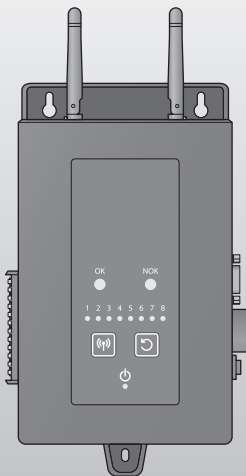


Operating Instructions Assembly Controller

Model No.:
EYFRW2



IMPORTANT

Read and follow the safety and operating instructions before using this product.
Do not use the wireless function outside the country where you purchased the product.
Doing so may violate the local laws and regulations.

Original instructions: English
Translation of the original instructions:
Other languages

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CLEANING AND STORAGE

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INFORMATION

GETTING STARTED

Operating Environment

You need to use a web browser to configure the controller.
Prepare a PC satisfying the following requirements.

Operating environment

Compatible OS	Windows 10 or later (supporting any of the web browsers below)
Web browser	Microsoft Edge version 102 or later or Google Chrome version 102 or later

- Some PCs are not available even if they meet the operating environment.
- Depending on the use environment etc. of your PC, the descriptions and screens in this Operating Instructions might be different from the actual descriptions and screens. Please be forewarned.
- The contents of this Operating Instructions are subject to change without prior notice.
- Any reproduction of the contents of this Operating Instructions in whole or in part is prohibited without permission.
- Figures in this Operating Instructions are for reference only.

[Note]

Always keep the firmware up to date.
You can find the latest firmware data on the following website which provides access to the Operating Instructions.
For how to update the firmware, see "Updating the Firmware".

Refer to P87

How to Access the Operating Instructions

The current version of the controller's Operating Instructions and other resources can be downloaded from the web site below.

<https://panasonic.net/electricworks/ecm/powerelctrictools/download/>



Trademark

- Microsoft and Windows are either registered trademarks or trademarks of Microsoft Corporation in the U.S. and/or other countries.
- The screenshots are used in accordance with the guidelines of Microsoft Corporation.

Other names including company names and product names in this Operating Instructions are trademarks or registered trademarks of their respective companies.
™ and ® may be omitted in this Operating Instructions.

Intended Use

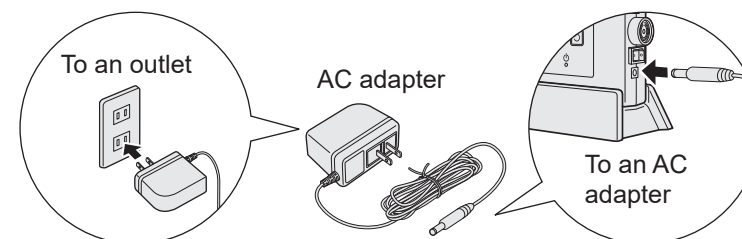
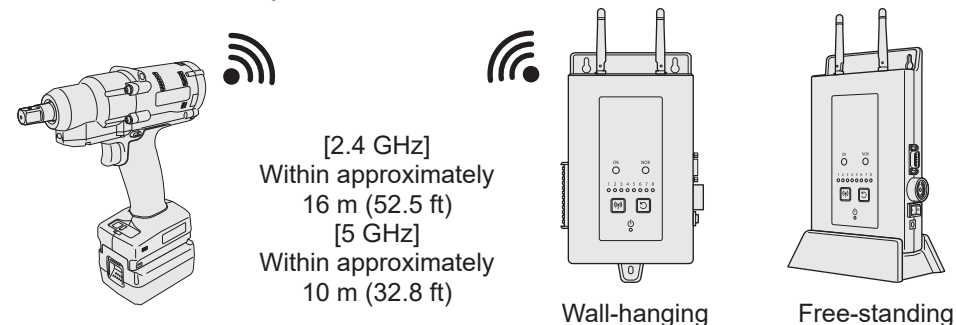
This product is a controller that wirelessly communicates with tools.
It can receive fastening history data from tools, make settings of tools, and control the quantity to fasten.



- 01 Connect to up to 8 tools.
- 02 Support 2.4 GHz and 5 GHz bands
- 03 Support a fastening control function and a history storing function

Setup

Install the controller in a range where wireless communication with tools is possible.
Supply power via an AC outlet and connect to external devices through communication interfaces as necessary.



- The controller contains a coin cell battery to keep the clock function (RTC) running. It is recommended that you keep the power on to reduce consumption of the internal coin cell battery.
- The wireless coverage may change depending on the environment.

SAFETY PRECAUTIONS Always adhere to the instructions

Below are the instructions you should always adhere to, to prevent human harm and property damage.

■ The severity of harm and damage caused by incorrect use is presented with the following.

 WARNING	May cause death or serious injury.
 CAUTION	May cause minor injury or property damage.

■ The content that should be observed is presented with the following symbols. (The following are examples)

	You MUST NOT do the action.
	You MUST do the action.

 WARNING	
 Mandatory	● Make sure that there are no buried objects such as conduits, water pipes, and gas pipes in the installation place. Touching such buried objects may cause electric shock or lead to electric leakage or gas leakage.
	● Insert the power plug all the way seated. Incomplete insertion may cause electric shock or heat generation resulting in fire. Do not use a damaged plug or loose socket.
	● Clean dust off the power plug routinely. Accumulated dust on the plug may absorb moisture and cause poor insulation resulting in fire. Disconnect the power plug and wipe it with dry cloth.
	● Use the specified power cord only. Using any other plug may cause electric shock, short circuit, or fire.
	● Keep the workplace sufficiently bright. Poor visibility in a dark workplace may lead to an accident or injury.

 WARNING	
 Prohibited	● Do not use a socket or wiring device in the manner of exceeding the rated value. Use 100 V-240 V AC only. Exceeding the rated value due to an overloaded socket may cause heat generation resulting in fire.
	● Do not damage the power cord or plug. (Avoid damaging, breaking, modifying, putting close to a heat source, bending with force, twisting, pulling, putting a heavy load on it, pinching, or binding) Using the damaged cord or plug may cause electric shock, short circuit, or fire. Check the cord and plug periodically and if any damage, consult your dealer.
	● Do not use the controller with a DC power supply, engine generator, or transformer. ● Do not use the controller in a place with flammable liquid or gas. Doing so may cause generation of heat, smoke, fire, or burst.
	● Do not install the controller on a mortar wall. Screwing it on a mortar wall may cause heat generation from wire mesh inside, resulting in fire in case of electric leakage.
	● Disconnect the power plug between uses. Keeping it connected may cause poor insulation resulting in electric shock or fire from electric leakage.
 No disassembly	● Do not modify the controller. Do not disassemble or repair the controller. Doing so may cause fire, electric shock, or injury. For repair, consult your dealer or our Customer Support Centre.
 Keep dry	Avoid the following use of charged tools. ● Do not use or leave them exposed to rain or moisture. ● Do not use them immersed under water. Doing so may cause smoke, fire, or burst.
 No wet hand	● Do not use a wet hand to connect or disconnect the power plug to or from the outlet. Doing so may cause electric shock.

BEFORE USE

⚠ CAUTION



Prohibited

- **Do not use the controller for any other purpose than intended.**
Doing so may cause injury.
- **Do not put the controller in a place accessible by a child.**
Doing so may cause an accident or trouble.
- **Do not use the controller with oil or other foreign material attached to it.**
Such oil or other foreign material may enter the inside, resulting in generation of heat, fire, or burst.
- **Do not store the main body in a place where the temperature may rise to 45 °C (113 °F) or higher.**
Doing so may lead to abnormal operation.
- **Do not work in an unusual position.**
Otherwise you may fall over and be injured.
Always stand on a stable footing and keep a good balance.
- **Do not use the controller when you are tired.**
Doing so may cause an accident or injury.
- **Do not allow a child or any other person who is not an operator to come near the workplace or touch the controller.**
Doing so may cause injury.
- **Do not use the controller with incompatible devices.**
Doing so may cause malfunction resulting in an accident.

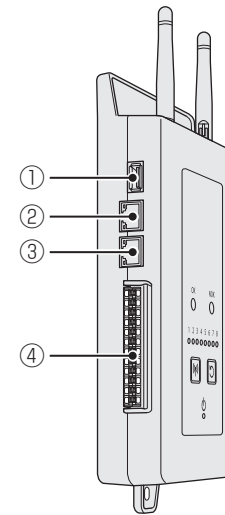


Mandatory

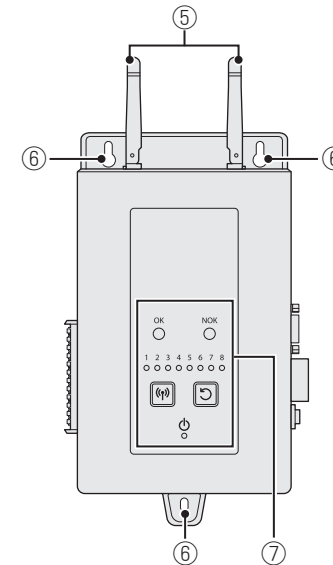
- **To install the controller on a wall, secure it with screws to prevent it from falling.**
You may be injured if it falls.
- **To disconnect the power plug, always hold the power plug without pulling the cord.**
Pulling the cord may cause electric shock or short circuit.
- **Before use, check the controller and other parts for any damage and confirm their normal operation.**
Failure to do so may lead to breakage resulting in injury.
- **Keep the workplace clean.**
A disordered workplace or work table may lead to an accident.
- **Consider well how to handle and work, pay attention to the surrounding environment, and use common sense during work.**
Failure to do so may cause an accident or injury.

Main Body

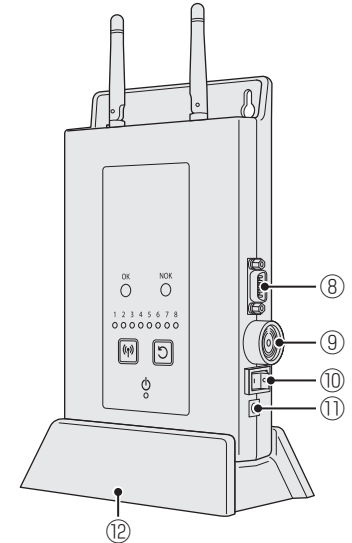
■ Left side



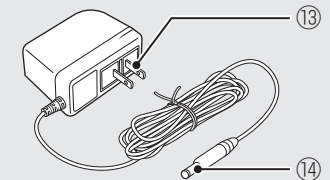
■ Front side



■ Right side



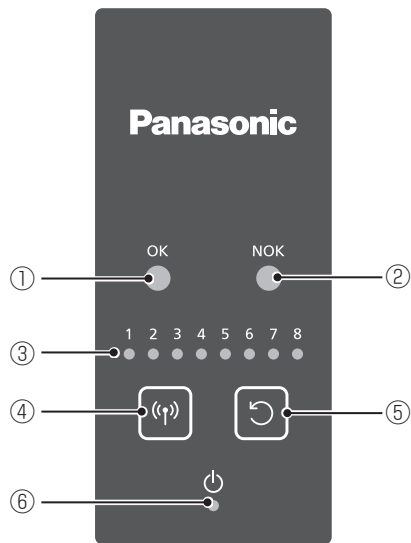
■ AC adapter



①	USB Port (USB-A)
②	Ethernet port (for maintenance)
③	Ethernet port (for network)
④	1~24 I/O port
⑤	Diversity antenna
⑥	Wall-hanging hole
⑦	Control panel

⑧	IOIOI Serial port (RS232C)
⑨	Buzzer
⑩	Power switch
⑪	AC adapter socket
⑫	Controller stand
⑬	Power plug
⑭	Power connector

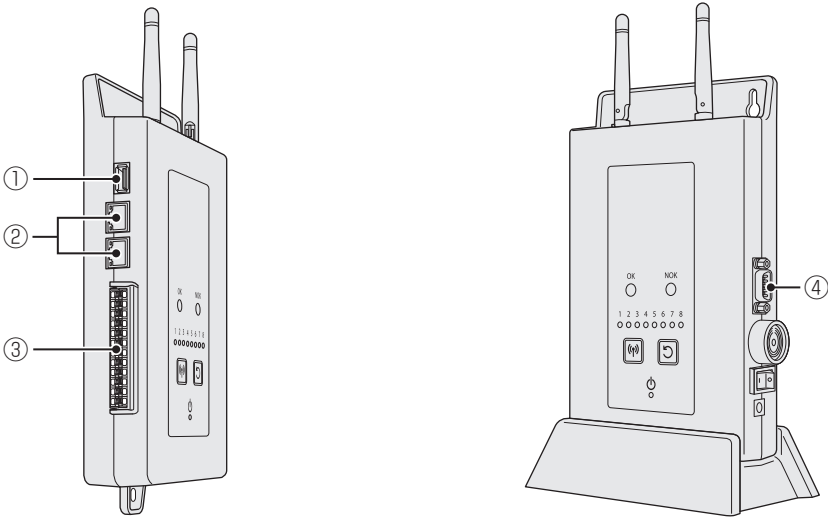
Control panel



①	Fastening OK lamp Blinking green: Barcode reading reception state. Solid green: A fastening completion signal has been received. Off: A fastening completion signal is not received yet.
②	Fastening NOK lamp Solid red: A fastening failure signal has been received. Off: A fastening failure signal is not received yet.

③	Communication lamp (No. 1 to No. 8) Solid blue: A tool has been registered. Blinking blue: A tool is being registered or out of coverage. Off: A tool is not registered yet.
④	Pairing key
⑤	Reset key
⑥	Power lamp Solid yellow: Power on (receiving mode) Off: Power off Blinking yellow: Error

Communication interface

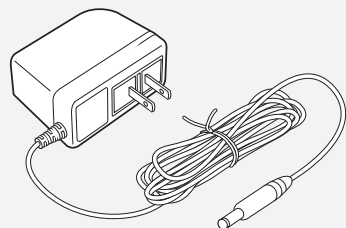


Interface		Details
①	USB	Use this port to connect a USB flash drive to update the firmware. * Directly connect a USB flash drive (without extension) A wireless receiver is connected to this port to connect a barcode reader. * Only wireless barcode readers are available. • USB2.0 USB-A × 1
②	Ethernet (for maintenance and network)	Use this port to connect to a PC for configuration or a host system. * Connect the Ethernet port (for maintenance) directly to a PC for configuration. (Do not use a hub) • 10Base-T/100Base-TX × 2 • Cable length: Less than 30 m (98.4 ft)
③	Input/output (I/O) terminal	Use this port to connect to an external device (e.g., a PLC). • 8 inputs and 8 outputs • Cable length: 10 m (32.8 ft) or less • Input terminal rating: 24 V DC, 50 mA • Output terminal rating: 30 V DC, 3 A
④	Serial port (RS232C)	Use this port to connect to an external device (e.g., a PLC). • RS232C × 1 • Cable length: 10 m (32.8 ft) or less

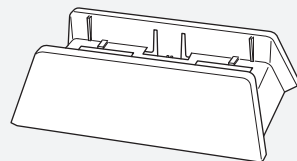
BEFORE USE

Accessory

■ **AC adapter × 1**
(WEYFRW1K7651)



■ **Controller stand × 1**
(EYFRW1F7001)

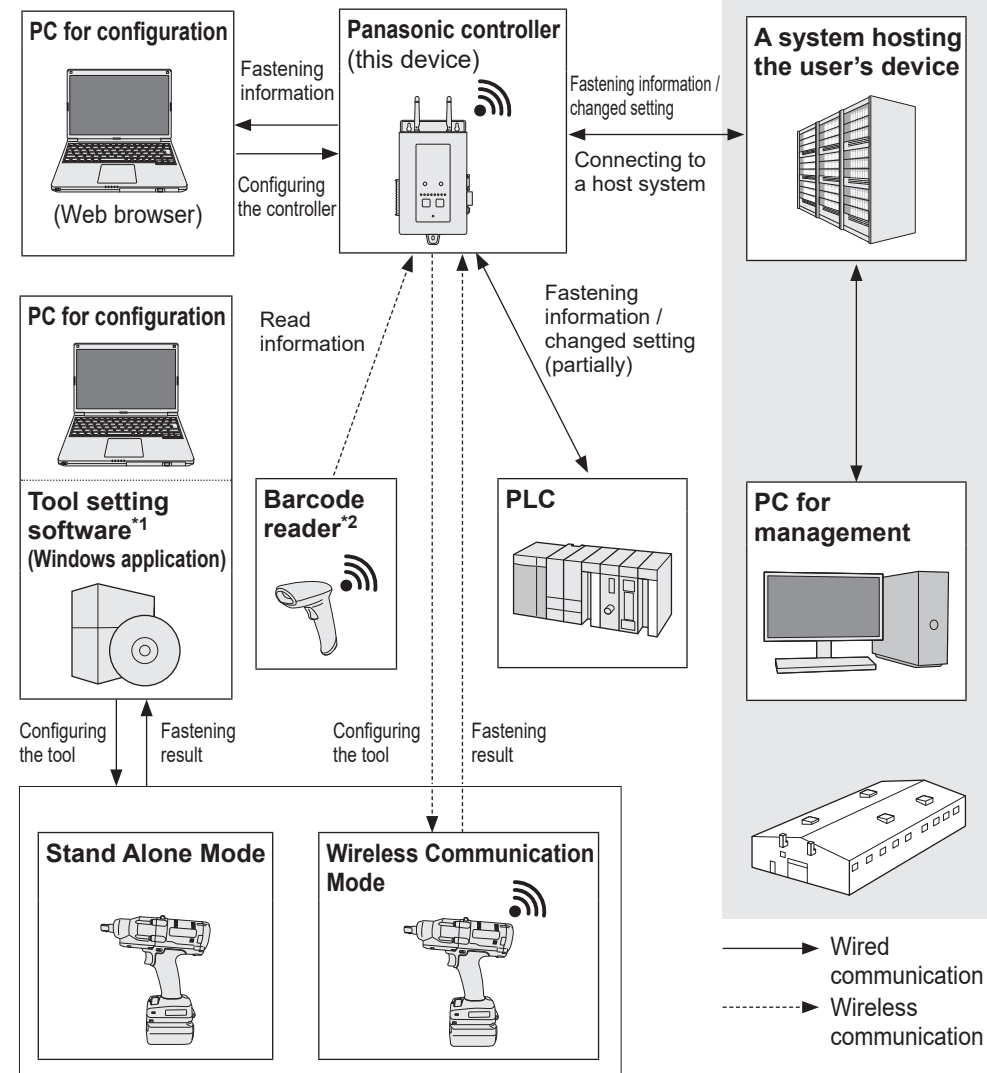


Consumables

■ **Coin cell battery (CR2450) × 1**
For how to replace, see “Replacing the Coin Cell Battery”.
Refer to P88



System Configuration



*1 The “tool setting software” can be downloaded from our web site. **Refer to P2**

*2 This is only supported by the firmware version 2.03.00 or later.

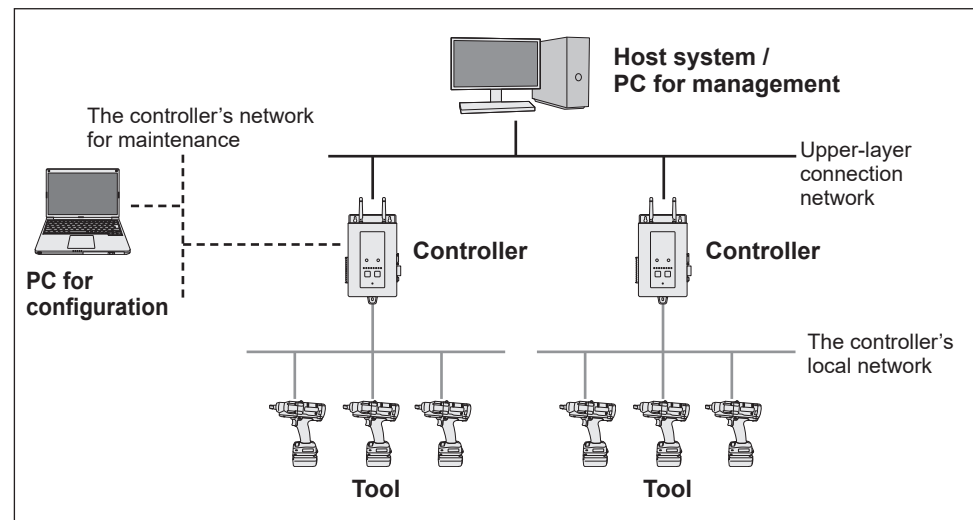
BEFORE USE

Typical Network Configurations

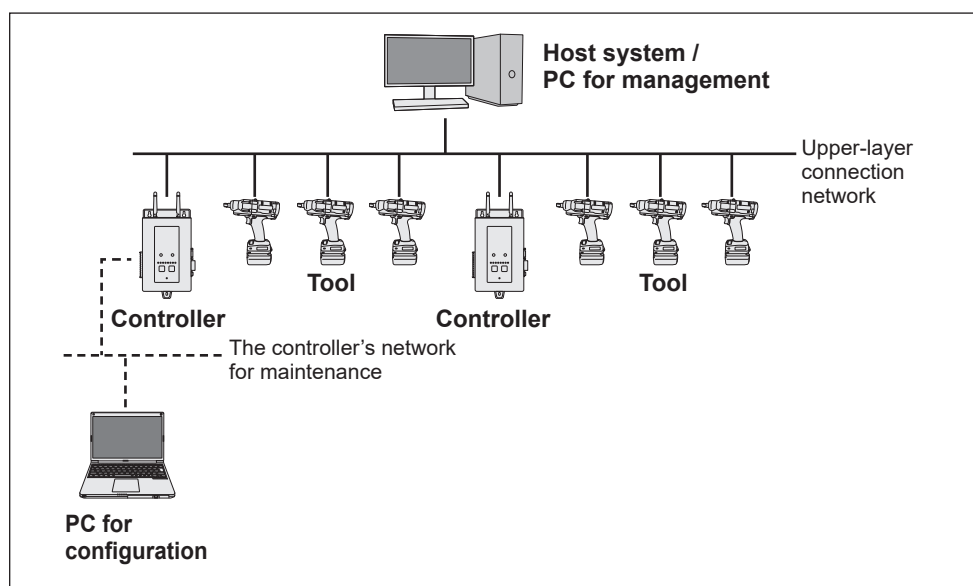
The controller can be used in the 3 configurations below.

■ Not managing tools' IP addresses

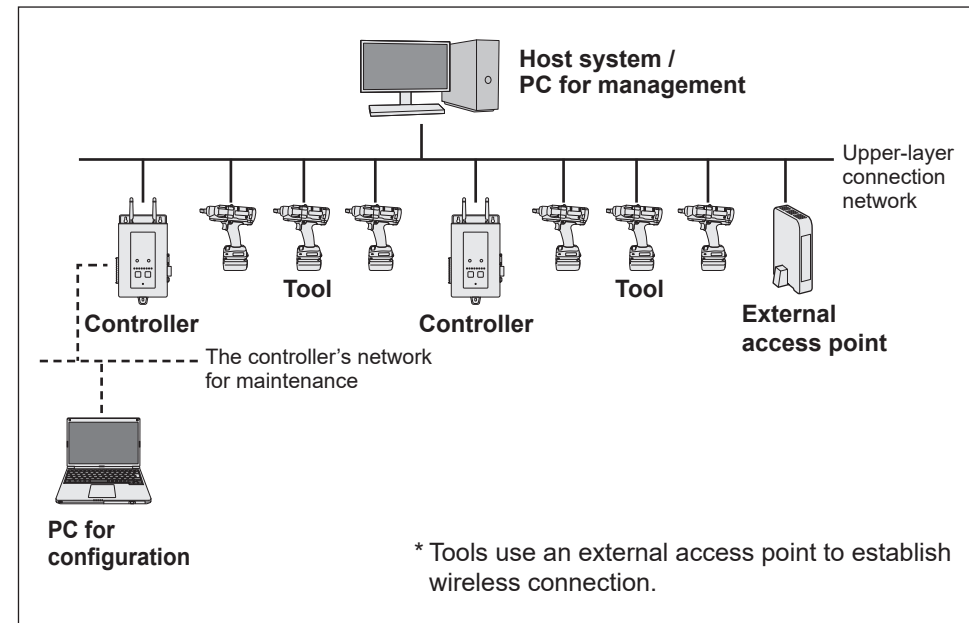
* Automatic assignment (using the access point built in the controller)



■ Managing tools' IP addresses (using the access point built in the controller)



■ Recognising tools' IP addresses (using external access points)



- * Use the system within your local network (with no Internet connection).
- * Be sure to check the IP address setting for network of the controller before starting use. (Change the default if necessary)

Applicable Tool Models List

Models that can be registered	EYFNH1WC/WP*1 EYFMH1WC/WP EYFMH2WC/WP
-------------------------------	---

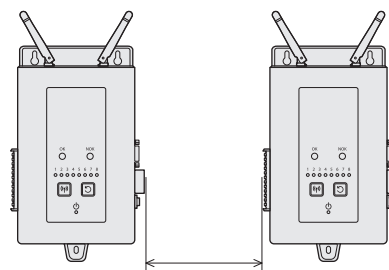
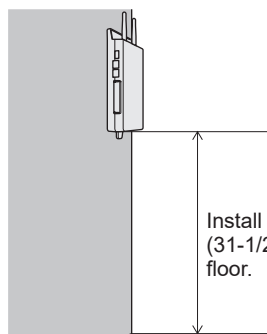
*1 This is only supported by the firmware version 2.02.00 or later.

Cautions for Installation

Install the controller 80 cm (31-1/2") or more above the floor. Keep 10 cm (3-15/16") or more between the installed controllers. (1 m (39-3/8") or more is recommended)
Keep obstructions away from the antennas of the installed controller.
The controller has 2 diversity antennas. Keep obstructions away from both antennas.

CAUTION

For safe installation, use wood screws with a nominal diameter of 3.5 mm (1/8") to 4.1 mm (5/32").

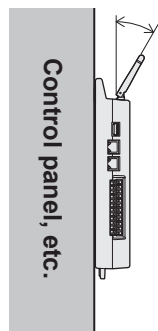


Keep 10 cm (3-15/16") or more between the installed controllers.

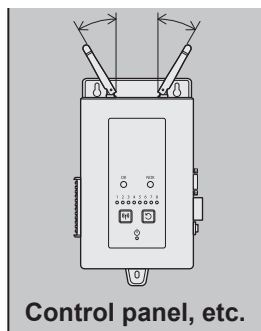
Adjust the antennas' angles if communication is unstable.

* Particularly for the controller installed on a metal panel, adjusting the antennas' angles may improve the communication stability.

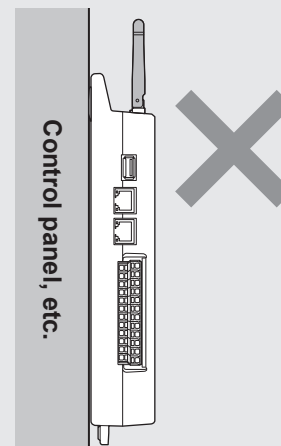
Tilt the antennas 30 to 45° from the wall.



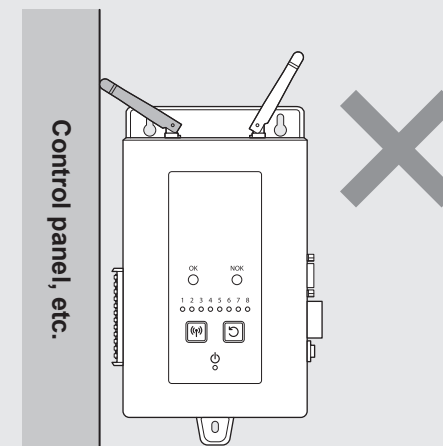
Tilt the antennas 30 to 45° outward when seen from the front.



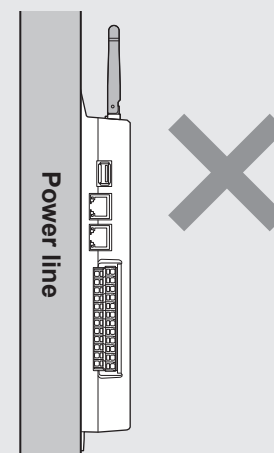
Avoid the following installation.



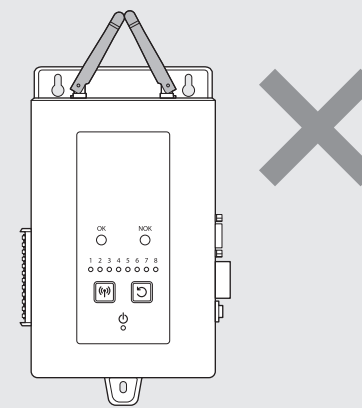
The antenna is in parallel with the control panel (metal panel) on the back side.



The antenna is in contact with the control panel (metal panel).



The controller is installed very close to a power line.



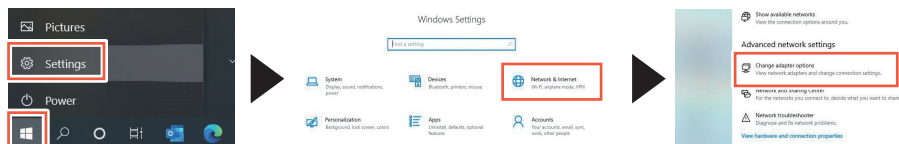
The antennas are in contact with each other.

PREPARATION BEFORE USE

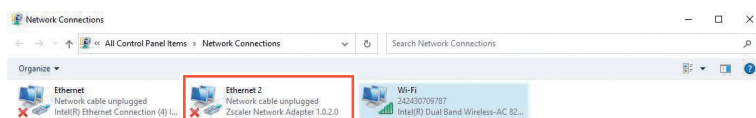
Network Settings on the PC for Configuration

Set the network settings on the PC for configuration as below when you connect it and the controller for the first time.

