 코드와 플러그를 주기적으로 점검하고 손상된 부분이 있으면 대리점에 문의하십시오.
	● **컨트롤러를 DC 전원 공급 장치, 엔진 발전기 또는 변압기와 함께 사용하지 마십시오.** ● **가연성 액체나 가스가 있는 장소에서 컨트롤러를 사용하지 마십시오.** 그런 곳에서 사용하면 발열, 연기, 화재, 폭발의 원인이 됩니다.
	● **모르타르 벽에 컨트롤러를 설치하지 마십시오.** 모르타르 벽면에 나사로 고정하면 내부의 철망에서 열로 인해 누전 시 화재가 발생할 수 있습니다.
	● **사용이 끝나면 전원 플러그를 분리하십시오.** 계속 전원에 연결하면 절연 불량으로 인해 감전이나 누전으로 인한 화재가 발생할 수 있습니다.
분해 금지	● **컨트롤러를 개조하지 마십시오. 컨트롤러를 분해하거나 수리하지 마십시오.** 그렇게 하면 화재, 감전, 부상의 원인이 됩니다. 수리하려면 대리점이나 고객 지원 센터에 문의하십시오.
건조한 상태 유지	**충전된 도구를 다음과 같이 사용하지 마십시오.** ● **비나 습기에 노출된 상태로 두거나 사용하지 마십시오.** ● **물에 잠긴 상태에서 사용하지 마십시오.** 그렇게 하면 연기, 화재, 폭발의 원인이 됩니다.
젖은 손 접촉 금지	● **젖은 손으로 전원 플러그를 콘센트에 연결하거나 분리하지 마세요.** 그렇게 하면 감전될 수 있습니다.

안전 예방 조치 항상 지침을 따르십시오.

⚠ 주의

금지

- **원래 목적 이외의 용도로 컨트롤러를 사용하지 마십시오.**
  그렇게 하면 부상을 입을 수 있습니다.
- **컨트롤러를 어린이의 손이 닿는 곳에 두지 마십시오.**
  그렇게 하면 사고나 고장의 원인이 됩니다.
- **컨트롤러에 기름이나 기타 이물질이 묻은 상태로 사용하지 마십시오.**
  이러한 기름이나 이물질이 내부로 유입되어 발열, 화재, 폭발의 원인이 됩니다.
- **온도가 45 °C 이상으로 올라갈 수 있는 장소에 본체를 보관하지 마십시오.**
  그렇게 하면 오작동의 원인이 됩니다.
- **비정상적인 위치에서 작업하지 마십시오.**
  그렇지 않으면 넘어져 다칠 수 있습니다.
  항상 안정된 발판에 서서 균형을 제대로 잡으십시오.
- **피곤할 때 컨트롤러를 사용하지 마십시오.**
  그렇게 하면 사고나 부상의 원인이 됩니다.
- **어린이나 작업자가 아닌 사람이 작업장에 접근하거나 컨트롤러를 만지지 않도록 하십시오.**
  그렇게 하면 부상을 입을 수 있습니다.
- **호환되지 않는 장치와 함께 컨트롤러를 사용하지 마십시오.**
  그렇게 하면 고장으로 인해 사고가 발생할 수 있습니다.

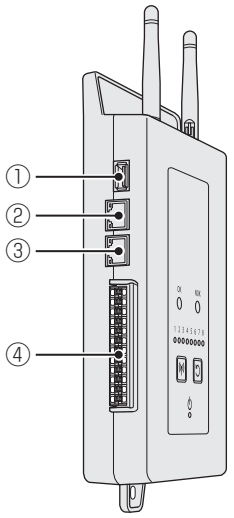
필수

- **컨트롤러를 벽에 설치할 경우 떨어지지 않도록 나사로 고정하십시오.**
  떨어지면 부상을 입을 수 있습니다.
- **전원 플러그를 뽑을 때는 코드를 당기지 말고 항상 전원 플러그를 잡으십시오.**
  코드를 잡아당기면 감전 또는 단락이 발생할 수 있습니다.
- **사용하기 전에 컨트롤러 및 기타 부품에 손상이 없는지 검사하고 정상적인 작동을 확인하십시오.**
  그렇지 않으면 파손으로 이어져 부상을 입을 수 있습니다.
- **작업장을 청결하게 유지하십시오.**
  정리되지 않은 작업장이나 작업대는 사고로 이어질 수 있습니다.
- **취급 및 작업 방법을 잘 고려하고, 주변 환경에 주의를 기울이며, 상식적인 수준에서 작업하십시오.**
  그렇게 하지 않으면 사고를 당하거나 부상을 입을 수 있습니다.

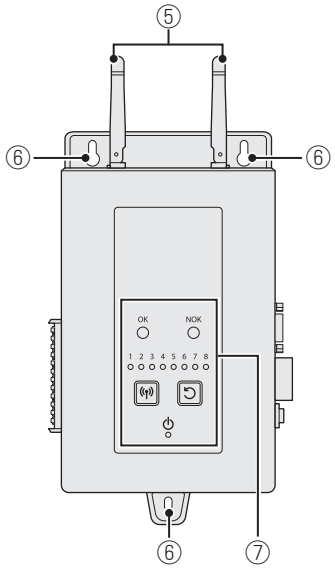
기능 설명

본체

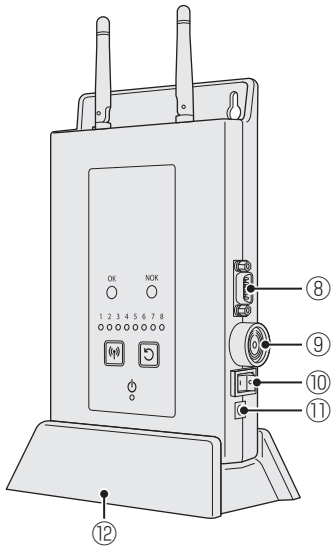
■ 좌측 면



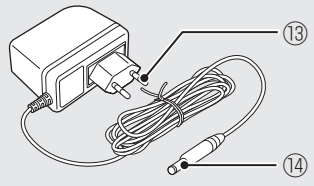
■ 전면



■ 우측 면



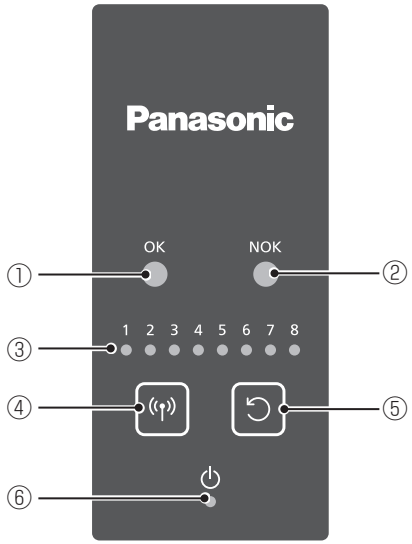
■ AC 어댑터



①	USB 포트(USB-A)
②	이더넷 포트(유지 보수용)
③	이더넷 포트(네트워크용)
④	1～24 I/O 포트
⑤	다이버시티 안테나
⑥	벽걸이 구멍
⑦	제어판

⑧	직렬 포트(RS232C)
⑨	버저
⑩	전원 스위치
⑪	AC 어댑터 소켓
⑫	컨트롤러 스탠드
⑬	전원 플러그
⑭	전원 커넥터

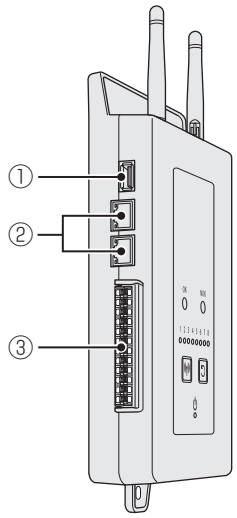
■제어판

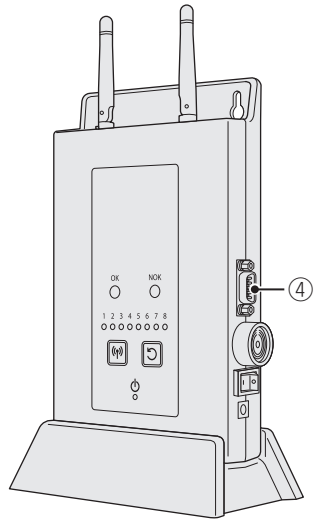


①	체결 OK 램프 녹색으로 깜박임: 바코드 판독 수신 상태입니다. 솔리드 녹색: 체결 완료 신호를 수신했습니다. OFF: 체결 완료 신호가 수신되지 않았습니다.
②	체결 NOK 램프 솔리드 빨간색: 체결 실패 신호를 수신했습니다. OFF: 체결 실패 신호가 수신되지 않았습니다.
③	통신 램프(1~8번) 솔리드 파란색: 도구가 등록되었습니다. 파란색 깜박임: 도구가 등록 중이거나 범위를 벗어났습니다. OFF: 도구가 등록되지 않았습니다.

④	페어링 키
⑤	재설정 키
⑥	전원 램프 노란색 점등: 전원 켜기(수신 모드) OFF: 전원 끄기 노란색 깜박임: 오류

■통신 인터페이스



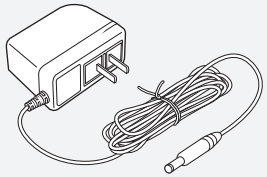


인터페이스		세부 정보
①	USB	펌웨어를 업데이트하려면 이 포트를 사용하여 USB 플래시 드라이브를 연결합니다. * USB 플래시 드라이브 직접 연결(확장 없음) 무선 수신기는 바코드 리더를 연결하기 위해 이 포트에 연결됩니다. * 무선 바코드 리더만 사용할 수 있습니다. • USB2.0 USB-A × 1
②	이더넷 (유지 보수 및 네트워크용)	이 포트를 사용하여 구성용 PC 또는 호스트 시스템에 연결합니다. * 이더넷 포트(유지 보수용)를 구성용 PC에 직접 연결합니다. (허브를 사용하지 않음) • 10Base-T/100Base-TX × 2 • 케이블 길이: 30 m 이하
③	입력/출력(I/O) 단자	이 포트를 사용하여 외부 장치(예: PLC)에 연결합니다. • 입력 8개 및 출력 8개 • 케이블 길이: 10 m 이하 • 입력 단자 정격: 24 V DC, 50 mA • 출력 단자 정격: 30 V DC, 3 A
④	직렬 포트(RS232C)	이 포트를 사용하여 외부 장치(예: PLC)에 연결합니다. • RS232C × 1 • 케이블 길이: 10 m 이하

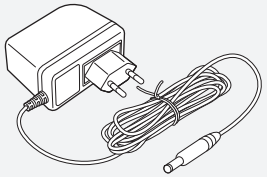
액세서리

■**AC 어댑터 × 1**

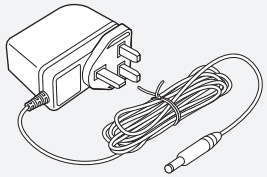
[중국에만 해당]
(WEYFRW1K7951)



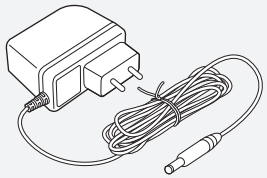
[한국에만 해당]
(WEYFRW1K7051)



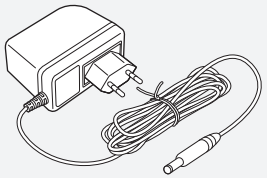
[말레이시아에만 해당]
(WEYFRW1K7851)



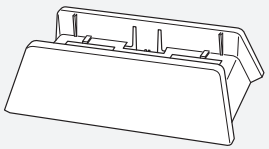
[인도에만 해당]
(WEYFRW1K7151)



[태국/인도네시아만 해당]
(WEYFRW1K7751)



■**컨트롤러 스탠드 × 1**
(EYFRW1F7001)

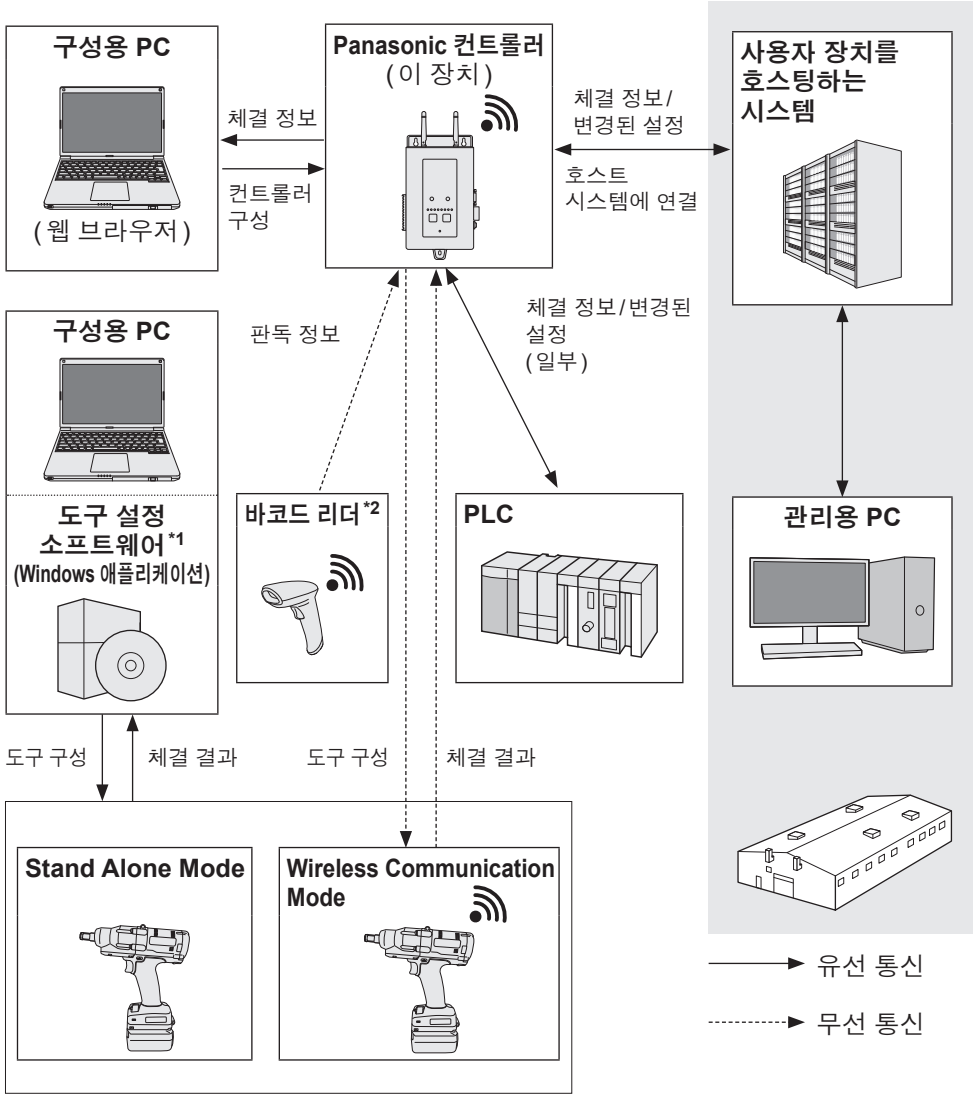


소 모 품

■**코인 셀 배터리**(CR2450) × 1
교체 방법은 “코인 셀 배터리 교체” 를 참조하십시오.
P96 참조



시스템 구성

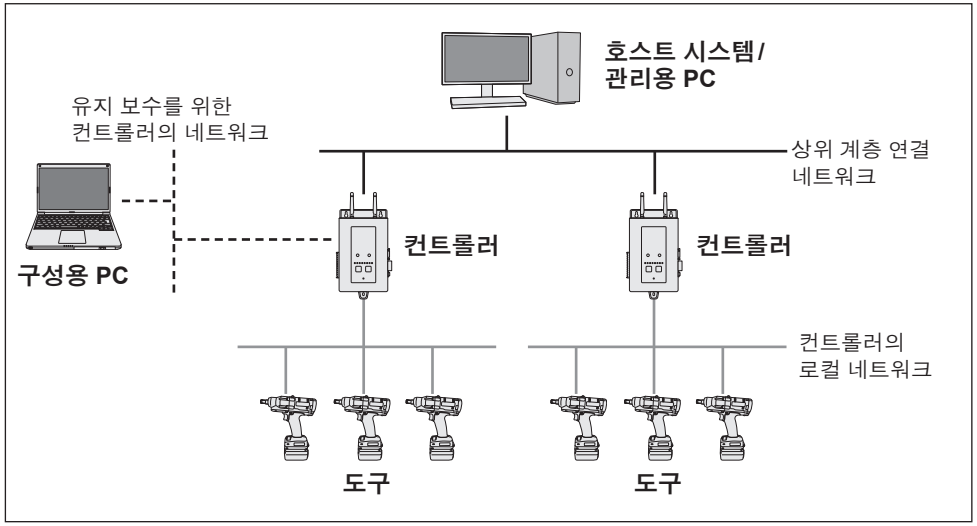


*1 “도구 설정 소프트웨어”는 웹 사이트에서 다운로드할 수 있습니다. **P2 참조**
*2 이는 펌웨어 버전 2.03.00 이상에서만 지원됩니다.

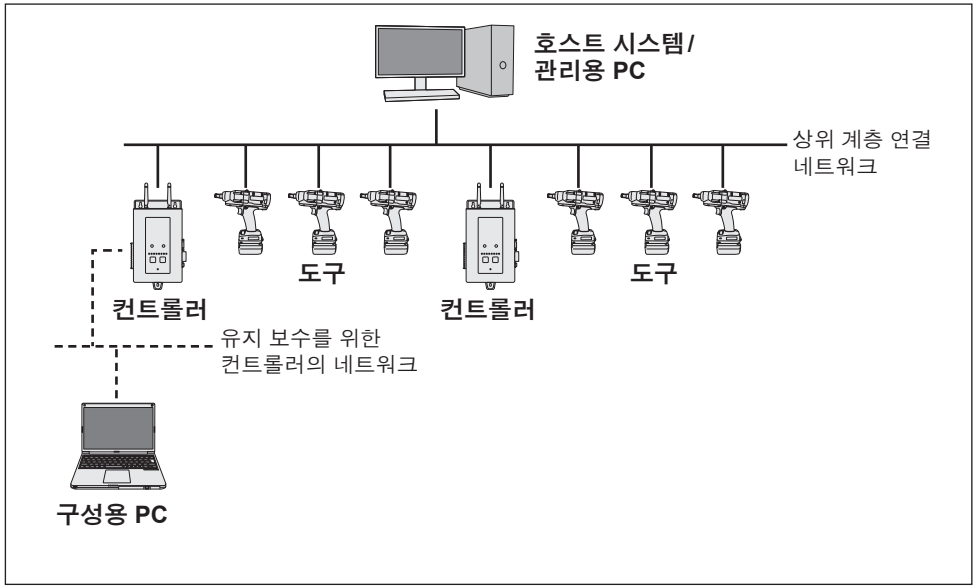
일반적인 네트워크 구성

컨트롤러는 아래 4가지 구성으로 사용할 수 있습니다.

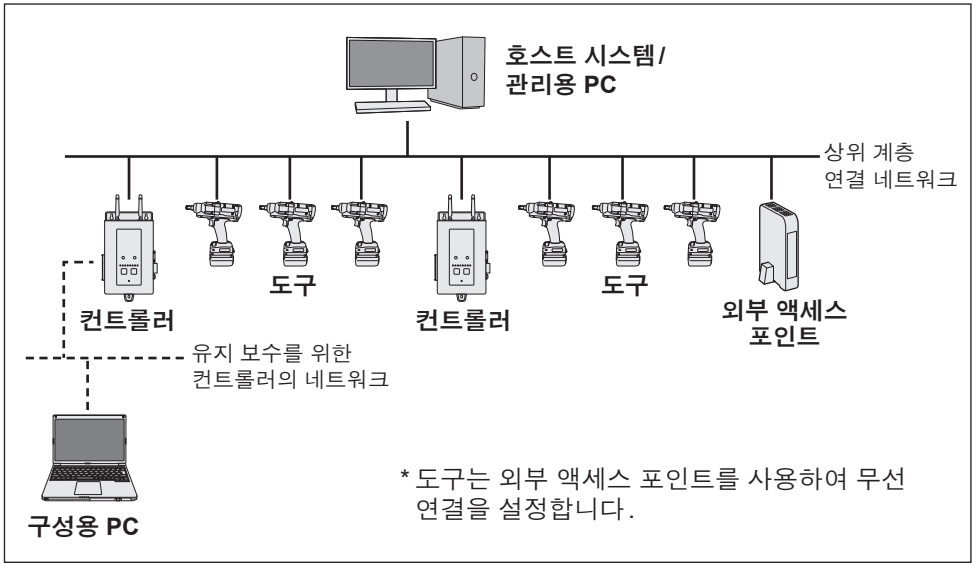
■도구의 IP 주소를 관리하지 않음
*** 자동 할당(컨트롤러에 내장된 액세스 포인트 사용)**



■도구의 IP 주소 관리(컨트롤러에 내장된 액세스 포인트 사용)

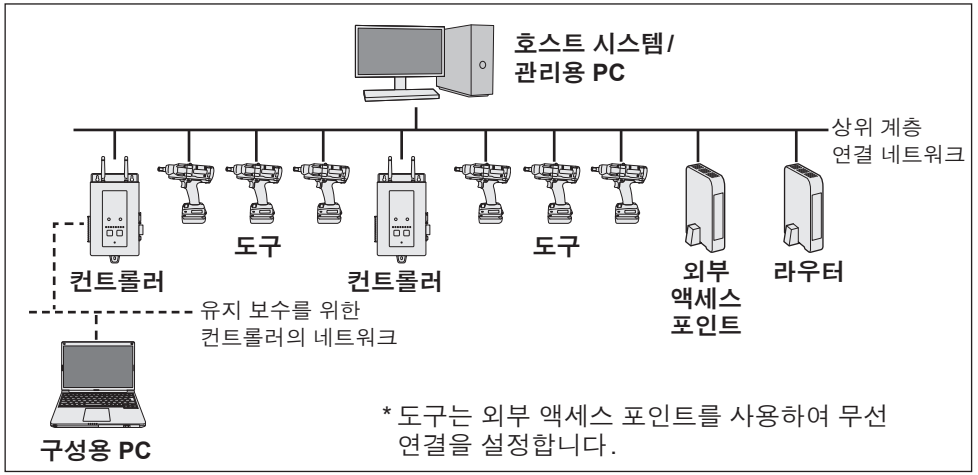


■도구의 IP 주소 인식(외부 액세스 포인트 사용)



* 로컬 네트워크 내에서 시스템을 사용하십시오(인터넷에 연결하지 않음).
* 사용을 시작하기 전에 컨트롤러의 네트워크에 대한 IP 주소 설정을 확인하십시오.
(필요한 경우 기본값 변경)

■도구의 IP 주소를 관리하지 않음
*** 자동 할당 (상위 계층 연결 네트워크의 DHCP에서)**



* 네트워크 방화벽 설정에 따라 사용하지 못할 수도 있습니다.
사전에 설정을 확인하십시오.

컨트롤러 및 도구 본체 펌웨어 버전

호환성

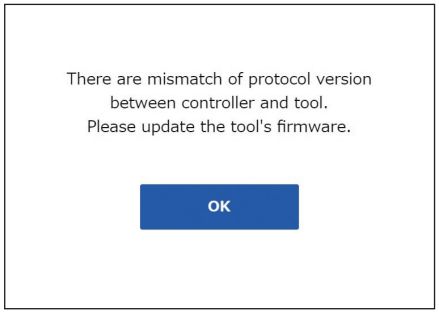
일부 네트워크 구성 패턴을 구현하려면 다음과 같이 펌웨어를 최신 버전으로 업데이트해야 합니다.
아래의 호환성 표를 확인하고 필요에 따라 업데이트합니다. **P95 참조**

컨트롤러 펌웨어	도구 본체 펌웨어
버전 2.04.00 이상	버전 2.04.00 이상
버전 2.00.00 ~ 2.03.00	버전 2.00.00 이상

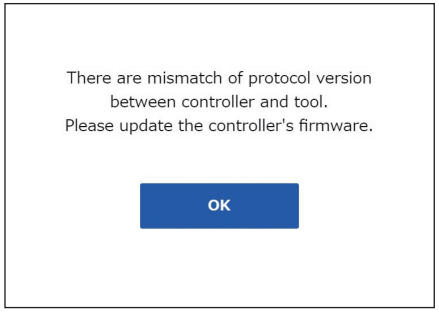
버전 불일치 표시

상기 호환성이 없는 도구가 컨트롤러에 페어링되어 등록된 경우, 다음과 같이 경고가 표시됩니다.

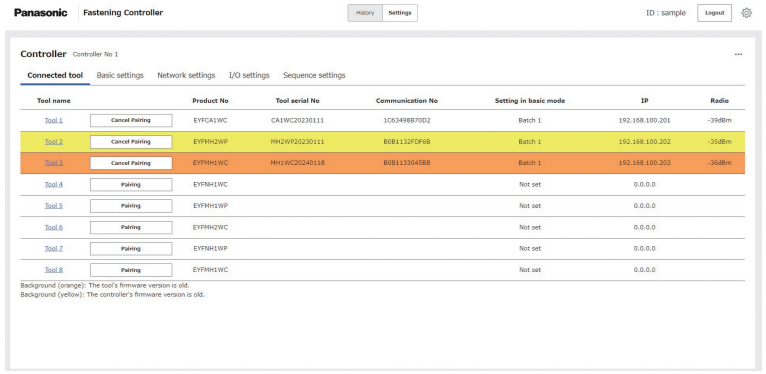
도구 펌웨어 버전이 오래된 경우



컨트롤러 펌웨어 버전이 오래된 경우



주황색 배경 : 도구 펌웨어 버전이 오래됨
노란색 배경 : 컨트롤러 펌웨어 버전이 오래됨



적용 가능한 도구 모델 목록

등록 가능한 모델	EYFMH1WC, EYFMH2WC EYFNH1WC*1, EYFCA1WC*2

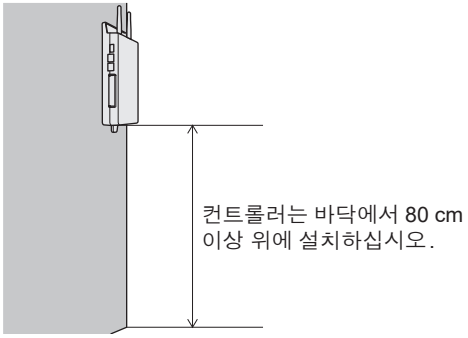
*1 이는 펌웨어 버전 2.02.00 이상에서만 지원됩니다.
*2 이는 펌웨어 버전 2.04.00 이상에서만 지원됩니다.

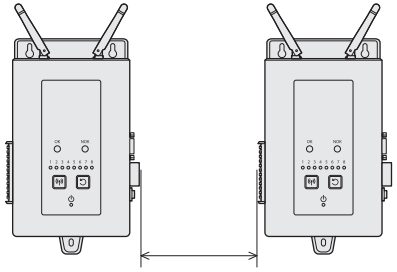
• 최신 종합 카탈로그를 참조하십시오.

설치 주의

컨트롤러는 바닥에서 80 cm 이상 위에 설치하십시오. 설치된 컨트롤러 사이에 10 cm 이상을 유지하십시오. (1 m 이상 권장)
설치된 컨트롤러의 안테나가 장애물에 가리지 않게 하십시오.
컨트롤러에는 2개의 다이버시티 안테나가 있습니다. 양쪽 안테나가 장애물에 가리지 않게 하십시오.

⚠ 주의
안전한 설치를 위해 공칭 직경 3.5 mm~4.1 mm의 목재 나사를 사용하십시오.



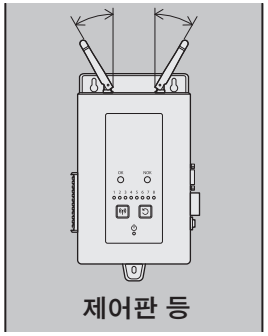


통신이 불안정한 경우 안테나의 각도를 조정하십시오.
* 특히 금속 패널에 설치되는 컨트롤러의 경우 안테나의 각도를 조정하면 통신 안정성이 향상될 수 있습니다.

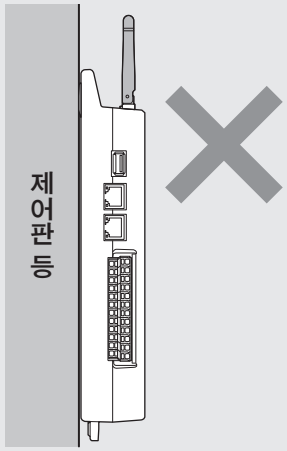
안테나를 벽에서 30~45° 기울입니다.



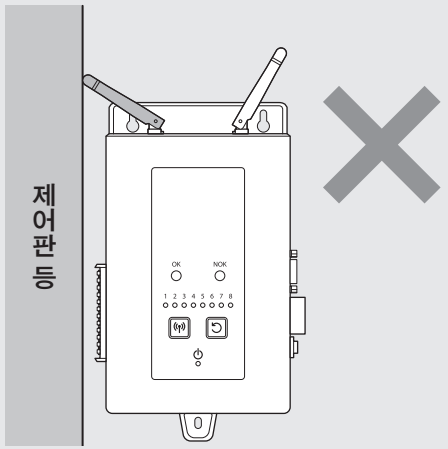
정면에서 보았을 때 안테나를 바깥쪽으로 30~45° 기울입니다.



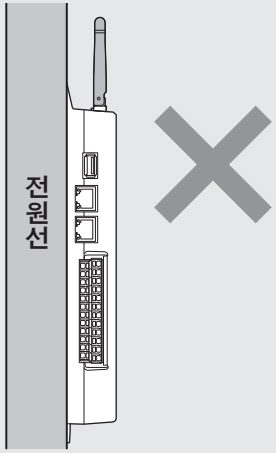
■다음 설치를 피하십시오.



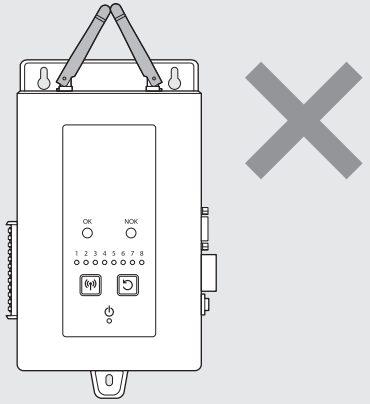
안테나가 후면의 제어판(금속 패널)과 평행합니다.



안테나는 제어판(금속 패널)과 접촉합니다.



컨트롤러는 전원선에 매우 가깝게 설치됩니다.

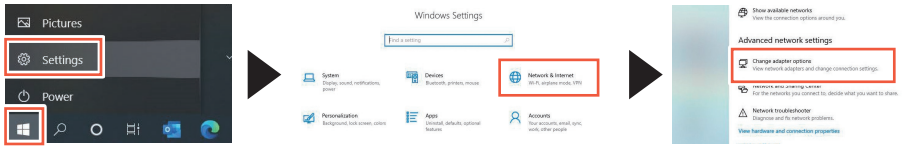


안테나는 서로 접촉되어 있습니다.

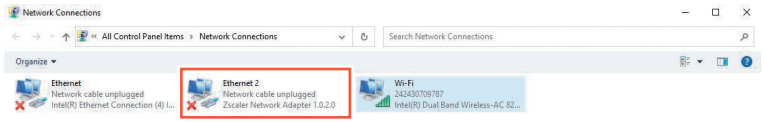
구성용 PC의 네트워크 설정

구성용 PC와 컨트롤러를 처음 연결할 때 아래와 같이 구성용 PC의 네트워크 설정을 설정하십시오.

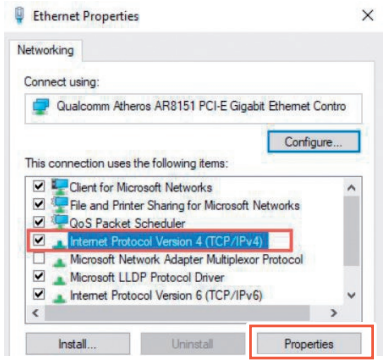
1 **화면 좌측 하단의 ⊞를 클릭하고 ⚙ (Settings) - [Network & Internet] - [Change adapter options] 을 클릭합니다.**



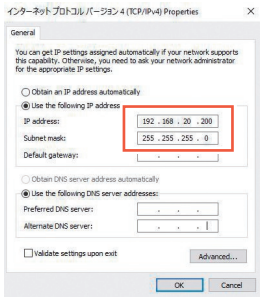
2 **장치를 마우스 오른쪽 버튼으로 클릭하여 연결하고 [Properties] 를 클릭합니다.**



3 **“Internet Protocol Version 4” 를 선택하고 [Properties] 를 클릭합니다.**



4 **“IP address”와 “Subnet mask” 를 아래와 같이 설정합니다.**



IP address	192 . 168 . 20 . 200
Subnet mask	255 . 255 . 255 . 0

* 처음 연결 후 컨트롤러의 IP 주소를 변경한 경우 구성용 PC에서 네트워크 설정(IP 주소 및 서브넷 마스크)을 반환하여 연결을 활성화합니다. 이 때 컨트롤러와 구성용 PC가 같은 네트워크에 있도록 IP 주소를 설정합니다.
* 변경하기 전에 구성용 PC의 네트워크 설정(IP 주소 및 서브넷 마스크)을 기록하고 보관합니다.
* 기본 게이트웨이를 미지정 상태(공백)로 두는 것이 좋습니다.

설정 화면 표시

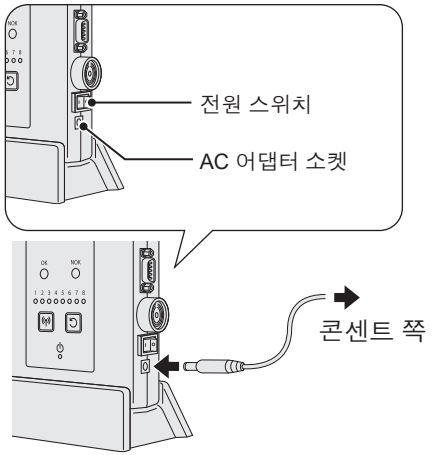
컨트롤러를 구성하려면 웹 브라우저를 통해 액세스하십시오.
컨트롤러의 설정 화면을 아래와 같이 표시합니다.

컨트롤러를 처음 사용하는 경우 코인 셀 배터리에서 보호 필름을 제거하십시오.

1 **컨트롤러를 켭니다.**

① 제공된 AC 어댑터를 컨트롤러에 연결하고 전원 플러그를 콘센트에 연결합니다.

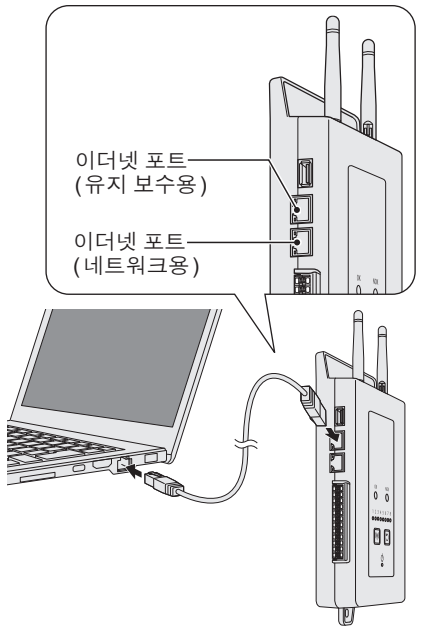
② 컨트롤러의 전원 스위치를 켭니다.
* 시작하는 데 수십 초가 걸립니다.
* 시작하는 동안 체결 OK 램프, 체결 NOK 램프, 통신 램프(1~8번)가 함께 깜박입니다.
* LAN 케이블을 연결하지 마십시오.



2 **LAN 케이블을 사용하여 컨트롤러를 구성용 PC에 연결합니다.**

① LAN 케이블을 컨트롤러의 이더넷 포트에 연결합니다.
* 컨트롤러에는 2개의 이더넷 포트가 있습니다. 하나는 유지 보수용이고 다른 하나는 네트워크용입니다. 처음 연결할 때는 유지 보수용을 사용하십시오.

② LAN 케이블을 사용하여 구성용 PC 에 연결합니다.



3 구성용 PC 에서 웹 브라우저를 시작하고 컨트롤러에 액세스합니다.

① 구성용 PC 에서 웹 브라우저를 시작합니다. (Microsoft Edge 권장)

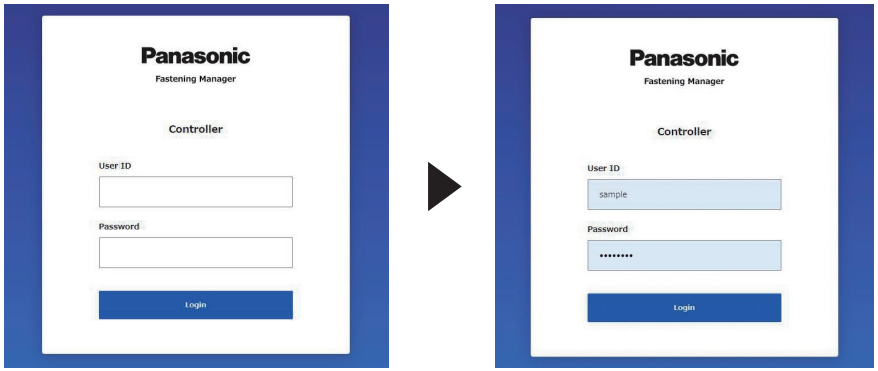
② 웹 브라우저의 주소 표시줄에 컨트롤러의 IP 주소를 입력합니다.
* 이더넷 포트(유지 보수용)의 기본 IP 주소는 "192.168.20.10" 입니다.

웹 브라우저의 주소 표시줄에서 "http://192.168.20.10/controller" 를 입력하여 액세스합니다.
* "192.168.20.10/controller" 를 입력해도 액세스가 허용됩니다.

* 이더넷 포트(네트워크용)를 통한 액세스 방법은 "네트워크를 통해 연결" 을 참조하십시오. P23 참조
* IP 주소도 구성용 PC 에 설정해야 합니다.

③ 표시되는 로그인 화면에서 사용자 ID 와 비밀번호를 입력합니다.
* 초기 로그인용 사용자 ID 와 비밀번호는 아래와 같습니다.

④ 상단 페이지(설정 화면의 초기 페이지)가 표시됩니다.



초기 로그인용 사용자 ID 및 비밀번호

아래 사용자 ID와 비밀번호로 로그인합니다.

■ **사용자 ID: root**
■ **비밀번호: abcABC123**

* 초기 로그인의 계정 유형은 "default" 입니다.
계정 유형의 경우 "계정 유형(권한)" 을 참조하십시오. P21 참조
* 위 사용자 ID와 비밀번호로 로그인해야만 계정 생성이 가능합니다. 사용을 시작하기 전에 새 계정을 생성합니다.
* 보안을 위해 최초 로그인 후 위 비밀번호를 변경하는 것이 좋습니다.

계정 유형(권한)

다음은 계정 유형입니다. 용도에 따라 사용하십시오.

계정 유형	기능
기본	• 초기 로그인의 경우. P20 참조 사용자 계정 추가 또는 변경.
Administrator	• 체결 기록 보기. • 컨트롤러 구성. • 도구 구성. • 사용자 계정 추가 또는 변경. * 하나 이상의 관리자 계정을 생성합니다.
General	• 체결 기록 보기(작업 모니터 보기 포함).

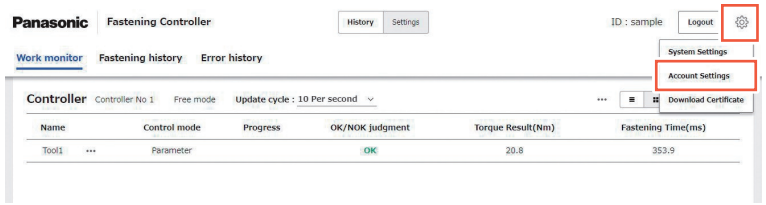
최대 10개의 계정을 등록할 수 있습니다.
따라서 한 명 이상의 운영자가 동시에 로그인할 수 있습니다.
* 동시에 하나의 계정만 관리자로 로그인할 수 있습니다.
다중 접속 시도 시 마지막 세션이 우선합니다.

사용자 계정 생성

사용을 시작하기 전에 새 계정을 생성합니다.

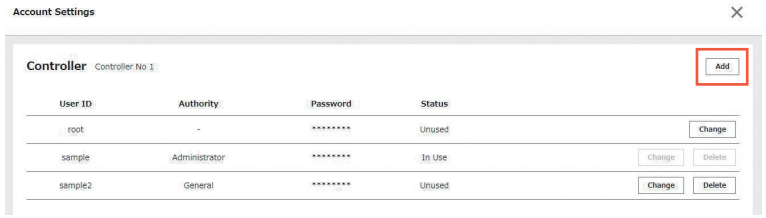
1 상단 페이지(설정 화면의 초기 페이지)에서 우측 상단의 옵션 키를 클릭하고 "Account Settings" 를 선택합니다.

"Account Settings" 화면이 표시됩니다.



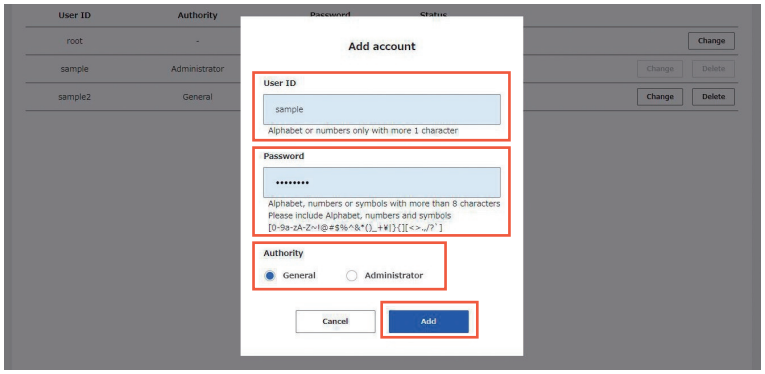
2 "Account Settings" 화면에서 [Add] 를 클릭합니다.

"Add account" 화면이 표시됩니다.
• 계정을 변경하려면 [Change] 를 클릭하고 계정을 삭제하려면 [Delete] 를 클릭합니다.



3 "User ID" 및 "Password" 를 입력하고 "Authority" 을 선택한 다음 [Add] 를 클릭합니다.

* 도구를 구성하려면 관리자 계정을 생성합니다.
* 비밀번호는 항상 대문자, 소문자, 숫자, 기호 중 3가지 이상의 조합을 사용해야 합니다.



[참조] 사용자 ID나 비밀번호를 분실한 경우

■ 일반 계정

[방법 1] 관리자로 로그인하고 관련 계정을 변경합니다.
* 일반 사용자는 사용자 ID 와 비밀번호를 변경할 수 없으며 관리자에게 변경을 요청해야 합니다.

[방법 2] 새로 생성된 관리자 계정으로 로그인하여 해당 계정을 변경합니다.
* 초기 로그인용 사용자 ID 와 비밀번호로 로그인하고 새 관리자 계정을 생성합니다. P20 참조

■ 관리자 계정

A) 관리자 계정이 여러 개 생성된 경우

[방법 1] 다른 관리자 계정으로 로그인하여 해당 계정을 변경합니다.

[방법 2] 새로 생성된 관리자 계정으로 로그인하여 해당 계정을 변경합니다.
* 초기 로그인용 사용자 ID 와 비밀번호로 로그인하고 새 관리자 계정을 생성합니다. P20 참조

[방법 3] 모든 관리자 계정의 ID와 비밀번호를 분실한 경우 설정을 초기화합니다. P93 참조

B) 관리자 계정이 하나만 생성된 경우

[방법 1] 새로 생성된 관리자 계정으로 로그인하여 해당 계정을 변경합니다.
* 초기 로그인용 사용자 ID 와 비밀번호로 로그인하고 새 관리자 계정을 생성합니다. P20 참조

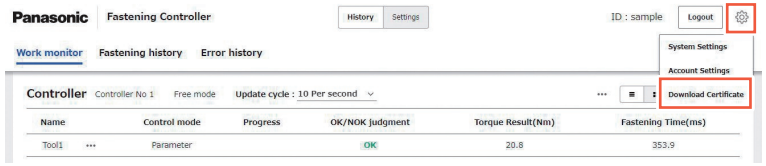
[방법 2] 모든 관리자 계정의 ID 와 비밀번호를 분실한 경우 설정을 초기화합니다. P93 참조

인증서 받기

이더넷 포트(네트워크용)를 통해 컨트롤러에 액세스하려면 인증서가 필요합니다. 아래와 같이 인증서를 받을 수 있습니다.

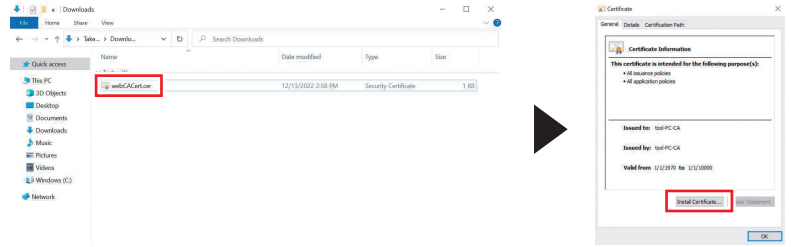
1 상단 페이지(설정 화면의 초기 페이지)에서 우측 상단의 옵션 키를 클릭하고 "Download Certificate" 를 선택합니다.

인증서 데이터가 구성용 PC에 다운로드됩니다.

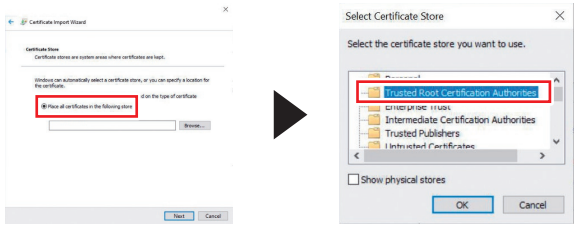


2 "네트워크를 통해 컨트롤러에 액세스하는 데 사용되는 구성용 PC" 에 인증서를 설치합니다.

① 다운로드한 인증서 데이터를 두 번 클릭하고 "Install Certificate"를 선택합니다.



② "Place all certificates in the following store" 를 선택한 다음 "Trusted Root Certification Authorities" 를 선택합니다.

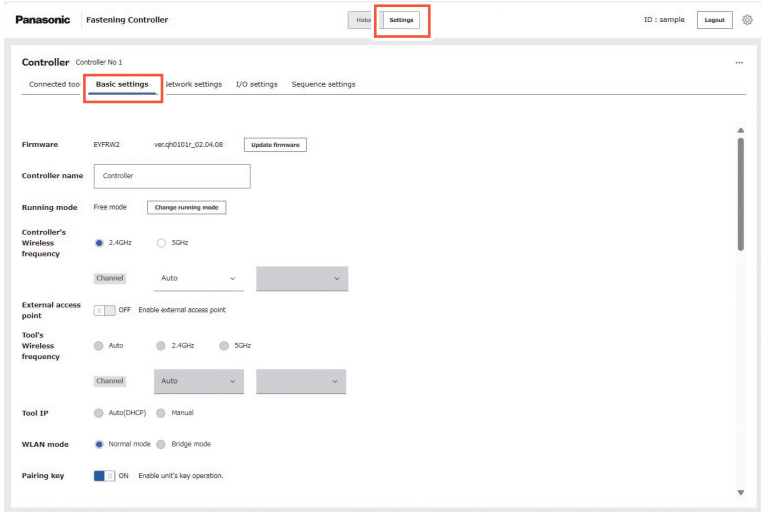


네트워크를 통해 연결

웹 브라우저의 주소 표시줄에 "https://XXX.XXX.XXX.XXX/controller" 를 입력하여 이더넷 포트(네트워크용)를 통해 컨트롤러를 연결합니다.
* "XXX.XXX.XXX.XXX" 는 IP 주소입니다.
* 기본 IP 주소는 "192.168.0.10" 입니다. 기본 주소를 변경한 경우 변경된 주소를 입력합니다. P30 참조

기본 설정

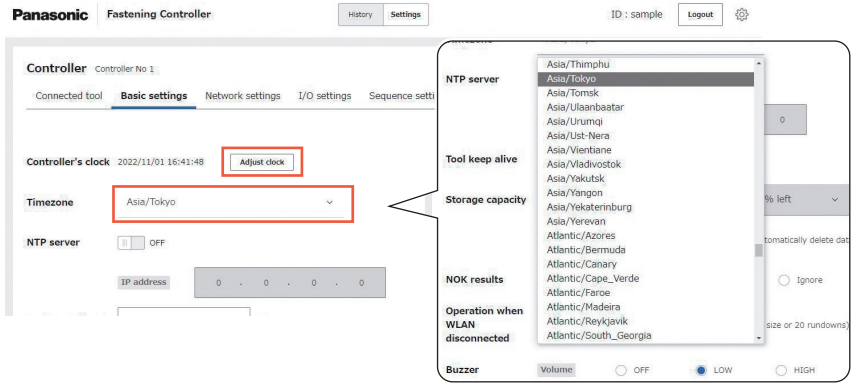
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Basic settings” 탭을 선택합니다.
컨트롤러를 구성할 수 있습니다.



■시간 설정

“Timezone” 을 선택한 다음 [Adjust clock] 을 클릭합니다.
시간이 업데이트됩니다.

- 제품 선적 시에는 아직 시간이 설정되어 있지 않습니다. 컨트롤러를 처음 사용할 때 시간을 설정하십시오.

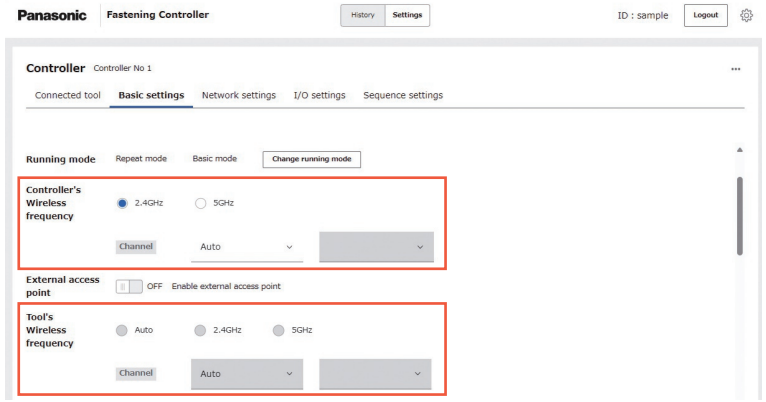


* NTP 서버를 사용하는 경우 IP 주소를 입력합니다.

■무선 주파수 및 채널 설정

사용할 주파수를 설정할 수 있습니다.
“2.4GHz” 또는 “5GHz” 를 선택한 다음 사용할 채널을 선택합니다.

* 외부 액세스 포인트를 사용할 경우 “Tool's Wireless frequency”에서 도구의 주파수를 설정하십시오.
* 선택 가능한 채널은 “2.4GHz” 와 “5GHz” 가 다릅니다.
* “Channel”이 “Auto”로 설정된 경우, 컨트롤러는 전원이 켜질 때 주변 환경에서 사용 가능한 채널을 자동으로 선택합니다.
  이 설정은 무선 간섭에 효과적일 수 있습니다.
* 여러 컨트롤러를 서로 가까이 설치할 때 인접 채널을 설정하지 마십시오.



■설정 항목

Firmware

컨트롤러의 펌웨어 버전이 표시됩니다.
펌웨어를 업데이트하려면 [Update firmware] 를 클릭합니다.
업데이트 방법은 "펌웨어 업데이트" 를 참조하십시오. P95 참조

Controller name

컨트롤러의 이름을 등록할 수 있습니다.
최대 32자의 영숫자 문자를 사용하십시오.
[기본] Controller
[설정 범위] 최대 32자의 영숫자 문자
* 기호의 경우 "-"(하이픈), "_"(밑줄), " "(반각 공백)만 사용할 수 있습니다.

Running mode

컨트롤러의 실행 모드를 선택합니다.
[기본] Free mode
[설정 범위] Free mode / Repeat mode (Basic mode / Sequence mode) / External control mode

Controller's Wireless frequency

무선 통신에 사용할 컨트롤러 주파수 채널을 선택합니다.
[기본] 2.4GHz
[설정 범위] 2.4GHz (Auto / Channel 1 ~ 13) / 5GHz (Auto / Channel 36, 40, 44, 48)
* 채널 12와 13은 중국과 한국에서 사용할 수 없습니다.

External access point

외부 액세스 포인트를 통해 통신을 활성화할 수 있습니다. P73 참조
[기본] OFF (비활성화됨)
[설정 범위] OFF (비활성화됨) / ON (활성화됨)
* "Tool IP"를 "Auto (DHCP)"로 설정하면 도구의 IP 주소를 관리하지 않고도 네트워크를 구성할 수 있습니다. P13 참조

Tool's Wireless frequency

외부 액세스 포인트를 사용할 때 도구가 사용하는 채널을 선택합니다.
[기본] Auto
[설정 범위] Auto / 2.4GHz (Auto / Channel 1 ~ 13) / 5GHz (Auto / Channel 36, 40, 44, 48)
* "Auto"로 설정하면 "2.4GHz"와 "5GHz" 중에서 사용 가능한 채널이 자동으로 선택됩니다.
* 채널 12와 13은 중국과 한국에서 사용할 수 없습니다.

Tool IP

도구의 IP 주소를 설정하는 방법을 선택할 수 있습니다.
[기본] Manual
[설정 범위] Auto (DHCP) / Manual
* 이 설정은 "External access point"가 ON으로 설정된 경우에만 사용할 수 있습니다.

WLAN mode

컨트롤러는 내장된 액세스 포인트를 사용할 때 도구의 IP 주소를 설정하는 방법을 선택할 수 있습니다.
[기본] Normal mode
[설정 범위] Normal mode / Bridge mode
* "Normal mode": 도구의 IP 주소가 자동으로 할당됩니다.
* "Bridge mode": 도구의 IP 주소가 수동으로 지정됩니다.

Pairing key

페어링 키를 활성화할 수 있습니다.
[기본] ON (활성화됨)
[설정 범위] OFF (비활성화됨) / ON (활성화됨)

Reset key

재설정 키를 활성화할 수 있습니다.
[기본] ON (활성화됨)
[설정 범위] OFF (비활성화됨) / ON (활성화됨)

Controller's clock

컨트롤러의 시계를 설정합니다.
시간을 업데이트하려면 [Adjust clock] 을 클릭합니다.

Timezone

컨트롤러의 시계를 조정할 때 원하는 시간대를 설정할 수 있습니다.

NTP server

자동 시계 조정을 사용하는 경우 NTP 서버를 설정합니다.

Tool keep alive

컨트롤러가 Wireless Communication Mode 에서 도구의 가용성을 확인하는 시간 간격을 설정합니다.
응답하지 않는 도구는 오프라인으로 감지된 다음 연결이 끊어집니다.

[기본] 30 s
[설정 범위] 10 s ~ 3600 s

Storage capacity

저장 용량 부족 알림을 활성화 또는 비활성화하고 용량 부족 시 동작을 설정합니다.
[기본] 알림 - OFF,
용량 부족 시 동작 - Automatically delete data
[설정 범위] 알림 - OFF/ON(남은 용량 10/20/30/40/50%),
용량 부족 시 동작 - Suspend operation/Automatically delete data

기본 설정은 “Automatically delete data” 입니다.
필요에 따라 “Suspend operation” 을 선택하기 전에 데이터 처리 방법을 잘 고려하십시오.

NOK results

체결 실패 결과 처리 방법을 선택합니다.

[기본] Store data only
[설정 범위] Report to system / Store data only / Ignore

Operation when WLAN disconnected

무선 통신이 일시적으로 중단되는 경우 동작을 선택합니다.
[기본] Suspend tool
[설정 범위] Suspend tool / Enable fastening (Until batch size or 20 rundowns)

자세한 내용은 “무선 통신 연결이 끊긴 상태에서 도구의 동작” 을 참조하십시오.
P80 참조

Buzzer

버저의 음량과 의미를 선택합니다.

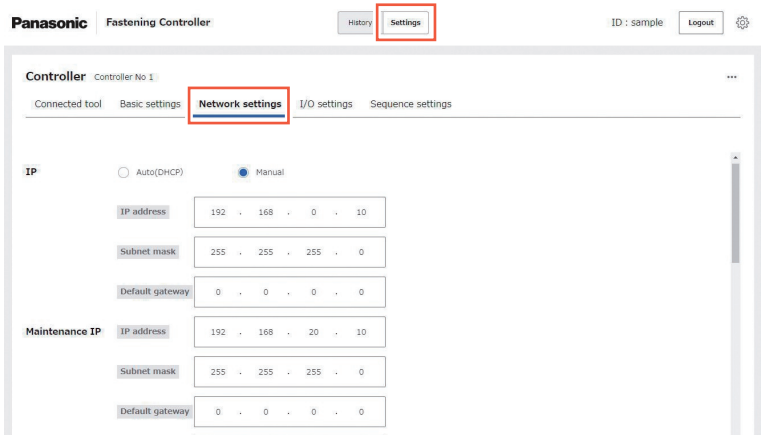
[기본] Volume - LOW,
Beep - 모두 선택됨
[설정 범위] Volume - OFF / LOW / HIGH,
Beep - 각 항목 선택 또는 선택 해제

Barcode reader settings

바코드 리더를 연결하여 체결 내역 데이터에 판독 정보를 추가할 수 있습니다.
[Reading Test] 바코드 리더에서 판독 정보를 표시합니다.
[Bluetooth settings] 이 설정은 Bluetooth 유형 바코드 리더를 연결할 때 사용됩니다.
“Search” 버튼은 연결 가능한 장치를 표시합니다.
“Pairing” 을 사용하여 연결할 장치를 선택하십시오.
이미 연결된 경우 MAC 주소/장치 이름이 표시됩니다.
“Cancel registration” 을 선택하여 연결을 취소할 수 있습니다.

네트워크 설정

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Network settings” 탭을 선택합니다.
컨트롤러의 네트워크 설정을 할 수 있습니다.



■설정 항목

IP

이더넷 포트(네트워크용)의 IP 주소를 설정합니다.

[기본] Manual
[설정 범위] Auto (DHCP) / Manual

* “Manual”
[기본] IP address - 192.168.0.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Maintenance IP

이더넷 포트(유지 보수용)의 IP 주소를 설정합니다.

[기본] IP address - 192.168.20.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

WLAN

도구와의 무선 통신을 위한 IP 주소(컨트롤러 측)를 설정합니다.

[기본] IP address - 192.168.100.1
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Atlas Open Protocol

Atlas Open Protocol 관련 매개 변수를 설정합니다.
자세한 내용은 “개방형 프로토콜 통신을 통한 연결” 을 참조하십시오. P61 참조

RS232C

이는 TOYOTA MOTOR CORPORATION에만 적용되는 설정입니다. 외부 장치에서 제어할 수 있습니다.
[기본] Disable
[설정 범위] Disable / Enable

Step flow after tightening NG

이 설정은 조임 NG 결과가 발생할 경우 다음 조임으로 진행할 수 있는지 여부를 결정합니다.
[기본] Keep
[설정 범위] Next (다음 조임을 수행할 수 있습니다.) / Keep (다음 조임을 수행할 수 없습니다.)

Access point

도구와의 무선 통신을 위한 내부 액세스 포인트를 설정합니다.

[기본] SSID - 컨트롤러의 모델 번호-MAC 주소
Security - WPA2
[설정 범위] SSID - 최대 32자의 영숫자 문자
Security - WPA2

External access point

사용할 외부 액세스 포인트를 설정합니다.

[기본] SSID - 비어 있음
Security - 비어 있음
Password - 비어 있음
[설정 범위] SSID - 최대 32자의 영숫자 문자
Security - 개방형/WPA2
Password - 8~63자의 영숫자 문자

* 기호의 경우 “"”, “¥”, “,”, “'(역따옴표)”만 사용할 수 있습니다.
* 이 옵션은 기본 설정에서 “External access point” 가 “ON” 으로 설정된 경우에만 활성화됩니다.

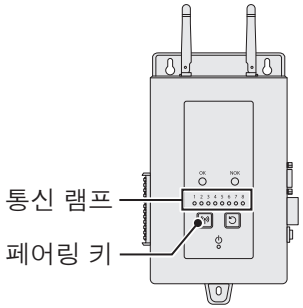
- “IP” 및 “Maintenance IP” 의 IP 주소는 동일한 서브넷을 사용하지 마십시오. (“Subnet mask” 에 기본값(255.255.255.0)을 설정할 때 “192.168.0” 또는 “192.168.20” 에 해당하는 부분에 다른 값을 설정합니다.)
- “Atlas Open Protocol” 과 “RS232C” 중 하나만 켤 수 있습니다. 동시에 사용할 수 없습니다.

컨트롤러에서 페어링 모드 시작

"장치의 키 사용" 또는 "설정 화면의 설정"을 통해 컨트롤러를 페어링 모드로 전환할 수 있습니다.
페어링 모드 2분 동안 적용 범위 내의 도구에서 페어링 모드를 시작하여 자동으로 페어링을 설정합니다.
시간 내에 페어링이 설정되지 않으면 페어링 모드가 종료됩니다.
* 페어링을 시작한 후 컨트롤러가 페어링 모드로 전환될 때까지 시간이 걸릴 수 있습니다.

■장치의 키 사용

컨트롤러 장치에서 페어링 키를 사용합니다.
등록되지 않은(램프 꺼짐) 번호의 통신 램프를 선택하고 페어링 키를 길게 눌러 페어링 모드로 전환합니다.
자세한 내용은 다음 절차를 참조하십시오.



(4번 도구를 등록하려면)

1 컨트롤러에서 페어링 키를 4번 눌러 4번 도구를 선택합니다.

4번 통신 램프가 깜박입니다.



2 4번을 선택하고 있는 동안 컨트롤러의 페어링 키를 길게 눌러 4번 도구의 페어링 모드로 이동합니다.

페어링 모드에서 4번 통신 램프가 빠르게 깜박이기 시작합니다.



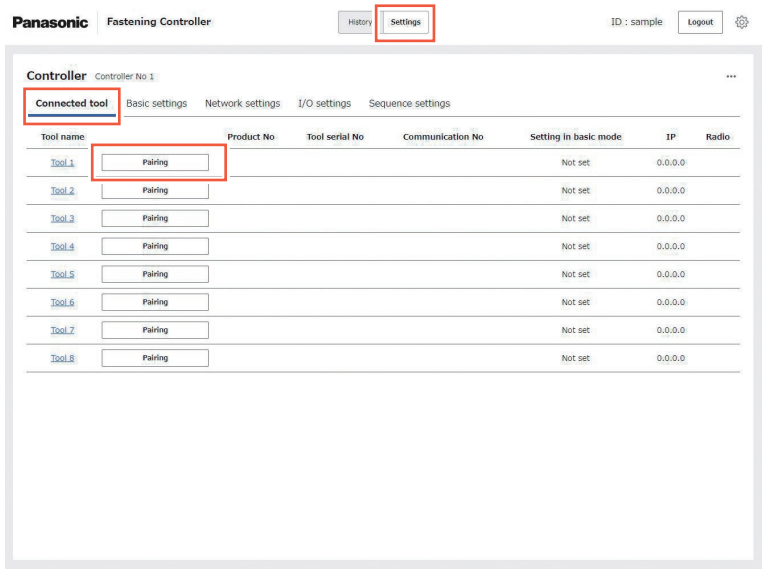
3 4번 도구를 작동시켜 페어링을 설정합니다.

4번 통신 램프가 켜져 있습니다.
도구 작동 방법은 "도구에서 페어링 모드 시작" 을 참조하십시오.
P34 참조



■설정 화면의 설정

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 "Connected tool" 탭을 선택합니다.
"Connected tool" 화면에서 원하는 도구 번호의 [Pairing] 을 클릭합니다.
컨트롤러가 페어링 모드로 전환된 후 "도구의 페어링 모드 시작" 의 절차를 수행합니다.
P34 참조



<참조용> 예비 도구로 교체

페어링된 도구에 결함이 있어 동일한 모델 번호의 새 것으로 교체할 때 페어링을 취소 P34 참조 한 다음 페어링 P32 참조 을 수행하면 체결 매개 변수 및 기타 설정이 자동으로 전송될 수 있습니다.
* 제품 번호가 다른 도구와 페어링하려면 페어링을 취소하여 현재 페어링 정보를 삭제한 후 페어링하십시오. P38 참조

페어링 완료 후 표시

페어링이 완료된 후 설정 화면에 페어링된 도구의 정보가 표시되지 않으면 설정 화면에서 디스플레이 업데이트를 수행합니다.

* "Bridge mode" 에서나 "External access point" 가 활성화되었을 때 페어링 등록을 시작하기 전에 도구의 IP 주소를 설정하십시오.

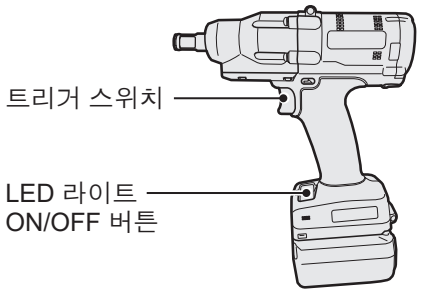
도구에서 페어링 모드 시작

도구에서 페어링 모드를 시작하기 전에 컨트롤러를 페어링 모드로 전환합니다.

■절차

1 **배터리 팩을 설정합니다. LED 라이트 ON/OFF 버튼을 누른 상태에서 트리거 스위치를 당깁니다.**

도구가 페어링 모드로 전환됩니다.
무선 통신이 자동으로 설정되고 페어링 등록이 완료됩니다.
* 자세한 내용은 도구의 사용설명서를 참조하십시오.
* 페어링에 실패하는 경우 컨트롤러에서 페어링을 취소한 다음 다시 시도하십시오.

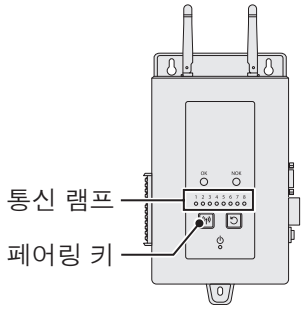


페어링 취소

"장치의 키 사용" 또는 "설정 화면의 설정" 을 통해 컨트롤러에서 페어링 등록을 취소할 수 있습니다.

■장치의 키 사용

컨트롤러 장치에서 페어링 키를 사용합니다.
등록을 취소(램프 점등)할 도구 번호의 통신 램프를 선택하고 페어링 키를 길게 눌러 페어링 등록을 취소합니다.
자세한 내용은 다음 절차를 참조하십시오.



(4번 도구를 취소하려면)

1 **컨트롤러에서 페어링 키를 4번 눌러 4번 도구를 선택합니다.**

4번 통신 램프가 깜박입니다.



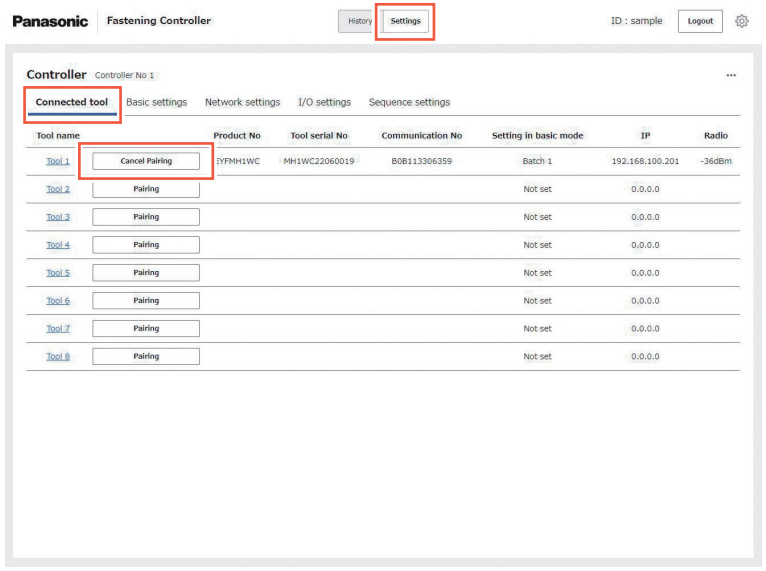
2 **4번을 선택하고 있는 동안 컨트롤러의 페어링 키를 길게 눌러 4번 도구의 페어링 등록을 취소합니다.**

페어링이 취소되면 4번 통신 램프가 깜박임을 멈추고 꺼집니다.



■설정 화면의 설정

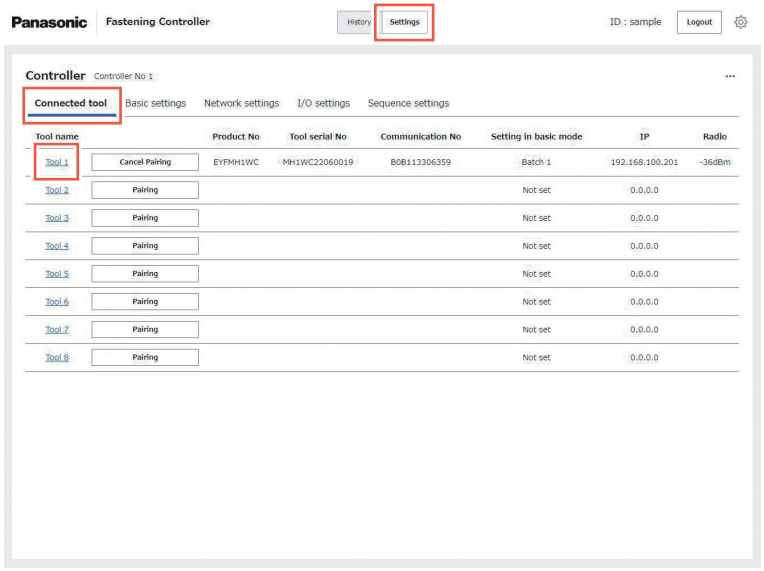
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 "Connected tool" 탭을 선택합니다.
"Connected tool" 화면에서 원하는 도구 번호의 [Cancel Pairing] 을 클릭합니다.



* 도구가 꺼져 있거나 다른 이유로 컨트롤러가 도구와 통신할 수 없는 경우 페어링 취소 확인 대화 상자에서 [Force to unpair] 를 선택하십시오.

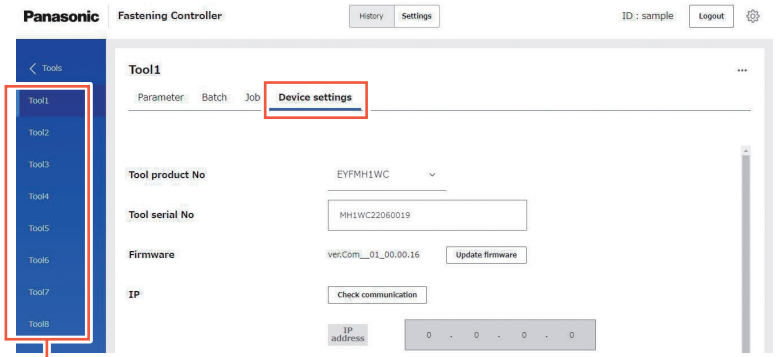
도구 화면 표시

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다.
“Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.
도구 번호에 대한 화면이 표시됩니다.



도구 설정 화면 표시

도구 번호에 대한 화면의 “Device settings” 탭에서 도구의 기본 설정을 지정하고 공통 매개 변수를 입력할 수 있습니다.
* 도구를 전환하려면 도구 목록에서 원하는 도구를 선택합니다.



도구 목록

도구 설정 항목

Tool product No

도구 제품 번호를 선택합니다.

[기본] 비어 있음
[설정 범위] 풀다운 메뉴에서 선택 가능

* 사전에 페어링을 설정하면 자동으로 선택됩니다.
* 페어링 후에는 도구 제품 번호를 변경할 수 없습니다. 페어링을 취소한 다음 변경하십시오.

Tool serial No

도구의 장치 식별을 설정하고 표시할 수 있습니다.

[기본] 모델 ID 5 자리 + 일련 번호 8 자리(제조연도 2 자리 + 월 2 자리 + 생산 로트 4 자리)

[설정 범위] 영숫자 13~16 자

* 정보가 변경되면 모델 번호가 올바르게 인식되지 않을 수 있습니다. 관리 규칙에 따라 필요하지 않는 한 변경하지 마십시오.

Firmware

도구 통신 부분의 펌웨어 버전이 표시됩니다.
펌웨어를 업데이트하려면 [Update firmware] 를 클릭합니다.
업데이트 방법은 “펌웨어 업데이트” 를 참조하십시오. P95 참조

IP

도구와의 무선 통신을 위한 IP 주소(도구 측)를 설정합니다.

[기본] IP address - 192.168.100.201(도구 1)~208(도구 8)
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

* Bridge mode 에서나 “External access point” 가 활성화된 경우 모두 “0.0.0.0” 이 됩니다.