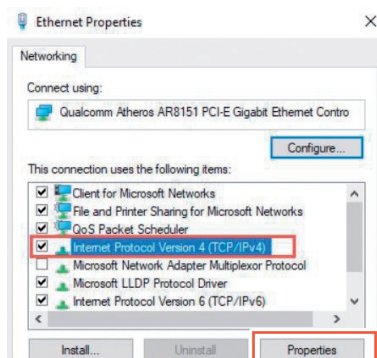
- 1 Click  on the lower left of the screen and click  (Settings) - [Network & Internet] - [Change adapter options].



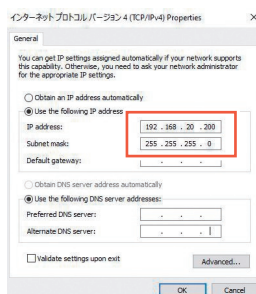
- 2 Right-click the device to connect and click [Properties].



- 3 Select "Internet Protocol Version 4" and click [Properties].



- 4 Set the "IP address" and "Subnet mask" as below.



IP address	192 . 168 . 20 . 200
Subnet mask	255 . 255 . 255 . 0

- * If you changed the IP address for the controller after initial connection, enable connection by returning the network settings (IP address and subnet mask) on the PC for configuration. At the time, set the IP address so that the controller and the PC for configuration belong to the same network.
- * Write down and keep the network settings of the PC for configuration (IP address and subnet mask) before you change it.
- * Leaving the default gateway unspecified (blank) is recommended.

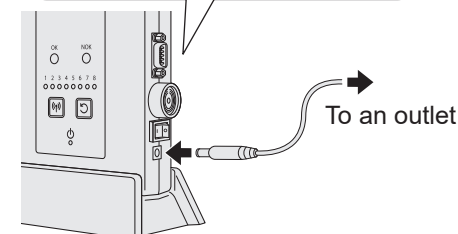
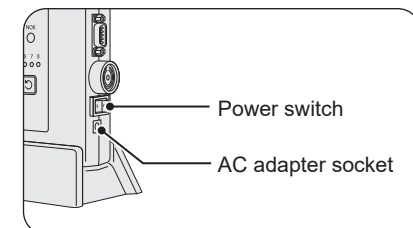
Displaying the Setting Screen

To configure the controller, access it via a web browser.
Display the controller's setting screen as below.

When you use the controller for the first time, remove the protective film from the coin cell battery.

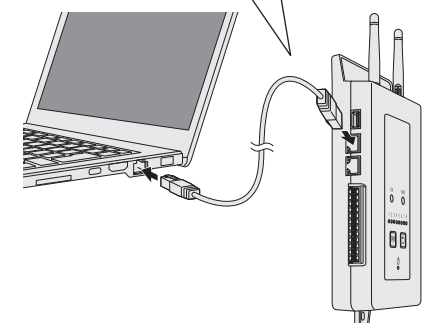
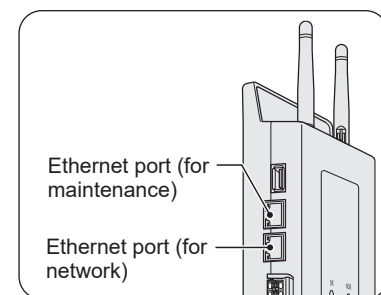
- 1 Turn the controller on.

- 1 Connect the supplied AC adapter to the controller and connect the power plug to an outlet.
- 2 Turn the controller's Power switch on.
 - * It takes a few tens of seconds to start up.
 - * During startup, the fastening OK lamp, fastening NOK lamp, and communication lamps (No. 1 to No. 8) blink together.
 - * Do not connect LAN cables.



- 2 Connect the controller to the PC for configuration with a LAN cable.

- 1 Connect a LAN cable to the Ethernet port of the controller.
 - * The controller has 2 Ethernet ports: one for maintenance and one for network. Use the one for maintenance for the first connection.
- 2 Connect to the PC for configuration with the LAN cable.



3 Start a web browser on the PC for configuration and access the controller.

- ① Start a web browser on the PC for configuration. (Microsoft Edge is recommended)
- ② Input the IP address of the controller in the address bar of the web browser.

* The default IP address for the Ethernet port (for maintenance) is "192.168.20.10".

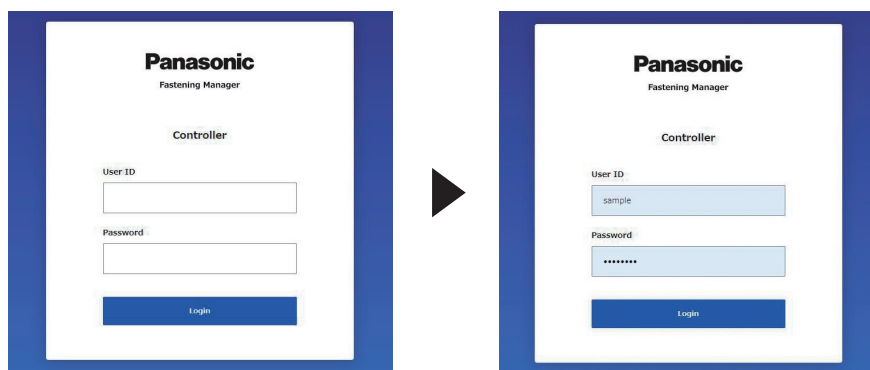
In the address bar of the web browser, input "http://192.168.20.10/controller" to access.

* Inputting "192.168.20.10/controller" only also allows for access.

* For how to access via the Ethernet port (for network), see "Connecting via Network". **Refer to P21**

* The IP address should also be set on the PC for configuration.

- ③ In the displayed login screen, input the user ID and password.
 - * The user ID and password for the initial login are shown below.
- ④ The top page (the initial page of the setting screen) is displayed.



User ID and password for the initial login

Log in with the user ID and password below.

■ User ID: **root**

■ Password: **abcABC123**

* The account type for the initial login is "default".

For the account types, see "Account Types (Authorities)". **Refer to P19**

* Only account creation is possible when you log in with the user ID and password above. Create a new account before starting use.

* For security, changing the password above is recommended after the initial login.

Account Types (Authorities)

Below are the account types. Use them according to the applications.

Account Type	Function
Default	- For the initial login. Refer to P18 - Adding or changing a user account.
Administrator	- Viewing the fastening history. - Configuring the controller. - Configuring tools. - Adding or changing a user account. * Create at least one administrator account.
General	Viewing the fastening history (including viewing the work monitor).

Up to 10 accounts can be registered.

Thus, more than one operator can log in simultaneously.

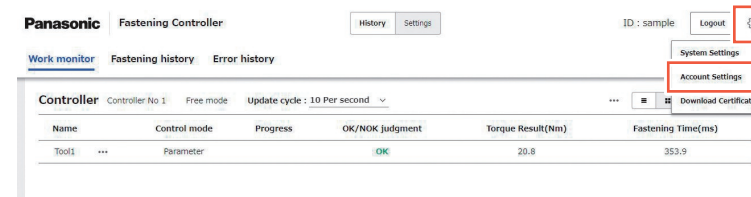
* Only one account can log in as administrator at the same time.

When multiple accesses are attempted, the last session takes priority.

Creating a User Account

Create a new account before starting use.

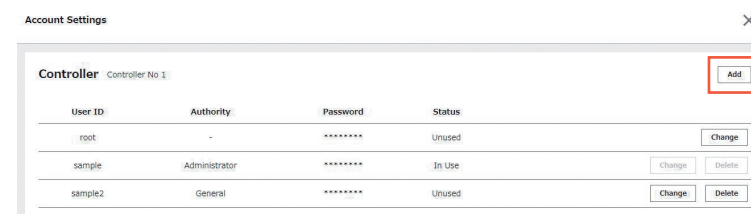
- 1 In the top page (the initial page of the setting screen), click the option key on the upper right and select "Account Settings".
The "Account Settings" screen is displayed.



- 2 In the "Account Settings" screen, click [Add].

The "Add account" screen is displayed.

• Click [Change] to change the account and [Delete] to delete the account.



PREPARATION BEFORE USE (cont.)

3 Input “User ID” and “Password”, select “Authority”, and click [Add].

- * Create an administrator account to configure tools.
- * For a password, always use a combination of 3 or more types from upper case, lower case, number, and symbol.

[Reference] If you lost the user ID or password

■ General account

- [Method 1] Log in as administrator and make changes to the account concerned.
- * A general user cannot change the user ID and password and needs to ask an administrator to change them.
- [Method 2] Log in with a newly created administrator account and make changes to the account concerned.
- * Log in with the user ID and password for the initial login and create a new administrator account. **Refer to P18**

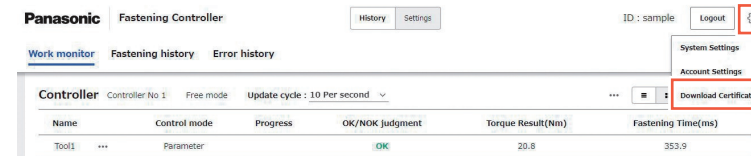
■ Administrator account

- A) When multiple administrator accounts have been created
- [Method 1] Log in with another administrator account and make changes to the account concerned.
- [Method 2] Log in with a newly created administrator account and make changes to the account concerned.
- * Log in with the user ID and password for the initial login and create a new administrator account. **Refer to P18**
- [Method 3] Initialise the settings if you lost IDs and passwords of all administrator accounts. **Refer to P85**
- B) When only one administrator account has been created
- [Method 1] Log in with a newly created administrator account and make changes to the account concerned.
- * Log in with the user ID and password for the initial login and create a new administrator account. **Refer to P18**
- [Method 2] Initialise the settings if you lost IDs and passwords of all administrator accounts. **Refer to P85**

Obtaining a Certificate

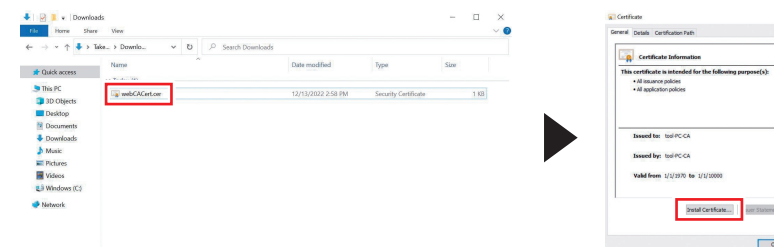
A certificate is necessary to access the controller via the Ethernet port (for network). You can obtain a certificate as below.

- 1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “Download Certificate”. A certificate datum is downloaded to the PC for configuration.

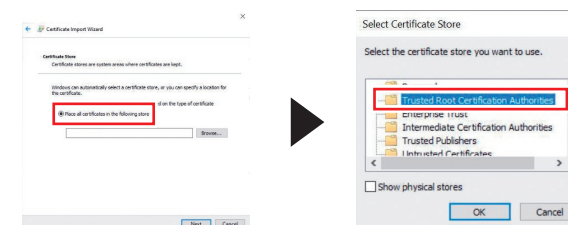


- 2 Install the certificate in the “PC for configuration used to access the controller via network”.

① Double-click the downloaded certificate datum and select “Install Certificate”.



② Select “Place all certificates in the following store” and then select “Trusted Root Certification Authorities”.



Connecting via Network

In the address bar of the web browser, input “https://XXX.XXX.XXX.XXX/controller” to connect the controller via the Ethernet port (for network).

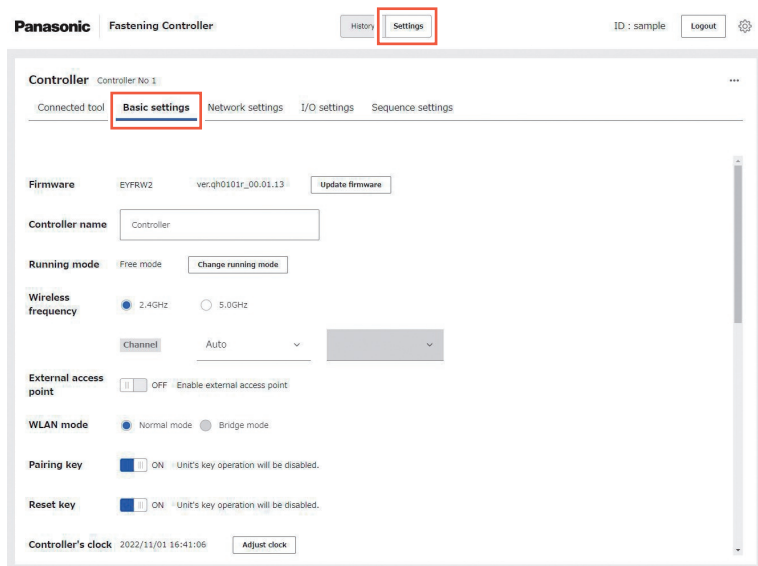
- * “XXX.XXX.XXX.XXX” is an IP address.
- * The default IP address is “192.168.0.10”. If you changed the default address, input the changed one. **Refer to P26**

CONFIGURING THE CONTROLLER

Basic settings

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.

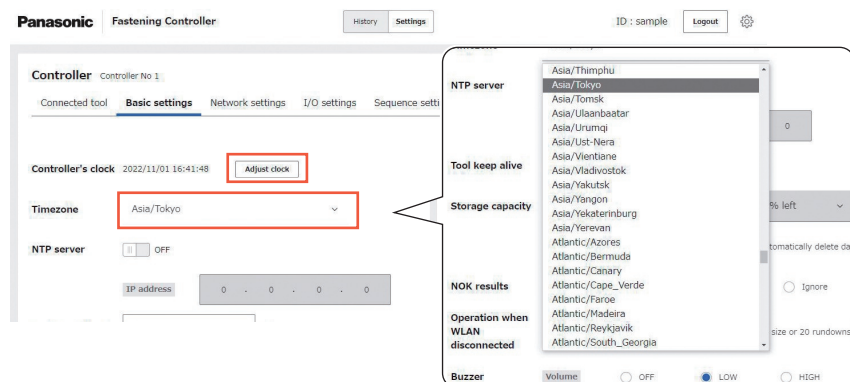
You can configure the controller.



Time setting

Select “Timezone” and then click [Adjust clock].
The time is updated.

- The time is not set yet at the time of shipment. Be sure to set the time when you use the controller for the first time.



* If you use an NTP server, input the IP address.

Radio frequency and channel setting

You can set the frequency to use.

Select “2.4GHz” or “5GHz” and then the channel to use.

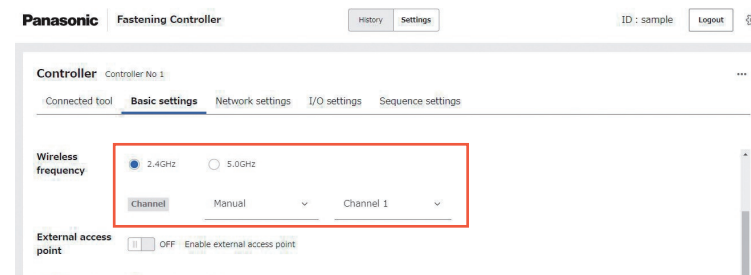
* Selectable channels differ between “2.4GHz” and “5GHz”.

* You can set “Auto Channel”.

The controller automatically selects available channels in the surrounding environment when it turns on.

The setting may be effective against radio interference.

* When installing multiple controllers close to each other, do not set adjacent channels.



Setting items

Firmware

The firmware version of the controller is displayed.

Click [Update firmware] to update the firmware.

For how to update, see “Updating the Firmware”. **Refer to P87**

Controller name

You can register the controller's name.

Use a maximum of 32 alphanumeric characters.

[Default] Controller

[Setting range] Up to 32 alphanumeric characters

* For symbols, only “-” (hyphen), “_” (underscore), and “ ” (half-width space) can be used.

Running mode

Select the running mode of the controller.

[Default] Free mode

[Setting range] Free mode / Repeat mode (Basic mode / Sequence mode) / External control mode

Wireless frequency

Select the frequency channel to use for wireless communication.

[Default] 2.4GHz

[Setting range] 2.4GHz (Auto / Channel 1 to 13) / 5GHz (Auto / Channel 36, 40, 44, 48)

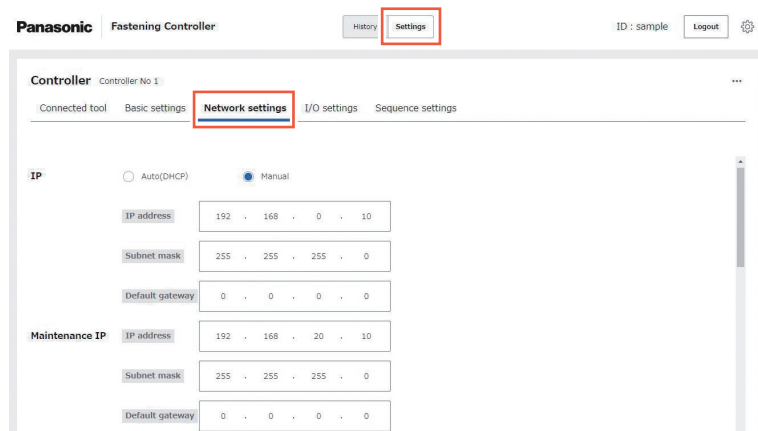
External access point
You can enable communication via an external access point. Refer to P69 [Default] OFF (disabled) [Setting range] OFF (disabled) / ON (enabled) * WLAN mode: This setting is for operation without using an external access point. Normal mode: When not managing tool's IP addresses (automatic assignment) Bridge mode: When managing (specifying) tools' IP addresses
Pairing key
You can enable the Pairing key. [Default] ON (enabled) [Setting range] OFF (disabled) / ON (enabled)
Reset key
You can enable the Reset key. [Default] ON (enabled) [Setting range] OFF (disabled) / ON (enabled)
Controller's clock
Set the controller's clock. Click [Adjust clock] to update the time.
Timezone
You can set a desired time zone when adjusting the controller's clock.
NTP server
Set an NTP server if you use automatic clock adjustment.
Tool keep alive
Set the time interval when the controller checks availability of tools in the wireless communication mode. Tools not responding are detected as offline and then disconnected. [Default] 30 s [Setting range] 10 s to 3600 s

Storage capacity
Enable or disable notification of low storage capacity and set the behaviour in case of capacity shortage. [Default] Notification - OFF, Operation when capacity is insufficient - Automatically delete data [Setting range] Notification - OFF/ON (remaining capacity 10/20/30/40/50%), Operation when capacity is insufficient - Suspend operation / Automatically delete data The default setting is "Automatically delete data". Consider well how to handle data before selecting "Suspend operation" as necessary.
NOK results
Select how to handle the fastening failure results. [Default] Store data only [Setting range] Report to system / Store data only / Ignore
Operation when WLAN disconnected
Select the behaviour in case of temporary disruption of wireless communication. [Default] Suspend tool [Setting range] Suspend tool / Enable fastening (Until batch size or 20 rundowns) For details, see "TOOLS' BEHAVIOUR WITH WIRELESS COMMUNICATION DISCONNECTED". Refer to P76
Buzzer
Select the volume and meaning of the buzzer. [Default] Volume - LOW, Beep - All checked [Setting range] Volume - OFF/LOW/HIGH, Beep - Check or uncheck each item
Barcode reader settings
You can connect a barcode reader to add read information to the fastening history data. [Reading Test] Displays the information read by the barcode reader. [Bluetooth settings] These settings are used when you connect a Bluetooth-type barcode reader. The "Search" button displays connectable devices. Use "Pairing" to select a device to connect. If it is already connected, the MAC address/device name will be displayed. You can disconnect it by selecting "Cancel Registration".

Network Settings

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Network settings” tab.

You can make network settings of the controller.



Setting items

IP

Set the IP address of the Ethernet port (for network).

[Default] Manual

[Setting range] Auto (DHCP) / Manual

* For “Manual”

[Default] IP address - 192.168.0.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Maintenance IP

Set the IP address of the Ethernet port (for maintenance).

[Default] IP address - 192.168.20.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

WLAN

Set the IP address (on the controller's side) for wireless communication with tools.

[Default] IP address - 192.168.100.1
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Atlas Open Protocol

Set the parameters related to Atlas Open Protocol.

For details, see “Connecting via Open Protocol Communication”. **Refer to P57**

RS232C

This is a setting specific to TOYOTA MOTOR CORPORATION. Control from external devices is possible.

[Default] Disable

[Setting range] Disable / Enable

Step flow after tightening NG

This setting determines whether you can proceed to the next tightening in case of a tightening NG result.

[Default] Keep

[Setting range] Next (The next tightening can be performed.) / Keep (The next tightening cannot be performed.)

Access point

Set the internal access point for wireless communication with tools.

[Default] SSID - Controller's model number-MAC address

Security - WPA2

[Setting range] SSID - A maximum of 32 alphanumeric characters
Security - WPA2

External access point

Set the external access point to use.

[Default] SSID - Blank

Security - Blank

Password - Blank

[Setting range] SSID - A maximum of 32 alphanumeric characters
Security - Open/WPA2
Password - 8 to 63 alphanumeric characters

* For symbols, only “”, “¥”, “”, and “” (back quote) can be used.

* The option is enabled only when “External access point” has been set to “ON” in the basic setting.

- For the IP addresses for “IP” and “Maintenance IP”, do not use the same subnet. (When you set a default value (255.255.255.0) in “Subnet mask”, set different values in the part corresponding to “192.168.0” or “192.168.20”.)
- Only one of “Atlas Open Protocol” and “RS232C” can be turned ON. They cannot be used simultaneously.

Starting the Pairing Mode on the Controller

You can put the controller in the pairing mode by “Using the key on the unit” or “Setting in the setting screen”.

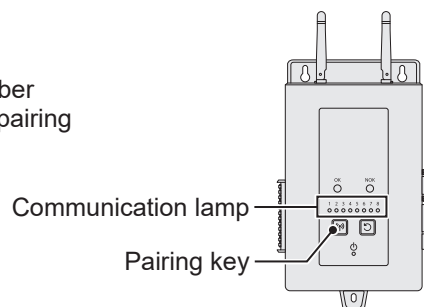
During 2 minutes of the pairing mode, start the pairing mode on a tool within the coverage to automatically establish pairing.

If pairing is not established within the time, the pairing mode will end.

* After you attempt to start pairing, it may take some time until the controller enters the pairing mode.

Using the key on the unit

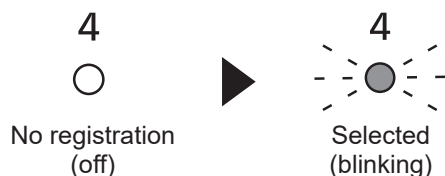
Use the Pairing key on the controller unit.
Select the communication lamp of the number with no registration (lamp off) and hold the pairing key down to enter the pairing mode.
See the following procedure for details.



(To register Tool No. 4)

1 Press the Pairing key on the controller 4 times to select Tool No. 4.

Communication lamp No. 4 blinks.



2 While No. 4 is selected, hold down the Pairing key on the controller to enter the pairing mode of Tool No. 4.

In the pairing mode, Communication lamp No. 4 starts blinking rapidly.



3 Operate Tool No. 4 to establish pairing.

Communication lamp No. 4 stays lit. For how to operate the tool, see “Starting the Pairing Mode on a Tool”. **Refer to P30**

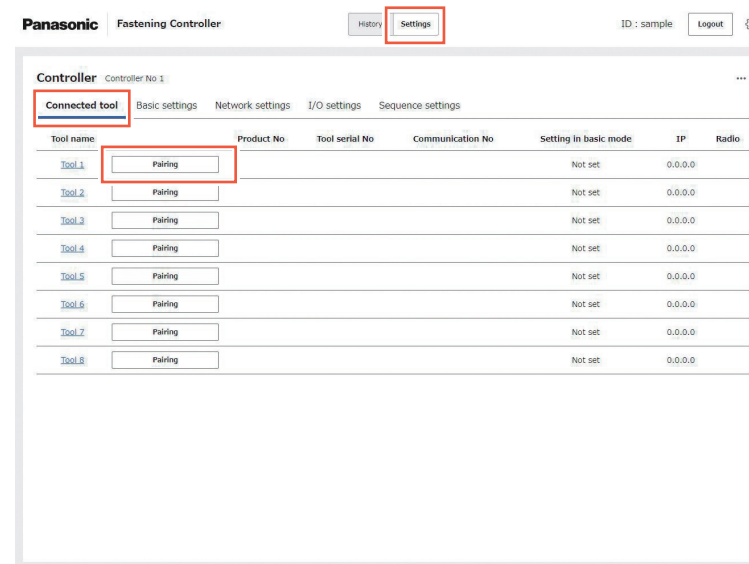


Setting in the setting screen

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

In the “Connected tool” screen, click [Pairing] of the desired tool number.

After the controller enters the pairing mode, perform the procedure in “Starting the Pairing Mode on a Tool”. **Refer to P30**



<For reference> Replacing with a spare tool

When replacing a defective paired tool with a new one with the same model number, cancel pairing **Refer to P30** and then conduct pairing **Refer to P28** so that the fastening parameters and other settings can be automatically transferred.

* To pair with a tool with a different product number, cancel pairing to delete the current pairing information before pairing with it. **Refer to P34**

Display after pairing is completed

After pairing is completed, if the setting screen does not display the information of the paired tool, conduct display update in the setting screen.

* In the “Bridge mode” or when “External access point” is enabled, set the tool’s IP address before starting pairing registration.

Starting the Pairing Mode on a Tool

Put the controller in the pairing mode before starting the pairing mode on a tool.

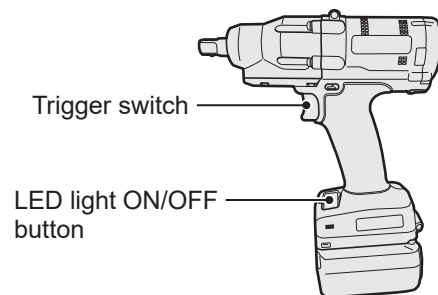
■ Procedure

- 1 Set the battery pack. While holding down the LED light ON/OFF button, pull the Trigger switch.**

The tool enters the pairing mode. Wireless communication is automatically established and pairing registration is completed.

* For details, see the tool's Operating Instructions.

* If pairing fails, cancel pairing on the controller and then try again.



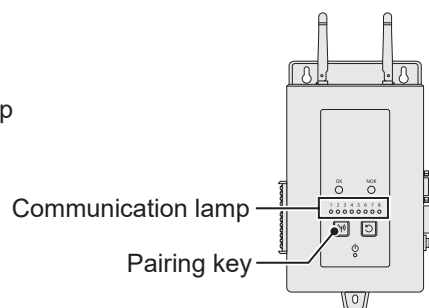
Cancelling Pairing

You can cancel pairing registration on the controller by “Using the key on the unit” or “Setting in the setting screen”.

■ Using the key on the unit

Use the Pairing key on the controller unit. Select the communication lamp of the tool number you want to cancel registration (lamp on) and hold the pairing key down to cancel pairing registration.

See the following procedure for details.



(To cancel Tool No. 4)

- 1 Press the Pairing key on the controller 4 times to select Tool No. 4.**

Communication lamp No. 4 blinks.



- 2 While No. 4 is selected, hold down the Pairing key on the controller to cancel pairing registration of Tool No. 4.**

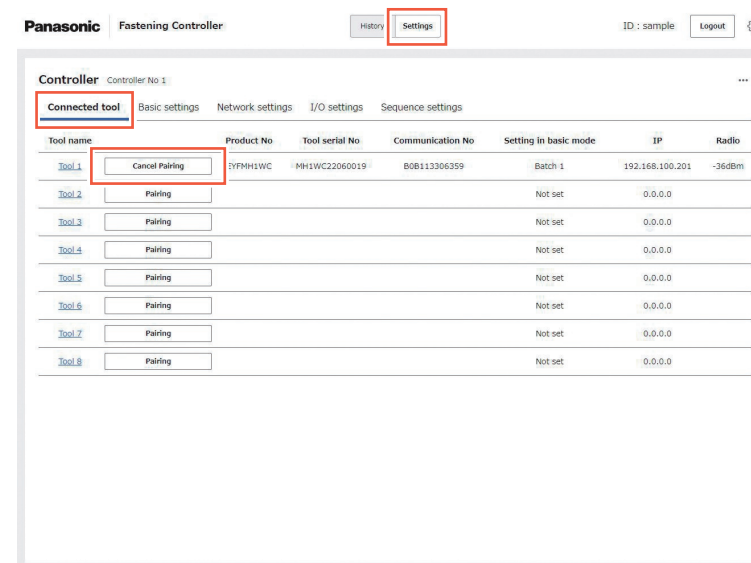
When pairing is cancelled, Communication lamp No. 4 stops blinking and turns off.



■ Setting in the setting screen

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

In the “Connected tool” screen, click [Cancel Pairing] of the desired tool number.



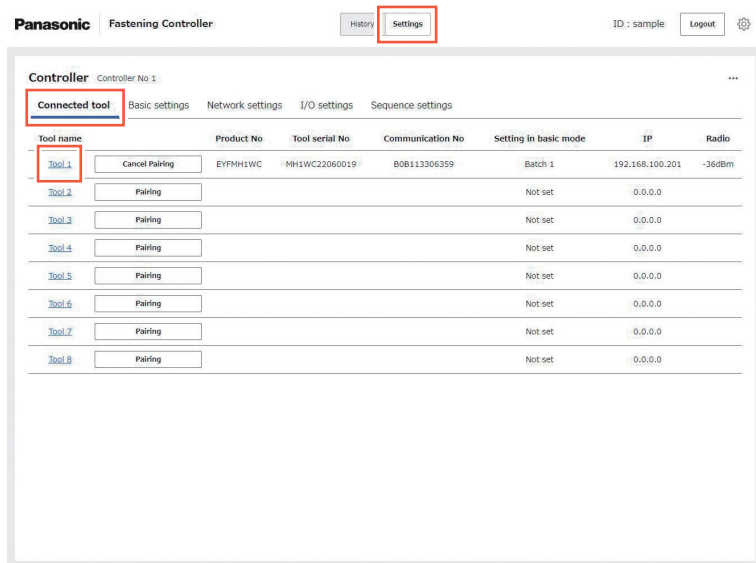
* If the controller cannot communicate with the tool due to the tool being turned off or any other reason, check [Force to unpair] in the pairing cancellation confirmation dialogue.