Tool’s clock

도구의 시계가 표시됩니다. 시계를 조정하려면 [Adjust to controller] 를 클릭합니다.

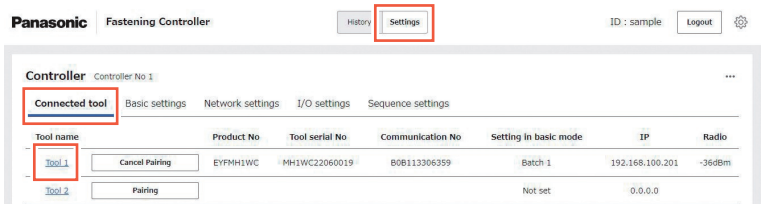
• 다른 설정 항목은 도구의 사용설명서를 참조하십시오.

등록 정보 삭제

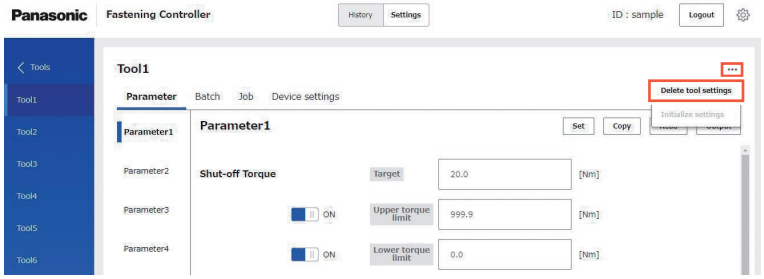
도구 사용을 중지하거나 제품 번호가 다른 도구를 페어링하려면 페어링 정보를 삭제하십시오.
* 사전에 페어링을 취소하십시오.

1 **상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다.**
“Connected tool” 화면이 표시됩니다.

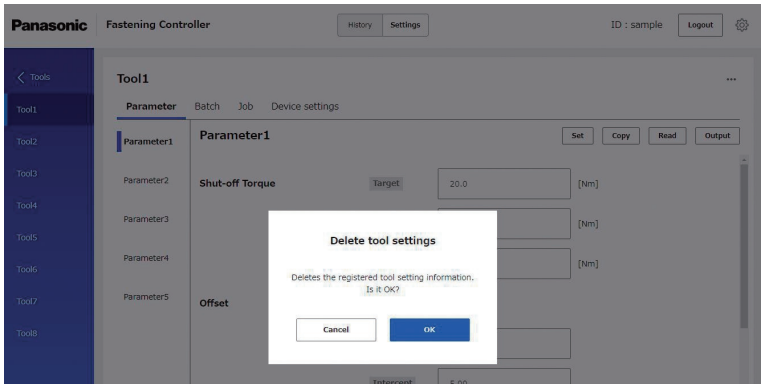
2 **“Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.**
도구 번호에 대한 화면이 표시됩니다.



3 **… (도구 옵션 키)를 클릭한 다음 [Delete tool settings] 를 클릭합니다.**
“Delete tool settings” 화면이 표시됩니다.



4 **“Delete tool settings” 화면에서 [OK] 를 클릭합니다.**

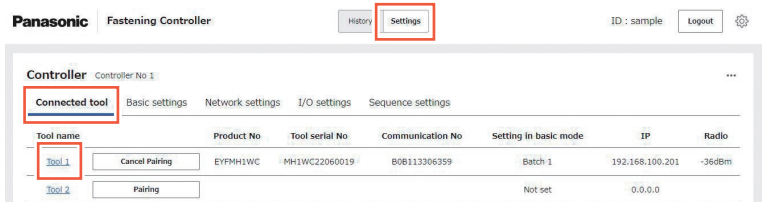


공장 설정으로 재설정

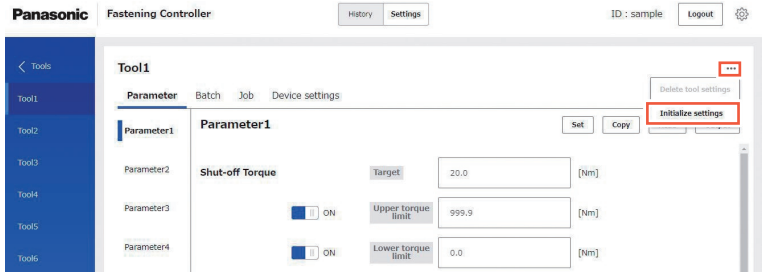
도구를 공장 설정으로 재설정할 수 있습니다.
* 재설정하면 페어링이 취소됩니다.

1 **상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다.**
“Connected tool” 화면이 표시됩니다.

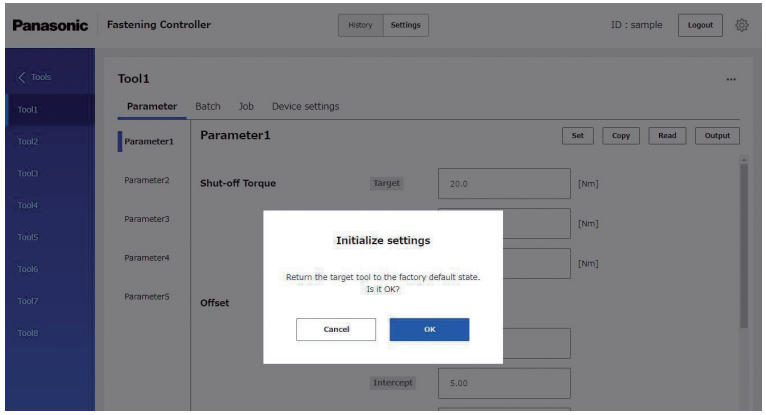
2 **“Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.**
도구 번호에 대한 화면이 표시됩니다.



3 **… (도구 옵션 키)를 클릭한 다음 [Initialize settings] 를 클릭합니다.**
“Initialize settings” 화면이 표시됩니다.



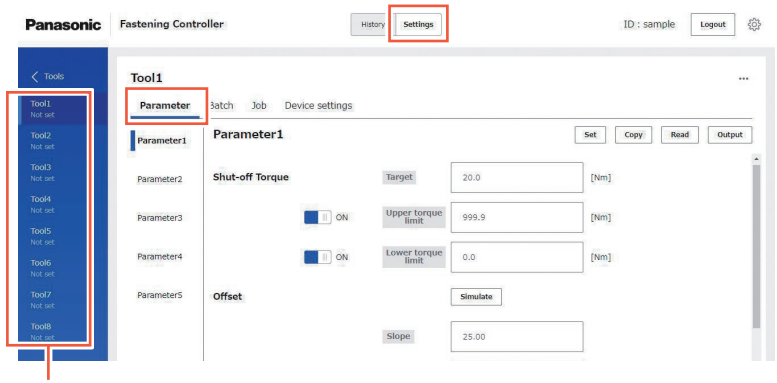
4 **“Initialize settings” 화면에서 [OK] 를 클릭합니다.**



도구 체결 매개 변수 설정

매개 변수 설정

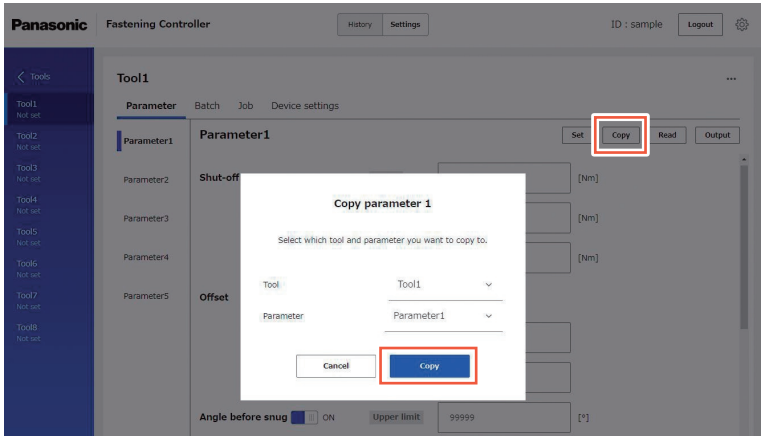
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “연결된 도구” 탭을 선택합니다.
“Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.
도구 번호에 대한 화면에서 “Parameter” 탭을 선택하여 설정합니다.
각 도구에 대해 5개의 매개 변수(매개 변수 1~5)를 설정할 수 있습니다.
* 도구를 전환하려면 도구 목록에서 원하는 도구를 선택합니다.



도구 목록

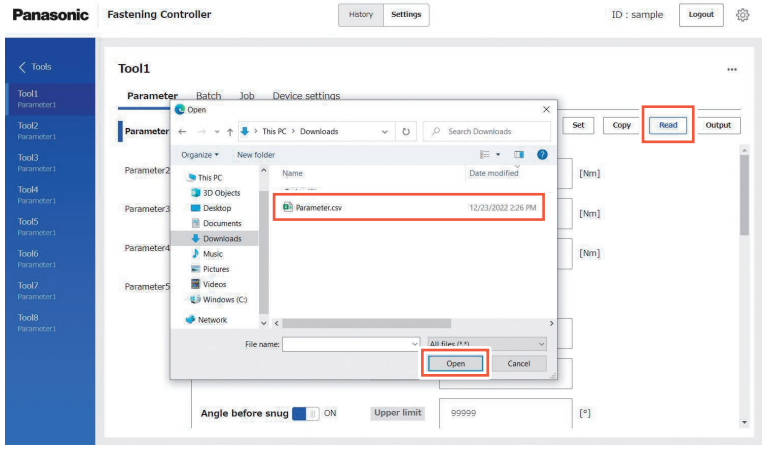
매개 변수 복사

설정된 매개 변수를 복사하여 새 매개 변수를 생성하거나 다른 도구에서 사용할 수 있습니다.
도구 번호에 대한 화면의 “Parameter” 탭에서 [Copy] 를 클릭하여 매개 변수 복사 화면을 표시합니다. 화면에서 대상을 선택하고 [Copy] 를 클릭합니다.



매개 변수 로드

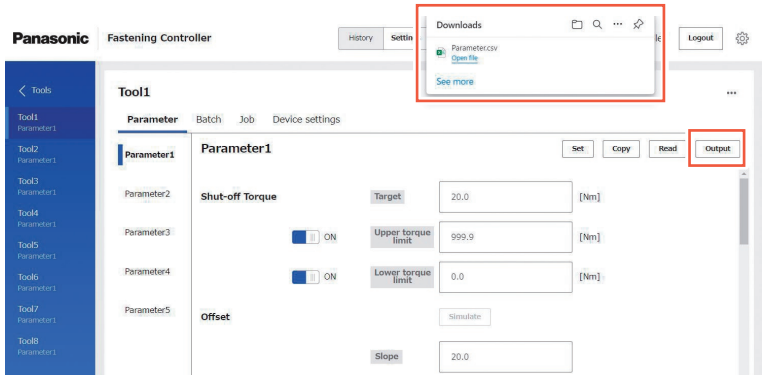
구성용 PC에 저장된 매개 변수 파일을 컨트롤러에 불러와 매개 변수를 등록할 수 있습니다.
“Tool Manager” 로 생성한 매개 변수 파일을 로드할 수도 있습니다.
도구 번호에 대한 화면의 “Parameter” 탭에서 [Read] 를 클릭하여 매개 변수 파일을 엽니다.



매개 변수 내보내기

생성된 매개 변수를 구성용 PC 로 내보낼 수 있습니다.
내보낸 파일을 백업으로 사용하여 다른 컨트롤러에 복사하거나 다른 구성용 PC로 옮길 수 있습니다.
도구 번호에 대한 화면의 “Parameter” 탭에서 [Output] 을 클릭해 매개 변수 파일을 저장합니다.

내보낸 매개 변수 파일을 편집하지 마십시오.
편집하면 올바르게 읽지 못할 수 있습니다.

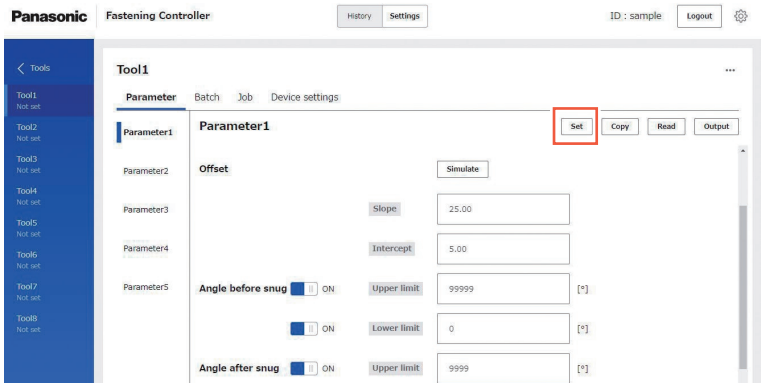


매개 변수 등록

컨트롤러 실행 모드 중 “Free mode” 에서 도구를 제어하는 데 사용하기 위해 매개 변수를 등록합니다.

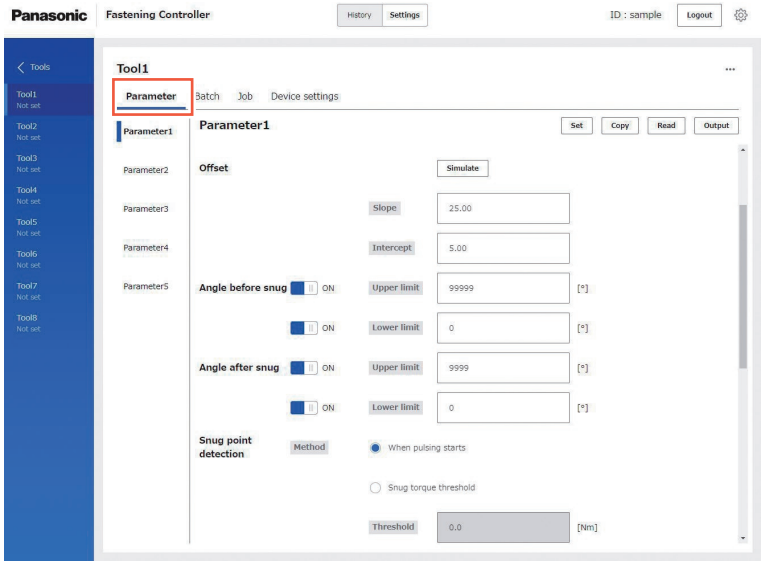
* “Repeat mode” 와 “External control mode” 에서는 사용되지 않습니다.
(“Free mode”, “Repeat mode”, “External control mode” 는 “실행 모드 설정” 을 참조하십시오. P49 참조

도구 번호에 대한 화면의 “Parameter” 탭에서 [Set] 을 클릭합니다.



매개 변수 항목

체결 매개 변수 항목을 설정합니다.
자세한 내용은 도구의 사용설명서를 참조하십시오.

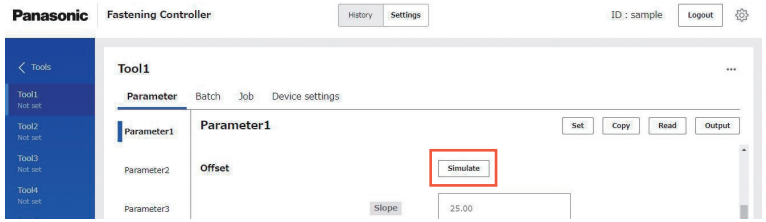


■오프셋 설정(매개 변수, 참조 ①)

토크 출력 값과 실제 측정 값이 일치하도록 오프셋을 설정합니다.

1 도구 번호에 대한 화면의 “Parameter” 탭에서 “Offset” 에 있는 [Simulate] 를 클릭합니다.

“Offset” 페이지가 표시됩니다.



2 값을 입력하고 설정하고 [Apply] 를 클릭합니다.

“Socket length” 와 “Shut-Off Torque” 를 입력합니다.
[Apply] 를 클릭하여 입력 값을 도구로 보냅니다.
도구가 오프셋 모드로 전환됩니다(T2에 표시된 대로).

3 도구를 사용하여 실제 작업을 수행한 다음 [Get data] 를 클릭합니다.

체결 기록 로그가 “Offset” 페이지의 기록 목록에 추가됩니다.

* [Get data] 를 클릭하면 도구 체결 준비가 완료(“C 모드”)되지만 오프셋 설정이 완료될 때까지 정상적인 체결을 시작하지 마십시오.

4 획득한 체결 기록 로그를 선택한 상태에서 실제 측정된 토크(다시 체결) 값을 입력하고 [Calculate] 를 클릭합니다.

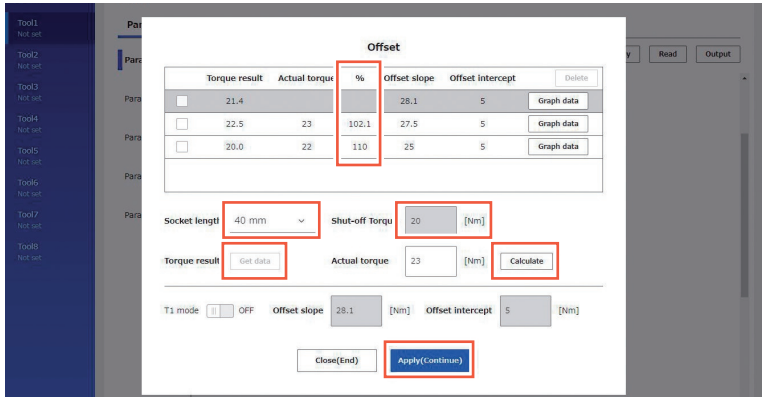
도구의 실제 측정된 토크와 출력 토크를 일치시키는 오프셋이 자동으로 계산됩니다.

5 오프셋이 업데이트되었는지 확인하고 [Apply] 를 클릭합니다.

조정된 값이 도구로 전송됩니다.

6 차이가 충분히 작아질 때까지 3~5 단계를 반복합니다.

* “%” 열의 값을 95% 에서 105% 범위 내로 유지하십시오.



[T1 mode 정보]
오프셋 설정 화면에서 [T1 mode] 를 선택하면 컨트롤러가 최소 출력 모드로 전환됩니다.
([T1 mode] 선택을 취소하면 컨트롤러가 "Offset Mode" 로 되돌아갑니다.)



T1 mode
[설명] 목표 토크가 컨트롤러의 토크 제어 범위의 하한에 가까워졌을 때 토크 제어가 잘 되는지 확인할 수 있습니다. 이 모드에서는 컨트롤러가 분당 최소 카운트(최소 출력)에서 차단됩니다. 이때 작업 기록 로그는 저장되지 않습니다. 이 모드에서 작업한 후 토크 게이지 또는 토크 렌치를 사용하여 컨트롤러의 출력 토크가 목표 토크를 초과하지 않았는지 확인하십시오. 이 모드에서 출력 토크가 목표 토크를 초과하면 컨트롤러 장치를 일부 작업에 사용하지 못할 수 있습니다.

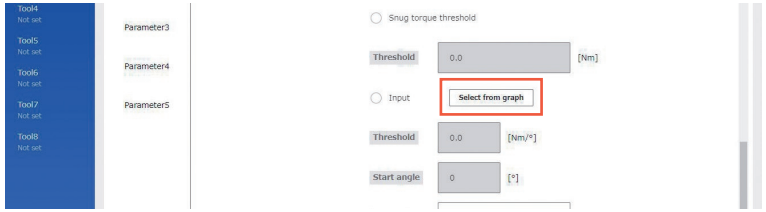
* 오프셋을 설정하는 동안 다른 도구를 사용한 체결이 일시 중지됩니다.

■스너그 포인트 설정(매개 변수, 참조 ②)

파형을 기반으로 스너그 포인트를 설정할 수 있습니다.

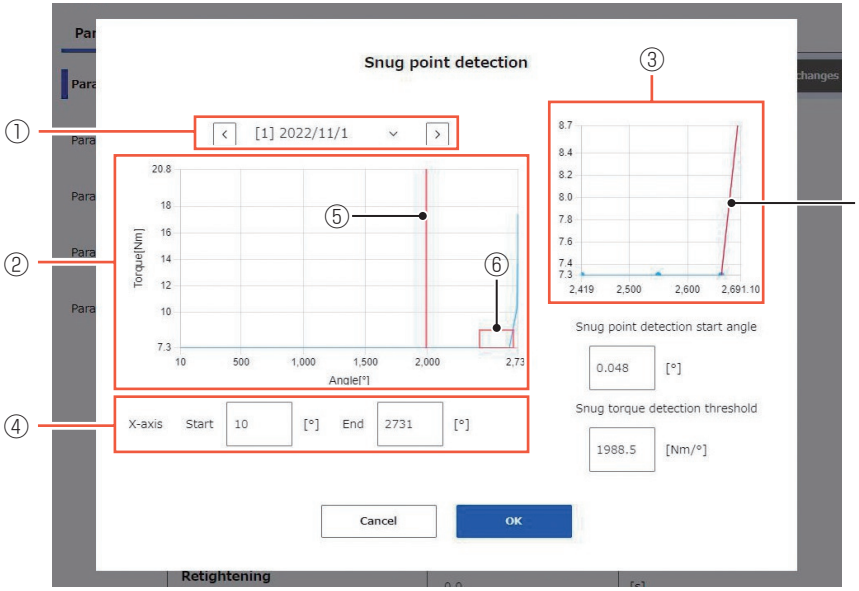
1 도구 번호에 대한 화면의 "Parameter" 탭에서 "Snug point detection" 에 있는 [Select from graph] 를 클릭합니다.

- 도구의 현재 파형을 보여주는 "Snug Point detection" 화면이 표시됩니다.
- 체결 기록 데이터는 참조용으로 필요합니다. 한 번 이상 체결 후 설정합니다.
- 화살표(①)와 함께 사용할 파형을 전환할 수 있습니다.



2 그래프에서 임계값을 설정합니다.

- 기본 창(②)은 전체 파형을 표시하고 하위 창(③)은 전체 파형의 특정 부분을 확대합니다.
- 그래프 아래 "X-axis"(④)에서 시작 작도와 종료 각도를 입력하여 기본 창에 표시되는 파형 범위를 변경할 수 있습니다.
- 세로 막대를 이동시켜 스너그 포인트 감지 시작 각도(⑤)를 설정할 수 있습니다.
- 기본 창에서 선택 프레임(⑥) 위치를 조정하여 하위 창의 표시 범위를 변경합니다.
- 하위 창(③)에서 설정할 임계값을 선택합니다.

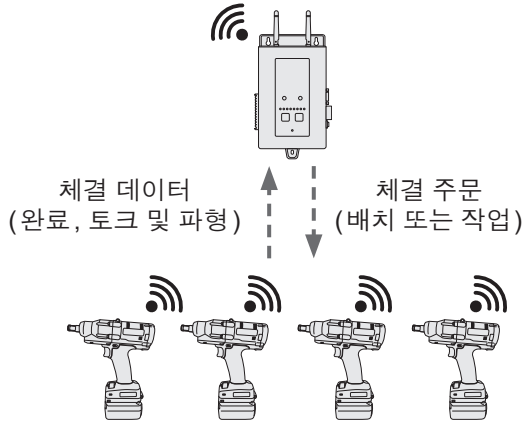


체결 제어 모드 설정

도구로 체결 제어

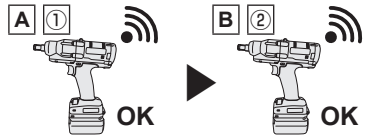
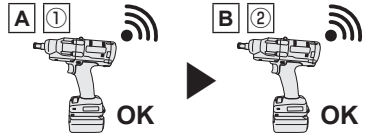
컨트롤러는 체결을 위해 최대 8개의 연결된 도구를 제어할 수 있습니다.
각 체결 작업의 체결 데이터를 수신하여 체결 수량을 카운트합니다.

최대 연결 장치 수: 8



일반적인 체결 제어 조합

다양한 체결 제어 설정 조합을 생성할 수 있습니다. 아래와 같은 일반적인 조합을 참조하십시오.

모드	[Free mode]	[Repeat mode]	
		[Basic mode]	[Sequence mode]
통과 기준	– (수량은 지정되지 않음)	목표 수량 체결이 완료됨	도구는 지정된 주문으로 각각의 목표 수량 체결 완료
[Batch] "단일 설정 값" (동일한 조건에서 체결) * 단일 유형의 공작물	 설정 값 / 목표 수량: 10 Nm / ∞ Parameter	 설정 값 / 목표 수량: 10 Nm / 10 Batch	 설정 값 / 목표 수량: 10 Nm / 10; 20 Nm / 5 Batch 및 Sequence
[Job] 다중 설정 값 (다른 조건에서 체결) * 여러 유형의 공작물		 설정 값 / 목표 수량: 10 Nm / 2; 20 Nm / 3; 30 Nm / 5 Job	 설정 값 / 목표 수량: 10 Nm / 2; 20 Nm / 3; 30 Nm / 5; 20 Nm / 5; 30 Nm / 10 Job 및 Sequence
주의	–	* 작업에는 최대 10단계가 포함될 수 있습니다.	* 시퀀스에는 최대 10단계가 포함될 수 있습니다.

작동

등록 가능한 조합 수

컨트롤러에 등록할 수 있는 조합의 수는 아래와 같습니다.

컨트롤러의 모드		도구의 설정	등록 가능한 조합 수
Free mode		Parameter	○ 도구당 5개의 조합
Repeat mode	Basic mode (독립 제어)	Batch	○ 도구당 5개의 조합
		Job	○ 도구당 5개의 조합
	Sequence mode (순차 제어)	Batch/Job	○ 5개의 조합
External control mode		–	○

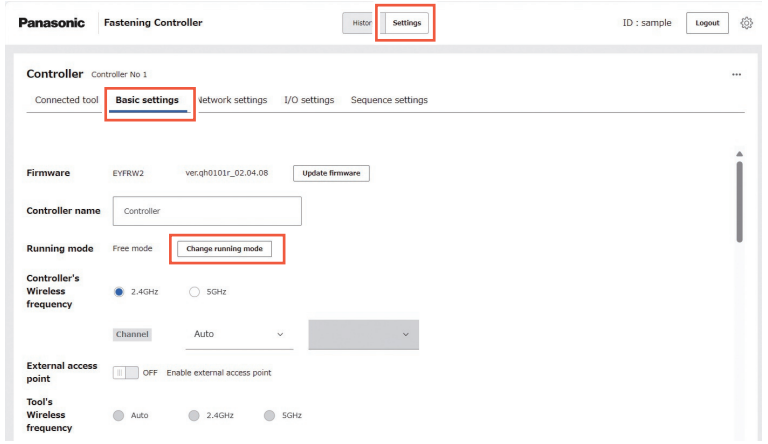
실행 모드 설정

컨트롤러의 실행 모드를 아래와 같이 설정합니다.

1 **상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 "Basic settings" 탭을 선택합니다.**

2 **"Basic settings" 탭에서 [Change running mode] 를 클릭합니다.**

"Change running mode" 화면이 표시됩니다.



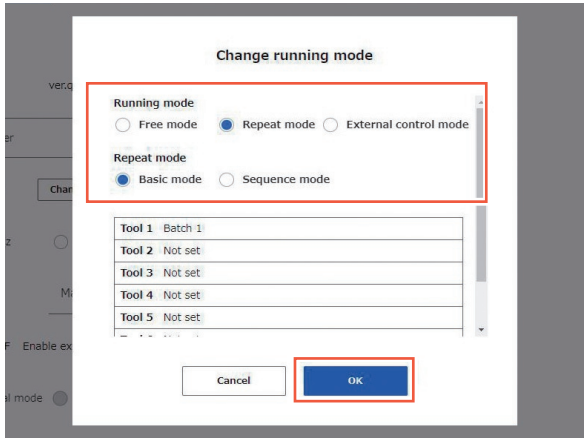
3 **"Running mode" 를 선택하고 [OK] 를 클릭합니다.**

실행 모드가 설정됩니다.

"Free mode", "Repeat mode", "External control mode" 중에서 실행 모드를 선택합니다.

"Repeat mode" 의 경우, "Basic mode" 또는 "Sequence mode" 를 선택합니다.

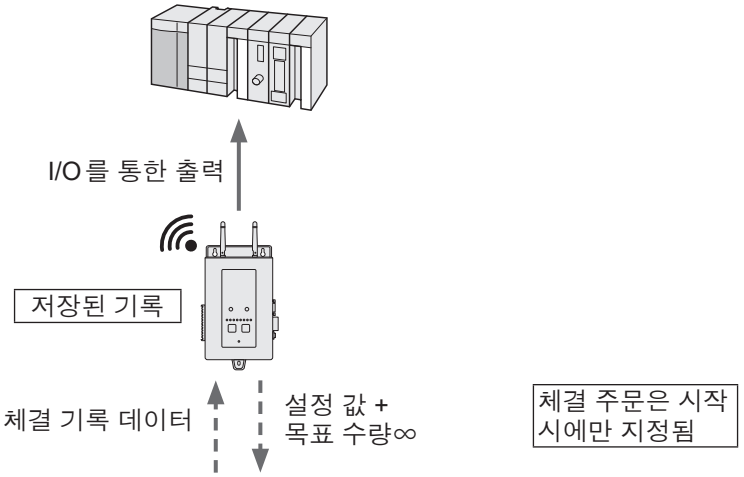
P50 ~ 53 참조

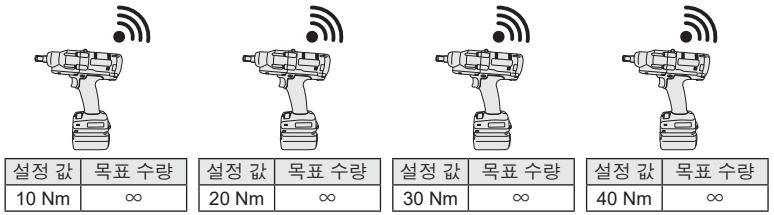


* "Free mode" 로 설정하기 전에 "Parameter" 를 등록합니다.
* "Repeat mode" 로 설정하기 전에 "Batch/Job" 을 등록합니다.

■ Free mode

이 모드에서는 체결 수량 지정 없이 무조건 체결할 수 있습니다.
도구는 체결을 위해 미리 등록된 매개 변수를 사용합니다.
최대 8개의 도구가 독립적으로 작동할 수 있습니다.
I/O 출력 설정이 활성화됩니다.
* 외부 장치에서 체결 수량을 카운트할 때 사용하는 모드입니다.





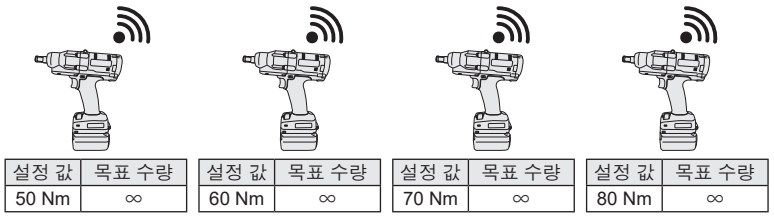
설정 값	목표 수량
10 Nm	∞

설정 값	목표 수량
20 Nm	∞

설정 값	목표 수량
30 Nm	∞

설정 값	목표 수량
40 Nm	∞

최대 8개의 도구를 동시에 제어할 수 있음



설정 값	목표 수량
50 Nm	∞

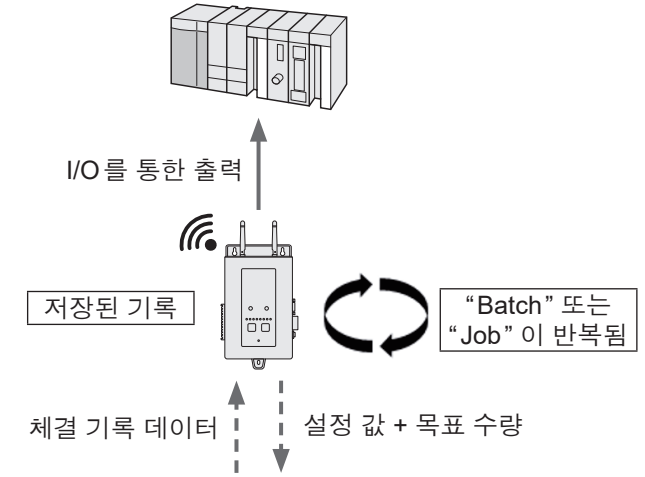
설정 값	목표 수량
60 Nm	∞

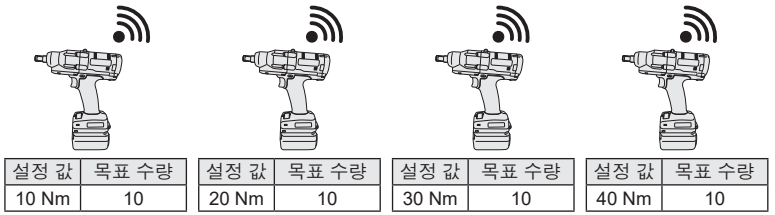
설정 값	목표 수량
70 Nm	∞

설정 값	목표 수량
80 Nm	∞

■ Repeat mode (Basic mode)

이 모드는 “Batch” 또는 “Job” 프로세스를 반복합니다.
도구는 체결을 위해 미리 등록된 “Batch” 또는 “Job” 설정을 사용합니다.
최대 8개의 도구가 독립적으로 작동할 수 있습니다.
I/O 출력 설정이 활성화됩니다.





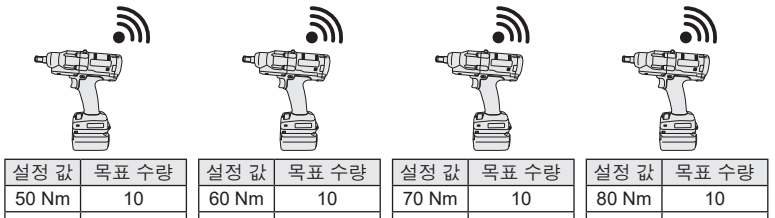
설정 값	목표 수량
10 Nm	10

설정 값	목표 수량
20 Nm	10

설정 값	목표 수량
30 Nm	10

설정 값	목표 수량
40 Nm	10

최대 8개의 도구를 동시에 제어할 수 있음



설정 값	목표 수량
50 Nm	10
60 Nm	5
70 Nm	5

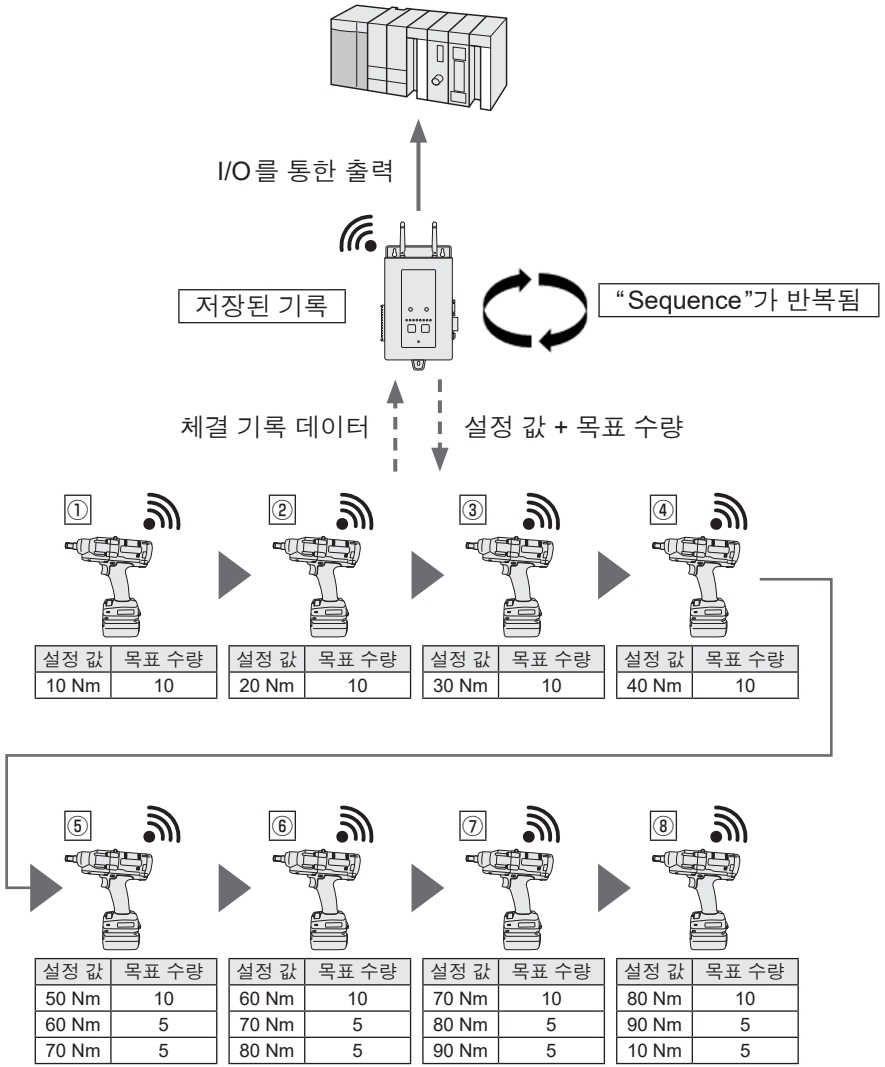
설정 값	목표 수량
60 Nm	10
70 Nm	5
80 Nm	5

설정 값	목표 수량
70 Nm	10
80 Nm	5
90 Nm	5

설정 값	목표 수량
80 Nm	10
90 Nm	5
10 Nm	5

■ Repeat mode (Sequence mode)

이 모드는 사용 가능한 도구가 주문대로 제어되는 “Sequence” 프로세스를 반복합니다.
도구는 순차 체결을 위해 미리 등록된 “Sequence” 설정을 사용합니다.
최대 10단계까지 설정할 수 있습니다. 시퀀스는 최대 8개의 도구를 지원하지만 한 번에 하나의 도구만 작동시킬 수 있습니다.
I/O 출력 설정이 활성화됩니다.



설정 값	목표 수량
10 Nm	10

설정 값	목표 수량
20 Nm	10

설정 값	목표 수량
30 Nm	10

설정 값	목표 수량
40 Nm	10

설정 값	목표 수량
50 Nm	10
60 Nm	5
70 Nm	5

설정 값	목표 수량
60 Nm	10
70 Nm	5
80 Nm	5

설정 값	목표 수량
70 Nm	10
80 Nm	5
90 Nm	5

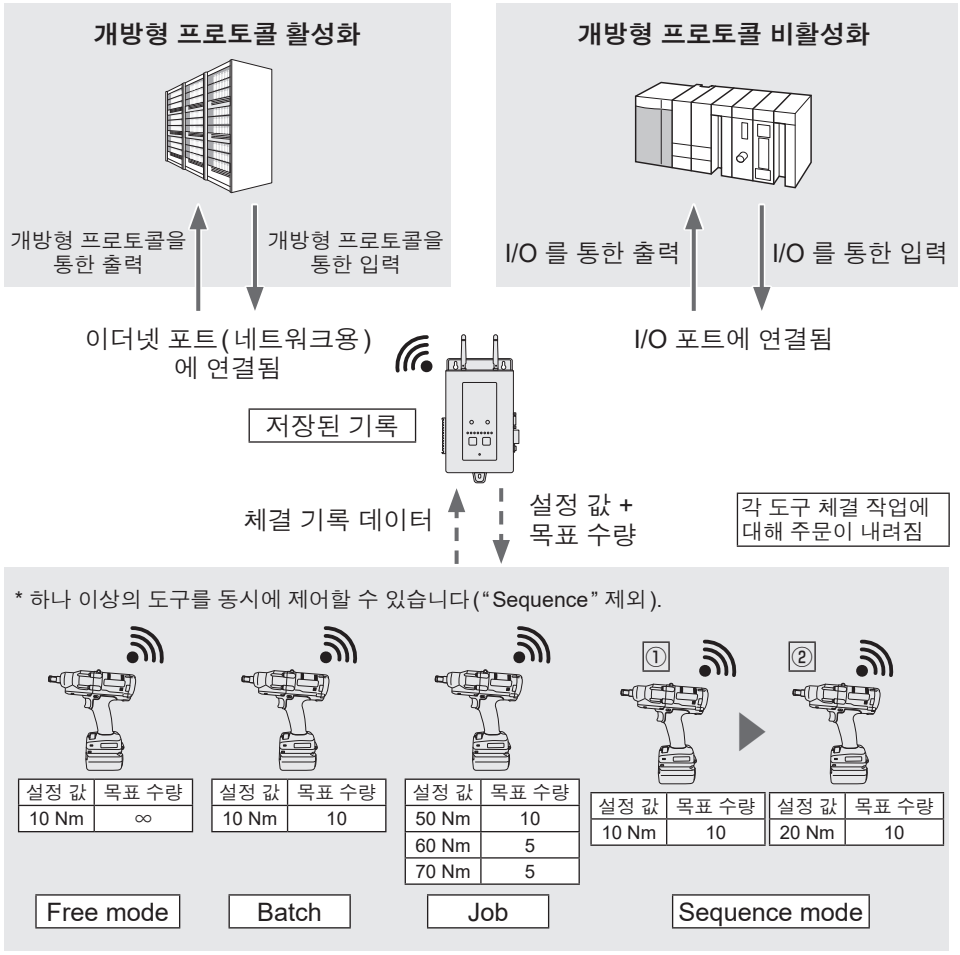
설정 값	목표 수량
80 Nm	10
90 Nm	5
10 Nm	5

■ External control mode

이 모드에서는 외부 장치(호스트 시스템)의 주문에 따라 체결 제어가 가능합니다.
다음 2가지 유형의 제어가 지원됩니다.

● **개방형 프로토콜을 통한 제어(개방형 프로토콜 활성화)**
호스트 시스템이 개방형 프로토콜을 통해 체결을 제어합니다.
최대 8개의 도구를 독립적으로 제어할 수 있습니다.
* 작업 및 시퀀스 제어는 지원되지 않습니다.

● **I/O를 통한 제어(개방형 프로토콜 비활성화)**
외부 장치의 I/O 포트를 통한 입력으로 체결을 제어합니다.
최대 8개의 도구를 독립적으로 제어하거나 순차적으로 제어할 수 있습니다.



설정 값	목표 수량
10 Nm	∞

설정 값	목표 수량
10 Nm	10

설정 값	목표 수량
50 Nm	10
60 Nm	5
70 Nm	5

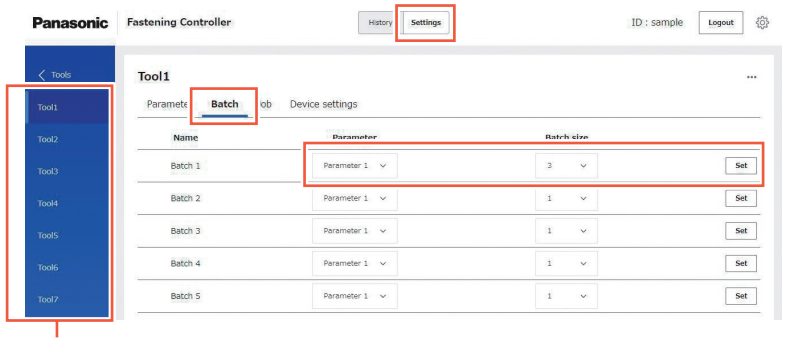
설정 값	목표 수량
10 Nm	10

설정 값	목표 수량
20 Nm	10

* 체결 도중 컨트롤러가 꺼지면 컨트롤러가 켜진 후 체결이 재개되지 않습니다. 외부 장치에서 주문하면 체결이 다시 시작됩니다.
* I/O 출력 설정이 활성화됩니다.

배치 생성(설정)

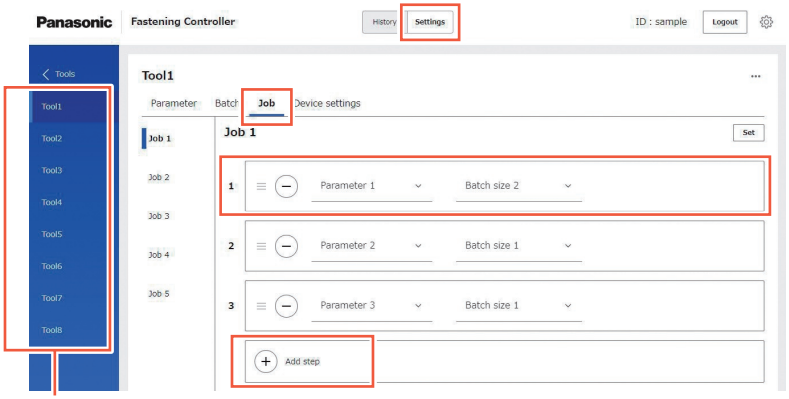
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다. “Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.
도구 번호에 대한 화면에서 “Batch” 탭을 선택하여 설정합니다.
“Parameter” 풀다운 메뉴에서 매개 변수를 선택하고 “Batch size” (체결 수량, 최대 99개)를 설정합니다. [Set] 을 클릭하여 “Repeat mode (Basic mode)” 의 값을 설정합니다.
* 도구를 전환하려면 도구 목록에서 원하는 도구를 선택합니다.
* 최대 5개의 배치를 등록할 수 있습니다.



도구 목록

작업 생성(설정)

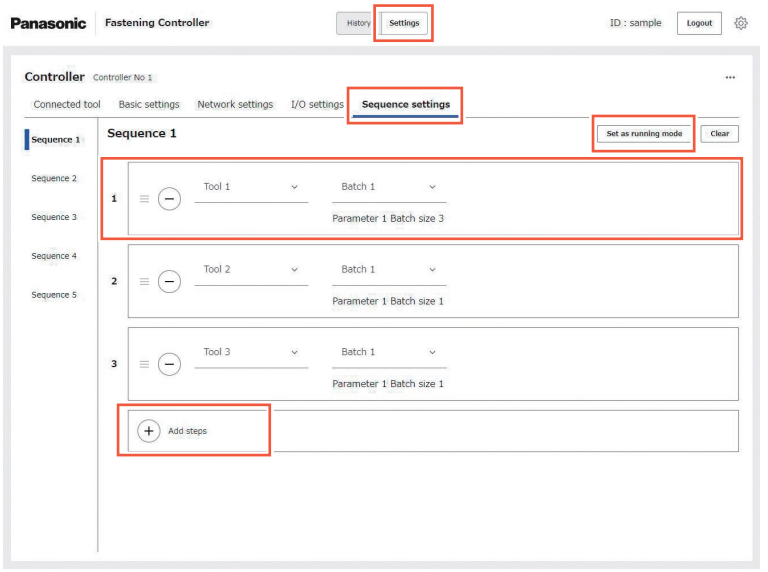
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다. “Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.
도구 번호에 대한 화면에서 “Job” 탭을 선택하여 설정합니다.
“Parameter” 풀다운 메뉴에서 매개 변수를 선택하고 “Batch size” (체결 수량, 최대 99개)를 설정합니다. [Set] 을 클릭하여 “Repeat mode (Basic mode)” 의 값을 설정합니다.
* 최대 10단계를 등록할 수 있습니다.
* 도구를 전환하려면 도구 목록에서 원하는 도구를 선택합니다.
* 최대 5개의 작업을 등록할 수 있습니다.



도구 목록

시퀀스 생성(설정)

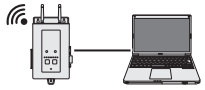
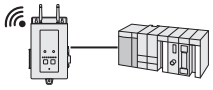
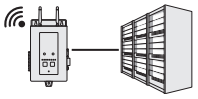
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings]를 클릭하고 “Sequence settings” 탭을 선택합니다.
“Sequence settings” 화면의 “Tool” 풀다운 메뉴에서 도구를 선택하고 “Batch” 또는 “Job” 을 설정합니다.
[Set as running mode] 를 클릭하여 “Repeat mode (Sequence mode)” 에 대한 값을 설정합니다.
* 최대 5개의 시퀀스를 등록할 수 있습니다.
* 최대 10단계를 등록할 수 있습니다.
* 동일한 도구를 시퀀스에서 두 번 이상 사용할 수 있습니다.



외부 장치에 연결

지원되는 외부 장치 유형

컨트롤러는 다음 유형의 외부 장치를 지원합니다.

기능	구성용 PC	PLC	고객의 호스트 시스템
그림			
통신 방법	Ethernet	I/O	Ethernet
통신 프로토콜	http/https	– (ON/OFF 신호만)	개방형 프로토콜을
주 용도	• 체결 기록 보기 및 저장 • 설정 변경	• 완료 및 실패 신호 출력 • 체결 주문 전환	• 체결 기록 내보내기 • 체결 주문 전환
내보낼 수 있는 데이터	• 도구의 일련 번호 • 시간 • 완료 및 실패 결과 • 토크 값, 각도, 체결 시간 길이 • 파형 데이터	• 완료 및 실패 결과 • Batch/job/sequence 완료 • Batch/job/sequence 선택됨 • 도구 활성화	• 도구의 일련 번호 • 시간 • 완료 및 실패 결과 • 토크 값, 각도, 체결 시간 길이 • 파형 데이터
체결 주문 전환	–	• Batch/job/sequence 선택됨	• Parameter/batch 선택됨
기타	웹 브라우저에 표시됩니다. Microsoft Edge 가 권장됩니다.	각 입력 및 출력용 포트 8개	지원되는 명령은 “개방형 프로토콜과 호환되는 명령”을 참조하십시오. **P65 참조** 제어 순서는 각각 검토해야 합니다.

원격 위치에서 구성용 PC에 연결

인증서가 설치된 구성용 PC는 컨트롤러에 원격으로 연결할 수 있습니다.
한 번에 하나의 구성 기능 액세스만 허용됩니다.
연결하려면 웹 브라우저에 원하는 컨트롤러의 IP 주소를 입력합니다.
P23 참조



I/O를 통해 외부 장치에 연결

I/O를 통한 연결

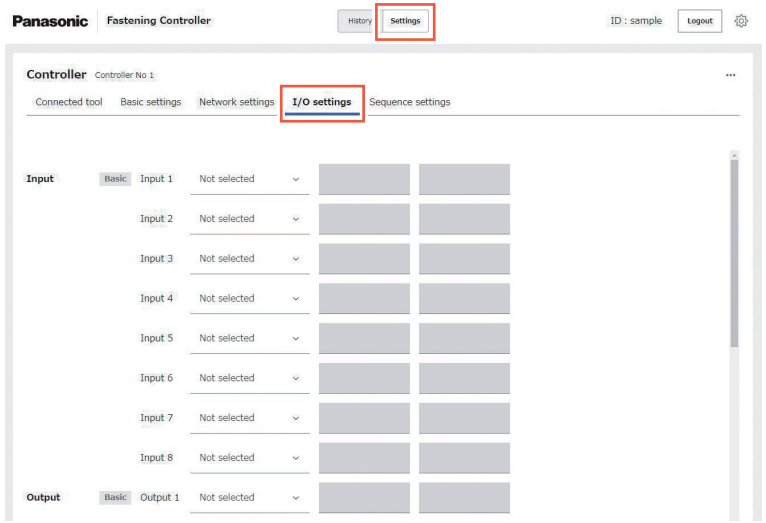
8개의 입력 포트와 8개의 출력 포트에 지원되는 명령을 원하는 대로 할당할 수 있습니다.
“I/O settings” 화면에서 할당합니다.
포트에 할당할 수 있는 명령은 다음과 같습니다.

입력	지원되는 명령
1	Batch (도구 1~5) Job (도구 1~5) Sequence (1~5) Batch reset (1~8) Reset Suspend tool (1~8) Suspend controller Emergency stop (1~8)
2	
3	
4	
5	
6	
7	
8	

출력	지원되는 명령
1	OK(도구 1~8) NOK(도구 1~8) Batch complete (도구 1~5) Job complete (도구 1~5) Sequence complete (1~5) Tool active (도구 1~8) Batch selected (도구 1~5) Job selected (도구 1~5) Sequence selected (1~5)
2	
3	
4	
5	
6	
7	
8	

I/O 설정

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “I/O settings” 탭을 선택합니다.



* 아직 등록되지 않은 동작이나 이벤트를 지정할 수 있습니다. (직업 선택 및 시퀀스 선택 제외)

작동

입력 포트에 할당된 명령

입력 포트에 할당할 수 있는 명령은 다음과 같습니다.
외부 장치의 신호가 포트 중 하나에 입력되면 할당된 명령이 실행됩니다.

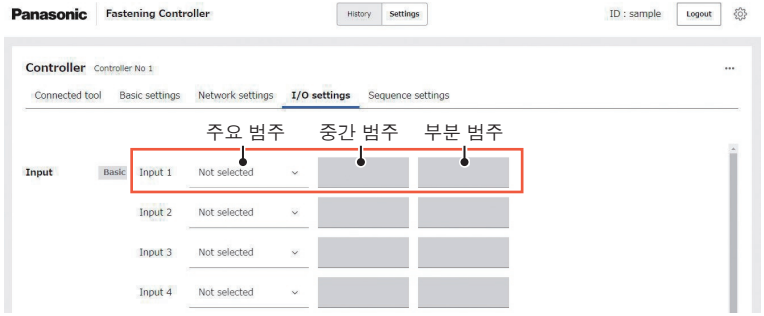
주요 범주(동작)	중간 범주(도구)	부분 범주(배치 번호 등)
Batch	도구 1~8	1-5
Job	도구 1~8	1-5
Sequence	–	1-5
Suspend tool*1	도구 1~8	–
Suspend controller*1	–	–
Batch reset	도구 1~8	–
Reset	–	–
Emergency stop*1	도구 1~8	–

*1 입력 신호가 유지되는 동안에만 활성화됩니다.

"Suspend tool" 또는 "Suspend controller" 명령이 입력인 경우

- "Suspend controller"가 활성 상태인 경우 체결 주문이 허용되지 않습니다.
- "Suspend tool" 이 활성화된 도구 번호의 경우 "Batch" 또는 "Job" 체결 주문이 허용되지 않습니다.
- "Suspend tool" 이 활성화된 도구 번호 이외의 도구 번호에서는 "Batch" 또는 "Job" 체결 주문이 허용됩니다.
- "Suspend tool" 이 활성 상태인 경우 "Sequence" 체결 주문이 허용되지 않습니다. 이때 "Suspend tool" 이 활성화된 도구에 도달할 때까지 프로세스가 계속됩니다.
- "Batch reset" 및 "Reset" 은 체결 주문과 동일한 방식으로 취급됩니다.

주요 범주에서 동작을 선택하고 도구를 선택한 다음 필요에 따라 번호(예: 배치 번호)를 선택합니다.



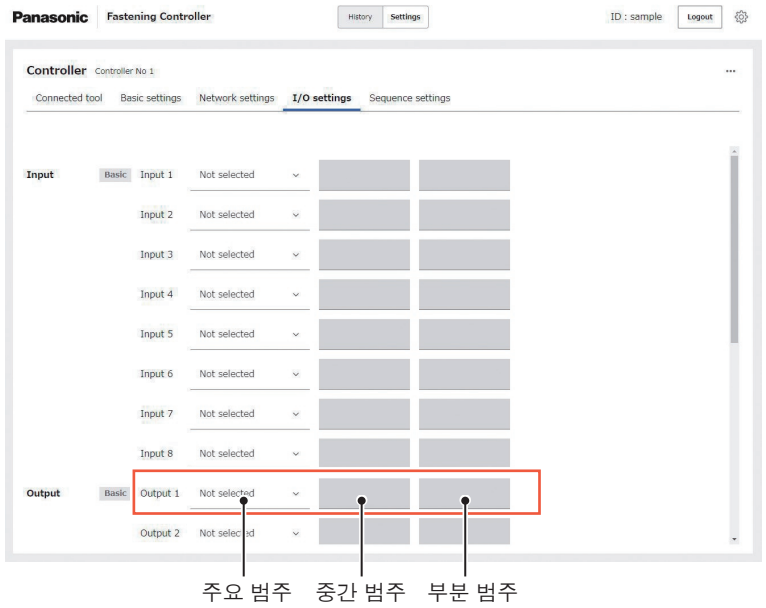
* 할당되지 않은 신호가 입력되면 아무 조치도 취하지 않습니다. (발생 오류 없음)

출력 포트에 할당된 명령

출력 포트에 할당할 수 있는 명령은 다음과 같습니다.
해당 이벤트가 발생하면 컨트롤러는 할당된 명령에 지정된 대로 해당 포트에서 외부 장치로 신호를 출력합니다.

주요 범주(이벤트)	중간 범주(도구)	부분 범주(배치 번호 등)
OK	도구 1~8	–
NOK	도구 1~8	–
Batch complete	도구 1~8	1-5
Job complete	도구 1~8	1-5
Sequence complete	–	1-5
Tool active	도구 1~8	–
Batch selected	도구 1~8	1-5
Job selected	도구 1~8	1-5
Sequence selected	–	1-5

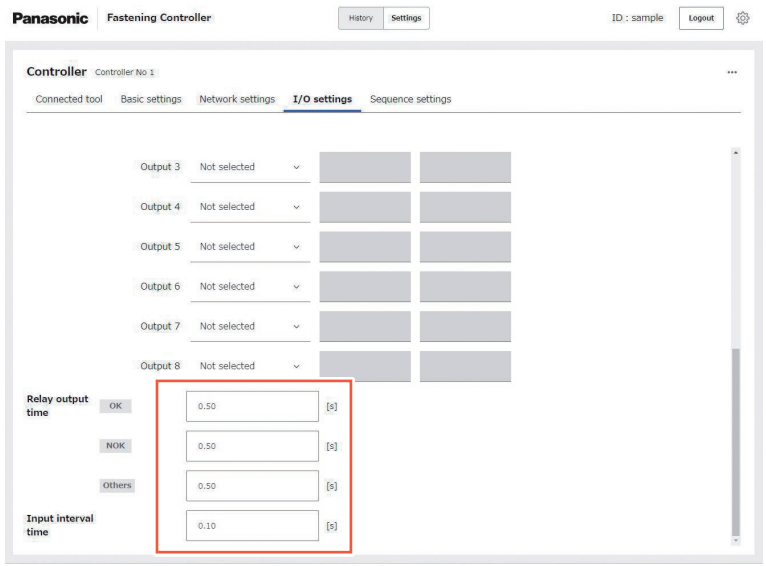
주요 범주에서 이벤트를 선택하고 도구를 선택한 다음 필요에 따라 번호(예: 배치 번호)를 선택합니다.



* 출력 명령을 실행하는 동안 컨트롤러가 꺼지면 컨트롤러가 켜진 후 프로세스가 다시 시작되지 않습니다. (체결 기록 데이터가 저장됩니다.)

기타 설정

아래와 같이 기타 I/O 관련 설정을 지정할 수 있습니다.

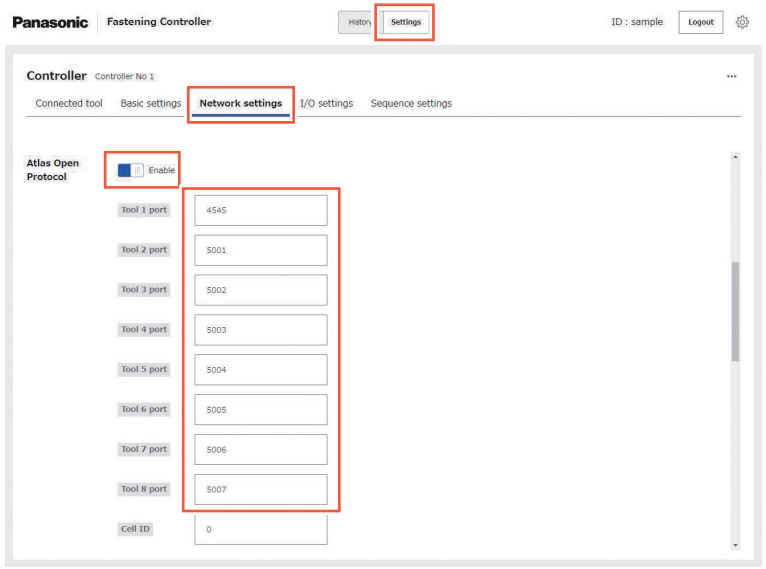


Relay output time (OK)
체결 완료 신호가 릴레이로 출력될 때까지의 시간을 선택합니다. [기본] 0.5 s [설정 범위] 0.01 s~10 s
Relay output time (NOK)
체결 실패 신호가 릴레이로 출력될 때까지의 시간을 선택합니다. [기본] 0.5 s [설정 범위] 0.01 s~10 s
Relay output time (Others)
체결 완료 및 실패 신호 이외의 신호가 릴레이에서 출력될 때까지의 시간을 선택합니다. [기본] 0.5 s [설정 범위] 0.01 s~10 s
Input interval time
연속 입력 신호를 카운트(수락)하지 않는 시간을 선택합니다. 노이즈 등에 의한 중복 카운트를 방지하기 위해 설정합니다. [기본] 0.1 s [설정 범위] 0.01 s~10 s

개방형 프로토콜 통신을 통한 연결

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Network settings” 탭을 선택합니다.

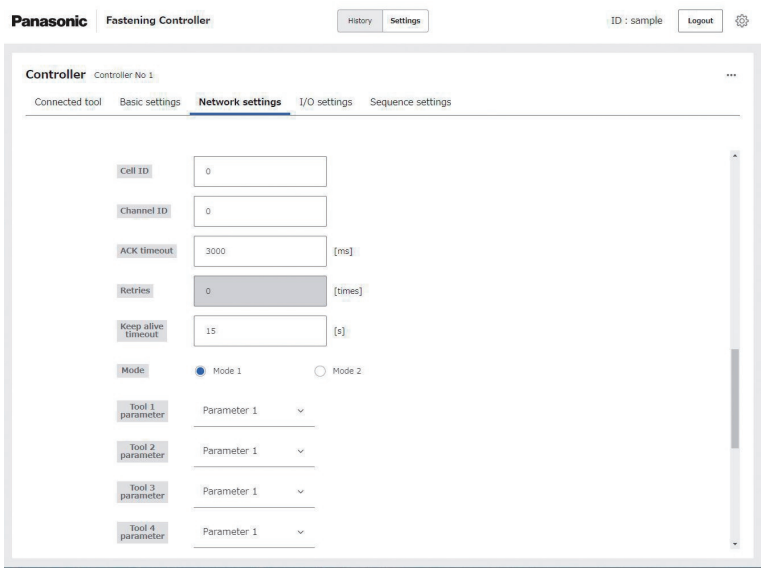
“Atlas Open Protocol” 을 활성화합니다.
각각 사용하는 도구에 포트 번호를 설정합니다.



Tool port
개방형 프로토콜 통신을 위한 포트 번호를 각 도구에 할당합니다. [기본] 도구 1 - 4545, 도구 2~8 - 5001~5007 [설정 범위] 도구 1~8 - 1024~49151

기타 설정

필요에 따라 다른 항목을 설정합니다.



Cell ID

셀 ID를 설정합니다.
[기본] 0
[설정 범위] 0~9999

Channel ID

채널 ID를 설정합니다.
[기본] 0
[설정 범위] 0~99

ACK timeout

컨트롤러의 요청 메시지에 대한 응답을 기다리는 시간을 설정합니다.
[기본] 3000 ms
[설정 범위] 100 ms~30000 ms

Retries

컨트롤러에서 요청 메시지 전송을 반복할 횟수를 설정합니다.
[기본] 0 times
[설정 범위] 선택할 수 없음(고정됨)

Keep alive timeout

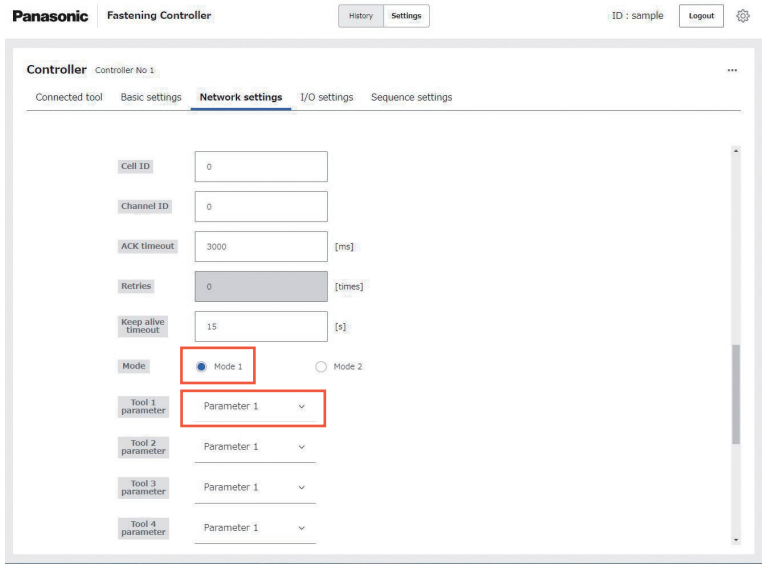
호스트 시스템과의 마지막 통신 후 연결이 끊어진 경우를 판단하는 시간을 설정합니다.
[기본] 15 s
[설정 범위] 1 s~60 s

Mode

실행 모드를 설정합니다.
Mode 1: 미리 등록된 매개 변수로 무조건 체결
Mode 2: 호스트 시스템에서 주문한 매개 변수로 체결
[기본] Mode 1
[설정 범위] Mode 1 / Mode 2

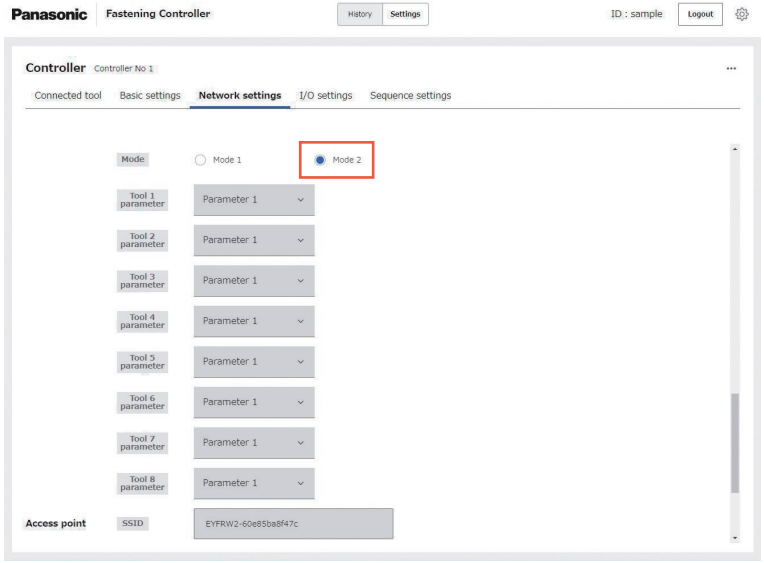
체결 매개 변수 할당(Mode 1)

"Mode 1"(주문한 매개 변수 없음)에는 도구에 미리 등록된 체결 매개 변수가 필요합니다.
아래와 같이 풀다운 메뉴에서 매개 변수를 선택합니다.



체결 매개 변수 할당 (Mode 2)

체결은 외부 장치에서 MID 0018 주문을 통해 명령할 수 있습니다.
체결 주문에 “Parameter” 또는 “Batch” 를 지정할 수 있습니다.



■체결 주문에 “Parameter” 를 지정하려면

ID 의 백 자리에 “0” 을 입력합니다.
십의 자리와 일의 자리는 매개 변수 번호를 나타냅니다.

예: 매개 변수 1 의 ID: 001
매개 변수 5 의 ID: 005

■체결 주문에 “Batch” 를 지정하려면

ID 의 백 자리에 “1” 을 입력합니다.
십의 자리와 일의 자리는 배치 번호를 나타냅니다.

예: 배치 1 의 ID: 101
배치 5 의 ID: 105

* “Job” 및 “Sequence” 제어는 지원되지 않습니다.

■개방형 프로토콜과 호환되는 명령

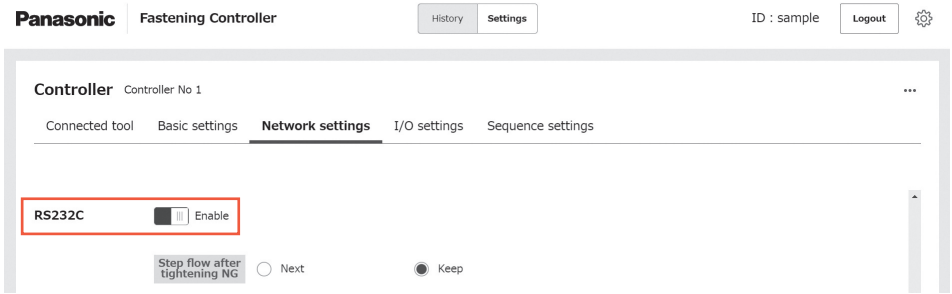
컨트롤러는 다음 명령을 지원합니다.
명령에 대한 자세한 내용은 개방형 프로토콜 사양을 참조하십시오.

MID 0001 Application communication start
개정 1 이 지원됩니다. [내용] 통신 시작
MID 0002 Application communication start acknowledge
개정 1 이 지원됩니다. [내용] 통신 확인
MID 0004 Application command error
개정 1 이 지원됩니다. [내용] 명령 오류
MID 0005 Application command accepted
개정 1 이 지원됩니다. [내용] 명령 수락
MID 0018 Select parameter set, Dynamic Job included
개정 1 이 지원됩니다. 할당 방법은 “체결 매개 변수 할당 (Mode 2)” 을 참조하십시오. P64 참조 [내용] 매개 변수 설정 주문
MID 0042 Disable tool
개정 1 이 지원됩니다. [내용] 도구 비활성화됨
MID 0043 Enable tool
개정 1 이 지원됩니다. [내용] 도구 활성화됨
MID 0050 Vehicle ID number download request
개정 1 이 지원됩니다. [내용] 차량 ID 취득 요청

MID 0060 Last tightening result data subscribe
개정 1과 2가 지원됩니다. [내용] 최종 체결 결과 데이터 등록
MID 0061 Last tightening result data
개정 1과 2가 지원됩니다. [내용] 체결 결과 업로드
MID 0062 Last tightening result data acknowledge
개정 1과 2가 지원됩니다. [내용] 체결 결과 업로드 승인
MID 9999 Keep alive message
개정 1이 지원됩니다. [내용] 가용성 확인

TOYOTA MOTOR CORPORATION 특정 사양을 갖춘 외부 장치에 연결

외부 장치에서의 제어가 지원됩니다.
[Settings] 의 “Network settings” 탭에서 “RS232C” 를 활성화합니다.

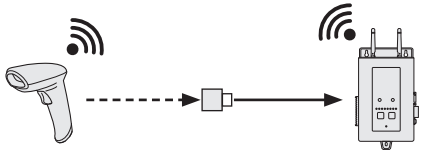


RS232C
이는 TOYOTA MOTOR CORPORATION에만 적용되는 설정입니다. 외부 장치에서 제어할 수 있습니다. [기본] Disable [설정 범위] Disable / Enable
Step flow after tightening NG
이 설정은 조임 NG 결과가 발생할 경우 다음 조임으로 진행할 수 있는지 여부를 결정합니다. [기본] Keep [설정 범위] Next (다음 조임을 수행할 수 있습니다.) / Keep (다음 조임을 수행할 수 없습니다.)

이는 펌웨어 버전 2.03.00 이상에서만 지원됩니다.
펌웨어를 업데이트하는 방법은 “펌웨어 업데이트”를 참조하십시오.
P95 참조

설정

시중에서 판매하는 바코드 리더를 연결하여 체결 내역 데이터와 연동하면서 판독 정보를 저장할 수 있습니다.
이는 제품을 체결 내역에 연결하는 데 사용할 수 있습니다.

연결	통신 방법	중요
 바코드 리더 무선 수신기 Panasonic 컨트롤러	무선 2.4 GHz 또는 Bluetooth	• 제품 정보 (제조 일련번호 등) 를 읽고 이를 내역 데이터에 반영합니다.

유선 USB 유형 바코드 리더를 사용하지 마십시오.

적용 가능한 장치

다음 바코드 리더가 컨트롤러와 호환됩니다.

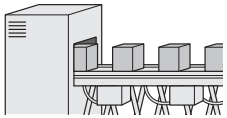
항목	설명
통신 인터페이스	USB-HID
키보드 레이아웃	US
지원되는 문자	반각 영숫자 문자, 기호 지원되는 코드 / 코드 설명 (예상 정보) 반각 숫자 / 0-9 반각 알파벳 문자 / A-Z, a-z 기호 / !"#$%&'()*+,-./:;<=>?@[¥]^_`{|}~
허용 가능한 1D 코드	JAN, EAN, UPC, CODE39, ITF
허용 가능한 2D 코드	QR 코드 모델 1/2, 마이크로 QR
허용 가능한 문자 수	100자 (최대)

권장 모델
Bluetooth: Honeywell Xenon XP 1952g, ZEBRA DS2278

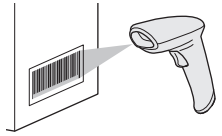
작업 프로세스 흐름

아래 절차에 따라 체결 내역 데이터와 연결하여 제품 정보를 저장할 수 있습니다.