Displaying the Tool Screen

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

In the “Connected tool” screen, click the desired tool number.

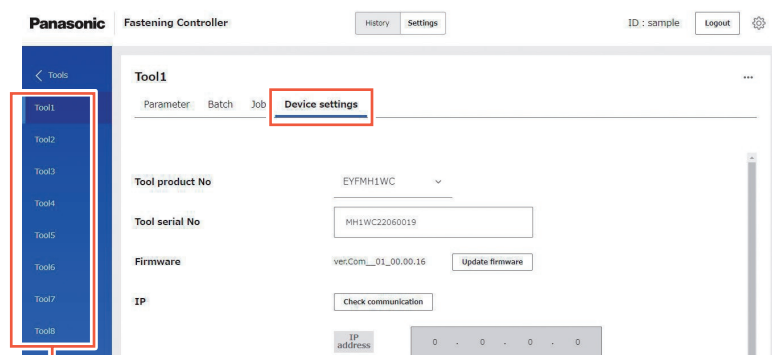
The screen for the tool number is displayed.



Displaying the Tool Setting Screen

From the “Device settings” tab in the screen for the tool number, you can make basic settings of the tool and enter common parameters.

* To switch the tool, select the desired one from the tool list.



Tool list

Tool Setting Items

Tool product No

Select the tool product number.

[Default] Blank

[Setting range] Selectable from the pull-down menu

* Automatically selected if you establish pairing beforehand.

* The tool product number cannot be changed after pairing. Cancel pairing and then change it.

Tool serial No

You can set and display the tool's unit identification.

[Default] 5-digit model ID + 8-digit serial number (2-digit manufacturing year + 2-digit month + 4-digit production lot)

[Setting range] 13 to 16 alphanumeric characters

* The model number may not be recognised correctly if the information is changed. Do not change it unless required by the management rule.

Firmware

The firmware version of the tool's communication part is displayed.

Click [Update firmware] to update the firmware.

For how to update, see “Updating the Firmware”. **Refer to P87**

IP

Set the IP address (on the tool's side) for wireless communication with tools.

[Default] IP address - 192.168.100.201 (Tool 1) to 208 (Tool 8)

Subnet mask - 255.255.255.0

Default gateway - 0.0.0.0

* They all become “0.0.0.0” in the Bridge mode or when “External access point” is enabled.

Tool's clock

The tool's clock is displayed. Click [Adjust to controller] to adjust the time.

• For other setting items, see the tool's Operating Instructions.

Deleting the Registration Information

To stop use of a tool or pair a tool with a different product number, delete the pairing information.

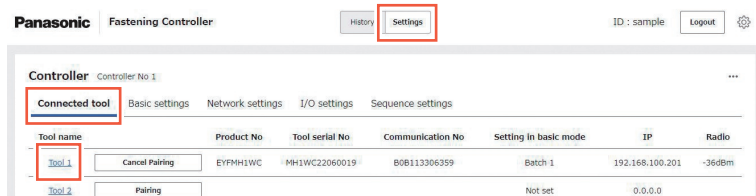
* Cancel pairing beforehand.

1 In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

The “Connected tool” screen is displayed.

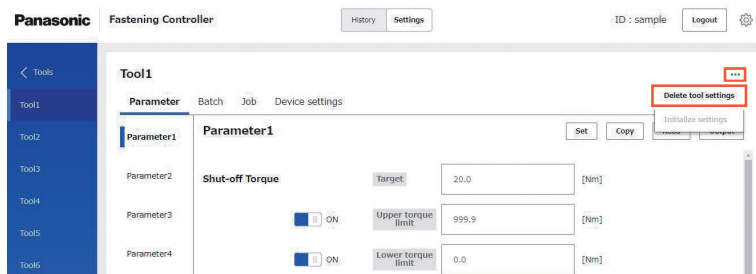
2 In the “Connected tool” screen, click the desired tool number.

The screen for the tool number is displayed.

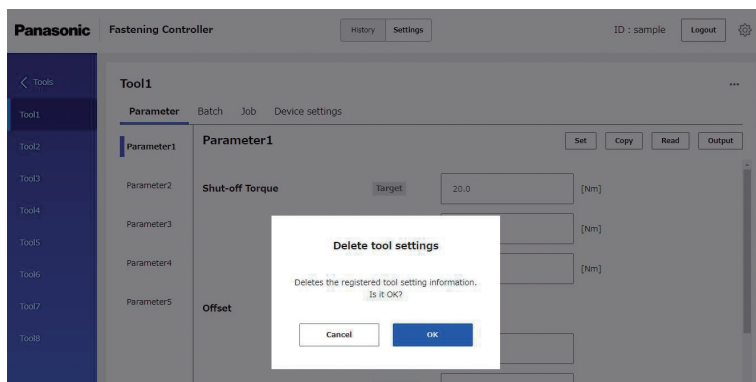


3 Click ... (tool option key) and then [Delete tool settings].

The “Delete tool settings” screen is displayed.



4 In the “Delete tool settings” screen, click [OK].



Resetting to Factory Settings

You can reset a tool to its factory settings.

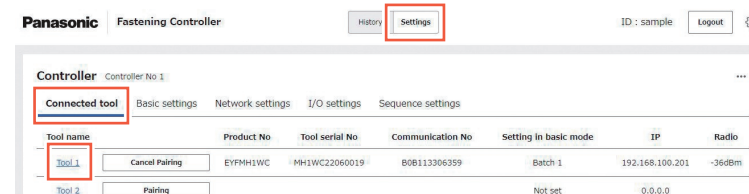
* Resetting cancels pairing.

1 In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

The “Connected tool” screen is displayed.

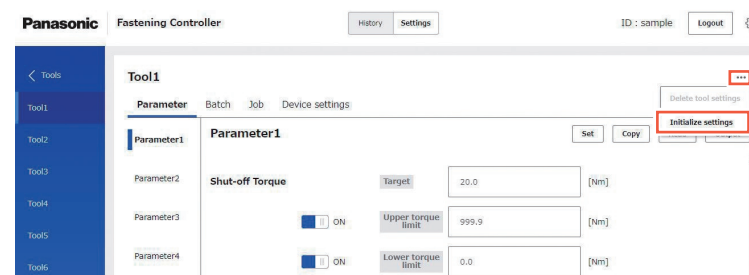
2 In the “Connected tool” screen, click the desired tool number.

The screen for the tool number is displayed.

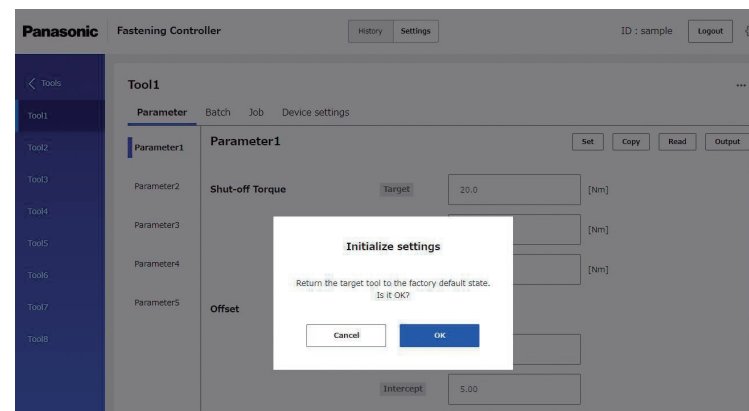


3 Click ... (tool option key) and then [Initialize settings].

The “Initialize settings” screen is displayed.



4 In the “Initialize settings” screen, click [OK].



SETTING FASTENING PARAMETERS OF TOOLS

Setting Parameters

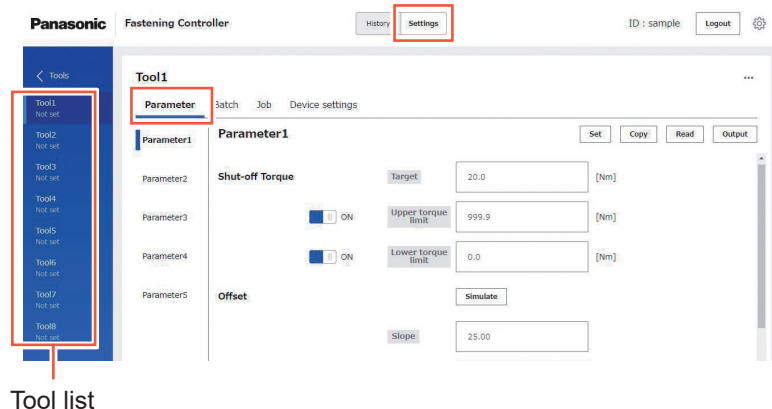
In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.

In the “Connected tool” screen, click the desired tool number.

In the screen for the tool number, select the “Parameter” tab to make settings.

You can set five parameters (Parameter 1 to 5) for each tool.

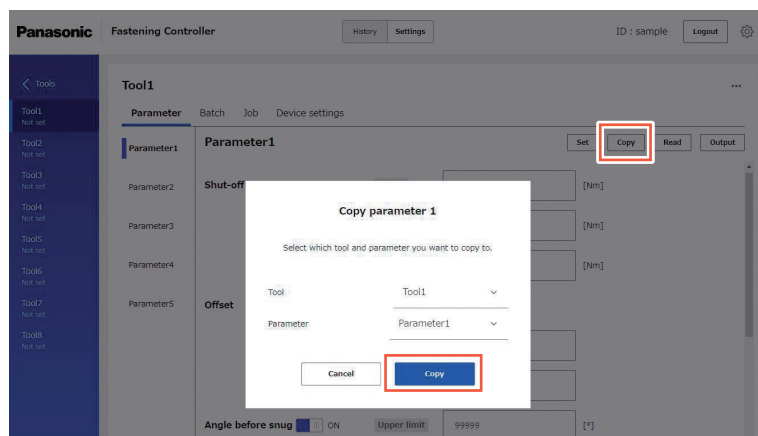
* To switch the tool, select the desired one from the tool list.



Copying Parameters

You can copy the set parameter to create a new parameter from it or use it on another tool.

In the “Parameter” tab in the screen for the tool number, click [Copy] to display the screen for copying the parameter. In the screen, select the destination and click [Copy].

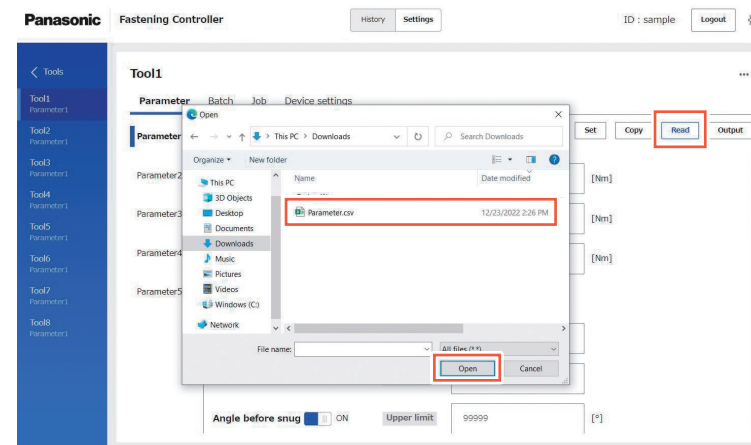


Loading Parameters

You can register a parameter by loading a parameter file saved in the PC for configuration into the controller.

You can also load a parameter file created with “Tool Manager”.

From the “Parameter” tab in the screen for the tool number, click [Read] and open the parameter file.



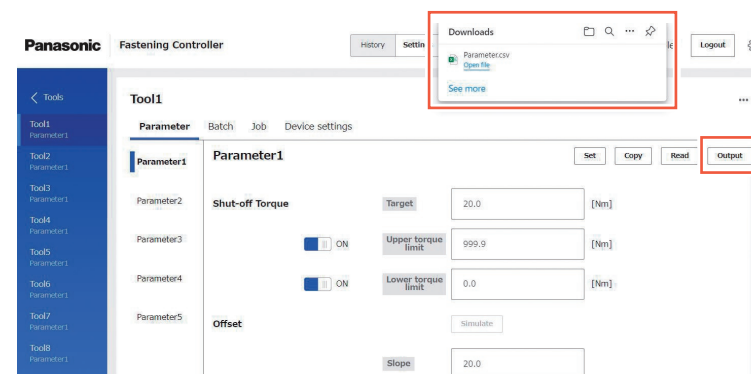
Exporting Parameters

You can export the created parameter to the PC for configuration.

You can use the exported file as a backup, to copy it to another controller, or to move it to another PC for configuration.

From the “Parameter” tab in the screen for the tool number, click [Output] and save the parameter file.

Do not edit the exported parameter file.
Otherwise it may not be read correctly.



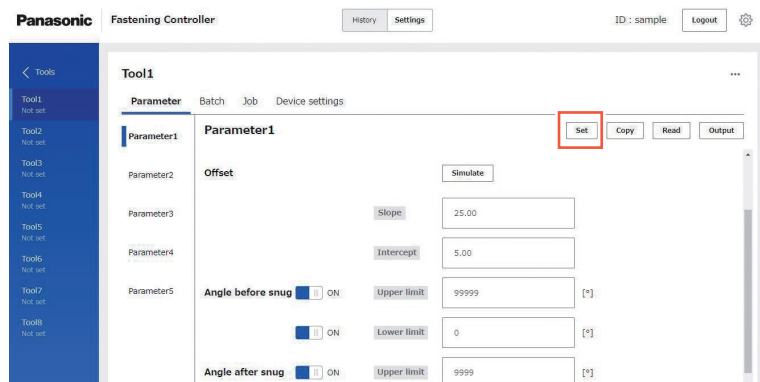
Registering Parameters

Register a parameter to use it to control a tool in “Free mode” of the controller’s running mode.

* It is not used in “Repeat mode” and “External control mode”.

(For “Free mode”, “Repeat mode”, and “External control mode”, see “Setting the Running Mode”. **Refer to P45**)

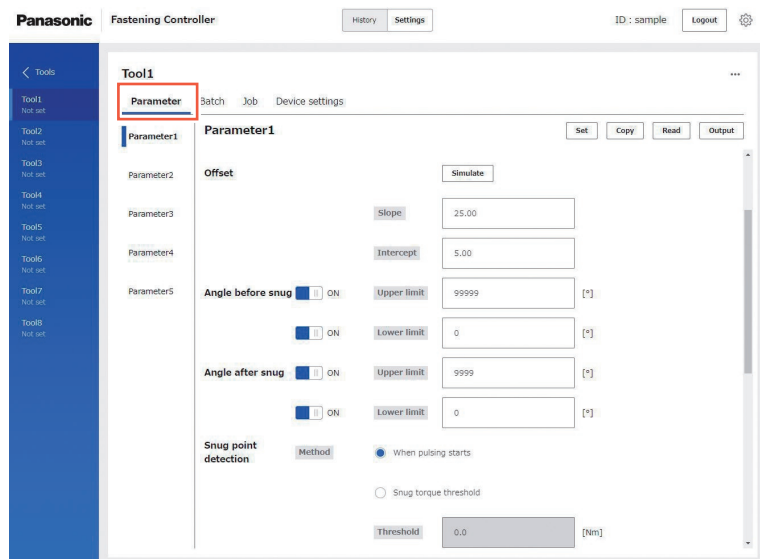
From the “Parameter” tab in the screen for the tool number, click [Set].



Parameter Items

Set the fastening parameter items.

For details, see the tool’s Operating Instructions.

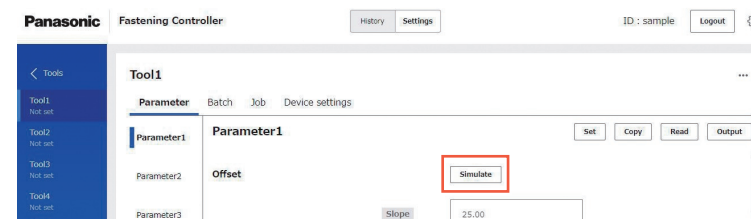


Setting an offset (Parameter, reference ①)

Set an offset to match the torque output value with the actual measured value.

1 From the “Parameter” tab in the screen for the tool number, click [Simulate] in “Offset”.

The “Offset” page is displayed.



2 Input a value to set and click [Apply].

Input “Socket length” and “Shut-off Torque”.

Click [Apply] to send the input values to the tool.

The tool enters the offset mode (shown as T2).

3 Conduct actual work using the tool and then click [Get data].

A fastening history log is added to the history list in the “Offset” page.

* Although the tool becomes ready for fastening (“C mode”) after you click [Get data], do not start normal fastening until offset setting is completed.

4 While the obtained fastening history log is selected, input an actual measured torque (refastening) value and click [Calculate].

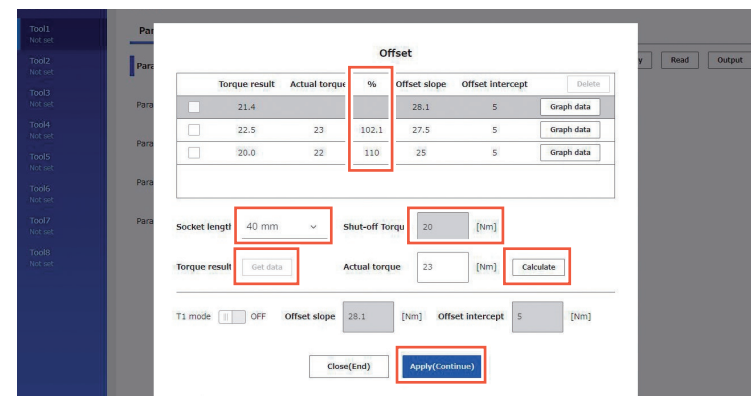
An offset to match the output torque with the actual measured torque of the tool is automatically calculated.

5 Confirm that the offset is updated and click [Apply].

The adjusted value is sent to the tool.

6 Repeat steps 3 to 5 until the difference becomes sufficiently small.

* Keep the values in the “%” column within the range of 95% to 105%.



[About T1 mode]

Checking [T1 mode] in the offset setting screen puts the controller in the minimum output mode.

(Unchecking [T1 mode] returns the controller to “Offset Mode”).



T1 mode

[Description]

You can check whether torque control works successfully when the target torque is close to the lower limit of the controller's torque control range. In this mode, the controller is shut off at the minimum counts per minute (minimum output).

At the time, the work history log is not stored.

After working in this mode, use a torque gauge or torque wrench to confirm that the controller's output torque has not exceeded the target torque.

The controller unit may not be usable for some work if its output torque exceeds the target torque in this mode.

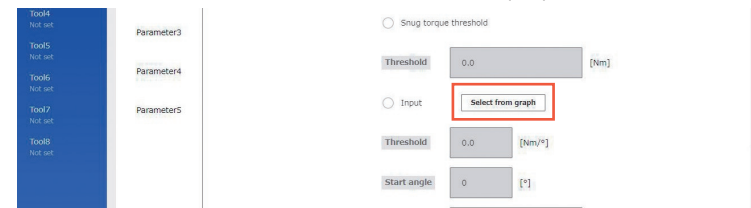
* Fastening by other tools is suspended while you are setting an offset.

■ Setting a snug point (Parameter, reference ②)

You can set a snug point based on a waveform.

1 From the “Parameter” tab in the screen for the tool number, click [Select from graph] in “Snug point detection”.

- The “Snug point detection” screen is displayed showing the current waveform of the tool.
- Fastening history data are necessary for reference. Make this setting after at least one time of fastening.
- You can switch the waveform to use with arrows (①).



2 Set a threshold in the graph.

- The main window (②) shows an entire waveform and the subwindow (③) enlarges a specific part from the entire waveform.
- You can change the range of waveform shown in the main window by inputting the start and end angles in “X-axis” (④) below the graph.
- You can set the snug point detection start angle (⑤) by moving the vertical bar.
- Adjust the position of the selection frame (⑥) in the main window to change the display range of the subwindow.
- Select a threshold to set in the subwindow (③).

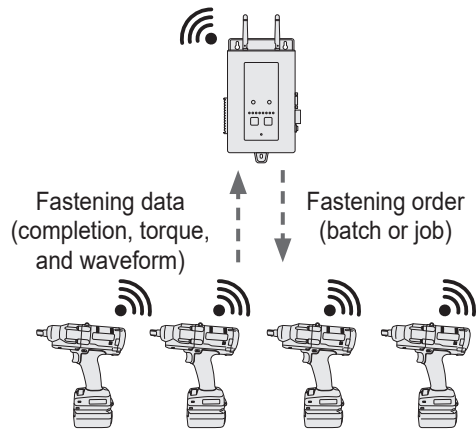


SETTING THE FASTENING CONTROL MODE

Controlling Fastening by Tools

The controller can control up to 8 connected tools for fastening.
It receives fastening data of each fastening job and counts up the fastened quantity.

Maximum number of connected devices: 8



Typical Fastening Control Combinations

You can create different combinations of fastening control settings. See typical combinations as below.

Mode	[Free mode]	[Repeat mode]																					
		[Basic mode]	[Sequence mode]																				
Pass criterion	— (The quantity is not specified)	Fastening the target quantity is completed	Tools complete fastening the respective target quantities in the specified order																				
[Batch] “Single set value” (Fastening in the same condition) * Single type of workpiece	A  OK <table><tr><td>Set value</td><td>Target quantity</td></tr><tr><td>10 Nm</td><td>∞</td></tr></table> Parameter	Set value	Target quantity	10 Nm	∞	A  OK <table><tr><td>Set value</td><td>Target quantity</td></tr><tr><td>10 Nm</td><td>10</td></tr></table> Batch	Set value	Target quantity	10 Nm	10	A ①  OK B ②  OK <table><tr><td>Set value</td><td>Target quantity</td><td>Set value</td><td>Target quantity</td></tr><tr><td>10 Nm</td><td>10</td><td>20 Nm</td><td>5</td></tr></table> Batch and Sequence	Set value	Target quantity	Set value	Target quantity	10 Nm	10	20 Nm	5				
Set value	Target quantity																						
10 Nm	∞																						
Set value	Target quantity																						
10 Nm	10																						
Set value	Target quantity	Set value	Target quantity																				
10 Nm	10	20 Nm	5																				
[Job] Multiple set values (Fastening in different conditions) * Multiple types of workpiece		A  OK <table><tr><td>Set value</td><td>Target quantity</td></tr><tr><td>10 Nm</td><td>2</td></tr><tr><td>20 Nm</td><td>3</td></tr><tr><td>30 Nm</td><td>5</td></tr></table> Job	Set value	Target quantity	10 Nm	2	20 Nm	3	30 Nm	5	A ①  OK B ②  OK <table><tr><td>Set value</td><td>Target quantity</td><td>Set value</td><td>Target quantity</td></tr><tr><td>10 Nm</td><td>2</td><td>20 Nm</td><td>5</td></tr><tr><td>20 Nm</td><td>3</td><td>30 Nm</td><td>10</td></tr></table> Job and Sequence	Set value	Target quantity	Set value	Target quantity	10 Nm	2	20 Nm	5	20 Nm	3	30 Nm	10
Set value	Target quantity																						
10 Nm	2																						
20 Nm	3																						
30 Nm	5																						
Set value	Target quantity	Set value	Target quantity																				
10 Nm	2	20 Nm	5																				
20 Nm	3	30 Nm	10																				
Remark	—	* A job can contain up to 10 steps.	* A sequence can contain up to 10 steps.																				

Number of Combinations That Can Be Registered

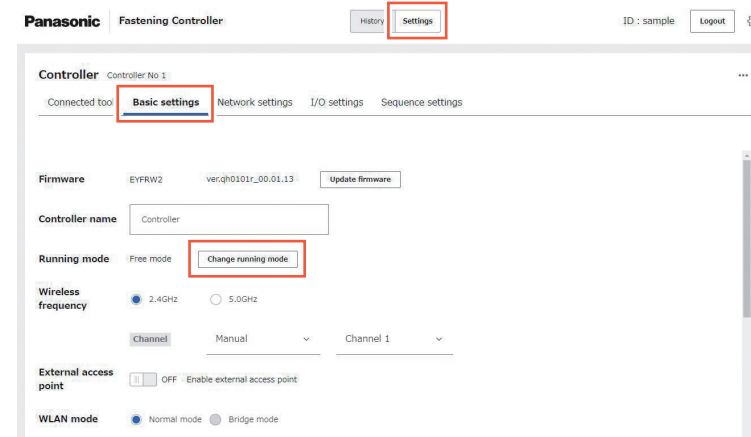
See the number of combinations that can be registered in the controller as below.

Controller's mode		Tool's setting	Number of Combinations That Can Be Registered
Free mode		Parameter	○ 5 combinations per tool
Repeat mode	Basic mode (Independent control)	Batch	○ 5 combinations per tool
		Job	○ 5 combinations per tool
	Sequence mode (Sequential control)	Batch/Job	○ 5 combinations
External control mode		—	○

Setting the Running Mode

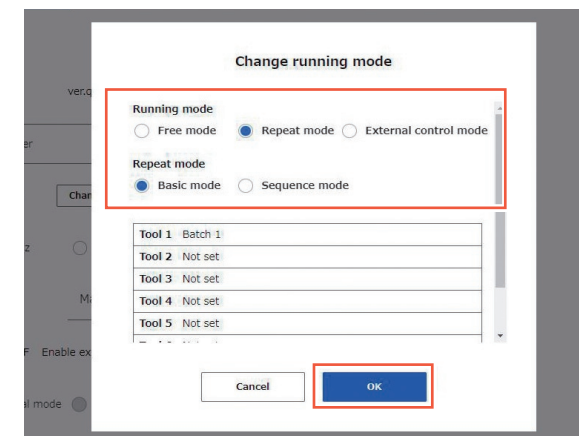
Set the running mode of the controller as below.

- 1 In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.
- 2 In the “Basic settings” tab, click [Change running mode]. The “Change running mode” screen is displayed.



- 3 Select a “Running mode” and click [OK]. The running mode is set. Select a running mode from “Free mode”, “Repeat mode”, and “External control mode”. For “Repeat mode”, select “Basic mode” or “Sequence mode”.

Refer to P46 to 49



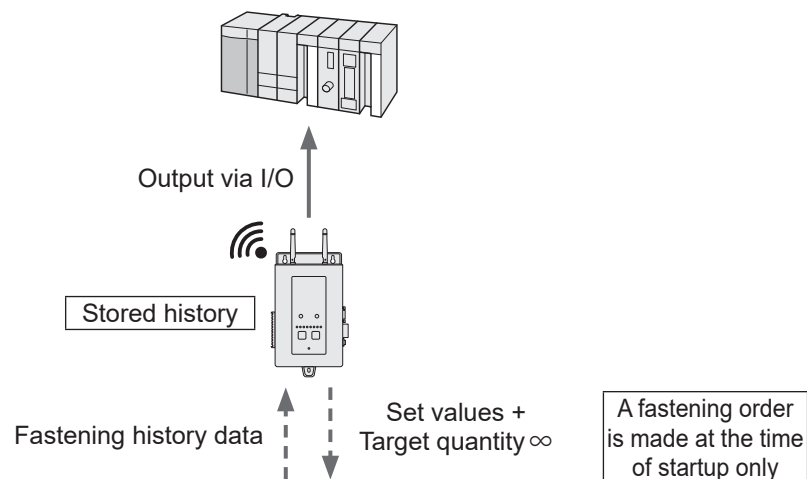
- * Register “Parameter” before setting to “Free mode”.
- * Register a “Batch/Job” before setting to “Repeat mode”.

SETTING THE FASTENING CONTROL MODE (cont.)

■ Free mode

This mode allows for unconditional fastening without specifying the quantity to fasten. Tools use pre-registered parameters for fastening. Up to 8 tools can conduct independent operation. The I/O output settings are enabled.

* Use the mode when the fastened quantity is counted by an external device.








			
Set value	Target quantity	Set value	Target quantity
10 Nm	∞	20 Nm	∞
30 Nm	∞	40 Nm	∞

Up to 8 tools can be controlled at the same time

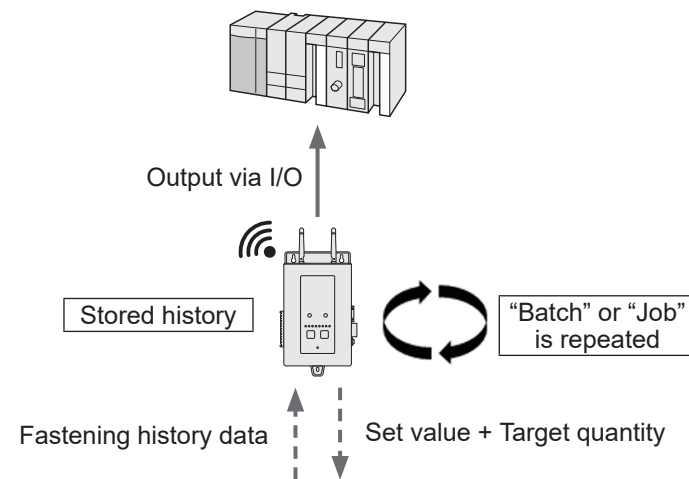





			
Set value	Target quantity	Set value	Target quantity
50 Nm	∞	60 Nm	∞
70 Nm	∞	80 Nm	∞

■ Repeat mode (Basic mode)

This mode repeats a “Batch” or “Job” process. Tools use pre-registered “Batch” or “Job” settings for fastening. Up to 8 tools can conduct independent operation. The I/O output settings are enabled.