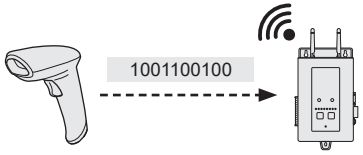
1 **제품은 라인을 따라 이동합니다.**



2 **바코드 리더로 제품 정보를 읽습니다.**

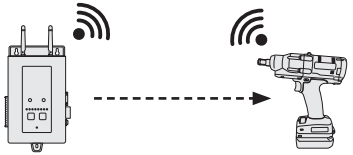


3 **바코드 리더에서 읽은 정보는 컨트롤러로 전송됩니다.**

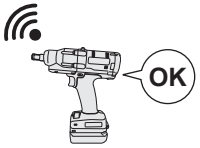


4 **체결 명령은 컨트롤러에서 도구로 전송됩니다.**

* 이 단계는 3단계 전이나 후에 올 수 있습니다.



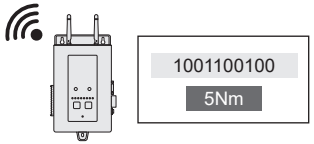
5 **도구를 사용하여 체결 작업을 수행합니다.**



6 **체결 작업 결과(예: 토크)는 컨트롤러로 전송됩니다.**



7 **컨트롤러에 보관된 판독 정보와 체결 작업 결과는 서로 연결되어 저장소에 저장됩니다.**



8 **바코드 판독 정보가 업데이트될 때까지(또는 작업이 완료될 때까지) 5~7단계를 반복합니다.**

설정 절차

설정 절차는 바코드 리더의 사양에 따라 다릅니다.

■무선 2.4 GHz 방식(전용 무선 수신기 사용)
아래 절차에 따라 연결합니다.
(2~3단계는 필수가 아닙니다.)

■Bluetooth 방식(전용 무선 수신기 없음)
별도로 Bluetooth 무선 수신기를 준비한 후 아래 절차에 따라 연결하십시오.

사용 가능한 Bluetooth 무선 수신기

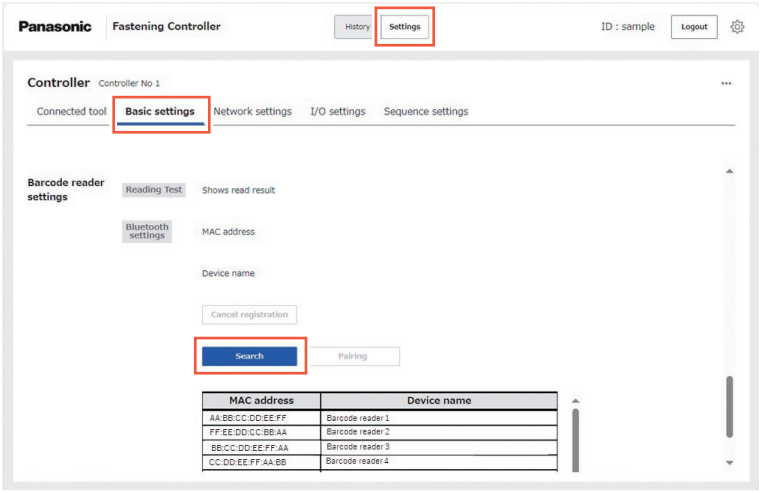
- Bluetooth 버전: Ver4.0 과 호환
- Linux OS와 호환 (전용 드라이버가 필요하지 않은 OS만 해당)

권장 모델
EDIMAX BT-8500

1 **바코드 리더의 무선 수신기를 컨트롤러의 USB-A 포트에 연결합니다.**

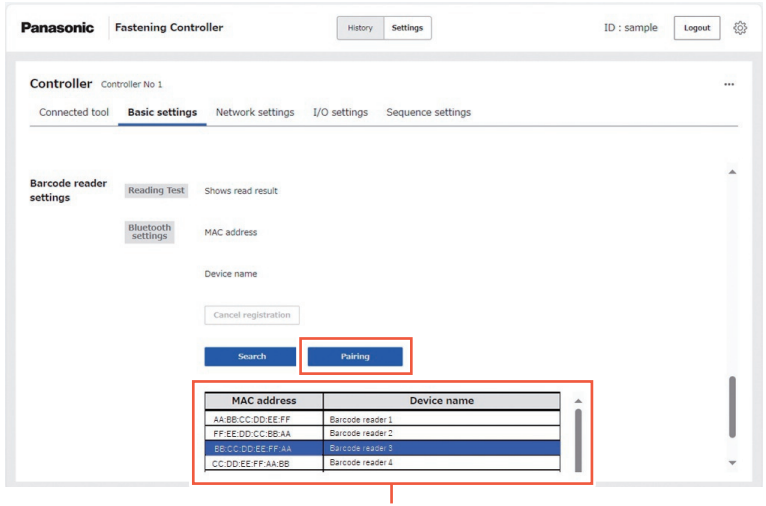
2 **상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings]를 클릭하고 "Basic settings" 탭을 선택한 다음 "Barcode reader settings" 에서 "Search" 를 클릭합니다.**

* 사양에 따라 바코드 리더를 페어링 모드로 전환하십시오.



3 장치 이름 목록에서 연결할 바코드 리더를 선택하고 “Pairing” 을 누르십시오.

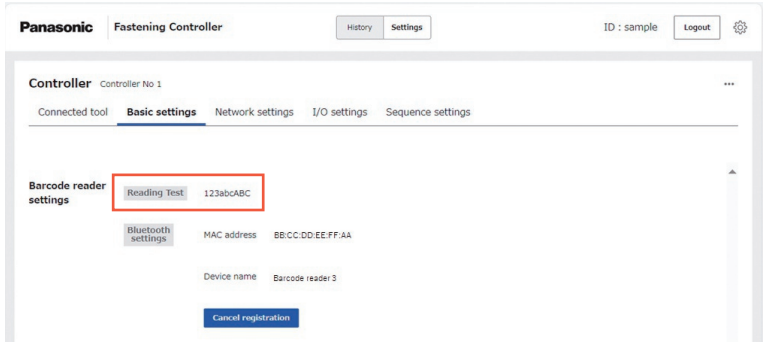
바코드 리더와 페어링됩니다.



장치 이름 목록

- 검색 상태는 약 10초간 유지됩니다.
- 페어링이 등록되면 두 번째부터 자동으로 다시 연결됩니다.
  * 바코드 리더 사양에 따라 페어링을 다시 해야 할 수도 있습니다.
  * 페어링에 실패하면 컨트롤러에서 페어링을 취소한 다음 다시 시도하십시오.

4 바코드 정보를 읽고 “Reading Test” 에서 정보가 올바르게 표시되는지 확인하십시오.

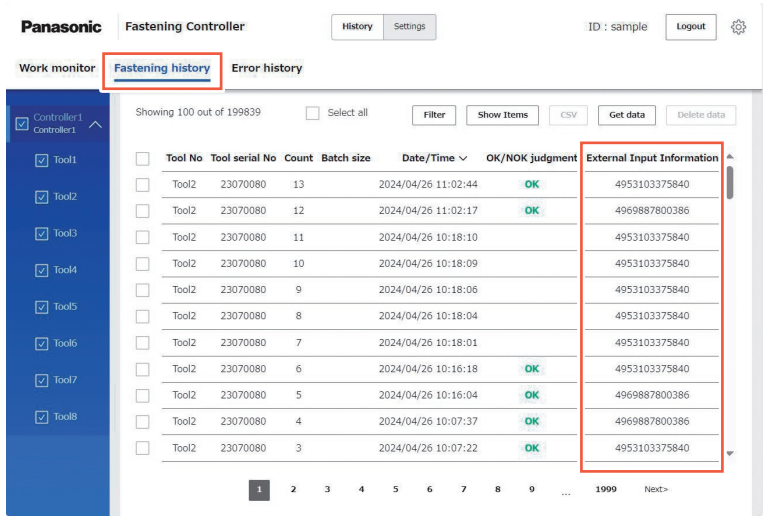


5 바코드 리더로 정보를 읽은 후 체결 작업을 수행합니다.

판독 데이터는 체결 내역 데이터의 “External Input Information” 에 표시됩니다.

작동 중 중요 사항

- 바코드 판독 수신 상태에서는 “체결 OK 램프” 가 깜박입니다.
  작업 중 바코드 판독 수신 상태가 활성화되어 있는지 작업 전에 확인하십시오.



판독 값에 대한 중요 사항

판독 값은 다음과 같습니다.

- 판독한 다음 컨트롤러가 기록한 모든 도구의 작업 결과에 반영됩니다.
- 컨트롤러가 꺼진 상태일 때는 보관되지 않습니다.
- 새로 읽은 정보로 덮어씁니다.
- 다음 조건이 충족될 때까지 보관됩니다.

Running mode	데이터 보관 조건
Free mode	데이터는 업데이트될 때까지 보관됩니다.
Repeat mode (Basic mode)	“Batch”/“Job” 이 완료될 때까지입니다. 또는 데이터는 업데이트될 때까지 보관됩니다.
Repeat mode (Sequence mode)	“Sequence” 가 완료될 때까지입니다. 또는 데이터는 업데이트될 때까지 보관됩니다.
External control mode * 개방형 프로토콜을 통한 제어	VIN 정보에 우선순위가 있으므로 추가되지 않습니다.
External control mode * I/O를 통한 제어	“Batch”/“Job”/“Sequence” 가 완료될 때까지입니다. 또는 데이터는 업데이트될 때까지 보관됩니다.

- 사용하는 바코드 리더의 장치 사양에 따라서는 컨트롤러와의 연결을 위해 세부적인 설정이 필요할 수 있습니다. 이 기능을 사용하기 전에 장치의 사용설명서와 설정을 주의 깊게 읽으십시오.
- 0.5초 이내에 데이터를 연속적으로 읽는다면 정보가 통합될 것이므로 읽는 간격을 띄워주십시오.
- 컨트롤러와 동시에 하나의 바코드 리더만 작동할 수 있습니다. 여러 대의 리더를 연결하면 오작동이 발생할 수 있습니다.

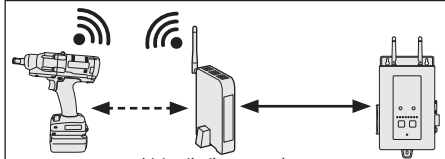
라이선스

Bluetooth® 워드 마크와 로고는 Bluetooth SIG, Inc.가 소유한 등록 상표이며 Panasonic Corporation 은 라이선스에 따라 이러한 마크를 사용합니다. 기타 상표 및 상호는 해당 소유자의 자산입니다.

이 설명서에 표시된 다양한 이름, 회사 이름 및 제품 이름은 각 회사의 상표 또는 등록 상표입니다. 참고로 이 문서에서는 일부 TM 또는 ® 기호가 생략되었습니다.

설정

컨트롤러는 내장된 액세스 포인트 대신 외부 액세스 포인트를 사용하여 무선 통신을 통해 도구에 연결할 수 있습니다.
컨트롤러는 설치된 위치에 관계없이 도구를 제어할 수 있습니다.
액세스 포인트와 컨트롤러를 유선 LAN 에 연결합니다.
* 무선 범위와 성능은 사용하는 액세스 포인트에 따라 달라집니다.

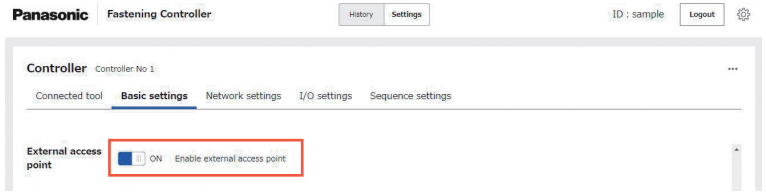
연결	통신 방법	중요
	Ethernet	• 모드 선택에서 내부 액세스 포인트 또는 외부 액세스 포인트를 선택합니다. • 최대 연결 도구 수: 8 * 내부 액세스 포인트 또는 외부 액세스 포인트 모두

* “Tool IP”를 “Auto (DHCP)”로 설정하면 도구의 IP 주소를 관리하지 않고도 네트워크를 구성할 수 있습니다. P13 참조

설정 절차

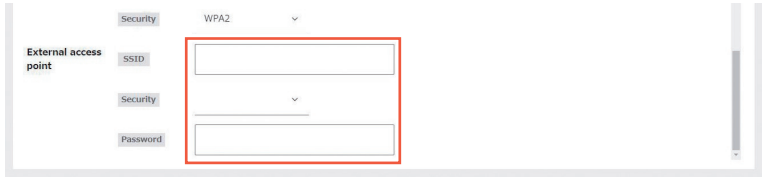
1 상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings]를 클릭하고 “Basic settings” 탭을 선택한 다음 “External access point” 를 “ON” 으로 설정합니다.

* “External access point” 가 활성화되면 “WLAN mode” 가 비활성화됩니다.



2 상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Network settings” 탭을 선택합니다. “External access point” 에서 “SSID”, “Security”, “Password” 를 설정합니다.

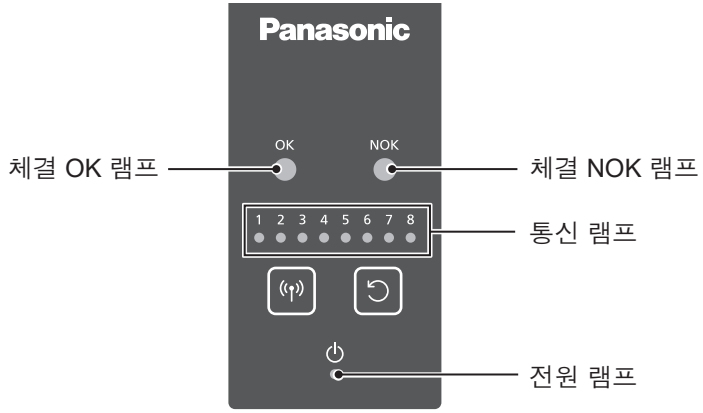
* 컨트롤러에는 하나의 SSID 만 등록할 수 있습니다. (도구마다 다른 SSID 를 등록할 수 없음)
* 외부 액세스 포인트의 사용설명서를 참조하십시오.
* 도구와 페어링 등록을 시작하기 전에 이 설정을 지정합니다.
* 페어링 등록을 시작하기 전에 도구의 IP 주소를 설정합니다.



표시 램프 및 버저

표시 램프 및 버저는 컨트롤러의 상태를 표시합니다.

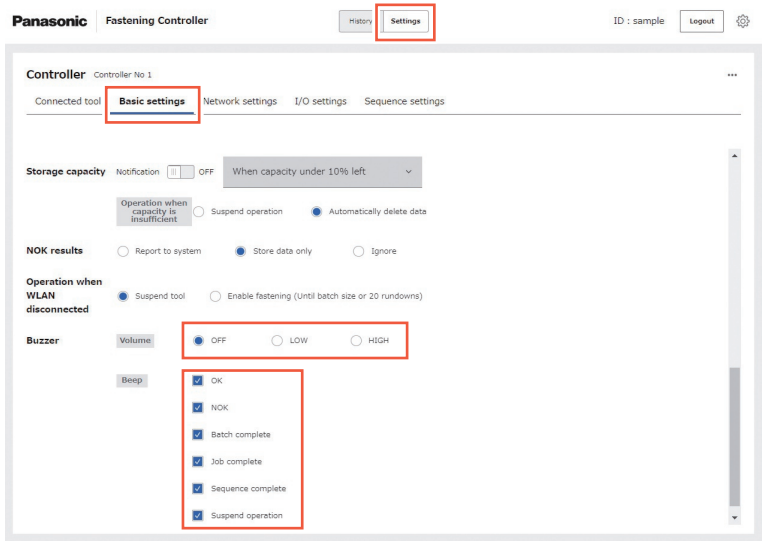
> **⚠ 주의**
> 램프가 깜박이는 동안에는 전원 스위치를 끄지 마십시오.
> 초기화가 필요할 수 있습니다.



상태	표시 램프	버저
전원 켜짐	전원 램프(노란색) 계속 켜짐	–
페어링할 도구가 선택됨	통신 램프(파란색) 느리게 깜박임	–
페어링 설정됨	통신 램프(파란색) 빠르게 깜박임	–
페어링 완료됨	통신 램프(파란색) 계속 켜짐	짧은 신호음 ■
페어링되지 않음	통신 램프(파란색) 매우 느리게 깜박임	–
페어링 연결 끊김	통신 램프(파란색) 꺼짐	–
체결 완료	OK 램프(녹색) 계속 켜짐	짧은 신호음 ■
체결 실패	NOK 램프(빨간색) 계속 켜짐	긴 신호음 ▬
Batch/job 완료	OK 램프(녹색) 두 번 깜박임	짧은 신호음 2번 ■ ■
시퀀스 완료	OK 램프(녹색) 세 번 깜박임	짧은 신호음 3번 ■ ■ ■
오류	전원 램프(노란색) 깜박임	긴 신호음 2번 ▬ ▬

버저 설정

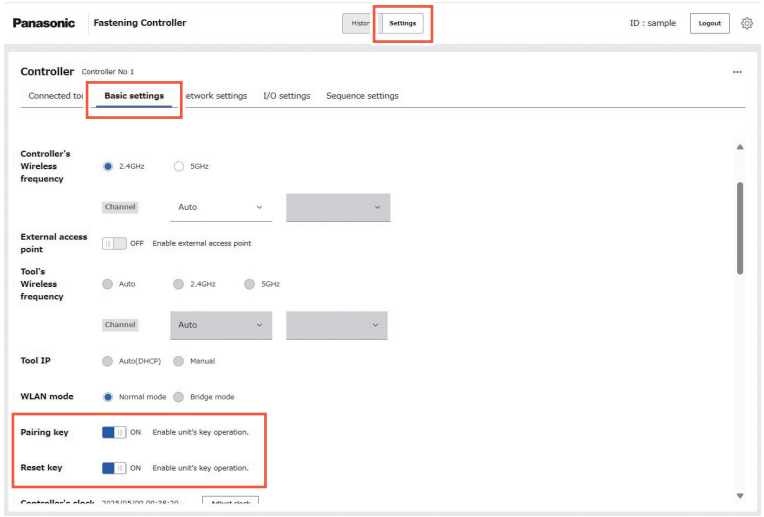
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Basic settings” 탭을 선택합니다.
“Buzzer” 에서 “Volume” 및 “Beep” 를 설정합니다.



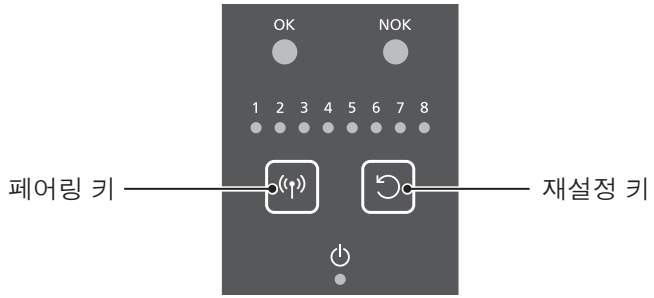
항목	설명
Volume	3 레벨(OFF/LOW/HIGH) (LOW: 75dB, HIGH: 85dB)
Beep	구성용 PC 에서 선택됨 (OK/NOK/Batch complete/Job complete/Sequence complete/Suspend operation)

작동 키 설정

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Basic settings” 탭을 선택합니다.
“Pairing key” 및 “Reset key” 에서 제어판의 페어링 키 및 재설정 키를 비활성화할 수 있습니다.

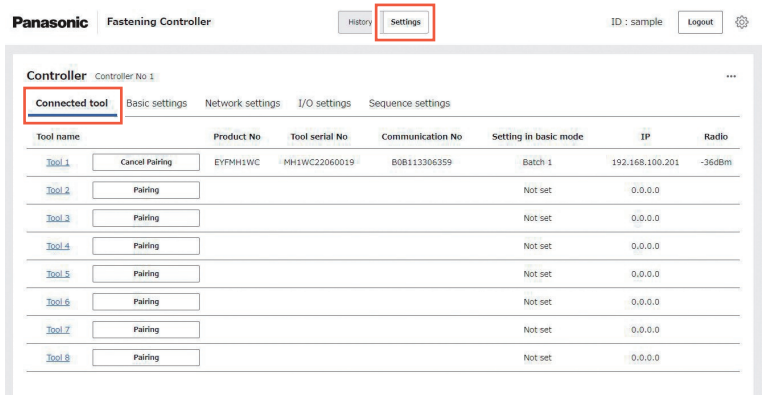


Pairing key
제어판에서 페어링 키를 활성화하거나 비활성화합니다. [기본] ON [설정 범위] ON(활성화됨) / OFF(비활성화됨)
Reset key
제어판에서 재설정 키를 활성화하거나 비활성화합니다. [기본] ON [설정 범위] ON(활성화됨) / OFF(비활성화됨)



연결된 도구 정보 확인

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다.
컨트롤러에 연결된 도구의 정보와 상태를 볼 수 있습니다.



아래는 표시된 항목입니다.

Tool name
등록된 도구 번호(1~8)가 표시됩니다.
Tool serial No
도구의 장치 식별을 설정하고 표시할 수 있습니다. 기본: 5자리 모델 ID + 8자리 일련 번호(2자리 제조연도 + 2자리 월 + 4자리 생산 로트)
Product No
도구 제품 번호가 표시됩니다.
Communication No
도구의 통신 부분에 대한 장치 식별(MAC 주소)이 표시됩니다.
Setting in basic mode
Running mode 가 “Repeat mode (Basic mode)” 로 설정된 경우의 동작이 표시됩니다.
IP
도구의 IP 주소가 표시됩니다.
Radio
도구에서 수신한 무선 신호(RSSI)의 강도가 표시됩니다. * 마지막 통신의 강도가 표시됩니다. * 외부 액세스 포인트를 사용하는 경우 측정할 수 없으며 “0dBm” 이 표시됩니다.

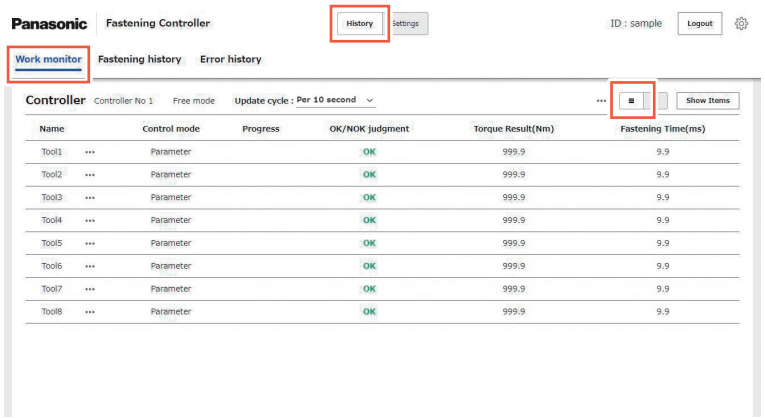
작업 모니터

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Work monitor” 탭을 선택합니다.
도구별 최근 체결 기록이 표시됩니다. 작업 결과를 참고하여 작업에 활용할 수 있습니다.
* 둘 이상의 구성용 PC 에서 동시에 표시할 수 있습니다. (최대 8개 액세스. 동일한 계정에서 다중 액세스가 허용됩니다.)
* 하나 이상의 계정으로 로그인하려면 다른 PC 를 사용하는 것이 좋습니다.
* 동일한 PC 에서 여러 계정을 사용하려면 서로 다른 웹 브라우저를 사용하는 것이 좋습니다.
* 한 번에 하나의 구성 기능 액세스만 허용됩니다.

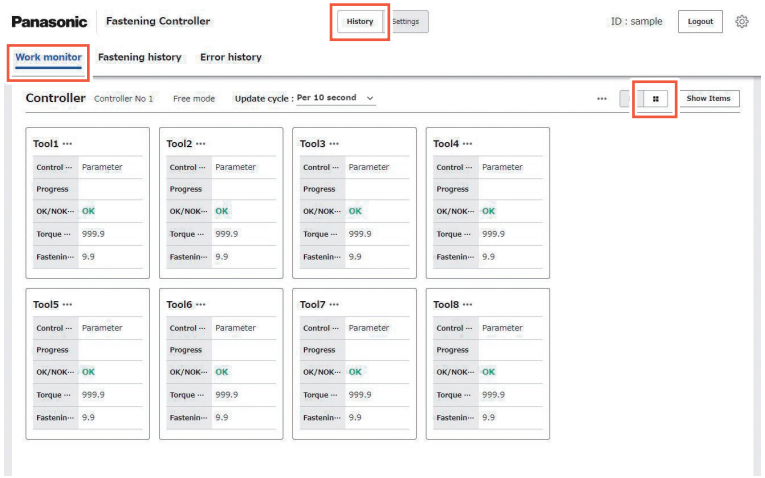
보기 형식 전환

“목록 보기” 및 “그리드 보기” 에서 선택할 수 있습니다.
화면 우측 상단의 보기 아이콘을 사용하십시오.

■목록 보기

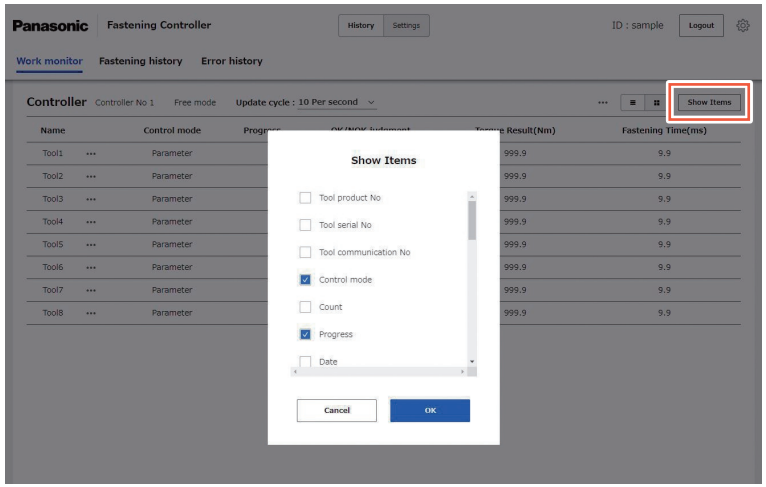


■그리드 보기



표시할 항목 선택

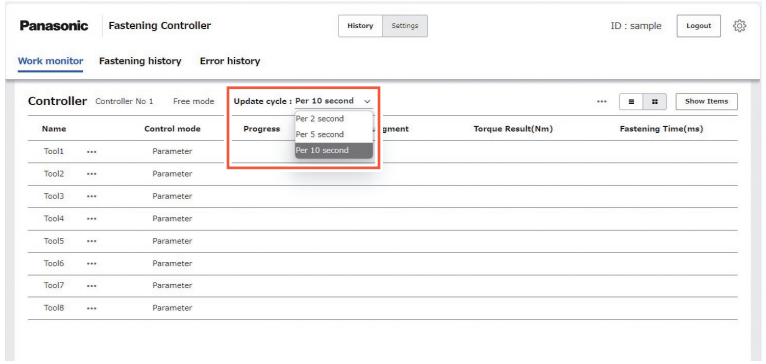
“Show Items” 를 사용하여 표시할 항목을 선택합니다.



* “목록 보기”에서 아래로 스크롤하여 표시할 많은 항목을 선택할 수 있습니다.
* “그리드 보기”에서는 최대 5개의 항목을 표시할 수 있습니다.

디스플레이 업데이트 주기 선택

자동 디스플레이 업데이트를 설정할 수 있습니다.
아래와 같이 “Per 2 second”, “Per 5 second”, “Per 10 second” 에서 업데이트 주기를 선택합니다.



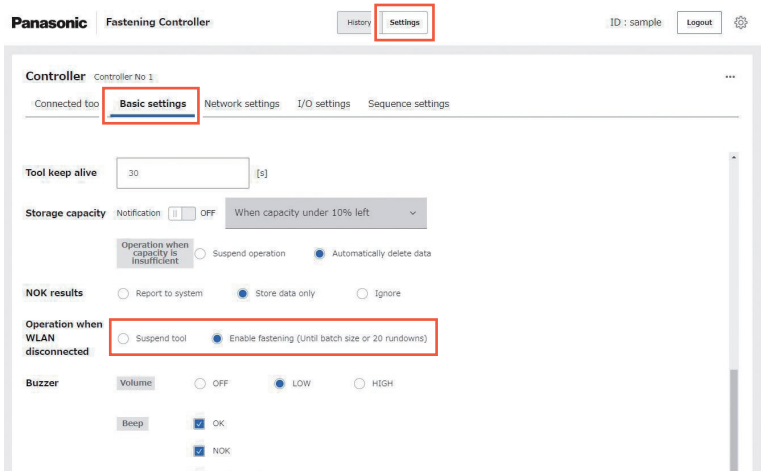
* 많은 개수의 도구나 구성용 PC가 연결된 경우 “Per 10 second” 업데이트 주기가 권장됩니다. (데이터 처리에 다소 시간이 걸릴 수 있습니다.)

무선 통신 연결이 끊긴 상태에서 도구의 동작

도구와 컨트롤러 사이의 무선 통신이 일시적으로 중단되는 경우 동일한 매개 변수로 체결을 계속할 수 있습니다.
무선 통신이 끊어졌을 때 도구의 작업 결과는 “도구가 다시 연결될 때” 또는 “도구 연결이 복구된 후 첫 번째 체결 시” 컨트롤러에 전송됩니다.



상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Basic settings” 탭을 선택합니다.
“Operation when WLAN disconnected” 를 “Suspend tool” 로 설정하면 중단 후 진행 중인 체결이 완료되지만 더 이상의 체결은 진행되지 않습니다.
“Enable fastening” 을 설정하면 체결 수량이 상한에 도달한 후 더 이상 체결하지 않습니다.



“Enable fastening” 에서 모드별 상한 수량은 아래와 같습니다.

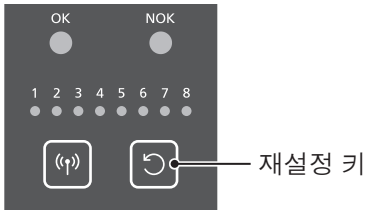
모드		동작
Free mode		최대 20개의 나사를 계속 체결
Repeat mode	Basic mode	배치가 끝날 때까지 또는 최대 20개의 나사까지 계속 체결
	Sequence mode	배치가 끝날 때까지 또는 최대 20개의 나사까지 계속 체결 * 해당 도구 이외의 도구는 계속해서 정상적으로 실행됩니다.
External control mode		배치가 끝날 때까지 또는 최대 20개의 나사까지 계속 체결

작동 중 카운트 재설정

설정을 변경하기 위해 컨트롤러가 체결 제어를 진행 중이면 중지하십시오. 변경 사항을 적용하면 확인 대화 상자가 나타납니다.
“장치의 키 사용” 또는 “설정 화면의 설정” 으로 카운트된 수량을 재설정할 수 있습니다.
* 이는 “Free mode” 에 적용되지 않습니다.

장치의 키 사용

컨트롤러의 재설정 키를 3초 이상 길게 누릅니다.
* 모든 활성 도구의 수량이 재설정됩니다.

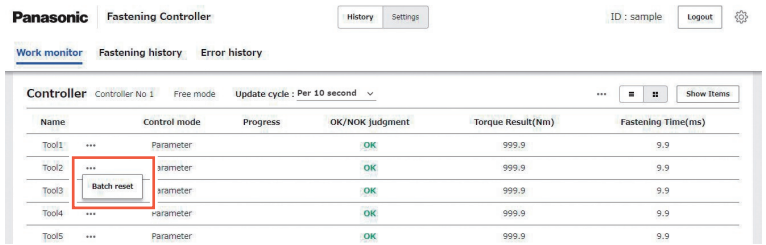


설정 화면의 설정

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Work monitor” 탭을 선택합니다.

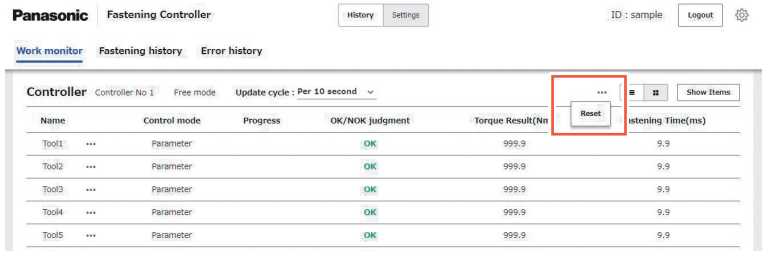
■도구로 수량을 재설정하려면

“Work monitor” 화면에서 ⋯ (도구 옵션 키)을 클릭한 다음 원하는 도구 번호의 [Batch reset] 을 클릭합니다.



■모든 도구의 수량을 일괄적으로 재설정하려면

“Work monitor” 화면에서 ⋯ (컨트롤러 옵션 키)을 클릭한 다음 오른쪽 상단의 [Reset] 을 클릭합니다.

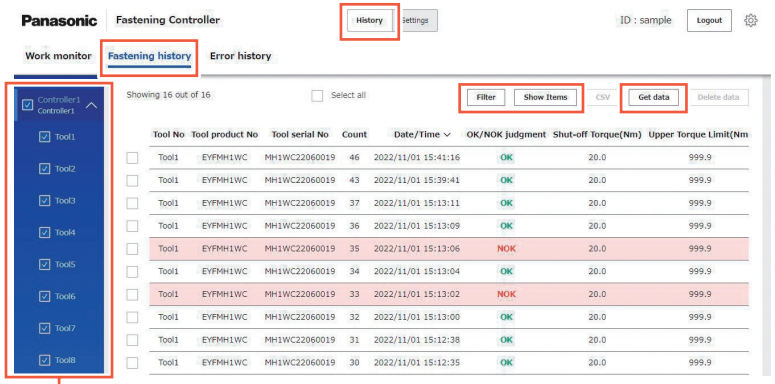


* Sequence mode 에서 수량은 첫 번째 도구까지 재설정됩니다.

체결 기록 데이터 표시

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Fastening history” 탭을 선택합니다.
도구에서 컨트롤러로 전송된 체결 기록 데이터를 볼 수 있습니다.

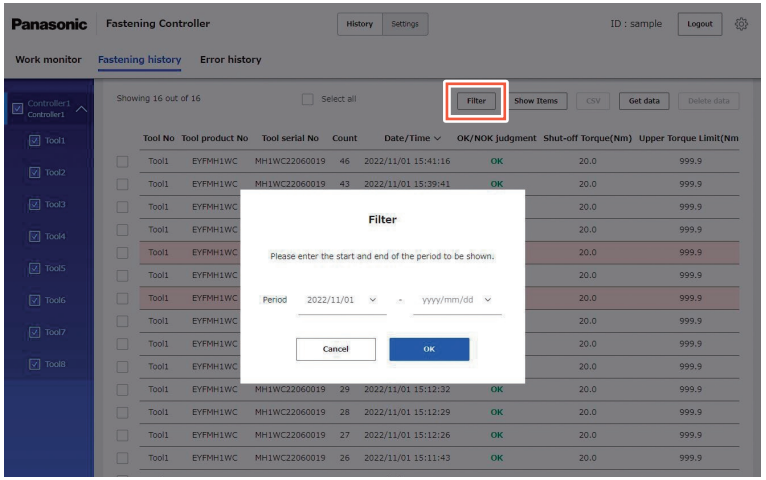
데이터를 표시하려면 왼쪽의 도구 목록에서 원하는 컨트롤러 및 도구를 선택하고 오른쪽 상단에서 [Get data] 를 클릭합니다.
체결 기록 로그는 최신에서 가장 오래된 순으로 표시됩니다.
* 체결 기록 항목의 내용은 도구의 사용설명서를 참조하십시오.



도구 목록

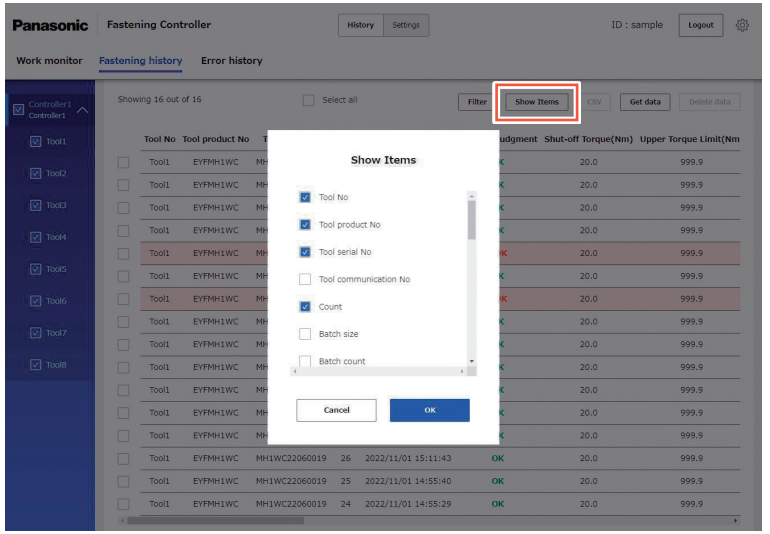
■기간별 체결 기록 로그 추출

[Filter] 를 클릭하고 표시할 체결 기록 로그의 범위를 좁히기 위해 기간을 지정합니다.



■표시할 항목 설정

표시된 항목을 변경하려면 [Show Items] 를 클릭하고 원하는 항목을 선택합니다.



체결 기록 데이터 용량

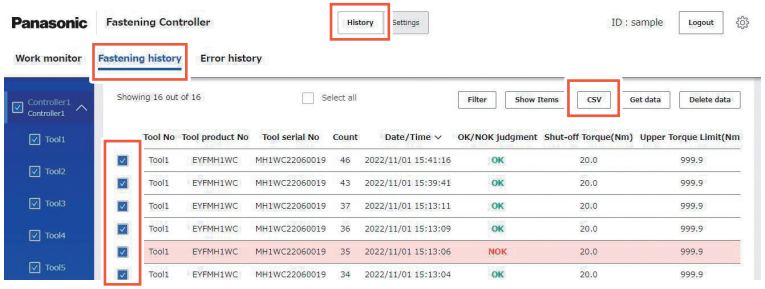
컨트롤러는 최대 약 200,000 개의 체결 기록 로그(파형 데이터 포함)를 저장할 수 있습니다.
더 많은 로그를 수신하면 작업을 일시 중지하거나 로그를 자동으로 삭제(덮어쓰기)합니다.
아래 가이드를 참조하여 주기적으로 로그를 CSV 형식으로 내보내는 것이 좋습니다.

■전체 저장 용량에 도달하는 예상 시간

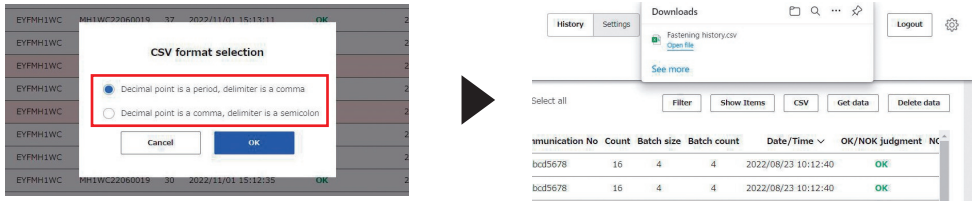
	도구당 일일 수량		
도구 수	1,000	3,000	5,000
2	약 100 일	약 33 일	약 20 일
4	약 50 일	약 16 일	약 10 일
8	약 25 일	약 8 일	약 5 일

체결 기록 데이터를 CSV 형식으로 내보내기

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Fastening history” 탭을 선택합니다.
원하는 로그를 선택하고 [CSV] 를 클릭합니다.
체결 기록 로그는 CSV 형식으로 내보냅니다.
내보낸 데이터에는 “Show Items” 설정과 관계없이 각 도구의 모든 항목이 포함됩니다.

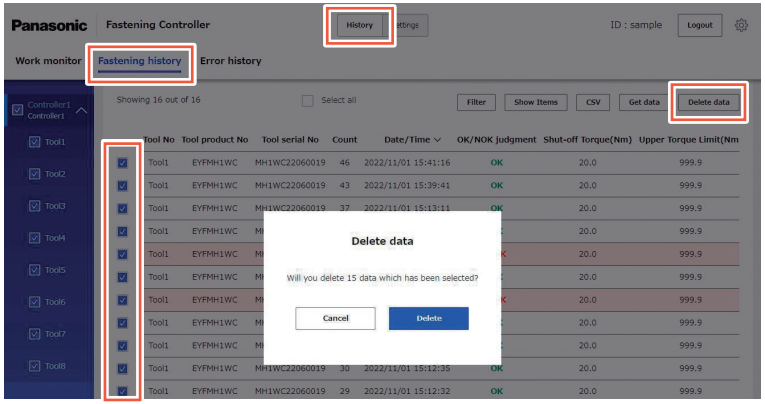


“Decimal point is a period, delimiter is a comma” 와 “Decimal point is a comma, delimiter is a semicolon” 중에서 선택할 수 있습니다.



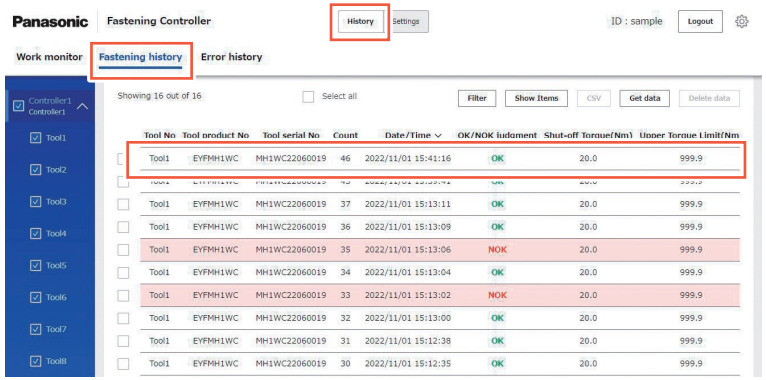
체결 기록 데이터 삭제

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Fastening history” 탭을 선택합니다.
원하는 로그를 선택하고 [Delete data] 를 클릭합니다.
체결 기록 로그가 삭제됩니다.

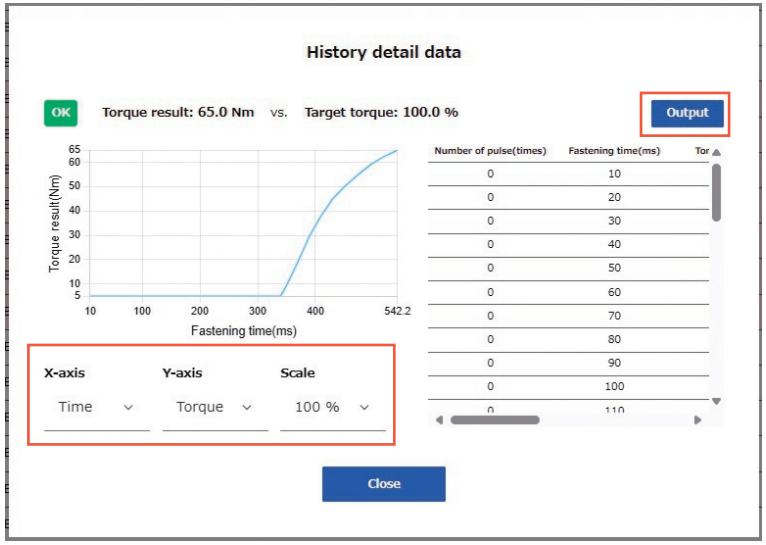


파형 데이터 표시

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 를 클릭하고 “Fastening history” 탭을 선택합니다.
파형 데이터를 저장하도록 설정한 경우 원하는 체결 기록 로그 행을 클릭하여 파형 데이터 팝업 창을 표시할 수 있습니다.



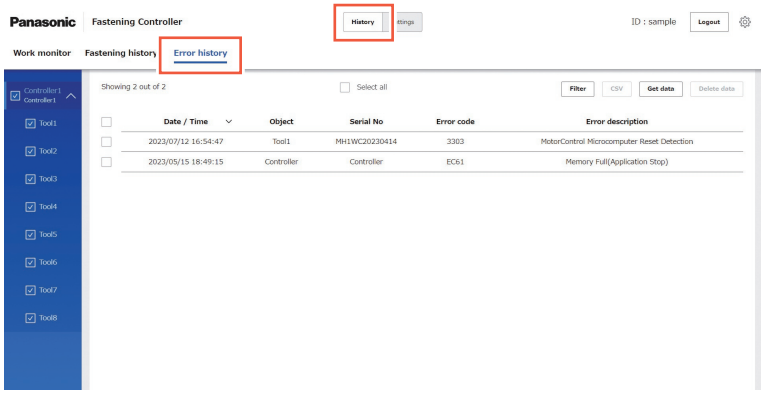
“X-axis”, “Y-axis”, “Scale” 을 선택하여 디스플레이를 조정할 수 있습니다.
[Output] 을 클릭하면 데이터를 CSV 형식으로 내보냅니다.



* “Device settings” 에서 “Graph sending timing” 을 “After every fastening” 으로 설정합니다.

오류 기록 표시

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History] 을 클릭하고 “Error history” 탭을 선택합니다.
생성된 오류 기록이 표시됩니다.

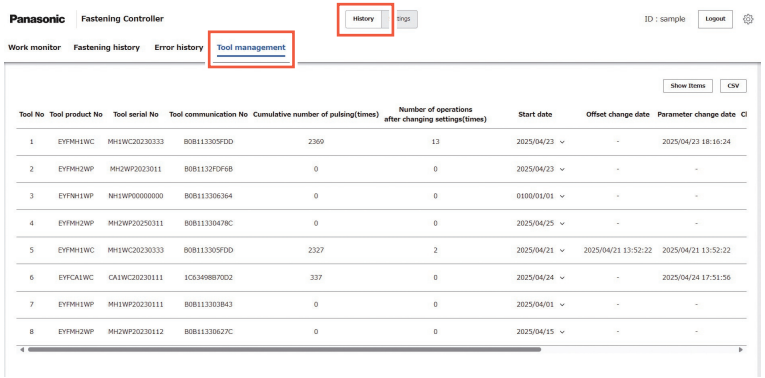


아래는 표시된 항목입니다.
* 오류 내용은 “오류 코드” 를 참조하십시오. **P104 참조**

Date / Time
오류가 발생한 날짜와 시간이 표시됩니다.
Object
오류를 발생시킨 장치(컨트롤러 또는 도구 1~8 중 하나)가 표시됩니다.
Serial No
오류가 발생한 장치(컨트롤러 또는 도구 1~8 중 하나)의 일련 번호가 표시됩니다.
Error code
발생한 오류 코드가 표시됩니다.
Error description
발생한 오류 내용이 표시됩니다.

관리 항목 보기

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History]를 클릭하고 “Tool management” 탭을 선택합니다.
각 “Tool No”에 대한 관리 항목을 볼 수 있습니다.



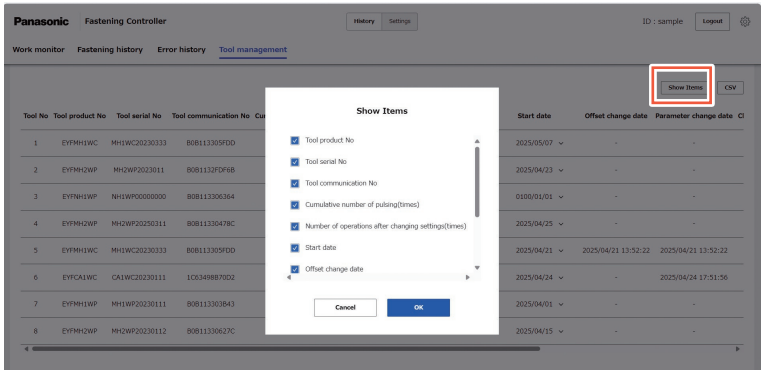
다음은 표시된 항목입니다.
최신 정보는 화면에서 확인할 수 있습니다.
각 항목은 도구의 작업 결과 데이터를 기반으로 표시됩니다.
도구가 교체되거나 새 도구가 페어링되면 모든 정보가 삭제됩니다.
* 컨트롤러 - 도구 페어링이 취소되어도 정보는 삭제되지 않습니다.

Tool product No
페어링된 도구의 제품 번호를 표시합니다.
Tool serial No
도구의 고유 식별 정보를 표시합니다.
Tool communication No
도구 통신 부분의 단위 식별(MAC 주소)이 표시됩니다.
Cumulative number of pulsing (times)
도구가 수행한 누적 펄스 작업을 표시합니다.
Number of operations after changing settings (times)
도구 설정을 변경한 후 수행된 누적 작업 횟수를 표시합니다.

Start date
도구 사용 시작 날짜를 설정합니다. 이 설정은 관리자 계정으로만 수행할 수 있습니다. [설정 값] 0100/01/01 ~ 9999/12/31
Offset change date
“Offset”, “Slope” 또는 “Offset”, “Intercept”를 포함하여 도구 설정이 변경된 날짜와 시간을 표시합니다.
Parameter change date
도구 설정이 변경된 날짜와 시간을 표시합니다.
Changed parameter No
변경된 매개변수 번호를 표시합니다. “Device settings”이 변경된 경우에도 이 필드에 표시됩니다.
Cumulative fastening time (h)
도구의 누적 작업 시간을 표시합니다.
Cumulative pulsing time (h)
도구 펄싱이 포함된 누적 작업 시간을 표시합니다.

■표시할 항목 설정

표시된 항목을 변경하려면 [Show Items] 를 클릭하고 원하는 항목을 선택합니다.



도구 사용 시작 날짜 구성

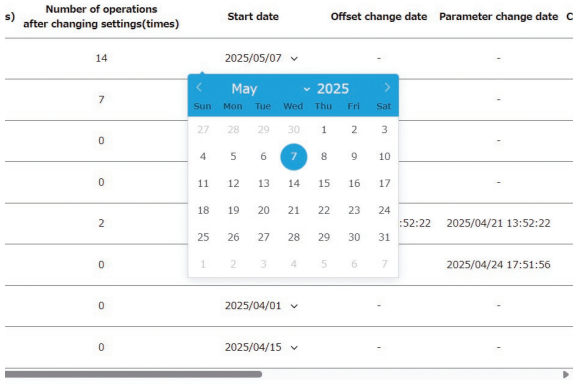
* 이 작업은 관리자 계정으로만 수행할 수 있습니다. P21 참조

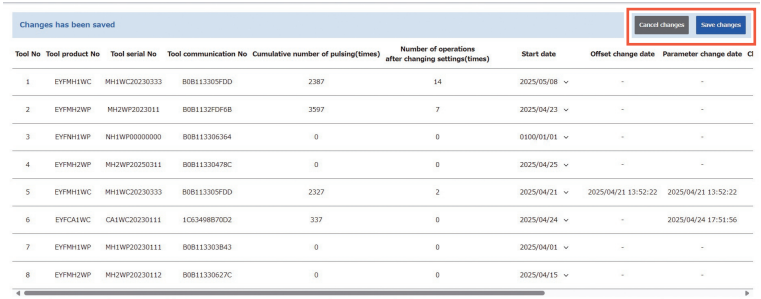
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History]를 클릭하고 “Tool management” 탭을 선택합니다.

각 도구의 “Start date” 항목을 클릭합니다.
시작 날짜는 캘린더 스타일 UI에서 설정할 수 있습니다.

시작 날짜를 선택한 후 “Save changes”을 클릭하여 변경 사항을 확인합니다.
확인하기 전 “Start date”를 수정하거나 다른 도구의 “Start date”를 변경할 수 있습니다.

“Cancel changes”를 클릭하면 이전 상태로 되돌릴 수 있습니다.





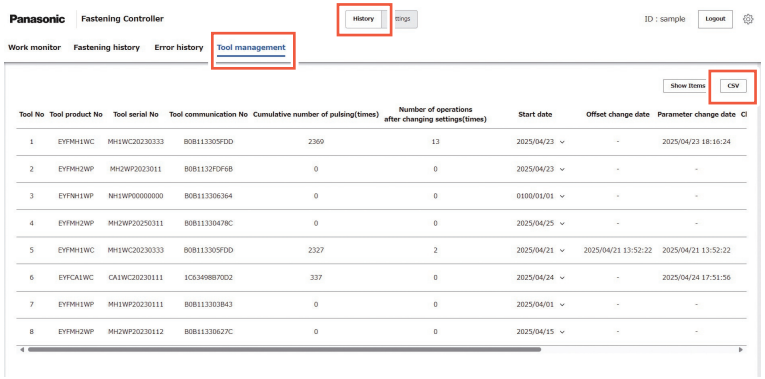
CSV 형식으로 도구 관리 데이터 내보내기

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [History]를 클릭하고 “Tool management” 탭을 선택합니다.

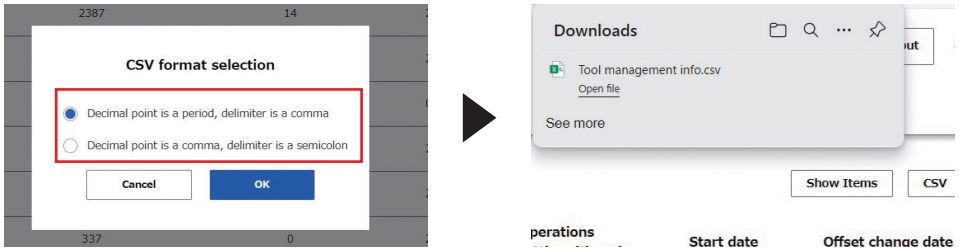
“CSV”를 클릭하십시오.

화면에 표시된 데이터가 CSV 형식으로 내보내집니다.

내보낸 데이터에는 “Show Items” 설정과 관계없이 각 도구의 모든 항목이 포함됩니다.



CSV 형식은 “Decimal point is a period, delimiter is a comma” 또는 “Decimal point is a comma, delimiter is a semicolon”에서 선택할 수 있습니다.

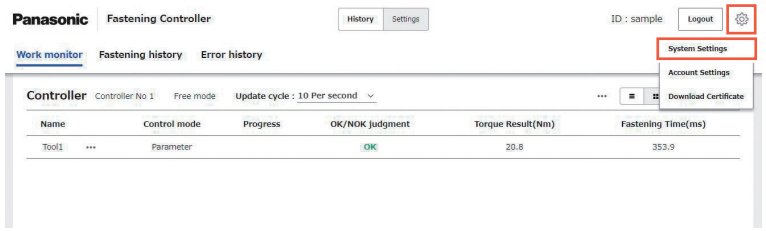


언어 변경

“Japanese” 또는 “English” 를 선택할 수 있습니다.

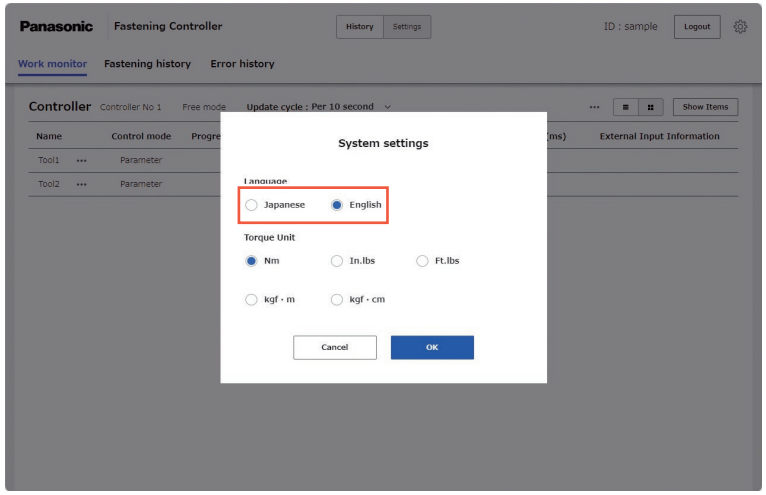
1 상단 페이지(설정 화면의 초기 페이지)에서 우측 상단의 옵션 키를 클릭하고 “System settings” 를 선택합니다.

“System settings” 화면이 표시됩니다.



2 “System settings” 화면에서 언어를 선택합니다.

“Japanese” 또는 “English” 를 선택할 수 있습니다.

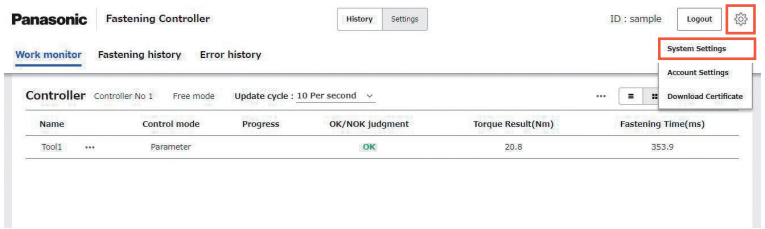


표시할 토크 단위 변경

“Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, “kgf·cm” 를 선택할 수 있습니다.

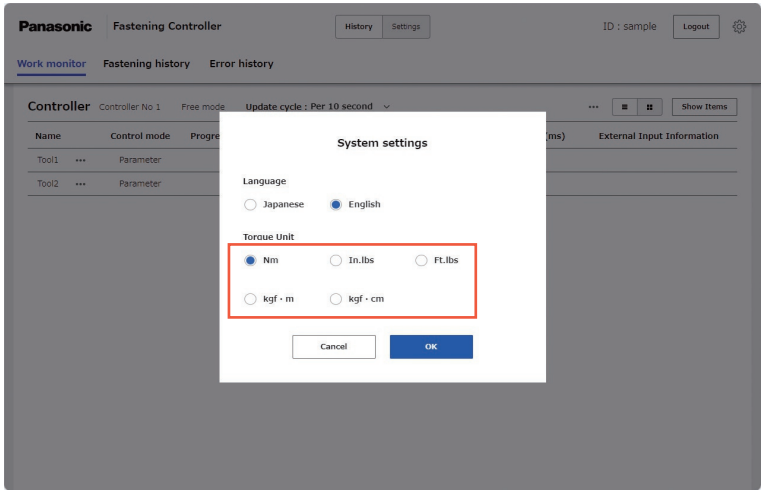
1 상단 페이지(설정 화면의 초기 페이지)에서 우측 상단의 옵션 키를 클릭하고 “System settings” 를 선택합니다.

“System settings” 화면이 표시됩니다.



2 “System settings” 화면에서 토크 단위를 선택합니다.

“Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, “kgf·cm” 중에서 토크 단위를 선택할 수 있습니다.



* 일부 단위 표시에서 숫자가 수정될 수 있습니다.

청소 방법

부드러운 천으로 닦기

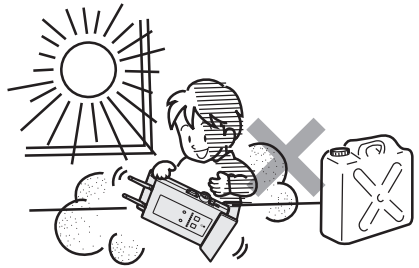
젖은 천, 시너, 알코올, 벤진 또는 기타 휘발성 액체를 사용하지 마십시오.
(변색, 변형, 균열의 원인이 됨)



보관 방법

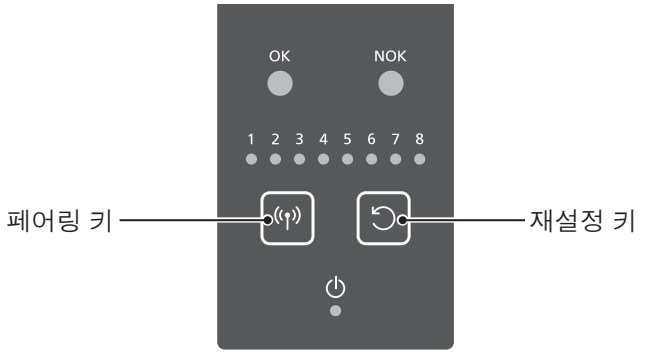
보관 중에는 다음 조건을 피하십시오.

- 차량 보관소 또는 기타 뜨거운 장소
- 직사광선에 노출된 장소
- 물이나 습기에 노출된 장소
- 이물질이나 먼지가 많은 장소
- 어린이의 손이 닿는 장소
- 휘발유나 기타 가연성 물질이 있는 장소
- 넘어질 위험이 있는 장소



컨트롤러 초기화

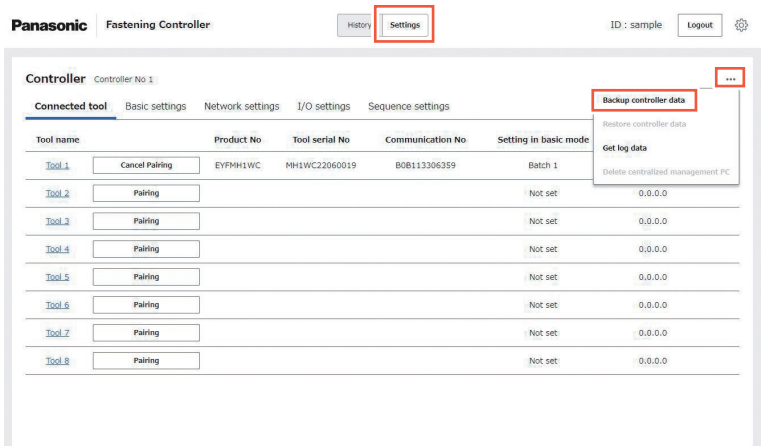
컨트롤러를 초기화(공장 재설정)하려면 페어링 키와 재설정 키를 함께 10초 이상 길게 누릅니다.



* 저장소 사용량에 따라 5분 이상 소요될 수 있습니다.
* 장치의 키가 비활성화되어 있으면 작업을 수행할 수 없습니다. P76 참조

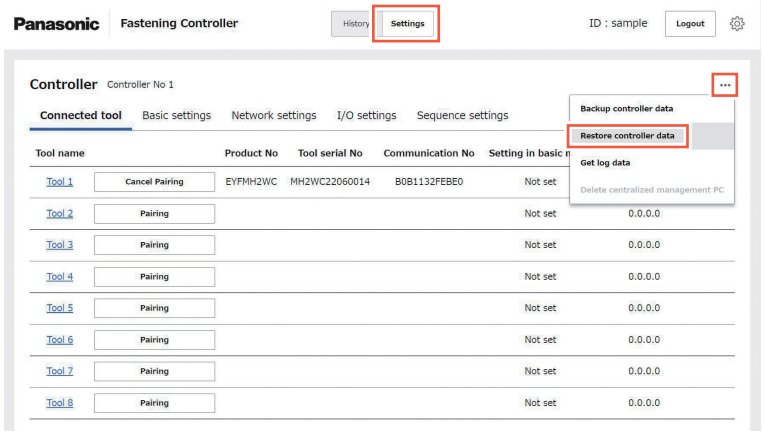
설정 백업

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭합니다.
… (컨트롤러 옵션 키)을 클릭한 다음 [Backup controller data] 를 클릭합니다.
컨트롤러 및 도구의 설정을 백업할 수 있습니다.
* 체결 기록 데이터는 백업되지 않습니다. 필요한 경우 CSV 형식으로 내보냅니다.



설정 복원

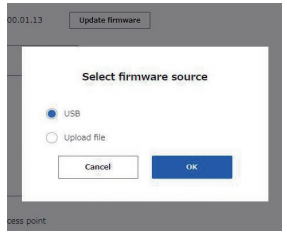
상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭합니다.
… (컨트롤러 옵션 키)을 클릭한 다음 [Restore controller data] 를 클릭합니다.
백업에서 컨트롤러 및 도구의 설정을 복원할 수 있습니다.
* 체결 제어 중에는 작업을 수행할 수 없습니다.
* 도구와의 페어링이 등록되어 있으면 실행할 수 없습니다. 페어링을 취소합니다.



펌웨어 업데이트

컨트롤러의 펌웨어와 도구의 통신 부분을 업데이트할 수 있습니다.

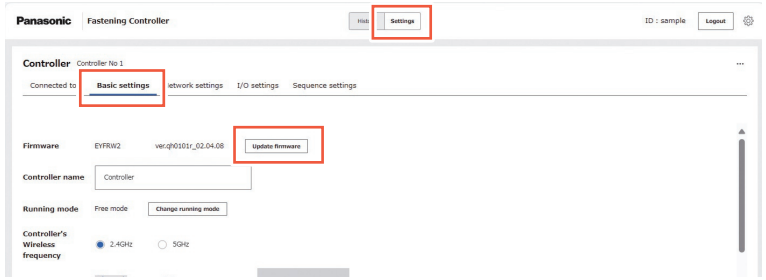
다음 중 하나를 사용하여 펌웨어를 업데이트합니다.
① 컨트롤러의 USB 포트 사용.
* 비밀번호 잠금이 설정된 USB 플래시 드라이브는 사용할 수 없습니다.
* 폴더를 만들지 않고 펌웨어 데이터 파일 하나만 USB 플래시 드라이브에 직접 저장합니다.
② 구성용 PC 에 기록.
* “파일 업로드”를 선택할 때 선택 화면에서 PC 에 저장된 펌웨어 데이터 파일을 선택합니다.



현재 펌웨어 버전은 회사 웹 사이트에 액세스하십시오. P2 참조
또는 영업 담당자에게 문의하십시오.

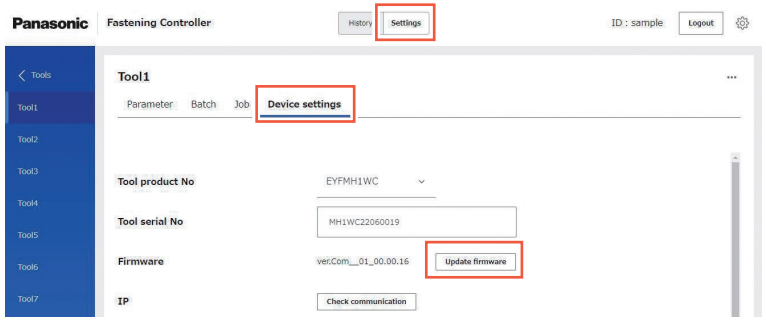
■컨트롤러의 경우

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Basic settings” 탭을 선택한 다음 [Update firmware] 를 클릭합니다.



■도구의 통신 부분의 경우

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭하고 “Connected tool” 탭을 선택합니다.
“Connected tool” 화면에서 원하는 도구 번호를 클릭합니다.
도구 번호에 대한 화면의 “Device settings” 탭에서 [Update firmware] 를 클릭합니다.



코인 셀 배터리 교체

컨트롤러의 시계(RTC)를 계속 실행하려면 아래 교체 가이드를 참조하여 코인 셀 배터리를 교체하십시오.

■배터리 유형



CR2450

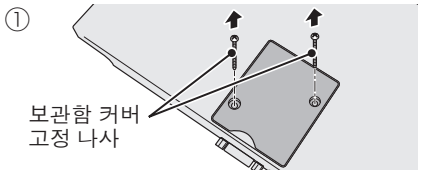
■교체 가이드

코인 셀 배터리는 컨트롤러가 꺼져 있을 때 시계를 계속 실행하는 데 사용됩니다.
소비를 최소화하기 위해 원칙적으로 제어 장치부를 끄지 않습니다.

전원이 하루 12시간 켜짐 (영업일에만)	전원이 항상 켜짐
약 3년	약 8년

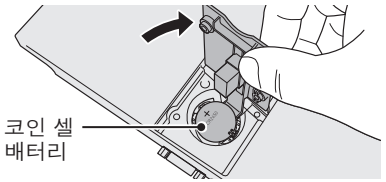
다음 절차에 따라 교체하거나 대리점에 문의하십시오.
전기 지식이 있는 사람이 작업하는 것이 좋습니다.

1 2개의 보관함 커버 고정 나사를 제거한 후 보관함 커버를 제거합니다.

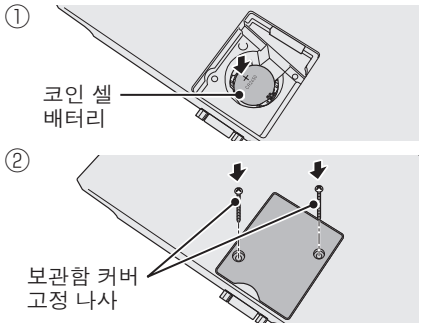


2 보관함 커버를 사용하여 코인 셀 배터리를 꺼냅니다.

보관함 커버의 고리로 코인 셀 배터리를 들어 올립니다.

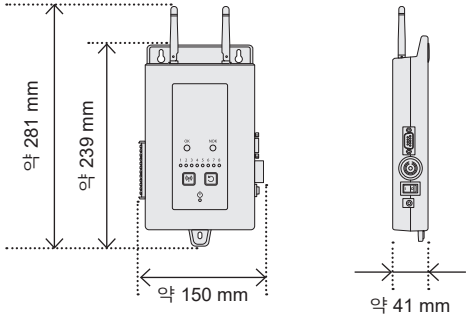


3 새 코인 셀 배터리를 넣고 보관함 커버를 2개의 보관함 커버 고정 나사로 부착합니다.



컨트롤러 사양

실내 제품 조립 작업 시 체결 완료 및 고장 신호 수신

모델 번호	EYFRW2
전원 공급 장치	100 V-240 V AC, 50/60 Hz
무선 통신 표준	무선 LAN (IEEE.802.11 a/b/g/n) n: HT20 에만 해당
주파수 대역	2.4 GHz: 2.412 GHz~2.472 GHz 5 GHz: 5.180 GHz~5.240 GHz [중국, 한국에만 해당] 2.4 GHz: 2.412 GHz~2.462 GHz 5 GHz: 5.180 GHz~5.240 GHz
채널	2.4 GHz: 1~13 채널 5 GHz: 36, 40, 44, 48 채널 [중국, 한국에만 해당] 2.4 GHz: 1~11 채널 5 GHz: 36, 40, 44, 48 채널
적용 범위	2.4 GHz: 약 16 m 5 GHz: 약 10 m
등록 가능한 도구 수	8개(최대)
입력/출력(I/O) 단자	8개 입력 및 8개 출력
I/O 입력 단자 등급	24 V DC, 5 mA
I/O 출력 단자 등급	30 V DC, 3 A
I/O 전원 공급 등급	24 V DC, 50 mA
전력 소비	약 30 W
작동 온도 및 습도 범위	0 °C~45 °C, 20%~90%
크기(예상 치수) 총 길이 × 총 높이 × 너비	약 150 × 239 × 41 mm (안테나 포함 높이: 281 mm) 
질량(무게)	약 550 g (본체만)
통신 인터페이스	Ethernet × 2, RS232C × 1, USB-A × 1
저장할 수 있는 데이터 수	약 200,000개의 체결 이력 로그 (파형 데이터 포함)
호환 가능한 도구 모델	EYFMH1WC, EYFMH2WC, EYFNH1WC *1, EYFCA1WC *2

*1 이는 펌웨어 버전 2.02.00 이상에서만 지원됩니다.
*2 이는 펌웨어 버전 2.04.00 이상에서만 지원됩니다.

• 최신 종합 카탈로그를 참조하십시오.

무선 사양

채널별 주파수

주파수 대역	채널	주파수
2.4 GHz	채널 1	2.412 GHz
	채널 2	2.417 GHz
	채널 3	2.422 GHz
	채널 4	2.427 GHz
	채널 5	2.432 GHz
	채널 6	2.437 GHz
	채널 7	2.442 GHz
	채널 8	2.447 GHz
	채널 9	2.452 GHz
	채널 10	2.457 GHz
	채널 11	2.462 GHz
	채널 12	2.467 GHz
	채널 13	2.472 GHz
5 GHz	채널 36	5.180 GHz
	채널 40	5.200 GHz
	채널 44	5.220 GHz
	채널 48	5.240 GHz

• 채널 12와 13은 중국과 한국에서 사용할 수 없습니다.

WebUI 사양

호환 OS	Windows 10 이상 (아래 웹 브라우저 지원)
지원되는 웹 브라우저	Microsoft Edge 버전 102 이상 또는 Google Chrome 버전 102 이상
지원 언어	영어, 일본어
권장 화면 해상도	1024 × 768 이상

주의

- 일부 PC 는 작동 환경을 충족하더라도 사용할 수 없습니다.
- PC 의 사용 환경 등에 따라 본 사용설명서의 설명 및 화면이 실제 설명 및 화면과 다를 수 있습니다.
  미리 양해를 구합니다.
- 이 사용설명서의 내용은 사전 통지 없이 변경될 수 있습니다.
- 이 사용설명서의 내용 전체 또는 일부를 무단으로 복제하는 것은 금지되어 있습니다.
- 이 사용설명서에서 Windows 를 작동하는 방법에 대한 설명은 Windows 10 의 절차 및 화면을 사용합니다.
- WebUI 는 호환 OS 이외의 OS 에서는 동작하지 않습니다.
- 권장 환경을 충족하는 모든 PC 에서 작동이 보장되는 것은 아닙니다.

■ 이용 약관 (사용 전 읽어보기)

<제한 사항>

WebUI 는 EYFRW2 용 구성 소프트웨어입니다.

주의

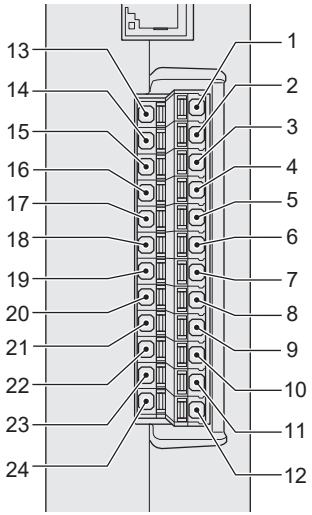
- 기능을 사용할 때 다음 사항을 준수하십시오.
  기능을 사용하면 다음 이용 약관에 동의하는 것으로 간주됩니다.

[사용 조건]

Panasonic 은 기능과 관련하여 어떠한 종류의 보증도 하지 않습니다.
Panasonic 은 직접 손실, 간접 손실, 확산 손실, 결과적 손실 및 기능의 사용 또는 작동으로 인한 특수 손실을 포함하되 이에 국한되지 않는 모든 손실에 대해 책임을 지지 않습니다.
해당 기능의 무단 전재 및 배포를 금지합니다.

접촉 I/O 사양

■출력 릴레이 단자와 입력 단자 간의 할당



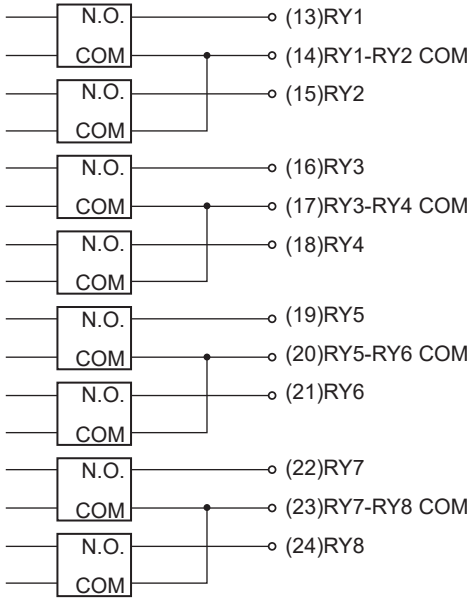
IN: 입력 RY: 출력

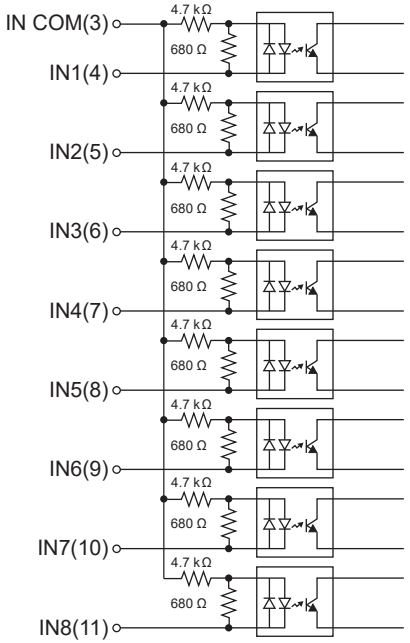
번호	핀 할당
1	24 V 출력 (+)*
2	24 V 출력 (+)*
3	IN COM
4	IN 1
5	IN 2
6	IN 3
7	IN 4
8	IN 5
9	IN 6
10	IN 7
11	IN 8
12	24 V 출력 (–)*

번호	핀 할당
13	RY1
14	RY1-RY2 COM
15	RY2
16	RY3
17	RY3-RY4 COM
18	RY4
19	RY5
20	RY5-RY6 COM
21	RY6
22	RY7
23	RY7-RY8 COM
24	RY8

* 외부 장치에 24 V 전원을 공급할 수 있습니다.
단자 1과 2는 병렬로 사용할 수 있습니다.

■단자 블록 연결도





라디오 인증

무선 통신 유의 사항

■다음과 같은 환경 조건에서는 노이즈, 짧은 전파 도달 거리 또는 고장이 발생할 수 있습니다.

- 무선 운용 가능 도구 유닛 및 컨트롤러 간의 원활한 무선 전파를 방해하는 방해물(예: 금속 또는 강화 콘크리트 구조물)이 있습니다.
- 컨트롤러의 안테나는 금속으로 마감되어 있습니다.
- 오퍼레이터의 바디가 오퍼레이터(무선 운용 가능 도구 유닛)와 컨트롤러 사이의 무선 전파를 방해합니다.
- 부근에 마이크로웨이브, PC 또는 기타 기기 등 노이즈를 초래하는 장치가 있습니다.
- 무선 운용이 가능한 도구 유닛과 컨트롤러 주변에서 휴대폰이나 PHS 폰을 사용합니다.

라이선스 조건

소프트웨어 라이선스 조건

이 제품은 다음 소프트웨어를 통합합니다.

(1) Panasonic Corporation 에서 독자적으로 개발했거나 Panasonic Corporation 에서 사용하기 위해 개발된 소프트웨어,

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(11) GPL V1.0, GPL V2.0, GPL V3.0, LGPL V2.1, LGPL V3.1, SMAIL, MPL V1.1 및/또는 MPL V2.0 에 따라 라이선스가 부여된 소프트웨어 이외의 오픈 소스 소프트웨어.

(3) - (11)로 분류된 소프트웨어는 유용할 것이라는 확신을 가지고 배포하지만 상품성 또는 특정 목적에의 적합성에 대한 묵시적 보증을 포함하여 어떠한 보증도 하지 않습니다.

저작권자 및 라이선스에 대한 자세한 내용은 109 페이지 이후를 참조하십시오.

이 제품의 인도로부터 최소 3년 동안 Panasonic 은 아래에 제공된 연락처 정보로 연락하는 모든 제3자에게 GPL V1.0, GPL V2.0, GPL V3.0, LGPL V2.1, LGPL V3.1, SMAIL 또는 그렇게 해야 할 의무가 있는 기타 라이선스에 포함되는 해당 소스 코드와 해당 저작권 표시 하에 물리적으로 소스 코드 배포를 수행하는 당사 비용보다 적은 비용으로 완전한 기계 판독 가능 사본을 제공할 예정입니다.

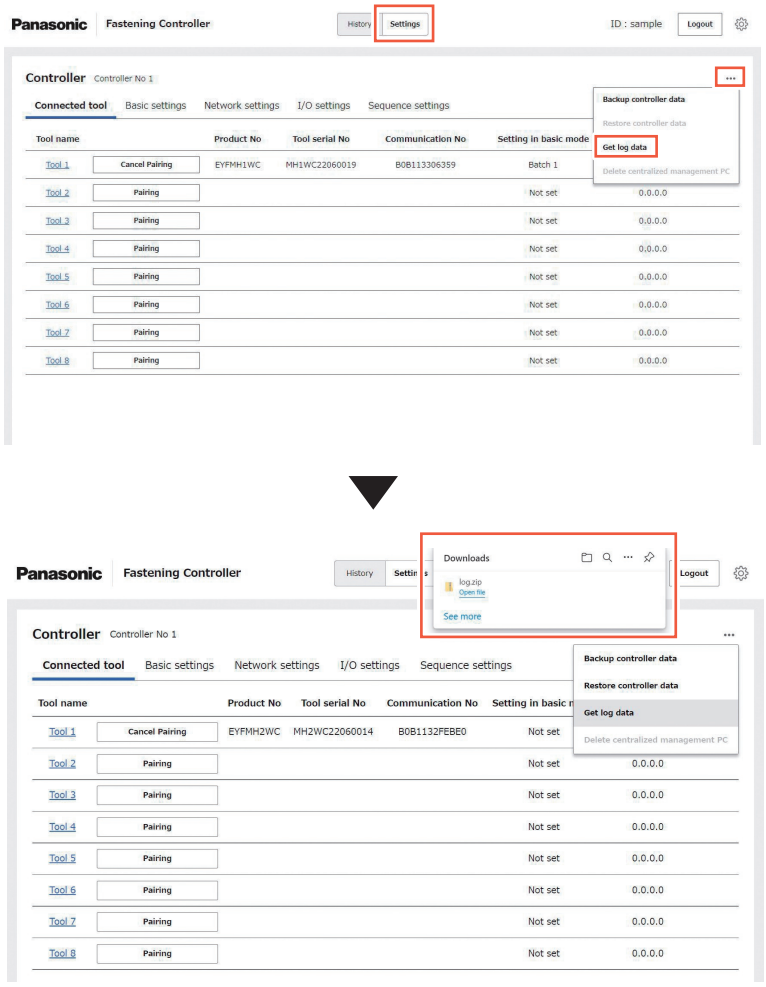
연락처 정보: oss-cd-powertools-gl@ml.jp.panasonic.com

장치	오류 코드	유형	범주	이벤트	조치
컨트롤러	0xEF21	경고	하드웨어 장애	보조 CPU 오류(장애)	컨트롤러를 다시 시작합니다. 문제가 지속되면 장치가 고장난 것일 수 있습니다. 대리점에 문의하십시오.
	0xEF51	경고	하드웨어 장애	Ether0 오류	장치가 고장난 것일 수 있습니다. 대리점에 문의하십시오.
	0xEF52	경고	하드웨어 장애	Ether1 오류	장치가 고장난 것일 수 있습니다. 대리점에 문의하십시오.
	0xEF61	경고	하드웨어 장애	WLAN 모듈 오류(장애)	컨트롤러를 다시 시작합니다. 문제가 지속되면 장치가 고장난 것일 수 있습니다. 대리점에 문의하십시오.
	0xCE42	오류	소프트웨어 장애	설정 내용 오류	컨트롤러를 공장 초기화하고 다시 설정하십시오.
	0xCE43	오류	소프트웨어 장애	수축 정보 오류	컨트롤러의 재설정 키를 3초 이상 길게 누릅니다.
	0xEC61	경고	소프트웨어 장애	체결 이력 저장 용량이 가득 참(작동 중단)	체결 이력 화면에서 체결 이력 로그를 삭제하여 여유 공간을 확보하십시오. 필요한 경우 삭제하기 전에 내보냅니다.
도구	0x4301	주의	소프트웨어 장애	저장 용량이 가득 참	도구 설정 소프트웨어(Tool Manager 소프트웨어)에 액세스하고 작업 이력 로그를 삭제합니다.
	0x4302	주의	소프트웨어 장애	대기열의 전송된 결과 수가 상한에 도달함	도구가 컨트롤러와 통신할 수 없습니다. 작업장을 바꾸십시오. 문제가 지속되면 장치가 고장난 것일 수 있습니다. 대리점에 문의하십시오.
	0x3303	오류	소프트웨어 장애	모터 제어 마이크로컨트롤러 재설정이 감지됨	발생한 오류가 해결되었습니다.
	0x3304	오류	소프트웨어 장애	토크 계산 마이크로컨트롤러 재설정이 감지됨	발생한 오류가 해결되었습니다.

장치	오류 코드	유형	범주	이벤트	조치
도구	0x4305	주의	소프트웨어 장애	RTC 배터리 부족	도구 장치 내부의 코인 셀 배터리를 교체하십시오.
	0x4306	주의	소프트웨어 장애	펌웨어 업데이트 오류	펌웨어 파일이 올바른지 확인하십시오.
	0x4315	주의	소프트웨어 장애	USB 통신 오류	발생한 오류가 해결되었습니다.
	0x4316	주의	소프트웨어 장애	WLAN 모듈이 다시 시작됨	발생한 오류가 해결되었습니다.
	0x1401	경고	하드웨어 장애	WLAN 모듈 오류	발생한 오류가 해결되었습니다.
	0x1402	경고	하드웨어 장애	모터 제어 마이크로컨트롤러 오류	발생한 오류가 해결되었습니다.
	0x1403	경고	하드웨어 장애	토크 계산 마이크로컨트롤러 오류	발생한 오류가 해결되었습니다.
	0x1404	경고	하드웨어 장애	외장 플래시 드라이브 오류	발생한 오류가 해결되었습니다.
	0x1405	경고	하드웨어 장애	RTC 오류	발생한 오류가 해결되었습니다.
	0x1406	경고	하드웨어 장애	회로 식별 오류	발생한 오류가 해결되었습니다.
	0x1407	경고	하드웨어 장애	남은 스왑 공간 없음	발생한 오류가 해결되었습니다.
	0x1408	경고	하드웨어 장애	손상된 매개 변수 공간	발생한 오류가 해결되었습니다.

작동 로그 데이터

상단 페이지(설정 화면의 초기 페이지)에서 위에 있는 [Settings] 를 클릭합니다.
… (컨트롤러 옵션 키)을 클릭한 다음 [Get log data] 를 클릭합니다.
컨트롤러의 작업 로그를 받을 수 있습니다.



AC 어댑터 제조일 설명



S/No. X X X - X X X X X X X

년 월 일련 번호

일련 번호 정보. 2010년부터 연도 표기는 아래와 같습니다.

예:

2022/11 .....N11-XXXXXXX
2023/06 .....P06-XXXXXXX
2024/01 .....Q01-XXXXXXX
2025/01 .....R01-XXXXXXX
2026/01 .....S01-XXXXXXX

(A, B, C-Z) "I"와 "O" 문자는 사용되지 않습니다.
(1과 0을 혼동하지 않기 위해 사용합니다.)

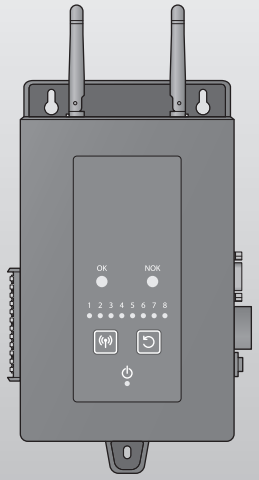
Panasonic

Operating Instructions

Assembly Controller

Model No.:

EYFRW2



IMPORTANT

Read and follow the safety and operating instructions before using this product.
Do not use the wireless function outside the country where you purchased the product. Doing so may violate the local laws and regulations.

Original instructions: English
Translation of the original instructions: Other languages

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Operating Environment

You need to use a web browser to configure the controller.
Prepare a PC satisfying the following requirements.

Operating environment

Compatible OS	Windows 10 or later (supporting any of the web browsers below)
Web browser	Microsoft Edge version 102 or later or Google Chrome version 102 or later

- Some PCs are not available even if they meet the operating environment.
- Depending on the use environment etc. of your PC, the descriptions and screens in this Operating Instructions might be different from the actual descriptions and screens. Please be forewarned.
- The contents of this Operating Instructions are subject to change without prior notice.
- Any reproduction of the contents of this Operating Instructions in whole or in part is prohibited without permission.
- Figures in this Operating Instructions are for reference only.

[Note]

Always keep the firmware up to date.
You can find the latest firmware data on the following website which provides access to the Operating Instructions.
For how to update the firmware, see “Updating the Firmware”.
Refer to P95

How to Access the Operating Instructions

The current version of the controller’s Operating Instructions and other resources can be downloaded from the web site below.

https://panasonic.net/electricworks/ecm/powerelctrictools/download/

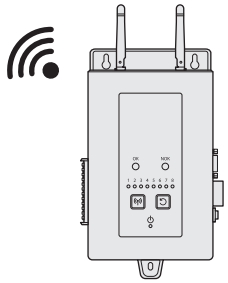
Trademark

- Microsoft and Windows are either registered trademarks or trademarks of Microsoft Corporation in the U.S. and/or other countries.
- The screenshots are used in accordance with the guidelines of Microsoft Corporation.

Other names including company names and product names in this Operating Instructions are trademarks or registered trademarks of their respective companies. ™ and ® may be omitted in this Operating Instructions.

Intended Use

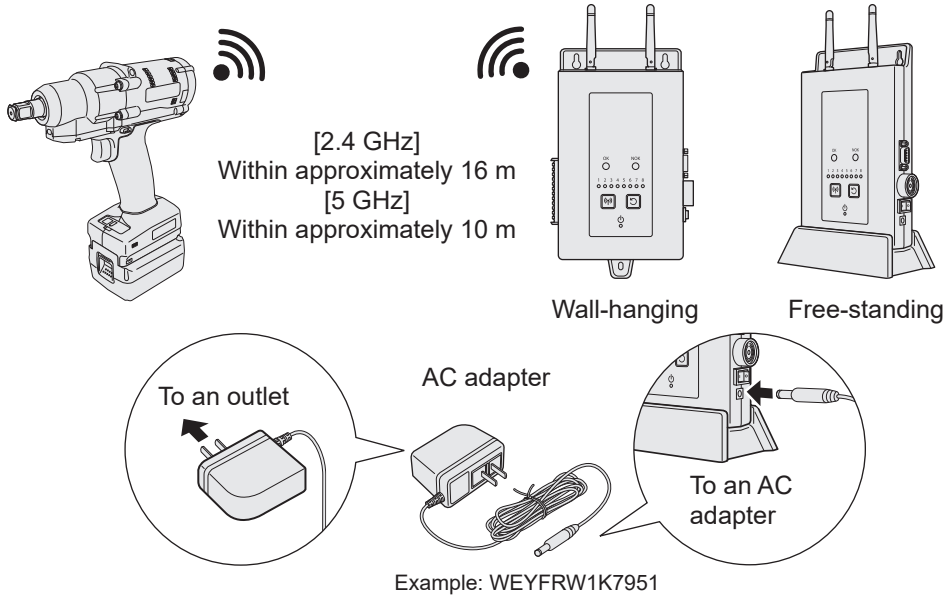
This product is a controller that wirelessly communicates with tools.
It can receive fastening history data from tools, make settings of tools, and control the quantity to fasten.



01	Connect to up to 8 tools.
02	Support 2.4 GHz and 5 GHz bands
03	Support a fastening control function and a history storing function

Setup

Install the controller in a range where wireless communication with tools is possible.
Supply power via an AC outlet and connect to external devices through communication interfaces as necessary.



Example: WEYFRW1K7951

- The controller contains a coin cell battery to keep the clock function (RTC) running. It is recommended that you keep the power on to reduce consumption of the internal coin cell battery.
- The wireless coverage may change depending on the environment.

SAFETY PRECAUTIONS Always adhere to the instructions

Below are the instructions you should always adhere to, to prevent human harm and property damage.

■ **The severity of harm and damage caused by incorrect use is presented with the following.**

⚠ **WARNING**	May cause death or serious injury.
⚠ **CAUTION**	May cause minor injury or property damage.

■ **The content that should be observed is presented with the following symbols. (The following are examples)**

	You MUST NOT do the action.
	You MUST do the action.

⚠ WARNING

Mandatory

- **Make sure that there are no buried objects such as conduits, water pipes, and gas pipes in the installation place.**
  Touching such buried objects may cause electric shock or lead to electric leakage or gas leakage.
- **Insert the power plug all the way seated.**
  Incomplete insertion may cause electric shock or heat generation resulting in fire.
  Do not use a damaged plug or loose socket.
- **Clean dust off the power plug routinely.**
  Accumulated dust on the plug may absorb moisture and cause poor insulation resulting in fire. Disconnect the power plug and wipe it with dry cloth.
- **Use the specified power cord only.**
  Using any other plug may cause electric shock, short circuit, or fire.
- **Keep the workplace sufficiently bright.**
  Poor visibility in a dark workplace may lead to an accident or injury.

⚠ WARNING

Prohibited

- **Do not use a socket or wiring device in the manner of exceeding the rated value. Use 100 V-240 V AC only.**
  Exceeding the rated value due to an overloaded socket may cause heat generation resulting in fire.
- **Do not damage the power cord or plug. (Avoid damaging, breaking, modifying, putting close to a heat source, bending with force, twisting, pulling, putting a heavy load on it, pinching, or binding)**
  Using the damaged cord or plug may cause electric shock, short circuit, or fire.
  Check the cord and plug periodically and if any damage, consult your dealer.
- **Do not use the controller with a DC power supply, engine generator, or transformer.**
- **Do not use the controller in a place with flammable liquid or gas.**
  Doing so may cause generation of heat, smoke, fire, or burst.
- **Do not install the controller on a mortar wall.**
  Screwing it on a mortar wall may cause heat generation from wire mesh inside, resulting in fire in case of electric leakage.
- **Disconnect the power plug between uses.**
  Keeping it connected may cause poor insulation resulting in electric shock or fire from electric leakage.

No disassembly

- **Do not modify the controller. Do not disassemble or repair the controller.**
  Doing so may cause fire, electric shock, or injury.
  For repair, consult your dealer or our Customer Support Centre.

Keep dry

Avoid the following use of charged tools.

- **Do not use or leave them exposed to rain or moisture.**
- **Do not use them immersed under water.**
  Doing so may cause smoke, fire, or burst.

No wet hand

- **Do not use a wet hand to connect or disconnect the power plug to or from the outlet.**
  Doing so may cause electric shock.

⚠ CAUTION

Prohibited

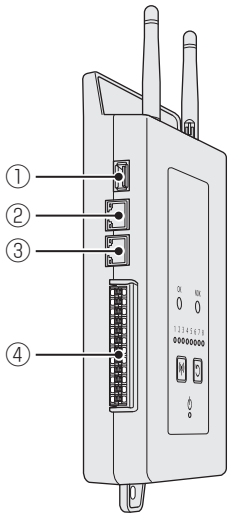
- **Do not use the controller for any other purpose than intended.**
  Doing so may cause injury.
- **Do not put the controller in a place accessible by a child.**
  Doing so may cause an accident or trouble.
- **Do not use the controller with oil or other foreign material attached to it.**
  Such oil or other foreign material may enter the inside, resulting in generation of heat, fire, or burst.
- **Do not store the main body in a place where the temperature may rise to 45 °C or higher.**
  Doing so may lead to abnormal operation.
- **Do not work in an unusual position.**
  Otherwise you may fall over and be injured.
  Always stand on a stable footing and keep a good balance.
- **Do not use the controller when you are tired.**
  Doing so may cause an accident or injury.
- **Do not allow a child or any other person who is not an operator to come near the workplace or touch the controller.**
  Doing so may cause injury.
- **Do not use the controller with incompatible devices.**
  Doing so may cause malfunction resulting in an accident.

Mandatory

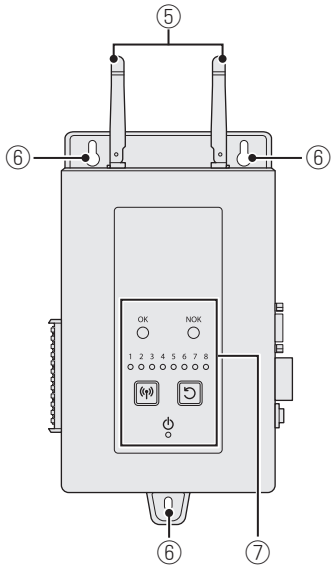
- **To install the controller on a wall, secure it with screws to prevent it from falling.**
  You may be injured if it falls.
- **To disconnect the power plug, always hold the power plug without pulling the cord.**
  Pulling the cord may cause electric shock or short circuit.
- **Before use, check the controller and other parts for any damage and confirm their normal operation.**
  Failure to do so may lead to breakage resulting in injury.
- **Keep the workplace clean.**
  A disordered workplace or work table may lead to an accident.
- **Consider well how to handle and work, pay attention to the surrounding environment, and use common sense during work.**
  Failure to do so may cause an accident or injury.

Main Body

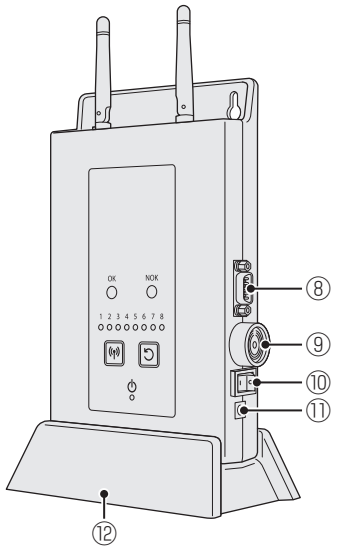
■ Left side



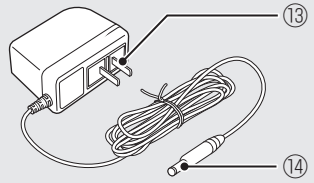
■ Front side



■ Right side



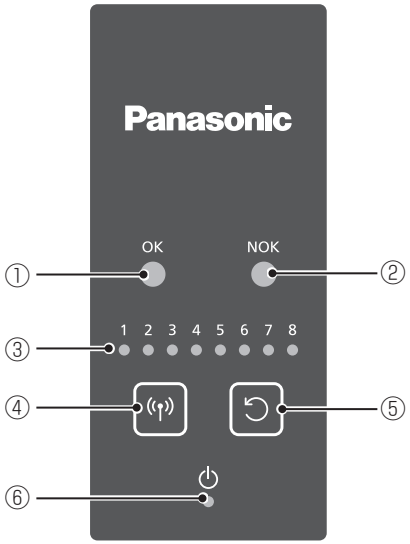
■ AC adapter



①	USB Port (USB-A)
②	Ethernet port (for maintenance)
③	Ethernet port (for network)
④	1～24 I/O port
⑤	Diversity antenna
⑥	Wall-hanging hole
⑦	Control panel

⑧	Serial port (RS232C)
⑨	Buzzer
⑩	Power switch
⑪	AC adapter socket
⑫	Controller stand
⑬	Power plug
⑭	Power connector

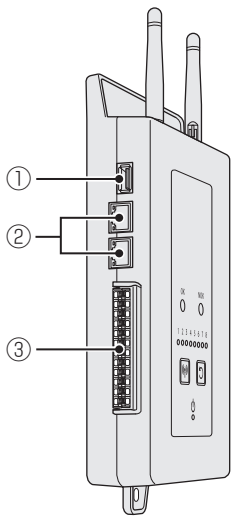
■ Control panel

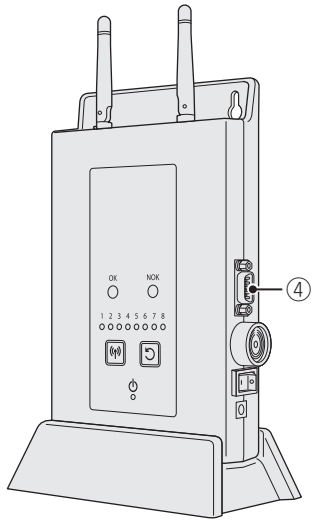


①	Fastening OK lamp Blinking green: Barcode reading reception state. Solid green: A fastening completion signal has been received. Off: A fastening completion signal is not received yet.
②	Fastening NOK lamp Solid red: A fastening failure signal has been received. Off: A fastening failure signal is not received yet.
③	Communication lamp (No. 1 to No. 8) Solid blue: A tool has been registered. Blinking blue: A tool is being registered or out of coverage. Off: A tool is not registered yet.

④	Pairing key
⑤	Reset key
⑥	Power lamp Solid yellow: Power on (receiving mode) Off: Power off Blinking yellow: Error

■ Communication interface



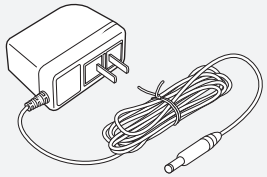


Interface		Details
①	USB	Use this port to connect a USB flash drive to update the firmware. * Directly connect a USB flash drive (without extension) A wireless receiver is connected to this port to connect a barcode reader. * Only wireless barcode readers are available. • USB2.0 USB-A × 1
②	Ethernet (for maintenance and network)	Use this port to connect to a PC for configuration or a host system. * Connect the Ethernet port (for maintenance) directly to a PC for configuration. (Do not use a hub) • 10Base-T/100Base-TX × 2 • Cable length: Less than 30 m
③	Input/output (I/O) terminal	Use this port to connect to an external device (e.g., a PLC). • 8 inputs and 8 outputs • Cable length: 10 m or less • Input terminal rating: 24 V DC, 50 mA • Output terminal rating: 30 V DC, 3 A
④	Serial port (RS232C)	Use this port to connect to an external device (e.g., a PLC). • RS232C × 1 • Cable length: 10 m or less

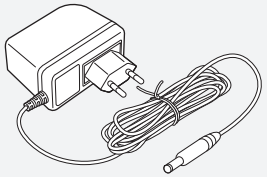
Accessory

■ **AC adapter × 1**

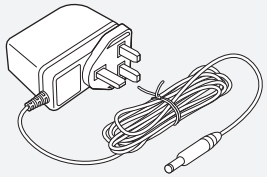
[For China only]
(WEYFRW1K7951)



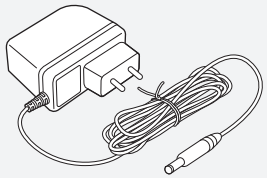
[For Korea only]
(WEYFRW1K7051)



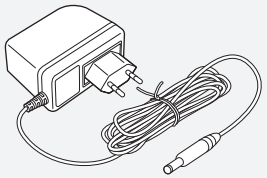
[[For Malaysia only]
(WEYFRW1K7851)



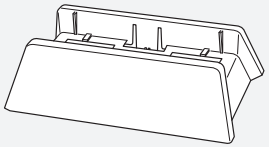
[For India only]
(WEYFRW1K7151)



[For Thailand/Indonesia only]
(WEYFRW1K7751)



■ **Controller stand × 1**
(EYFRW1F7001)

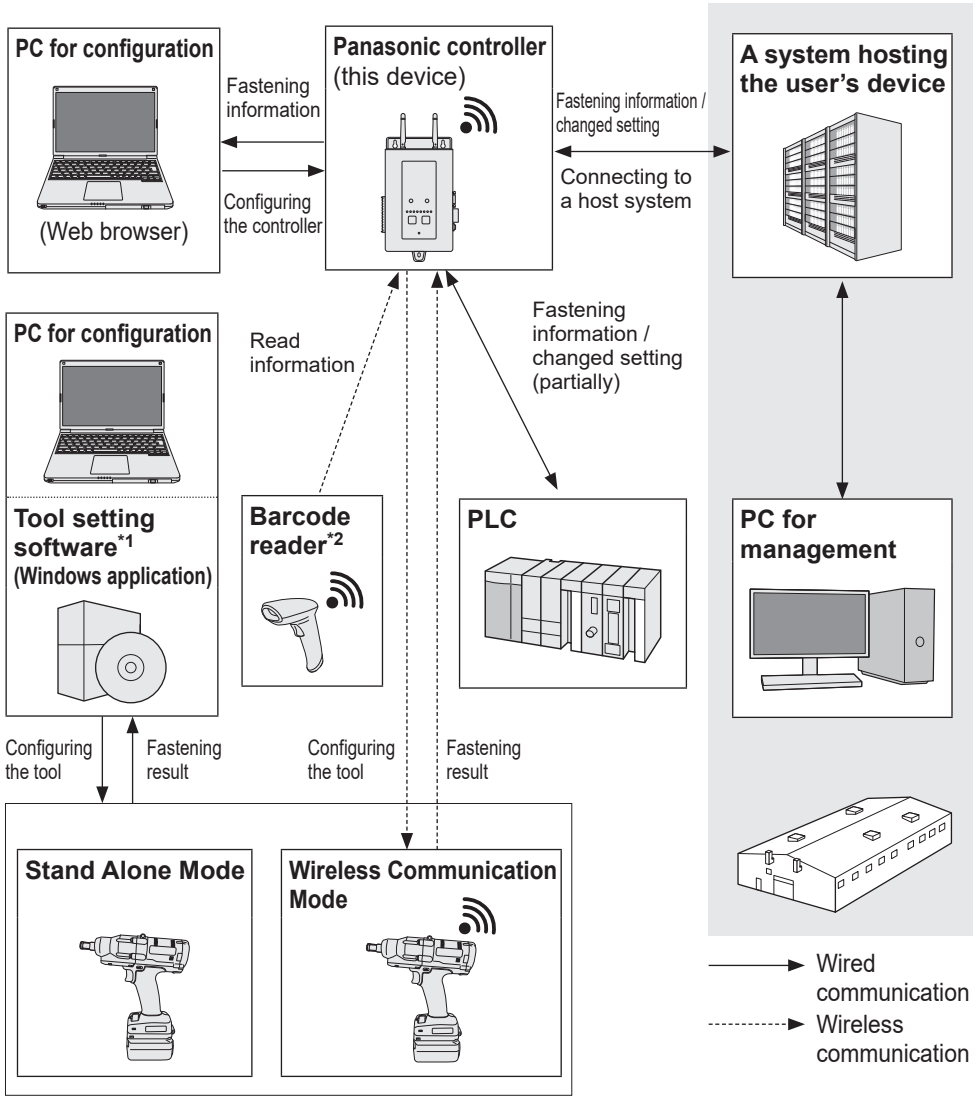


Consumables

■ **Coin cell battery** (CR2450) × 1
For how to replace, see “Replacing the Coin Cell Battery”.
Refer to P96



System Configuration

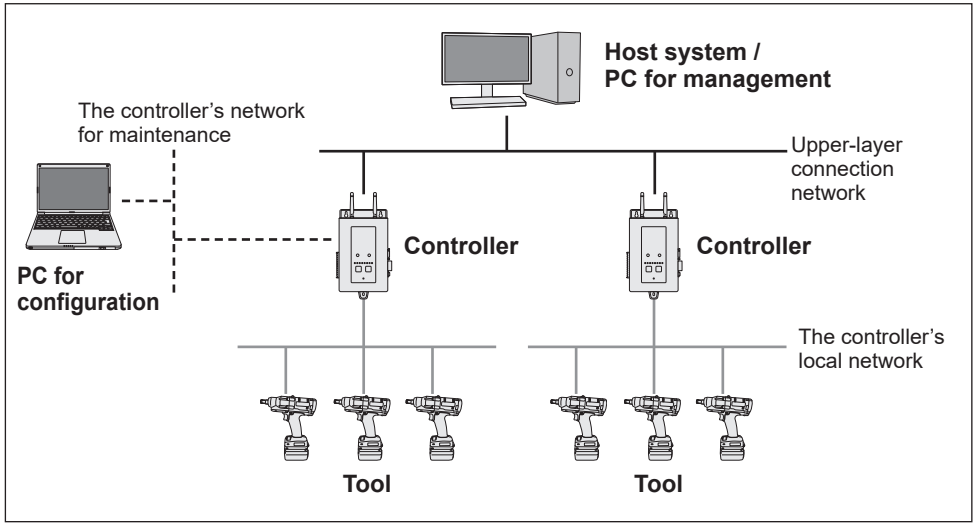


*1 The “tool setting software” can be downloaded from our web site. **Refer to P2**
*2 This is only supported by the firmware version 2.03.00 or later.

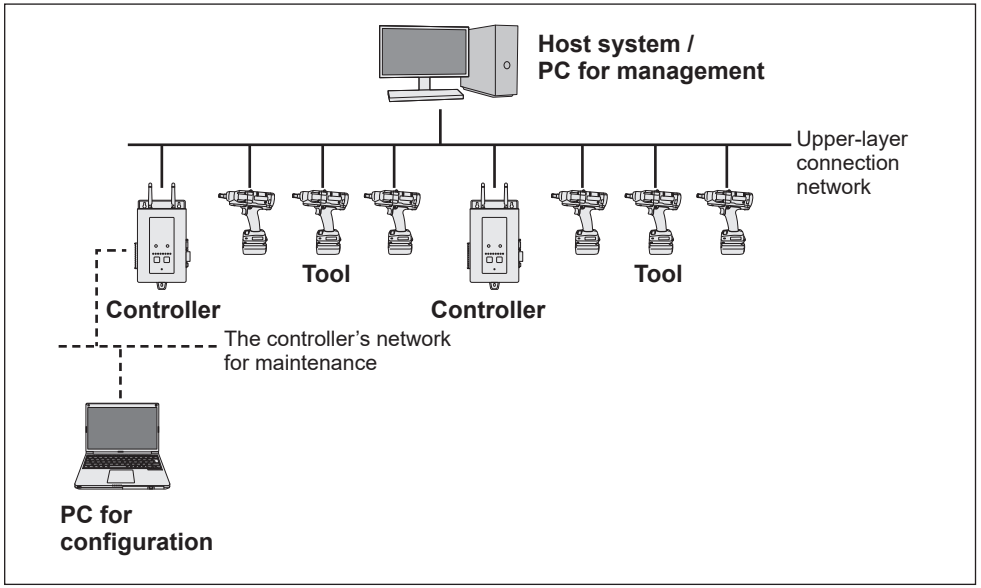
Typical Network Configurations

The controller can be used in the 4 configurations below.

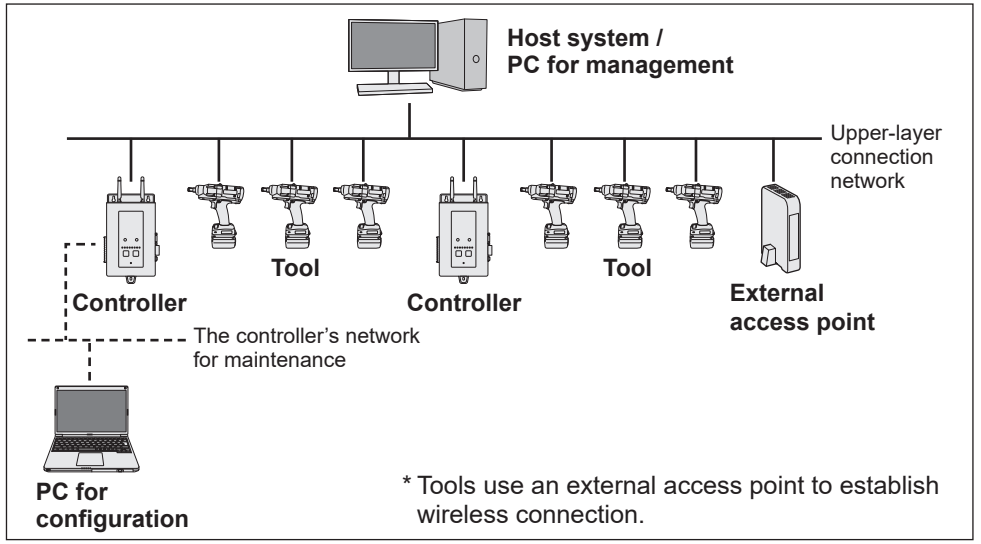
■ Not managing tools' IP addresses
*** Automatic assignment (using the access point built in the controller)**



■ Managing tools' IP addresses (using the access point built in the controller)

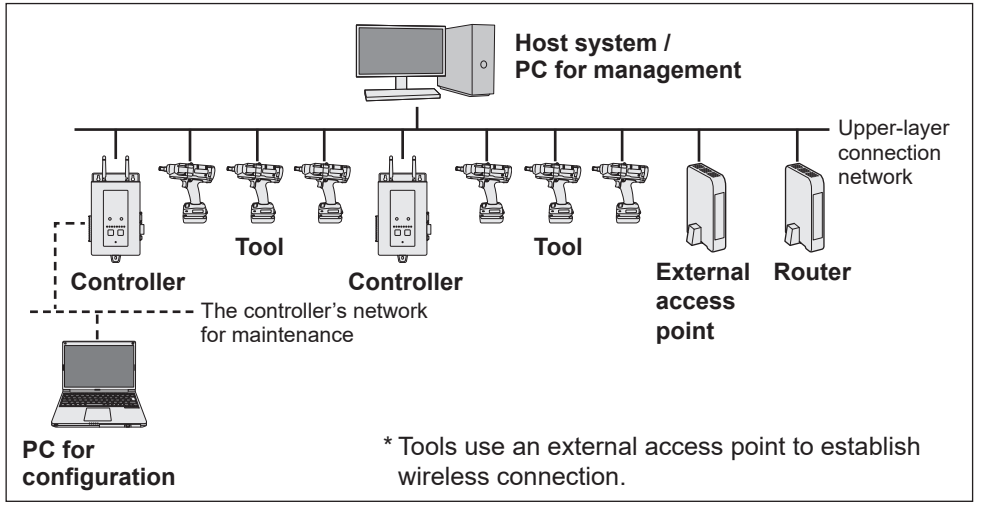


■ Recognising tools' IP addresses (using external access points)



* Use the system within your local network (with no Internet connection).
* Be sure to check the IP address setting for network of the controller before starting use. (Change the default if necessary)

■ Not managing tools' IP addresses
*** Automatic assignment (From the DHCP server in the upper-layer connection network)**



* Depending on the network firewall settings, it may not be available. Check the settings in advance.

Compatibility

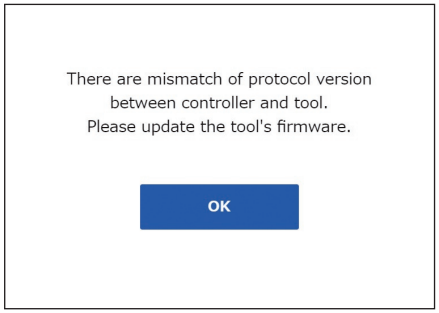
To realize some of the network configuration patterns, it is necessary to update the firmware to the latest version as follows.
Check the compatibility table below and update it as necessary. **Refer to P95**

Controller firmware	Tool body firmware
Ver2.04.00 or later	Ver2.04.00 or later
Ver2.00.00 to 2.03.00	Ver2.00.00 or later

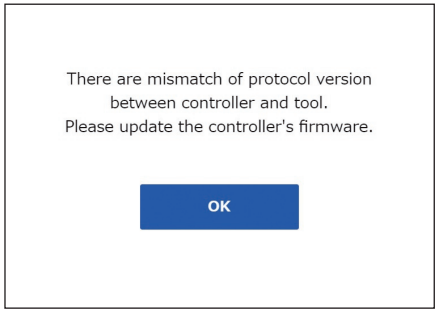
Display for Version Mismatch

If a tool without the above compatibility is paired and registered to the controller, a warning will be displayed as follows.

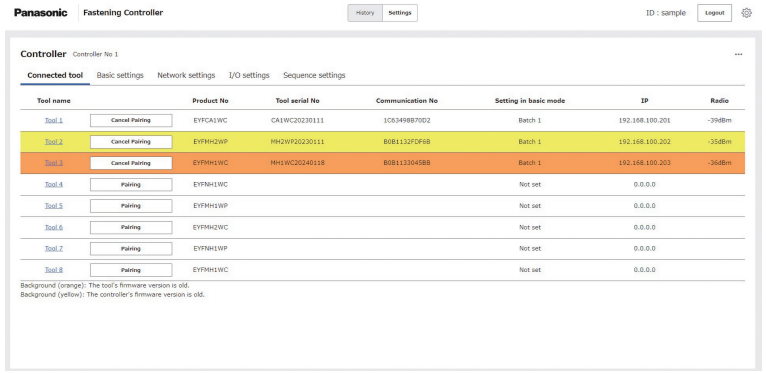
If the tool firmware version is outdated



If the controller firmware version is outdated



For orange background: The tool firmware version is outdated
For yellow background: The controller firmware version is outdated



Applicable Tool Models List

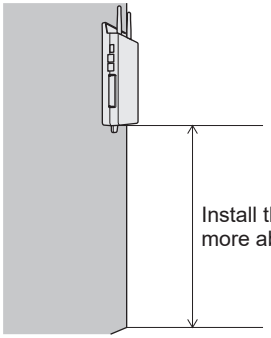
Models that can be registered	EYFMH1WC, EYFMH2WC EYFNH1WC*1, EYFCA1WC*2

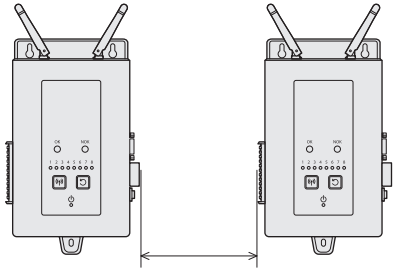
*1 This is only supported by the firmware version 2.02.00 or later.
*2 This is only supported by the firmware version 2.04.00 or later.
• Please refer to the latest general catalogue.

Cautions for Installation

Install the controller 80 cm or more above the floor. Keep 10 cm or more between the installed controllers. (1 m or more is recommended)
Keep obstructions away from the antennas of the installed controller.
The controller has 2 diversity antennas. Keep obstructions away from both antennas.

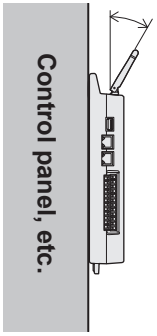
⚠ CAUTION
For safe installation, use wood screws with a nominal diameter of 3.5 mm to 4.1 mm.



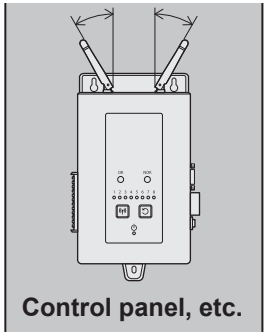


Adjust the antennas' angles if communication is unstable.
* Particularly for the controller installed on a metal panel, adjusting the antennas' angles may improve the communication stability.

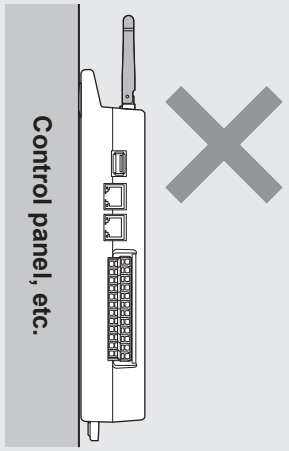
Tilt the antennas 30 to 45° from the wall.



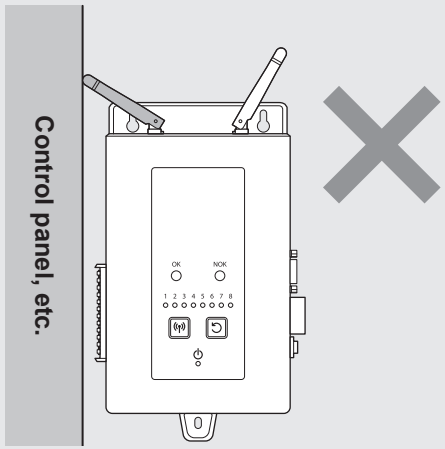
Tilt the antennas 30 to 45° outward when seen from the front.



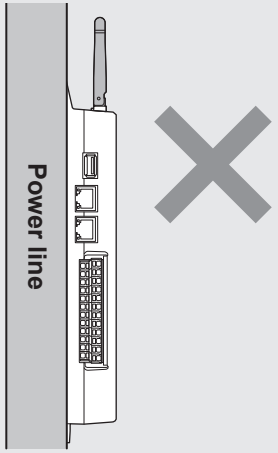
■ Avoid the following installation.



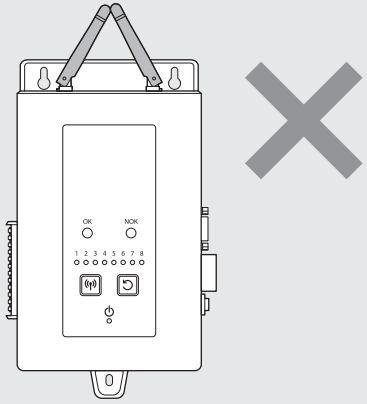
The antenna is in parallel with the control panel (metal panel) on the back side.



The antenna is in contact with the control panel (metal panel).



The controller is installed very close to a power line.

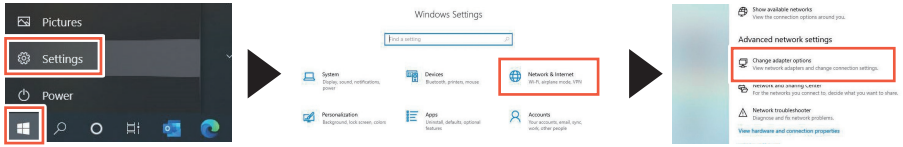


The antennas are in contact with each other.

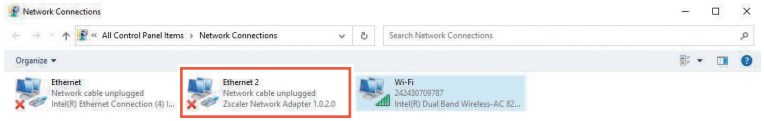
Network Settings on the PC for Configuration

Set the network settings on the PC for configuration as below when you connect it and the controller for the first time.

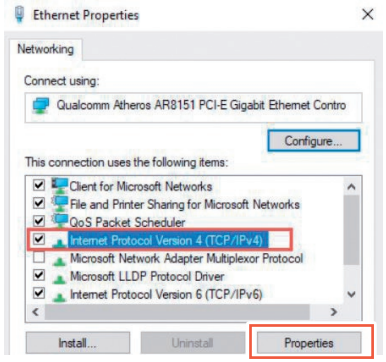
1 Click on the lower left of the screen and click (Settings) - [Network & Internet] - [Change adapter options].



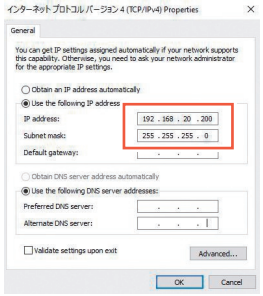
2 Right-click the device to connect and click [Properties].



3 Select “Internet Protocol Version 4” and click [Properties].



4 Set the “IP address” and “Subnet mask” as below.



IP address	192	. 168	. 20	. 200
Subnet mask	255	. 255	. 255	. 0

* If you changed the IP address for the controller after initial connection, enable connection by returning the network settings (IP address and subnet mask) on the PC for configuration. At the time, set the IP address so that the controller and the PC for configuration belong to the same network.
* Write down and keep the network settings of the PC for configuration (IP address and subnet mask) before you change it.
* Leaving the default gateway unspecified (blank) is recommended.

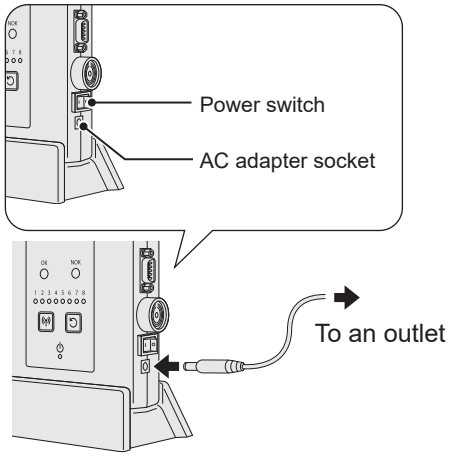
Displaying the Setting Screen

To configure the controller, access it via a web browser.
Display the controller’s setting screen as below.

When you use the controller for the first time, remove the protective film from the coin cell battery.

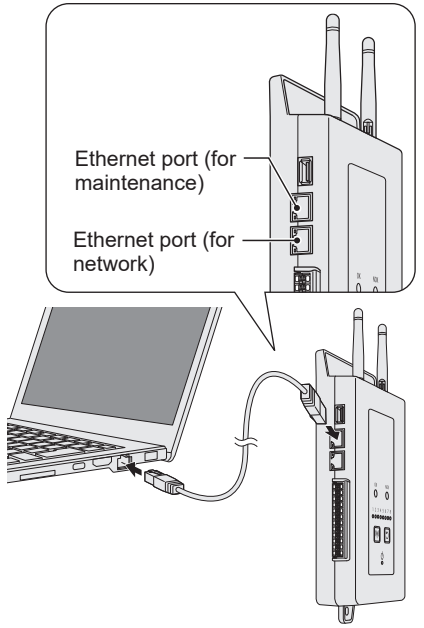
1 Turn the controller on.

① Connect the supplied AC adapter to the controller and connect the power plug to an outlet.
② Turn the controller’s Power switch on.
* It takes a few tens of seconds to start up.
* During startup, the fastening OK lamp, fastening NOK lamp, and communication lamps (No. 1 to No. 8) blink together.
* Do not connect LAN cables.



2 Connect the controller to the PC for configuration with a LAN cable.

① Connect a LAN cable to the Ethernet port of the controller.
* The controller has 2 Ethernet ports: one for maintenance and one for network.
Use the one for maintenance for the first connection.
② Connect to the PC for configuration with the LAN cable.



3 Start a web browser on the PC for configuration and access the controller.

① Start a web browser on the PC for configuration. (Microsoft Edge is recommended)

② Input the IP address of the controller in the address bar of the web browser.

* The default IP address for the Ethernet port (for maintenance) is “192.168.20.10”.

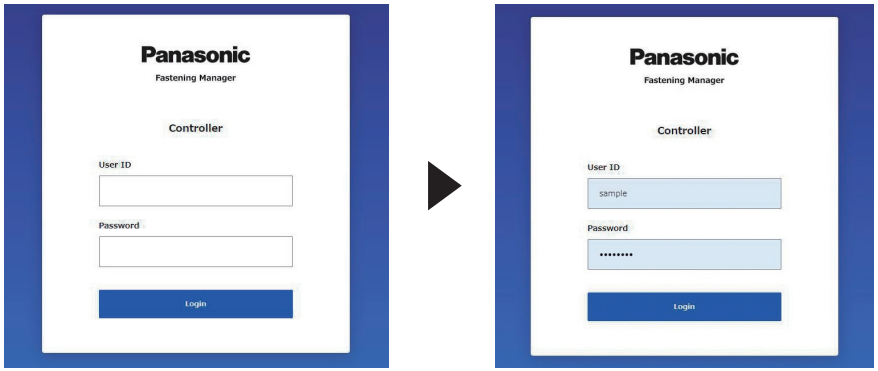
In the address bar of the web browser, input “http://192.168.20.10/controller” to access.
* Inputting “192.168.20.10/controller” only also allows for access.

* For how to access via the Ethernet port (for network), see “Connecting via Network”. Refer to P23

* The IP address should also be set on the PC for configuration.

③ In the displayed login screen, input the user ID and password.
* The user ID and password for the initial login are shown below.

④ The top page (the initial page of the setting screen) is displayed.



User ID and password for the initial login

Log in with the user ID and password below.

■ **User ID:** **root**

■ **Password:** **abcABC123**

* The account type for the initial login is “default”.
For the account types, see “Account Types (Authorities)”. Refer to P21

* Only account creation is possible when you log in with the user ID and password above. Create a new account before starting use.

* For security, changing the password above is recommended after the initial login.

Account Types (Authorities)

Below are the account types. Use them according to the applications.

Account Type	Function
Default	• For the initial login. Refer to P20 Adding or changing a user account.
Administrator	• Viewing the fastening history. • Configuring the controller. • Configuring tools. • Adding or changing a user account. * Create at least one administrator account.
General	• Viewing the fastening history (including viewing the work monitor).

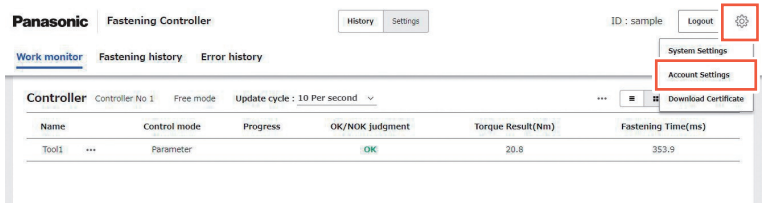
Up to 10 accounts can be registered.
Thus, more than one operator can log in simultaneously.
* Only one account can log in as administrator at the same time.
When multiple accesses are attempted, the last session takes priority.

Creating a User Account

Create a new account before starting use.

1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “Account Settings”.

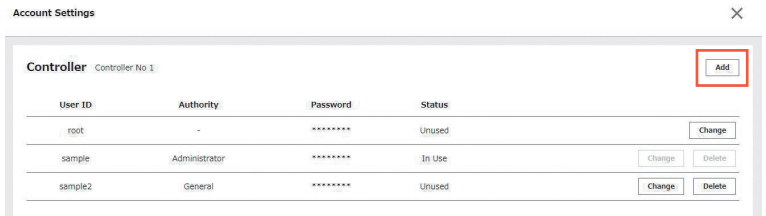
The “Account Settings” screen is displayed.



2 In the “Account Settings” screen, click [Add].

The “Add account” screen is displayed.

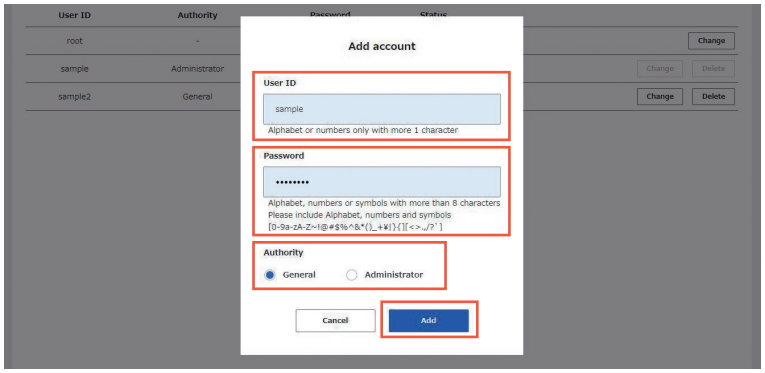
• Click [Change] to change the account and [Delete] to delete the account.



OPERATION

3 Input “User ID” and “Password”, select “Authority”, and click [Add].

* Create an administrator account to configure tools.
* For a password, always use a combination of 3 or more types from upper case, lower case, number, and symbol.



[Reference] If you lost the user ID or password

■ General account

[Method 1] Log in as administrator and make changes to the account concerned.
* A general user cannot change the user ID and password and needs to ask an administrator to change them.

[Method 2] Log in with a newly created administrator account and make changes to the account concerned.
* Log in with the user ID and password for the initial login and create a new administrator account. Refer to P20

■ Administrator account

A) When multiple administrator accounts have been created

[Method 1] Log in with another administrator account and make changes to the account concerned.

[Method 2] Log in with a newly created administrator account and make changes to the account concerned.
* Log in with the user ID and password for the initial login and create a new administrator account. Refer to P20

[Method 3] Initialise the settings if you lost IDs and passwords of all administrator accounts. Refer to P93

B) When only one administrator account has been created

[Method 1] Log in with a newly created administrator account and make changes to the account concerned.
* Log in with the user ID and password for the initial login and create a new administrator account. Refer to P20

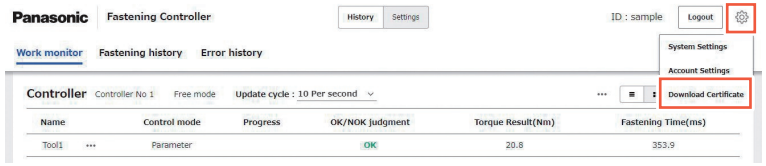
[Method 2] Initialise the settings if you lost IDs and passwords of all administrator accounts. Refer to P93

Obtaining a Certificate

A certificate is necessary to access the controller via the Ethernet port (for network). You can obtain a certificate as below.

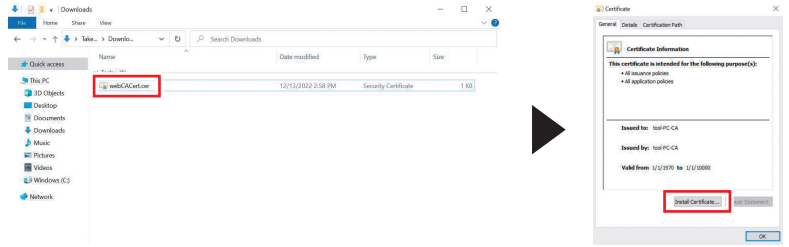
1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “Download Certificate”.

A certificate datum is downloaded to the PC for configuration.

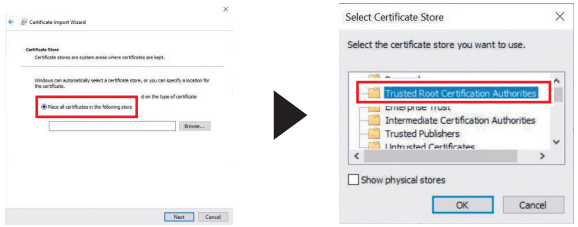


2 Install the certificate in the “PC for configuration used to access the controller via network”.

① Double-click the downloaded certificate datum and select “Install Certificate”.



② Select “Place all certificates in the following store” and then select “Trusted Root Certification Authorities”.

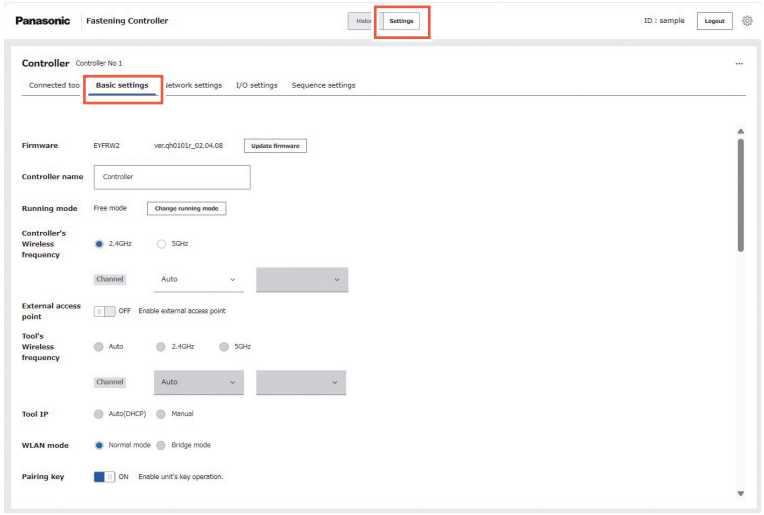


Connecting via Network

In the address bar of the web browser, input “https://XXX.XXX.XXX.XXX/controller” to connect the controller via the Ethernet port (for network).
* “XXX.XXX.XXX.XXX” is an IP address.
* The default IP address is “192.168.0.10”. If you changed the default address, input the changed one. Refer to P30

Basic settings

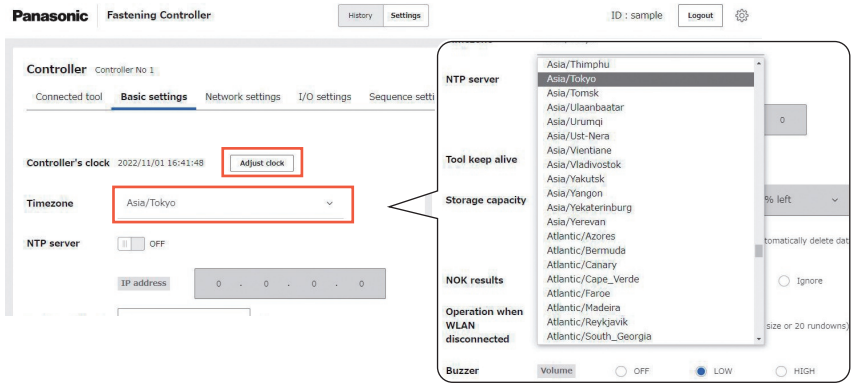
In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.
You can configure the controller.



■ Time setting

Select “Timezone” and then click [Adjust clock].
The time is updated.

- The time is not set yet at the time of shipment. Be sure to set the time when you use the controller for the first time.

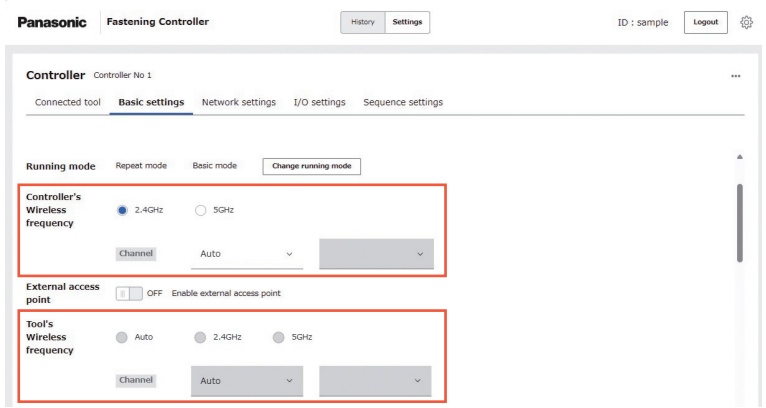


* If you use an NTP server, input the IP address.

■ Radio frequency and channel setting

You can set the frequency to use.
Select “2.4GHz” or “5GHz” and then the channel to use.

* When using the external access point, set the tool's frequency in “Tool’s Wireless frequency”.
* Selectable channels differ between “2.4GHz” and “5GHz”.
* When “Channel” is set to “Auto”, the controller automatically selects available channels in the surrounding environment when it turns ON.
  The setting may be effective against radio interference.
* When installing multiple controllers close to each other, do not set adjacent channels.



■ Setting items

Firmware

The firmware version of the controller is displayed.
Click [Update firmware] to update the firmware.
For how to update, see “Updating the Firmware”. Refer to P95

Controller name

You can register the controller’s name.
Use a maximum of 32 alphanumeric characters.
[Default] Controller
[Setting range] Up to 32 alphanumeric characters

* For symbols, only “-” (hyphen), “_” (underscore), and “ ” (half-width space) can be used.

Running mode

Select the running mode of the controller.
[Default] Free mode
[Setting range] Free mode / Repeat mode (Basic mode / Sequence mode) / External control mode

Controller’s Wireless frequency

Select the controller frequency channel to use for wireless communication.
[Default] 2.4GHz
[Setting range] 2.4GHz (Auto / Channel 1 to 13) / 5GHz (Auto / Channel 36, 40, 44, 48)

* Channels 12 and 13 are not available in China and Korea.

External access point

You can enable communication via an external access point. Refer to P73
[Default] OFF (disabled)
[Setting range] OFF (disabled) / ON (enabled)

* Setting “Tool IP” to “Auto (DHCP)” allows the network configuration without managing the tool’s IP address. Refer to P13

Tool’s Wireless frequency

Select the channel used by the tool when using an external access point.
[Default] Auto
[Setting range] Auto / 2.4GHz (Auto / Channel 1 to 13)/ 5GHz (Auto / Channel 36, 40, 44, 48)

* When set to “Auto”, a usable channel is automatically selected from “2.4GHz” and “5GHz”.
* Channels 12 and 13 are not available in China and Korea.

Tool IP

The method for setting the tool’s IP address can be selected.
[Default] Manual
[Setting range] Auto (DHCP) / Manual

* This setting is available only when “External access point” is turned ON.

WLAN mode

The controller can select the method for setting the tool’s IP address when using the built-in access point.
[Default] Normal mode
[Setting range] Normal mode / Bridge mode

* “Normal mode” : The tool’s IP address is automatically assigned.
* “Bridge mode” : The tool’s IP address is specified manually.

Pairing key

You can enable the Pairing key.
[Default] ON (enabled)
[Setting range] OFF (disabled) / ON (enabled)

Reset key

You can enable the Reset key.
[Default] ON (enabled)
[Setting range] OFF (disabled) / ON (enabled)

Controller's clock

Set the controller's clock.
Click [Adjust clock] to update the time.

Timezone

You can set a desired time zone when adjusting the controller's clock.

NTP server

Set an NTP server if you use automatic clock adjustment.

Tool keep alive

Set the time interval when the controller checks availability of tools in the wireless communication mode.
Tools not responding are detected as offline and then disconnected.

[Default] 30 s
[Setting range] 10 s to 3600 s

Storage capacity

Enable or disable notification of low storage capacity and set the behaviour in case of capacity shortage.

[Default] Notification - OFF,
Operation when capacity is insufficient - Automatically delete data
[Setting range] Notification - OFF/ON (remaining capacity 10/20/30/40/50%),
Operation when capacity is insufficient - Suspend operation / Automatically delete data

The default setting is "Automatically delete data".
Consider well how to handle data before selecting "Suspend operation" as necessary.

NOK results

Select how to handle the fastening failure results.

[Default] Store data only
[Setting range] Report to system / Store data only / Ignore

Operation when WLAN disconnected

Select the behaviour in case of temporary disruption of wireless communication.

[Default] Suspend tool
[Setting range] Suspend tool / Enable fastening (Until batch size or 20 rundowns)
For details, see "TOOLS' BEHAVIOUR WITH WIRELESS COMMUNICATION DISCONNECTED". Refer to P80

Buzzer

Select the volume and meaning of the buzzer.

[Default] Volume - LOW,
Beep - All checked
[Setting range] Volume - OFF/LOW/HIGH,
Beep - Check or uncheck each item

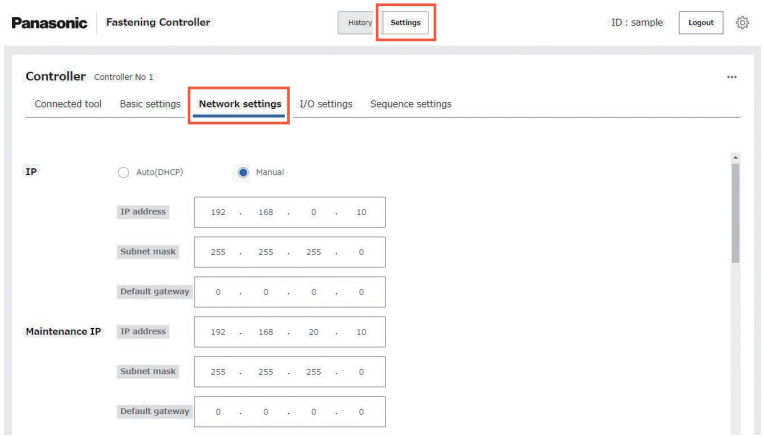
Barcode reader settings

You can connect a barcode reader to add read information to the fastening history data.

[Reading Test] Displays the information read by the barcode reader.
[Bluetooth settings] These settings are used when you connect a Bluetooth-type barcode reader.
The "Search" button displays connectable devices.
Use "Pairing" to select a device to connect.
If it is already connected, the MAC address/device name will be displayed.
You can disconnect it by selecting "Cancel registration".

Network Settings

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Network settings” tab.
You can make network settings of the controller.



■ Setting items

IP

Set the IP address of the Ethernet port (for network).

[Default] Manual
[Setting range] Auto (DHCP) / Manual

* For “Manual”

[Default] IP address - 192.168.0.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Maintenance IP

Set the IP address of the Ethernet port (for maintenance).

[Default] IP address - 192.168.20.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

WLAN

Set the IP address (on the controller’s side) for wireless communication with tools.

[Default] IP address - 192.168.100.1
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Atlas Open Protocol

Set the parameters related to Atlas Open Protocol.
For details, see “Connecting via Open Protocol Communication”. Refer to P61

RS232C

This is a setting specific to TOYOTA MOTOR CORPORATION. Control from external devices is possible.
[Default] Disable
[Setting range] Disable / Enable

Step flow after tightening NG

This setting determines whether you can proceed to the next tightening in case of a tightening NG result.
[Default] Keep
[Setting range] Next (The next tightening can be performed.) / Keep (The next tightening cannot be performed.)

Access point

Set the internal access point for wireless communication with tools.

[Default] SSID - Controller’s model number-MAC address
Security - WPA2
[Setting range] SSID - A maximum of 32 alphanumeric characters
Security - WPA2

External access point

Set the external access point to use.

[Default] SSID - Blank
Security - Blank
Password - Blank
[Setting range] SSID - A maximum of 32 alphanumeric characters
Security - Open/WPA2
Password - 8 to 63 alphanumeric characters

* For symbols, only “"”, “¥”, “,”, and “‘ (back quote)” can be used.
* The option is enabled only when “External access point” has been set to “ON” in the basic setting.

- For the IP addresses for “IP” and “Maintenance IP”, do not use the same subnet. (When you set a default value (255.255.255.0) in “Subnet mask”, set different values in the part corresponding to “192.168.0” or “192.168.20”.)
- Only one of “Atlas Open Protocol” and “RS232C” can be turned ON. They cannot be used simultaneously.

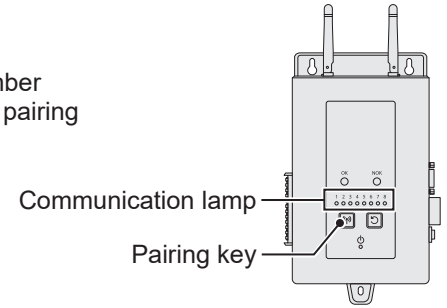
Starting the Pairing Mode on the Controller

You can put the controller in the pairing mode by “Using the key on the unit” or “Setting in the setting screen”.
During 2 minutes of the pairing mode, start the pairing mode on a tool within the coverage to automatically establish pairing.
If pairing is not established within the time, the pairing mode will end.

* After you attempt to start pairing, it may take some time until the controller enters the pairing mode.

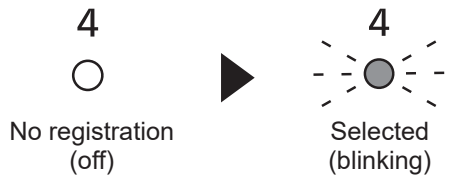
■ Using the key on the unit

Use the Pairing key on the controller unit.
Select the communication lamp of the number with no registration (lamp off) and hold the pairing key down to enter the pairing mode.
See the following procedure for details.

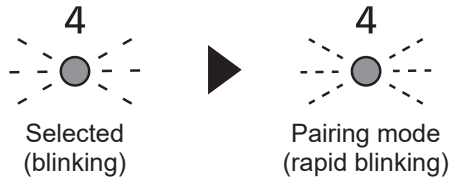


(To register Tool No. 4)

1 Press the Pairing key on the controller 4 times to select Tool No. 4.
Communication lamp No. 4 blinks.



2 While No. 4 is selected, hold down the Pairing key on the controller to enter the pairing mode of Tool No. 4.
In the pairing mode, Communication lamp No. 4 starts blinking rapidly.