			
Set value	Target quantity	Set value	Target quantity
10 Nm	10	20 Nm	10
Set value	Target quantity	Set value	Target quantity
30 Nm	10	40 Nm	10

Up to 8 tools can be controlled at the same time









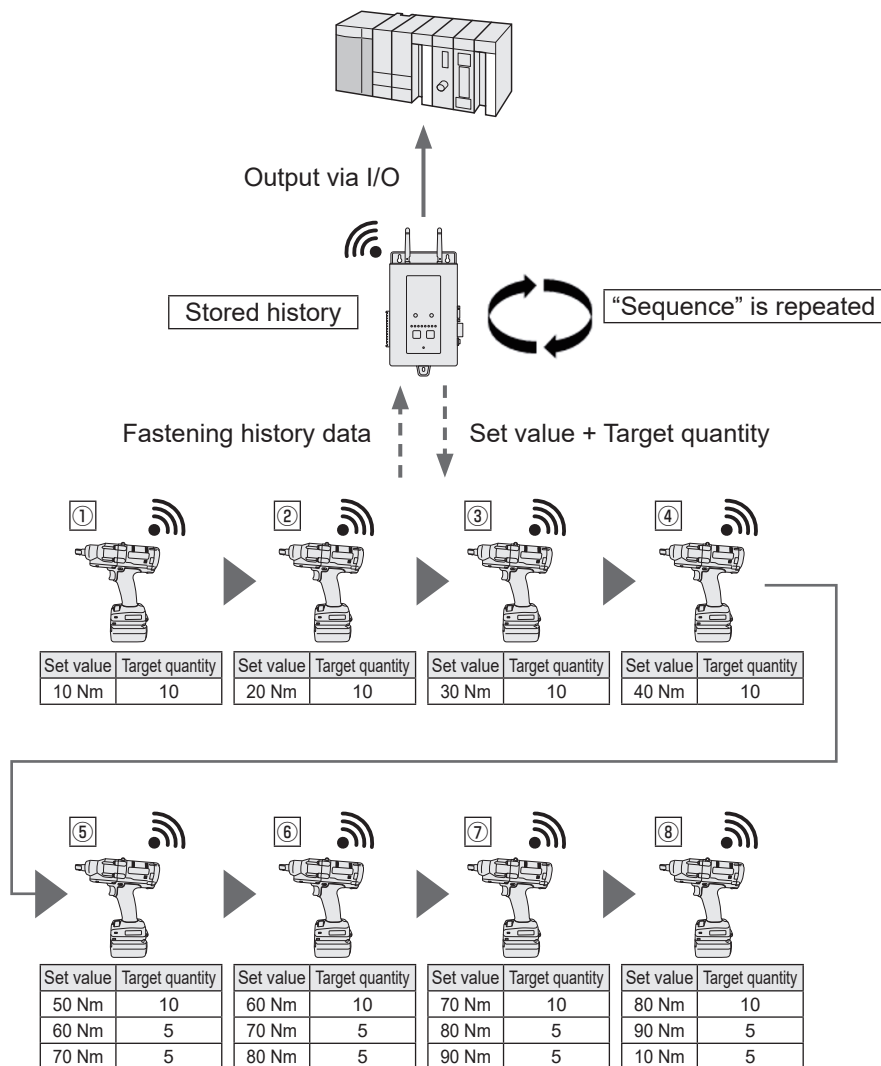


Set value	Target quantity	Set value	Target quantity	Set value	Target quantity	Set value	Target quantity
50 Nm	10	60 Nm	10	70 Nm	10	80 Nm	10
60 Nm	5	70 Nm	5	80 Nm	5	90 Nm	5
70 Nm	5	80 Nm	5	90 Nm	5	10 Nm	5

SETTING THE FASTENING CONTROL MODE (cont.)

■ Repeat mode (Sequence mode)

This mode repeats a “Sequence” process where available tools are controlled in order. Tools use pre-registered “Sequence” settings for sequential fastening. Up to 10 steps can be set. A sequence supports up to 8 tools but allows only one tool to operate at a time. The I/O output settings are enabled.



■ External control mode

This mode allows for fastening control as ordered by an external device (host system). The following 2 types of control are supported.

● Control via Open Protocol (with Open Protocol enabled)

Fastening is controlled via Open Protocol by a host system.

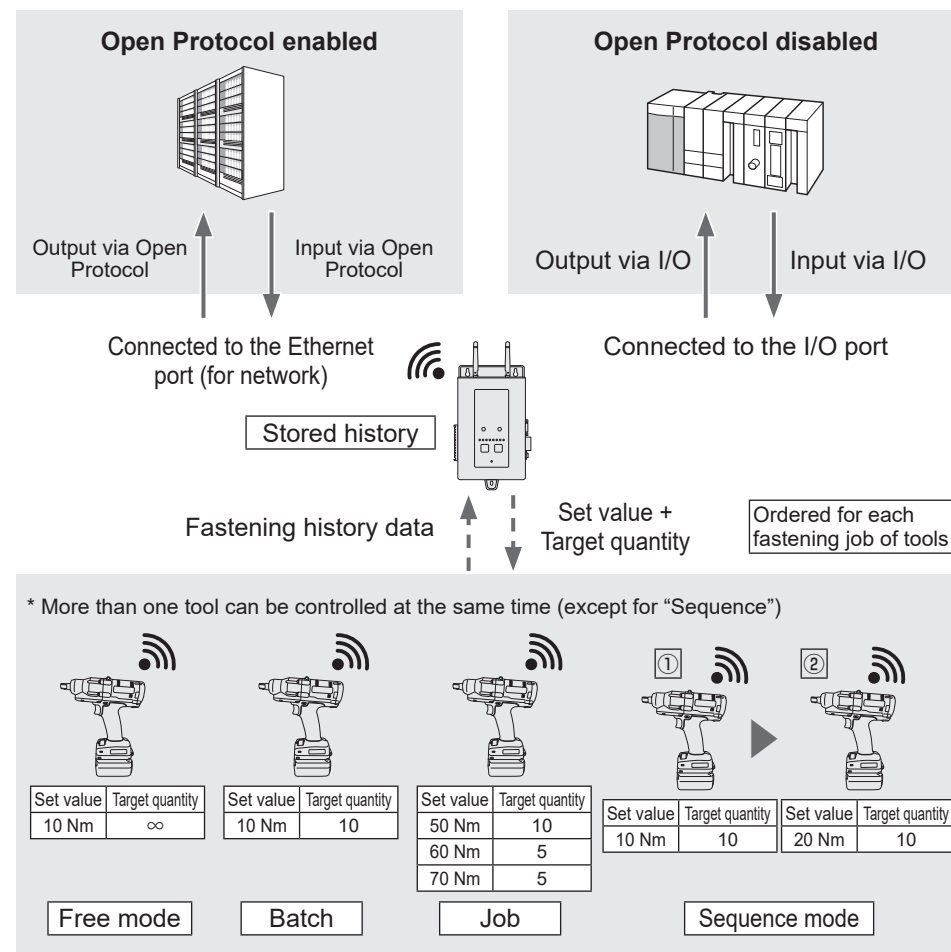
Up to 8 tools can be controlled independently.

* Job and sequence controls are not supported.

● Control via I/O (with Open Protocol disabled)

Fastening is controlled by inputs via the I/O port from an external device.

Up to 8 tools can be controlled independently or sequentially.



* If the controller turns off during fastening, fastening does not resume after the controller turns on. Fastening starts again when ordered by an external device.

* The I/O output settings are enabled.

Creating (Setting) a Batch

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab. In the “Connected tool” screen, click the desired tool number.

In the screen for the tool number, select the “Batch” tab and make settings.

Select a parameter from the “Parameter” pull-down menu and set “Batch size” (quantity to fasten, up to 99). Click [Set] to set the values for “Repeat mode (Basic mode)”.

* To switch the tool, select the desired one from the tool list.

* Up to 5 batches can be registered.

Name	Parameter	Batch size	Set
Batch 1	Parameter 1	3	Set
Batch 2	Parameter 1	1	Set
Batch 3	Parameter 1	1	Set
Batch 4	Parameter 1	1	Set
Batch 5	Parameter 1	1	Set

Tool list

Creating (Setting) a Job

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab. In the “Connected tool” screen, click the desired tool number.

In the screen for the tool number, select the “Job” tab and make settings.

Select a parameter from the “Parameter” pull-down menu and set “Batch size” (quantity to fasten, up to 99). Click [Set] to set the values for “Repeat mode (Basic mode)”.

* Up to 10 steps can be registered.

* To switch the tool, select the desired one from the tool list.

* Up to 5 jobs can be registered.

Name	Parameter	Batch size	Set
Job 1	Parameter 1	2	Set
Job 2	Parameter 2	1	Set
Job 3	Parameter 3	1	Set
Job 4	Parameter 2	1	Set
Job 5	Parameter 3	1	Set

Tool list

Creating (Setting) a Sequence

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Sequence settings” tab.

In the “Sequence settings” screen, select a tool from the “Tool” pull-down menu and set “Batch” or “Job”.

Click [Set as running mode] to set the values for “Repeat mode (Sequence mode)”.

* Up to 5 sequences can be registered.

* Up to 10 steps can be registered.

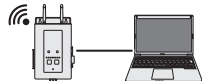
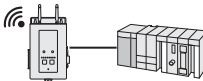
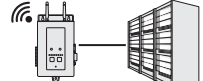
* The same tool can be used more than once in a sequence.

Sequence	Tool	Batch size	Set as running mode
Sequence 1	Tool 1	Batch 1	Set as running mode
Sequence 2	Tool 2	Batch 1	Set as running mode
Sequence 3	Tool 3	Batch 1	Set as running mode
Sequence 4	Tool 1	Batch 1	Set as running mode
Sequence 5	Tool 2	Batch 1	Set as running mode

CONNECTING TO EXTERNAL DEVICE

Supported Types of External Devices

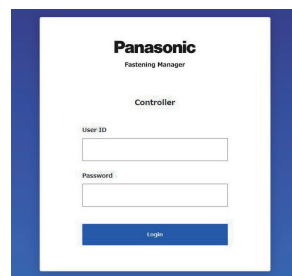
The controller supports the following types of external device.

Feature	PC for Configuration	PLC	Customer's Host System
Illustration			
Communication method	Ethernet	I/O	Ethernet
Communication protocol	http/https	— (ON/OFF signal only)	Open Protocol
Main use	- Viewing and storing the fastening history - Changing the settings	- Outputting completion and failure signals - Switching the fastening order	- Exporting the fastening history - Switching the fastening order
Data that can be exported	- Serial numbers of tools - Time - Completion and failure results - Torque values, angles, fastening time lengths - Waveform data	- Completion and failure results - Batch/job/sequence complete - Batch/job/sequence selected - Tool active	- Serial numbers of tools - Time - Completion and failure results - Torque values, angles, fastening time lengths - Waveform data
Switching the fastening order	—	Batch/job/sequence selected	Parameter/batch selected
Other	Displayed in a web browser. Microsoft Edge is recommended.	8 ports each for input and output	For supported commands, see "Commands compatible with Open Protocol". Refer to P61 Control sequences should be reviewed respectively.

Connecting to the PC for Configuration in a Remote Location

The PC for configuration with the certificate installed can remotely connect to controllers. Note that only one access to the configuration function is accepted at a time. To connect, input the IP address of the desired controller in a web browser.

Refer to P21



CONNECTING TO EXTERNAL DEVICE VIA I/O

Connecting via I/O

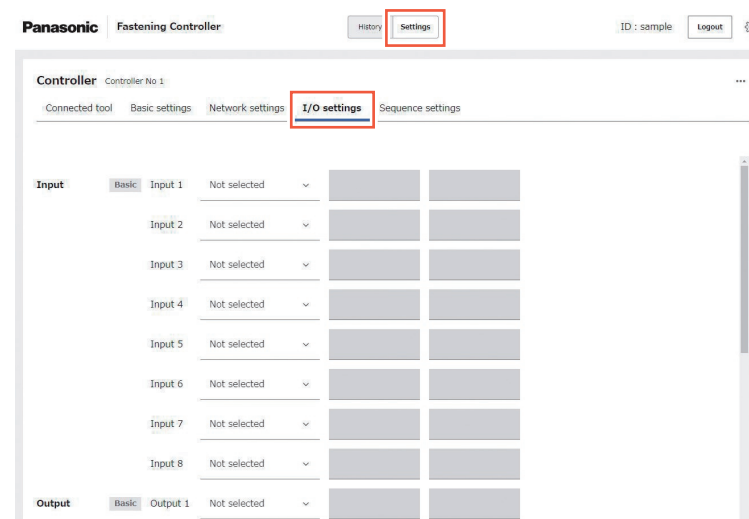
You can assign supported commands to 8 input ports and 8 output ports as desired. Assign them in the "I/O settings" screen.

Below are the commands that can be assigned to the ports.

Input	Supported command	Output	Supported command
1	Batch (Tool 1 to 5) Job (Tool 1 to 5) Sequence (1 to 5) Batch reset (1 to 8) Reset Suspend tool (1 to 8) Suspend controller	1	OK (Tool 1 to 8) NOK (Tool 1 to 8) Batch complete (Tool 1 to 5) Job complete (Tool 1 to 5) Sequence complete (1 to 5) Tool active (Tool 1 to 8) Batch selected (Tool 1 to 5) Job selected (Tool 1 to 5) Sequence selected (1 to 5)
2		2	
3		3	
4		4	
5		5	
6		6	
7		7	
8		8	

Setting I/O

In the top page (the initial page of the setting screen), click [Settings] on the top and select the "I/O settings" tab.



* It is possible to assign a behaviour or event not registered yet. (Except for job selection and sequence selection)

Commands Assigned to Input Ports

Below are the commands that can be assigned to the input ports.
When a signal from an external device is input to one of the ports, the assigned command is executed.

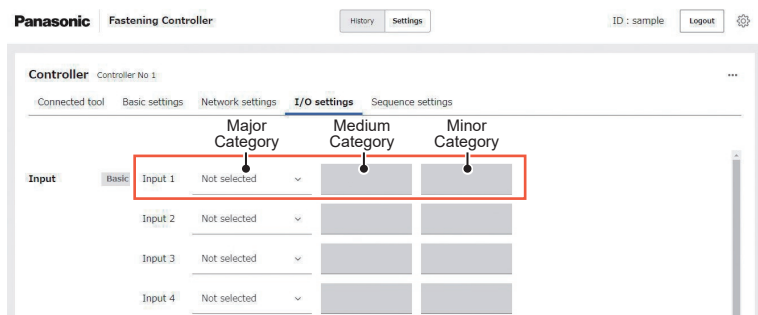
Major Category (Behaviour)	Medium Category (Tool)	Minor Category (Batch No., Etc.)
Batch	Tool 1 to 8	1-5
Job	Tool 1 to 8	1-5
Sequence	—	1-5
Suspend tool*1	Tool 1 to 8	—
Suspend controller*1	—	—
Batch reset	Tool 1 to 8	—
Reset	—	—

*1 Enabled only while the input signal is held.

Notes when the “Suspend tool” or “Suspend controller” command is input

- While “Suspend controller” is active, no fastening order is accepted.
- For the tool number with “Suspend tool” active, no “Batch” or “Job” fastening order is accepted.
- For other tool numbers than that with “Suspend tool” active, a “Batch” or “Job” fastening order is accepted.
- While “Suspend tool” is active, no “Sequence” fastening order is accepted.
At the time, the process continues until it reaches the tool with “Suspend tool” active.
- “Batch reset” and “Reset” are treated in the same manner as a fastening order.

After selecting a behaviour in the major category, select a tool and then a number (e.g., batch number) as necessary.



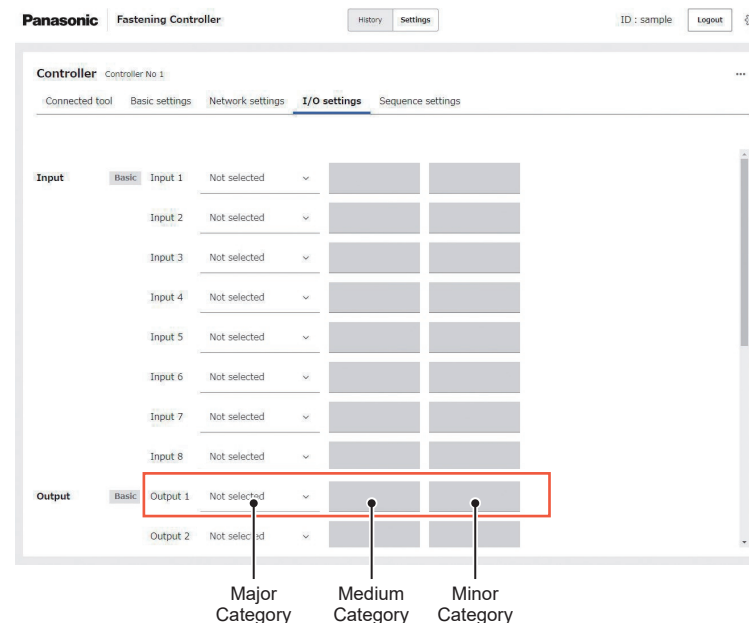
* No action is conducted if an unassigned signal is input. (No error occurs)

Commands Assigned to Output Ports

Below are the commands that can be assigned to the output ports.
When a relevant event has occurred, the controller outputs a signal from the corresponding port to an external device as specified by the assigned command.

Major Category (Event)	Medium Category (Tool)	Minor Category (Batch No., Etc.)
OK	Tool 1 to 8	—
NOK	Tool 1 to 8	—
Batch complete	Tool 1 to 8	1-5
Job complete	Tool 1 to 8	1-5
Sequence complete	—	1-5
Tool active	Tool 1 to 8	—
Batch selected	Tool 1 to 8	1-5
Job selected	Tool 1 to 8	1-5
Sequence selected	—	1-5

After selecting an event in the major category, select a tool and then a number (e.g., batch number) as necessary.



* If the controller turns off while executing an output command, the process does not resume after the controller turns on. (Note that fastening history data are saved.)

Other Settings

You can set other I/O related settings as below.

The screenshot shows the 'I/O settings' tab for 'Controller No. 1'. It lists outputs 3 through 8, each with a 'Not selected' dropdown and two empty input fields. Below this, there are three sections for 'Relay output time': 'OK' (0.50 s), 'NOK' (0.50 s), and 'Others' (0.50 s). The 'Input interval time' is set to 0.10 s. A red box highlights the 'Relay output time (OK)' and 'Input interval time' fields.

Relay output time (OK)

Select the time length until a fastening completion signal is output by the relay.

[Default] 0.5 s

[Setting range] 0.01 s to 10 s

Relay output time (NOK)

Select the time length until a fastening failure signal is output by the relay.

[Default] 0.5 s

[Setting range] 0.01 s to 10 s

Relay output time (Others)

Select the time length until any other signal than fastening completion and failure signals is output by the relay.

[Default] 0.5 s

[Setting range] 0.01 s to 10 s

Input interval time

Select the time length when the successive input signals are not counted (accepted). Set it to prevent double-counting caused by noise, etc.

[Default] 0.1 s

[Setting range] 0.01 s to 10 s

Connecting via Open Protocol Communication

In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Network settings" tab.

Enable "Atlas Open Protocol".

Set port numbers to the tools used respectively.

The screenshot shows the 'Network settings' tab for 'Controller No. 1'. The 'Atlas Open Protocol' checkbox is checked, labeled 'Enable'. Below it, there are eight 'Tool port' fields, numbered 1 through 8, with values 4545, 5001, 5002, 5003, 5004, 5005, 5006, and 5007 respectively. A red box highlights the 'Atlas Open Protocol' checkbox and the 'Tool 1 port' through 'Tool 8 port' fields.

Tool port

Assign a port number for Open Protocol communication to each tool.

[Default] Tool 1 - 4545,

Tool 2 to 8 - 5001 to 5007

[Setting range] Tool 1 to 8 - 1024 to 49151

Other Settings

Set other items as necessary.

Panasonic Fastening Controller History Settings ID : sample Login ⚙

Controller Controller No 1 ...

Connected tool Basic settings **Network settings** I/O settings Sequence settings

Cell ID

Channel ID

ACK timeout [ms]

Retries [times]

Keep alive timeout [s]

Mode ☒ Mode 1 ☐ Mode 2

Tool 1 parameter

Tool 2 parameter

Tool 3 parameter

Tool 4 parameter

Cell ID
Set the cell ID. [Default] 0 [Setting range] 0 to 9999
Channel ID
Set the channel ID. [Default] 0 [Setting range] 0 to 99
ACK timeout
Set the time length to wait for a response to a request message from the controller. [Default] 3000 ms [Setting range] 100 ms to 30000 ms
Retries
Set the number of times to repeat sending a request message from the controller. [Default] 0 times [Setting range] Not selectable (Fixed)

Keep alive timeout
Set the time length to determine occurrence of disconnection after the last communication with a host system. [Default] 15 s [Setting range] 1 s to 60 s
Mode
Set the running mode. Mode 1: Unconditional fastening with pre-registered parameters Mode 2: Fastening with parameters ordered by a host system [Default] Mode 1 [Setting range] Mode 1 / Mode 2

Assigning Fastening Parameters (Mode 1)

“Mode 1” (without parameters ordered) requires fastening parameters pre-registered to tools.
Select a parameter from the pull-down menu as below.

Panasonic Fastening Controller History Settings ID : sample Login ⚙

Controller Controller No 1 ...

Connected tool Basic settings **Network settings** I/O settings Sequence settings

Cell ID

Channel ID

ACK timeout [ms]

Retries [times]

Keep alive timeout [s]

Mode ☒ Mode 1 ☐ Mode 2

Tool 1 parameter

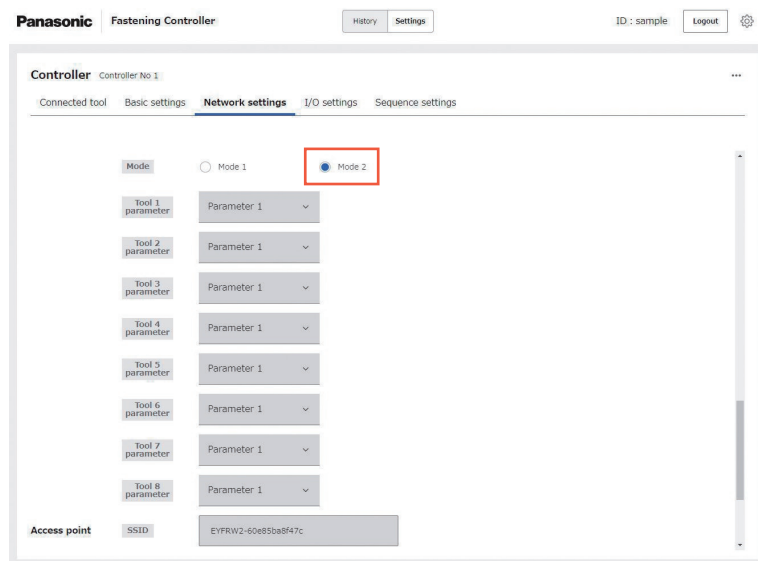
Tool 2 parameter

Tool 3 parameter

Tool 4 parameter

Assigning Fastening Parameters (Mode 2)

Fastening can be ordered with a MID 0018 command by an external device. You can specify “Parameter” or “Batch” in a fastening order.



■ To specify “Parameter” in a fastening order

Put “0” in the hundreds digit of ID.

The tens and ones digits show a parameter number.

Example: Parameter 1’s ID: 001

Parameter 5’s ID: 005

■ To specify “Batch” in a fastening order

Put “1” in the hundreds digit of ID.

The tens and ones digits show a batch number.

Example: Batch 1’s ID: 101

Batch 5’s ID: 105

* “Job” and “Sequence” are not supported.

■ Commands compatible with Open Protocol

The controller supports the following commands.

For details of commands, see the Open Protocol Specification.

MID 0001 Application communication start

Revision 1 is supported.

[Content] Communication start

MID 0002 Application communication start acknowledge

Revision 1 is supported.

[Content] Communication acknowledgement

MID 0004 Application command error

Revision 1 is supported.

[Content] Command error

MID 0005 Application command accepted

Revision 1 is supported.

[Content] Command acceptance

MID 0018 Select parameter set, Dynamic Job included

Revision 1 is supported.

For how to assign, see “Assigning Fastening Parameters (Mode 2)”. **Refer to P60**

[Content] Parameter set order

MID 0042 Disable tool

Revision 1 is supported.

[Content] Tool disabled

MID 0043 Enable tool

Revision 1 is supported.

[Content] Tool enabled

MID 0050 Vehicle ID number download request

Revision 1 is supported.

[Content] Vehicle ID acquisition request

MID 0060 Last tightening result data subscribe

Revision 1 and 2 are supported.

[Content] Final fastening result data registration

MID 0061 Last tightening result data

Revision 1 and 2 are supported.

[Content] Fastening result upload

MID 0062 Last tightening result data acknowledge

Revision 1 and 2 are supported.

[Content] Fastening result upload acknowledgement

MID 9999 Keep alive message

Revision 1 is supported.

[Content] Availability check

Connecting to External Devices with TOYOTA MOTOR CORPORATION-Specific Specifications

Control from external devices is supported.

Enable “RS232C” from the “Network settings” tab in [Settings].

Panasonic Fastening Controller

History Settings

ID : sample

Logout



Controller Controller No 1

Connected tool Basic settings **Network settings** I/O settings Sequence settingsRS232C ☒ Enable

Step flow after tightening NG

☐ Next☒ Keep**RS232C**

This is a setting specific to TOYOTA MOTOR CORPORATION. Control from external devices is possible.

[Default] Disable

[Setting range] Disable / Enable

Step flow after tightening NG

This setting determines whether you can proceed to the next tightening in case of a tightening NG result.

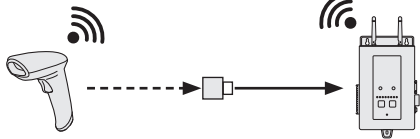
[Default] Keep

[Setting range] Next (The next tightening can be performed.) / Keep (The next tightening cannot be performed.)

This is only supported by the firmware version 2.03.00 or later.
For how to update the firmware, see “Updating the Firmware”.**Refer to P87****Setup**

You can connect a commercially available barcode reader to save read information while linking it to the fastening history data.

This can be used to link products to the fastening history.

Connection	Communication method	Note
 Barcode reader Wireless receiver Panasonic controller	Wireless 2.4 GHz or Bluetooth	Reads product information (such as manufacturing serial numbers) and reflects it in the history data.

Do not use wired USB-type barcode readers.

Applicable Devices

The following barcode readers are compatible with the controller.

Item	Description	
Communication interface	USB-HID	
Keyboard layout	US	
Supported characters	Alphanumeric characters, symbols	
	Supported codes	Code description (Anticipated information)
	Numbers	0-9
	Alphabetic characters	A-Z, a-z
	Symbols	!"#\$%&'()*+,-./:;<=>?@[¥]^_`{ }~
Acceptable 1D codes	JAN, EAN, UPC, CODE39, ITF	
Acceptable 2D codes	QR Code Model 1/2, Micro QR	
Acceptable number of characters	100 characters (maximum)	

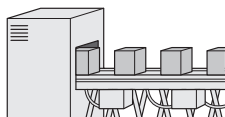
Recommended models

Bluetooth: Honeywell Xenon XP 1952g, ZEBRA DS2278

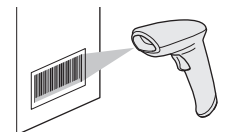
Work Process Flow

By following the procedure below, you can save product information while linking it to the fastening history data.

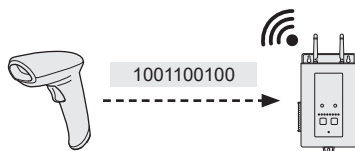
1 Products flow through the line.



2 Read product information with a barcode reader.



3 The information read by the barcode reader is sent to the controller.

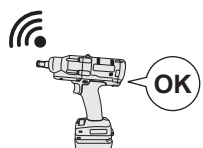


4 A fastening order is sent from the controller to the tools.

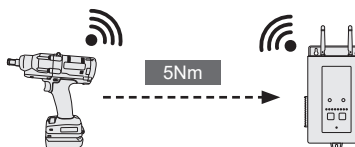
* This step may come before or after step 3.



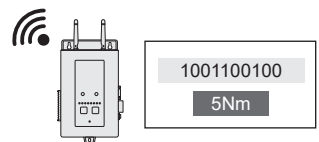
5 Perform fastening work using the tools.



6 The fastening work result (such as torque) is sent to the controller.



7 The read information retained in the controller and the fastening work result are linked to each other and saved to the storage.



8 Repeat steps 5 to 7 until the barcode reading information is updated (or the work is completed).

Setting Procedure

The setting procedure varies depending on the specifications of the barcode reader.

■ Wireless 2.4 GHz method (with dedicated wireless receiver)

Connect it following the procedure below.

(Steps 2 to 3 are not required.)

■ Bluetooth method (without dedicated wireless receiver)

Prepare a Bluetooth wireless receiver separately and connect it following the procedure below.