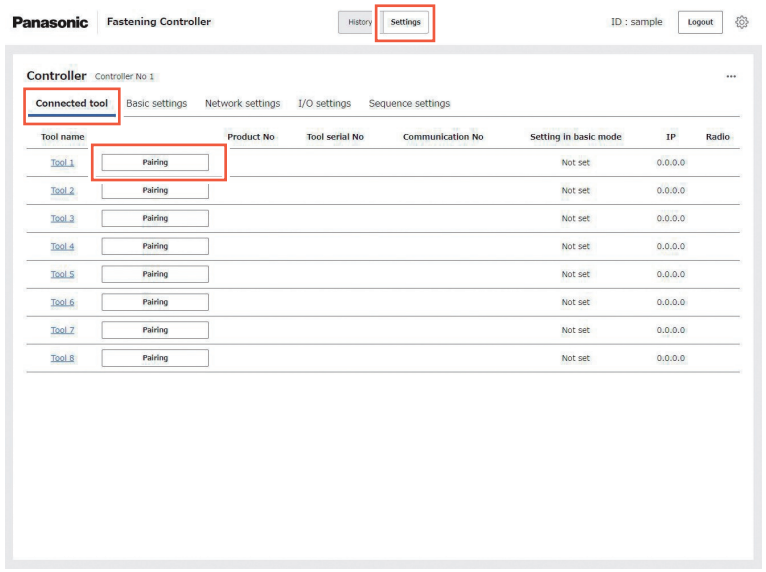


3 Operate Tool No. 4 to establish pairing.
Communication lamp No. 4 stays lit.
For how to operate the tool, see “Starting the Pairing Mode on a Tool”. Refer to P34



■ Setting in the setting screen

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.
In the “Connected tool” screen, click [Pairing] of the desired tool number.
After the controller enters the pairing mode, perform the procedure in “Starting the Pairing Mode on a Tool”. Refer to P34



<For reference> Replacing with a spare tool

When replacing a defective paired tool with a new one with the same model number, cancel pairing Refer to P34 and then conduct pairing Refer to P32 so that the fastening parameters and other settings can be automatically transferred.

* To pair with a tool with a different product number, cancel pairing to delete the current pairing information before pairing with it. Refer to P38

Display after pairing is completed

After pairing is completed, if the setting screen does not display the information of the paired tool, conduct display update in the setting screen.

* In the “Bridge mode” or when “External access point” is enabled, set the tool’s IP address before starting pairing registration.

Starting the Pairing Mode on a Tool

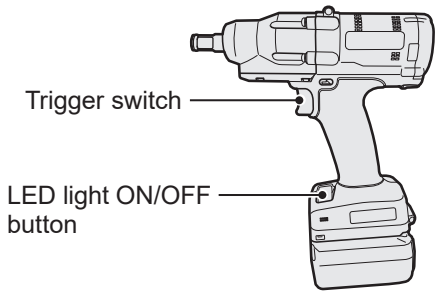
Put the controller in the pairing mode before starting the pairing mode on a tool.

■ Procedure

1 Set the battery pack. While holding down the LED light ON/OFF button, pull the Trigger switch.

The tool enters the pairing mode. Wireless communication is automatically established and pairing registration is completed.

* For details, see the tool's Operating Instructions.
* If pairing fails, cancel pairing on the controller and then try again.

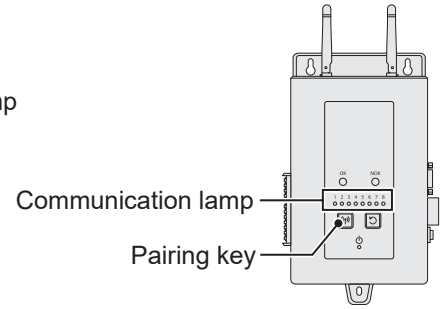


Cancelling Pairing

You can cancel pairing registration on the controller by "Using the key on the unit" or "Setting in the setting screen".

■ Using the key on the unit

Use the Pairing key on the controller unit. Select the communication lamp of the tool number you want to cancel registration (lamp on) and hold the pairing key down to cancel pairing registration.
See the following procedure for details.



(To cancel Tool No. 4)

1 Press the Pairing key on the controller 4 times to select Tool No. 4.

Communication lamp No. 4 blinks.



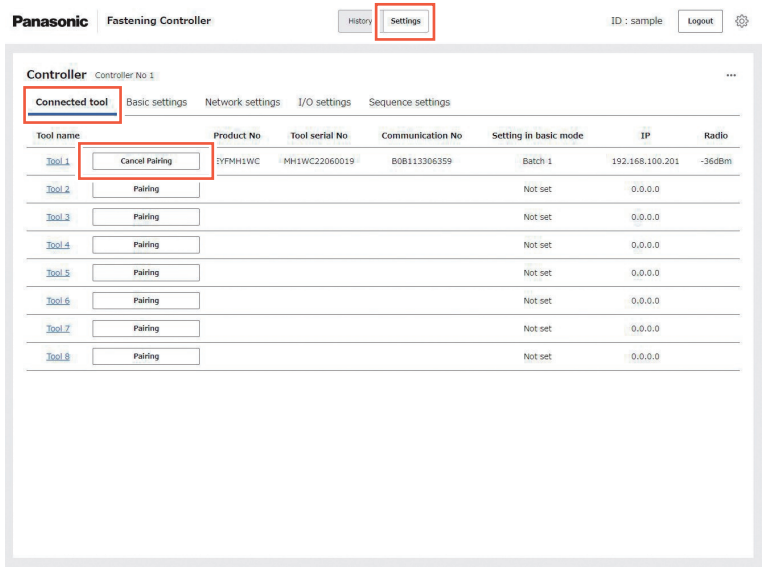
2 While No. 4 is selected, hold down the Pairing key on the controller to cancel pairing registration of Tool No. 4.

When pairing is cancelled, Communication lamp No. 4 stops blinking and turns off.



■ Setting in the setting screen

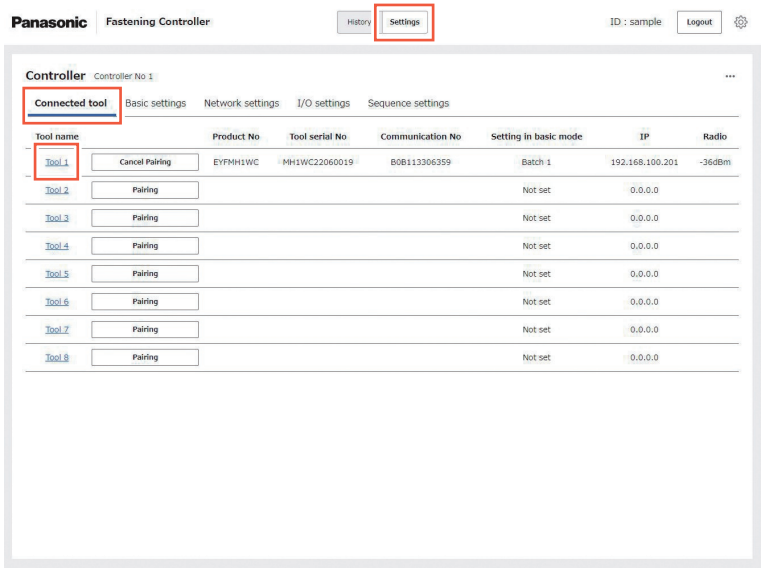
In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Connected tool" tab.
In the "Connected tool" screen, click [Cancel Pairing] of the desired tool number.



* If the controller cannot communicate with the tool due to the tool being turned off or any other reason, check [Force to unpair] in the pairing cancellation confirmation dialogue.

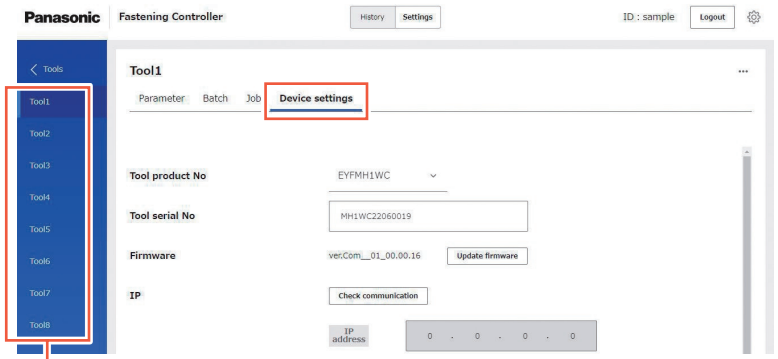
Displaying the Tool Screen

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.
In the “Connected tool” screen, click the desired tool number.
The screen for the tool number is displayed.



Displaying the Tool Setting Screen

From the “Device settings” tab in the screen for the tool number, you can make basic settings of the tool and enter common parameters.
* To switch the tool, select the desired one from the tool list.



Tool list

Tool Setting Items

Tool product No

Select the tool product number.

[Default] Blank
[Setting range] Selectable from the pull-down menu

* Automatically selected if you establish pairing beforehand.
* The tool product number cannot be changed after pairing. Cancel pairing and then change it.

Tool serial No

You can set and display the tool’s unit identification.

[Default] 5-digit model ID + 8-digit serial number (2-digit manufacturing year + 2-digit month + 4-digit production lot)
[Setting range] 13 to 16 alphanumeric characters

* The model number may not be recognised correctly if the information is changed. Do not change it unless required by the management rule.

Firmware

The firmware version of the tool’s communication part is displayed.
Click [Update firmware] to update the firmware.
For how to update, see “Updating the Firmware”. **Refer to P95**

IP

Set the IP address (on the tool’s side) for wireless communication with tools.

[Default] IP address - 192.168.100.201 (Tool 1) to 208 (Tool 8)
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

* They all become “0.0.0.0” in the Bridge mode or when “External access point” is enabled.

Tool’s clock

The tool’s clock is displayed. Click [Adjust to controller] to adjust the time.

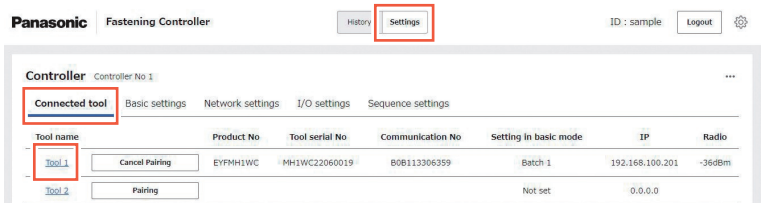
• For other setting items, see the tool’s Operating Instructions.

Deleting the Registration Information

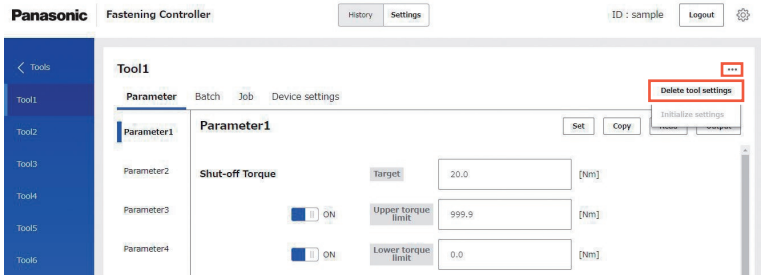
To stop use of a tool or pair a tool with a different product number, delete the pairing information.
* Cancel pairing beforehand.

1 **In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.**
The “Connected tool” screen is displayed.

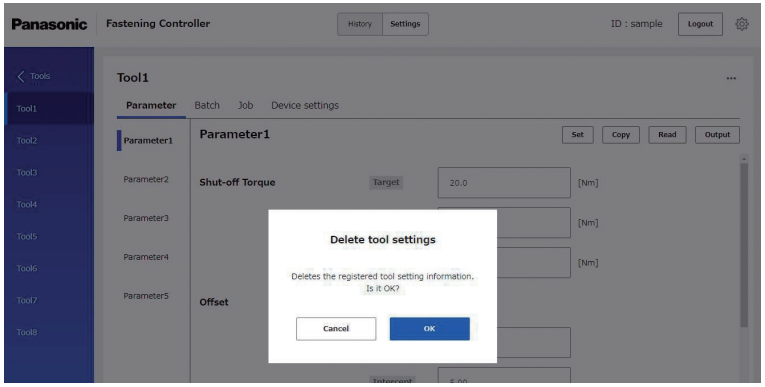
2 **In the “Connected tool” screen, click the desired tool number.**
The screen for the tool number is displayed.



3 **Click ··· (tool option key) and then [Delete tool settings].**
The “Delete tool settings” screen is displayed.



4 **In the “Delete tool settings” screen, click [OK].**

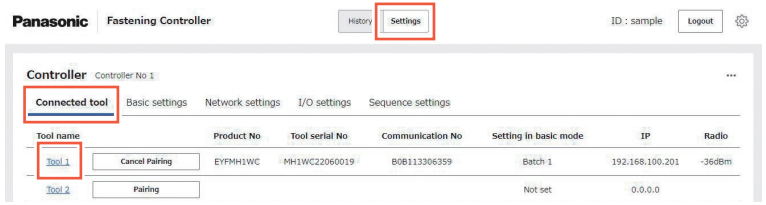


Resetting to Factory Settings

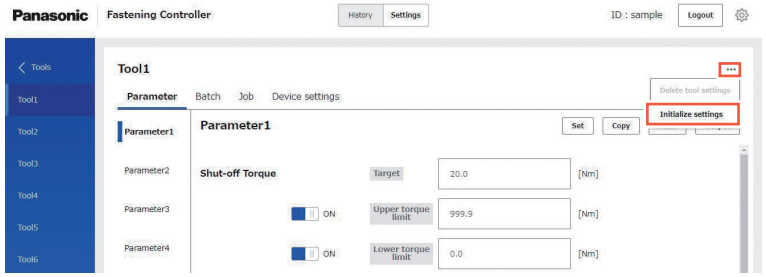
You can reset a tool to its factory settings.
* Resetting cancels pairing.

1 **In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.**
The “Connected tool” screen is displayed.

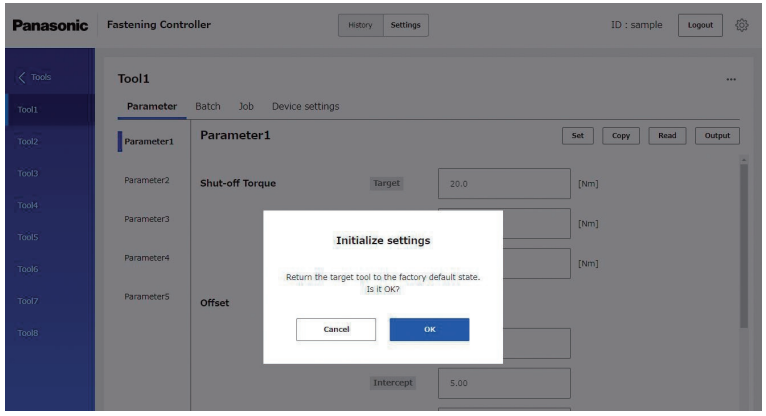
2 **In the “Connected tool” screen, click the desired tool number.**
The screen for the tool number is displayed.



3 **Click ··· (tool option key) and then [Initialize settings].**
The “Initialize settings” screen is displayed.

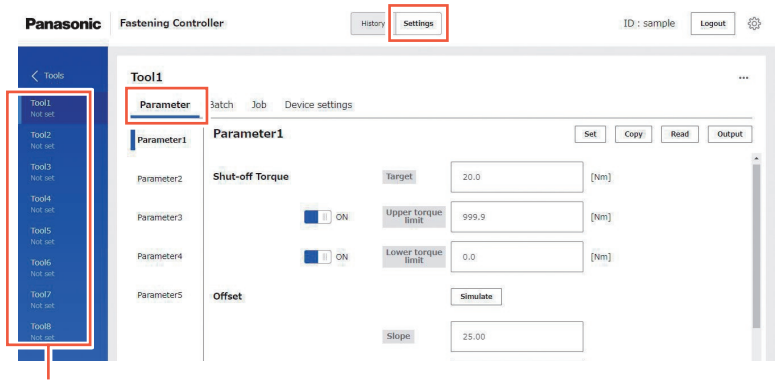


4 **In the “Initialize settings” screen, click [OK].**



Setting Parameters

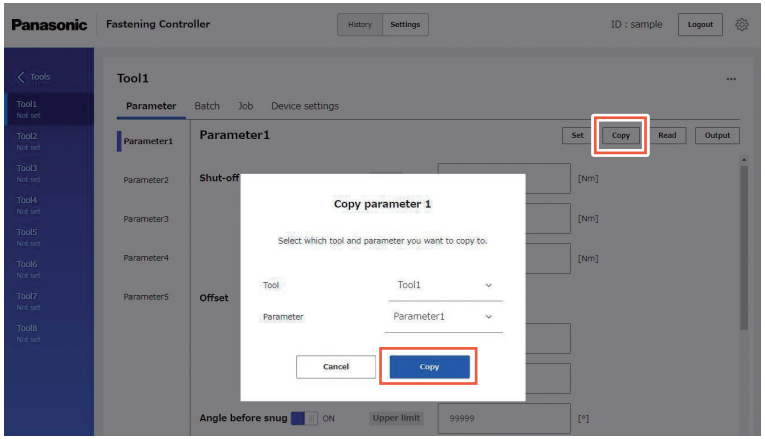
In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.
In the “Connected tool” screen, click the desired tool number.
In the screen for the tool number, select the “Parameter” tab to make settings.
You can set five parameters (Parameter 1 to 5) for each tool.
* To switch the tool, select the desired one from the tool list.



Tool list

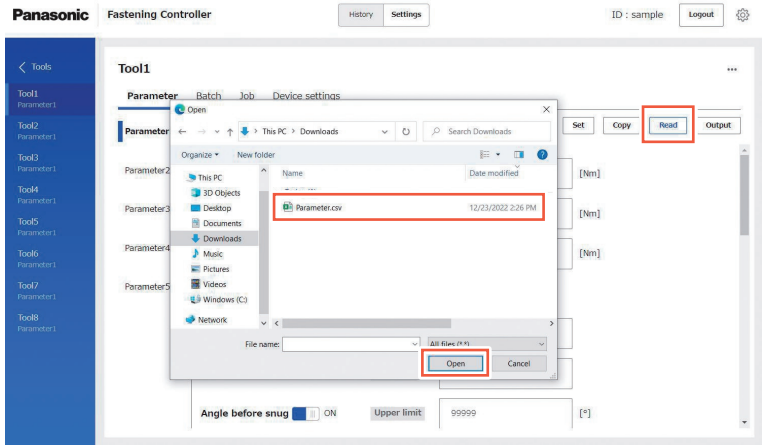
Copying Parameters

You can copy the set parameter to create a new parameter from it or use it on another tool.
In the “Parameter” tab in the screen for the tool number, click [Copy] to display the screen for copying the parameter. In the screen, select the destination and click [Copy].



Loading Parameters

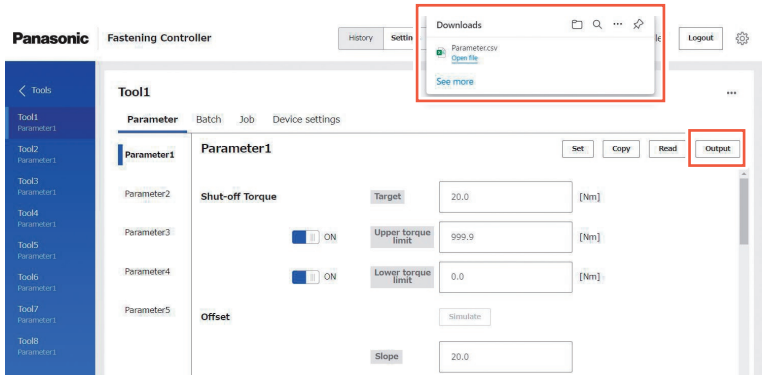
You can register a parameter by loading a parameter file saved in the PC for configuration into the controller.
You can also load a parameter file created with “Tool Manager”.
From the “Parameter” tab in the screen for the tool number, click [Read] and open the parameter file.



Exporting Parameters

You can export the created parameter to the PC for configuration.
You can use the exported file as a backup, to copy it to another controller, or to move it to another PC for configuration.
From the “Parameter” tab in the screen for the tool number, click [Output] and save the parameter file.

Do not edit the exported parameter file.
Otherwise it may not be read correctly.

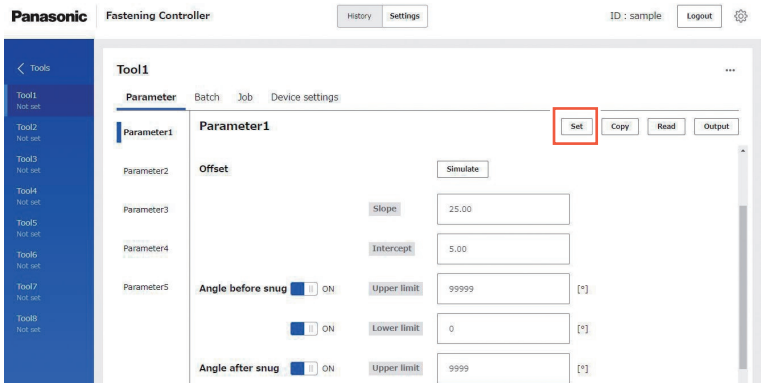


Registering Parameters

Register a parameter to use it to control a tool in “Free mode” of the controller’s running mode.

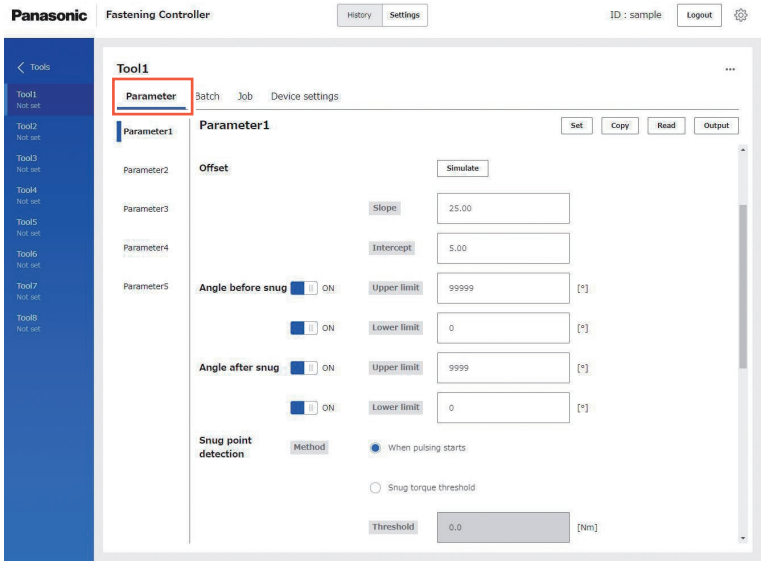
* It is not used in “Repeat mode” and “External control mode”.
  (For “Free mode”, “Repeat mode”, and “External control mode”, see “Setting the Running Mode”. Refer to P49

From the “Parameter” tab in the screen for the tool number, click [Set].



Parameter Items

Set the fastening parameter items.
For details, see the tool’s Operating Instructions.

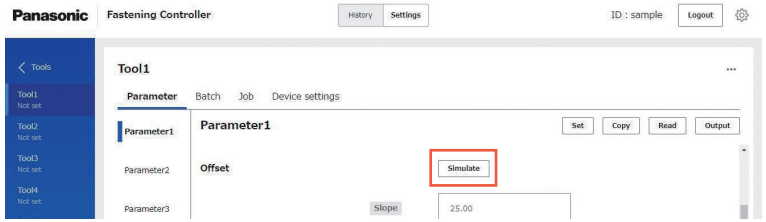


■Setting an offset (Parameter, reference ①)

Set an offset to match the torque output value with the actual measured value.

1 From the “Parameter” tab in the screen for the tool number, click [Simulate] in “Offset”.

The “Offset” page is displayed.



2 Input a value to set and click [Apply].

Input “Socket length” and “Shut-off Torque”.
Click [Apply] to send the input values to the tool.
The tool enters the offset mode (shown as T2).

3 Conduct actual work using the tool and then click [Get data].

A fastening history log is added to the history list in the “Offset” page.

* Although the tool becomes ready for fastening (“C mode”) after you click [Get data], do not start normal fastening until offset setting is completed.

4 While the obtained fastening history log is selected, input an actual measured torque (refastening) value and click [Calculate].

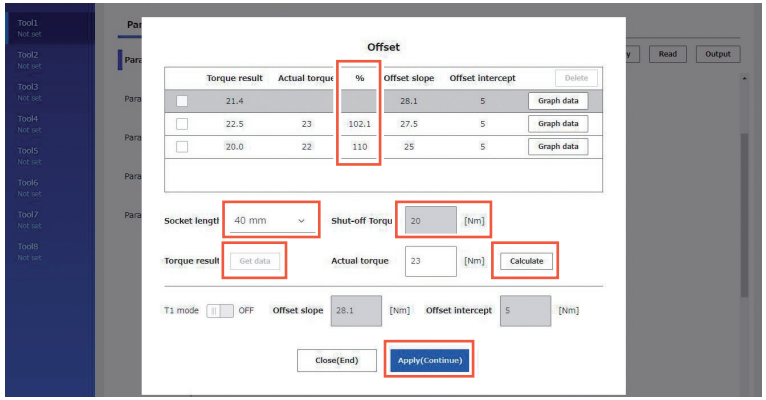
An offset to match the output torque with the actual measured torque of the tool is automatically calculated.

5 Confirm that the offset is updated and click [Apply].

The adjusted value is sent to the tool.

6 Repeat steps 3 to 5 until the difference becomes sufficiently small.

* Keep the values in the “%” column within the range of 95% to 105%.



[About T1 mode]
Checking [T1 mode] in the offset setting screen puts the controller in the minimum output mode.
(Unchecking [T1 mode] returns the controller to “Offset Mode”.)



T1 mode
[Description] You can check whether torque control works successfully when the target torque is close to the lower limit of the controller’s torque control range. In this mode, the controller is shut off at the minimum counts per minute (minimum output). At the time, the work history log is not stored. After working in this mode, use a torque gauge or torque wrench to confirm that the controller’s output torque has not exceeded the target torque. The controller unit may not be usable for some work if its output torque exceeds the target torque in this mode.

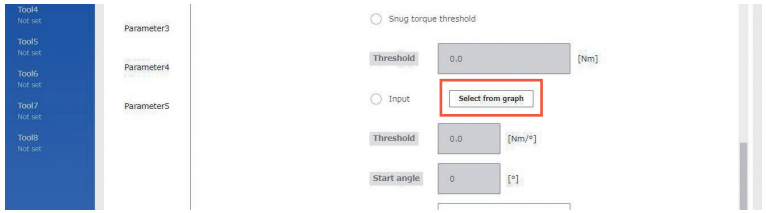
* Fastening by other tools is suspended while you are setting an offset.

■ Setting a snug point (Parameter, reference ②)

You can set a snug point based on a waveform.

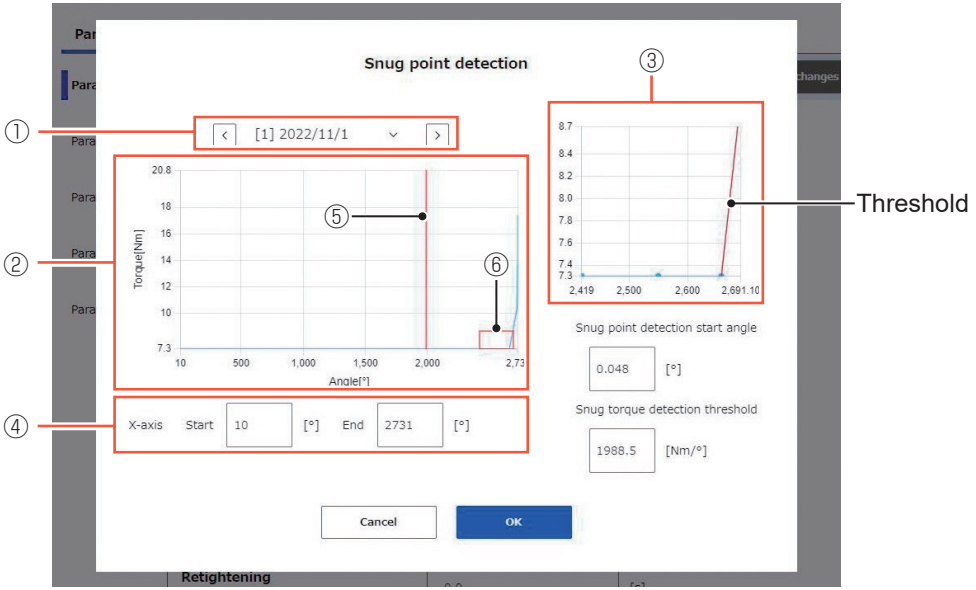
1 From the “Parameter” tab in the screen for the tool number, click [Select from graph] in “Snug point detection”.

- The “Snug point detection” screen is displayed showing the current waveform of the tool.
- Fastening history data are necessary for reference. Make this setting after at least one time of fastening.
- You can switch the waveform to use with arrows (①).



2 Set a threshold in the graph.

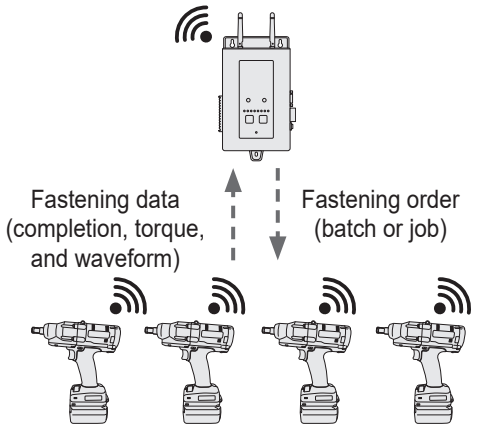
- The main window (②) shows an entire waveform and the subwindow (③) enlarges a specific part from the entire waveform.
- You can change the range of waveform shown in the main window by inputting the start and end angles in “X-axis” (④) below the graph.
- You can set the snug point detection start angle (⑤) by moving the vertical bar.
- Adjust the position of the selection frame (⑥) in the main window to change the display range of the subwindow.
- Select a threshold to set in the subwindow (③).



Controlling Fastening by Tools

The controller can control up to 8 connected tools for fastening.
It receives fastening data of each fastening job and counts up the fastened quantity.

Maximum number of connected devices: 8



Typical Fastening Control Combinations

You can create different combinations of fastening control settings. See typical combinations as below.

Mode	[Free mode]	[Repeat mode]	
		[Basic mode]	[Sequence mode]
Pass criterion	– (The quantity is not specified)	Fastening the target quantity is completed	Tools complete fastening the respective target quantities in the specified order
[Batch] "Single set value" (Fastening in the same condition) * **Single type of workpiece**	A OK Set value: 10 Nm, Target quantity: ∞ Parameter	A OK Set value: 10 Nm, Target quantity: 10 Batch	A ① OK ▶ B ② OK A: Set value 10 Nm, Target quantity 10 B: Set value 20 Nm, Target quantity 5 Batch and Sequence
[Job] Multiple set values (Fastening in different conditions) * **Multiple types of workpiece**		A OK 10 Nm: 2 20 Nm: 3 30 Nm: 5 Job	A ① OK ▶ B ② OK A: 10 Nm: 2; 20 Nm: 3; 30 Nm: 5 B: 20 Nm: 5; 30 Nm: 10 Job and Sequence
Remark	–	* A job can contain up to 10 steps.	* A sequence can contain up to 10 steps.

Number of Combinations That Can Be Registered

See the number of combinations that can be registered in the controller as below.

Controller's mode		Tool's setting	Number of Combinations That Can Be Registered
Free mode		Parameter	○ 5 combinations per tool
Repeat mode	Basic mode (Independent control)	Batch	○ 5 combinations per tool
		Job	○ 5 combinations per tool
	Sequence mode (Sequential control)	Batch/Job	○ 5 combinations
External control mode		–	○

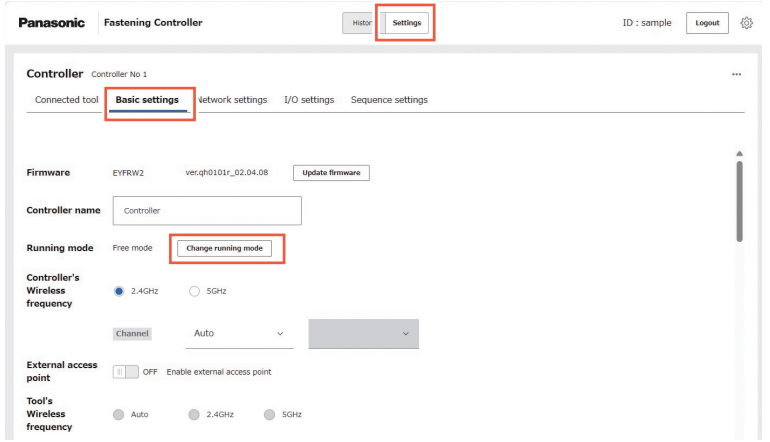
Setting the Running Mode

Set the running mode of the controller as below.

1 In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Basic settings" tab.

2 In the "Basic settings" tab, click [Change running mode].

The "Change running mode" screen is displayed.



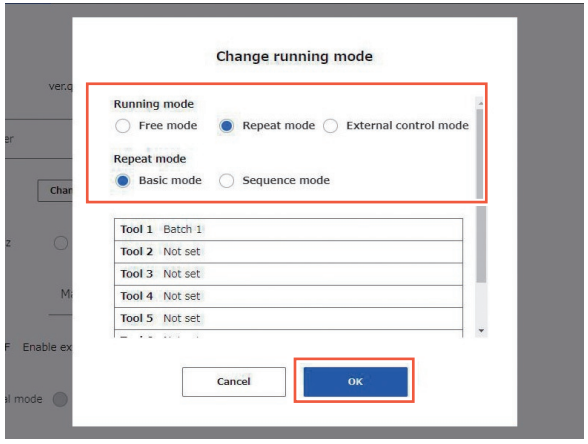
3 Select a "Running mode" and click [OK].

The running mode is set.

Select a running mode from "Free mode", "Repeat mode", and "External control mode".

For "Repeat mode", select "Basic mode" or "Sequence mode".

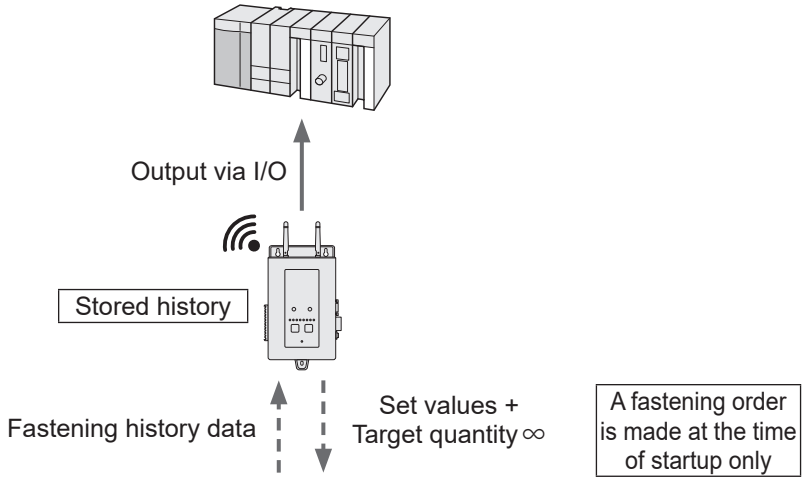
Refer to P50 to 53

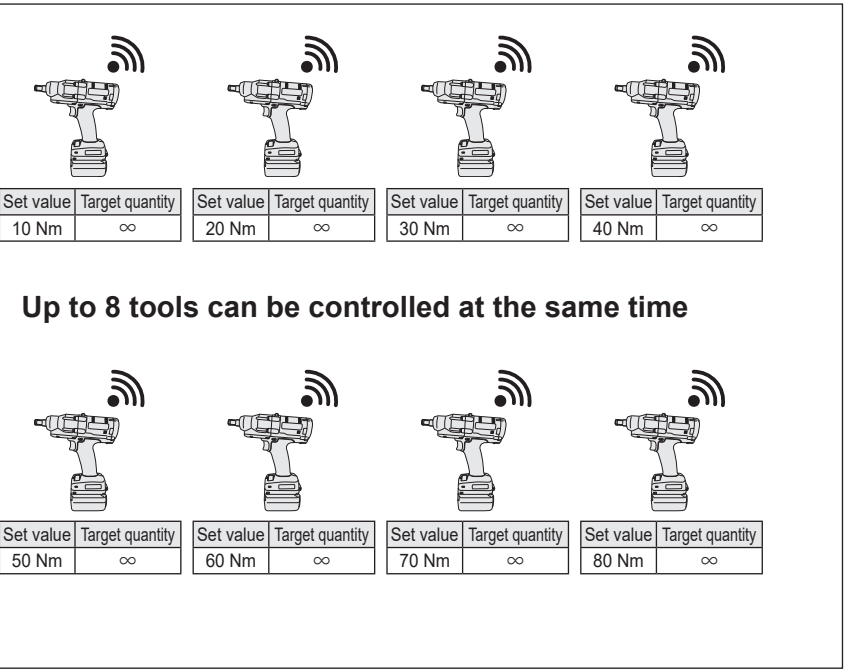


* Register "Parameter" before setting to "Free mode".
* Register a "Batch/Job" before setting to "Repeat mode".

■ Free mode

This mode allows for unconditional fastening without specifying the quantity to fasten.
Tools use pre-registered parameters for fastening.
Up to 8 tools can conduct independent operation.
The I/O output settings are enabled.
* Use the mode when the fastened quantity is counted by an external device.





Set value	Target quantity
10 Nm	∞

Set value	Target quantity
20 Nm	∞

Set value	Target quantity
30 Nm	∞

Set value	Target quantity
40 Nm	∞

Up to 8 tools can be controlled at the same time

Set value	Target quantity
50 Nm	∞

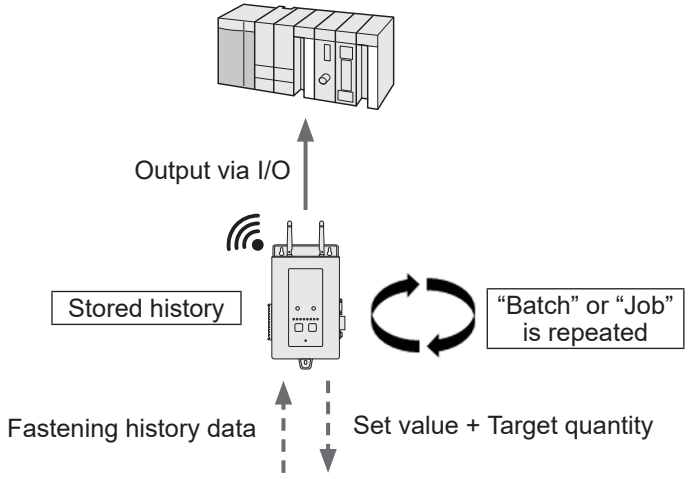
Set value	Target quantity
60 Nm	∞

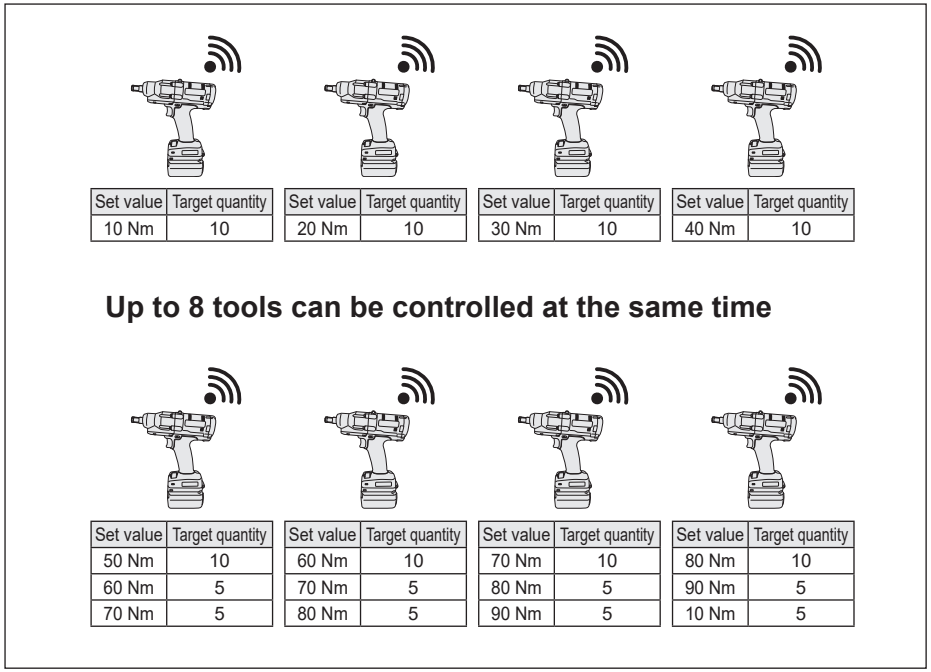
Set value	Target quantity
70 Nm	∞

Set value	Target quantity
80 Nm	∞

■ Repeat mode (Basic mode)

This mode repeats a “Batch” or “Job” process.
Tools use pre-registered “Batch” or “Job” settings for fastening.
Up to 8 tools can conduct independent operation.
The I/O output settings are enabled.





Set value	Target quantity
10 Nm	10

Set value	Target quantity
20 Nm	10

Set value	Target quantity
30 Nm	10

Set value	Target quantity
40 Nm	10

Up to 8 tools can be controlled at the same time

Set value	Target quantity
50 Nm	10
60 Nm	5
70 Nm	5

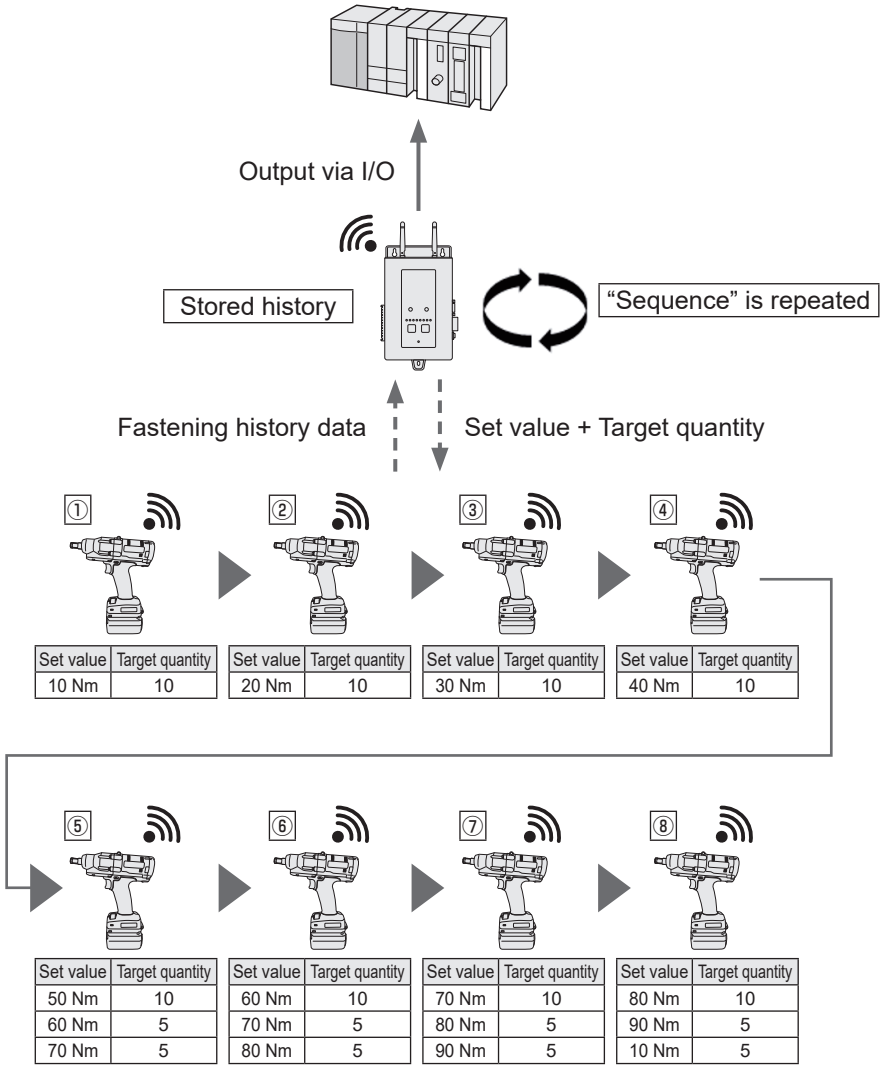
Set value	Target quantity
60 Nm	10
70 Nm	5
80 Nm	5

Set value	Target quantity
70 Nm	10
80 Nm	5
90 Nm	5

Set value	Target quantity
80 Nm	10
90 Nm	5
10 Nm	5

■ Repeat mode (Sequence mode)

This mode repeats a “Sequence” process where available tools are controlled in order.
Tools use pre-registered “Sequence” settings for sequential fastening.
Up to 10 steps can be set. A sequence supports up to 8 tools but allows only one tool to operate at a time.
The I/O output settings are enabled.



Set value	Target quantity
10 Nm	10

Set value	Target quantity
20 Nm	10

Set value	Target quantity
30 Nm	10

Set value	Target quantity
40 Nm	10

Set value	Target quantity
50 Nm	10
60 Nm	5
70 Nm	5

Set value	Target quantity
60 Nm	10
70 Nm	5
80 Nm	5

Set value	Target quantity
70 Nm	10
80 Nm	5
90 Nm	5

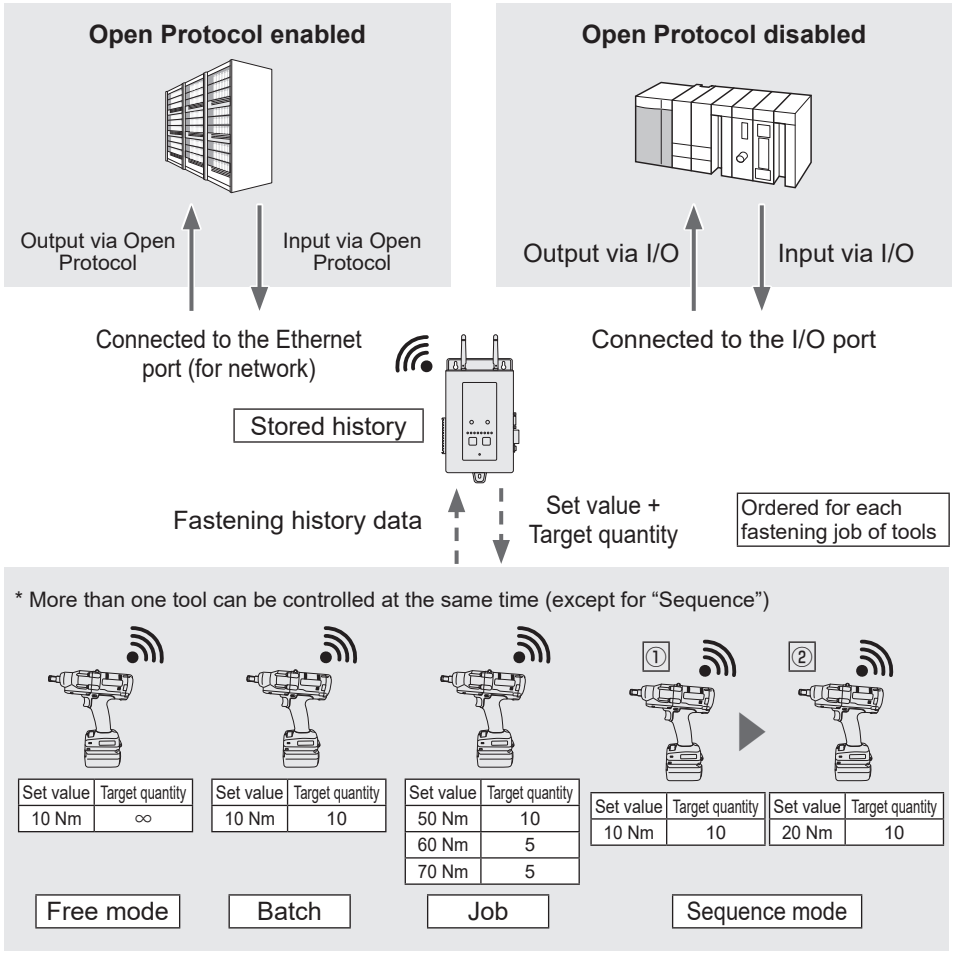
Set value	Target quantity
80 Nm	10
90 Nm	5
10 Nm	5

■ External control mode

This mode allows for fastening control as ordered by an external device (host system).
The following 2 types of control are supported.

● **Control via Open Protocol (with Open Protocol enabled)**
Fastening is controlled via Open Protocol by a host system.
Up to 8 tools can be controlled independently.
* Job and sequence controls are not supported.

● **Control via I/O (with Open Protocol disabled)**
Fastening is controlled by inputs via the I/O port from an external device.
Up to 8 tools can be controlled independently or sequentially.



Set value	Target quantity
10 Nm	∞

Set value	Target quantity
10 Nm	10

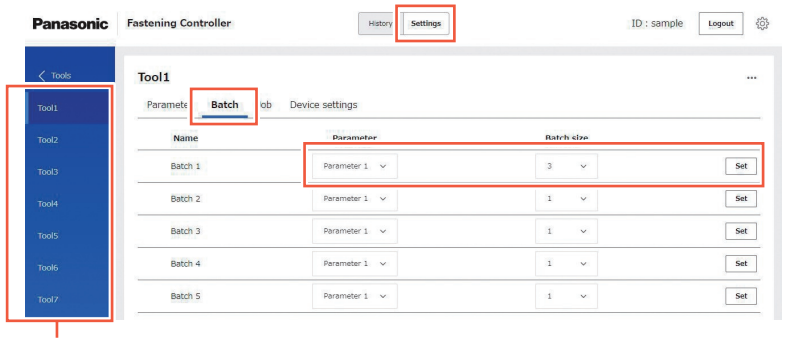
Set value	Target quantity
50 Nm	10
60 Nm	5
70 Nm	5

Set value	Target quantity	Set value	Target quantity
10 Nm	10	20 Nm	10

* If the controller turns off during fastening, fastening does not resume after the controller turns on. Fastening starts again when ordered by an external device.
* The I/O output settings are enabled.

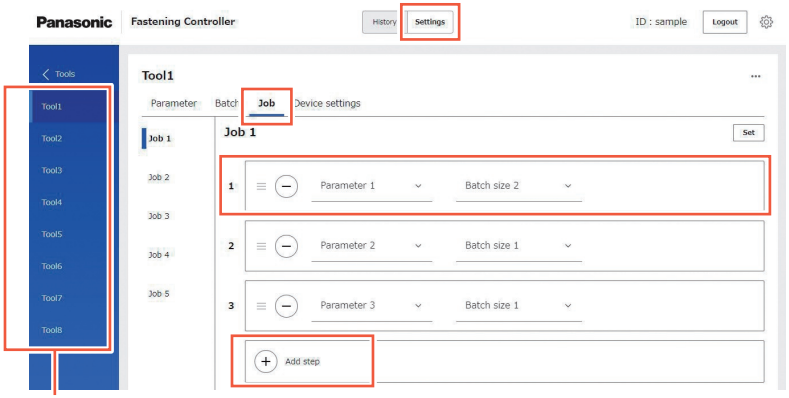
Creating (Setting) a Batch

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab. In the “Connected tool” screen, click the desired tool number.
In the screen for the tool number, select the “Batch” tab and make settings.
Select a parameter from the “Parameter” pull-down menu and set “Batch size” (quantity to fasten, up to 99). Click [Set] to set the values for “Repeat mode (Basic mode)”.
* To switch the tool, select the desired one from the tool list.
* Up to 5 batches can be registered.



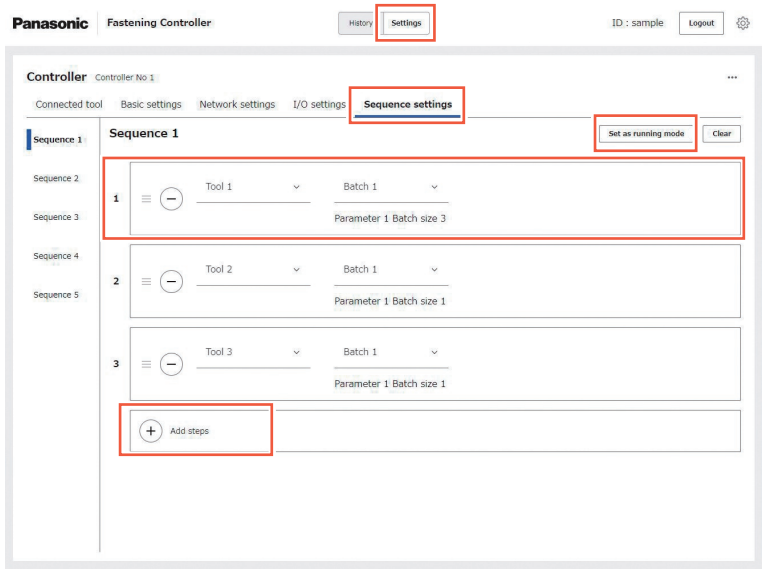
Creating (Setting) a Job

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab. In the “Connected tool” screen, click the desired tool number.
In the screen for the tool number, select the “Job” tab and make settings.
Select a parameter from the “Parameter” pull-down menu and set “Batch size” (quantity to fasten, up to 99). Click [Set] to set the values for “Repeat mode (Basic mode)”.
* Up to 10 steps can be registered.
* To switch the tool, select the desired one from the tool list.
* Up to 5 jobs can be registered.



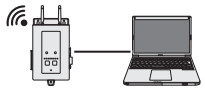
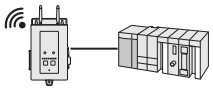
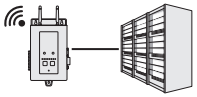
Creating (Setting) a Sequence

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Sequence settings” tab.
In the “Sequence settings” screen, select a tool from the “Tool” pull-down menu and set “Batch” or “Job”.
Click [Set as running mode] to set the values for “Repeat mode (Sequence mode)”.
* Up to 5 sequences can be registered.
* Up to 10 steps can be registered.
* The same tool can be used more than once in a sequence.



Supported Types of External Devices

The controller supports the following types of external device.

Feature	PC for Configuration	PLC	Customer's Host System
Illustration			
Communication method	Ethernet	I/O	Ethernet
Communication protocol	http/https	— (ON/OFF signal only)	Open Protocol
Main use	• Viewing and storing the fastening history • Changing the settings	• Outputting completion and failure signals • Switching the fastening order	• Exporting the fastening history • Switching the fastening order
Data that can be exported	• Serial numbers of tools • Time • Completion and failure results • Torque values, angles, fastening time lengths • Waveform data	• Completion and failure results • Batch/job/sequence complete • Batch/job/sequence selected • Tool active	• Serial numbers of tools • Time • Completion and failure results • Torque values, angles, fastening time lengths • Waveform data
Switching the fastening order	—	• Batch/job/sequence selected	• Parameter/batch selected
Other	Displayed in a web browser. Microsoft Edge is recommended.	8 ports each for input and output	For supported commands, see "Commands compatible with Open Protocol". **Refer to P65** Control sequences should be reviewed respectively.

Connecting to the PC for Configuration in a Remote Location

The PC for configuration with the certificate installed can remotely connect to controllers.
Note that only one access to the configuration function is accepted at a time.
To connect, input the IP address of the desired controller in a web browser.

Refer to P23



Connecting via I/O

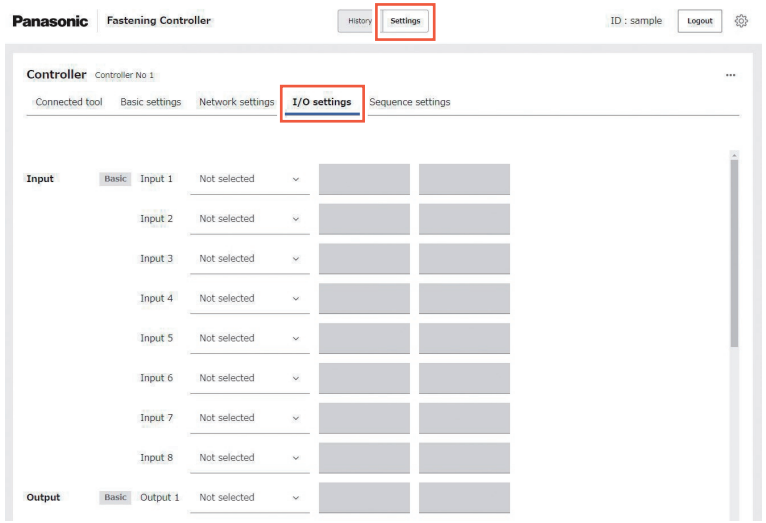
You can assign supported commands to 8 input ports and 8 output ports as desired.
Assign them in the "I/O settings" screen.
Below are the commands that can be assigned to the ports.

Input	Supported command
1	Batch (Tool 1 to 5) Job (Tool 1 to 5) Sequence (1 to 5) Batch reset (1 to 8) Reset Suspend tool (1 to 8) Suspend controller Emergency stop (1 to 8)
2	
3	
4	
5	
6	
7	
8	

Output	Supported command
1	OK (Tool 1 to 8) NOK (Tool 1 to 8) Batch complete (Tool 1 to 5) Job complete (Tool 1 to 5) Sequence complete (1 to 5) Tool active (Tool 1 to 8) Batch selected (Tool 1 to 5) Job selected (Tool 1 to 5) Sequence selected (1 to 5)
2	
3	
4	
5	
6	
7	
8	

Setting I/O

In the top page (the initial page of the setting screen), click [Settings] on the top and select the "I/O settings" tab.



* It is possible to assign a behaviour or event not registered yet. (Except for job selection and sequence selection)

Commands Assigned to Input Ports

Below are the commands that can be assigned to the input ports.
When a signal from an external device is input to one of the ports, the assigned command is executed.

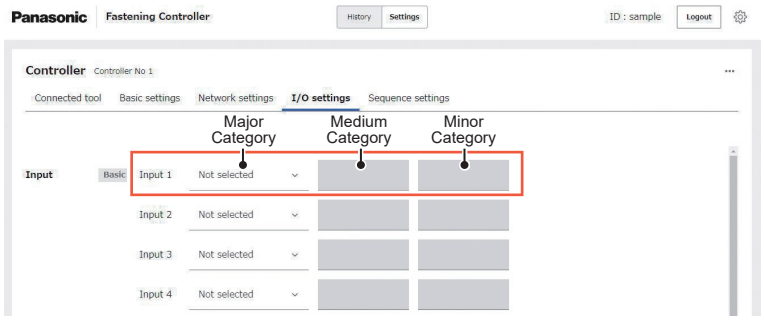
Major Category (Behaviour)	Medium Category (Tool)	Minor Category (Batch No., Etc.)
Batch	Tool 1 to 8	1-5
Job	Tool 1 to 8	1-5
Sequence	—	1-5
Suspend tool*1	Tool 1 to 8	—
Suspend controller*1	—	—
Batch reset	Tool 1 to 8	—
Reset	—	—
Emergency stop*1	Tool 1 to 8	—

*1 Enabled only while the input signal is held.

Notes when the "Suspend tool" or "Suspend controller" command is input

- While "Suspend controller" is active, no fastening order is accepted.
- For the tool number with "Suspend tool" active, no "Batch" or "Job" fastening order is accepted.
- For other tool numbers than that with "Suspend tool" active, a "Batch" or "Job" fastening order is accepted.
- While "Suspend tool" is active, no "Sequence" fastening order is accepted.
  At the time, the process continues until it reaches the tool with "Suspend tool" active.
- "Batch reset" and "Reset" are treated in the same manner as a fastening order.

After selecting a behaviour in the major category, select a tool and then a number (e.g., batch number) as necessary.



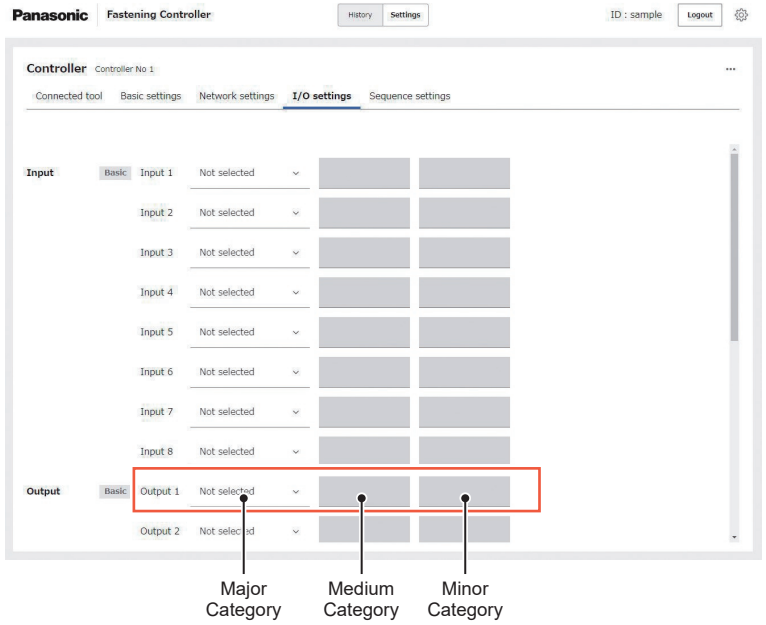
* No action is conducted if an unassigned signal is input. (No error occurs)

Commands Assigned to Output Ports

Below are the commands that can be assigned to the output ports.
When a relevant event has occurred, the controller outputs a signal from the corresponding port to an external device as specified by the assigned command.

Major Category (Event)	Medium Category (Tool)	Minor Category (Batch No., Etc.)
OK	Tool 1 to 8	—
NOK	Tool 1 to 8	—
Batch complete	Tool 1 to 8	1-5
Job complete	Tool 1 to 8	1-5
Sequence complete	—	1-5
Tool active	Tool 1 to 8	—
Batch selected	Tool 1 to 8	1-5
Job selected	Tool 1 to 8	1-5
Sequence selected	—	1-5

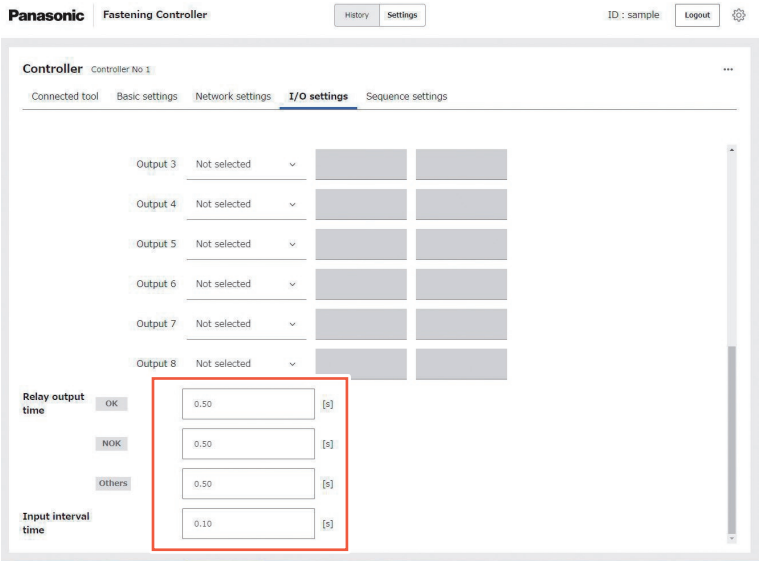
After selecting an event in the major category, select a tool and then a number (e.g., batch number) as necessary.



* If the controller turns off while executing an output command, the process does not resume after the controller turns on. (Note that fastening history data are saved.)

Other Settings

You can set other I/O related settings as below.

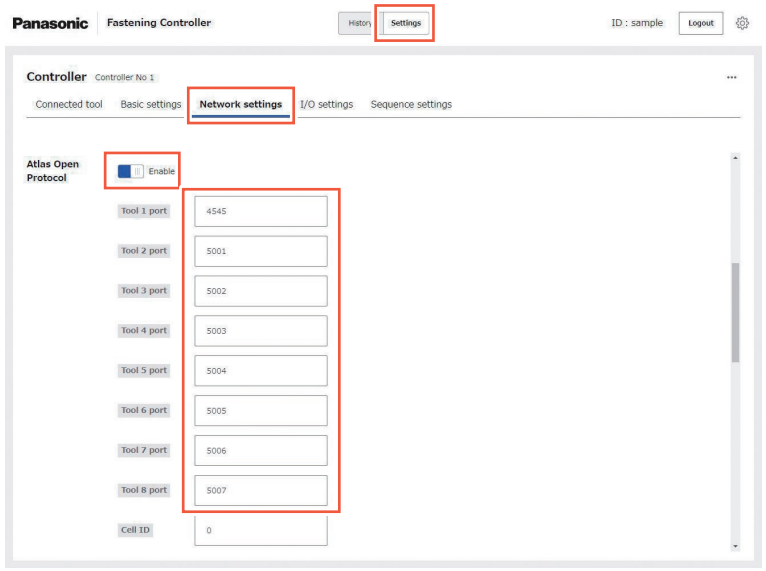


Relay output time (OK)
Select the time length until a fastening completion signal is output by the relay. [Default] 0.5 s [Setting range] 0.01 s to 10 s
Relay output time (NOK)
Select the time length until a fastening failure signal is output by the relay. [Default] 0.5 s [Setting range] 0.01 s to 10 s
Relay output time (Others)
Select the time length until any other signal than fastening completion and failure signals is output by the relay. [Default] 0.5 s [Setting range] 0.01 s to 10 s
Input interval time
Select the time length when the successive input signals are not counted (accepted). Set it to prevent double-counting caused by noise, etc. [Default] 0.1 s [Setting range] 0.01 s to 10 s

Connecting via Open Protocol Communication

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Network settings” tab.

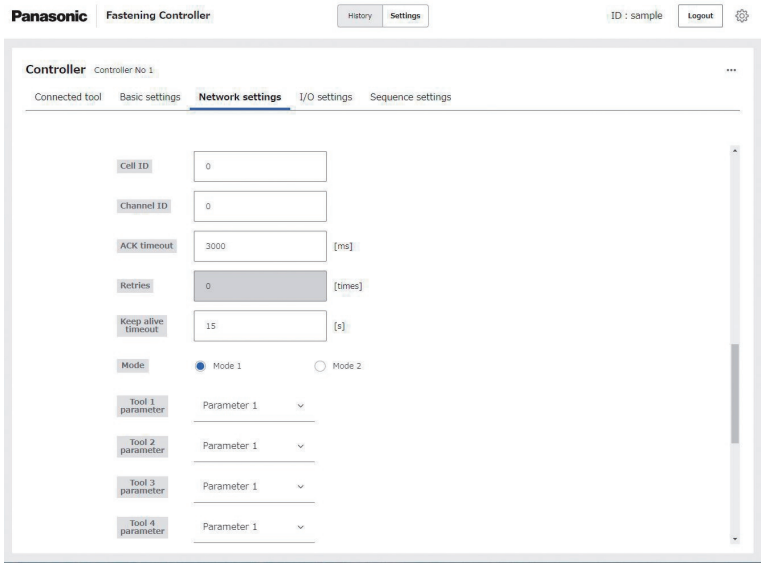
Enable “Atlas Open Protocol”.
Set port numbers to the tools used respectively.



Tool port
Assign a port number for Open Protocol communication to each tool. [Default] Tool 1 - 4545, Tool 2 to 8 - 5001 to 5007 [Setting range] Tool 1 to 8 - 1024 to 49151

Other Settings

Set other items as necessary.



Cell ID

Set the cell ID.
[Default] 0
[Setting range] 0 to 9999

Channel ID

Set the channel ID.
[Default] 0
[Setting range] 0 to 99

ACK timeout

Set the time length to wait for a response to a request message from the controller.
[Default] 3000 ms
[Setting range] 100 ms to 30000 ms

Retries

Set the number of times to repeat sending a request message from the controller.
[Default] 0 times
[Setting range] Not selectable (Fixed)

Keep alive timeout

Set the time length to determine occurrence of disconnection after the last communication with a host system.
[Default] 15 s
[Setting range] 1 s to 60 s

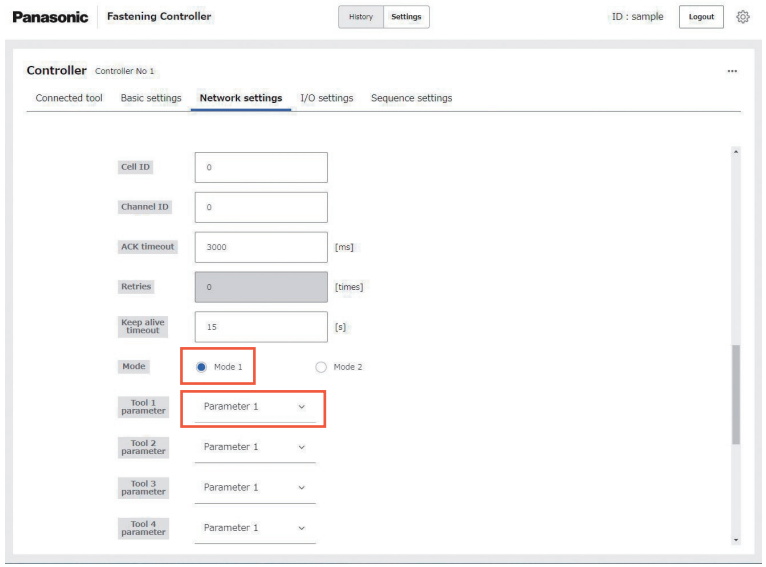
Mode

Set the running mode.
Mode 1: Unconditional fastening with pre-registered parameters
Mode 2: Fastening with parameters ordered by a host system
[Default] Mode 1
[Setting range] Mode 1 / Mode 2

Assigning Fastening Parameters (Mode 1)

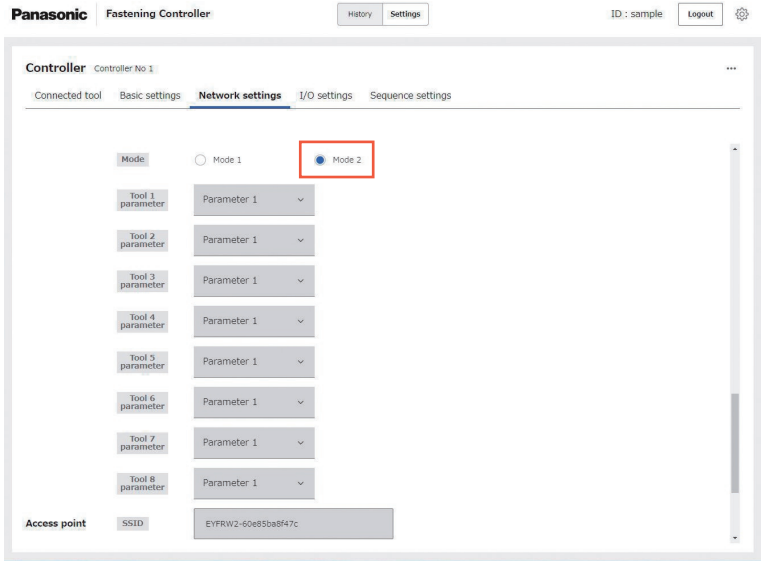
“Mode 1” (without parameters ordered) requires fastening parameters pre-registered to tools.

Select a parameter from the pull-down menu as below.



Assigning Fastening Parameters (Mode 2)

Fastening can be ordered with a MID 0018 command by an external device.
You can specify “Parameter” or “Batch” in a fastening order.



■ To specify “Parameter” in a fastening order

Put “0” in the hundreds digit of ID.
The tens and ones digits show a parameter number.

Example: Parameter 1’s ID: 001
Parameter 5’s ID: 005

■ To specify “Batch” in a fastening order

Put “1” in the hundreds digit of ID.
The tens and ones digits show a batch number.

Example: Batch 1’s ID: 101
Batch 5’s ID: 105

* “Job” and “Sequence” are not supported.

■ Commands compatible with Open Protocol

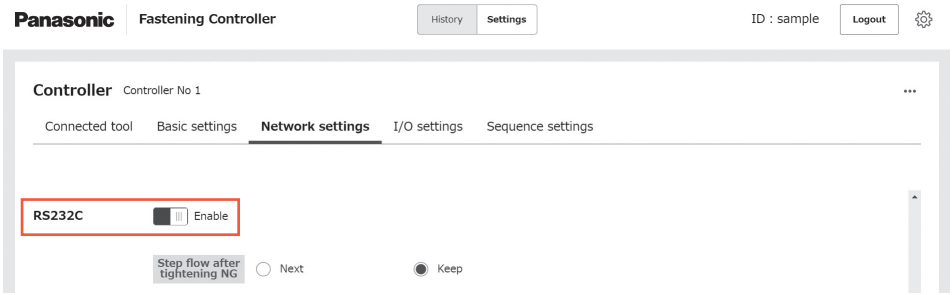
The controller supports the following commands.
For details of commands, see the Open Protocol Specification.

MID 0001 Application communication start
Revision 1 is supported. [Content] Communication start
MID 0002 Application communication start acknowledge
Revision 1 is supported. [Content] Communication acknowledgement
MID 0004 Application command error
Revision 1 is supported. [Content] Command error
MID 0005 Application command accepted
Revision 1 is supported. [Content] Command acceptance
MID 0018 Select parameter set, Dynamic Job included
Revision 1 is supported. For how to assign, see “Assigning Fastening Parameters (Mode 2)”. Refer to P64 [Content] Parameter set order
MID 0042 Disable tool
Revision 1 is supported. [Content] Tool disabled
MID 0043 Enable tool
Revision 1 is supported. [Content] Tool enabled
MID 0050 Vehicle ID number download request
Revision 1 is supported. [Content] Vehicle ID acquisition request

MID 0060 Last tightening result data subscribe
Revision 1 and 2 are supported. [Content] Final fastening result data registration
MID 0061 Last tightening result data
Revision 1 and 2 are supported. [Content] Fastening result upload
MID 0062 Last tightening result data acknowledge
Revision 1 and 2 are supported. [Content] Fastening result upload acknowledgement
MID 9999 Keep alive message
Revision 1 is supported. [Content] Availability check

Connecting to External Devices with TOYOTA MOTOR CORPORATION-Specific Specifications

Control from external devices is supported.
Enable “RS232C” from the “Network settings” tab in [Settings].

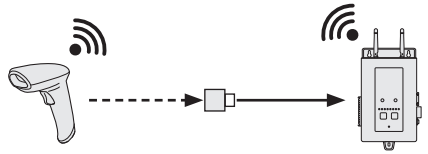


RS232C
This is a setting specific to TOYOTA MOTOR CORPORATION. Control from external devices is possible. [Default] Disable [Setting range] Disable / Enable
Step flow after tightening NG
This setting determines whether you can proceed to the next tightening in case of a tightening NG result. [Default] Keep [Setting range] Next (The next tightening can be performed.) / Keep (The next tightening cannot be performed.)

This is only supported by the firmware version 2.03.00 or later.
For how to update the firmware, see “Updating the Firmware”.
Refer to P95

Setup

You can connect a commercially available barcode reader to save read information while linking it to the fastening history data.
This can be used to link products to the fastening history.

Connection	Communication method	Note
	Wireless 2.4 GHz or Bluetooth	• Reads product information (such as manufacturing serial numbers) and reflects it in the history data.

Do not use wired USB-type barcode readers.

Applicable Devices

The following barcode readers are compatible with the controller.

Item	Description
Communication interface	USB-HID
Keyboard layout	US
Supported characters	Half-width alphanumeric characters, symbols

Supported codes	Code description (Anticipated information)
Half-width numbers	0-9
Half-width alphabetic characters	A-Z, a-z
Symbols	!"#$%&'()*+,-./:;<=>?@[¥]^_`{|}~

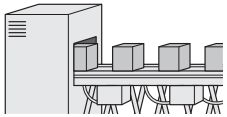
Acceptable 1D codes	JAN, EAN, UPC, CODE39, ITF
Acceptable 2D codes	QR Code Model 1/2, Micro QR
Acceptable number of characters	100 characters (maximum)

Recommended models
Bluetooth: Honeywell Xenon XP 1952g, ZEBRA DS2278

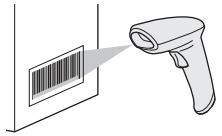
Work Process Flow

By following the procedure below, you can save product information while linking it to the fastening history data.

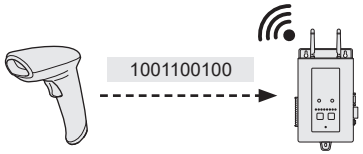
1 **Products flow through the line.**



2 **Read product information with a barcode reader.**

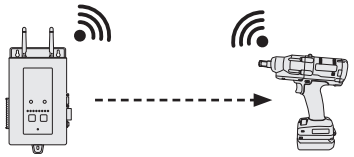


3 **The information read by the barcode reader is sent to the controller.**

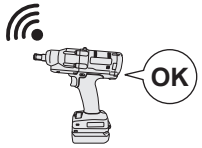


4 **A fastening order is sent from the controller to the tools.**

* This step may come before or after step 3.



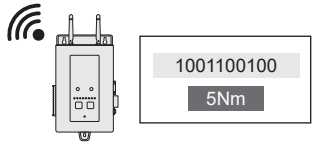
5 **Perform fastening work using the tools.**



6 **The fastening work result (such as torque) is sent to the controller.**



7 **The read information retained in the controller and the fastening work result are linked to each other and saved to the storage.**



8 **Repeat steps 5 to 7 until the barcode reading information is updated (or the work is completed).**

Setting Procedure

The setting procedure varies depending on the specifications of the barcode reader.

■ Wireless 2.4 GHz method (with dedicated wireless receiver)

Connect it following the procedure below.
(Steps 2 to 3 are not required.)

■ Bluetooth method (without dedicated wireless receiver)

Prepare a Bluetooth wireless receiver separately and connect it following the procedure below.

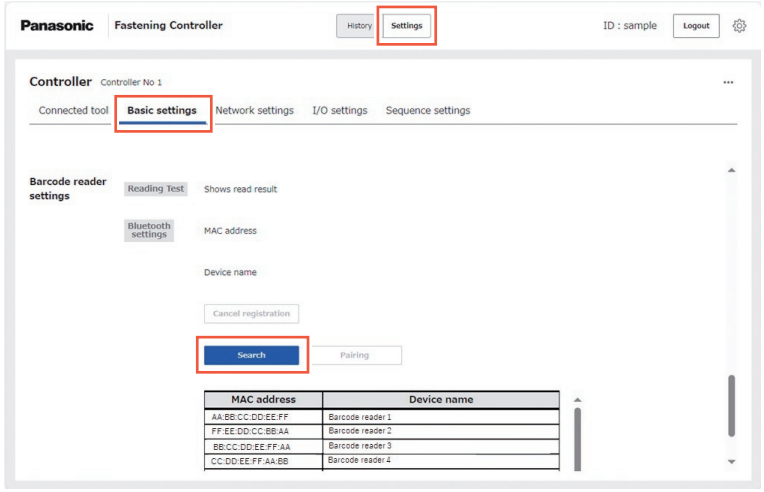
Available Bluetooth wireless receivers
- Bluetooth version: Compatible with Ver4.0
- Compatible with Linux OS (only those that do not require dedicated drivers)

Recommended models
EDIMAX BT-8500

1 **Connect the wireless receiver of the barcode reader to the USB-A port of the controller.**

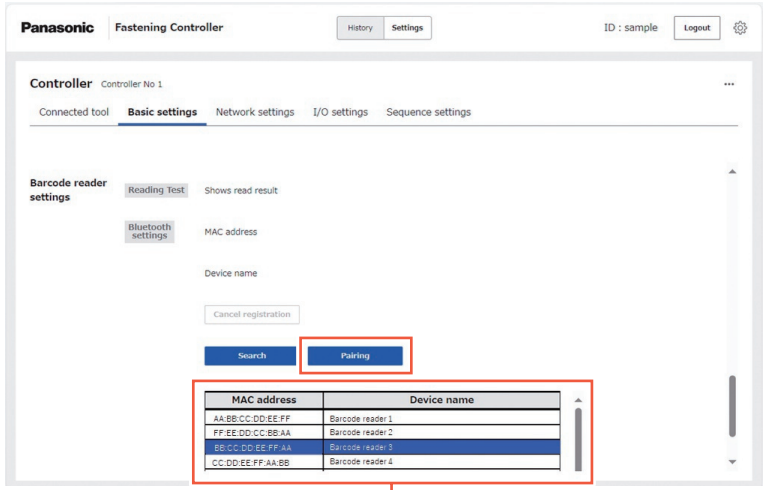
2 **In the top page (the initial page of the setting screen), click [Settings] on the top, select the “Basic settings” tab, and click “Search” from “Barcode reader settings”.**

* Put also the barcode reader in pairing mode according to its specifications.



3 Select the barcode reader to connect from the device name list and press “Pairing”.

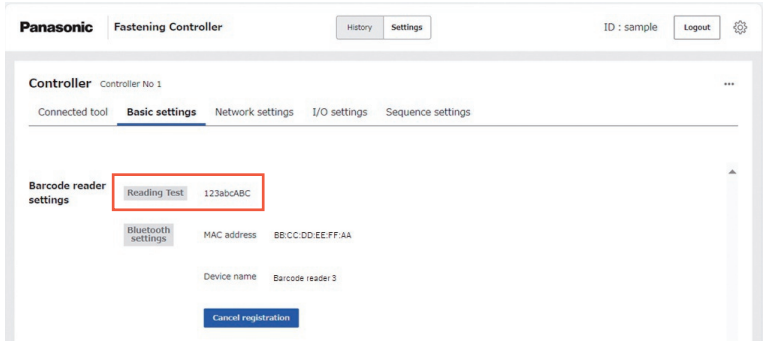
It will be paired with the barcode reader.



Device name list

- The search state is kept for about 10 seconds.
- Once pairing is registered, it will be reconnected automatically the second and subsequent times.
  * Depending on the specifications of the barcode reader, pairing may be required again.
  * If pairing fails, cancel pairing on the controller and then try again.

4 Read barcode information and check that the information is displayed correctly in “Reading Test”.

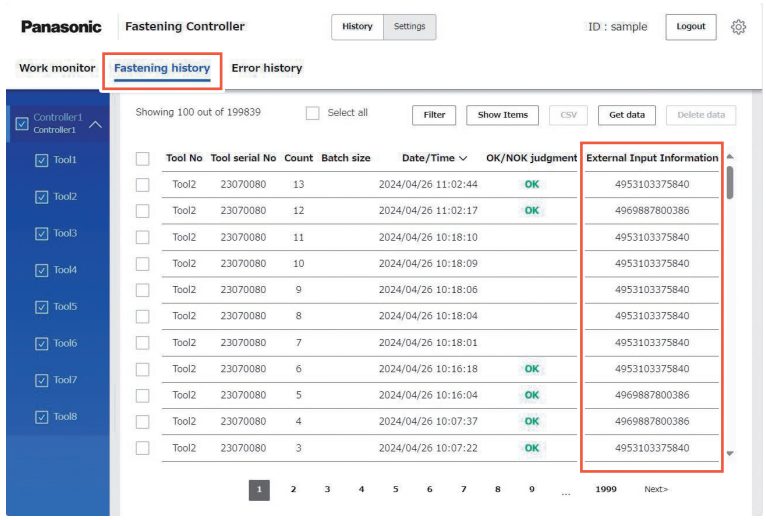


5 Perform fastening work with the barcode reader having read the information.

The read data will be displayed in “External Input Information” of the fastening history data.

Notes during operation

- The “Fastening OK lamp” will blink in the barcode reading reception state. During operation, check that the barcode reading reception state is active before work.



Notes on Read Values

The read values are:

- Reflected in the work results of all tools recorded by the controller after reading.
- Not retained when the controller is OFF.
- Overwritten by newly read information.
- Retained until the following conditions are met.

Running mode	Data Retention Conditions
Free mode	Data is retained until updated.
Repeat mode (Basic mode)	Until “Batch”/“Job” completion. Or data is retained until updated.
Repeat mode (Sequence mode)	Until “Sequence” completion. Or data is retained until updated.
External control mode * Control via Open Protocol	VIN information takes priority, and they are not added.
External control mode * Control via I/O	Until “Batch”/“Job”/“Sequence” completion. Or data is retained until updated.

- Depending on the device specifications of the barcode reader you are using, detailed settings may be required for connection with the controller. Before using this function, carefully read the Operating Instructions and settings of your device.
- If data is read continuously within 0.5 seconds, the information will be consolidated; therefore, space out the readings.
- Only one barcode reader can be operated simultaneously with the controller. Connecting multiple readers may result in a malfunction.

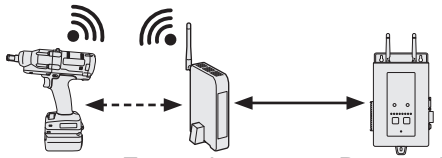
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The various names, company names and product names presented in this manual are the trademarks or registered trademarks of their respective companies. Please note that some TM or ® symbols are omitted in this document.

Setup

The controller can connect to tools via wireless communication using an external access point instead of the built-in access point.
The controller can control tools wherever it is installed.
Connect the access point and the controller to wired LAN.
* The wireless coverage and performance change depending on the access point used.

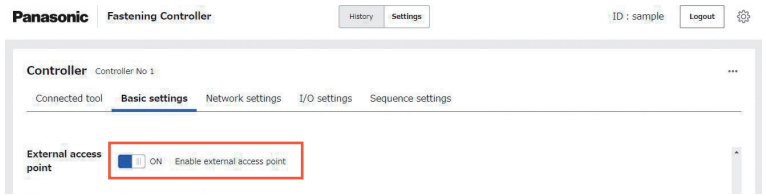
Connection	Communication Method	Note
	Ethernet	• In the mode selection, select the internal access point or external access point. • Maximum number of connected tools: 8 * For both the internal access point or external access point

* Setting “Tool IP” to “Auto (DHCP)” allows the network configuration without managing the tool’s IP address. Refer to P13

Setting Procedure

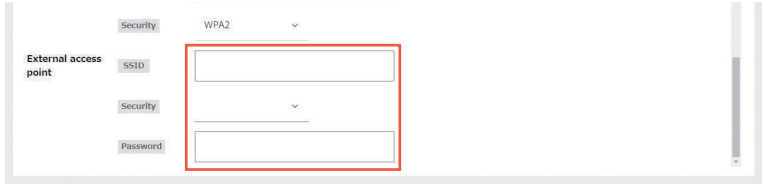
1 In the top page (the initial page of the setting screen), click [Settings] on the top, select the “Basic settings” tab, and set “External access point” to “ON”.

* “WLAN mode” is disabled when “External access point” is enabled.



2 In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Network settings” tab. In “External access point”, set “SSID”, “Security”, and “Password”.

* You can register only one SSID in the controller. (You cannot register different SSIDs for different tools)
* See the Operating Instructions of your external access point.
* Make this setting before starting pairing registration with tools.
* Set the tool’s IP address before starting pairing registration.



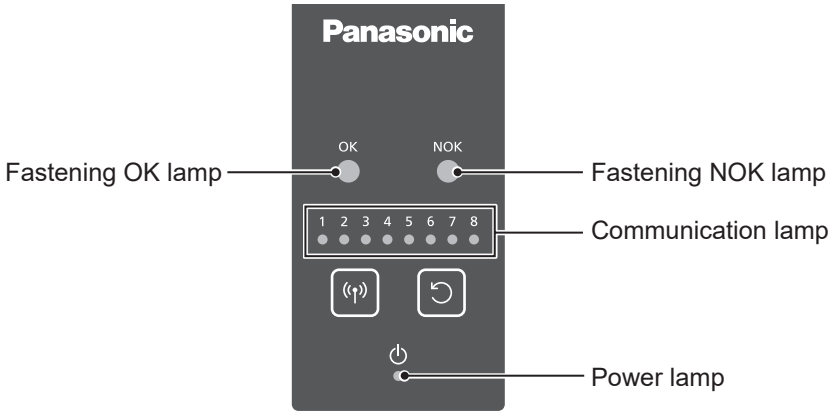
OPERATION

Indicator Lamps and a Buzzer

The indicator lamps and buzzer show the controller's status.

⚠ CAUTION

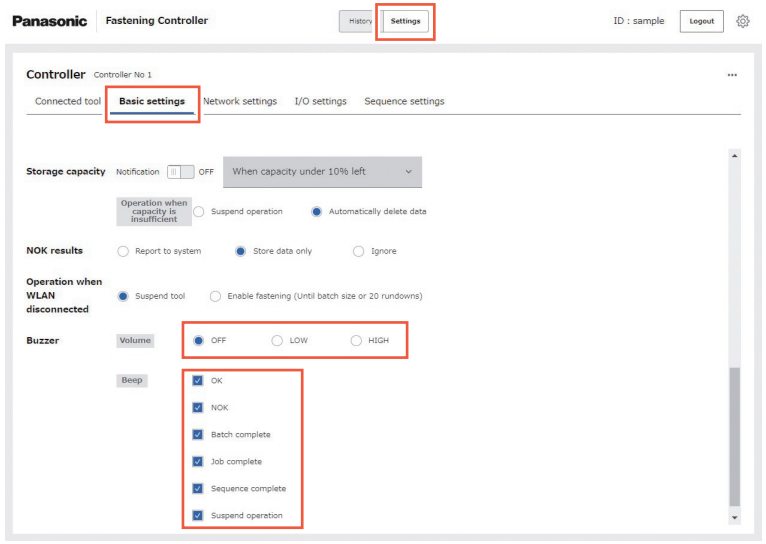
Do not turn off the power switch while the lamp is blinking startup.
Initialization may be required.



Status	Indicator Lamp	Buzzer
Power on	Power lamp (yellow) Stays lit	–
A tool to pair selected	Communication lamp (blue) Blinks slowly	–
Pairing established	Communication lamp (blue) Blinks rapidly	–
Pairing completed	Communication lamp (blue) Stays lit	A short beep ■
Pairing not established	Communication lamp (blue) Blinks very slowly	–
Pairing disconnected	Communication lamp (blue) Off	–
Fastening completion	OK lamp (green) Stays lit	A short beep ■
Fastening failure	NOK lamp (red) Stays lit	A long beep ▬
Batch/job completion	OK lamp (green) Blinks twice	Two short beeps ■ ■
Sequence complete	OK lamp (green) Blinks three times	Three short beeps ■ ■ ■
Error	Power lamp (yellow) Blinks	Two long beeps ▬ ▬

Buzzer Setting

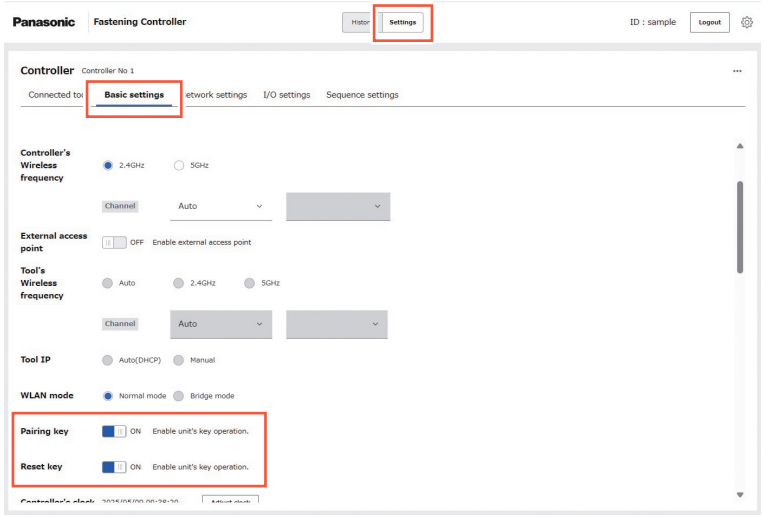
In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Basic settings" tab.
In "Buzzer", set "Volume" and "Beep".



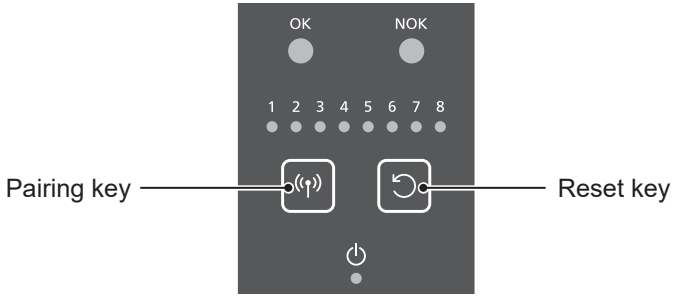
Item	Description
Volume	3 levels (OFF/LOW/HIGH) (LOW: 75 dB, HIGH: 85 dB)
Beep	Selected on the PC for configuration (OK / NOK / Batch complete / Job complete / Sequence complete / Suspend operation)

SETTING THE OPERATION KEYS

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.
In “Pairing key” and “Reset key”, you can disable the Pairing key and Reset key on the control panel.

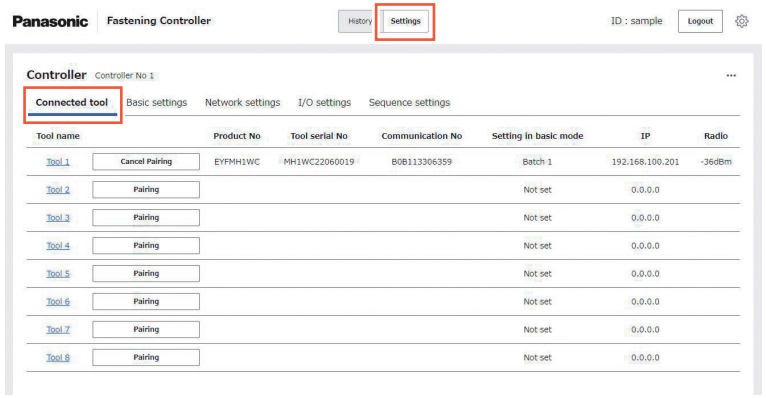


Pairing key
Enable or disable the Pairing key on the control panel. [Default] ON [Setting range] ON (enabled) / OFF (disabled)
Reset key
Enable or disable the Reset key on the control panel. [Default] ON [Setting range] ON (enabled) / OFF (disabled)



CHECKING THE INFORMATION OF CONNECTED TOOLS

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.
You can see the information and status of the tools connected to the controller.



Below are the displayed items.

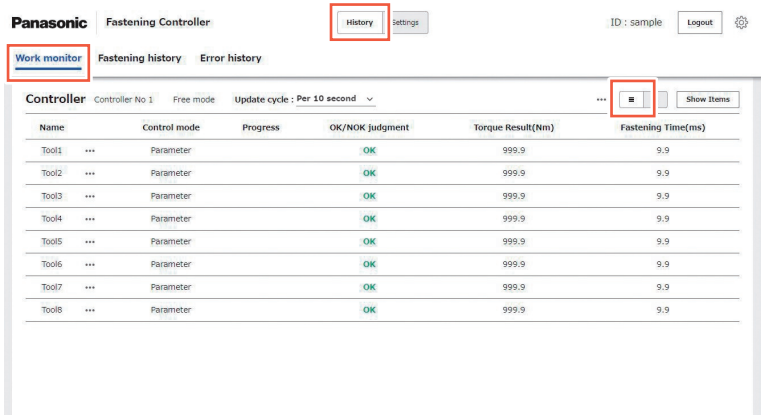
Tool name
The registered tool number (1 to 8) is displayed.
Tool serial No
You can set and display the tool’s unit identification. Default: 5-digit model ID + 8-digit serial number (2-digit manufacturing year + 2-digit month + 4-digit production lot)
Product No
The tool product number is displayed.
Communication No
Unit identification (MAC address) of the tool’s communication part is displayed.
Setting in basic mode
A behaviour when the Running mode is set to “Repeat mode (Basic mode)” is displayed.
IP
The IP address of the tool is displayed.
Radio
Strength of a radio signal (RSSI) received from the tool is displayed. * Strength at the last communication is displayed. * It cannot be measured and “0dBm” appears when an external access point is used.

In the top page (the initial page of the setting screen), click [History] on the top and select the “Work monitor” tab.
The latest fastening history logs by tool are displayed. You can use them to work by referring to the work results.
* More than one PCs for configuration can display them at the same time. (Up to 8 accesses. Multiple accesses from the same account are accepted.)
* To log in with more than one account, using different PCs is recommended.
* To use more than one account on the same PC, using different web browsers is recommended.
* Only one access to the configuration function is accepted at a time.

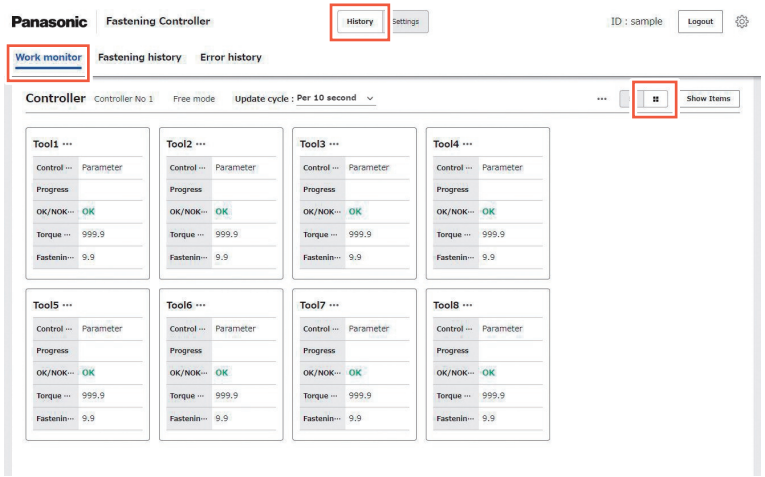
Switching the View Format

You can select between “List view” and “Grid view”.
Use the view icon on the upper right of the screen.

■ List view

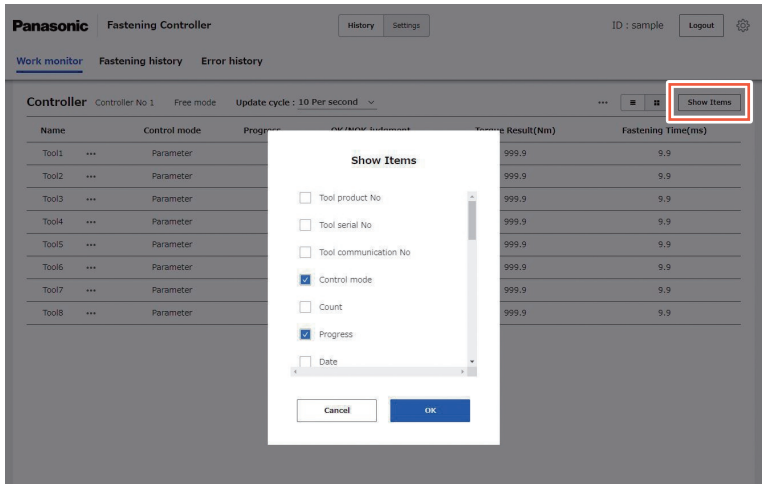


■ Grid view



Selecting Items to Show

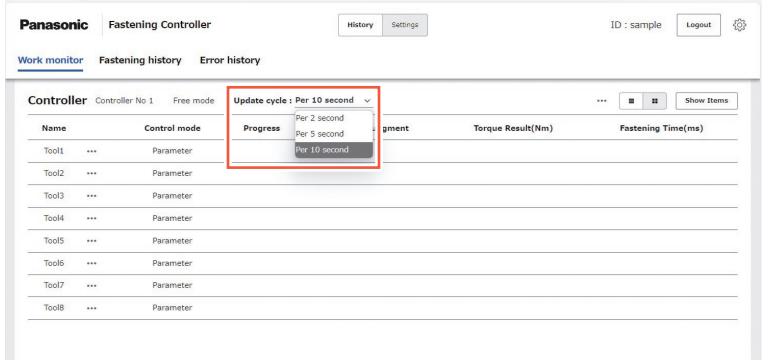
Select items to show using “Show Items”.



* In “List view”, you can scroll down and select many items to show.
* In “Grid view”, you can show up to 5 items.

Selecting the Display Update Cycle

You can set automatic display update.
Select the update cycle from “Per 2 second”, “Per 5 second”, and “Per 10 second” as below.



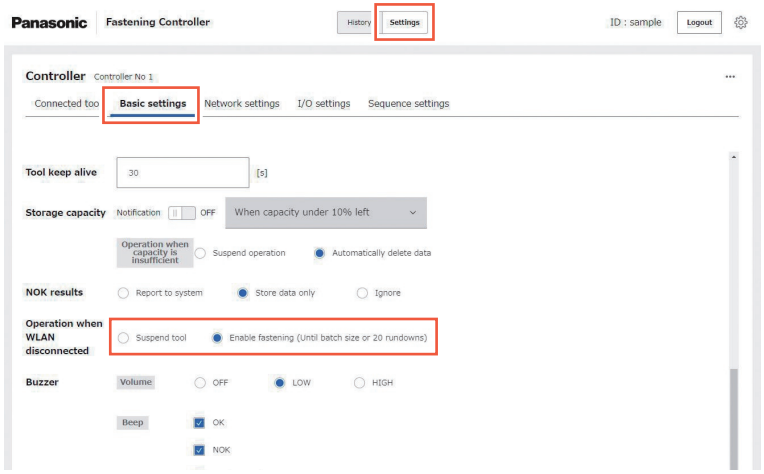
* If a large number of tools or PCs for configuration are connected, the update cycle of “Per 10 second” is recommended. (It may take some time to process data.)

TOOLS' BEHAVIOUR WITH WIRELESS COMMUNICATION DISCONNECTED

You can continue the fastening with the same parameters in case of temporary disruption of wireless communication between a tool and the controller.
The work results of tools during wireless communication disconnection are notified to the controller "When the tool gets reconnected" or "At the first fastening after the tool's connection recovered".



In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Basic settings" tab.
If you set "Operation when WLAN disconnected" to "Suspend tool", the ongoing fastening is completed after disruption but no further fastening is conducted.
If you set "Enable fastening", no further fastening is conducted after the fastened quantity has reached the upper limit.



With "Enable fastening", the upper limit quantities by mode are as below.

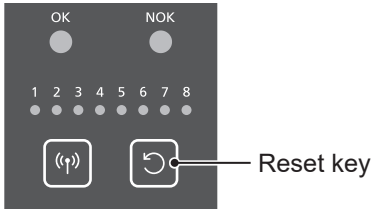
Mode		Behaviour
Free mode		Continues fastening up to 20 screws
Repeat mode	Basic mode	Continues fastening up to the end of the batch or up to 20 screws
	Sequence mode	Continues fastening up to the end of the batch or up to 20 screws * Tools other than the one concerned continue to run normally.
External control mode		Continues fastening up to the end of the batch or up to 20 screws

RESETTING THE COUNT DURING OPERATION

To change settings, stop fastening control by the controller if it is ongoing. A confirmation dialogue appears when you apply the change.
You can reset the counted quantities by "Using the key on the unit" or "Setting in the setting screen".
* This does not apply to "Free mode".

Using the key on the unit

Hold down the Reset key on the controller 3 seconds or more.
* The quantities of all active tools are reset.

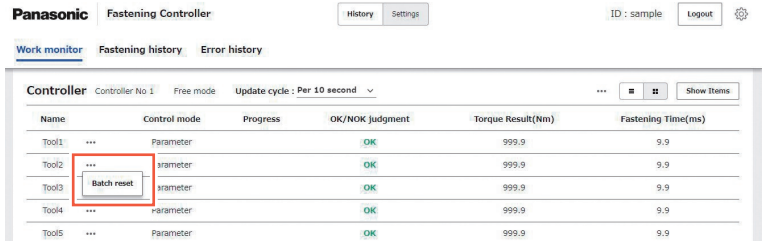


Setting in the setting screen

In the top page (the initial page of the setting screen), click [History] on the top and select the "Work monitor" tab.

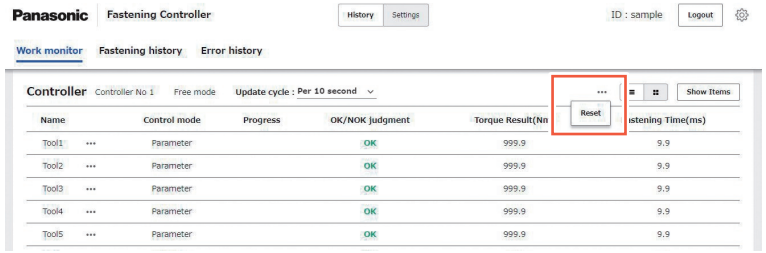
■ To reset the quantities by tool

In the "Work monitor" screen, click ··· (tool option key) and then [Batch reset] of the desired tool number.



■ To reset the quantities of all tools collectively

In the "Work monitor" screen, click ··· (controller option key) and then [Reset] on the upper right.



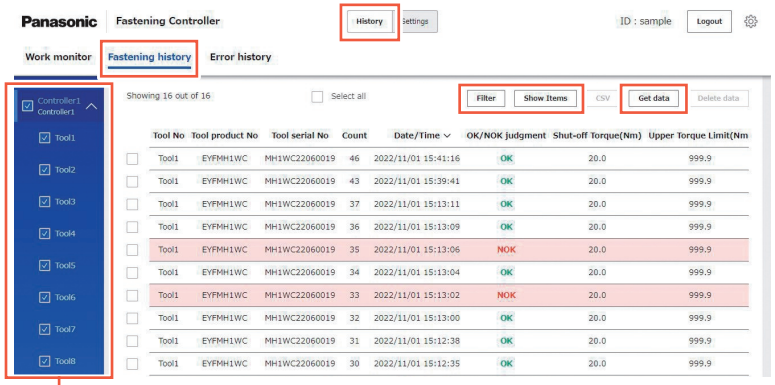
* In the Sequence mode, the quantities are reset up to the first tool.

Displaying the Fastening History Data

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
You can view the fastening history data sent from tools to the controller.

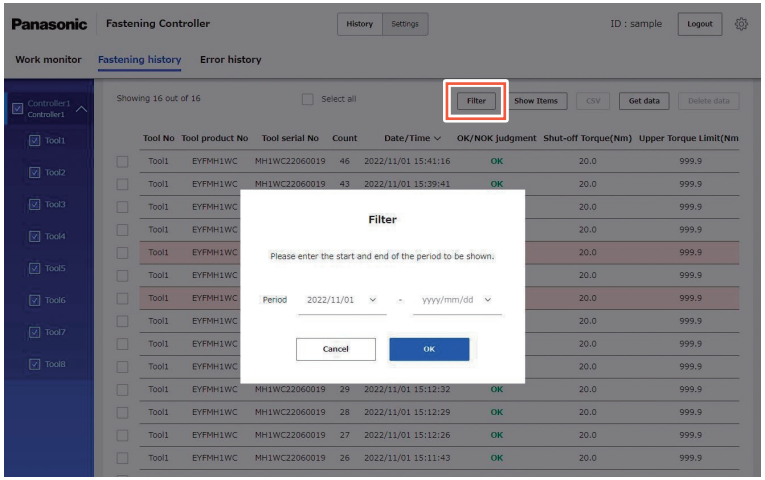
To display the data, select the desired controller and tools from the tool list on the left and click [Get data] on the upper right.
The fastening history logs are displayed from newest to oldest.

* For the content of fastening history items, see the tool’s Operating Instructions.



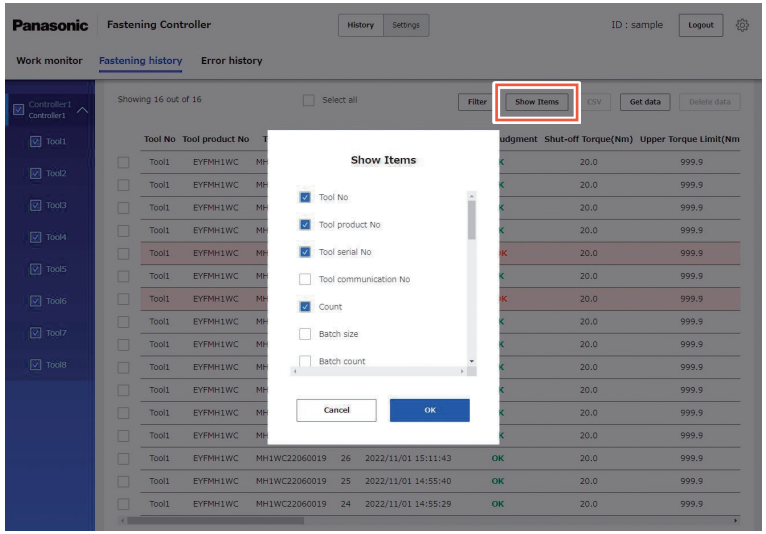
Extracting the fastening history logs by time period

Click [Filter] and specify the time period to narrow down the fastening history logs to display.



Setting Items to Display

To change the displayed items, click [Show Items] and select the desired items.



Capacity for Fastening History Data

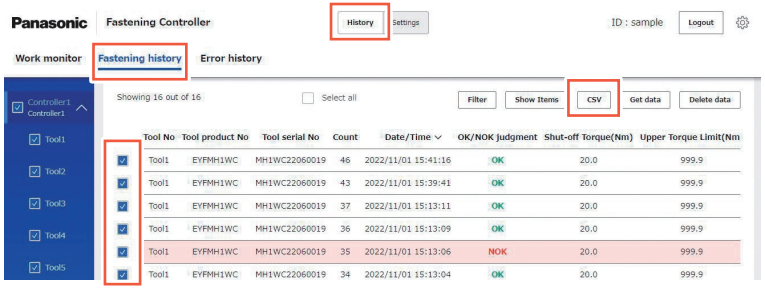
The controller can store a maximum of about 200,000 fastening history logs (including waveform data).
It suspends operation or automatically deletes the logs (by overwriting) if it receives more logs.
It is recommended that you periodically export the logs in the CSV format as necessary by referring to the guide below.

Estimated time to reach full storage capacity

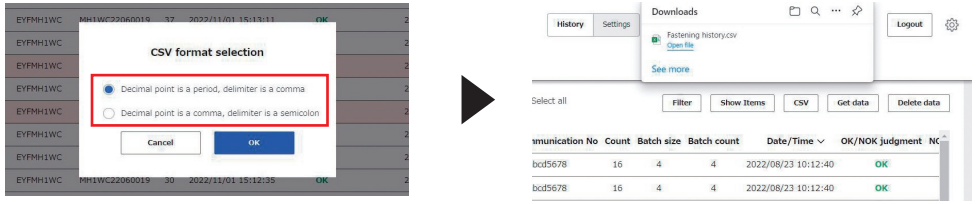
	Quantity per Day per Tool		
Number of Tools	1,000	3,000	5,000
2	About 100 days	About 33 days	About 20 days
4	About 50 days	About 16 days	About 10 days
8	About 25 days	About 8 days	About 5 days

Exporting the Fastening History Data in the CSV Format

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
Select the desired logs and click [CSV].
The fastening history logs are exported in the CSV format.
The exported data includes all items of each tool regardless of the “Show Items” setting.

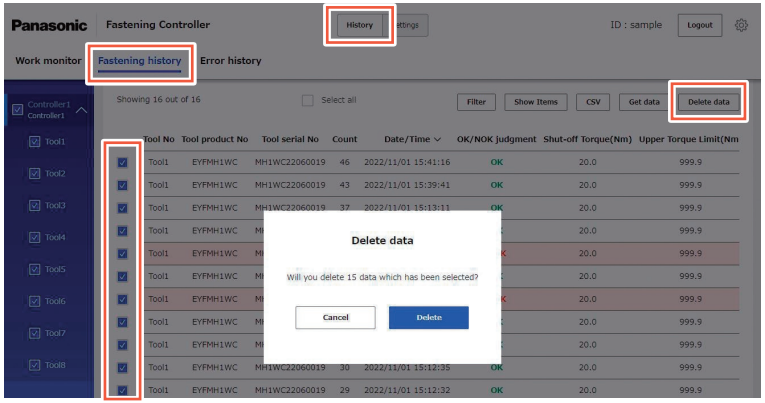


You can select between “Decimal point is a period, delimiter is a comma” and “Decimal point is a comma, delimiter is a semicolon”.



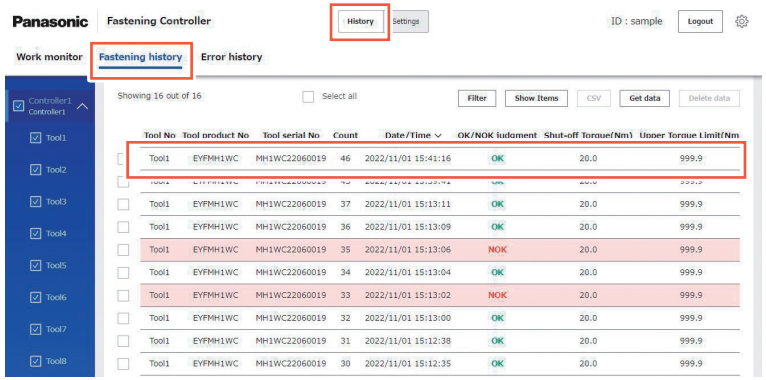
Deleting the Fastening History Data

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
Select the desired logs and click [Delete data].
The fastening history logs are deleted.

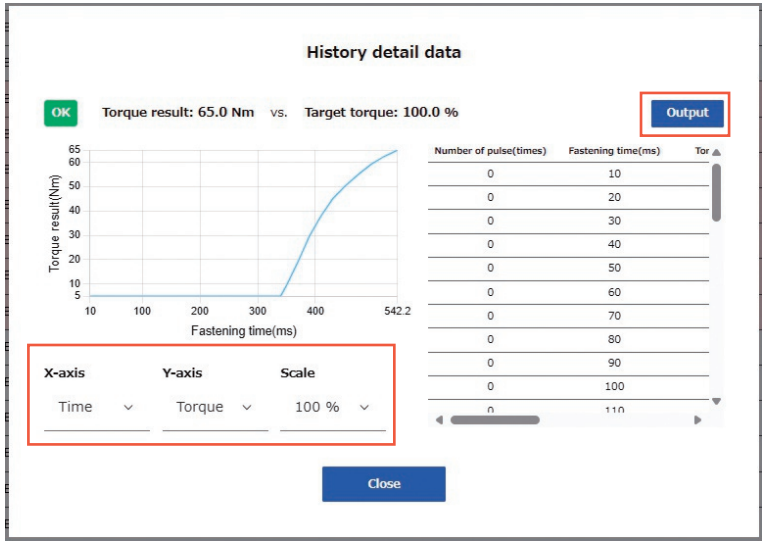


Displaying the Waveform Data

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
If you have enabled to save waveform data, you can click on the row of the desired fastening history log to display a waveform data popup window.



You can adjust the display by selecting “X-axis”, “Y-axis”, and “Scale”.
Clicking [Output] exports the data in the CSV format.

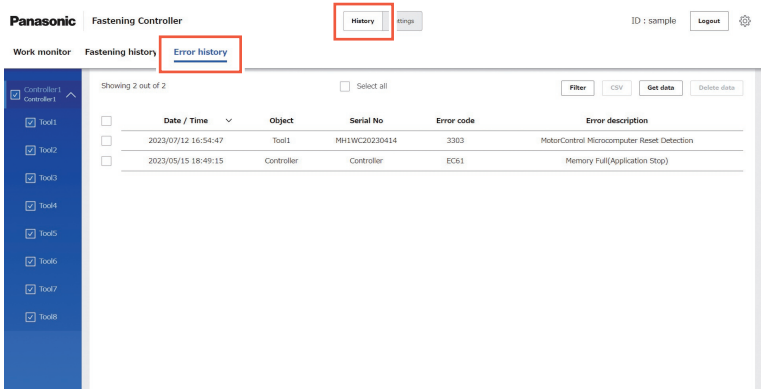


* Please set “Graph sending timing” in “Device settings” to “After every fastening”.

OPERATION

Displaying the Error History

In the top page (the initial page of the setting screen), click [History] on the top and select the “Error history” tab.
The history of errors that occurred is displayed.



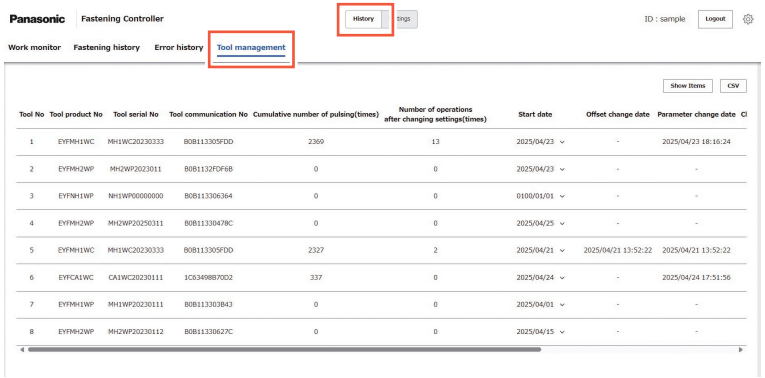
Below are the displayed items.
* For the error content, see “ERROR CODE”. Refer to P104

Date / Time
The date and time of error occurrence are displayed.
Object
The device (the controller or any of Tool 1 to 8) causing an error is displayed.
Serial No
The serial number of the device (the controller or any of Tool 1 to 8) causing an error is displayed.
Error code
An error code that occurred is displayed.
Error description
Content of an error that occurred is displayed.

Viewing Management Items

In the top page (the initial page of the setting screen), click [History] on the top and select the “Tool management” tab.

You can view the management items for each “Tool No.”



Below are the displayed items.

The latest information can be checked on the screen.

Each item is displayed based on the tool’s work result data.

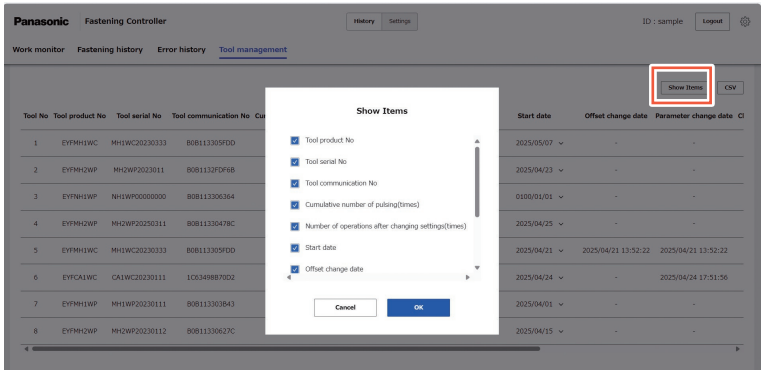
Note that all information will be cleared when the tool is replaced or a new tool is paired.
* Information is not cleared when the controller - tool pairing is cancelled.

Tool product No
Displays the product number of the paired tool.
Tool serial No
Displays the individual identification information of the tool.
Tool communication No
Unit identification (MAC address) of the tool’s communication part is displayed.
Cumulative number of pulsing (times)
Displays the cumulative number of pulsing operations performed by the tool.
Number of operations after changing settings (times)
Displays the cumulative number of operations after changing the tool settings.

Start date
Sets the start date for using the tool. The settings can only be done using an administrator account. [Set value] 0100/01/01 to 9999/12/31
Offset change date
Displays the date and time when the tool settings, including “Offset” “Slope” or “Offset” “Intercept”, were changed.
Parameter change date
Displays the date and time when the tool settings were changed.
Changed parameter No
Displays the changed parameter number. It will also be displayed in this field if “Device settings” are changed.
Cumulative fastening time (h)
Displays the accumulated working time of the tool.
Cumulative pulsing time (h)
Displays the accumulated working time involving tool pulsing.

■ Setting Items to Display

To change the displayed items, click [Show Items] and select the desired items.



Configure the Date of Starting Use of the Tool

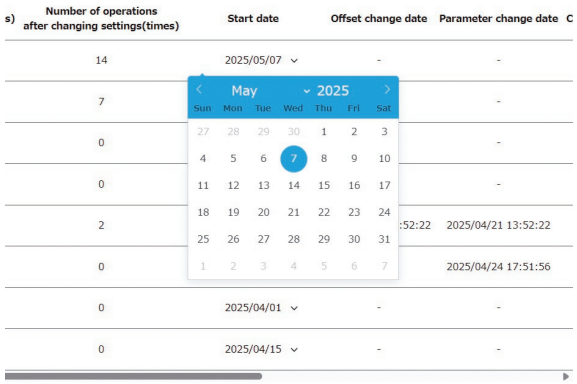
* This operation can only be performed with an administrator account. Refer to P21

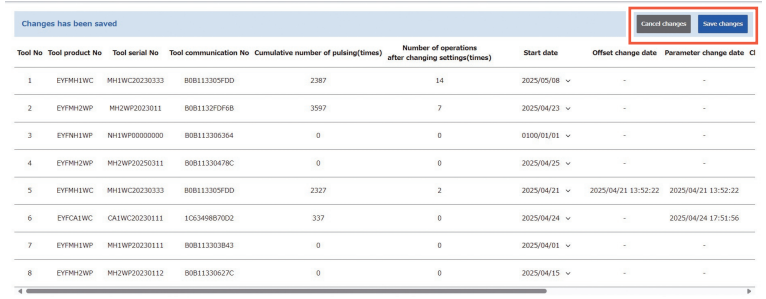
In the top page (the initial page of the setting screen), click [History] on the top and select the “Tool management” tab.

Click the “Start date” item for each tool.
The start date of use can be set from the calendar-style UI.

After selecting the start date, click “Save changes” to confirm the changes.
Before confirmation, you can modify the “Start date” or change the “Start date” of other tools.

Clicking “Cancel changes” allows it to revert to the previous state.



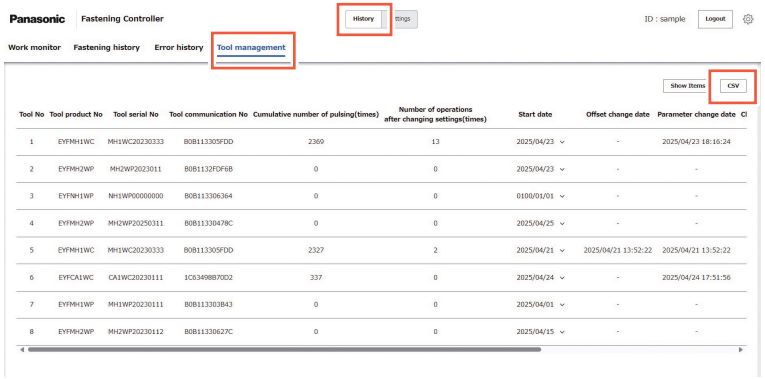


Export Tool Management Data in CSV Format

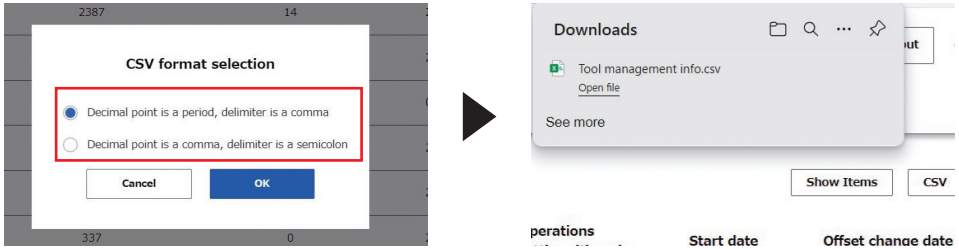
In the top page (the initial page of the setting screen), click [History] on the top and select the “Tool management” tab.

Click “CSV”.
The data displayed on the screen will be exported in CSV format.

The exported data includes all items of each tool regardless of the “Show Items” setting.



The CSV format can be selected from “Decimal point is a period, delimiter is a comma” or “Decimal point is a comma, delimiter is a semicolon”.

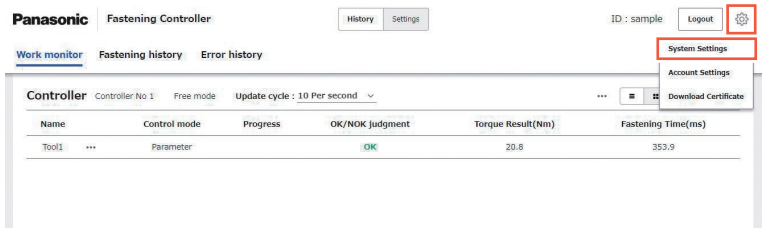


Changing the Language

You can select “Japanese” or “English”.

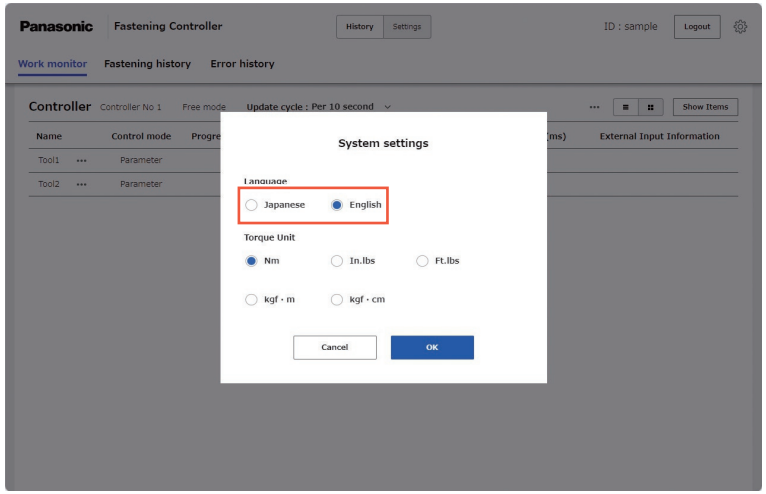
1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “System Settings”.

The “System settings” screen is displayed.



2 Select the language in the “System settings” screen.

You can select “Japanese” or “English”.

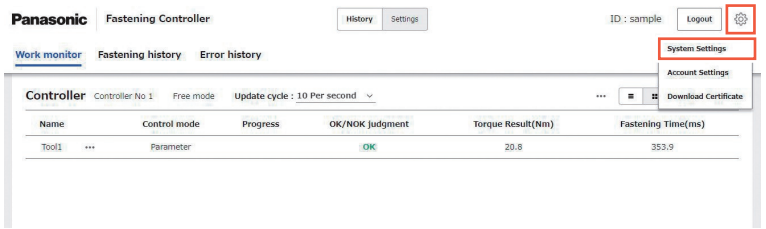


Changing the Torque Unit to Display

You can select “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, or “kgf·cm”.

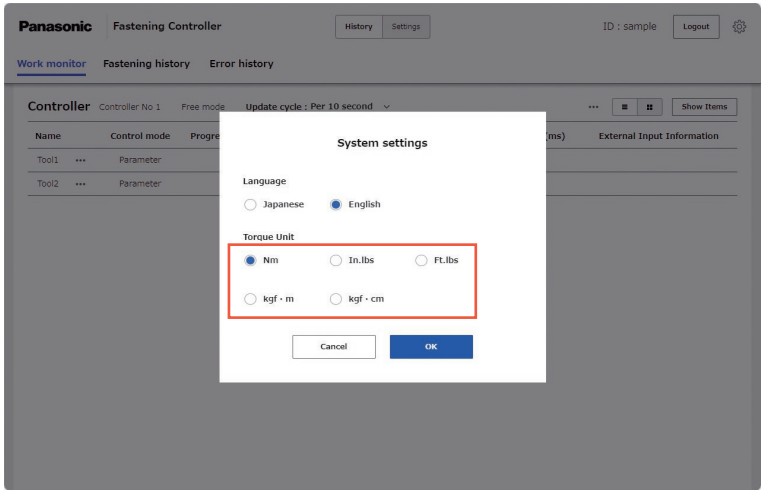
1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “System Settings”.

The “System settings” screen is displayed.



2 Select the torque unit in the “System settings” screen.

You can select the torque unit from “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, and “kgf·cm”.



* Some unit displays may experience numerical corrections.

How to Clean

Wiping with Soft Cloth

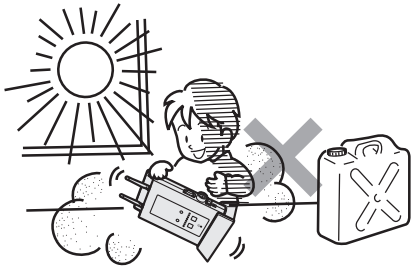
Do not use wet cloth, thinner, alcohol, benzine, or other volatile liquids.
(Cause of discoloration, deformation, or crack)



How to Store

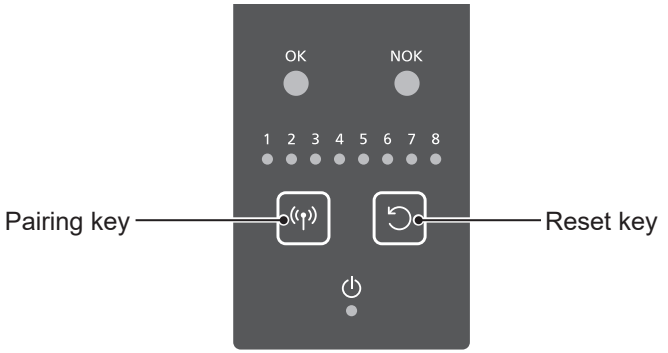
Avoid the following conditions during storage.

- Car cabin or other hot places
- Places exposed to direct sunlight
- Places exposed to water or dampness
- Places with a lot of foreign bodies or dust
- Places within reach of children
- Places with gasoline or other flammables
- Places with risk of fall



Initialising the Controller

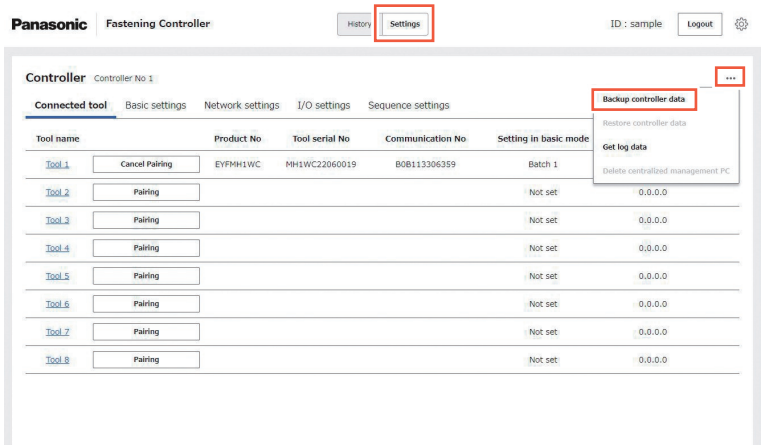
To initialise (factory-reset) the controller, hold down the Pairing key and Reset key together 10 seconds or more.



* It may take more than 5 minutes depending on the storage usage.
* You cannot conduct it when the keys on the unit are disabled. Refer to P76

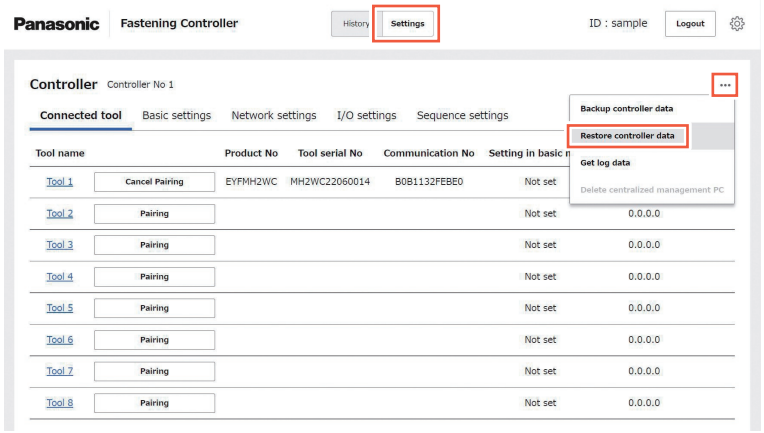
Making a Backup of the Settings

In the top page (the initial page of the setting screen), click [Settings] on the top.
Click ··· (controller option key) and then [Backup controller data].
You can back up the settings of the controller and tools.
* The fastening history data are not backed up. Export them in the CSV format as necessary.



Restoring the Settings

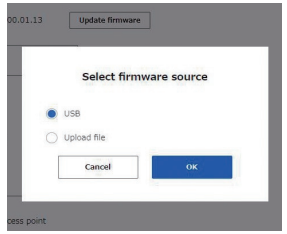
In the top page (the initial page of the setting screen), click [Settings] on the top.
Click ··· (controller option key) and then [Restore controller data].
You can restore the settings of the controller and tools from their backup.
* You cannot conduct it during fastening control.
* You cannot conduct it when pairing with tools is registered. Cancel the pairing.



Updating the Firmware

You can update the firmware of the controller and the tool's communication part.

Use either of the following to update the firmware.



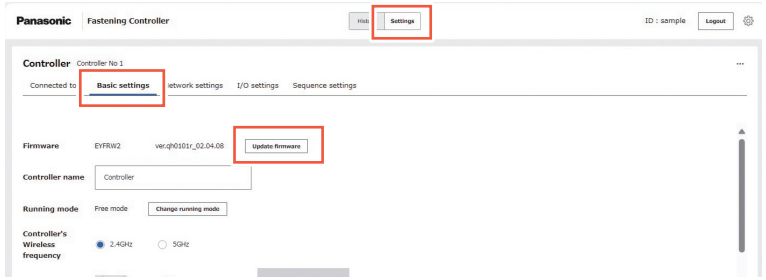
① Using the USB port of the controller.
  * A USB flash drive with a password lock cannot be used.
  * Save only one firmware data file directly in a USB flash drive without creating a folder.

② Writing from the PC for configuration.
  * When selecting "Upload file", select the firmware data file saved on the PC in the selection screen.

For the current firmware version, access our web site. Refer to P2
Or contact our sales person.

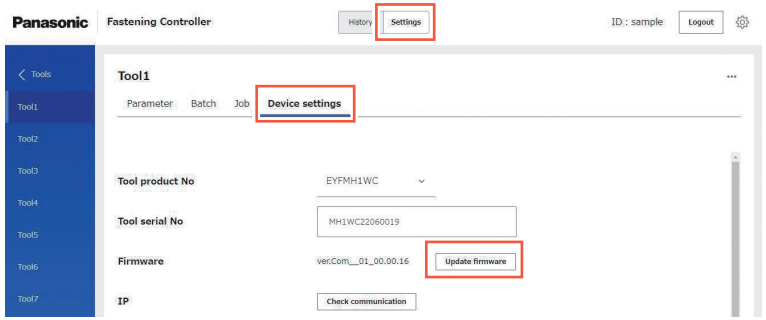
■ For the controller

In the top page (the initial page of the setting screen), click [Settings] on the top, select the "Basic settings" tab, and click [Update firmware].



■ For the tool's communication part

In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Connected tool" tab.
In the "Connected tool" screen, click the desired tool number.
From the "Device settings" tab in the screen for the tool number, click [Update firmware].



Replacing the Coin Cell Battery

To keep the clock (RTC) of the controller running, replace the coin cell battery by referring to the replacement guide below.

■ Battery type



CR2450

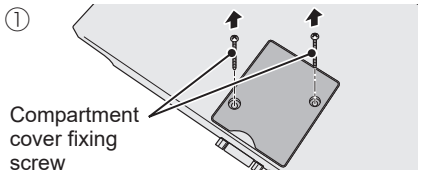
■ Replacement guide

The coin cell battery is used to keep the clock running when the controller is off.
To minimise its consumption, in principle, do not turn the controlled off.

Power is on 12 hours per day (business days only)	Power is always on
About 3 years	About 8 years

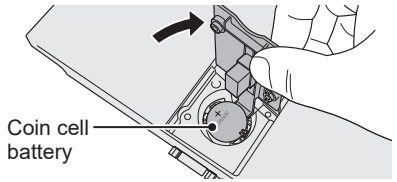
Replace it with the following procedure or contact your dealer.
It is recommended that a person who has electrical knowledge should do the work.

1 Remove the 2 compartment cover fixing screws and then remove the compartment cover.

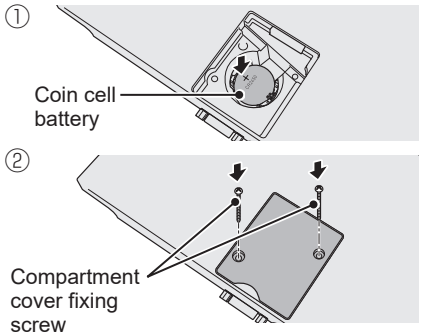


2 Using the compartment cover, take out the coin cell battery.

Pick up the coin cell battery with the hook of the compartment cover.

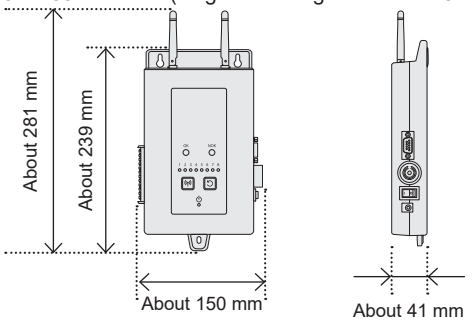


3 Put a new coin cell battery and attach the compartment cover with the 2 compartment cover fixing screws.



Controller Specifications

Receiving fastening completion and failure signals during indoor product assembly work

Model No.	EYFRW2
Power Supply	100 V-240 V AC, 50/60 Hz
Wireless Communication Standard	Wireless LAN (IEEE.802.11 a/b/g/n) n: HT20 only
Frequency Band	2.4 GHz: 2.412 GHz to 2.472 GHz 5 GHz: 5.180 GHz to 5.240 GHz [For China, Korea only] 2.4 GHz: 2.412 GHz to 2.462 GHz 5 GHz: 5.180 GHz to 5.240 GHz
Channel	2.4 GHz: 1 to 13 channels 5 GHz: 36, 40, 44, 48 channels [For China, Korea only] 2.4 GHz: 1 to 11 channels 5 GHz: 36, 40, 44, 48 channels
Coverage	2.4 GHz: About 16 m 5 GHz: About 10 m
Number of Tools That Can Be Registered	8 (maximum)
Input/output (I/O) Terminals	8 inputs and 8 outputs
I/O input terminal rating	24 V DC, 5 mA
I/O output terminal rating	30 V DC, 3 A
I/O power supply rating	24 V DC, 50 mA
Power Consumption	About 30 W
Operating Temperature and Humidity Ranges	0 °C to 45 °C, 20% to 90%
Size (Estimated Dimensions) Total Length × Total Height × Width	About 150 × 239 × 41 mm (height including antennas: 281 mm) 
Mass (Weight)	About 550 g (main unit only)
Communication interface	Ethernet × 2, RS232C × 1, USB-A × 1
Number of Data That Can Be Stored	About 200,000 fastening history logs (including waveform data)
Compatible Tool Models	EYFMH1WC, EYFMH2WC, EYFNH1WC *1, EYFCA1WC*2

*1 This is only supported by the firmware version 2.02.00 or later.
*2 This is only supported by the firmware version 2.04.00 or later.

• Please refer to the latest general catalogue.

Wireless Specifications

Frequencies by channel

Frequency Band	Channel	Frequency
2.4 GHz	Channel 1	2.412 GHz
	Channel 2	2.417 GHz
	Channel 3	2.422 GHz
	Channel 4	2.427 GHz
	Channel 5	2.432 GHz
	Channel 6	2.437 GHz
	Channel 7	2.442 GHz
	Channel 8	2.447 GHz
	Channel 9	2.452 GHz
	Channel 10	2.457 GHz
	Channel 11	2.462 GHz
	Channel 12	2.467 GHz
	Channel 13	2.472 GHz
5 GHz	Channel 36	5.180 GHz
	Channel 40	5.200 GHz
	Channel 44	5.220 GHz
	Channel 48	5.240 GHz

• Channels 12 and 13 are not available in China and Korea.

WebUI Specifications

Compatible OS	Windows 10 or later (supporting any of the web browsers below)
Supported Web Browser	Microsoft Edge version 102 or later or Google Chrome version 102 or later
Supported language	English, Japanese
Recommended screen resolution	1024 × 768 or more

CAUTION

- Some PCs are not available even if they meet the operating environment.
- Depending on the use environment etc. of your PC, the descriptions and screens in this Operating Instructions might be different from the actual descriptions and screens.
  Please be forewarned.
- The contents of this Operating Instructions are subject to change without prior notice.
- Any reproduction of the contents of this Operating Instructions in whole or in part is prohibited without permission.
- Descriptions on how to operate Windows in this Operating Instructions use the procedures and screens of Windows 10.
- WebUI does not work on OS other than the compatible OS.
- Operation is not guaranteed for all the PCs meeting the recommended environment.

■ Terms of use (Read before use)

<Limitations>
WebUI is configuration software for EYFRW2.

CAUTION

- Observe the following when using the feature.
  You are deemed to agree the following terms of use by using the feature.

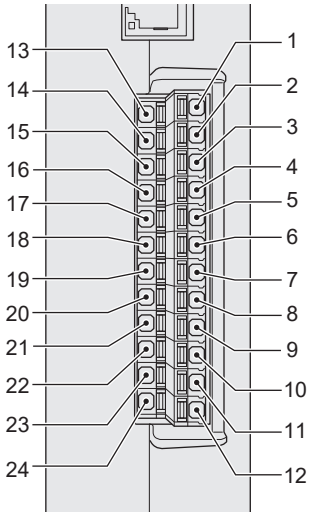
[Use conditions]

Panasonic makes no warranty of any kind regarding the feature.
Panasonic bears no responsibility for any damage including but not limited to direct loss, indirect loss, spreading loss, consequential loss, and special loss caused by use or operation of the feature.
Unauthorised reproduction and distribution of the feature is prohibited.

Contact I/O Specifications

■ Assignment between output relay terminals and input terminals

IN: Input RY: Output

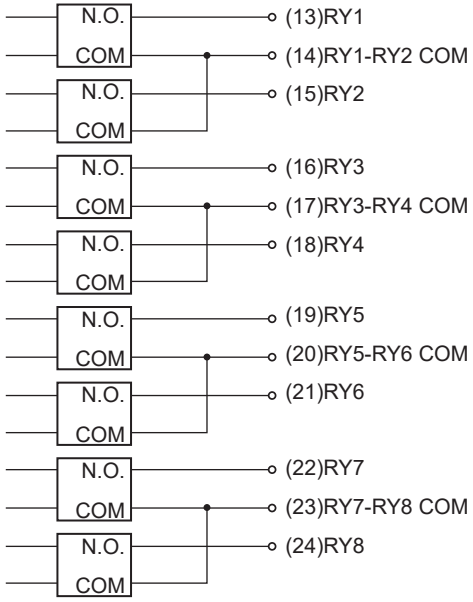


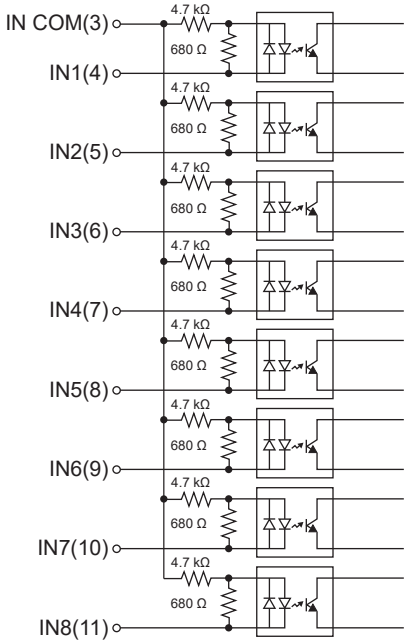
No.	Pin assignment
1	24 V output (+)*
2	24 V output (+)*
3	IN COM
4	IN 1
5	IN 2
6	IN 3
7	IN 4
8	IN 5
9	IN 6
10	IN 7
11	IN 8
12	24 V output (–)*

No.	Pin assignment
13	RY1
14	RY1-RY2 COM
15	RY2
16	RY3
17	RY3-RY4 COM
18	RY4
19	RY5
20	RY5-RY6 COM
21	RY6
22	RY7
23	RY7-RY8 COM
24	RY8

* Can supply 24 V power to external devices.
Terminals 1 and 2 can be used in parallel.

■ Terminal block connection diagram





PRECAUTIONS FOR WIRELESS COMMUNICATION

■ There may be noise, shorter radio coverage, or malfunction occurring in the following environmental conditions.

- There is an obstruction (e.g., a metal or reinforced concrete object) that prevents smooth radio propagation between the wireless-enabled tool unit and the controller.
- The antennas of the controller are covered with metal.
- An operator's body is interfering with radio propagation between an operator (the wireless-enabled tool unit) and the controller.
- There is a microwave, PC, or any other device causing noise in the vicinity.
- A cell-phone or PHS phone is used near the wireless-enabled tool unit and the controller.