Available Bluetooth wireless receivers

- Bluetooth version: Compatible with Ver4.0
- Compatible with Linux OS (only those that do not require dedicated drivers)

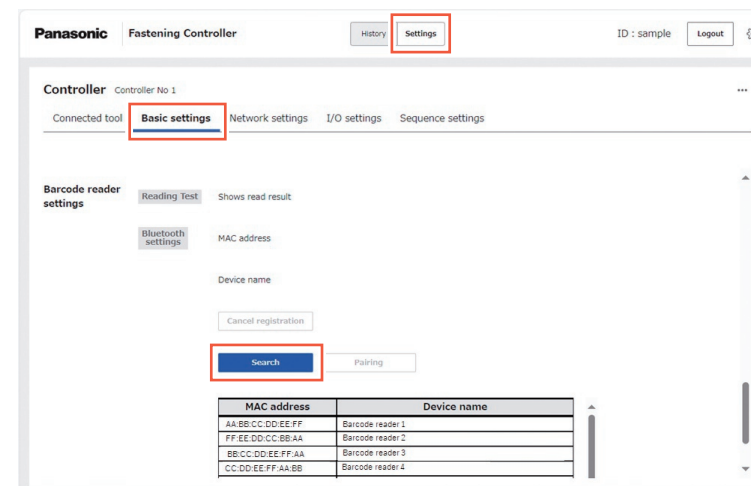
Recommended models

EDIMAX BT-8500

1 Connect the wireless receiver of the barcode reader to the USB-A port of the controller.

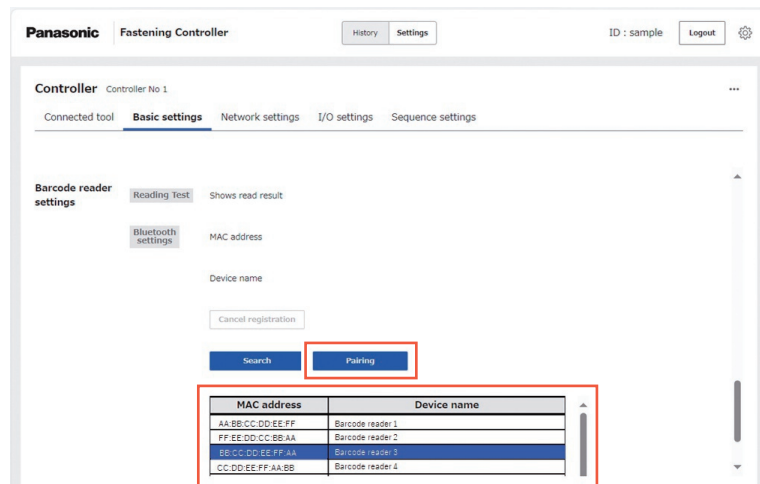
2 In the top page (the initial page of the setting screen), click [Settings] on the top, select the “Basic settings” tab, and click “Search” from “Barcode reader settings”.

* Put also the barcode reader in pairing mode according to its specifications.



3 Select the barcode reader to connect from the device name list and press “Pairing”.

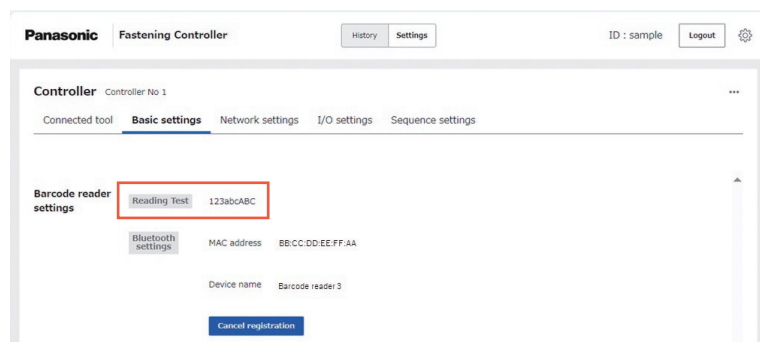
It will be paired with the barcode reader.



Device name list

- The search state is kept for about 10 seconds.
- Once pairing is registered, it will be reconnected automatically the second and subsequent times.
- * Depending on the specifications of the barcode reader, pairing may be required again.
- * If pairing fails, cancel pairing on the controller and then try again.

4 Read barcode information and check that the information is displayed correctly in “Reading Test”.

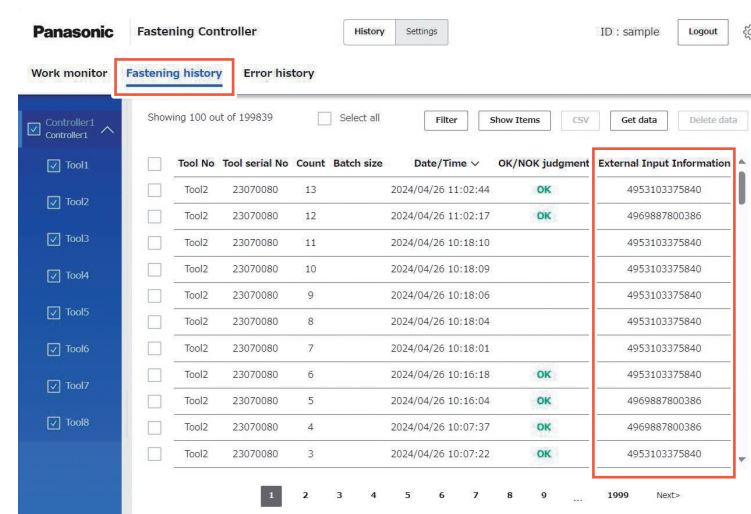


5 Perform fastening work with the barcode reader having read the information.

The read data will be displayed in “External Input Information” of the fastening history data.

Notes during operation

- The “Fastening OK lamp” will blink in the barcode reading reception state. During operation, check that the barcode reading reception state is active before work.



Notes on Read Values

The read values are:

- Reflected in the work results of all tools recorded by the controller after reading.
- Not retained when the controller is OFF.
- Overwritten by newly read information.
- Retained until the following conditions are met.

Running Mode	Data Retention Conditions
Free mode	Data is retained until updated.
Repeat mode (Basic mode)	Until Batch/Job completion. Or data is retained until updated.
Repeat mode (Sequence mode)	Until Sequence completion. Or data is retained until updated.
External control mode * Control via Open Protocol	VIN information takes priority, and they are not added.
External control mode * Control via I/O	Until Batch/Job/Sequence completion. Or data is retained until updated.

- Depending on the device specifications of the barcode reader you are using, detailed settings may be required for connection with the controller. Before using this function, carefully read the Operating Instructions and settings of your device.
- If data is read continuously within 0.5 seconds, the information will be consolidated; therefore, space out the readings.
- Only one barcode reader can be operated simultaneously with the controller. Connecting multiple readers may result in a malfunction.

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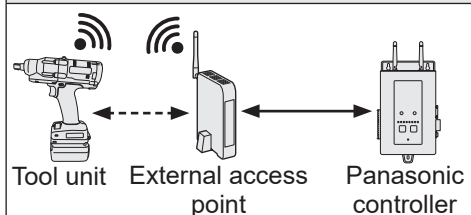
Setup

The controller can connect to tools via wireless communication using an external access point instead of the built-in access point.

The controller can control tools wherever it is installed.

Connect the access point and the controller to wired LAN.

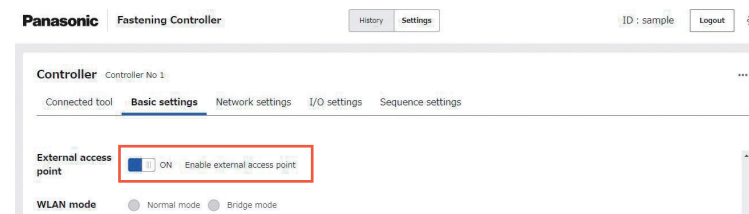
* The wireless coverage and performance change depending on the access point used.

Connection	Communication Method	Note
 Tool unit External access point Panasonic controller	Ethernet	• In the mode selection, select the internal access point or external access point. • Maximum number of connected tools: 8 * For both the internal access point or external access point

Setting Procedure

- 1 In the top page (the initial page of the setting screen), click [Settings] on the top, select the “Basic settings” tab, and set “External access point” to “ON”.

* “WLAN mode” is disabled when “External access point” is enabled.



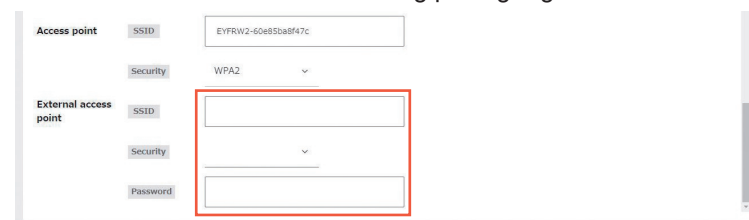
- 2 In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Network settings” tab. In “External access point”, set “SSID”, “Security”, and “Password”.

* You can register only one SSID in the controller. (You cannot register different SSIDs for different tools)

* See the Operating Instructions of your external access point.

* Make this setting before starting pairing registration with tools.

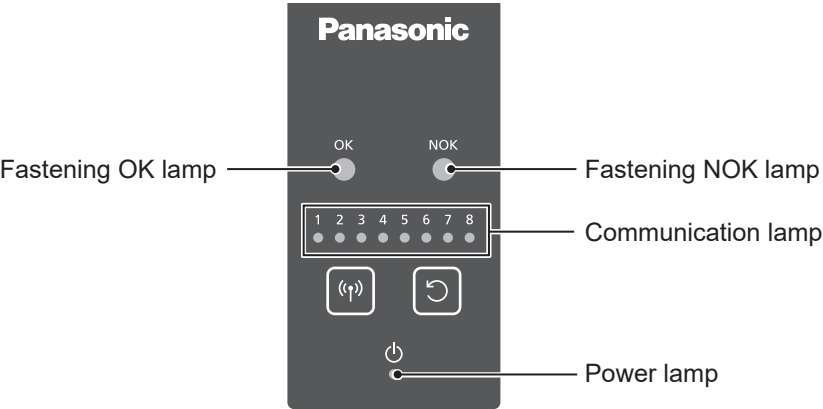
* Set the tool's IP address before starting pairing registration.



Indicator Lamps and a Buzzer

The indicator lamps and buzzer show the controller’s status.

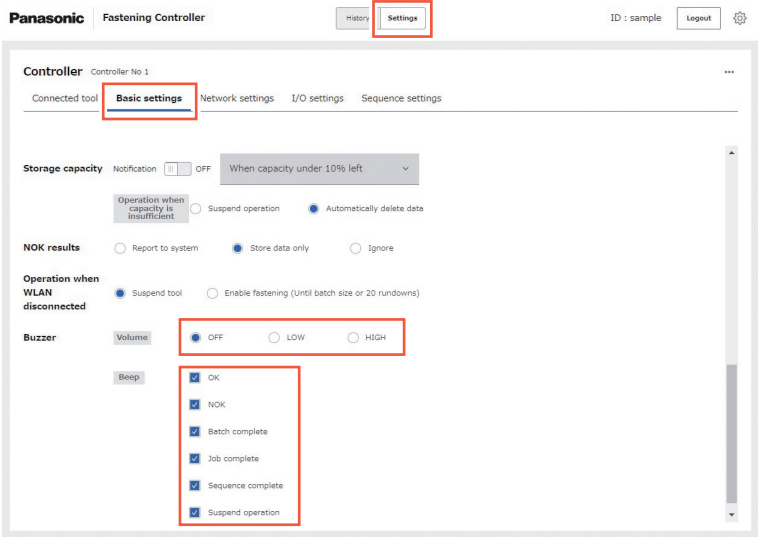
**CAUTION**
Do not turn off the power switch while the lamp is blinking startup.
Initialization may be required.



Status	Indicator Lamp	Buzzer
Power on	Power lamp (yellow) Stays lit	—
A tool to pair selected	Communication lamp (blue) Blinks slowly	—
Pairing established	Communication lamp (blue) Blinks rapidly	—
Pairing completed	Communication lamp (blue) Stays lit	A short beep ■
Pairing not established	Communication lamp (blue) Blinks very slowly	—
Pairing disconnected	Communication lamp (blue) Off	—
Fastening completion	OK lamp (green) Stays lit	A short beep ■
Fastening failure	NOK lamp (red) Stays lit	A long beep ■■
Batch/job completion	OK lamp (green) Blinks twice	Two short beeps ■■
Sequence complete	OK lamp (green) Blinks three times	Three short beeps ■■■
Error	Power lamp (yellow) Blinks	Two long beeps ■■

Buzzer Setting

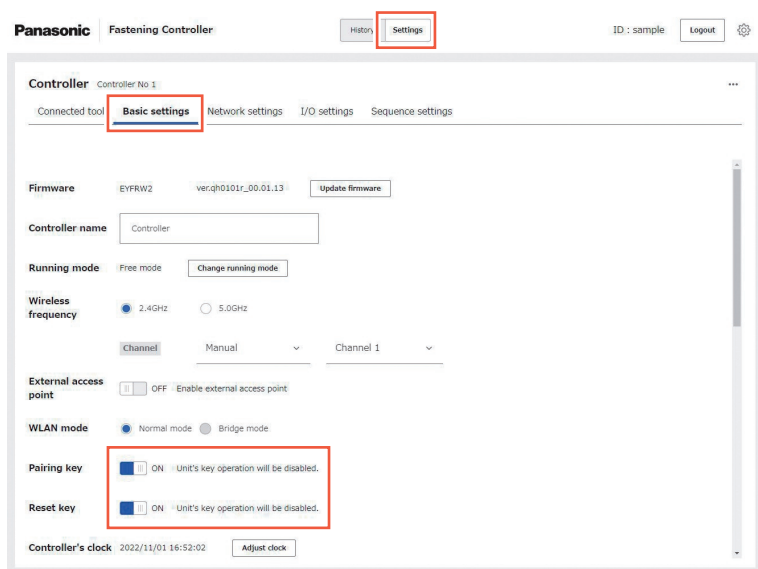
In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.
In “Buzzer”, set “Volume” and “Beep”.



Item	Description
Volume	3 levels (OFF / LOW / HIGH) (LOW: 75 dB, HIGH: 85 dB)
Beep	Selected on the PC for configuration (OK / NOK / Batch complete / Job complete / Sequence complete / Suspend operation)

SETTING THE OPERATION KEYS

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.
In “Pairing key” and “Reset key”, you can disable the Pairing key and Reset key on the control panel.

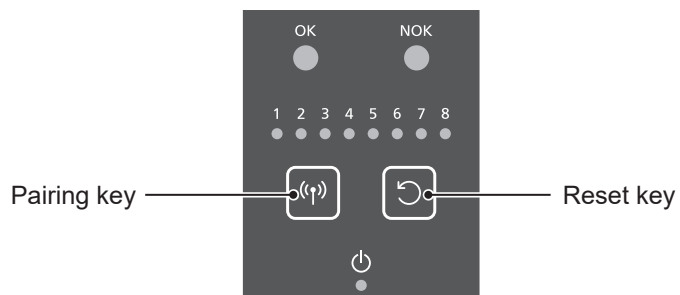


Pairing key

Enable or disable the Pairing key on the control panel.
[Default] ON
[Setting range] ON (enabled) / OFF (disabled)

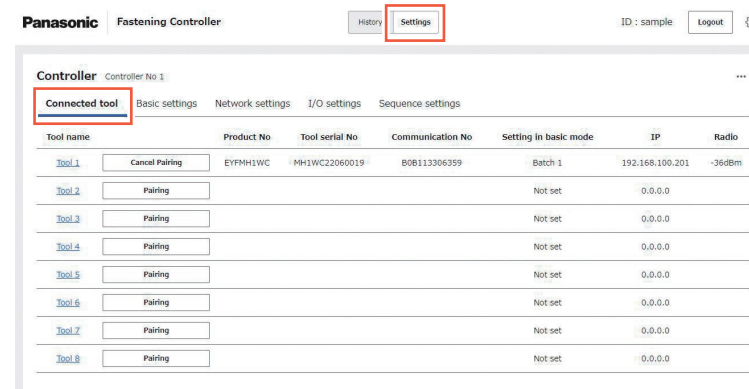
Reset key

Enable or disable the Reset key on the control panel.
[Default] ON
[Setting range] ON (enabled) / OFF (disabled)



CHECKING THE INFORMATION OF CONNECTED TOOLS

In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Connected tool” tab.
You can see the information and status of the tools connected to the controller.



Below are the displayed items.

Tool name

The registered tool number (1 to 8) is displayed.

Tool serial No

You can set and display the tool's unit identification.
Default: 5-digit model ID + 8-digit serial number (2-digit manufacturing year + 2-digit month + 4-digit production lot)

Product No

The tool product number is displayed.

Communication No

Unit identification (MAC address) of the tool's communication part is displayed.

Setting in basic mode

A behaviour when the Running mode is set to “Repeat mode (Basic mode)” is displayed.

IP

The IP address of the tool is displayed.

Radio

Strength of a radio signal (RSSI) received from the tool is displayed.
* Strength at the last communication is displayed.
* It cannot be measured and “0dBm” appears when an external access point is used.

WORK MONITOR

In the top page (the initial page of the setting screen), click [History] on the top and select the “Work monitor” tab.

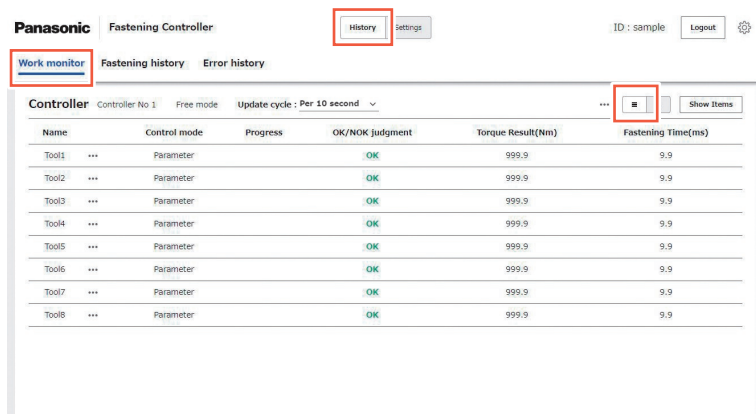
The latest fastening history logs by tool are displayed. You can use them to work by referring to the work results.

- * More than one PCs for configuration can display them at the same time. (Up to 8 accesses. Multiple accesses from the same account are accepted.)
- * To log in with more than one account, using different PCs is recommended.
- * To use more than one account on the same PC, using different web browsers is recommended.
- * Only one access to the configuration function is accepted at a time.

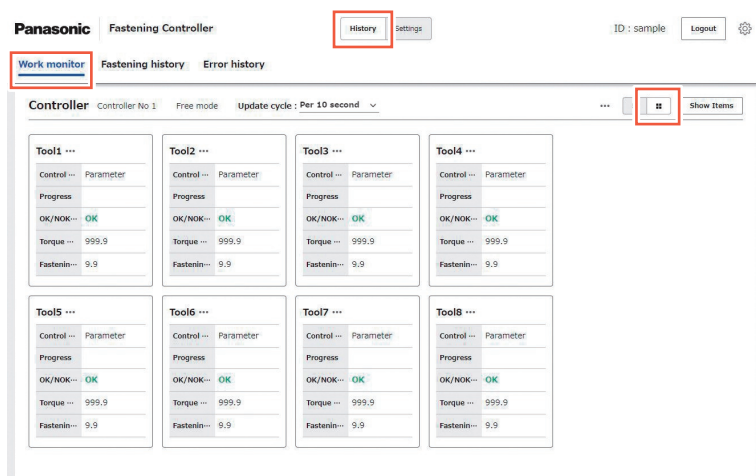
Switching the View Format

You can select between “List view” and “Grid view”.
Use the view icon on the upper right of the screen.

List view

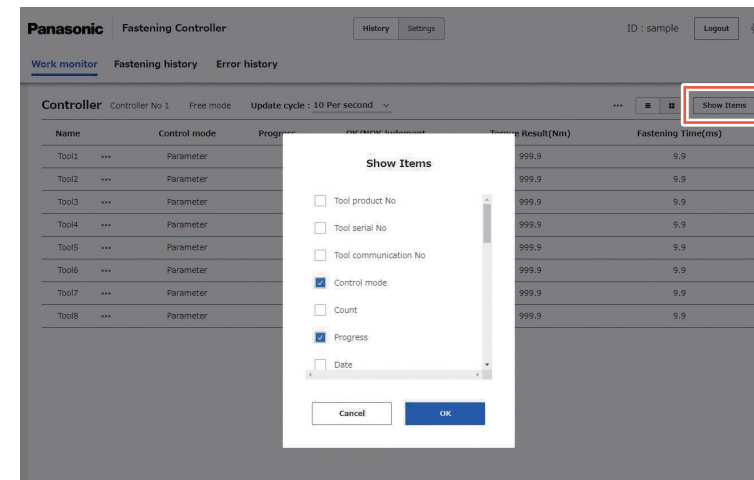


Grid view



Selecting Items to Show

Select items to show using “Show Items”.



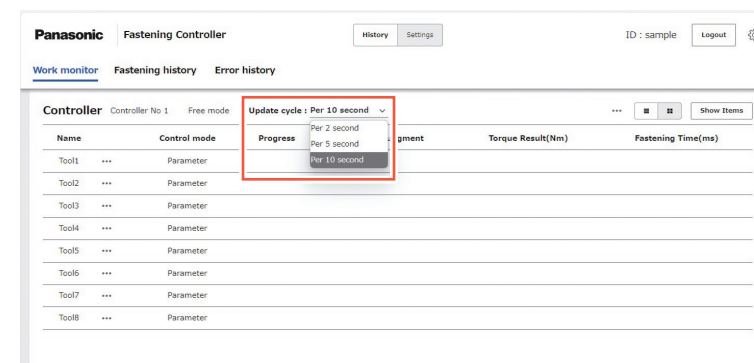
* In “List view”, you can scroll down and select many items to show.

* In “Grid view”, you can show up to 5 items.

Selecting the Display Update Cycle

You can set automatic display update.

Select the update cycle from “Per 2 second”, “Per 5 second”, and “Per 10 second” as below.



* If a large number of tools or PCs for configuration are connected, the update cycle of “Per 10 second” is recommended. (It may take some time to process data.)

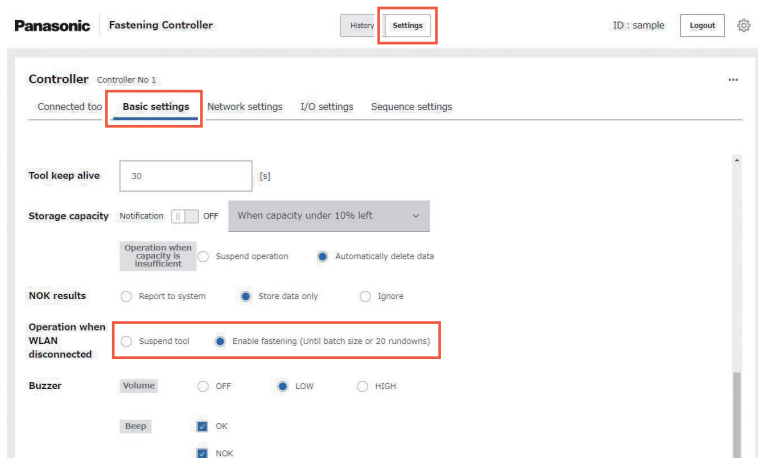
TOOLS' BEHAVIOUR WITH WIRELESS COMMUNICATION DISCONNECTED

You can continue the fastening with the same parameters in case of temporary disruption of wireless communication between a tool and the controller.
The work results of tools during wireless communication disconnection are notified to the controller “When the tool gets reconnected” or “At the first fastening after the tool’s connection recovered”.



In the top page (the initial page of the setting screen), click [Settings] on the top and select the “Basic settings” tab.

If you set “Operation when WLAN disconnected” to “Suspend tool”, the ongoing fastening is completed after disruption but no further fastening is conducted.
If you set “Enable fastening”, no further fastening is conducted after the fastened quantity has reached the upper limit.



With “Enable fastening”, the upper limit quantities by mode are as below.

Mode		Behaviour
Free mode		Continues fastening up to 20 screws
Repeat mode	Basic mode	Continues fastening up to the end of the batch or up to 20 screws
	Sequence mode	Continues fastening up to the end of the batch or up to 20 screws * Tools other than the one concerned continue to run normally.
External control mode		Continues fastening up to the end of the batch or up to 20 screws

RESETTING THE COUNT DURING OPERATION

To change settings, stop fastening control by the controller if it is ongoing. A confirmation dialogue appears when you apply the change.

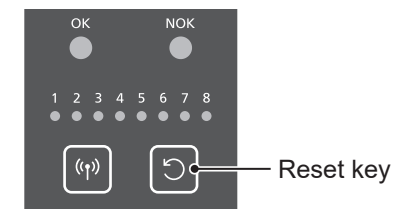
You can reset the counted quantities by “Using the key on the unit” or “Setting in the setting screen”.

* This does not apply to “Free mode”.

Using the key on the unit

Hold down the Reset key on the controller 3 seconds or more.

* The quantities of all active tools are reset.

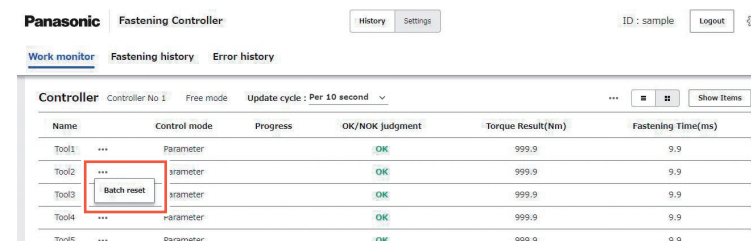


Setting in the setting screen

In the top page (the initial page of the setting screen), click [History] on the top and select the “Work monitor” tab.

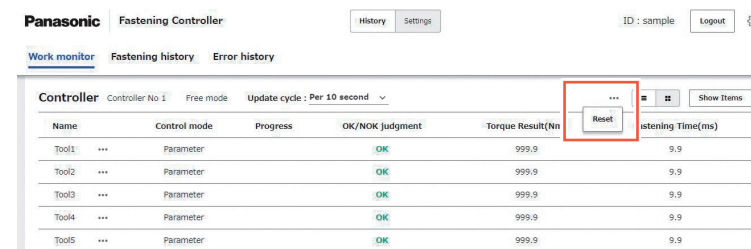
To reset the quantities by tool

In the “Work monitor” screen, click ... (tool option key) and then [Batch reset] of the desired tool number.



To reset the quantities of all tools collectively

In the “Work monitor” screen, click ... (controller option key) and then [Reset] on the upper right.



* In the Sequence mode, the quantities are reset up to the first tool.

CHECKING THE FASTENING HISTORY DATA

Displaying the Fastening History Data

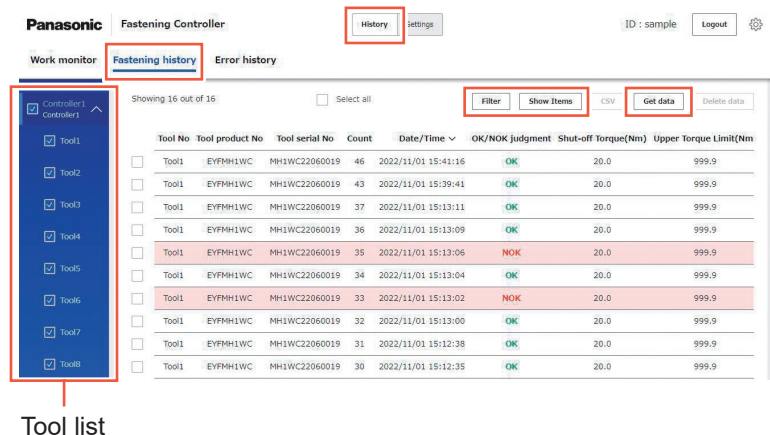
In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.

You can view the fastening history data sent from tools to the controller.

To display the data, select the desired controller and tools from the tool list on the left and click [Get data] on the upper right.

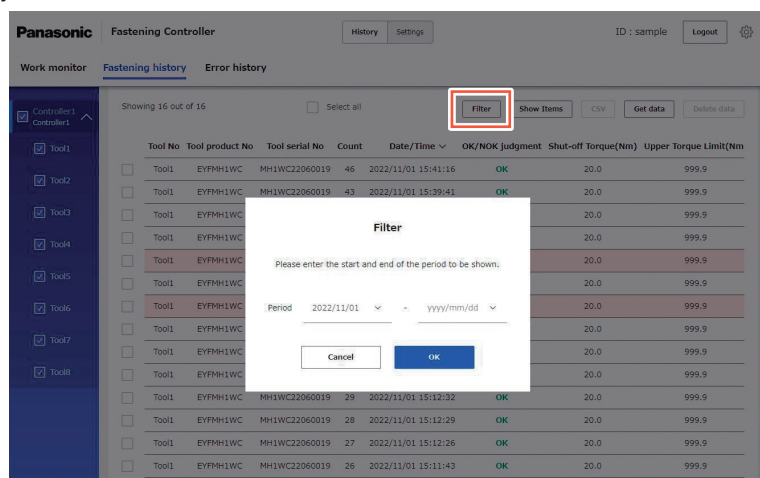
The fastening history logs are displayed from newest to oldest.

* For the content of fastening history items, see the tool's Operating Instructions.



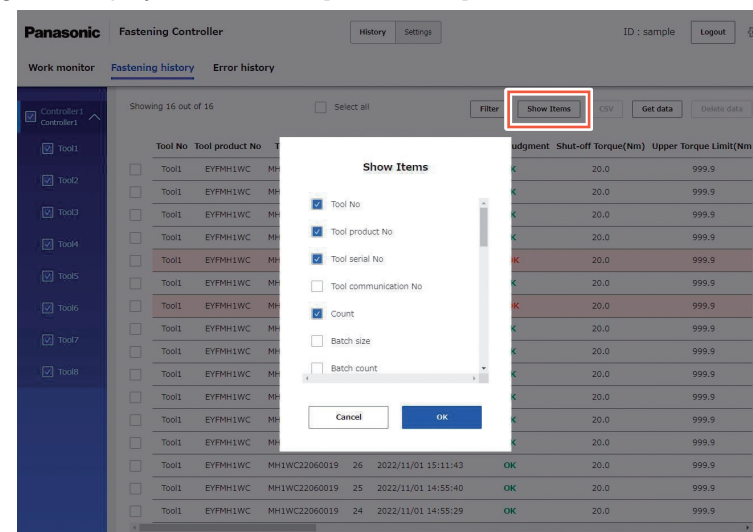
Extracting the fastening history logs by time period

Click [Filter] and specify the time period to narrow down the fastening history logs to display.