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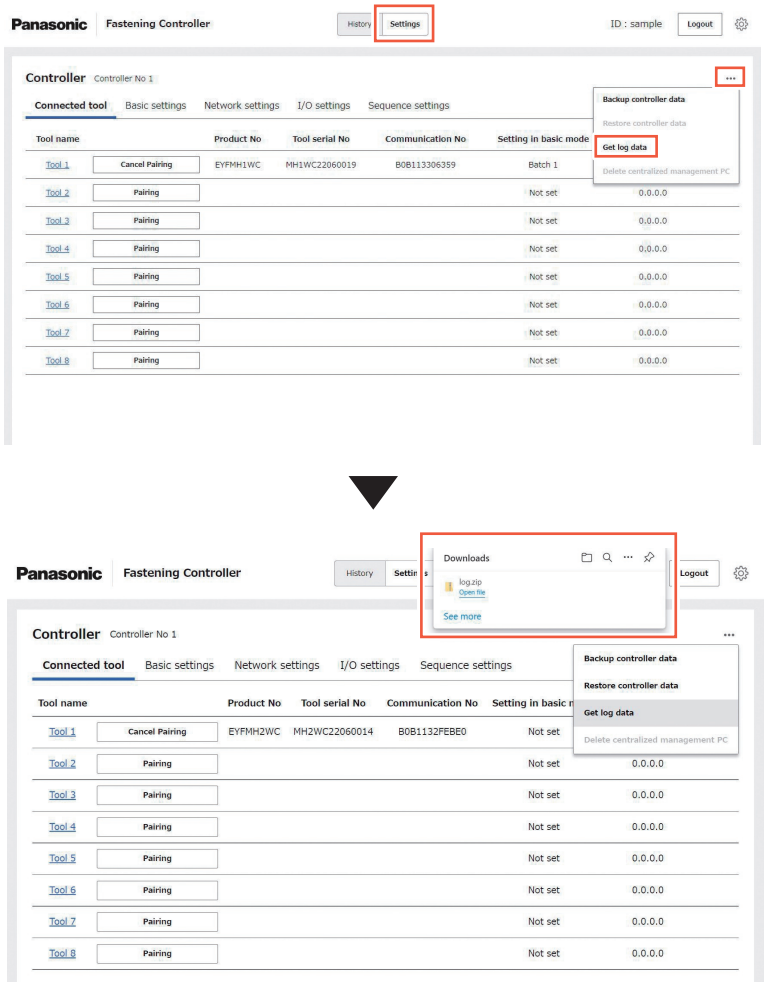
Contact Information: oss-cd-powertools-gl@ml.jp.panasonic.com

Device	Error Code	Type	Category	Event	Action
Controller	0xEF21	Warning	Hardware failure	Secondary CPU error (failure)	Restart the controller. If the problem persists, the device may be broken. Contact your dealer.
	0xEF51	Warning	Hardware failure	Ether0 error	The device may be broken. Contact your dealer.
	0xEF52	Warning	Hardware failure	Ether1 error	The device may be broken. Contact your dealer.
	0xEF61	Warning	Hardware failure	WLAN module error (failure)	Restart the controller. If the problem persists, the device may be broken. Contact your dealer.
	0xCE42	Error	Software failure	Setting content error	Factory-reset the controller and make settings again.
	0xCE43	Error	Software failure	Retraction information error	Hold down the reset key on the controller 3 seconds or more.
	0xEC61	Warning	Software failure	Capacity to store the fastening history is full (operation suspended)	Delete the fastening history logs in the fastening history screen to free up some capacity. Export them before deleting as necessary.
Tool	0x4301	Caution	Software failure	Storage capacity is full	Access the tool setting software (Tool Manager software) and delete the work history logs.
	0x4302	Caution	Software failure	The number of sent results in a queue has reached the upper limit.	The tool cannot communicate with the controller. Change the workplace. If the problem persists, the device may be broken. Contact your dealer.
	0x3303	Error	Software failure	Motor control microcontroller reset detected	An error that occurred has been solved.
	0x3304	Error	Software failure	Torque calculation microcontroller reset detected	An error that occurred has been solved.

Device	Error Code	Type	Category	Event	Action
Tool	0x4305	Caution	Software failure	Low RTC battery	Replace the coin cell battery inside the tool unit.
	0x4306	Caution	Software failure	Firmware update error	Confirm that the firmware file is correct.
	0x4315	Caution	Software failure	USB communication error	An error that occurred has been solved.
	0x4316	Caution	Software failure	WLAN module restarted	An error that occurred has been solved.
	0x1401	Warning	Hardware failure	WLAN module error	An error that occurred has been solved.
	0x1402	Warning	Hardware failure	Motor control microcontroller error	An error that occurred has been solved.
	0x1403	Warning	Hardware failure	Torque calculation microcontroller error	An error that occurred has been solved.
	0x1404	Warning	Hardware failure	External flash drive error	An error that occurred has been solved.
	0x1405	Warning	Hardware failure	RTC error	An error that occurred has been solved.
	0x1406	Warning	Hardware failure	Circuit identification error	An error that occurred has been solved.
	0x1407	Warning	Hardware failure	No remaining swap space	An error that occurred has been solved.
	0x1408	Warning	Hardware failure	Damaged parameter space	An error that occurred has been solved.

OPERATION LOG DATA

In the top page (the initial page of the setting screen), click [Settings] on the top.
Click ··· (controller option key) and then [Get log data].
You can get the operation logs of the controller.



Instructional Safeguard Symbols

Symbol	Meaning
	To reduce the risk of injury, user must read and understand instruction manual.
	For indoor use only.

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ENABLE_UNICODE_PRESERVE_BROKEN define unicode_mark_raw_byte(wc) ((wc) | 0x20000000) define unicode_is_raw_byte(wc) ((wc) & 0x20000000) else define unicode_is_raw_byte(wc) 0 endif;(c) bb_putchar(c) Should never be called: */ int adjust_width_and_validate_wc(unsigned *width_adj, int wc); endif
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Copyright (C) 2008-2018 Free Software Foundation, Inc. This file is part of the GNU C Library. Written by Eric Blake <ebb9@byu.net>, 2008.;(c) A macro that canonicalizes an element right after it has been fetched from one of the two strings. The argument is an 'unsigned char'; the result must be an 'unsigned char' as well.;(c) c endif ifndef CMP_FUNC define CMP_FUNC memcmp endif
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Copyright (C) 2001, 2005-2007, 2009-2018 Free Software Foundation, Inc.;(c) tests whether the single-byte character c is in the ISO C "basic character set". This is a convenience function, and is in this file only to share code between mbiter_multi.h and mbfile_multi.h. */ if (' ' == 32) && ('!' == 33) && ('"' == 34) && ('#' == 35) \ 37) && ('&
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```
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GCC RUNTIME LIBRARY EXCEPTION

Version 3.1, 31 March 2009

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3. [3]Bernd Altmeier <altmeier@atlsoft.de> hopf Elektronik serial line and PCI-bus devices
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5. [6]Michael Barone <michael,barone@lmco.com> GPSVME fixes
6. [7]Karl Berry <karl@owl.HQ.ileaf.com> syslog to file option
7. [8]Greg Brackley <greg.brackley@bigfoot.com> Major rework of WINNT port. Clean up recvbuf and iosignal code into separate modules.
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9. [10]Piete Brooks <Piete.Brooks@cl.cam.ac.uk> MSF clock driver, Trimble PARSE support
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15. [16]Sven Dietrich <sven_dietrich@trimble.com> Palisade reference clock driver, NT adj. residuals, integrated Greg's Winnt port.
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46. [50]Wilfredo Sanchez <wsanchez@apple.com> added support for NetInfo
47. [51]Nick Sayer <mrapple@quack.kfu.com> SunOS streams modules
48. [52]Jack Sasportas <jack@innovativeinternet.com> Saved a Lot of space on the stuff in the html/pic/ subdirectory
49. [53]Ray Schnitzler <schnitz@unipress.com> Unixware1 port
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 *
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 *
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agere_sta_fw.bin -- 9.48 Hermes I
agere_ap_fw.bin -- 9.48 Hermes I

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The Linux driver architecture was based on two modules, the MSF (Module specific functions) and the HCF (Hardware Control Functions). Included in the HCF is run-time firmware (binary format) which is downloaded into the RAM of the Hermes 1/2/2.5 WMAC.

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Hope this helps.

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Viren Pathare
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Chelsio Communication Terminator 4/5 ethernet controller firmware

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Firmware provided by Patrick Boettcher <pboettcher@dibcom.fr> to Devin Heitmueller <dheitmueller@kernellabs.com> on October 8, 2009.

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```

The following XC500 firmware file "dvb-fe-xc5000-1.6.114.fw" was created based on "xc5000_firmwares_32000Khz.h".

Firmware provided as part of an XC5000 Linux developers kit by Brian Mathews <bmathews@xceive.com> to Devin Heitmueller <dheitmueller@linuxtv.org> on July 1, 2009.

The code was released by Xceive under the following license:

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```

The following XC500C firmware file "dvb-fe-xc5000C-4.1.30.7.fw" was created based on "Xc5200_firmwares_32000Khz.h".

Firmware provided as part of an XC5000C Linux developers kit by Ramon Cazares <Ramon.Cazares@CrestaTech.com> to Devin Heitmueller dheitmueller@linuxtv.org on July 25, 2012.

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The source code for HDCP Cipher can is available here:
http://www3.cs.stonybrook.edu/~rob/hdcp.html

SSL Library is licensed under the Apache License, Version 2.0.
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http://www.apache.org/licenses/LICENSE-2.0.
The original source code for SSL Library can is available here:
https://tls.mbed.org/download

Fast discrete Fourier and cosine transforms and inverses
author: Monty <xiphmont@mit.edu>
modifications by: Monty
last modification date: Jul 1 1996

/* These Fourier routines were originally based on the Fourier
routines of the same names from the NETLIB bihar and fftpack
fortran libraries developed by Paul N. Swarztrauber at the National
Center for Atmospheric Research in Boulder, CO USA. They have been
reimplemented in C and optimized in a few ways for OggSquish. */

/* As the original fortran libraries are public domain, the C Fourier
routines in this file are hereby released to the public domain as
well. The C routines here produce output exactly equivalent to the
original fortran routines. Of particular interest are the facts
that (like the original fortran), these routines can work on
arbitrary length vectors that need not be powers of two in
length. */

****
* WHENCE *
****

This file attempts to document the origin and licensing information,
if known, for each piece of firmware distributed for use with the Linux
kernel.

Driver: BCM-0bb4-0306 Cypress Bluetooth firmware for HTC Vive

File: brcm/BCM-0bb4-0306.hcd

Licence: Redistributable. See LICENCE.cypress for details.

Driver: ambassador -- Madge Ambassador (Collage PCI 155 Server) ATM NIC.

File: atmsar11.fw

Licence: Allegedly GPLv2+, but no source visible. Marked:

Madge Ambassador ATM Adapter microcode.
Copyright (C) 1995-1999 Madge Networks Ltd.

This microcode data is placed under the terms of the GNU General
Public License. The GPL is contained in /usr/doc/copyright/GPL on a
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We would prefer you not to distribute modified versions without
consultation and not to ask for assembly/other microcode source.

Driver: snd-korg1212 -- Korg 1212 IO audio device

File: korg/k1212.dsp

Licence: Unknown

Found in alsa-firmware package in hex form; no licensing information.

Driver: snd-maestro3 -- ESS Allegro Maestro3 audio device

File: ess/maestro3_assp_kernel.fw
File: ess/maestro3_assp_minisrc.fw

Licence: Unknown

Found in alsa-firmware package in hex form with a comment claiming to
be GPLv2+, but without source -- and with another comment saying "ESS
drops binary dsp code images on our heads, but we don't get to see
specs on the dsp."

Driver: snd-ymfpci -- Yamaha YMF724/740/744/754 audio devices

File: yamaha/ds1_ctrl.fw
File: yamaha/ds1_dsp.fw
File: yamaha/ds1e_ctrl.fw

Licence: Unknown

Found alsa-firmware package in hex form, with the following comment:
Copyright (c) 1997-1999 Yamaha Corporation. All Rights Reserved.

Driver: advansys - AdvanSys SCSI

File: advansys/mcode.bin
File: advansys/3550.bin
File: advansys/38C0800.bin
File: advansys/38C1600.bin

Licence: BSD, no source available.

Found in hex form in kernel source.

Driver: qla1280 - Qlogic QLA 1240/1x80/1x160 SCSI support

File: qlogic/1040.bin
File: qlogic/1280.bin
File: qlogic/12160.bin

Licence: Redistributable. See LICENCE.qla1280 for details

Driver: smctr -- SMC ISA/MCA Token Ring adapter

File: tr_smctr.bin
Version: 6.3C1
Info: MCT.BIN v6.3C1 03/01/95

Original licence info:

```
 * This firmware is licensed to you strictly for use in conjunction
 * with the use of SMC TokenRing adapters. There is no waranty
 * expressed or implied about its fitness for any purpose.
```

Driver: kaweth -- USB KLSI KL5USB101-based Ethernet device

File: kaweth/new_code.bin
File: kaweth/new_code_fix.bin
File: kaweth/trigger_code.bin
File: kaweth/trigger_code_fix.bin

Licence: Redistributable. See LICENCE.kaweth for details

Found in hex form in the kernel source.

Driver: dvb-ttusb-budget -- Technotrend/Hauppauge Nova-USB devices

File: ttusb-budget/dspbootcode.bin

Licence: Unknown

Found in hex form in the kernel source.

Driver: keyspan -- USB Keyspan USA-xxx serial device

File: keyspan/mpr.fw
File: keyspan/usa18x.fw
File: keyspan/usa19.fw
File: keyspan/usa19qi.fw
File: keyspan/usa19qw.fw
File: keyspan/usa19w.fw
File: keyspan/usa28.fw
File: keyspan/usa28xa.fw
File: keyspan/usa28xb.fw
File: keyspan/usa28x.fw
File: keyspan/usa49w.fw
File: keyspan/usa49wlc.fw

Converted from Intel HEX files, used in our binary representation of ihex.

Original licence information:

```
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        keyspan.c driver which includes this firmware, in whole or in
        part, requires the inclusion of this statement."
```

Driver: keyspan_pda -- USB Keyspan PDA single-port serial device

File: keyspan_pda/keyspan_pda.fw
Source: keyspan_pda/keyspan_pda.S

File: keyspan_pda/xircom_pgs.fw
Source: keyspan_pda/xircom_pgs.S

Source: keyspan_pda/Makefile

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

Compiled from original 8051 source into Intel HEX, used in our binary ihex form.

Driver: emi26 -- EMI 2|6 USB Audio interface

File: emi26/bitstream.fw
Version: 1.1.1.131
Info: DATE=2001dec06

File: emi26/firmware.fw
Version: 1.0.2.916
Info: DATE=12.02.2002

File: emi26/loader.fw

Converted from Intel HEX files, used in our binary representation of ihex.

Original licence information:

```
/*
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 *
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 *
 * This firmware may not be modified and may only be used with the
 * Emagic EMI 2|6 Audio Interface. Distribution and/or Modification of
 * any driver which includes this firmware, in whole or in part,
 * requires the inclusion of this statement.
 */
```

Driver: emi62 -- EMI 6|2m USB Audio interface

File: emi62/bitstream.fw
Version: 1.0.0.191
Info: DATE= 2002oct28

File: emi62/loader.fw
Version: 1.0.2.002
Info: DATE=10.01.2002

File: emi62/midi.fw
Version: 1.04.062
Info: DATE=16.10.2002

File: emi62/spdif.fw
Version: 1.04.062
Info: DATE=16.10.2002

Converted from Intel HEX files, used in our binary representation of ihex.

Original licence information: None

Driver: ti_usb_3410_5052 -- USB TI 3410/5052 serial device

File: ti_3410.fw
Info: firmware 9/10/04 FW3410_Special_StartWdogOnStartPort

File: ti_5052.fw
Info: firmware 9/18/04

Licence: Allegedly GPLv2+, but no source visible. Marked:
Copyright (C) 2004 Texas Instruments

Found in hex form in kernel source.

Driver: ti_usb_3410_5052 -- Multi-Tech USB cell modems

File: mts_cdma.fw
File: mts_gsm.fw
File: mts_edge.fw

Licence: "all firmware components are redistributable in binary form"
per support@multitech.com
Copyright (C) 2005 Multi-Tech Systems, Inc.

Found in hex form in ftp://ftp.multitech.com/wireless/wireless_linux.zip

---

Driver: ti_usb_3410_5052 -- Multi-Tech USB fax modems

File: mts_mt9234mu.fw
File: mts_mt9234zba.fw

Licence: Unknown

Driver: whiteheat -- USB ConnectTech WhiteHEAT serial device

File: whiteheat.fw
Version: 4.06

File: whiteheat_loader.fw

Licence: Allegedly GPLv2, but no source visible. Marked:
Copyright (C) 2000-2002 ConnectTech Inc

Debug loader claims the following behaviour:
Port 1 LED flashes when the vend_ax program is running
Port 2 LED flashes when any SETUP command arrives

Port 3 LED flashes when any valid VENDOR request occurs
Port 4 LED flashes when the EXTERNAL RAM DOWNLOAD request occurs

Converted from Intel HEX files, used in our binary representation of ihex.

Driver: ip2 -- Computone IntelliPort Plus serial device

File: intelliport2.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: cpia2 -- cameras based on Vision's CPiA2

File: cpia2/stv0672_vp4.bin

Licence: Allegedly GPLv2+, but no source visible. Marked:
Copyright (C) 2001 STMicroelectronics, Inc.
Contact: steve.miller@st.com
Description: This file contains patch data for the CPiA2 (stv0672) VP4.

Found in hex form in kernel source.

Driver: dabusb -- Digital Audio Broadcasting (DAB) Receiver for USB and Linux

File: dabusb/firmware.fw
File: dabusb/bitstream.bin

Licence: Distributable

```
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```

Driver: vicam -- USB 3com HomeConnect (aka vicam)

File: vicam/firmware.fw

Licence: Unknown

Found in hex form in kernel source.

Driver: io_edgeport - USB Inside Out Edgeport Serial Driver

File: edgeport/boot.fw
File: edgeport/boot2.fw
File: edgeport/down.fw
File: edgeport/down2.fw

Licence: Allegedly GPLv2+, but no source visible. Marked:

```
//************************************************************
//* Edgeport/4 Binary Image
//* Generated by HEX2C v1.06
//* Copyright (C) 1998 Inside Out Networks, All rights reserved.
//************************************************************
```

Found in hex form in kernel source.

Driver: io_ti - USB Inside Out Edgeport Serial Driver
(TI Devices)

File: edgeport/down3.bin

Licence:

```
//************************************************************
//* Edgeport Binary Image (for TI based products)
//* Generated by TIBin2C v2.00 (watchport)
//* Copyright (C) 2001 Inside Out Networks, All rights reserved.
//************************************************************
```

Found in hex form in kernel source.

Driver: dsp56k - Atari DSP56k support

File: dsp56k/bootstrap.bin
Source: dsp56k/bootstrap.asm
Source: dsp56k/Makefile
Source: dsp56k/concat-bootstrap.pl

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

DSP56001 assembler, buildable with a56 from
http://www.zdomain.com/a56.html

Driver: snd-sb16-csp - Sound Blaster 16/AWE CSP support

File: sb16/mulaw_main.csp
File: sb16/alaw_main.csp
File: sb16/ima_adpcm_init.csp
File: sb16/ima_adpcm_playback.csp
File: sb16/ima_adpcm_capture.csp

Licence: Allegedly GPLv2+, but no source visible. Marked:
/*
 * Copyright (c) 1994 Creative Technology Ltd.
 * Microcode files for SB16 Advanced Signal Processor
 */

Found in hex form in kernel source.

Driver: qla2xxx - QLogic QLA2XXX Fibre Channel

File: ql2100_fw.bin
Version: 1.19.38 TP
File: ql2200_fw.bin
Version: 2.02.08 TP
File: ql2300_fw.bin
Version: 3.03.28 IPX
File: ql2322_fw.bin
Version: 3.03.28 IPX
File: ql2400_fw.bin
Version: 8.07.00 MID
File: ql2500_fw.bin
Version: 8.07.00 MIDQ

Licence: Redistributable. See LICENCE.qla2xxx for details

Available from http://ldriver.qlogic.com/firmware/

Driver: orinoco - Agere/Prism/Symbol Orinoco support

File: agere_sta_fw.bin
Version: 9.48 Hermes I
File: agere_ap_fw.bin
Version: 9.48 Hermes I

Licence: Redistributable. See LICENCE.agere for details

Driver: ar9170 - Atheros 802.11n "otus" USB

File: ar9170-1.fw
File: ar9170-2.fw

Licence: Redistributable. See LICENCE.atheros_firmware for details

---

Driver: ath9k_htc - Atheros HTC devices (USB)

File: ar9271.fw
File: ar7010.fw
File: ar7010_1_1.fw
File: htc_9271.fw

Version: 1.3.1
File: htc_7010.fw
Version: 1.3.1

Licence: Redistributable. See LICENCE.atheros_firmware for details

File: ath9k_htc/htc_7010-1.4.0.fw
Version: 1.4.0
File: ath9k_htc/htc_9271-1.4.0.fw
Version: 1.4.0

Licence: Free software. See LICENCE.open-ath9k-htc-firmware for details

---

Driver: cassini - Sun Cassini

File: sun/cassini.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: slicoss - Alacritech IS-NIC products

File: slicoss/gbdownload.sys
File: slicoss/gbrcvucode.sys
File: slicoss/oasisdbgdownload.sys
File: slicoss/oasisdownload.sys
File: slicoss/oasisrcvucode.sys

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Driver: sxg - Alacritech IS-NIC products

File: sxg/saharadownloadB.sys
File: sxg/saharadbgdownloadB.sys

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Driver: cxgb3 - Chelsio Terminator 3 1G/10G Ethernet adapter

File: cxgb3/t3b_psram-1.1.0.bin
File: cxgb3/t3c_psram-1.1.0.bin
File: cxgb3/t3fw-7.0.0.bin
File: cxgb3/t3fw-7.1.0.bin
File: cxgb3/t3fw-7.4.0.bin
File: cxgb3/t3fw-7.10.0.bin
File: cxgb3/t3fw-7.12.0.bin

Licence: GPLv2 or OpenIB.org BSD license, no source visible

Driver: cxgb3 - Chelsio Terminator 3 1G/10G Ethernet adapter

File: cxgb3/ael2005_opt_edc.bin
File: cxgb3/ael2005_twx_edc.bin
File: cxgb3/ael2020_twx_edc.bin

Licence:
```
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 *
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```

Found in hex form in kernel source.

Driver: cxgb4 - Chelsio Terminator 4/5/6 1/10/25/40/100G Ethernet adapter

File: cxgb4/t4fw-1.14.4.0.bin
File: cxgb4/t4fw-1.15.37.0.bin
File: cxgb4/t4fw-1.24.3.0.bin
Link: cxgb4/t4fw.bin -> t4fw-1.24.3.0.bin
File: cxgb4/t5fw-1.14.4.0.bin

File: cxgb4/t5fw-1.15.37.0.bin
File: cxgb4/t5fw-1.24.3.0.bin
Link: cxgb4/t5fw.bin -> t5fw-1.24.3.0.bin
File: cxgb4/t6fw-1.24.3.0.bin
Link: cxgb4/t6fw.bin -> t6fw-1.24.3.0.bin
File: cxgb4/aq1202_fw.cld
File: cxgb4/bcm8483.bin

Licence: Redistributable. See LICENCE.chelsio_firmware for details

---

Driver: e100 -- Intel PRO/100 Ethernet NIC

File: e100/d101m_ucode.bin
File: e100/d101s_ucode.bin
File: e100/d102e_ucode.bin

Licence: Redistributable. See LICENCE.e100 for details

Driver: acenic -- Alteon AceNIC Gigabit Ethernet card

File: acenic/tg1.bin
File: acenic/tg2.bin

Licence: Unknown

Found in hex form in kernel source, but source allegedly available at http://alteon.shareable.org/

Driver: tg3 -- Broadcom Tigon3 based gigabit Ethernet cards

File: tigon/tg3.bin
File: tigon/tg3_tso.bin
File: tigon/tg3_tso5.bin
File: tigon/tg357766.bin

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```
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 *
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 *      notice is accompanying it.
```

Found in hex form in kernel source.

Driver: starfire - Adaptec Starfire/DuraLAN support

File: adaptec/starfire_rx.bin

File: adaptec/starfire_tx.bin

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Driver: i2400m-usb - Intel 2400 Wireless WiMAX Connection over USB

File: i2400m-fw-usb-1.4.sbcf
File: i2400m-fw-usb-1.5.sbcf
File: i6050-fw-usb-1.5.sbcf

Licence: Redistributable. See LICENCE.i2400m for details

Also available from http://linuxwimax.org/Download

Driver: libertas - Marvell Libertas fullmac-type 802.11b/g cards

File: libertas/cf8381.bin
File: libertas/cf8381_helper.bin
File: libertas/cf8385.bin
File: libertas/cf8385_helper.bin
File: libertas/gspi8682.bin
File: libertas/gspi8682_helper.bin
File: libertas/gspi8686_v9.bin
File: libertas/gspi8686_v9_helper.bin
File: libertas/gspi8688.bin
File: libertas/gspi8688_helper.bin
File: libertas/sd8385.bin
File: libertas/sd8385_helper.bin
File: libertas/sd8682.bin
File: libertas/sd8682_helper.bin
File: libertas/sd8686_v8.bin
File: libertas/sd8686_v8_helper.bin
File: libertas/sd8686_v9.bin
File: libertas/sd8686_v9_helper.bin
File: libertas/usb8388_v5.bin
File: libertas/usb8388_v9.bin
File: libertas/usb8682.bin
File: mrvl/sd8688.bin
Link: libertas/sd8688.bin -> ../mrvl/sd8688.bin
File: mrvl/sd8688_helper.bin
Link: libertas/sd8688_helper.bin -> ../mrvl/sd8688_helper.bin

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Linux driver tarballs downloaded from Marvell's "Extranet" with permission.

Driver: libertas - Marvell Libertas 802.11b/g cards, OLPC firmware

File: libertas/lbtf_sdio.bin
Version: 9.0.7.p4

File: lbtf_usb.bin
Version: 5.132.3.p1

File: libertas/usb8388_olpc.bin
Version: 5.110.22.p23

Licence: Redistributable. See LICENCE.OLPC for details.

Available from http://dev.laptop.org/pub/firmware/libertas/

Driver: mwl8k - Marvell Libertas softmac-type 802.11b/g/n cards

File: mwl8k/fmimage_8687.fw
File: mwl8k/helper_8687.fw
File: mwl8k/fmimage_8366.fw
File: mwl8k/fmimage_8366_ap-1.fw
File: mwl8k/fmimage_8366_ap-2.fw
File: mwl8k/fmimage_8366_ap-3.fw
Version: 5.2.8.16
File: mwl8k/helper_8366.fw

File: mwl8k/fmimage_8764_ap-1.fw
Version: 7.4.0.9

Licence: Redistributable. See LICENCE.Marvell for details. 8687 images downloaded from Marvell's "Extranet" with permission. 8366 images contributed directly by Marvell.

Driver: mwifiex - Marvell Wi-Fi fullmac-type 802.11n/ac cards

File: mrvl/sd8787_uapsta.bin
Version: W14.68.35.p66

File: mrvl/usb8766_uapsta.bin
Version: 14.68.22.p16

File: mrvl/sd8797_uapsta.bin
Version: W14.68.29.p59

File: mrvl/usb8797_uapsta.bin
Version: W14.68.29.p60

File: mrvl/sd8897_uapsta.bin
Version: W15.68.19.17

File: mrvl/usb8897_uapsta.bin
Version: 15.68.4.p103

File: mrvl/pcie8897_uapsta.bin
Version: W15.68.19.p21

File: mrvl/sd8887_uapsta.bin
Version: W15.68.7.p189

File: mrvl/sd8801_uapsta.bin
Version: W14.68.36.p204

File: mrvl/usb8801_uapsta.bin
Version: W14.68.36.p138

File: mrvl/pcieuart8997_combo_v4.bin
Version: W16.68.1.p179

File: mrvl/pcieusb8997_combo_v4.bin
Version: W16.68.1.p195

File: mrvl/pcie8997_wlan_v4.bin
Version: W16.68.1.p195

File: mrvl/usbusb8997_combo_v4.bin
Version: W16.68.1.p183

File: mrvl/sdsd8997_combo_v4.bin
Version: W16.68.1.p179

File: mrvl/sdsd8977_combo_v2.bin
Version: W16.68.1.p195

Licence: Redistributable. See LICENCE.Marvell for details. Originates from
http://git.marvell.com/?p=mwifiex-firmware.git

Driver: iwlwifi - Intel Wireless Wifi

File: iwlwifi-3945-2.ucode
Version: 15.32.2.9

File: iwlwifi-4965-2.ucode
Version: 228.61.2.24

File: iwlwifi-5000-1.ucode
Version: 5.4.A.11 (aka 5.4.1.16)

File: iwlwifi-5000-2.ucode
Version: 8.24.2.12

File: iwlwifi-5000-5.ucode
Version: 8.83.5.1

File: iwlwifi-5150-2.ucode

Version: 8.24.2.2

File: iwlwifi-1000-3.ucode
Version: 128.50.3.1

File: iwlwifi-1000-5.ucode
Version: 39.31.5.1

File: iwlwifi-6000-4.ucode
Version: 9.221.4.1

File: iwlwifi-6050-4.ucode
Version: 9.201.4.1

File: iwlwifi-6050-5.ucode
Version: 41.28.5.1

File: iwlwifi-6000g2a-5.ucode
Version: 17.168.5.3

File: iwlwifi-6000g2a-6.ucode
Version: 18.168.6.1

File: iwlwifi-6000g2b-5.ucode
Version: 17.168.5.1

File: iwlwifi-6000g2b-6.ucode
Version: 18.168.6.1

File: iwlwifi-135-6.ucode
Version: 18.168.6.1

File: iwlwifi-100-5.ucode
Version: 39.31.5.1

File: iwlwifi-105-6.ucode
Version: 18.168.6.1

File: iwlwifi-2030-6.ucode
Version: 18.168.6.1

File: iwlwifi-2000-6.ucode
Version: 18.168.6.1

File: iwlwifi-7260-7.ucode
Version: 22.1.7.0

File: iwlwifi-7260-8.ucode
Version: 22.24.8.0

File: iwlwifi-7260-9.ucode
Version: 25.228.9.0

File: iwlwifi-7260-10.ucode
Version: 23.15.10.0

File: iwlwifi-7260-12.ucode

Version: 25.17.12.0

File: iwlwifi-7260-13.ucode
Version: 25.30.13.0

File: iwlwifi-7260-16.ucode
Version: 16.242414.0

File: iwlwifi-7260-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-3160-7.ucode
Version: 22.1.7.0

File: iwlwifi-3160-8.ucode
Version: 22.24.8.0

File: iwlwifi-3160-9.ucode
Version: 25.228.9.0

File: iwlwifi-3160-10.ucode
Version: 23.15.10.0

File: iwlwifi-3160-12.ucode
Version: 25.17.12.0

File: iwlwifi-3160-13.ucode
Version: 25.30.13.0

File: iwlwifi-3160-16.ucode
Version: 16.242414.0

File: iwlwifi-3160-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-7265-8.ucode
Version: 22.24.8.0

File: iwlwifi-7265-9.ucode
Version: 25.228.9.0

File: iwlwifi-7265-10.ucode
Version: 23.15.10.0

File: iwlwifi-7265-12.ucode
Version: 25.17.12.0

File: iwlwifi-7265-13.ucode
Version: 25.30.13.0

File: iwlwifi-7265-16.ucode
Version: 16.242414.0

File: iwlwifi-7265-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-7265D-10.ucode

Version: 23.15.10.0

File: iwlwifi-7265D-12.ucode
Version: 25.17.12.0

File: iwlwifi-7265D-13.ucode
Version: 25.30.13.0

File: iwlwifi-7265D-16.ucode
Version: 16.242414.0

File: iwlwifi-7265D-17.ucode
Version: 17.352738.0

File: iwlwifi-7265D-21.ucode
Version: 21.302800.0

File: iwlwifi-7265D-22.ucode
Version: 22.391740.0

File: iwlwifi-7265D-27.ucode
Version: 27.541033.0

File: iwlwifi-7265D-29.ucode
Version: 29.3e3b4de5.0

File: iwlwifi-3168-21.ucode
Version: 21.302800.0

File: iwlwifi-3168-22.ucode
Version: 22.391740.0

File: iwlwifi-3168-27.ucode
Version: 27.541033.0

File: iwlwifi-3168-29.ucode
Version: 29.3e3b4de5.0

File: iwlwifi-8000C-13.ucode
Version: 25.30.13.0

File: iwlwifi-8000C-16.ucode
Version: 16.242414.0

File: iwlwifi-8000C-21.ucode
Version: 21.302800.0

File: iwlwifi-8000C-22.ucode
Version: 22.391740.0

File: iwlwifi-8000C-27.ucode
Version: 27.541033.0

File: iwlwifi-8000C-31.ucode
Version: 31.560484.0

File: iwlwifi-8000C-34.ucode

Version: 34.610288.0

File: iwlwifi-8000C-36.ucode
Version: 36.8fd77bb3.0

File: iwlwifi-8265-21.ucode
Version: 21.302800.0

File: iwlwifi-8265-22.ucode
Version: 22.391740.0

File: iwlwifi-8265-27.ucode
Version: 27.541033.0

File: iwlwifi-8265-31.ucode
Version: 31.560484.0

File: iwlwifi-8265-34.ucode
Version: 34.610288.0

File: iwlwifi-8265-36.ucode
Version: 36.8fd77bb3.0

File: iwlwifi-9000-pu-b0-jf-b0-33.ucode
Version: 33.610294.0

File: iwlwifi-9000-pu-b0-jf-b0-34.ucode
Version: 34.ba501b11.0

File: iwlwifi-9000-pu-b0-jf-b0-38.ucode
Version: 38.755cfdd8.0

File: iwlwifi-9000-pu-b0-jf-b0-41.ucode
Version: 41.fc1a7aea.0

File: iwlwifi-9000-pu-b0-jf-b0-43.ucode
Version: 43.95eb4e97.0

File: iwlwifi-9000-pu-b0-jf-b0-46.ucode
Version: 46.a41adfe7.0

File: iwlwifi-9260-th-b0-jf-b0-33.ucode
Version: 33.610294.0

File: iwlwifi-9260-th-b0-jf-b0-34.ucode
Version: 34.ba501b11.0

File: iwlwifi-9260-th-b0-jf-b0-38.ucode
Version: 38.755cfdd8.0

File: iwlwifi-9260-th-b0-jf-b0-41.ucode
Version: 41.fc1a7aea.0

File: iwlwifi-9260-th-b0-jf-b0-43.ucode
Version: 43.95eb4e97.0

File: iwlwifi-9260-th-b0-jf-b0-46.ucode

Version: 46.a41adfe7.0

File: iwlwifi-cc-a0-46.ucode
Version: 46.3cfab8da.0

File: iwlwifi-cc-a0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-b0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-b0-jf-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-c0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-c0-jf-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-QuZ-a0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-QuZ-a0-jf-b0-48.ucode
Version: 48.13675109.0

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Also available from http://wireless.kernel.org/en/users/Drivers/iwlwifi#Firmware

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Driver: ipu3-imgu - Intel IPU3 (3rd Gen Image Processing Unit) driver

File: intel/irci_irci_ecr-master_20161208_0213_20170112_1500.bin
Version: irci_irci_ecr-master_20161208_0213_20170112_1500
md5sum: 59abc311fce49c5a180b5a8a3917912d
Link: intel/ipu3-fw.bin -> irci_irci_ecr-master_20161208_0213_20170112_1500.bin

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---

Driver: cx231xx - Conexant Cx23100/101/102 USB broadcast A/V decoder

File: v4l-cx231xx-avcore-01.fw

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Driver: tehuti - Tehuti Networks 10G Ethernet

File: tehuti/bdx.bin

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Driver: typhoon - 3cr990 series Typhoon

File: 3com/typhoon.bin

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/*
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 * COMBINATION WITH THE 3c990img.h MICROCODE SOFTWARE
 */

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Driver: yam - YAM driver for AX.25

File: yam/1200.bin
File: yam/9600.bin

Licence:
 * (C) F6FBB 1998

Found in hex form in kernel source.

Driver: 3c359 - 3Com 3C359 Token Link Velocity XL adapter

File: 3com/3C359.bin

Licence:
/*
 * The firmware this driver downloads into the tokenring card is a
 * separate program and is not GPL'd source code, even though the Linux
 * side driver and the routine that loads this data into the card are.
 *
 * This firmware is licensed to you strictly for use in conjunction
 * with the use of 3Com 3C359 TokenRing adapters. There is no
 * waranty expressed or implied about its fitness for any purpose.
 */
/* 3c359_microcode.mac: 3Com 3C359 Tokenring microcode.
 *
 * Notes:
 * - Loaded from xl_init upon adapter initialization.
 *
 * Available from 3Com as part of their standard 3C359 driver.
 */

Found in hex form in kernel source.

Driver: pcnet_cs - NE2000 compatible PCMCIA adapter

File: cis/LA-PCM.cis
File: cis/PCMLM28.cis
File: cis/DP83903.cis
File: cis/NE2K.cis
File: cis/tamarack.cis
File: cis/PE-200.cis
File: cis/PE520.cis
Source: cis/

Licence: Dual GPLv2/MPL

Originally developed by the pcmcia-cs project
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Driver: 3c589_cs - 3Com PCMCIA adapter

File: cis/3CXEM556.cis
Source: cis/src/3CXEM556.cis

Licence: Dual GPLv2/MPL

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Driver: 3c574_cs - 3Com PCMCIA adapter

File: cis/3CCFEM556.cis
Source: cis/src/3CCFEM556.cis

Licence: Dual GPLv2/MPL

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Driver: serial_cs - Serial PCMCIA adapter

File: cis/MT5634ZLX.cis
File: cis/RS-COM-2P.cis
File: cis/COMpad2.cis
File: cis/COMpad4.cis
Source: cis/src/MT5634ZLX.cis
Source: cis/src/RS-COM-2P.cis
Source: cis/src/COMpad2.cis
Source: cis/src/COMpad4.cis

Licence: Dual GPLv2/MPL

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Driver: serial_cs - Serial PCMCIA adapter

File: cis/SW_555_SER.cis
File: cis/SW_7xx_SER.cis
File: cis/SW_8xx_SER.cis

Licence: GPLv3. See GPL-3 for details.

Copyright Sierra Wireless

Driver: smc91c92_cs - SMC 91Cxx PCMCIA

File: ositech/Xilinx7OD.bin

Licence: Allegedly GPL, but no source visible. Marked:
This file contains the firmware of Seven of Diamonds from OSITECH.
(Special thanks to Kevin MacPherson of OSITECH)

Found in hex form in kernel source.

Driver: cx23418 - Conexant PCI Broadcast A/V with MPEG encoder

File: v4l-cx23418-apu.fw
File: v4l-cx23418-cpu.fw
File: v4l-cx23418-dig.fw

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Driver: cx23885 - Conexant PCI Express Broadcast A/V decoder

File: v4l-cx23885-avcore-01.fw

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Driver: cx23840 - Conexant sideport Broadcast A/V decoder

File: v4l-cx25840.fw

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Driver: qlogicpti - PTI Qlogic, ISP Driver

File: qlogic/isp1000.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: myri_sbus - MyriCOM Gigabit Ethernet

File: myricom/lanai.bin

Licence: Unknown

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Driver: bnx2x: Broadcom Everest

File: bnx2x-e1-4.8.53.0.fw
File: bnx2x-e1h-4.8.53.0.fw
File: bnx2x-e1-5.2.7.0.fw
File: bnx2x-e1h-5.2.7.0.fw
File: bnx2x-e1-5.2.13.0.fw
File: bnx2x-e1h-5.2.13.0.fw
File: bnx2x/bnx2x-e1-6.0.34.0.fw
File: bnx2x/bnx2x-e1h-6.0.34.0.fw
File: bnx2x/bnx2x-e2-6.0.34.0.fw
File: bnx2x/bnx2x-e1-6.2.5.0.fw
File: bnx2x/bnx2x-e1h-6.2.5.0.fw
File: bnx2x/bnx2x-e2-6.2.5.0.fw
File: bnx2x/bnx2x-e1-6.2.9.0.fw
File: bnx2x/bnx2x-e1h-6.2.9.0.fw
File: bnx2x/bnx2x-e2-6.2.9.0.fw
File: bnx2x/bnx2x-e2-7.0.20.0.fw
File: bnx2x/bnx2x-e1-7.0.20.0.fw
File: bnx2x/bnx2x-e1h-7.0.20.0.fw
File: bnx2x/bnx2x-e2-7.0.23.0.fw
File: bnx2x/bnx2x-e1-7.0.23.0.fw
File: bnx2x/bnx2x-e1h-7.0.23.0.fw
File: bnx2x/bnx2x-e2-7.0.29.0.fw
File: bnx2x/bnx2x-e1-7.0.29.0.fw
File: bnx2x/bnx2x-e1h-7.0.29.0.fw
File: bnx2x/bnx2x-e2-7.2.16.0.fw
File: bnx2x/bnx2x-e1-7.2.16.0.fw
File: bnx2x/bnx2x-e1h-7.2.16.0.fw
File: bnx2x/bnx2x-e2-7.2.51.0.fw

File: bnx2x/bnx2x-e1-7.2.51.0.fw
File: bnx2x/bnx2x-e1h-7.2.51.0.fw
File: bnx2x/bnx2x-e1-7.8.2.0.fw
File: bnx2x/bnx2x-e1h-7.8.2.0.fw
File: bnx2x/bnx2x-e2-7.8.2.0.fw
File: bnx2x/bnx2x-e1-7.8.17.0.fw
File: bnx2x/bnx2x-e1h-7.8.17.0.fw
File: bnx2x/bnx2x-e2-7.8.17.0.fw
File: bnx2x/bnx2x-e1-7.8.19.0.fw
File: bnx2x/bnx2x-e1h-7.8.19.0.fw
File: bnx2x/bnx2x-e2-7.8.19.0.fw
File: bnx2x/bnx2x-e1-7.10.51.0.fw
File: bnx2x/bnx2x-e1h-7.10.51.0.fw
File: bnx2x/bnx2x-e2-7.10.51.0.fw
File: bnx2x/bnx2x-e1-7.12.30.0.fw
File: bnx2x/bnx2x-e1h-7.12.30.0.fw
File: bnx2x/bnx2x-e2-7.12.30.0.fw
File: bnx2x/bnx2x-e1-7.13.1.0.fw
File: bnx2x/bnx2x-e1h-7.13.1.0.fw
File: bnx2x/bnx2x-e2-7.13.1.0.fw
File: bnx2x/bnx2x-e1-7.13.11.0.fw
File: bnx2x/bnx2x-e1h-7.13.11.0.fw
File: bnx2x/bnx2x-e2-7.13.11.0.fw

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Driver: bnx2 - Broadcom NetXtremeII

File: bnx2/bnx2-mips-06-4.6.16.fw
File: bnx2/bnx2-mips-06-5.0.0.j3.fw
File: bnx2/bnx2-mips-06-5.0.0.j6.fw
File: bnx2/bnx2-mips-06-6.0.15.fw
File: bnx2/bnx2-mips-06-6.2.1.fw
File: bnx2/bnx2-mips-06-6.2.3.fw
File: bnx2/bnx2-mips-09-4.6.17.fw
File: bnx2/bnx2-mips-09-5.0.0.j3.fw
File: bnx2/bnx2-mips-09-5.0.0.j9.fw
File: bnx2/bnx2-mips-09-5.0.0.j15.fw
File: bnx2/bnx2-mips-09-6.0.17.fw
File: bnx2/bnx2-mips-09-6.2.1.fw
File: bnx2/bnx2-mips-09-6.2.1a.fw
File: bnx2/bnx2-mips-09-6.2.1b.fw
File: bnx2/bnx2-rv2p-06-4.6.16.fw

File: bnx2/bnx2-rv2p-06-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-06-6.0.15.fw
File: bnx2/bnx2-rv2p-09-4.6.15.fw
File: bnx2/bnx2-rv2p-09-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-09-5.0.0.j10.fw
File: bnx2/bnx2-rv2p-09-6.0.17.fw
File: bnx2/bnx2-rv2p-09ax-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-09ax-5.0.0.j10.fw
File: bnx2/bnx2-rv2p-09ax-6.0.17.fw

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Driver: netxen_nic - NetXen Multi port (1/10) Gigabit Ethernet NIC

File: phanfw.bin
Version: 4.0.590

Licence: Redistributable. See LICENCE.phanfw for details.

Available from http://ldriver.qlogic.com/firmware/netxen_nic/new/

Driver: dvb-ttpci -- AV7110 cards

File: av7110/bootcode.bin
Source: av7110/Boot.S
Source: av7110/Makefile

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

ARM assembly source code from https://linuxtv.org/downloads/firmware/Boot.S

Driver: snd-wavefront - ISA WaveFront sound card

File: yamaha/yss225_registers.bin

Licence: Allegedly GPLv2+, but no source visible.

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Driver: rt61pci - Ralink RT2561, RT2561S, RT2661 wireless MACs

File: rt2561.bin
File: rt2561s.bin
File: rt2661.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Downloaded from http://www.ralinktech.com/ralink/Home/Support/Linux.html

---

Driver: rt73usb - Ralink RT2571W, RT2671 wireless MACs

File: rt73.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Downloaded from http://www.ralinktech.com/ralink/Home/Support/Linux.html

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Driver: mt7601u - MediaTek MT7601U Wireless MACs

File: mt7601u.bin
Version: 34

Licence: Redistributable. See LICENCE.ralink_a_mediatek_company_firmware for details

Downloaded from http://www.mediatek.com/en/downloads/

Driver: rt2800pci - Ralink RT2860, RT2890, RT3090, RT3290, RT5390 wireless MACs

File: rt2860.bin
Version: 40

File: rt3290.bin
Version: 37

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Binary file supplied originally by Shiang Tu <shiang_tu@ralinktech.com>, latest from http://www.mediatek.com/en/downloads1/downloads/

Driver: rt2860sta - Ralink RT3090 wireless MACs

Link: rt3090.bin -> rt2860.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

---

Driver: rt2800usb - Ralink RT2870, RT3070, RT3071, RT3072, RT5370 wireless MACs

File: rt2870.bin
Version: 36

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Binary file supplied originally by Shiang Tu <shiang_tu@ralinktech.com>, latest
from http://www.mediatek.com/en/downloads1/downloads/

Driver: rt2870sta - Ralink RT2870, RT3070, RT3071 wireless MACs

Link: rt3070.bin -> rt2870.bin
File: rt3071.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

rt3071.bin is a copy of bytes 4096-8191 of rt2870.bin for compatibility.

Driver: usbdux/usbduxfast/usbduxsigma - usbdux data acquisition cards

File: usbdux_firmware.bin
File: usbduxfast_firmware.bin
File: usbduxsigma_firmware.bin
Source: usbdux/

Licence: GPLv2. See GPL-2 for details.

Provided from the author, Bernd Porr <BerndPorr@f2s.com>

Driver: xc4000 - Xceive 4000 Tuner driver

File: dvb-fe-xc4000-1.4.1.fw
Version: 1.4.1

Licence: Redistributable. See LICENCE.xc4000 for details

Driver: xc5000 - Xceive 5000 Tuner driver

File: dvb-fe-xc5000-1.6.114.fw
Version: 1.6.114

File: dvb-fe-xc5000c-4.1.30.7.fw
Version: 4.1.30.7

Licence: Redistributable. See LICENCE.xc5000 and LICENCE.xc5000c for details

---

Driver: dib0700 - DiBcom dib0700 USB DVB bridge driver

File: dvb-usb-dib0700-1.20.fw
Version: 1.20

Licence: Redistributable. See LICENSE.dib0700 for details

Driver: ath3k - DFU Driver for Atheros bluetooth chipset AR3011

File: ath3k-1.fw
Version: 1.0

Fix EEPROM radio table issue and change PID to 3005

Licence: Redistributable. See LICENCE.atheros_firmware for details

---

Driver: mga - Matrox G200/G400/G550

File: matrox/g200_warp.fw
File: matrox/g400_warp.fw

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Found in hex form in kernel source.

Driver: r128 - ATI Rage 128

File: r128/r128_cce.bin

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```

Found in decimal form in kernel source.

Driver: radeon - ATI Radeon

File: radeon/R100_cp.bin
File: radeon/R200_cp.bin
File: radeon/R300_cp.bin
File: radeon/R420_cp.bin
File: radeon/RS600_cp.bin
File: radeon/RS690_cp.bin
File: radeon/R520_cp.bin
File: radeon/R600_pfp.bin
File: radeon/R600_me.bin
File: radeon/RV610_pfp.bin
File: radeon/RV610_me.bin
File: radeon/RV630_pfp.bin
File: radeon/RV630_me.bin
File: radeon/RV620_pfp.bin
File: radeon/RV620_me.bin
File: radeon/RV635_pfp.bin
File: radeon/RV635_me.bin
File: radeon/RV670_pfp.bin
File: radeon/RV670_me.bin
File: radeon/RS780_pfp.bin
File: radeon/RS780_me.bin
File: radeon/RV770_pfp.bin
File: radeon/RV770_me.bin
File: radeon/RV730_pfp.bin
File: radeon/RV730_me.bin
File: radeon/RV710_pfp.bin
File: radeon/RV710_me.bin

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```

Found in hex form in kernel source.

Driver: radeon - ATI Radeon

File: radeon/R600_rlc.bin
File: radeon/R600_uvd.bin
File: radeon/RS780_uvd.bin
File: radeon/R700_rlc.bin
File: radeon/RV710_uvd.bin
File: radeon/RV710_smc.bin
File: radeon/RV730_smc.bin
File: radeon/RV740_smc.bin
File: radeon/RV770_smc.bin
File: radeon/RV770_uvd.bin
File: radeon/CEDAR_me.bin
File: radeon/CEDAR_pfp.bin
File: radeon/CEDAR_rlc.bin
File: radeon/CEDAR_smc.bin
File: radeon/CYPRESS_me.bin
File: radeon/CYPRESS_pfp.bin
File: radeon/CYPRESS_rlc.bin
File: radeon/CYPRESS_uvd.bin
File: radeon/CYPRESS_smc.bin
File: radeon/JUNIPER_me.bin
File: radeon/JUNIPER_pfp.bin
File: radeon/JUNIPER_rlc.bin
File: radeon/JUNIPER_smc.bin
File: radeon/REDWOOD_me.bin
File: radeon/REDWOOD_pfp.bin
File: radeon/REDWOOD_rlc.bin
File: radeon/REDWOOD_smc.bin

File: radeon/PALM_me.bin
File: radeon/PALM_pfp.bin
File: radeon/SUMO_rlc.bin
File: radeon/SUMO_uvd.bin
File: radeon/BARTS_mc.bin
File: radeon/BARTS_me.bin
File: radeon/BARTS_pfp.bin
File: radeon/BARTS_smc.bin
File: radeon/BTC_rlc.bin
File: radeon/CAICOS_mc.bin
File: radeon/CAICOS_me.bin
File: radeon/CAICOS_pfp.bin
File: radeon/CAICOS_smc.bin
File: radeon/TURKS_mc.bin
File: radeon/TURKS_me.bin
File: radeon/TURKS_pfp.bin
File: radeon/TURKS_smc.bin
File: radeon/CAYMAN_mc.bin
File: radeon/CAYMAN_me.bin
File: radeon/CAYMAN_pfp.bin
File: radeon/CAYMAN_rlc.bin
File: radeon/CAYMAN_smc.bin
File: radeon/SUMO_pfp.bin
File: radeon/SUMO_me.bin
File: radeon/SUMO2_pfp.bin
File: radeon/SUMO2_me.bin
File: radeon/ARUBA_me.bin
File: radeon/ARUBA_pfp.bin
File: radeon/ARUBA_rlc.bin
File: radeon/PITCAIRN_ce.bin
File: radeon/PITCAIRN_mc.bin
File: radeon/PITCAIRN_mc2.bin
File: radeon/PITCAIRN_me.bin
File: radeon/PITCAIRN_pfp.bin
File: radeon/PITCAIRN_rlc.bin
File: radeon/PITCAIRN_smc.bin
File: radeon/TAHITI_ce.bin
File: radeon/TAHITI_mc.bin
File: radeon/TAHITI_mc2.bin
File: radeon/TAHITI_me.bin
File: radeon/TAHITI_pfp.bin
File: radeon/TAHITI_rlc.bin
File: radeon/TAHITI_uvd.bin
File: radeon/TAHITI_smc.bin
File: radeon/TAHITI_vce.bin
File: radeon/VERDE_ce.bin
File: radeon/VERDE_mc.bin
File: radeon/VERDE_mc2.bin
File: radeon/VERDE_me.bin
File: radeon/VERDE_pfp.bin
File: radeon/VERDE_rlc.bin
File: radeon/VERDE_smc.bin
File: radeon/OLAND_ce.bin
File: radeon/OLAND_mc.bin
File: radeon/OLAND_mc2.bin
File: radeon/OLAND_me.bin
File: radeon/OLAND_pfp.bin

File: radeon/OLAND_rlc.bin
File: radeon/OLAND_smc.bin
File: radeon/HAINAN_ce.bin
File: radeon/HAINAN_mc.bin
File: radeon/HAINAN_mc2.bin
File: radeon/HAINAN_me.bin
File: radeon/HAINAN_pfp.bin
File: radeon/HAINAN_rlc.bin
File: radeon/HAINAN_smc.bin
File: radeon/BONAIRE_ce.bin
File: radeon/BONAIRE_mc.bin
File: radeon/BONAIRE_mc2.bin
File: radeon/BONAIRE_me.bin
File: radeon/BONAIRE_mec.bin
File: radeon/BONAIRE_pfp.bin
File: radeon/BONAIRE_rlc.bin
File: radeon/BONAIRE_sdma.bin
File: radeon/BONAIRE_uvd.bin
File: radeon/BONAIRE_smc.bin
File: radeon/BONAIRE_vce.bin
File: radeon/KABINI_ce.bin
File: radeon/KABINI_me.bin
File: radeon/KABINI_mec.bin
File: radeon/KABINI_pfp.bin
File: radeon/KABINI_rlc.bin
File: radeon/KABINI_sdma.bin
File: radeon/KAVERI_ce.bin
File: radeon/KAVERI_me.bin
File: radeon/KAVERI_mec.bin
File: radeon/KAVERI_pfp.bin
File: radeon/KAVERI_rlc.bin
File: radeon/KAVERI_sdma.bin
File: radeon/HAWAII_ce.bin
File: radeon/HAWAII_mc.bin
File: radeon/HAWAII_mc2.bin
File: radeon/HAWAII_me.bin
File: radeon/HAWAII_mec.bin
File: radeon/HAWAII_pfp.bin
File: radeon/HAWAII_rlc.bin
File: radeon/HAWAII_sdma.bin
File: radeon/HAWAII_smc.bin
File: radeon/MULLINS_ce.bin
File: radeon/MULLINS_me.bin
File: radeon/MULLINS_mec.bin
File: radeon/MULLINS_pfp.bin
File: radeon/MULLINS_rlc.bin
File: radeon/MULLINS_sdma.bin
File: radeon/pitcairn_ce.bin
File: radeon/pitcairn_k_smc.bin
File: radeon/pitcairn_mc.bin
File: radeon/pitcairn_me.bin
File: radeon/pitcairn_pfp.bin
File: radeon/pitcairn_rlc.bin
File: radeon/pitcairn_smc.bin
File: radeon/tahiti_ce.bin
File: radeon/tahiti_k_smc.bin
File: radeon/tahiti_mc.bin

File: radeon/tahiti_me.bin
File: radeon/tahiti_pfp.bin
File: radeon/tahiti_rlc.bin
File: radeon/tahiti_smc.bin
File: radeon/verde_ce.bin
File: radeon/verde_k_smc.bin
File: radeon/verde_mc.bin
File: radeon/verde_me.bin
File: radeon/verde_pfp.bin
File: radeon/verde_rlc.bin
File: radeon/verde_smc.bin
File: radeon/oland_ce.bin
File: radeon/oland_k_smc.bin
File: radeon/oland_mc.bin
File: radeon/oland_me.bin
File: radeon/oland_pfp.bin
File: radeon/oland_rlc.bin
File: radeon/oland_smc.bin
File: radeon/hainan_ce.bin
File: radeon/hainan_k_smc.bin
File: radeon/hainan_mc.bin
File: radeon/hainan_me.bin
File: radeon/hainan_pfp.bin
File: radeon/hainan_rlc.bin
File: radeon/hainan_smc.bin
File: radeon/bonaire_ce.bin
File: radeon/bonaire_k_smc.bin
File: radeon/bonaire_mc.bin
File: radeon/bonaire_me.bin
File: radeon/bonaire_mec.bin
File: radeon/bonaire_pfp.bin
File: radeon/bonaire_rlc.bin
File: radeon/bonaire_sdma.bin
File: radeon/bonaire_sdma1.bin
File: radeon/bonaire_smc.bin
File: radeon/bonaire_uvd.bin
File: radeon/bonaire_vce.bin
File: radeon/kabini_ce.bin
File: radeon/kabini_me.bin
File: radeon/kabini_mec.bin
File: radeon/kabini_pfp.bin
File: radeon/kabini_rlc.bin
File: radeon/kabini_sdma.bin
File: radeon/kabini_sdma1.bin
File: radeon/kabini_uvd.bin
File: radeon/kabini_vce.bin
File: radeon/kaveri_ce.bin
File: radeon/kaveri_me.bin
File: radeon/kaveri_mec.bin
File: radeon/kaveri_mec2.bin
File: radeon/kaveri_pfp.bin
File: radeon/kaveri_rlc.bin
File: radeon/kaveri_sdma.bin
File: radeon/kaveri_sdma1.bin
File: radeon/kaveri_uvd.bin
File: radeon/kaveri_vce.bin
File: radeon/hawaii_ce.bin

File: radeon/hawaii_k_smc.bin
File: radeon/hawaii_mc.bin
File: radeon/hawaii_me.bin
File: radeon/hawaii_mec.bin
File: radeon/hawaii_pfp.bin
File: radeon/hawaii_rlc.bin
File: radeon/hawaii_sdma.bin
File: radeon/hawaii_sdma1.bin
File: radeon/hawaii_smc.bin
File: radeon/hawaii_uvd.bin
File: radeon/hawaii_vce.bin
File: radeon/mullins_ce.bin
File: radeon/mullins_me.bin
File: radeon/mullins_mec.bin
File: radeon/mullins_pfp.bin
File: radeon/mullins_rlc.bin
File: radeon/mullins_sdma.bin
File: radeon/mullins_sdma1.bin
File: radeon/mullins_uvd.bin
File: radeon/mullins_vce.bin
File: radeon/banks_k_2_smc.bin
File: radeon/si58_mc.bin

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Driver: amdgpu - AMD Radeon

File: amdgpu/tahiti_ce.bin
File: amdgpu/tahiti_k_smc.bin
File: amdgpu/tahiti_mc.bin
File: amdgpu/tahiti_me.bin
File: amdgpu/tahiti_pfp.bin
File: amdgpu/tahiti_rlc.bin
File: amdgpu/tahiti_smc.bin
File: amdgpu/pitcairn_ce.bin
File: amdgpu/pitcairn_k_smc.bin
File: amdgpu/pitcairn_mc.bin
File: amdgpu/pitcairn_me.bin
File: amdgpu/pitcairn_pfp.bin
File: amdgpu/pitcairn_rlc.bin
File: amdgpu/pitcairn_smc.bin
File: amdgpu/verde_ce.bin
File: amdgpu/verde_k_smc.bin
File: amdgpu/verde_mc.bin
File: amdgpu/verde_me.bin
File: amdgpu/verde_pfp.bin
File: amdgpu/verde_rlc.bin
File: amdgpu/verde_smc.bin
File: amdgpu/hainan_ce.bin
File: amdgpu/hainan_k_smc.bin
File: amdgpu/hainan_mc.bin
File: amdgpu/hainan_me.bin
File: amdgpu/hainan_pfp.bin
File: amdgpu/hainan_rlc.bin
File: amdgpu/hainan_smc.bin

File: amdgpu/oland_ce.bin
File: amdgpu/oland_k_smc.bin
File: amdgpu/oland_mc.bin
File: amdgpu/oland_me.bin
File: amdgpu/oland_pfp.bin
File: amdgpu/oland_rlc.bin
File: amdgpu/oland_smc.bin
File: amdgpu/si58_mc.bin
File: amdgpu/banks_k_2_smc.bin
File: amdgpu/bonaire_ce.bin
File: amdgpu/bonaire_k_smc.bin
File: amdgpu/bonaire_mc.bin
File: amdgpu/bonaire_me.bin
File: amdgpu/bonaire_mec.bin
File: amdgpu/bonaire_pfp.bin
File: amdgpu/bonaire_rlc.bin
File: amdgpu/bonaire_sdma.bin
File: amdgpu/bonaire_sdma1.bin
File: amdgpu/bonaire_smc.bin
File: amdgpu/bonaire_uvd.bin
File: amdgpu/bonaire_vce.bin
File: amdgpu/hawaii_ce.bin
File: amdgpu/hawaii_k_smc.bin
File: amdgpu/hawaii_mc.bin
File: amdgpu/hawaii_me.bin
File: amdgpu/hawaii_mec.bin
File: amdgpu/hawaii_pfp.bin
File: amdgpu/hawaii_rlc.bin
File: amdgpu/hawaii_sdma.bin
File: amdgpu/hawaii_sdma1.bin
File: amdgpu/hawaii_smc.bin
File: amdgpu/hawaii_uvd.bin
File: amdgpu/hawaii_vce.bin
File: amdgpu/kabini_ce.bin
File: amdgpu/kabini_me.bin
File: amdgpu/kabini_mec.bin
File: amdgpu/kabini_pfp.bin
File: amdgpu/kabini_rlc.bin
File: amdgpu/kabini_sdma.bin
File: amdgpu/kabini_sdma1.bin
File: amdgpu/kabini_uvd.bin
File: amdgpu/kabini_vce.bin
File: amdgpu/mullins_ce.bin
File: amdgpu/mullins_me.bin
File: amdgpu/mullins_mec.bin
File: amdgpu/mullins_pfp.bin
File: amdgpu/mullins_rlc.bin
File: amdgpu/mullins_sdma.bin
File: amdgpu/mullins_sdma1.bin
File: amdgpu/mullins_uvd.bin
File: amdgpu/mullins_vce.bin
File: amdgpu/kaveri_ce.bin
File: amdgpu/kaveri_me.bin
File: amdgpu/kaveri_mec.bin
File: amdgpu/kaveri_mec2.bin
File: amdgpu/kaveri_pfp.bin
File: amdgpu/kaveri_rlc.bin

File: amdgpu/kaveri_sdma.bin
File: amdgpu/kaveri_sdma1.bin
File: amdgpu/kaveri_uvd.bin
File: amdgpu/kaveri_vce.bin
File: amdgpu/topaz_ce.bin
File: amdgpu/topaz_k_smc.bin
File: amdgpu/topaz_mc.bin
File: amdgpu/topaz_me.bin
File: amdgpu/topaz_mec2.bin
File: amdgpu/topaz_mec.bin
File: amdgpu/topaz_pfp.bin
File: amdgpu/topaz_rlc.bin
File: amdgpu/topaz_sdma1.bin
File: amdgpu/topaz_sdma.bin
File: amdgpu/topaz_smc.bin
File: amdgpu/tonga_ce.bin
File: amdgpu/tonga_k_smc.bin
File: amdgpu/tonga_mc.bin
File: amdgpu/tonga_me.bin
File: amdgpu/tonga_mec2.bin
File: amdgpu/tonga_mec.bin
File: amdgpu/tonga_pfp.bin
File: amdgpu/tonga_rlc.bin
File: amdgpu/tonga_sdma1.bin
File: amdgpu/tonga_sdma.bin
File: amdgpu/tonga_smc.bin
File: amdgpu/tonga_uvd.bin
File: amdgpu/tonga_vce.bin
File: amdgpu/carrizo_ce.bin
File: amdgpu/carrizo_me.bin
File: amdgpu/carrizo_mec2.bin
File: amdgpu/carrizo_mec.bin
File: amdgpu/carrizo_pfp.bin
File: amdgpu/carrizo_rlc.bin
File: amdgpu/carrizo_sdma1.bin
File: amdgpu/carrizo_sdma.bin
File: amdgpu/carrizo_uvd.bin
File: amdgpu/carrizo_vce.bin
File: amdgpu/fiji_ce.bin
File: amdgpu/fiji_mc.bin
File: amdgpu/fiji_me.bin
File: amdgpu/fiji_mec2.bin
File: amdgpu/fiji_mec.bin
File: amdgpu/fiji_pfp.bin
File: amdgpu/fiji_rlc.bin
File: amdgpu/fiji_sdma1.bin
File: amdgpu/fiji_sdma.bin
File: amdgpu/fiji_smc.bin
File: amdgpu/fiji_uvd.bin
File: amdgpu/fiji_vce.bin
File: amdgpu/stoney_ce.bin
File: amdgpu/stoney_me.bin
File: amdgpu/stoney_mec.bin
File: amdgpu/stoney_pfp.bin
File: amdgpu/stoney_rlc.bin
File: amdgpu/stoney_sdma.bin
File: amdgpu/stoney_uvd.bin

File: amdgpu/stoney_vce.bin
File: amdgpu/polaris10_ce.bin
File: amdgpu/polaris10_ce_2.bin
File: amdgpu/polaris10_mc.bin
File: amdgpu/polaris10_k_mc.bin
File: amdgpu/polaris10_me.bin
File: amdgpu/polaris10_me_2.bin
File: amdgpu/polaris10_mec2.bin
File: amdgpu/polaris10_mec2_2.bin
File: amdgpu/polaris10_mec.bin
File: amdgpu/polaris10_mec_2.bin
File: amdgpu/polaris10_pfp.bin
File: amdgpu/polaris10_pfp_2.bin
File: amdgpu/polaris10_rlc.bin
File: amdgpu/polaris10_sdma1.bin
File: amdgpu/polaris10_sdma.bin
File: amdgpu/polaris10_smc.bin
File: amdgpu/polaris10_k_smc.bin
File: amdgpu/polaris10_k2_smc.bin
File: amdgpu/polaris10_smc_sk.bin
File: amdgpu/polaris10_uvd.bin
File: amdgpu/polaris10_vce.bin
File: amdgpu/polaris11_ce.bin
File: amdgpu/polaris11_ce_2.bin
File: amdgpu/polaris11_mc.bin
File: amdgpu/polaris11_k_mc.bin
File: amdgpu/polaris11_me.bin
File: amdgpu/polaris11_me_2.bin
File: amdgpu/polaris11_mec2.bin
File: amdgpu/polaris11_mec2_2.bin
File: amdgpu/polaris11_mec.bin
File: amdgpu/polaris11_mec_2.bin
File: amdgpu/polaris11_pfp.bin
File: amdgpu/polaris11_pfp_2.bin
File: amdgpu/polaris11_rlc.bin
File: amdgpu/polaris11_sdma1.bin
File: amdgpu/polaris11_sdma.bin
File: amdgpu/polaris11_smc.bin
File: amdgpu/polaris11_k_smc.bin
File: amdgpu/polaris11_k2_smc.bin
File: amdgpu/polaris11_smc_sk.bin
File: amdgpu/polaris11_uvd.bin
File: amdgpu/polaris11_vce.bin
File: amdgpu/polaris12_ce.bin
File: amdgpu/polaris12_ce_2.bin
File: amdgpu/polaris12_mc.bin
File: amdgpu/polaris12_k_mc.bin
File: amdgpu/polaris12_me.bin
File: amdgpu/polaris12_me_2.bin
File: amdgpu/polaris12_mec.bin
File: amdgpu/polaris12_mec_2.bin
File: amdgpu/polaris12_mec2.bin
File: amdgpu/polaris12_mec2_2.bin
File: amdgpu/polaris12_pfp.bin
File: amdgpu/polaris12_pfp_2.bin
File: amdgpu/polaris12_rlc.bin
File: amdgpu/polaris12_sdma.bin

File: amdgpu/polaris12_sdma1.bin
File: amdgpu/polaris12_smc.bin
File: amdgpu/polaris12_k_smc.bin
File: amdgpu/polaris12_uvd.bin
File: amdgpu/polaris12_vce.bin
File: amdgpu/vegam_ce.bin
File: amdgpu/vegam_me.bin
File: amdgpu/vegam_mec.bin
File: amdgpu/vegam_mec2.bin
File: amdgpu/vegam_pfp.bin
File: amdgpu/vegam_rlc.bin
File: amdgpu/vegam_sdma.bin
File: amdgpu/vegam_sdma1.bin
File: amdgpu/vegam_smc.bin
File: amdgpu/vegam_uvd.bin
File: amdgpu/vegam_vce.bin
File: amdgpu/vega10_acg_smc.bin
File: amdgpu/vega10_asd.bin
File: amdgpu/vega10_ce.bin
File: amdgpu/vega10_gpu_info.bin
File: amdgpu/vega10_me.bin
File: amdgpu/vega10_mec.bin
File: amdgpu/vega10_mec2.bin
File: amdgpu/vega10_pfp.bin
File: amdgpu/vega10_rlc.bin
File: amdgpu/vega10_sdma.bin
File: amdgpu/vega10_sdma1.bin
File: amdgpu/vega10_smc.bin
File: amdgpu/vega10_sos.bin
File: amdgpu/vega10_uvd.bin
File: amdgpu/vega10_vce.bin
File: amdgpu/vega12_asd.bin
File: amdgpu/vega12_ce.bin
File: amdgpu/vega12_gpu_info.bin
File: amdgpu/vega12_me.bin
File: amdgpu/vega12_mec.bin
File: amdgpu/vega12_mec2.bin
File: amdgpu/vega12_pfp.bin
File: amdgpu/vega12_rlc.bin
File: amdgpu/vega12_sdma.bin
File: amdgpu/vega12_sdma1.bin
File: amdgpu/vega12_smc.bin
File: amdgpu/vega12_sos.bin
File: amdgpu/vega12_uvd.bin
File: amdgpu/vega12_vce.bin
File: amdgpu/vega20_asd.bin
File: amdgpu/vega20_ce.bin
File: amdgpu/vega20_me.bin
File: amdgpu/vega20_mec.bin
File: amdgpu/vega20_mec2.bin
File: amdgpu/vega20_pfp.bin
File: amdgpu/vega20_rlc.bin
File: amdgpu/vega20_sdma.bin
File: amdgpu/vega20_sdma1.bin
File: amdgpu/vega20_smc.bin
File: amdgpu/vega20_sos.bin
File: amdgpu/vega20_uvd.bin

File: amdgpu/vega20_vce.bin
File: amdgpu/raven_asd.bin
File: amdgpu/raven_ce.bin
File: amdgpu/raven_gpu_info.bin
File: amdgpu/raven_me.bin
File: amdgpu/raven_mec.bin
File: amdgpu/raven_mec2.bin
File: amdgpu/raven_pfp.bin
File: amdgpu/raven_rlc.bin
File: amdgpu/raven_sdma.bin
File: amdgpu/raven_vcn.bin
File: amdgpu/raven_dmcu.bin
File: amdgpu/picasso_asd.bin
File: amdgpu/picasso_ce.bin
File: amdgpu/picasso_gpu_info.bin
File: amdgpu/picasso_me.bin
File: amdgpu/picasso_mec.bin
File: amdgpu/picasso_mec2.bin
File: amdgpu/picasso_pfp.bin
File: amdgpu/picasso_rlc.bin
File: amdgpu/picasso_rlc_am4.bin
File: amdgpu/picasso_sdma.bin
File: amdgpu/picasso_vcn.bin
File: amdgpu/raven2_asd.bin
File: amdgpu/raven2_ce.bin
File: amdgpu/raven2_gpu_info.bin
File: amdgpu/raven2_me.bin
File: amdgpu/raven2_mec.bin
File: amdgpu/raven2_mec2.bin
File: amdgpu/raven2_pfp.bin
File: amdgpu/raven2_rlc.bin
File: amdgpu/raven2_sdma.bin
File: amdgpu/raven2_vcn.bin

Licence: Redistributable. See LICENSE.amdgpu for details.

Driver: s2255drv

File: f2255usb.bin
Version: 1.2.8

Licence: Redistributable.

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Driver: rtl8192e - Realtek 8192 PCI wireless driver

File: RTL8192E/boot.img
File: RTL8192E/data.img
File: RTL8192E/main.img

Licence: Redistributable, provided by Realtek in their driver
source download.

Driver: lgs8gxx - Legend Silicon GB20600 demodulator driver

File: lgs8g75.fw

Licence: Unknown

Driver: ib_qib - QLogic Infiniband

File: qlogic/sd7220.fw

Licence:

```
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```

Found in hex form in kernel source.

Driver: qed - QLogic 4xxxx Ethernet Driver Core Module.