Setting Items to Display

To change the displayed items, click [Show Items] and select the desired items.



Capacity for Fastening History Data

The controller can store a maximum of about 200,000 fastening history logs (including waveform data).

It suspends operation or automatically deletes the logs (by overwriting) if it receives more logs.

It is recommended that you periodically export the logs in the CSV format as necessary by referring to the guide below.

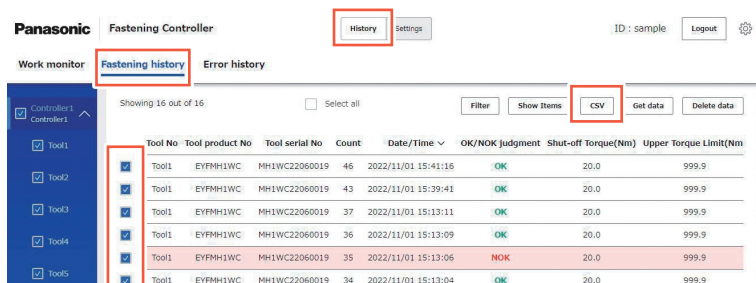
Estimated time to reach full storage capacity

	Quantity per Day per Tool		
Number of Tools	1,000	3,000	5,000
2	About 100 days	About 33 days	About 20 days
4	About 50 days	About 16 days	About 10 days
8	About 25 days	About 8 days	About 5 days

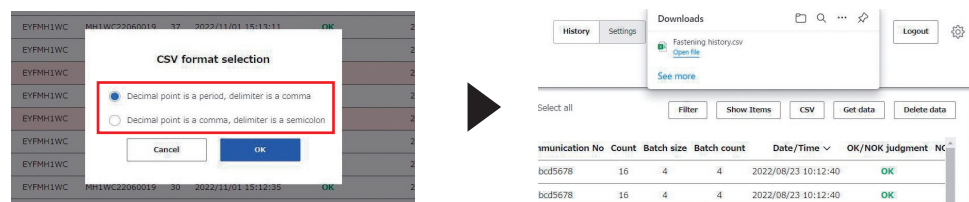
CHECKING THE FASTENING HISTORY DATA (cont.)

Exporting the Fastening History Data in the CSV Format

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
Select the desired logs and click [CSV].
The fastening history logs are exported in the CSV format.

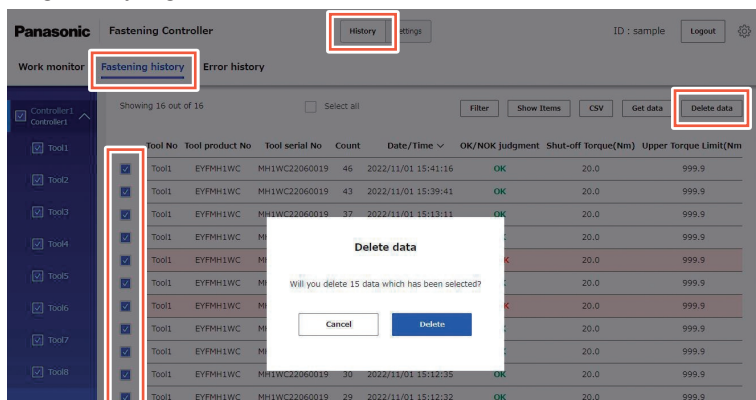


You can select between “Decimal point is a period, delimiter is a comma” and “Decimal point is a comma, delimiter is a semicolon”.



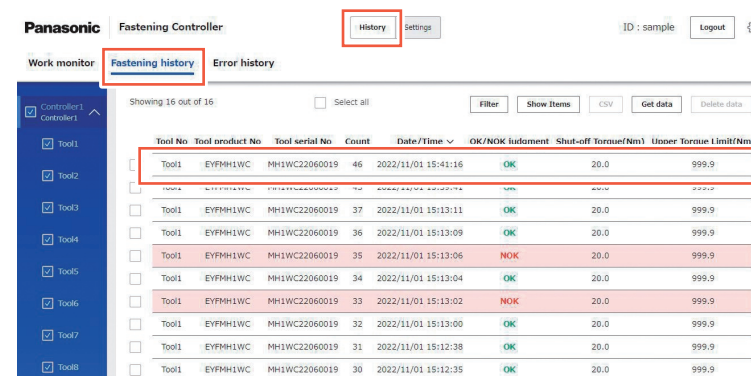
Deleting the Fastening History Data

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
Select the desired logs and click [Delete data].
The fastening history logs are deleted.

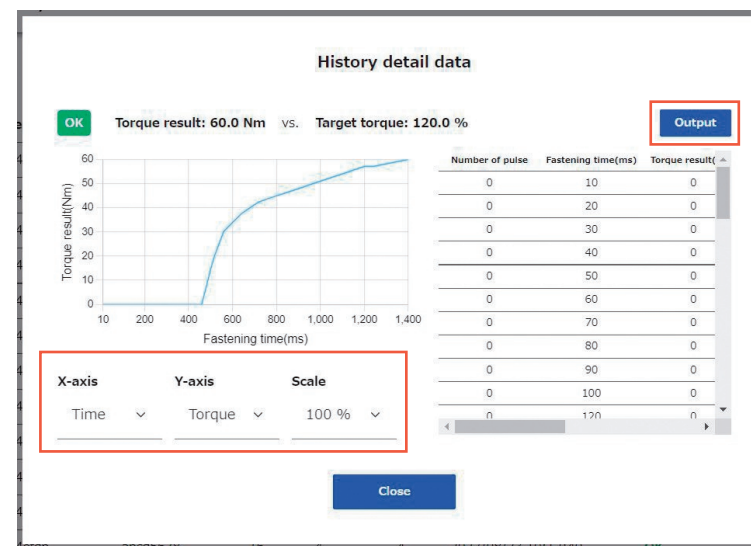


Displaying the Waveform Data

In the top page (the initial page of the setting screen), click [History] on the top and select the “Fastening history” tab.
If you have enabled to save waveform data, you can double-click on the row of the desired fastening history log to display a waveform data popup window.



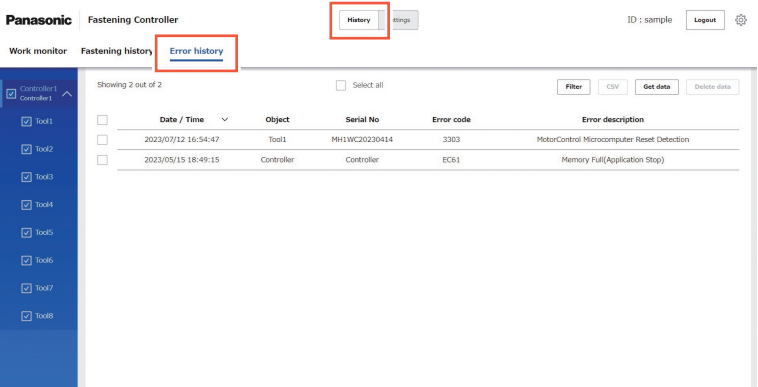
You can adjust the display by selecting “X-axis”, “Y-axis”, and “Scale”.
Clicking [Output] exports the data in the CSV format.



* Please set “Graph sending timing” in “Device settings” to “After every fastening”.

Displaying the Error History

In the top page (the initial page of the setting screen), click [History] on the top and select the “Error history” tab.
The history of errors that occurred is displayed.



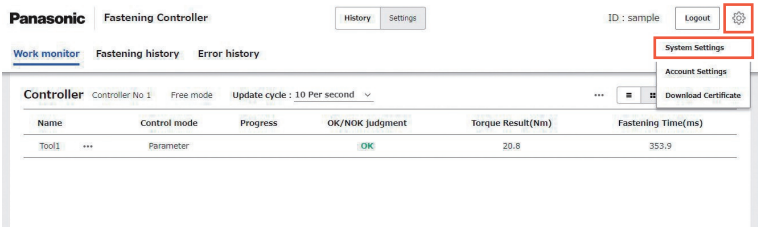
Below are the displayed items.
* For the error content, see “ERROR CODE”. Refer to P96

Date / Time
The date and time of error occurrence are displayed.
Object
The device (the controller or any of Tool 1 to 8) causing an error is displayed.
Serial No
The serial number of the device (the controller or any of Tool 1 to 8) causing an error is displayed.
Error code
An error code that occurred is displayed.
Error description
Content of an error that occurred is displayed.

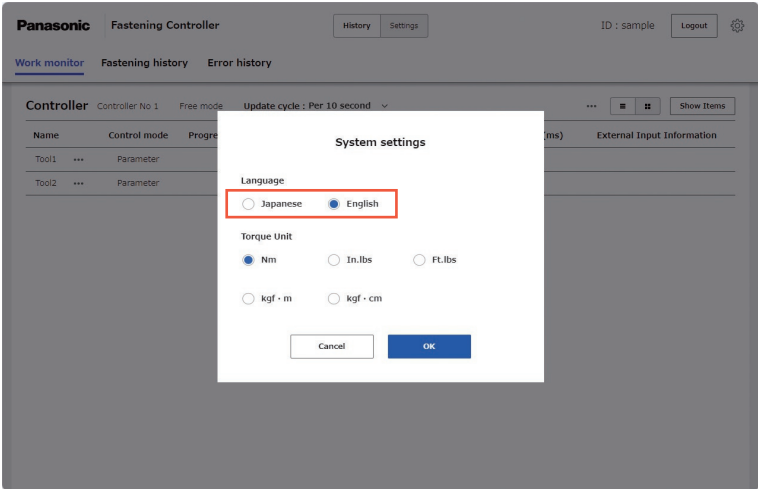
Changing the Language

You can select “Japanese” or “English”.

- 1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “System Settings”.
The “System settings” screen is displayed.



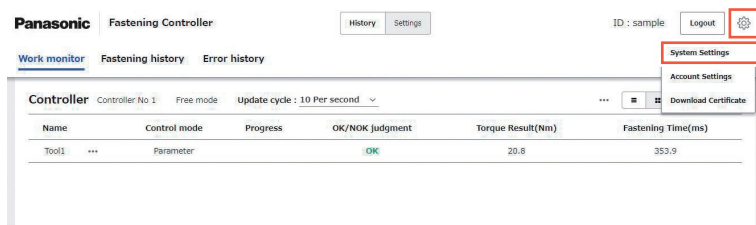
- 2 Select the language in the “System settings” screen.
You can select “Japanese” or “English”.



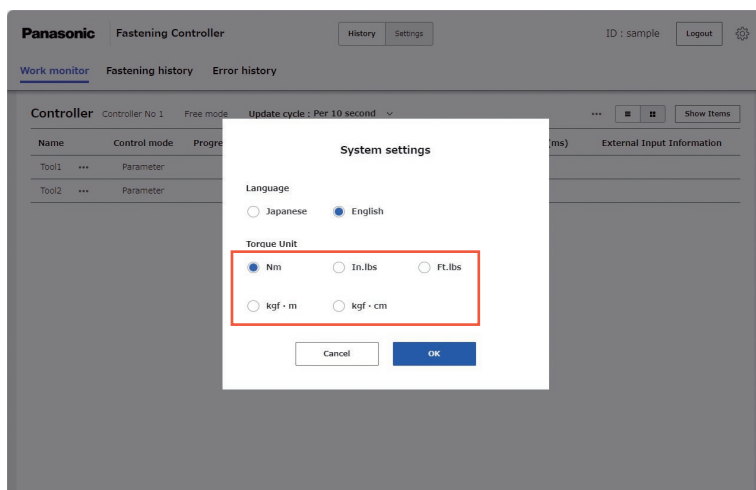
Changing the Torque Unit to Display

You can select “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, or “kgf·cm”.

- 1 In the top page (the initial page of the setting screen), click the option key on the upper right and select “System Settings”. The “System settings” screen is displayed.



- 2 Select the torque unit in the “System settings” screen. You can select the torque unit from “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m”, and “kgf·cm”.

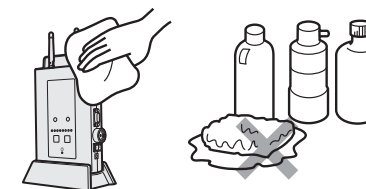


* Some unit displays may experience numerical corrections.

How to Clean

Wiping with Soft Cloth

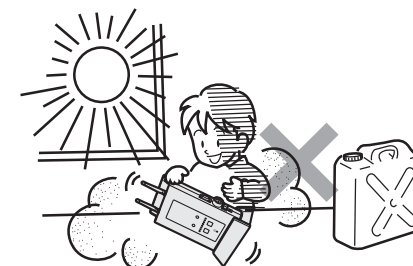
Do not use wet cloth, thinner, alcohol, benzine, or other volatile liquids.
(Cause of discoloration, deformation, or crack)



How to Store

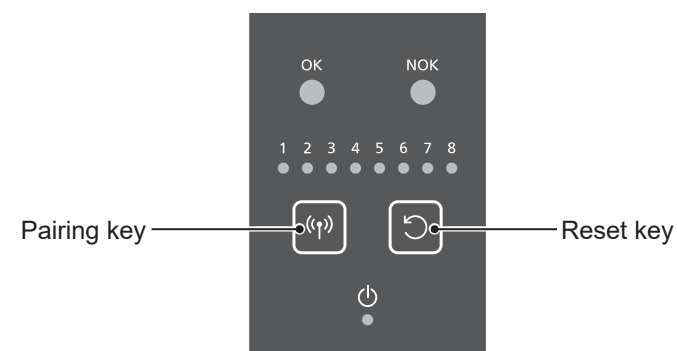
Avoid the following conditions during storage.

- Car cabin or other hot places
- Places exposed to direct sunlight
- Places exposed to water or dampness
- Places with a lot of foreign bodies or dust
- Places within reach of children
- Places with gasoline or other flammables
- Places with risk of fall



Initialising the Controller

To initialise (factory-reset) the controller, hold down the Pairing key and Reset key together 10 seconds or more.



* It may take more than 5 minutes depending on the storage usage.

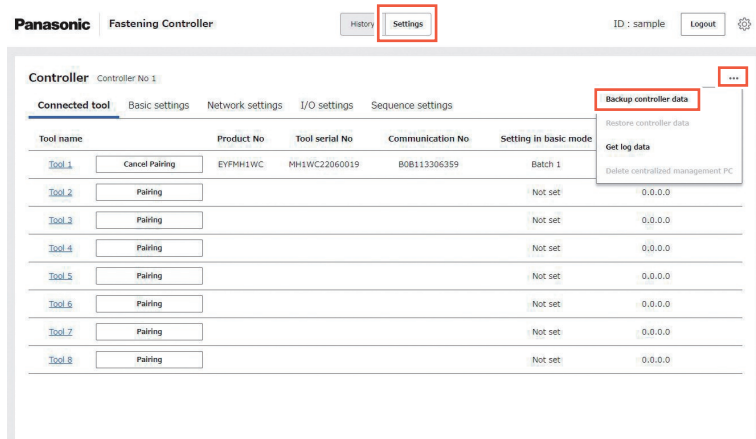
* You cannot conduct it when the keys on the unit are disabled. **Refer to P72**

Making a Backup of the Settings

In the top page (the initial page of the setting screen), click [Settings] on the top. Click ... (controller option key) and then [Backup controller data].

You can back up the settings of the controller and tools.

* The fastening history data are not backed up. Export them in the CSV format as necessary.



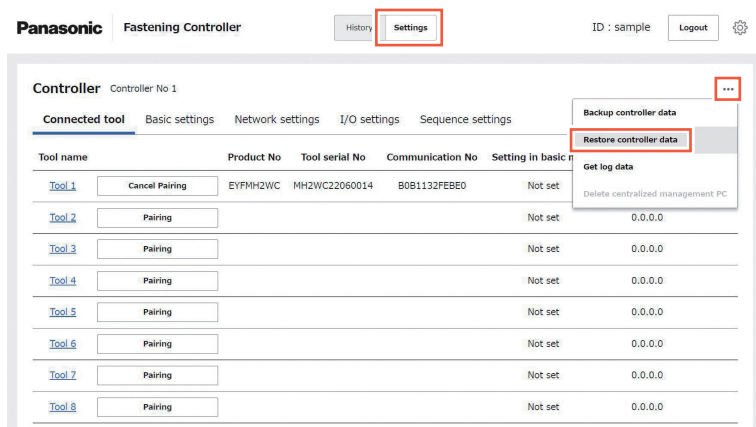
Restoring the Settings

In the top page (the initial page of the setting screen), click [Settings] on the top. Click ... (controller option key) and then [Restore controller data].

You can restore the settings of the controller and tools from their backup.

* You cannot conduct it during fastening control.

* You cannot conduct it when pairing with tools is registered. Cancel the pairing.

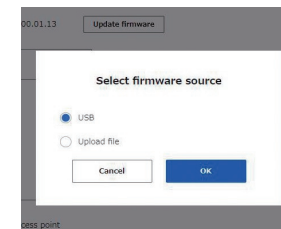


Updating the Firmware

You can update the firmware of the controller and the tool's communication part.

Use either of the following to update the firmware.

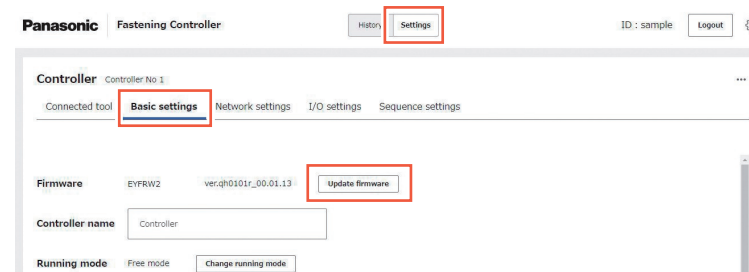
- Using the USB port of the controller.
 - A USB flash drive with a password lock cannot be used.
 - Save only one firmware data file directly in a USB flash drive without creating a folder.
- Writing from the PC for configuration.
 - When selecting "Upload file", select the firmware data file saved on the PC in the selection screen.



For the current firmware version, access our web site. **Refer to P2**
Or contact our sales person.

For the controller

In the top page (the initial page of the setting screen), click [Settings] on the top, select the "Basic settings" tab, and click [Update firmware].

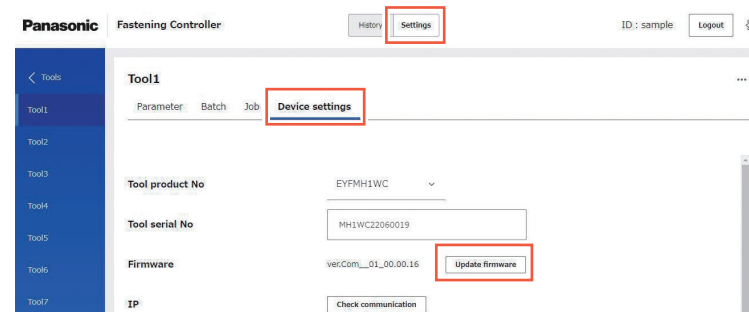


For the tool's communication part

In the top page (the initial page of the setting screen), click [Settings] on the top and select the "Connected tool" tab.

In the "Connected tool" screen, click the desired tool number.

From the "Device settings" tab in the screen for the tool number, click [Update firmware].



Replacing the Coin Cell Battery

To keep the clock (RTC) of the controller running, replace the coin cell battery by referring to the replacement guide below.

Battery type



CR2450

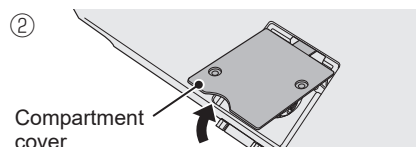
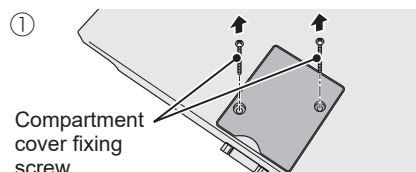
Replacement guide

The coin cell battery is used to keep the clock running when the controller is off.
To minimise its consumption, in principle, do not turn the controlled off.

Power is on 12 hours per day (business days only)	Power is always on
About 3 years	About 8 years

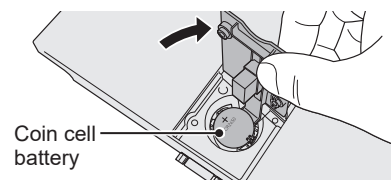
Replace it with the following procedure or contact your dealer.
It is recommended that a person who has electrical knowledge should do the work.

- Remove the 2 compartment cover fixing screws and then remove the compartment cover.**

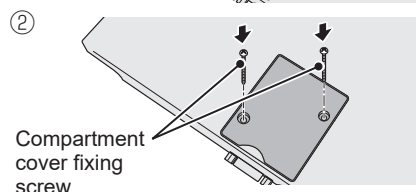
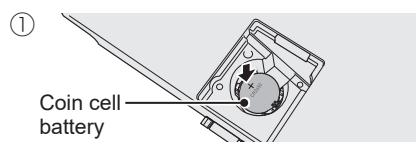


- Using the compartment cover, take out the coin cell battery.**

Pick up the coin cell battery with the hook of the compartment cover.



- Put a new coin cell battery and attach the compartment cover with the 2 compartment cover fixing screws.**



Controller Specifications

Receiving fastening completion and failure signals during indoor product assembly work

Model No.	EYFRW2	
Power Supply	100 V-240 V AC, 50/60 Hz	
Wireless Communication Standard	Wireless LAN (IEEE.802.11 a/b/g/n)	
Frequency Band	2.4 GHz:	2.412 GHz to 2.462 GHz
	5 GHz:	5.180 GHz to 5.240 GHz
Channel	2.4 GHz:	1 to 11 channels
	5 GHz:	36, 40, 44, 48 channels
Coverage	2.4 GHz:	About 16 m (52.5 ft)
	5 GHz:	About 10 m (32.8 ft)
Number of Tools That Can Be Registered	8 (maximum)	
Input/output (I/O) Terminals	8 inputs and 8 outputs	
Input Terminal Rating	24 V DC, 50 mA	
Output Terminal Rating	30 V DC, 3 A	
Power Consumption	About 30 W	
Operating Temperature and Humidity Ranges	0 °C (32 °F) to 45 °C (113 °F), 20% to 90%	
Size (Estimated Dimensions) Total Length × Total Height × Width	About 150 × 239 × 41 mm (5-29/32" × 9-13/32" × 1-5/8") (height including antennas: 281 mm (11-1/16"))	
Mass (Weight)	About 550 g (1.1 lbs) (main unit only)	
Communication interface	Ethernet × 2, RS232C × 1, USB-A × 1	
Number of Data That Can Be Stored	About 200,000 fastening history logs (including waveform data)	
Compatible Tool Models	EYFNH1WC/WP*, EYFMH1WC/WP, EYFMH2WC/WP	

*1 This is only supported by the firmware version 2.02.00 or later.

Wireless Specifications

Frequencies by channel

Frequency Band	Channel	Frequency
2.4 GHz	Channel 1	2.412 GHz
	Channel 2	2.417 GHz
	Channel 3	2.422 GHz
	Channel 4	2.427 GHz
	Channel 5	2.432 GHz
	Channel 6	2.437 GHz
	Channel 7	2.442 GHz
	Channel 8	2.447 GHz
	Channel 9	2.452 GHz
	Channel 10	2.457 GHz
	Channel 11	2.462 GHz
5 GHz	Channel 36	5.180 GHz
	Channel 40	5.200 GHz
	Channel 44	5.220 GHz
	Channel 48	5.240 GHz

WebUI Specifications

Compatible OS	Windows 10 or later (supporting any of the web browsers below)
Supported Web Browser	Microsoft Edge version 102 or later or Google Chrome version 102 or later
Supported language	English, Japanese
Recommended screen resolution	1024 × 768 or more

CAUTION

- Some PCs are not available even if they meet the operating environment.
- Depending on the use environment etc. of your PC, the descriptions and screens in this Operating Instructions might be different from the actual descriptions and screens.
Please be forewarned.
- The contents of this Operating Instructions are subject to change without prior notice.
- Any reproduction of the contents of this Operating Instructions in whole or in part is prohibited without permission.
- Descriptions on how to operate Windows in this Operating Instructions use the procedures and screens of Windows 10.
- WebUI does not work on OS other than the compatible OS.
- Operation is not guaranteed for all the PCs meeting the recommended environment.

■ Terms of use (Read before use)

<Limitations>

WebUI is configuration software for EYFRW2.

CAUTION

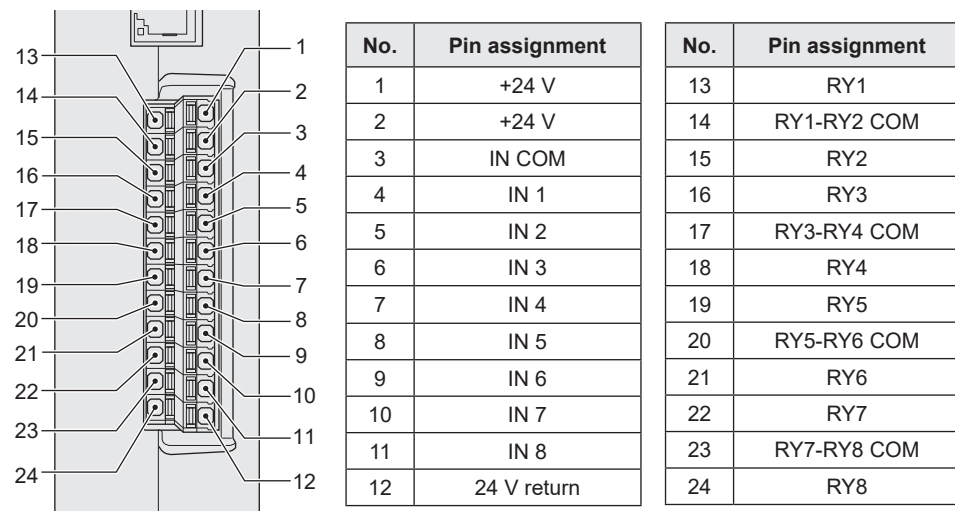
- Observe the following when using the feature.
You are deemed to agree the following terms of use by using the feature.

[Use conditions]

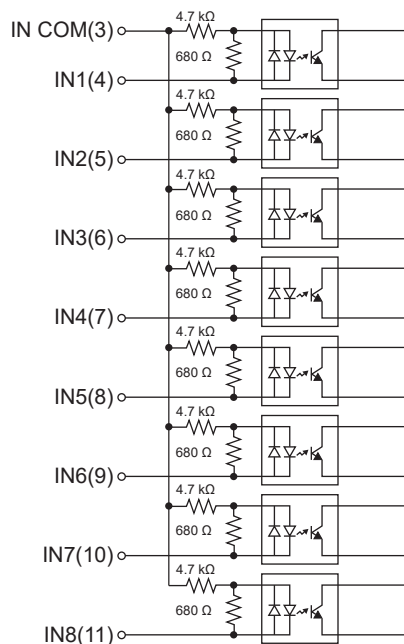
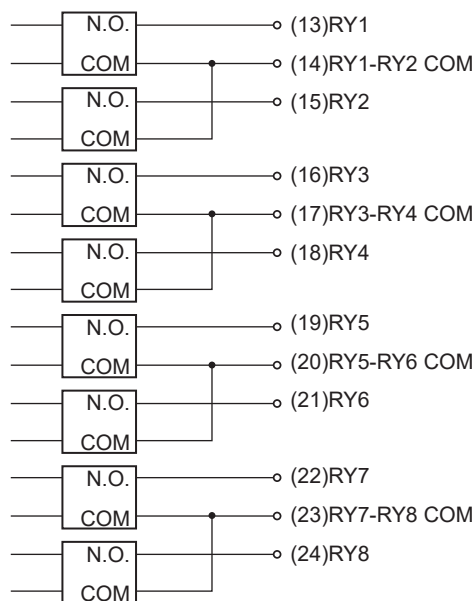
Panasonic makes no warranty of any kind regarding the feature.
Panasonic bears no responsibility for any damage including but not limited to direct loss, indirect loss, spreading loss, consequential loss, and special loss caused by use or operation of the feature.
Unauthorised reproduction and distribution of the feature is prohibited.

Contact I/O Specifications

■ Assignment between output relay terminals and input terminals



■ Terminal block connection diagram



■ Statement of explanatory text for various requirements

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

FCC Caution: To assume continued compliance, install and use in accordance with provided instructions. Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate this equipment.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Contains FCC ID: Z64-WL18DBMOD Contains IC: 4511-WL18DBMOD

This transmitter must not be co-located or operated in conjunction with any other antenna or transmitter.

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment has been approved for mobile operation requiring minimum 20 cm (7-7/8") spacing be provided between antenna(s) and all person's body (excluding extremities of hands, wrist and feet) during wireless modes of operation. This equipment may not be collocated or operated with any other antenna or transmitter.

This equipment complies with ISED radiation exposure limits set forth for an uncontrolled environment and meets RSS-102 of the ISED radio frequency (RF) Exposure rules. This equipment should be installed and operated keeping the radiator at least 20 cm (7-7/8") or more away from person's body.

This device contains licence-exempt transmitter(s)/receiver(s) that comply with Innovation, Science and Economic Development Canada's licence-exempt RSS(s). Operation is subject to the following two conditions:

1. This device may not cause interference.
2. This device must accept any interference, including interference that may cause undesired operation of the device.

For indoor use only.

PRECAUTIONS FOR WIRELESS COMMUNICATION

Cautions for using a WLAN device

The device uses a frequency band shared with other types of equipment including industrial, scientific, and medical devices (e.g., a microwave) and radio stations such as a premises radio station (licensed) and low-power radio station (unlicensed) for mobile identification used in factory manufacturing lines and an amateur radio station (licensed).

1. Before using the device, confirm that there is no premises or low-power radio station for mobile identification or no amateur radio station operating in the vicinity.
2. If the device causes harmful interference with a premises radio station for mobile identification, stop use of the band immediately and consult the support centre below for the solution of the interference problem (e.g., installing a partition).
3. If the device causes harmful interference with a premises or low-power radio station for mobile identification or an amateur radio station or such other problems, consult the support centre.

■ There may be noise, shorter radio coverage, or malfunction occurring in the following environmental conditions.

- There is an obstruction (e.g., a metal or reinforced concrete object) that prevents smooth radio propagation between the wireless-enabled tool unit and the controller.
- The antennas of the controller are covered with metal.
- An operator's body is interfering with radio propagation between an operator (the wireless-enabled tool unit) and the controller.
- There is a microwave, PC, or any other device causing noise in the vicinity.
- A cell-phone or PHS phone is used near the wireless-enabled tool unit and the controller.

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- (4) the software licensed under the GNU General Public License, Version 2.0 (GPL V2.0),
- (5) the software licensed under the GNU General Public License, Version 3.0 (GPL V3.0),
- (6) the software licensed under the GNU LESSER General Public License, Version 2.1 (LGPL V2.1),
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- (11) open source software other than the software licensed under the GPL V1.0, GPL V2.0, GPL V3.0, LGPL V2.1, LGPL V3.1, SMAIL, MPL V1.1 and/or MPL V2.0.

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Contact Information: oss-cd-powertools-gl@ml.jp.panasonic.com

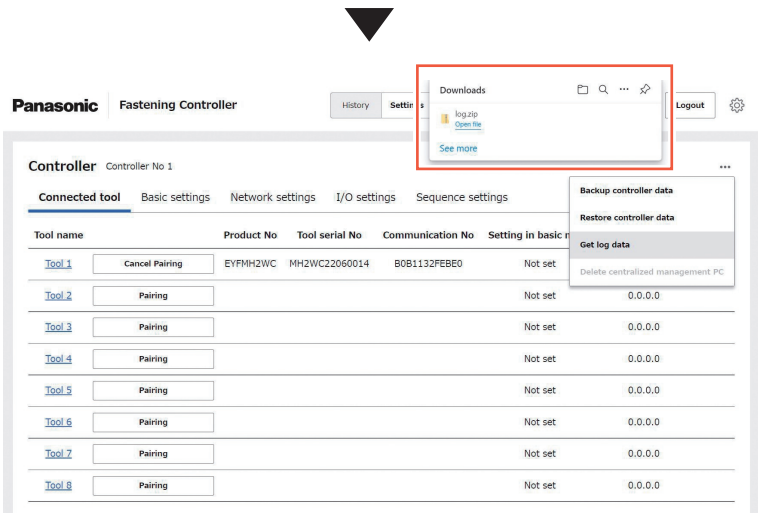
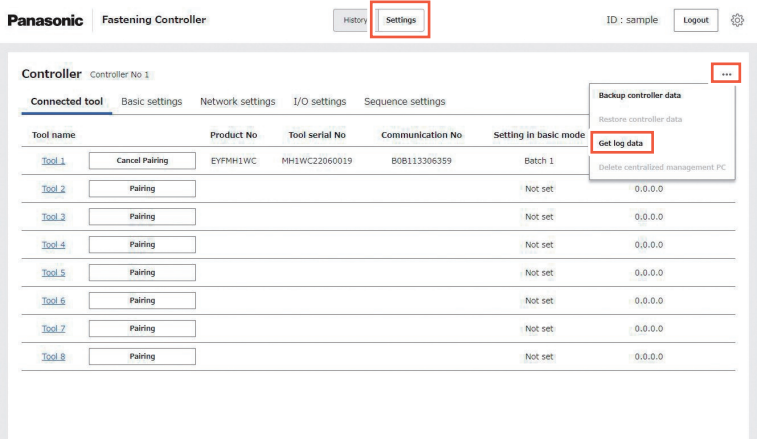
ERROR CODE

Device	Error Code	Type	Category	Event	Action
Controller	0xEF21	Warning	Hardware failure	Secondary CPU error (failure)	Restart the controller. If the problem persists, the device may be broken. Contact your dealer.
	0xEF51	Warning	Hardware failure	Ether0 error	The device may be broken. Contact your dealer.
	0xEF52	Warning	Hardware failure	Ether1 error	The device may be broken. Contact your dealer.
	0xEF61	Warning	Hardware failure	WLAN module error (failure)	Restart the controller. If the problem persists, the device may be broken. Contact your dealer.
	0xCE42	Error	Software failure	Setting content error	Factory-reset the controller and make settings again.
	0xCE43	Error	Software failure	Retraction information error	Hold down the reset key on the controller 3 seconds or more.
	0xEC61	Warning	Software failure	Capacity to store the fastening history is full (operation suspended)	Delete the fastening history logs in the fastening history screen to free up some capacity. Export them before deleting as necessary.
Tool	0x4301	Caution	Software failure	Storage capacity is full	Access the tool setting software (Tool Manager software) and delete the work history logs.
	0x4302	Caution	Software failure	The number of sent results in a queue has reached the upper limit.	The tool cannot communicate with the controller. Change the workplace. If the problem persists, the device may be broken. Contact your dealer.
	0x3303	Error	Software failure	Motor control microcontroller reset detected	An error that occurred has been solved.
	0x3304	Error	Software failure	Torque calculation microcontroller reset detected	An error that occurred has been solved.

Device	Error Code	Type	Category	Event	Action
Tool	0x4305	Caution	Software failure	Low RTC battery	Replace the coin cell battery inside the tool unit.
	0x4306	Caution	Software failure	Firmware update error	Confirm that the firmware file is correct.
	0x4315	Caution	Software failure	USB communication error	An error that occurred has been solved.
	0x4316	Caution	Software failure	WLAN module restarted	An error that occurred has been solved.
	0x1401	Warning	Hardware failure	WLAN module error	An error that occurred has been solved.
	0x1402	Warning	Hardware failure	Motor control microcontroller error	An error that occurred has been solved.
	0x1403	Warning	Hardware failure	Torque calculation microcontroller error	An error that occurred has been solved.
	0x1404	Warning	Hardware failure	External flash drive error	An error that occurred has been solved.
	0x1405	Warning	Hardware failure	RTC error	An error that occurred has been solved.
	0x1406	Warning	Hardware failure	Circuit identification error	An error that occurred has been solved.
	0x1407	Warning	Hardware failure	No remaining swap space	An error that occurred has been solved.
	0x1408	Warning	Hardware failure	Damaged parameter space	An error that occurred has been solved.

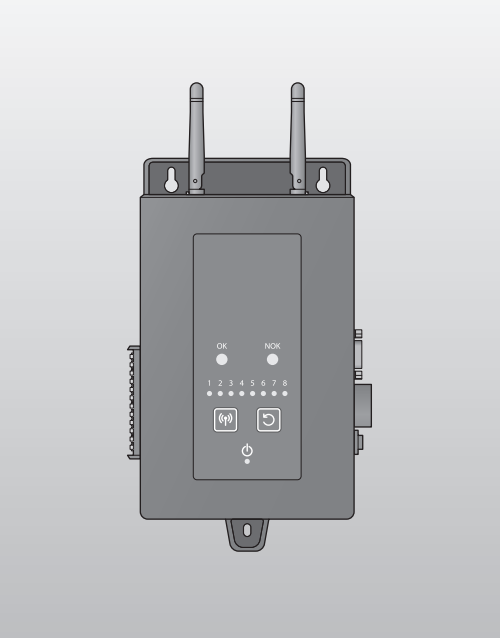
OPERATION LOG DATA

In the top page (the initial page of the setting screen), click [Settings] on the top.
Click ... (controller option key) and then [Get log data].
You can get the operation logs of the controller.



Instructions d'utilisation Contrôleur de montage

N° de modèle :
EYFRW2



IMPORTANT
Lisez et suivez les instructions d'utilisation et de sécurité avant d'utiliser ce produit.
N'utilisez pas la fonction sans fil en dehors du pays où vous avez acheté le produit.
Cela pourrait enfreindre les lois et réglementations locales.

Instructions originales: anglais
Traduction des instructions originales:
Autres langues

Panasonic®

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AVANT
UTILISATION

FONCTIONNEMENT

NETTOYAGE ET
ENTREPOSAGE

INFORMATIONS

FR

Environnement d'exploitation

Vous devez utiliser un navigateur web pour configurer le contrôleur.
Préparez un ordinateur répondant aux exigences suivantes.

Environnement d'exploitation

Système d'exploitation compatible	Windows 10 ou version ultérieure (supportant l'un des navigateurs Web ci-dessous)
Navigateur Web	Microsoft Edge version 102 ou ultérieure ou Google Chrome version 102 ou ultérieure

- Certains ordinateurs ne sont pas disponibles même s'ils sont conformes à l'environnement d'exploitation.
- Selon l'environnement d'utilisation, etc. de votre PC, les descriptions et les écrans de ces Instructions d'utilisation peuvent être différents des descriptions et écrans réels. Soyez avertis.
- Le contenu de ces Instructions d'utilisation peut faire l'objet de modifications sans préavis.
- Toute reproduction totale ou partielle du contenu de ces Instructions d'utilisation est interdite sans autorisation.
- Les figures dans ces Instructions d'utilisation sont à titre de référence uniquement.

[Remarque]

Maintenez toujours le micrologiciel à jour.
Vous pouvez trouver les dernières données du micrologiciel sur le site Web suivant qui donne accès aux Instructions d'utilisation.
Pour savoir comment mettre à jour le micrologiciel, consultez « Mise à jour du micrologiciel ». **Se reporter à P87**

Comment accéder aux Instructions d'utilisation

La version actuelle des Instructions d'utilisation du contrôleur et d'autres ressources peuvent être téléchargées à partir du site Web ci-dessous.

<https://panasonic.net/electricworks/ecm/powerelctrictools/download/>



Marque commerciale

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™ et ® peuvent être omis dans ces Instructions d'utilisation.

Utilisation prévue

Ce produit est un contrôleur qui communique sans fil avec les outils.
Il peut recevoir des données d'historique de fixation des outils, effectuer les réglages des outils et contrôler la quantité à fixer.

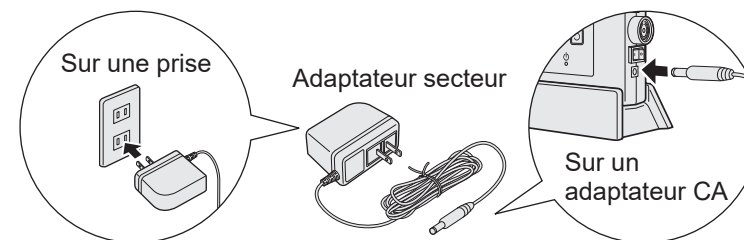
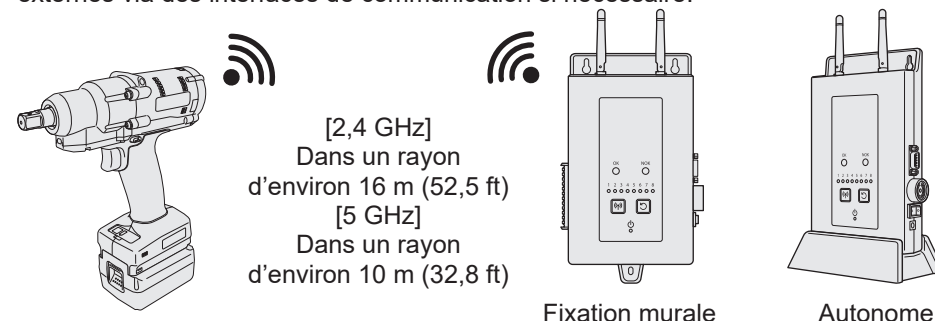


- 01** Raccorder jusqu'à 8 outils
- 02** Prendre en charge les bandes 2,4 GHz et 5 GHz
- 03** Prise en charge d'une fonction de contrôle de la fixation et d'une fonction de sauvegarde de l'historique

Configuration

Installez le contrôleur dans une plage où la communication sans fil avec les outils est possible.

Mettez l'appareil sous tension via une prise secteur et raccordez-le à des appareils externes via des interfaces de communication si nécessaire.



- Le contrôleur contient une pile bouton pour maintenir la fonction d'horloge (RTC) en marche.
Il est recommandé de garder l'appareil sous tension pour réduire la consommation de la pile bouton interne.
- La couverture sans fil peut changer en fonction de l'environnement.

Vous trouverez ci-dessous les instructions que vous devez toujours respecter afin d'éviter les dommages corporels et matériels.

■ **La gravité des dommages causés par une utilisation incorrecte est présentée dans la section suivante.**

 AVERTISSEMENT	Cela pourrait entraîner des blessures graves, voire mortelles.
 MISE EN GARDE	Risque de blessures légères ou de dommages matériels.

■ **Le contenu qui doit être observé est présenté avec les symboles suivants. (Voici quelques exemples)**

	Vous ne DEVEZ PAS effectuer l'action.
	Vous DEVEZ effectuer l'action.

 AVERTISSEMENT	
 Obligatoire	● Assurez-vous qu'il n'y a pas d'objets enfouis tels que les conduits, les conduites d'eau et les conduites de gaz dans le lieu d'installation. Tout contact avec des objets enfouis de ce type peut provoquer une électrocution ou une fuite électrique ou de gaz.
	● Insérez la prise d'alimentation à fond. Une insertion incomplète peut provoquer une électrocution ou une génération de chaleur, entraînant un incendie. N'utilisez pas une prise endommagée ou une prise de courant mal fixée.
	● Dépoussiérez la prise d'alimentation régulièrement. La poussière accumulée sur la prise peut absorber l'humidité et entraîner une mauvaise isolation et provoquer un incendie. Débranchez la prise d'alimentation et essuyez-la avec un chiffon sec.
	● Utilisez uniquement le cordon d'alimentation spécifié. L'utilisation de toute autre fiche peut provoquer une électrocution, un court-circuit ou un incendie.
	● Maintenez le lieu de travail suffisamment lumineux. Une mauvaise visibilité dans un lieu de travail sombre peut entraîner un accident ou des blessures.

 AVERTISSEMENT	
 Interdit	● N'utilisez pas de prise ou de dispositif de câblage excédant la valeur nominale. Utilisez une tension de 100 V-240 V CA uniquement. Tout dépassement de la valeur nominale en raison d'une prise surchargée peut provoquer une génération de chaleur et par conséquent un risque d'incendie.
	● N'endommagez pas le cordon d'alimentation ou la prise. (Évitez d'endommager, de casser, de modifier, de placer à proximité d'une source de chaleur, de plier en forçant, de tordre, de tirer, de placer une charge lourde dessus, de pincer ou de coincer) L'utilisation d'un cordon ou d'une prise endommagée peut entraîner une électrocution, un court-circuit ou un incendie. Vérifiez périodiquement le cordon et la fiche et s'ils sont endommagés, consultez votre revendeur.
	● N'utilisez pas le contrôleur avec une alimentation CC, un générateur de moteur ou un transformateur. ● N'utilisez pas le contrôleur dans un endroit contenant du liquide ou du gaz inflammable. Cela pourrait causer une génération de chaleur, de la fumée, un incendie ou une explosion.
	● N'installez pas le contrôleur sur une paroi de mortier. Le visser sur une paroi de mortier peut générer de la chaleur à l'intérieur de la grille, ce qui peut provoquer un incendie en cas de fuite électrique.
	● Débranchez la prise d'alimentation entre les utilisations. Si la prise reste branchée, cela peut provoquer une mauvaise isolation et entraîner une électrocution ou un incendie en cas de fuite électrique.
 Aucun démontage	● Ne modifiez pas le contrôleur. Ne démontez pas et ne réparez pas le contrôleur. Cela pourrait provoquer un incendie, une électrocution ou des blessures. Pour les réparations, consultez votre revendeur ou notre centre de service à la clientèle.
 Maintenir au sec	Évitez l'utilisation suivante d'outils chargés. ● Ne les utilisez pas et ne les laissez pas exposés à la pluie ou à l'humidité. ● Ne les utilisez pas sous l'eau. Cela pourrait provoquer une formation de fumée, un incendie ou une explosion.
 Pas de main humide	● Ne branchez pas et ne débranchez pas la prise d'alimentation sur/de la prise de courant avec la main mouillée. Cela pourrait provoquer une électrocution.

⚠ MISE EN GARDE



Interdit

- **N'utilisez pas le contrôleur à d'autres fins que celles prévues.**
Cela pourrait provoquer des blessures.
- **Ne placez pas le contrôleur dans un endroit accessible par un enfant.**
Cela pourrait entraîner un accident ou des problèmes.
- **N'utilisez pas le contrôleur s'il présente des traces d'huile ou tout autre corps étranger fixé dessus.**
Ces traces d'huile ou autres corps étrangers pourraient pénétrer à l'intérieur, provoquant une génération de chaleur, un incendie ou une explosion.
- **N'entrez pas l'unité principale dans un endroit où la température pourrait s'élever jusqu'à 45 °C (113 °F) ou plus.**
Cela pourrait provoquer un fonctionnement anormal.
- **Ne travaillez pas dans une position inhabituelle.**
Sinon, vous risquez de tomber et de vous blesser.
Tenez-vous toujours sur un sol stable et gardez un bon équilibre.
- **N'utilisez pas le contrôleur lorsque vous êtes fatigué.**
Cela pourrait provoquer un accident ou des blessures.
- **Ne laissez pas un enfant ou toute autre personne qui n'est pas un opérateur s'approcher du lieu de travail ou toucher le contrôleur.**
Cela pourrait provoquer des blessures.
- **N'utilisez pas le contrôleur avec des appareils incompatibles.**
Cela pourrait provoquer un dysfonctionnement et entraîner un accident.

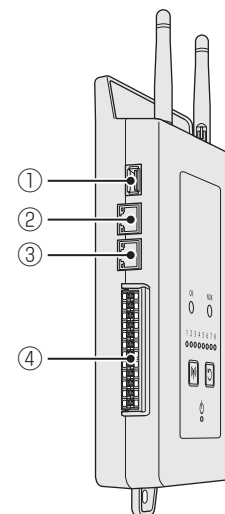


Obligatoire

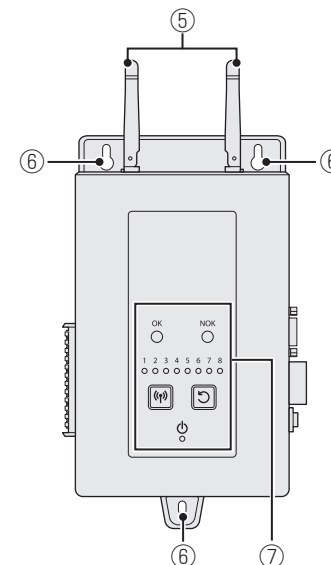
- **Pour installer le contrôleur sur un mur, fixez-le avec des vis pour l'empêcher de tomber.**
Vous risquez d'être blessé s'il tombe.
- **Pour débrancher la prise d'alimentation, tenez-la toujours sans tirer sur le cordon.**
Si vous tirez sur le cordon, cela peut provoquer une électrocution ou un court-circuit.
- **Avant l'utilisation, vérifiez si le contrôleur et d'autres pièces ne sont pas endommagés et vérifiez si leur fonctionnement est normal.**
Sinon, cela peut entraîner une rupture et des blessures.
- **Gardez le lieu de travail propre.**
Un lieu de travail ou un plan de travail désordonné peut entraîner un accident.
- **Réfléchissez bien aux méthodes de travail et de manipulation, faites attention à l'environnement environnant et faites preuve de bon sens pendant le travail.**
Le non-respect de cette consigne pourrait provoquer un accident ou des blessures.

Corps principal

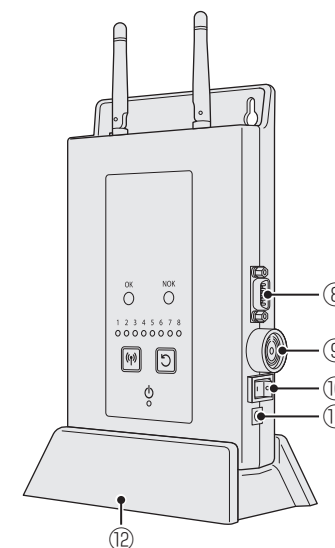
■ Côté gauche



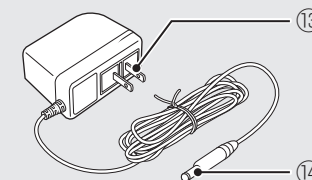
■ Côté avant



■ Côté droit



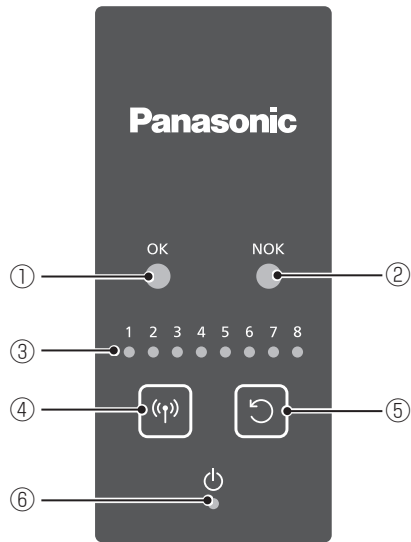
■ Adaptateur secteur



①	Port USB (USB-A)
②	Port Ethernet (pour l'entretien)
③	Port Ethernet (pour réseau)
④	1~24 Port E/S
⑤	Antenne en diversité
⑥	Trou de fixation au mur
⑦	Boîtier de commande

⑧	Port série (RS232C)
⑨	Alarme sonore
⑩	Interrupteur d'alimentation
⑪	Prise de l'adaptateur secteur
⑫	Socle du contrôleur
⑬	Prise d'alimentation
⑭	Connecteur d'alimentation

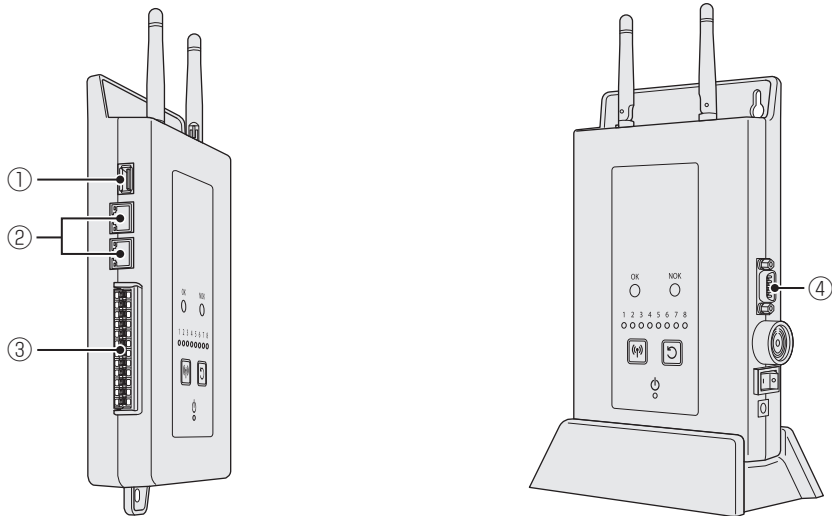
Boîtier de commande



①	Témoin de fixation OK Vert clignotant : État de réception de la lecture de code-barres. Vert continu : Un signal de fixation terminée a été reçu. Désactivé : Un signal de fixation terminée n'est pas encore reçu.
②	Témoin de fixation NOK Rouge continu : Un signal d'erreur de fixation a été reçu. Désactivé : Un signal d'erreur de fixation n'est pas encore reçu.

③	Témoin de communication (N° 1 à N° 8) Bleu continu : Un outil a été enregistré. Bleu clignotant : Un outil est en cours d'enregistrement ou hors de portée. Désactivé : Un outil n'est pas encore enregistré.
④	Touche d'appariement
⑤	Touche de réinitialisation
⑥	Témoin d'alimentation Jaune continu : Mise sous tension (mode de réception) Éteint : Mise hors tension Clignote en jaune : Erreur

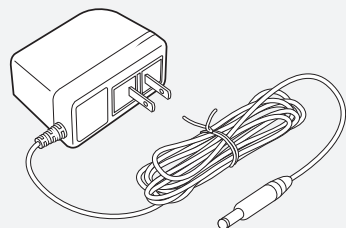
Interface de communication



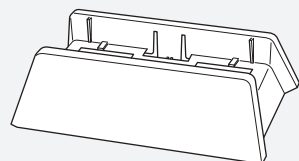
Interface		Détails
①	USB	Utilisez ce port pour connecter une clé USB afin de mettre à jour le micrologiciel. * Connectez directement une clé USB (sans extension) Un récepteur sans fil est connecté à ce port pour connecter un lecteur de codes-barres. * Seuls des lecteurs de codes-barres sans fil sont disponibles. • USB2.0 USB-A × 1
②	Ethernet (pour la maintenance et le réseau)	Utilisez ce port pour vous connecter à un PC de configuration ou à un système hôte. * Connectez le port Ethernet (pour la maintenance) directement à un PC de configuration. (Ne pas utiliser de concentrateur) • 10Base-T/100Base-TX × 2 • Longueur de câble : moins de 30 m (98,4 ft)
③	Borne d'entrée/sortie (E/S)	Utilisez ce port pour vous connecter à un périphérique externe (par exemple un API). • 8 entrées et 8 sorties • Longueur de câble : 10 m (32,8 ft) ou moins • Tension nominale de la borne d'entrée : 24 V CC, 50 mA • Tension nominale de la borne de sortie : 30 V CC, 3 A
④	Port série (RS232C)	Utilisez ce port pour vous connecter à un périphérique externe (par exemple un API). • RS232C × 1 • Longueur de câble : 10 m (32,8 ft) ou moins

Accessoire

■ **Adaptateur secteur × 1**
(WEYFRW1K7651)



■ **Socle du contrôleur × 1**
(EYFRW1F7001)



Consommables

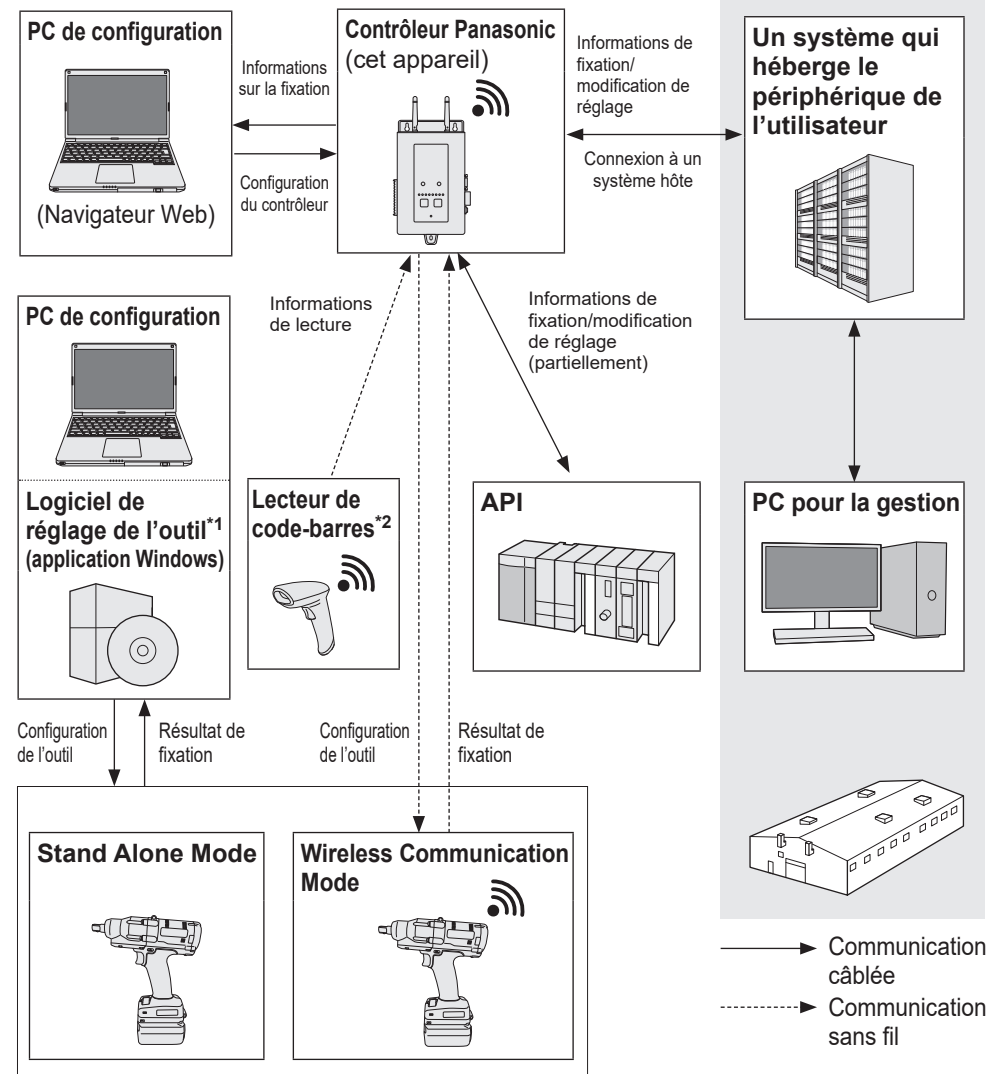
■ **Pile bouton (CR2450) × 1**

Pour savoir comment remplacer, voir « Remplacement de la pile bouton ».

Se reporter à P88



Configuration du système



*1 Le « logiciel de réglage de l'outil » peut être téléchargé depuis notre site Web.