File: qed/qed_init_values_zipped-8.4.2.0.bin
File: qed/qed_init_values_zipped-8.7.3.0.bin
File: qed/qed_init_values_zipped-8.10.5.0.bin
File: qed/qed_init_values-8.10.9.0.bin
File: qed/qed_init_values_zipped-8.10.10.0.bin
File: qed/qed_init_values-8.14.6.0.bin
File: qed/qed_init_values_zipped-8.15.3.0.bin
File: qed/qed_init_values-8.18.9.0.bin
File: qed/qed_init_values_zipped-8.20.0.0.bin
File: qed/qed_init_values-8.20.0.0.bin
File: qed/qed_init_values-8.30.12.0.bin
File: qed/qed_init_values_zipped-8.33.1.0.bin
File: qed/qed_init_values_zipped-8.33.11.0.bin
File: qed/qed_init_values-8.33.12.0.bin
File: qed/qed_init_values_zipped-8.37.2.0.bin
File: qed/qed_init_values_zipped-8.37.7.0.bin
File: qed/qed_init_values-8.37.7.0.bin

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Driver: ueagle-atm - Driver for USB ADSL Modems based on Eagle IV Chipset

File: ueagle-atm/CMV4p.bin.v2
File: ueagle-atm/DSP4p.bin
File: ueagle-atm/eagleIV.fw
Version: 1.0

Licence: Redistributable. See LICENCE.ueagle-atm4-firmware for details

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Driver: ueagle-atm - Driver for USB ADSL Modems based on Eagle I,II,III

File: ueagle-atm/930-fpga.bin
File: ueagle-atm/CMVeiWO.bin
File: ueagle-atm/CMVepFR10.bin
File: ueagle-atm/DSP9p.bin
File: ueagle-atm/eagleIII.fw
File: ueagle-atm/adi930.fw
File: ueagle-atm/CMVep.bin
File: ueagle-atm/CMVepFR.bin
File: ueagle-atm/DSPei.bin
File: ueagle-atm/CMV9i.bin
File: ueagle-atm/CMVepES03.bin
File: ueagle-atm/CMVepIT.bin
File: ueagle-atm/DSPep.bin

File: ueagle-atm/CMV9p.bin
File: ueagle-atm/CMVepES.bin
File: ueagle-atm/CMVepWO.bin
File: ueagle-atm/eagleI.fw
File: ueagle-atm/CMVei.bin
File: ueagle-atm/CMVepFR04.bin
File: ueagle-atm/DSP9i.bin
File: ueagle-atm/eagleII.fw
Version: 1.1

Licence: Redistributable. Based on
https://mail.gna.org/public/eagleusb-dev/2004-11/msg00172.html

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Driver: vxge - Exar X3100 Series 10GbE PCIe I/O Virtualized Server Adapter

File: vxge/X3fw.ncf
File: vxge/X3fw-pxe.ncf
Version: 1.8.1

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Driver: brcmsmac - Broadcom 802.11n softmac wireless LAN driver.

File: brcm/bcm43xx-0.fw
File: brcm/bcm43xx_hdr-0.fw
Version: 610.812

Licence: Redistributable. See LICENCE.broadcom_bcm43xx for details.

Driver: brcmfmac - Broadcom 802.11n fullmac wireless LAN driver.

File: brcm/bcm4329-fullmac-4.bin
File: brcm/brcmfmac43236b.bin
File: brcm/brcmfmac4329-sdio.bin
File: brcm/brcmfmac4330-sdio.bin
File: brcm/brcmfmac4334-sdio.bin
File: brcm/brcmfmac4335-sdio.bin
File: brcm/brcmfmac4339-sdio.bin
File: brcm/brcmfmac43241b0-sdio.bin
File: brcm/brcmfmac43241b4-sdio.bin
File: brcm/brcmfmac43241b5-sdio.bin
File: brcm/brcmfmac43242a.bin
File: brcm/brcmfmac43143.bin
File: brcm/brcmfmac43143-sdio.bin

File: brcm/brcmfmac43430a0-sdio.bin
File: brcm/brcmfmac43455-sdio.bin
File: brcm/brcmfmac4350c2-pcie.bin
File: brcm/brcmfmac4350-pcie.bin
File: brcm/brcmfmac4356-sdio.bin
File: brcm/brcmfmac43569.bin
File: brcm/brcmfmac43570-pcie.bin
File: brcm/brcmfmac4358-pcie.bin
File: brcm/brcmfmac43602-pcie.bin
File: brcm/brcmfmac43602-pcie.ap.bin
File: brcm/brcmfmac4366b-pcie.bin
File: brcm/brcmfmac4366c-pcie.bin
File: brcm/brcmfmac4371-pcie.bin

Licence: Redistributable. See LICENCE.broadcom_bcm43xx for details.

File: brcm/brcmfmac43340-sdio.bin
File: brcm/brcmfmac43362-sdio.bin
File: brcm/brcmfmac43430-sdio.bin
File: brcm/brcmfmac4354-sdio.bin
File: brcm/brcmfmac4356-pcie.bin
File: brcm/brcmfmac4373-sdio.bin
File: brcm/brcmfmac4373.bin

Licence: Redistributable. See LICENCE.cypress for details.

File: "brcm/brcmfmac4330-sdio.Prowise-PT301.txt"
File: "brcm/brcmfmac43340-sdio.meegopad-t08.txt"
File: "brcm/brcmfmac43362-sdio.cubietech,cubietruck.txt"
File: "brcm/brcmfmac43362-sdio.lemaker,bananapro.txt"
File: "brcm/brcmfmac43430a0-sdio.jumper-ezpad-mini3.txt"
File: "brcm/brcmfmac43430a0-sdio.ONDA-V80 PLUS.txt"
File: "brcm/brcmfmac43430-sdio.AP6212.txt"
File: "brcm/brcmfmac43430-sdio.Hampoo-D2D3_Vi8A1.txt"
File: "brcm/brcmfmac43430-sdio.MUR1DX.txt"
File: "brcm/brcmfmac43430-sdio.raspberrypi,3-model-b.txt"
File: "brcm/brcmfmac43455-sdio.raspberrypi,3-model-b-plus.txt"
File: "brcm/brcmfmac4356-pcie.gpd-win-pocket.txt"

Licence: GPLv2. See GPL-2 for details.

Driver: tda7706 - FM radio Highly integrated tuner for AM/FM car-radio

File: TDA7706_OM_v2.5.1_boot.txt
File: TDA7706_OM_v3.0.2_boot.txt

Licence: Redistributable. See LICENCE.tda7706-firmware.txt for details.
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Driver: wl1251 - Texas Instruments 802.11 WLAN driver for WiLink4 chips

File: ti-connectivity/wl1251-fw.bin
Version: 4.0.4.3.7

File: ti-connectivity/wl1251-nvs.bin

Licence: Redistributable. See LICENCE.wl1251 for details.

The published NVS files are for testing only. Every device needs to
have a unique NVS which is properly calibrated for best results.

The driver expects to find the firmwares under a ti-connectivity subdirectory.
So if your system looks for firmwares in /lib/firmware, the firmwares for
wl12xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: wl12xx - Texas Instruments 802.11 WLAN driver for WiLink6/7 chips

File: ti-connectivity/wl1271-fw.bin
Version: 6.1.0.50.350 (STA-only)
File: ti-connectivity/wl1271-fw-2.bin
Version: 6.1.5.50.74 (STA-only)
File: ti-connectivity/wl1271-fw-ap.bin
Version: 6.2.1.0.54 (AP-only)
File: ti-connectivity/wl127x-fw-3.bin
Version: 6.3.0.0.77
File: ti-connectivity/wl127x-fw-plt-3.bin
Version: 6.3.0.0.77 (PLT-only)
File: ti-connectivity/wl127x-fw-4-sr.bin
Version: 6.3.5.0.98 (Single-role)
File: ti-connectivity/wl127x-fw-4-mr.bin
Version: 6.5.2.0.15 (Multi-role)
File: ti-connectivity/wl127x-fw-4-plt.bin
Version: 6.3.5.0.98 (PLT-only)
File: ti-connectivity/wl127x-fw-5-sr.bin
Version: 6.3.10.0.142 (Single-role)
File: ti-connectivity/wl127x-fw-5-mr.bin
Version: 6.5.7.0.50 (Multi-role)
File: ti-connectivity/wl127x-fw-5-plt.bin
Version: 6.3.10.0.142 (PLT-only)

File: ti-connectivity/wl128x-fw.bin
Version: 7.1.5.50.74 (STA-only)
File: ti-connectivity/wl128x-fw-ap.bin
Version: 7.2.1.0.54 (AP-only)
File: ti-connectivity/wl128x-fw-3.bin
Version: 7.3.0.0.77
File: ti-connectivity/wl128x-fw-plt-3.bin
Version: 7.3.0.0.77
File: ti-connectivity/wl128x-fw-4-sr.bin
Version: 7.3.5.0.98 (Single-role)
File: ti-connectivity/wl128x-fw-4-mr.bin
Version: 7.5.2.0.15 (Multi-role)
File: ti-connectivity/wl128x-fw-4-plt.bin
Version: 7.3.5.0.98 (PLT)
File: ti-connectivity/wl128x-fw-5-sr.bin
Version: 7.3.10.0.142 (Single-role)

File: ti-connectivity/wl128x-fw-5-mr.bin
Version: 7.5.7.0.50 (Multi-role)
File: ti-connectivity/wl128x-fw-5-plt.bin
Version: 7.3.10.2.142 (PLT-only)

File: ti-connectivity/wl127x-nvs.bin
File: ti-connectivity/wl128x-nvs.bin
Link: ti-connectivity/wl12xx-nvs.bin -> wl127x-nvs.bin
Link: ti-connectivity/wl1271-nvs.bin -> wl127x-nvs.bin

Licence: Redistributable. See LICENCE.ti-connectivity for details.

The NVS file includes two parts:
- radio calibration
- HW configuration parameters (aka. INI values)

The published NVS files are for testing only. Every device needs to hava a unique NVS which is properly calibrated for best results. You can find more information about NVS generation for your device here:

http://wireless.kernel.org/en/users/Drivers/wl12xx/calibrator

If you're using a wl127x based device, use a symbolic link called wl1271-nvs.bin that links to the wl127x-nvs.bin file. If you are using wl128x, link to wl128x-nvs.bin instead.

The driver expects to find the firmwares under a ti-connectivity subdirectory. So if your system looks for firmwares in /lib/firmware, the firmwares for wl12xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: wl18xx - Texas Instruments 802.11 WLAN driver for WiLink8 chips

File: ti-connectivity/wl18xx-fw.bin
Version: 8.2.0.0.100
File: ti-connectivity/wl18xx-fw-2.bin
Version: 8.5.0.0.55
File: ti-connectivity/wl18xx-fw-3.bin
Version: 8.8.0.0.13
File: ti-connectivity/wl18xx-fw-4.bin
Version: 8.9.0.0.79

Licence: Redistributable. See LICENCE.ti-connectivity for details.

The driver expects to find the firmwares under a ti-connectivity subdirectory. So if your system looks for firmwares in /lib/firmware, the firmwares for wl18xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: TI_ST - Texas Instruments bluetooth driver

File: ti-connectivity/TIInit_6.2.31.bts
Version: 2.44 (TI_P31.123)

File: ti-connectivity/TIInit_6.6.15.bts
Version: 2.14 (TI_P6_15.93)
File: ti-connectivity/TIInit_7.2.31.bts

Licence: Redistributable. See LICENCE.ti-connectivity for details.

TIInit_7.2.31.bts version 7.2.31

In order to use that file copy it to /lib/firmware/ti-connectivity.

Driver: tlg2300 - Telgent 2300 V4L/DVB driver.

File: tlg2300_firmware.bin

Licence: Redistributable.

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Driver: r8712u - Realtek 802.11n WLAN driver for RTL8712U

File: rtlwifi/rtl8712u.bin
Info: From Vendor's rtl8712_8188_8191_8192SU_usb_linux_v7_0.20100831
Reverted rtl8188C_8192C_8192D_usb_linux_v3.4.2_3727.20120404

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192ce - Realtek 802.11n WLAN driver for RTL8192CE

File: rtlwifi/rtl8192cfw.bin
File: rtlwifi/rtl8192cfwU.bin
File: rtlwifi/rtl8192cfwU_B.bin
Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192cu - Realtek 802.11n WLAN driver for RTL8192CU

File: rtlwifi/rtl8192cufw.bin
File: rtlwifi/rtl8192cufw_A.bin
File: rtlwifi/rtl8192cufw_B.bin
File: rtlwifi/rtl8192cufw_TMSC.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192se - Realtek 802.11n WLAN driver for RTL8192SE

Info: updated from rtl_92ce_92se_92de_linux_mac80211_0004.0816.2011 driver version
File: rtlwifi/rtl8192sefw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192de - Realtek 802.11n WLAN driver for RTL8192DE

Info: Updated from Realtek version rtl_92ce_92se_92de_8723ae_linux_mac80211_0007.0809.2012
File: rtlwifi/rtl8192defw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723e - Realtek 802.11n WLAN driver for RTL8723E

Info: Taken from Realtek version rtl_92ce_92se_92de_8723ae_linux_mac80211_0007.0809.2012
File: rtlwifi/rtl8723fw.bin
File: rtlwifi/rtl8723fw_B.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723be - Realtek 802.11n WLAN driver for RTL8723BE

Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver
File: rtlwifi/rtl8723befw.bin
Info: Update to version 36 - Sent by Realtek
File: rtlwifi/rtl8723befw_36.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723de - Realtek 802.11ac WLAN driver for RTL8723DE

Info: Supplied by Vendor at https://github.com/pkshih/rtlwifi_rtl8723de
File: rtlwifi/rtl8723defw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: r8723au - Realtek 802.11n WLAN driver for RTL8723AU

Info: Taken from Realtek driver rtl8723A_WiFi_linux_v4.1.3_6044.20121224
    Firmware is embedded in the driver as data statements. This info
    has been extracted into a binary file.

File: rtlwifi/rtl8723aufw_A.bin
File: rtlwifi/rtl8723aufw_B.bin
File: rtlwifi/rtl8723aufw_B_NoBT.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8188ee - Realtek 802.11n WLAN driver for RTL8188EE

Info: Taken from Realtek version rtl_92ce_92se_92de_8723ae_88ee_linux_mac80211_0010.0109.2013
File: rtlwifi/rtl8188efw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8188eu - Realtek 802.11n WLAN driver for RTL8188EU

Info: Taken from Realtek version RTL8188EUS_linux_v4.1.4_6773.20130222
File: rtlwifi/rtl8188eufw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8821ae - Realtek 802.11n WLAN driver for RTL8821AE

Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver
File: rtlwifi/rtl8821aefw.bin
File: rtlwifi/rtl8821aefw_wowlan.bin
Info: Update to version 29 - Sent by Realtek
File: rtlwifi/rtl8821aefw_29.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8822be - Realtek 802.11n WLAN driver for RTL8822BE

Info: Sent to Larry Finger by Realtek engineer Ping-Ke Shih <pkshih@realtek.com>
File: rtlwifi/rtl8822befw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtw88 - Realtek 802.11ac WLAN driver for RTL8822BE and RTL8822CE

Info: Sent to Larry Finger by Realtek engineer Yan-Hsuan Chuang <yhchuang@realtek.com>
File: rtw88/rtw8822b_fw.bin
File: rtw88/rtw8822c_fw.bin
File: rtw88/rtw8822c_wow_fw.bin
File: rtw88/README

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192ee - Realtek 802.11n WLAN driver for RTL8192EE

Info: Initial version taken from Realtek version
rtl_92ce_92se_92de_8723ae_88ee_8723be_92ee_linux_mac80211_0017.1224.2013
Updated Jan. 14, 2015 with file added by Realtek to
http://github.com/lwfinger/rtlwifi_new.git.
File: rtlwifi/rtl8192eefw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723bs - Realtek 802.11n WLAN driver for RTL8723BS

Info: Firmware files extracted from data statements in Realtek driver
v4.3.5.5_12290.20140916_BTCOEX20140507-4E40.
File: rtlwifi/rtl8723bs_bt.bin
File: rtlwifi/rtl8723bs_nic.bin
File: rtlwifi/rtl8723bs_ap_wowlan.bin
File: rtlwifi/rtl8723bs_wowlan.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8xxxu - Realtek 802.11n WLAN driver for RTL8XXX USB devices

Info: rtl8723au taken from Realtek driver
rtl8723A_WiFi_linux_v4.1.3_6044.20121224
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8723aufw_A.bin
File: rtlwifi/rtl8723aufw_B.bin
File: rtlwifi/rtl8723aufw_B_NoBT.bin

Info: rtl8723bu taken from Realtek driver
rtl8723BU_WiFi_linux_v4.3.16_14189.20150519_BTCOEX20150119-5844
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8723bu_nic.bin
File: rtlwifi/rtl8723bu_wowlan.bin
File: rtlwifi/rtl8723bu_ap_wowlan.bin

Info: rtl8192eu taken from Realtek driver
rtl8192EU_linux_v4.3.1.1_11320.20140505
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8192eu_nic.bin
File: rtlwifi/rtl8192eu_wowlan.bin
File: rtlwifi/rtl8192eu_ap_wowlan.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: r8169 - RealTek 8169/8168/8101 ethernet driver.

File: rtl_nic/rtl8168d-1.fw
File: rtl_nic/rtl8168d-2.fw
File: rtl_nic/rtl8105e-1.fw
File: rtl_nic/rtl8168e-1.fw
File: rtl_nic/rtl8168e-2.fw

File: rtl_nic/rtl8168e-3.fw
Version: 0.0.4

File: rtl_nic/rtl8168f-1.fw
Version: 0.0.5

File: rtl_nic/rtl8168f-2.fw
Version: 0.0.4

File: rtl_nic/rtl8411-1.fw
Version: 0.0.3

File: rtl_nic/rtl8411-2.fw
Version: 0.0.1

File: rtl_nic/rtl8402-1.fw
Version: 0.0.1

File: rtl_nic/rtl8106e-1.fw
Version: 0.0.1

File: rtl_nic/rtl8106e-2.fw
Version: 0.0.1

File: rtl_nic/rtl8168g-1.fw
Version: 0.0.3

File: rtl_nic/rtl8168g-2.fw
Version: 0.0.1

File: rtl_nic/rtl8168g-3.fw
Version: 0.0.1

File: rtl_nic/rtl8168h-1.fw
Version: 0.0.2

File: rtl_nic/rtl8168h-2.fw
Version: 0.0.2

File: rtl_nic/rtl8107e-1.fw
Version: 0.0.2

File: rtl_nic/rtl8107e-2.fw
Version: 0.0.2

Licence:
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Driver: vt6656 - VIA VT6656 USB wireless driver

File: vntwusb.fw

Licence: Redistributable. See LICENCE.via_vt6656 for details.

Driver: DFU Driver for Atheros bluetooth chipset AR3012

File: ar3k/AthrBT_0x01020001.dfu
File: ar3k/ramps_0x01020001_26.dfu
File: ar3k/AthrBT_0x01020200.dfu
File: ar3k/ramps_0x01020200_26.dfu
File: ar3k/ramps_0x01020200_40.dfu
File: ar3k/AthrBT_0x31010000.dfu
File: ar3k/ramps_0x31010000_40.dfu
File: ar3k/AthrBT_0x11020000.dfu
File: ar3k/ramps_0x11020000_40.dfu
File: ar3k/ramps_0x01020201_26.dfu
File: ar3k/ramps_0x01020201_40.dfu
File: ar3k/AthrBT_0x41020000.dfu
File: ar3k/ramps_0x41020000_40.dfu
File: ar3k/AthrBT_0x11020100.dfu
File: ar3k/ramps_0x11020100_40.dfu
File: ar3k/AthrBT_0x31010100.dfu
File: ar3k/ramps_0x31010100_40.dfu

Licence: Redistributable. See LICENCE.atheros_firmware for details

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Driver: DFU Driver for Atheros bluetooth chipset AR3012

File: ar3k/AthrBT_0x01020201.dfu
File: ar3k/1020201coex/ramps_0x01020201_26_HighPriority.dfu

Licence: Redistributable. See LICENSE.QualcommAtheros_ar3k for details

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Driver:Atheros AR300x UART HCI Bluetooth Chip driver

File: ar3k/1020201/PS_ASIC.pst
File: ar3k/1020201/RamPatch.txt
File: ar3k/1020200/ar3kbdaddr.pst
File: ar3k/1020200/PS_ASIC.pst
File: ar3k/1020200/RamPatch.txt
File: ar3k/30101/ar3kbdaddr.pst
File: ar3k/30101/PS_ASIC.pst
File: ar3k/30101/RamPatch.txt
File: ar3k/30000/ar3kbdaddr.pst

File: ar3k/30000/PS_ASIC.pst
File: ar3k/30000/RamPatch.txt

Licence: Redistributable. See LICENCE.atheros_firmware for details

---

Driver: ath6kl - Atheros support for AR6003

File: ath6k/AR6004/hw1.3/fw-3.bin
File: ath6k/AR6004/hw1.3/bdata.bin
File: ath6k/AR6004/hw1.2/fw-2.bin
File: ath6k/AR6004/hw1.2/bdata.bin
File: ath6k/AR6003/hw1.0/otp.bin.z77
File: ath6k/AR6003/hw1.0/bdata.SD31.bin
File: ath6k/AR6003/hw1.0/bdata.SD32.bin
File: ath6k/AR6003/hw1.0/data.patch.bin
File: ath6k/AR6003/hw1.0/bdata.WB31.bin
File: ath6k/AR6003/hw1.0/athwlan.bin.z77
File: ath6k/AR6003/hw2.1.1/fw-2.bin
File: ath6k/AR6003/hw2.1.1/fw-3.bin
File: ath6k/AR6003/hw2.1.1/otp.bin
File: ath6k/AR6003/hw2.1.1/athwlan.bin
File: ath6k/AR6003/hw2.1.1/endpointping.bin
File: ath6k/AR6003/hw2.1.1/bdata.SD31.bin
File: ath6k/AR6003/hw2.1.1/bdata.SD32.bin
File: ath6k/AR6003/hw2.1.1/data.patch.bin
File: ath6k/AR6003/hw2.1.1/bdata.WB31.bin
File: ath6k/AR6003/hw2.0/otp.bin.z77
File: ath6k/AR6003/hw2.0/bdata.SD31.bin
File: ath6k/AR6003/hw2.0/bdata.SD32.bin
File: ath6k/AR6003/hw2.0/data.patch.bin
File: ath6k/AR6003/hw2.0/bdata.WB31.bin
File: ath6k/AR6003/hw2.0/athwlan.bin.z77
File: ath6k/AR6002/eeprom.data
File: ath6k/AR6002/eeprom.bin
File: ath6k/AR6002/athwlan.bin.z77
File: ath6k/AR6002/data.patch.hw2_0.bin

Licence: Redistributable. See LICENCE.atheros_firmware for details

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Driver: ath10k - Qualcomm Atheros support for QCA988x family of chips

File: ath10k/QCA988X/hw2.0/board.bin
File: ath10k/QCA988X/hw2.0/firmware-4.bin
Version: 10.2.4.45
Licence: ath10k/QCA988X/hw2.0/notice_ath10k_firmware-4.txt
File: ath10k/QCA988X/hw2.0/firmware-5.bin
Version: 10.2.4-1.0-00045
Licence: ath10k/QCA988X/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA6174/hw2.1/board.bin
File: ath10k/QCA6174/hw2.1/board-2.bin
File: ath10k/QCA6174/hw2.1/firmware-5.bin
Version: SW_RM.1.1.1-00157-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw2.1/notice_ath10k_firmware-5.txt

File: ath10k/QCA6174/hw3.0/board.bin
File: ath10k/QCA6174/hw3.0/board-2.bin
File: ath10k/QCA6174/hw3.0/firmware-4.bin
Version: WLAN.RM.2.0-00180-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw3.0/notice_ath10k_firmware-4.txt
File: ath10k/QCA6174/hw3.0/firmware-6.bin
Version: WLAN.RM.4.4.1-00140-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw3.0/notice_ath10k_firmware-6.txt
File: ath10k/QCA9377/hw1.0/board.bin
File: ath10k/QCA9377/hw1.0/board-2.bin
File: ath10k/QCA9377/hw1.0/firmware-5.bin
Version: WLAN.TF.1.0-00002-QCATFSWPZ-5
Licence: ath10k/QCA9377/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA99X0/hw2.0/board.bin
File: ath10k/QCA99X0/hw2.0/firmware-5.bin
Version: 10.4.1.00030-1
Licence: ath10k/QCA99X0/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA4019/hw1.0/board-2.bin
File: ath10k/QCA4019/hw1.0/firmware-5.bin
Version: 10.4-3.6-00140
Licence: ath10k/QCA4019/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9887/hw1.0/board.bin
File: ath10k/QCA9887/hw1.0/firmware-5.bin
Version: 10.2.4-1.0-00045
Licence: ath10k/QCA9887/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9888/hw2.0/board-2.bin
File: ath10k/QCA9888/hw2.0/firmware-5.bin
Version: 10.4-3.9.0.2-00040
Licence: ath10k/QCA9888/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9984/hw1.0/board-2.bin
File: ath10k/QCA9984/hw1.0/firmware-5.bin
Version: 10.4-3.9.0.2-00046
Licence: ath10k/QCA9984/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9377/hw1.0/firmware-6.bin
Version: WLAN.TF.2.1-00021-QCARMSWP-1
Licence: ath10k/QCA9377/hw1.0/notice_ath10k_firmware-6.txt

Licence: Redistributable. See LICENSE.QualcommAtheros_ath10k for details

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Driver: myri10ge - Myri10GE 10GbE NIC driver

File: myri10ge_eth_z8e.dat
File: myri10ge_ethp_z8e.dat
File: myri10ge_rss_eth_z8e.dat
File: myri10ge_rss_ethp_z8e.dat
File: myri10ge_eth_big_z8e.dat
File: myri10ge_ethp_big_z8e.dat
File: myri10ge_rss_eth_big_z8e.dat
File: myri10ge_rss_ethp_big_z8e.dat
Version: 1.4.57

License: Redistributable. See LICENCE.myri10ge_firmware for details.

Driver: ath6kl - Atheros support for AR6003 WiFi-Bluetooth combo module

File: ath6k/AR6003.1/hw2.1.1/athwlan.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.SD31.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.SD32.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.WB31.bin
File: ath6k/AR6003.1/hw2.1.1/data.patch.bin
File: ath6k/AR6003.1/hw2.1.1/endpointping.bin
File: ath6k/AR6003.1/hw2.1.1/otp.bin

License: Redistributable. See LICENCE.atheros_firmware for details

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Driver: ath6kl - Atheros support for AR3001 WiFi-Bluetooth combo module

File: ar3k/30101coex/ar3kbdaddr.pst
File: ar3k/30101coex/PS_ASIC_aclLowPri.pst
File: ar3k/30101coex/PS_ASIC_aclHighPri.pst
File: ar3k/30101coex/PS_ASIC.pst
File: ar3k/30101coex/RamPatch.txt

License: Redistributable. See LICENCE.atheros_firmware for details

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Driver: drxk - Micronas DRX-K demodulator driver

File: dvb-usb-terratec-h5-drxk.fw

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Driver: ene-ub6250 -- ENE UB6250 SD card reader driver

File: ene-ub6250/sd_init1.bin
File: ene-ub6250/sd_init2.bin
File: ene-ub6250/sd_rdwr.bin
File: ene-ub6250/ms_init.bin
File: ene-ub6250/msp_rdwr.bin
File: ene-ub6250/ms_rdwr.bin

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Driver: isci -- Intel C600 SAS controller driver

File: isci/isci_firmware.bin
Source: isci/

Licence: GPLv2. See GPL-2 for details.

Driver: ar5523 -- Atheros AR5523 based USB Wifi dongles

File: ar5523.bin

Licence: Redistributable. See LICENCE.atheros_firmware for details

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Driver: s5p-mfc - Samsung MFC video encoder/decoder driver

File: s5p-mfc.fw
File: s5p-mfc-v6.fw
File: s5p-mfc-v6-v2.fw
File: s5p-mfc-v7.fw
File: s5p-mfc-v8.fw

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Driver: carl9170 -- Atheros AR9170 802.11 draft-n USB driver

File: carl9170-1.fw
Version: 1.9.6
Source: carl9170fw/

Downloaded from http://linuxwireless.org/en/users/Drivers/carl9170

Licence: GPLv2. Some build scripts use the New BSD (3-clause) licence.. See GPL-2 for details.

Driver: snd-hda-codec-ca0132 - Creative Sound Core3D codec

File: ctefx.bin
File: ctspeq.bin

Licence: Redistributable. See LICENCE.ca0132 for details

Found also in alsa-firmware package.

Driver: btusb - Bluetooth USB driver

File: intel/ibt-hw-37.7.bseq
Version: 1316.02.00
File: intel/ibt-hw-37.7.10-fw-1.80.2.3.d.bseq
Version: BT_WilkinsPeak_B3_REL_87_0001
File: intel/ibt-hw-37.7.10-fw-1.0.2.3.d.bseq
Version: BT_WilkinsPeak_B3_REL_87_0001
File: intel/ibt-hw-37.7.10-fw-1.80.1.2d.d.bseq
Version: BT_WilkinsPeak_B5_REL_42_0001
File: intel/ibt-hw-37.7.10-fw-1.0.1.2d.d.bseq
Version: BT_WilkinsPeak_B5_REL_42_0001
File: intel/ibt-hw-37.8.bseq
Version: 1339_02.00
File: intel/ibt-hw-37.8.10-fw-1.10.2.27.d.bseq
Version: BT_StonePeak_C0_REL_59_0001
File: intel/ibt-hw-37.8.10-fw-1.10.3.11.e.bseq
Version: BT_StonePeak_D0_REL_50_0002
File: intel/ibt-hw-37.8.10-fw-22.50.19.14.f.bseq
Version: BT_StonePeak_D1_REL_52_00005
File: intel/ibt-11-5.ddc
Version: LnP/SfP_REL0522
File: intel/ibt-11-5.sfi
Version: BT_LightningPeak_REL0487
File: intel/ibt-12-16.ddc
Version: BT_WindStormPeak_REL0306
File: intel/ibt-12-16.sfi
Version: BT_WindStormPeak_REL0306
File: intel/ibt-17-16-1.sfi
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-16-1.ddc
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-2.sfi
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-2.ddc
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-0-1.sfi
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-0-1.ddc
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-1.sfi
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-1.ddc
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-18-16-1.sfi
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-16-1.ddc
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-2.sfi
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-2.ddc
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-0-1.sfi

Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-0-1.ddc
Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-1.sfi
Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-1.ddc
Version: BT_ThunderPeak_A0_B0_REL0201
File:intel/ibt-20-0-3.sfi
Version: BT_CyclonePeak_A0_REL0310
File:intel/ibt-20-0-3.ddc
Version: BT_CyclonePeak_A0_REL0310
File:intel/ibt-20-1-3.sfi
Version: BT_CyclonePeak_A0_REL0310
File:intel/ibt-20-1-3.ddc
Version: BT_CyclonePeak_A0_REL_0310
File:intel/ibt-20-1-4.sfi
Version: BT_CyclonePeak_A0_REL0310
File:intel/ibt-20-1-4.ddc
Version: BT_CyclonePeak_A0_REL0310
File:intel/ibt-19-0-0.sfi
Version: BT_Quasar_REL0310
File:intel/ibt-19-0-0.ddc
Version: BT_Quasar_REL0310
File:intel/ibt-19-0-1.sfi
Version: BT_Quasar_REL0310
File:intel/ibt-19-0-1.ddc
Version: BT_Quasar_REL0310
File:intel/ibt-19-0-4.sfi
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-0-4.ddc
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-16-4.sfi
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-16-4.ddc
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-32-1.sfi
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-32-1.ddc
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-32-0.sfi
Version: BT_HarrisonPeak_REL0310
File:intel/ibt-19-32-0.ddc
Version: BT_HarrisonPeak_REL0310

Licence: Redistributable. See LICENCE.ibt_firmware for details

File: rtl_bt/rtl8192ee_fw.bin
File: rtl_bt/rtl8192eu_fw.bin
File: rtl_bt/rtl8723a_fw.bin
File: rtl_bt/rtl8723b_fw.bin
File: rtl_bt/rtl8723bs_fw.bin
File: rtl_bt/rtl8723bs_config-OBDA8723.bin
File: rtl_bt/rtl8761a_fw.bin
File: rtl_bt/rtl8812ae_fw.bin
File: rtl_bt/rtl8821a_fw.bin
File: rtl_bt/rtl8822b_fw.bin

File: rtl_bt/rtl8822b_config.bin
File: rtl_bt/rtl8723d_fw.bin
File: rtl_bt/rtl8723d_config.bin
File: rtl_bt/rtl8821c_fw.bin
File: rtl_bt/rtl8821c_config.bin
File: rtl_bt/rtl8822cu_fw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Found in vendor driver, linux_bt_usb_2.11.20140423_8723be.rar
From https://github.com/troy-tan/driver_store
Files rtl_bt/rtl8822b_* came directly from Realtek. These files are
updated on April 14, 2017.
Files rtl_bt/rtl8821c_* and rtl_bt/rtl8723d_* came directly from Realtek.
File rtl_bt/rtl8822cu_fw.bin came directly from Realtek.
updated on February 24, 2019
File rtl_bt/rtl8822cu_fw.bin came directly from Realtek.

Driver: btmtk_usb - Bluetooth USB driver

File: mt7650.bin

Licence: Redistributable. See LICENCE.ralink_a_mediatek_company_firmware for details

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Driver: rp2 -- Comtrol RocketPort 2 serial driver

File: rp2.fw

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Driver: go7007

File: go7007/s2250-1.fw
File: go7007/s2250-2.fw
Link: s2250.fw -> go7007/s2250-2.fw
Link: s2250_loader.fw -> go7007/s2250-1.fw

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File: go7007/go7007fw.bin
File: go7007/go7007tv.bin
File: go7007/lr192.fw
File: go7007/px-m402u.fw
File: go7007/px-tv402u.fw
File: go7007/wis-startrek.fw

Licence: Redistributable. See LICENCE.go7007 for details

Driver: ccp - Platform Security Processor (PSP) device

File: amd/amd_sev_fam17h_model0xh.sbin
Version: 2019-02-13

License: Redistributable. See LICENSE.amd-sev for details

Driver: microcode_amd - AMD CPU Microcode Update Driver for Linux

File: amd-ucode/microcode_amd.bin
Version: 2013-07-10
File: amd-ucode/microcode_amd_fam15h.bin
Version: 2018-05-24
File: amd-ucode/microcode_amd_fam16h.bin
Version: 2014-10-28
File: amd-ucode/microcode_amd_fam17h.bin
Version: 2018-11-28

License: Redistributable. See LICENSE.amd-ucode for details

Driver: mxu11x0 - MOXA UPort 11x0 USB Serial hub driver

File: moxa/moxa-1110.fw
File: moxa/moxa-1130.fw
File: moxa/moxa-1131.fw
File: moxa/moxa-1150.fw
File: moxa/moxa-1151.fw

License: Redistributable. See LICENCE.moxa for details

Driver: mxuport - MOXA UPort USB Serial hub driver

File: moxa/moxa-1250.fw
File: moxa/moxa-1251.fw

File: moxa/moxa-1410.fw
File: moxa/moxa-1450.fw
File: moxa/moxa-1451.fw
File: moxa/moxa-1613.fw
File: moxa/moxa-1618.fw
File: moxa/moxa-1653.fw
File: moxa/moxa-1658.fw

License: Redistributable. See LICENCE.moxa for details

Driver: cw1200 - ST-E CW1100/CW1200 WLAN driver

File: wsm_22.bin
Version: WSM395
Licence: Redistributable. See LICENCE.cw1200 for details.

File: sdd_sagrad_1091_1098.bin

License:
Copyright (c) 2011-2013 Sagrad, Inc.

This SDD ("Static Dynamic Data") file is licensed strictly for use with
the Sagrad WiFi modules (such as the SG901-1091/1098) that utilize the
cw1200 driver. There is no warranty expressed or implied about its
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part of Linux or other Open Source operating system kernel in text or
binary form as required.

(Please note that the actual device firmware is separately licensed)

Driver: BFA/BNA - QLogic BR-series Adapter FC/FCOE drivers

File: cbfw-3.2.1.1.bin
File: ctfw-3.2.1.1.bin
File: ct2fw-3.2.1.1.bin
File: cbfw-3.2.3.0.bin
File: ctfw-3.2.3.0.bin
File: ct2fw-3.2.3.0.bin
File: cbfw-3.2.5.1.bin
File: ctfw-3.2.5.1.bin
File: ct2fw-3.2.5.1.bin

Licence:

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kernel or in any other form which would require these files themselves
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useful, but WITHOUT ANY WARRANTY; without even the implied warranty
of MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.

Driver: qat - Intel(R) QAT crypto accelerator

File: qat_895xcc.bin
File: qat_895xcc_mmp.bin
File: qat_c3xxx.bin
File: qat_c3xxx_mmp.bin
File: qat_c62x.bin
File: qat_c62x_mmp.bin
Link: qat_mmp.bin -> qat_895xcc_mmp.bin

Licence: Redistributable. See LICENCE.qat_firmware for details

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Driver: rsi -- Redpine Signals Inc 91x driver

File: rsi_91x.fw

File: rsi/rs9113_wlan_qspi.rps
Version: 1.6.1

File: rsi/rs9113_wlan_bt_dual_mode.rps
Version: 1.6.1

File: rsi/rs9113_ap_bt_dual_mode.rps
Version: 1.6.1

File: rsi/rs9116_wlan.rps
Version: 1.0.5b

File: rsi/rs9116_wlan_bt_classic.rps
Version: 1.0.5b

Licence:
 * Firmware is:
 *	Derived from proprietary unpublished source code,
 *	Copyright (C) 2019 Redpine Signals Inc.
 *
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 *	as part of Linux or other Open Source operating system kernel
 *	provided this copyright notice is accompanying it.

Driver: xhci-rcar -- Renesas R-Car Gen2/3 USB 3.0 host controller driver

File: r8a779x_usb3_v1.dlmem
File: r8a779x_usb3_v2.dlmem
File: r8a779x_usb3_v3.dlmem

Licence: Redistributable. See LICENCE.r8a779x_usb3 for details.

Driver: snd_soc_sst_acpi

File: intel/fw_sst_0f28.bin-48kHz_i2s_master

License: Redistributable. See LICENCE.fw_sst_0f28 for details

---

Driver: as102 - Abilis Systems Single DVB-T Receiver

File: as102_data1_st.hex
File: as102_data2_st.hex

License: Redistributable. See LICENCE.Abilis for details

Driver: it9135 -- ITEtech IT913x DVB-T USB driver

File: dvb-usb-it9135-01.fw
File: dvb-usb-it9135-02.fw

Licence: Redistributable. See LICENCE.it913x for details

Driver: snd_soc_sst_acpi

File: intel/IntcSST2.bin
Version: 8.4.1.77

License: Redistributable. See LICENCE.IntcSST2 for details

Driver: snd_intel_sst_core

File: intel/fw_sst_0f28.bin
File: intel/fw_sst_0f28_ssp0.bin

License: Redistributable. See LICENCE.fw_sst_0f28 for details

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Driver: snd_intel_sst_core

File: intel/fw_sst_22a8.bin
Version: 01.0B.02.02

License: Redistributable. See LICENCE.fw_sst_0f28 for details

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Driver: snd-soc-skl

File: intel/dsp_fw_release_v969.bin
Version: 8.20.00.969
File: intel/dsp_fw_release_v3402.bin
Version: 9.21.00.3402_161
Link: intel/dsp_fw_release.bin -> intel/dsp_fw_release_v3402.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_bxtn_v2219.bin
Version: 9.22.01.2219_64
File: intel/dsp_fw_bxtn_v3366.bin
Version: 9.22.01.3366_157
Link: intel/dsp_fw_bxtn.bin -> intel/dsp_fw_bxtn_v3366.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_kbl_v701.bin
Version: 9.21.00.701
File: intel/dsp_fw_kbl_v1037.bin
Version: 09.21.00.1037
File: intel/dsp_fw_kbl_v2042.bin
Version: 9.21.00.2042_46
File: intel/dsp_fw_kbl_v2630.bin
Version: 9.21.00.2630_97
File: intel/dsp_fw_kbl_v3266.bin
Version: 9.21.00.3266_144
File: intel/dsp_fw_kbl_v3420.bin
Version: 9.21.00.3420_163
File: intel/dsp_fw_kbl_v3402.bin
Version: 9.21.00.3402_161
Link: intel/dsp_fw_kbl.bin -> dsp_fw_kbl_v3402.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_glk_v1814.bin
Version: 9.92.01.1814
File: intel/dsp_fw_glk_v2880.bin
Version: 9.22.00.2880
File: intel/dsp_fw_glk_v2768.bin
Version: 9.22.01.2768
File: intel/dsp_fw_glk_v3366.bin
Version: 9.22.01.3366_157
Link: intel/dsp_fw_glk.bin -> dsp_fw_glk_v3366.bin

File: intel/dsp_fw_cnl_v1191.bin
Version: 10.00.00.1191
File: intel/dsp_fw_cnl_v1858.bin
Version: 10.23.00.1858
File: intel/dsp_fw_cnl.bin
Link: intel/dsp_fw_cnl.bin -> intel/dsp_fw_cnl_v1858.bin

License: Redistributable. See LICENCE.adsp_sst for details

Driver: smsmdtv - Siano MDTV Core module

File: cmmb_vega_12mhz.inp
File: cmmb_venice_12mhz.inp
File: dvb_nova_12mhz.inp
File: dvb_nova_12mhz_b0.inp
File: isdbt_nova_12mhz.inp
File: isdbt_nova_12mhz_b0.inp
File: isdbt_rio.inp
File: sms1xxx-hcw-55xxx-dvbt-02.fw
File: sms1xxx-hcw-55xxx-isdbt-02.fw
File: sms1xxx-nova-a-dvbt-01.fw
File: sms1xxx-nova-b-dvbt-01.fw
File: sms1xxx-stellar-dvbt-01.fw
File: tdmb_nova_12mhz.inp

Licence: Redistributable. See LICENCE.siano for details

Driver: xhci-tegra -- NVIDIA Tegra XHCI driver

File: nvidia/tegra124/xusb.bin
Version: v45.46

File: nvidia/tegra210/xusb.bin
Version: v50.10

Licence: Redistributable. See LICENCE.nvidia for details

Driver: tegra-vic -- NVIDIA Tegra VIC driver

File: nvidia/tegra124/vic03_ucode.bin
File: nvidia/tegra210/vic04_ucode.bin
File: nvidia/tegra186/vic04_ucode.bin

Licence: Redistributable. See LICENCE.nvidia for details

Driver: atusb - ATUSB IEEE 802.15.4 transceiver driver

File: atusb/atusb-0.2.dfu
Version: 0.2
File: atusb/atusb-0.3.dfu
Version: 0.3
File: atusb/rzusb-0.3.bin
Version: 0.3
Info: atusb/ChangeLog

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

Driver: qca - Qualcomm Atheros Bluetooth support for QCA61x4 chips

File: qca/nvm_usb_00000201.bin
File: qca/nvm_usb_00000200.bin
File: qca/nvm_usb_00000300.bin
File: qca/nvm_usb_00000302.bin
File: qca/nvm_00130300.bin
File: qca/nvm_00130302.bin
File: qca/rampatch_usb_00000200.bin
File: qca/rampatch_usb_00000201.bin
File: qca/rampatch_usb_00000300.bin
File: qca/rampatch_usb_00000302.bin
File: qca/rampatch_00130300.bin
File: qca/rampatch_00130302.bin
File: qca/crbtfw21.tlv
File: qca/crnv21.bin
File: qca/nvm_00440302.bin
File: qca/rampatch_00440302.bin

Licence: Redistributable. See LICENSE.QualcommAtheros_ath10k and qca/NOTICE.txt for details

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Driver: liquidio -- Cavium LiquidIO driver

File: liquidio/lio_23xx_nic.bin
Version: v1.7.2

File: liquidio/lio_23xx_vsw.bin
Version: v1.7.2

File: liquidio/lio_210nv_nic.bin
Version: v1.7.2

File: liquidio/lio_210sv_nic.bin
Version: v1.7.2

File: liquidio/lio_410nv_nic.bin
Version: v1.7.2

Licence: Redistributable. See LICENCE.cavium_liquidio for details

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Driver: nitrox -- Cavium CNN55XX crypto driver

File: cavium/cnn55xx_ae.fw
Version: v01

File: cavium/cnn55xx_se.fw
Version: v10

Licence: Redistributable. See LICENCE.cavium for details

Driver: i915 -- Intel Integrated Graphics driver

File: i915/skl_dmc_ver1_23.bin
File: i915/skl_dmc_ver1_26.bin
File: i915/skl_dmc_ver1_27.bin
File: i915/skl_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 27 for Skylake

File: i915/bxt_dmc_ver1_07.bin
File: i915/bxt_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 07 for Broxton

File: i915/kbl_dmc_ver1_01.bin
File: i915/kbl_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 01 for Kabylake

File: i915/kbl_dmc_ver1_04.bin
File: i915/kbl_dmc_ver1_04.bin
Version: DMC API/ABI ver 1 - release 04 for Kabylake

File: i915/skl_guc_ver1.bin
Version: Guc API/ABI ver 1 - release 1059 for Skylake

File: i915/skl_guc_ver4.bin
Version: Guc API/ABI ver 4 - release 3 for Skylake

File: i915/skl_guc_ver6_1.bin
File: i915/skl_guc_ver6.bin
Version: Guc API/ABI ver 6 - release 1 for Skylake

File: i915/skl_guc_ver9_33.bin
Version: Guc API/ABI ver 9 - release 33 for Skylake

File: i915/skl_guc_32.0.3.bin
Version: Guc API/ABI ver 32 - release 0 for Skylake

File: i915/skl_guc_33.0.0.bin
Version: Guc API/ABI ver 33 - release 0 for Skylake

File: i915/skl_huc_ver01_07_1398.bin
Version: HuC API/ABI ver 1 - release 7 for Skylake

File: i915/bxt_huc_ver01_07_1398.bin
Version: HuC API/APB ver 1 - release 7 for Broxton

File: i915/bxt_huc_ver01_8_2893.bin
Version: HuC API/APB ver 1 - release 8 for Broxton

File: i915/kbl_huc_ver02_00_1810.bin
Version: HuC API/APB ver 2 - for Kabylake

File: i915/bxt_guc_ver8_7.bin
Version: Guc API/APB ver 8 - release 7 for Broxton

File: i915/bxt_guc_ver9_29.bin
Version: Guc API/APB ver 9 - release 29 for Broxton

File: i915/bxt_guc_32.0.3.bin
Version: Guc API/APB ver 32 - release 0 for Broxton

File: i915/bxt_guc_33.0.0.bin
Version: Guc API/APB ver 33 - release 0 for Broxton

File: i915/kbl_guc_ver9_14.bin
Version: Guc API/APB ver 9 release 14 for Kabylake

File: i915/kbl_guc_ver9_39.bin
Version: Guc API/APB ver 9 release 39 for Kabylake

File: i915/kbl_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Kabylake

File: i915/kbl_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Kabylake

File: i915/glk_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Geminilake

File: i915/glk_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Geminilake

File: i915/glk_huc_ver03_01_2893.bin
Version: Huc API/APB ver 3 release 1 for Geminilake

File: i915/glk_dmc_ver1_04.bin
Version: DMC API/ABI ver 1 - release 04 for Geminilake

File: i915/cnl_dmc_ver1_06.bin
Version: DMC API/ABI ver 1 - release 06 for Cannonlake

File: i915/cnl_dmc_ver1_07.bin
Version: DMC API/ABI ver 1 - release 07 for Cannonlake

File: i915/icl_dmc_ver1_07.bin
Version: DMC API/ABI ver 1 - release 07 for icelake

File: i915/icl_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Icelake

File: i915/icl_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Icelake

File: i915/icl_huc_ver8_4_3238.bin
Version: Huc API/APB ver 8 release 4 for Icelake
License: Redistributable. See LICENSE.i915 for details

Driver: nouveau - NVIDIA GPU driver

File: nvidia/gk20a/fecs_data.bin
File: nvidia/gk20a/fecs_inst.bin
File: nvidia/gk20a/gpccs_data.bin
File: nvidia/gk20a/gpccs_inst.bin
File: nvidia/gk20a/sw_bundle_init.bin
File: nvidia/gk20a/sw_ctx.bin
File: nvidia/gk20a/sw_method_init.bin
File: nvidia/gk20a/sw_nonctx.bin
File: nvidia/gm200/acr/bl.bin
File: nvidia/gm200/acr/ucode_load.bin
File: nvidia/gm200/acr/ucode_unload.bin
File: nvidia/gm200/gr/fecs_bl.bin
File: nvidia/gm200/gr/fecs_data.bin
File: nvidia/gm200/gr/fecs_inst.bin
File: nvidia/gm200/gr/fecs_sig.bin
File: nvidia/gm200/gr/gpccs_bl.bin
File: nvidia/gm200/gr/gpccs_data.bin
File: nvidia/gm200/gr/gpccs_inst.bin
File: nvidia/gm200/gr/gpccs_sig.bin
File: nvidia/gm200/gr/sw_bundle_init.bin
File: nvidia/gm200/gr/sw_ctx.bin
File: nvidia/gm200/gr/sw_method_init.bin
File: nvidia/gm200/gr/sw_nonctx.bin
File: nvidia/gm204/acr/bl.bin
File: nvidia/gm204/acr/ucode_load.bin
File: nvidia/gm204/acr/ucode_unload.bin
File: nvidia/gm204/gr/fecs_bl.bin
File: nvidia/gm204/gr/fecs_data.bin
File: nvidia/gm204/gr/fecs_inst.bin
File: nvidia/gm204/gr/fecs_sig.bin
File: nvidia/gm204/gr/gpccs_bl.bin
File: nvidia/gm204/gr/gpccs_data.bin
File: nvidia/gm204/gr/gpccs_inst.bin
File: nvidia/gm204/gr/gpccs_sig.bin
File: nvidia/gm204/gr/sw_bundle_init.bin
File: nvidia/gm204/gr/sw_ctx.bin
File: nvidia/gm204/gr/sw_method_init.bin
File: nvidia/gm204/gr/sw_nonctx.bin
File: nvidia/gm206/acr/bl.bin
File: nvidia/gm206/acr/ucode_load.bin
File: nvidia/gm206/acr/ucode_unload.bin
File: nvidia/gm206/gr/fecs_bl.bin
File: nvidia/gm206/gr/fecs_data.bin
File: nvidia/gm206/gr/fecs_inst.bin
File: nvidia/gm206/gr/fecs_sig.bin
File: nvidia/gm206/gr/gpccs_bl.bin
File: nvidia/gm206/gr/gpccs_data.bin
File: nvidia/gm206/gr/gpccs_inst.bin
File: nvidia/gm206/gr/gpccs_sig.bin
File: nvidia/gm206/gr/sw_bundle_init.bin
File: nvidia/gm206/gr/sw_ctx.bin
File: nvidia/gm206/gr/sw_method_init.bin
File: nvidia/gm206/gr/sw_nonctx.bin
File: nvidia/gm20b/acr/bl.bin
File: nvidia/gm20b/acr/ucode_load.bin
File: nvidia/gm20b/gr/fecs_bl.bin
File: nvidia/gm20b/gr/fecs_data.bin
File: nvidia/gm20b/gr/fecs_inst.bin

File: nvidia/gm20b/gr/fecs_sig.bin
File: nvidia/gm20b/gr/gpccs_data.bin
File: nvidia/gm20b/gr/gpccs_inst.bin
File: nvidia/gm20b/gr/sw_bundle_init.bin
File: nvidia/gm20b/gr/sw_ctx.bin
File: nvidia/gm20b/gr/sw_method_init.bin
File: nvidia/gm20b/gr/sw_nonctx.bin
File: nvidia/gm20b/pmu/desc.bin
File: nvidia/gm20b/pmu/image.bin
File: nvidia/gm20b/pmu/sig.bin
File: nvidia/gp100/acr/bl.bin
File: nvidia/gp100/acr/ucode_load.bin
File: nvidia/gp100/acr/ucode_unload.bin
File: nvidia/gp100/gr/fecs_bl.bin
File: nvidia/gp100/gr/fecs_data.bin
File: nvidia/gp100/gr/fecs_inst.bin
File: nvidia/gp100/gr/fecs_sig.bin
File: nvidia/gp100/gr/gpccs_bl.bin
File: nvidia/gp100/gr/gpccs_data.bin
File: nvidia/gp100/gr/gpccs_inst.bin
File: nvidia/gp100/gr/gpccs_sig.bin
File: nvidia/gp100/gr/sw_bundle_init.bin
File: nvidia/gp100/gr/sw_ctx.bin
File: nvidia/gp100/gr/sw_method_init.bin
File: nvidia/gp100/gr/sw_nonctx.bin
File: nvidia/gp102/acr/bl.bin
File: nvidia/gp102/acr/ucode_load.bin
File: nvidia/gp102/acr/ucode_unload.bin
File: nvidia/gp102/acr/unload_bl.bin
File: nvidia/gp102/gr/fecs_bl.bin
File: nvidia/gp102/gr/fecs_data.bin
File: nvidia/gp102/gr/fecs_inst.bin
File: nvidia/gp102/gr/fecs_sig.bin
File: nvidia/gp102/gr/gpccs_bl.bin
File: nvidia/gp102/gr/gpccs_data.bin
File: nvidia/gp102/gr/gpccs_inst.bin
File: nvidia/gp102/gr/gpccs_sig.bin
File: nvidia/gp102/gr/sw_bundle_init.bin
File: nvidia/gp102/gr/sw_ctx.bin
File: nvidia/gp102/gr/sw_method_init.bin
File: nvidia/gp102/gr/sw_nonctx.bin
File: nvidia/gp102/nvdec/scrubber.bin
File: nvidia/gp102/sec2/desc.bin
File: nvidia/gp102/sec2/image.bin
File: nvidia/gp102/sec2/sig.bin
File: nvidia/gp102/sec2/desc-1.bin
File: nvidia/gp102/sec2/image-1.bin
File: nvidia/gp102/sec2/sig-1.bin
File: nvidia/gp104/acr/bl.bin
File: nvidia/gp104/acr/ucode_load.bin
File: nvidia/gp104/acr/ucode_unload.bin
File: nvidia/gp104/acr/unload_bl.bin
File: nvidia/gp104/gr/fecs_bl.bin
File: nvidia/gp104/gr/fecs_data.bin
File: nvidia/gp104/gr/fecs_inst.bin
File: nvidia/gp104/gr/fecs_sig.bin
File: nvidia/gp104/gr/gpccs_bl.bin

File: nvidia/gp104/gr/gpccs_data.bin
File: nvidia/gp104/gr/gpccs_inst.bin
File: nvidia/gp104/gr/gpccs_sig.bin
File: nvidia/gp104/gr/sw_bundle_init.bin
File: nvidia/gp104/gr/sw_ctx.bin
File: nvidia/gp104/gr/sw_method_init.bin
File: nvidia/gp104/gr/sw_nonctx.bin
File: nvidia/gp104/nvdec/scrubber.bin
File: nvidia/gp104/sec2/desc.bin
File: nvidia/gp104/sec2/image.bin
File: nvidia/gp104/sec2/sig.bin
File: nvidia/gp104/sec2/desc-1.bin
File: nvidia/gp104/sec2/image-1.bin
File: nvidia/gp104/sec2/sig-1.bin
File: nvidia/gp106/acr/bl.bin
File: nvidia/gp106/acr/ucode_load.bin
File: nvidia/gp106/acr/ucode_unload.bin
File: nvidia/gp106/acr/unload_bl.bin
File: nvidia/gp106/gr/fecs_bl.bin
File: nvidia/gp106/gr/fecs_data.bin
File: nvidia/gp106/gr/fecs_inst.bin
File: nvidia/gp106/gr/fecs_sig.bin
File: nvidia/gp106/gr/gpccs_bl.bin
File: nvidia/gp106/gr/gpccs_data.bin
File: nvidia/gp106/gr/gpccs_inst.bin
File: nvidia/gp106/gr/gpccs_sig.bin
File: nvidia/gp106/gr/sw_bundle_init.bin
File: nvidia/gp106/gr/sw_ctx.bin
File: nvidia/gp106/gr/sw_method_init.bin
File: nvidia/gp106/gr/sw_nonctx.bin
File: nvidia/gp106/nvdec/scrubber.bin
File: nvidia/gp106/sec2/desc.bin
File: nvidia/gp106/sec2/image.bin
File: nvidia/gp106/sec2/sig.bin
File: nvidia/gp106/sec2/desc-1.bin
File: nvidia/gp106/sec2/image-1.bin
File: nvidia/gp106/sec2/sig-1.bin
File: nvidia/gp107/acr/bl.bin
File: nvidia/gp107/acr/ucode_load.bin
File: nvidia/gp107/acr/ucode_unload.bin
File: nvidia/gp107/acr/unload_bl.bin
File: nvidia/gp107/gr/fecs_bl.bin
File: nvidia/gp107/gr/fecs_data.bin
File: nvidia/gp107/gr/fecs_inst.bin
File: nvidia/gp107/gr/fecs_sig.bin
File: nvidia/gp107/gr/gpccs_bl.bin
File: nvidia/gp107/gr/gpccs_data.bin
File: nvidia/gp107/gr/gpccs_inst.bin
File: nvidia/gp107/gr/gpccs_sig.bin
File: nvidia/gp107/gr/sw_bundle_init.bin
File: nvidia/gp107/gr/sw_ctx.bin
File: nvidia/gp107/gr/sw_method_init.bin
File: nvidia/gp107/gr/sw_nonctx.bin
File: nvidia/gp107/nvdec/scrubber.bin
File: nvidia/gp107/sec2/desc.bin
File: nvidia/gp107/sec2/image.bin
File: nvidia/gp107/sec2/sig.bin

File: nvidia/gp107/sec2/desc-1.bin
File: nvidia/gp107/sec2/image-1.bin
File: nvidia/gp107/sec2/sig-1.bin
File: nvidia/gp10b/acr/bl.bin
File: nvidia/gp10b/acr/ucode_load.bin
File: nvidia/gp10b/gr/fecs_bl.bin
File: nvidia/gp10b/gr/fecs_data.bin
File: nvidia/gp10b/gr/fecs_inst.bin
File: nvidia/gp10b/gr/fecs_sig.bin
File: nvidia/gp10b/gr/gpccs_bl.bin
File: nvidia/gp10b/gr/gpccs_data.bin
File: nvidia/gp10b/gr/gpccs_inst.bin
File: nvidia/gp10b/gr/gpccs_sig.bin
File: nvidia/gp10b/gr/sw_bundle_init.bin
File: nvidia/gp10b/gr/sw_ctx.bin
File: nvidia/gp10b/gr/sw_method_init.bin
File: nvidia/gp10b/gr/sw_nonctx.bin
File: nvidia/gp10b/pmu/desc.bin
File: nvidia/gp10b/pmu/image.bin
File: nvidia/gp10b/pmu/sig.bin
File: nvidia/gp108/acr/bl.bin
File: nvidia/gp108/acr/ucode_load.bin
File: nvidia/gp108/acr/ucode_unload.bin
File: nvidia/gp108/acr/unload_bl.bin
File: nvidia/gp108/gr/fecs_bl.bin
File: nvidia/gp108/gr/fecs_data.bin
File: nvidia/gp108/gr/fecs_inst.bin
File: nvidia/gp108/gr/fecs_sig.bin
File: nvidia/gp108/gr/gpccs_bl.bin
File: nvidia/gp108/gr/gpccs_data.bin
File: nvidia/gp108/gr/gpccs_inst.bin
File: nvidia/gp108/gr/gpccs_sig.bin
File: nvidia/gp108/gr/sw_bundle_init.bin
File: nvidia/gp108/gr/sw_ctx.bin
File: nvidia/gp108/gr/sw_method_init.bin
File: nvidia/gp108/gr/sw_nonctx.bin
File: nvidia/gp108/nvdec/scrubber.bin
File: nvidia/gp108/sec2/desc.bin
File: nvidia/gp108/sec2/image.bin
File: nvidia/gp108/sec2/sig.bin
File: nvidia/gv100/acr/bl.bin
File: nvidia/gv100/acr/ucode_load.bin
File: nvidia/gv100/acr/ucode_unload.bin
File: nvidia/gv100/acr/unload_bl.bin
File: nvidia/gv100/gr/fecs_bl.bin
File: nvidia/gv100/gr/fecs_data.bin
File: nvidia/gv100/gr/fecs_inst.bin
File: nvidia/gv100/gr/fecs_sig.bin
File: nvidia/gv100/gr/gpccs_bl.bin
File: nvidia/gv100/gr/gpccs_data.bin
File: nvidia/gv100/gr/gpccs_inst.bin
File: nvidia/gv100/gr/gpccs_sig.bin
File: nvidia/gv100/gr/sw_bundle_init.bin
File: nvidia/gv100/gr/sw_ctx.bin
File: nvidia/gv100/gr/sw_method_init.bin
File: nvidia/gv100/gr/sw_nonctx.bin
File: nvidia/gv100/nvdec/scrubber.bin

File: nvidia/gv100/sec2/desc.bin
File: nvidia/gv100/sec2/image.bin
File: nvidia/gv100/sec2/sig.bin

File: nvidia/tu10x/typec/ccg_primary.cyacd
File: nvidia/tu10x/typec/ccg_secondary.cyacd
File: nvidia/tu10x/typec/ccg_boot.cyacd

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Driver: wilc1000 - Atmel 802.11n WLAN driver for WILC1000

File: atmel/wilc1000_fw.bin
File: atmel/wilc1000_ap_fw.bin
File: atmel/wilc1000_p2p_fw.bin
File: atmel/wilc1000_wifi_firmware.bin

License: Redistributable. See LICENSE.atmel for details

Driver: hfi1 - Intel OPA Gen 1 adapter

File: hfi1_dc8051.fw
Version: 1.27.0
File: hfi1_fabric.fw
Version: 0x1055
File: hfi1_pcie.fw
Version: 0x4755
File: hfi1_sbus.fw
Version: 0x10130001

Licence: Redistributable. See LICENSE.hfi1_firmware for details

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Driver: knav_qmss_queue - TI Keystone 2 QMSS driver

File: ti-keystone/ks2_qmss_pdsp_acc48_k2_le_1_0_0_9.bin

Licence: Redistributable. See LICENCE.ti-keystone for details.

Driver: mwlwifi - Marvell mac80211 driver for 80211ac cards.

File: mwlwifi/88W8864.bin
Version: 7.2.8.6

File: mwlwifi/88W8897.bin
Version: 8.2.0.10

Licence: Redistributable. See LICENCE.Marvell for details.

Driver: mtk-vpu - Mediatek VPU video processing unit driver

File: vpu_d.bin
File: vpu_p.bin

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Driver: btmtk - MediaTek Bluetooth Driver

File: mediatek/mt7622pr2h.bin
Version: 20180621204904
File: mediatek/mt7668pr2h.bin
Version: 20180517181834

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: rk3399-dptx - ROCKCHIP rk3399 dptx firmware

File: rockchip/dptx.bin
Version: 3.1

Licence: Redistributable. See LICENCE.rockchip for details.

Driver: mt76x0 - MediaTek MT76x0 Wireless MACs

File: mediatek/mt7610u.bin
File: mediatek/mt7610e.bin
Version: 2.6
File: mediatek/mt7650e.bin
Version: 1.0.07-b370

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: mt76x2e - MediaTek MT76x2 Wireless MACs

File: mt7662.bin
Version: 1.9

File: mt7662_rom_patch.bin
Version: 0.0.2_P69

Licence: Redistributable. See LICENCE.ralink_a_mediatek_company_firmware for details

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Driver: mt76x2u - MediaTek MT76x2u Wireless MACs

File: mediatek/mt7662u.bin
Version: 1.5

File: mediatek/mt7662u_rom_patch.bin
Version: 0.0.2_P48

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: mt7615e - MediaTek MT7615e Wireless MACs

File: mediatek/mt7615_n9.bin
Version: 20190114
File: mediatek/mt7615_cr4.bin
Version: 20190114
File: mediatek/mt7615_rom_patch.bin
Version: 20190114

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: nfp - Netronome Flow Processor

Link: netronome/nic_AMDA0081-0001_1x40.nffw -> nic/nic_AMDA0081-0001_1x40.nffw
Link: netronome/nic_AMDA0097-0001_2x40.nffw -> nic/nic_AMDA0097-0001_2x40.nffw
Link: netronome/nic_AMDA0099-0001_2x10.nffw -> nic/nic_AMDA0099-0001_2x10.nffw
Link: netronome/nic_AMDA0081-0001_4x10.nffw -> nic/nic_AMDA0081-0001_4x10.nffw
Link: netronome/nic_AMDA0097-0001_4x10_1x40.nffw -> nic/nic_AMDA0097-0001_4x10_1x40.nffw
Link: netronome/nic_AMDA0099-0001_1x10_1x25.nffw -> nic/nic_AMDA0099-0001_1x10_1x25.nffw
Link: netronome/nic_AMDA0099-0001_2x25.nffw -> nic/nic_AMDA0099-0001_2x25.nffw
Link: netronome/nic_AMDA0096-0001_2x10.nffw -> nic/nic_AMDA0096-0001_2x10.nffw
Link: netronome/nic_AMDA0097-0001_8x10.nffw -> nic/nic_AMDA0097-0001_8x10.nffw
Link: netronome/nic_AMDA0058-0011_2x40.nffw -> nic/nic_AMDA0058-0011_2x40.nffw
Link: netronome/nic_AMDA0058-0012_2x40.nffw -> nic/nic_AMDA0058-0012_2x40.nffw
Link: netronome/nic_AMDA0078-0011_1x100.nffw -> nic/nic_AMDA0078-0011_1x100.nffw
File: netronome/nic/nic_AMDA0081-0001_1x40.nffw
File: netronome/nic/nic_AMDA0097-0001_2x40.nffw
File: netronome/nic/nic_AMDA0099-0001_2x10.nffw
File: netronome/nic/nic_AMDA0081-0001_4x10.nffw
File: netronome/nic/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/nic/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/nic/nic_AMDA0099-0001_2x25.nffw
File: netronome/nic/nic_AMDA0096-0001_2x10.nffw
File: netronome/nic/nic_AMDA0097-0001_8x10.nffw
File: netronome/nic/nic_AMDA0058-0011_2x40.nffw
File: netronome/nic/nic_AMDA0058-0012_2x40.nffw
File: netronome/nic/nic_AMDA0078-0011_1x100.nffw

File: netronome/nic-sriov/nic_AMDA0081-0001_1x40.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_2x10.nffw
File: netronome/nic-sriov/nic_AMDA0081-0001_4x10.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_2x25.nffw
File: netronome/nic-sriov/nic_AMDA0096-0001_2x10.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_8x10.nffw
File: netronome/nic-sriov/nic_AMDA0058-0011_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0058-0012_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0078-0011_1x100.nffw

Version: v2.1.16.1

File: netronome/flower/nic_AMDA0099.nffw
File: netronome/flower/nic_AMDA0096.nffw
File: netronome/flower/nic_AMDA0097.nffw
File: netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0081.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0081-0001_1x40.nffw -> netronome/flower/nic_AMDA0081.nffw
Link: netronome/flower/nic_AMDA0097-0001_2x40.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_2x10.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0081-0001_4x10.nffw -> netronome/flower/nic_AMDA0081.nffw
Link: netronome/flower/nic_AMDA0097-0001_4x10_1x40.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_2x25.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0096-0001_2x10.nffw -> netronome/flower/nic_AMDA0096.nffw
Link: netronome/flower/nic_AMDA0097-0001_8x10.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_1x10_1x25.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0058-0011_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw

Version: AOTC-2.10.A.38

File: netronome/bpf/nic_AMDA0081-0001_1x40.nffw
File: netronome/bpf/nic_AMDA0097-0001_2x40.nffw
File: netronome/bpf/nic_AMDA0099-0001_2x10.nffw
File: netronome/bpf/nic_AMDA0081-0001_4x10.nffw
File: netronome/bpf/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/bpf/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/bpf/nic_AMDA0099-0001_2x25.nffw
File: netronome/bpf/nic_AMDA0096-0001_2x10.nffw
File: netronome/bpf/nic_AMDA0097-0001_8x10.nffw
File: netronome/bpf/nic_AMDA0058-0011_2x40.nffw
File: netronome/bpf/nic_AMDA0058-0012_2x40.nffw
File: netronome/bpf/nic_AMDA0078-0011_1x100.nffw

Version: v2.0.6.124

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Driver: wil6210 - Qualcomm Atheros support for 11ad family of chips

File: wil6210.fw
File: wil6210.brd
Version: 5.2.0.18

Licence: Redistributable. See LICENSE.QualcommAtheros_ath10k for details

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Driver: venus - Qualcomm Venus video codec accelerator

File: qcom/venus-1.8/venus.mdt
File: qcom/venus-1.8/venus.b00
File: qcom/venus-1.8/venus.b01
File: qcom/venus-1.8/venus.b02
File: qcom/venus-1.8/venus.b03
File: qcom/venus-1.8/venus.b04

Version: 1.8-00109

File: qcom/venus-4.2/venus.mdt
File: qcom/venus-4.2/venus.b00
File: qcom/venus-4.2/venus.b01
File: qcom/venus-4.2/venus.b02
File: qcom/venus-4.2/venus.b03
File: qcom/venus-4.2/venus.b04

Version: 4.2

File: qcom/venus-5.2/venus.mdt
File: qcom/venus-5.2/venus.b00
File: qcom/venus-5.2/venus.b01
File: qcom/venus-5.2/venus.b02
File: qcom/venus-5.2/venus.b03
File: qcom/venus-5.2/venus.b04
File: qcom/venus-5.2/venus.mbn

Version: 5.2-00023

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Driver: imx-sdma - support for i.MX SDMA driver

File: imx/sdma/sdma-imx6q.bin
Version: 3.3
File: imx/sdma/sdma-imx7d.bin
Version: 4.2

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Driver: adreno - Qualcomm Adreno GPU firmware

File: qcom/a300_pfp.fw
Link: a300_pfp.fw -> qcom/a300_pfp.fw
File: qcom/a300_pm4.fw
Link: a300_pm4.fw -> qcom/a300_pm4.fw
File: qcom/a530_pfp.fw
File: qcom/a530_pm4.fw
File: qcom/a530v3_gpmu.fw2
File: qcom/a530_zap.b00
File: qcom/a530_zap.b01
File: qcom/a530_zap.b02
File: qcom/a530_zap.mdt

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Driver: mlxsw_spectrum - Mellanox Spectrum switch

File: mellanox/mlxsw_spectrum-13.1420.122.mfa2
File: mellanox/mlxsw_spectrum-13.1530.152.mfa2
File: mellanox/mlxsw_spectrum-13.1620.192.mfa2
File: mellanox/mlxsw_spectrum-13.1702.6.mfa2
File: mellanox/mlxsw_spectrum-13.1703.4.mfa2
File: mellanox/mlxsw_spectrum-13.1910.622.mfa2
File: mellanox/mlxsw_spectrum-13.2000.1122.mfa2

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Driver: cdns-mhdp - Cadence MHDP DP bridge

File: cadence/mhdp8546.bin
Version: 1.2.15

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Driver: fsl-mc bus - NXP Management Complex Bus Driver

File: dpaa2/mc/mc_10.10.0_ls1088a.itb
File: dpaa2/mc/mc_10.10.0_ls2088a.itb
File: dpaa2/mc/mc_10.10.0_lx2160a.itb
File: dpaa2/mc/mc_10.14.3_ls1088a.itb
File: dpaa2/mc/mc_10.14.3_ls2088a.itb
File: dpaa2/mc/mc_10.14.3_lx2160a.itb
File: dpaa2/mc/mc_10.16.2_ls1088a.itb
File: dpaa2/mc/mc_10.16.2_ls2088a.itb
File: dpaa2/mc/mc_10.16.2_lx2160a.itb

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Driver: mscc-phy - Microchip PHY drivers

File: microchip/mscc_vsc8574_revb_int8051_29e8.bin
File: microchip/mscc_vsc8584_revb_int8051_fb48.bin

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Driver: meson-vdec - Amlogic video decoder

File: meson/vdec/g12a_h264.bin
File: meson/vdec/g12a_vp9.bin
File: meson/vdec/gxbb_h264.bin
File: meson/vdec/gxl_h263.bin
File: meson/vdec/gxl_h264.bin
File: meson/vdec/gxl_hevc.bin
File: meson/vdec/gxl_hevc_mmu.bin
File: meson/vdec/gxl_mjpeg.bin
File: meson/vdec/gxl_mpeg12.bin
File: meson/vdec/gxl_mpeg4_5.bin
File: meson/vdec/gxm_h264.bin

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This quote is just too good to not pass on:

> ""BTW, I would have rejected the name Story Server because its
> initials are SS, the name of the secret police in Nazi
> Germany, probably the most despised pair of letters in western
> culture."" --- http://scriptingnewsarchive.userland.com/1999/12/13

Let no one say political correctness isn't dead....

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---

stdio.c
by Mark Gates <mgates@nlanr.net>
and Ajay Tirumalla <tirumala@ncsa.uiuc.edu>

---

input and output numbers, converting with kilo, mega, giga

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3. Mercury (Hg) – not over 0.1% by weight.
4. Hexavalent chromium (Cr6+) – not over 0.1% by weight.
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CN. KR. EN.
EY9411FRW205 20251024 S
发行:2025年10月