Se reporter à P2

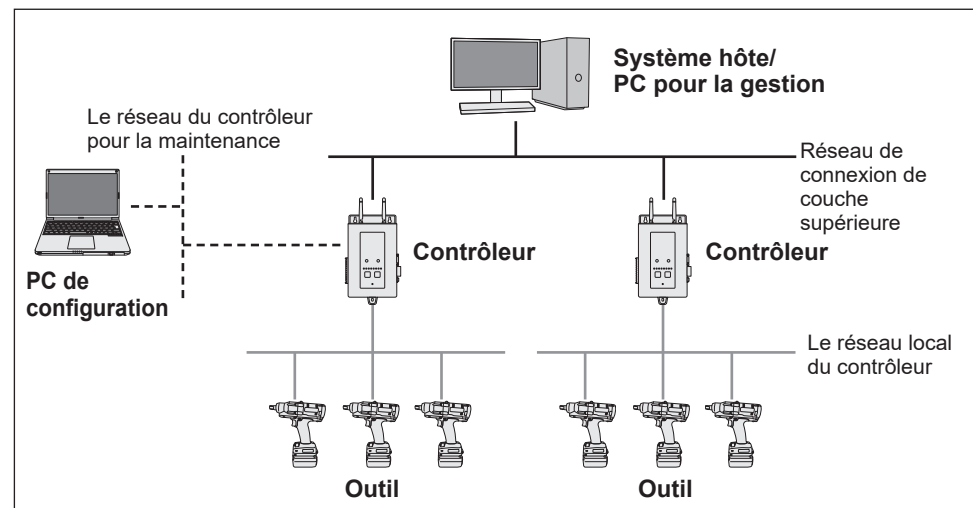
*2 Ceci est pris en charge uniquement par la version de micrologiciel 2.03.00 ou ultérieure.

Configurations de réseau typiques

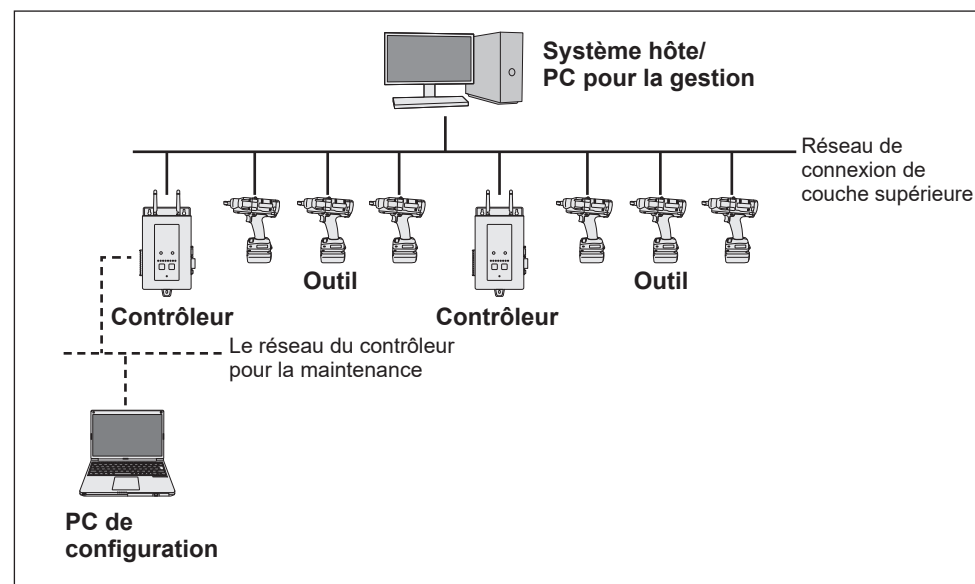
Le contrôleur peut être utilisé dans les 3 configurations ci-dessous.

■ Sans gérer les adresses IP de l'outil

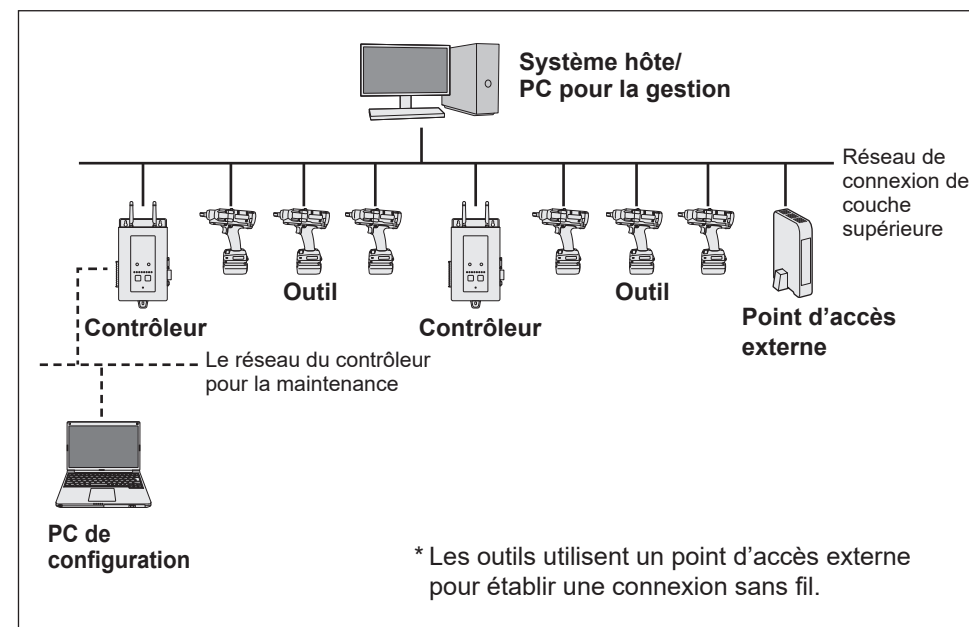
* Attribution automatique (utilisation du point d'accès intégré dans le contrôleur)



■ Gestion des adresses IP de l'outil (en utilisant le point d'accès intégré dans le contrôleur)



■ Reconnaissance des adresses IP de l'outil (en utilisant des points d'accès externes)



* Utilisez le système au sein de votre réseau local (sans connexion Internet).

* Assurez-vous de vérifier le réglage de l'adresse IP pour le réseau du contrôleur avant de commencer à l'utiliser. (Modifiez la valeur par défaut si nécessaire)

OUTIL CONNECTABLE/PRÉCAUTIONS À PRENDRE POUR L'INSTALLATION

Liste des modèles d'outil applicables

Modèles pouvant être enregistrés	EYFNH1WC/WP*1 EYFMH1WC/WP EYFMH2WC/WP
----------------------------------	---

*1 Ceci est pris en charge uniquement par la version de micrologiciel 2.02.00 ou ultérieure.

Précautions pour l'installation

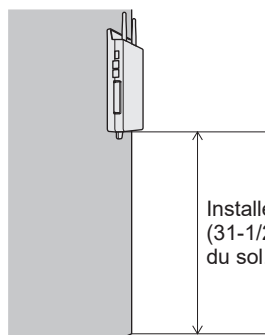
Installez le contrôleur à 80 cm (31-1/2") ou plus au-dessus du sol. Maintenez un espace de 10 cm (3-15/16") ou plus entre les contrôleurs installés. (une distance de 1 m (39-3/8") ou plus est recommandée)

Dégagez toute obstruction aux antennes du contrôleur installé.

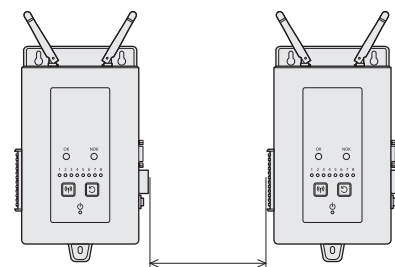
Le contrôleur a 2 antennes en diversité. Dégagez toute obstruction des deux antennes.

⚠ MISE EN GARDE

Pour garantir une installation en toute sécurité, utilisez des vis à bois d'un diamètre nominal compris entre 3,5 (1/8") et 4,1 mm (5/32").



Installez le contrôleur à 80 cm (31-1/2") ou plus au-dessus du sol.

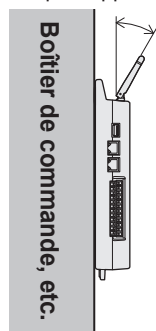


Maintenez un espace de 10 cm (3-15/16") ou plus entre les contrôleurs installés.

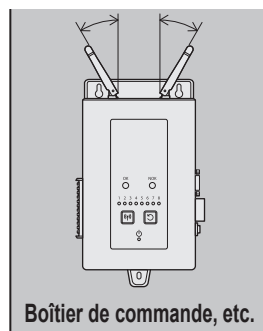
Régalez l'inclinaison des antennes si la communication est instable.

* En particulier pour le contrôleur installé sur un panneau métallique, le réglage de l'inclinaison des antennes peut améliorer la stabilité de la communication.

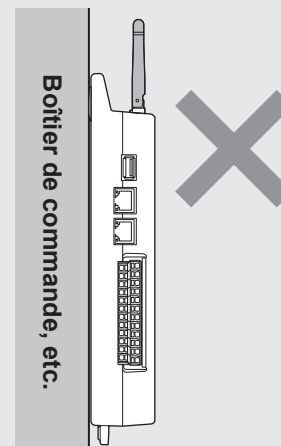
Inclinez les antennes de 30° à 45° par rapport au mur.



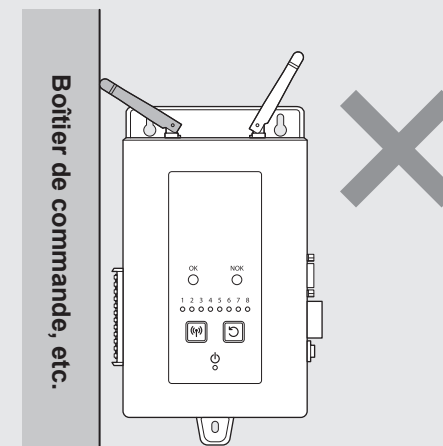
Inclinez les antennes de 30° à 45° vers l'extérieur, vue de l'avant.



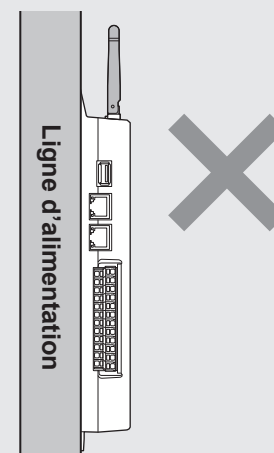
■ Évitez l'installation suivante.



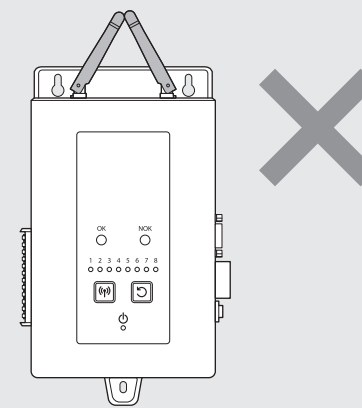
L'antenne est en parallèle avec le boîtier de commande (panneau métallique) à l'arrière.



L'antenne est en contact avec le boîtier de commande (panneau métallique).



Le contrôleur est installé très près d'une ligne d'alimentation.



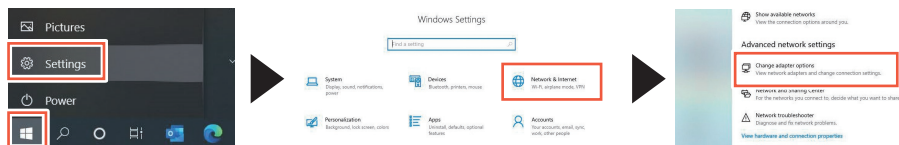
Les antennes sont en contact l'une avec l'autre.

PRÉPARATION AVANT L'UTILISATION

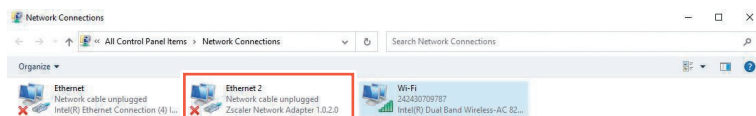
Réglages réseau sur le PC de configuration

Configurez les paramètres réseau sur le PC de configuration comme indiqué ci-dessous lorsque vous le connectez ainsi que le contrôleur pour la première fois.

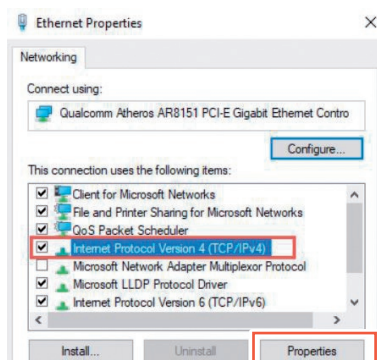
- 1 Cliquez sur  en bas à gauche de l'écran et cliquez sur  (Settings) – [Network & Internet] – [Change adapter options].



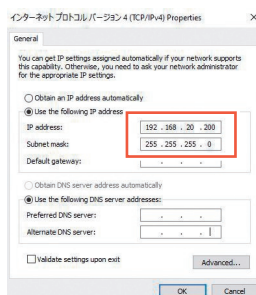
- 2 Cliquez avec le bouton droit sur l'appareil à connecter et cliquez sur [Properties].



- 3 Sélectionnez « Internet Protocol Version 4 » et cliquez sur [Properties].



- 4 Réglez « IP address » et « Subnet mask » comme ci-dessous.



IP address	192 . 168 . 20 . 200
Subnet mask	255 . 255 . 255 . 0

- * Si vous avez modifié l'adresse IP du contrôleur après la connexion initiale, activez la connexion en rétablissant les paramètres réseau (adresse IP et masque de sous-réseau) sur le PC de configuration. À ce stade, configurez l'adresse IP de sorte que le contrôleur et le PC de configuration appartiennent au même réseau.
- * Notez et conservez les paramètres réseau du PC de configuration (adresse IP et masque de sous-réseau) avant de les modifier.
- * Il est recommandé de laisser la passerelle par défaut non spécifiée (vide).

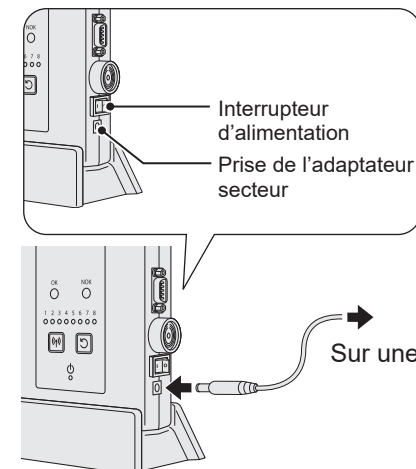
Affichage de l'écran de configuration

Pour configurer le contrôleur, accédez à travers un navigateur Web. Affichez l'écran de configuration du contrôleur comme ci-dessous.

Lorsque vous utilisez le contrôleur pour la première fois, retirez le film de protection de la pile bouton.

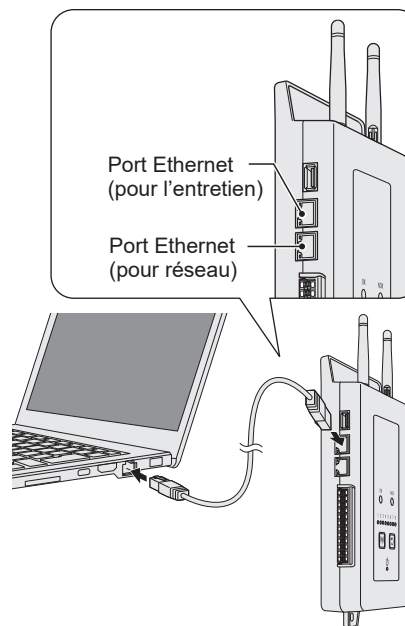
- 1 Activez le contrôleur.

- 1 Connectez l'adaptateur AC fourni au contrôleur et branchez la fiche d'alimentation sur une prise de courant.
- 2 Mettez l'interrupteur d'alimentation du contrôleur sur Marche.
 - * Le démarrage prend quelques dizaines de secondes.
 - * Au démarrage, le témoin de fixation OK, le témoin de fixation NOK, et le témoin de communication (N° 1 à N° 8) clignotent simultanément.
 - * Ne connectez pas de câbles LAN.



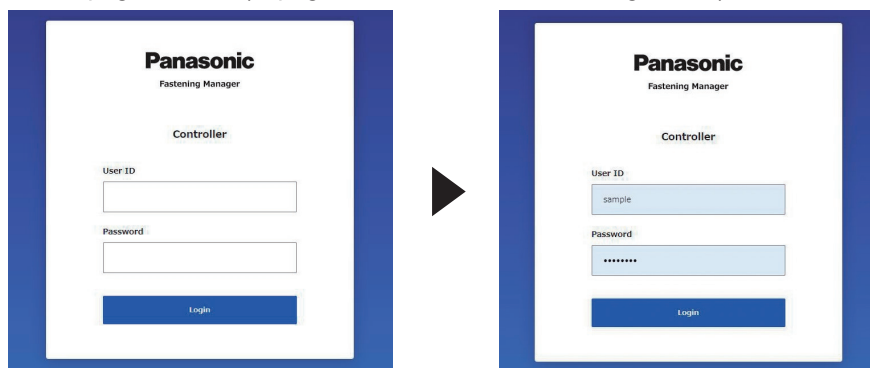
- 2 Connectez le contrôleur au PC de configuration à l'aide d'un câble LAN.

- 1 Connectez un câble LAN au port Ethernet du contrôleur.
 - * Le contrôleur possède 2 ports Ethernet : un pour la maintenance et un autre pour le réseau. Utilisez celui réservé à la maintenance pour la première connexion.
- 2 Connectez au PC de configuration avec le câble LAN.



3 Démarrez un navigateur Web sur le PC de configuration et accédez au contrôleur.

- ① Démarrez un navigateur web sur le PC de configuration. (Microsoft Edge est recommandé)
- ② Entrez l'adresse IP du contrôleur dans la barre d'adresse du navigateur web.
 - * L'adresse IP par défaut pour le port Ethernet (pour la maintenance) est « 192.168.20.10 ».
- ③ Dans l'écran de connexion affiché, saisissez l'ID utilisateur et le mot de passe.
 - * L'ID utilisateur et le mot de passe pour la connexion initiale sont indiqués ci-dessous.
- ④ La page du haut (la page initiale de l'écran de configuration) s'affiche.



ID utilisateur et mot de passe pour la connexion initiale

Connectez-vous avec l'ID utilisateur et le mot de passe ci-dessous.

■ ID utilisateur: **root**

■ Mot de passe: **abcABC123**

* Le type de compte pour la connexion initiale est « default ». Pour les types de compte, voir « Types de compte (autorités) ».

Se reporter à P19

* Seule la création de compte est possible lorsque vous vous connectez avec l'ID utilisateur et le mot de passe ci-dessus. Créez un nouveau compte avant de commencer l'utilisation.

* Pour des raisons de sécurité, le changement du mot de passe ci-dessus est recommandé après la connexion initiale.

Types de compte (autorités)

Voici les types de compte. Utilisez-les conformément aux applications.

Type de compte	Fonction
Par défaut	- Pour la connexion initiale. Se reporter à P18 - Ajout ou modification d'un compte utilisateur.
Administrator	- Affichage de l'historique de fixation. - Configuration du contrôleur. - Configuration des outils. - Ajout ou modification d'un compte utilisateur. * Créez au moins un compte administrateur.
General	Affichage de l'historique des fixations (y compris l'affichage du moniteur de travail).

Jusqu'à 10 comptes peuvent être enregistrés.

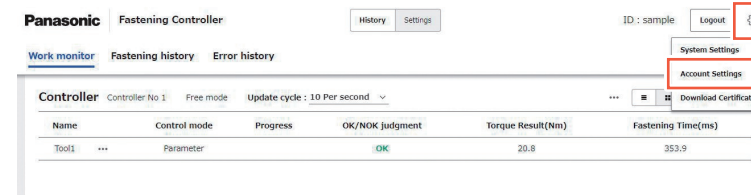
Ainsi, plusieurs opérateurs peuvent se connecter simultanément.

* Un seul compte peut se connecter en tant qu'administrateur en même temps. Lorsque plusieurs accès sont tentés, la dernière session est prioritaire.

Création d'un compte utilisateur

Créez un nouveau compte avant de commencer l'utilisation.

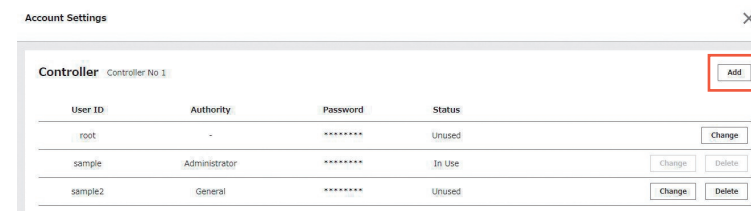
- 1 Dans la page supérieure (la page initiale de l'écran de configuration), cliquez sur la touche d'option dans le coin supérieur droit et sélectionnez « Account Settings ». L'écran « Account Settings » s'affiche.



- 2 Dans l'écran « Account settings », cliquez sur [Add].

L'écran « Add account » s'affiche.

* Cliquez sur [Change] pour changer le compte et sur [Delete] pour supprimer le compte.



3 Entrez « User ID » et « Password », sélectionnez « Authority » et cliquez sur [Add].

- * Créez un compte administrateur pour configurer les outils.
- * Pour un mot de passe, utilisez toujours une combinaison de 3 types de caractères ou parmi les majuscules, minuscules, chiffres et symboles.

[Référence] Si vous avez perdu l'ID utilisateur ou le mot de passe

■ Compte général

- [Méthode 1] Connectez-vous en tant qu'administrateur et modifiez le compte concerné.
- * Un utilisateur général ne peut pas modifier l'ID utilisateur et le mot de passe et doit demander à un administrateur de les modifier.
- [Méthode 2] Connectez-vous avec un nouveau compte administrateur et modifiez le compte concerné.
- * Connectez-vous avec l'ID utilisateur et le mot de passe pour la connexion initiale et créez un nouveau compte administrateur.

Se reporter à P18

■ Compte Administrateur

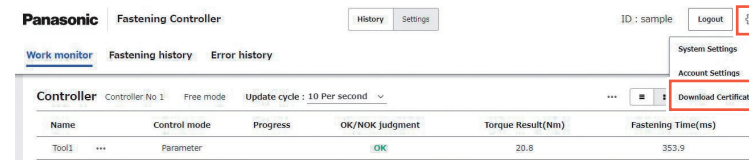
- A) Lorsque plusieurs comptes administrateur ont été créés
- [Méthode 1] Connectez-vous avec un autre compte administrateur et modifiez le compte concerné.
- [Méthode 2] Connectez-vous avec un nouveau compte administrateur et modifiez le compte concerné.
- * Connectez-vous avec l'ID utilisateur et le mot de passe pour la connexion initiale et créez un nouveau compte administrateur.
- Se reporter à P18**
- [Méthode 3] Initialisez les paramètres si vous avez perdu les identifiants et les mots de passe de tous les comptes administrateur. **Se reporter à P85**
- B) Lorsqu'un seul compte administrateur a été créé
- [Méthode 1] Connectez-vous avec un nouveau compte administrateur et modifiez le compte concerné.
- * Connectez-vous avec l'ID utilisateur et le mot de passe pour la connexion initiale et créez un nouveau compte administrateur.
- Se reporter à P18**
- [Méthode 2] Initialisez les paramètres si vous avez perdu les identifiants et les mots de passe de tous les comptes administrateur. **Se reporter à P85**

Obtention d'un certificat

Un certificat est nécessaire pour accéder au contrôleur via le port Ethernet (pour le réseau).

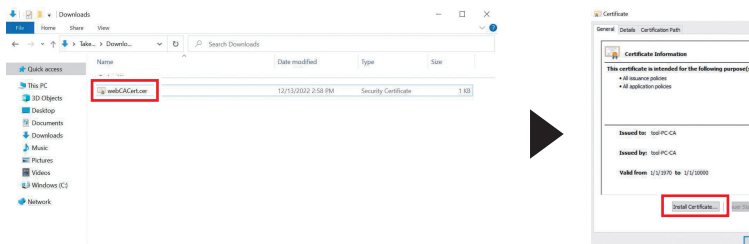
Vous pouvez obtenir un certificat comme ci-dessous.

- 1 Dans la page supérieure (la page initiale de l'écran de configuration), cliquez sur la touche d'option dans le coin supérieur droit et sélectionnez « Download Certificate ».
- Une référence de certificat est téléchargée sur le PC de configuration.

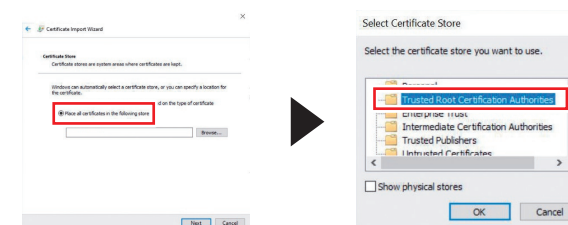


- 2 Installez le certificat dans le « PC de configuration utilisé pour accéder au contrôleur via le réseau ».

- ① Double-cliquez sur la référence du certificat téléchargé et sélectionnez « Install certificate ».



- ② Sélectionnez « Place all certificates in the following store » puis sélectionnez « Trusted Root Certification Authorities ».



Connexion via le réseau

Dans la barre d'adresse du navigateur Web, entrez « https://XXX.XXX.XXX.XXX/ » pour connecter le contrôleur via le port Ethernet (pour le réseau).

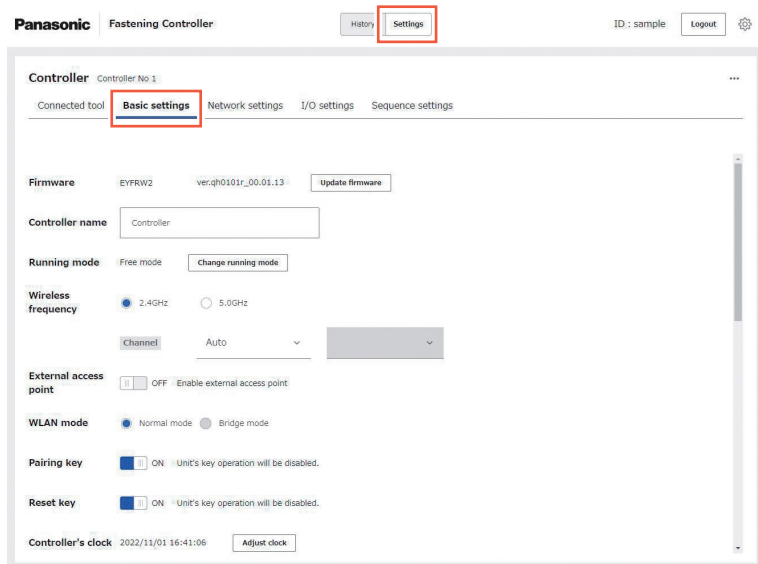
* « XXX.XXX.XXX.XXX » est une adresse IP.

* L'adresse IP par défaut est « 192.168.0.10 ». Si vous avez modifié l'adresse par défaut, entrez celle qui a été modifiée. **Se reporter à P26**

Paramètres de base

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Basic settings ».

Vous pouvez configurer le contrôleur.

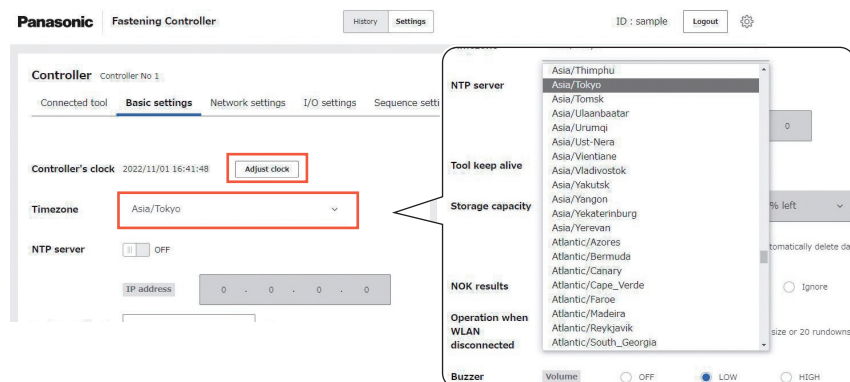


Réglage de l'heure

Sélectionnez « Timezone » puis cliquez sur [Adjust clock].

L'heure est actualisée.

- L'heure n'est pas encore réglée au moment de l'expédition. Assurez-vous de régler l'heure lorsque vous utilisez le contrôleur pour la première fois.



* Si vous utilisez un serveur NTP, entrez l'adresse IP.

Réglage de la fréquence radio et du canal

Vous pouvez régler la fréquence à utiliser.

Sélectionnez « 2.4GHz » ou « 5GHz » puis le canal à utiliser.

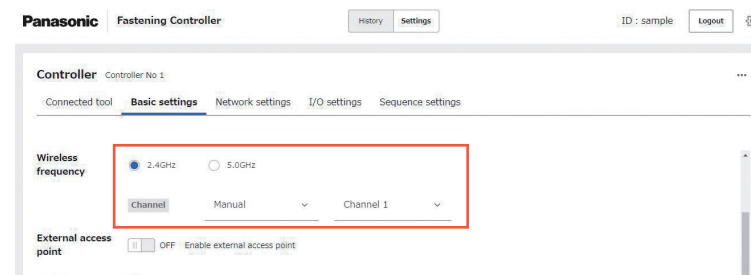
* Les canaux sélectionnables varient entre « 2.4GHz » et « 5GHz ».

* Vous pouvez régler « Auto Channel ».

Le contrôleur sélectionne automatiquement les canaux disponibles dans l'environnement proche lorsqu'il est activé.

Le réglage peut être efficace contre les interférences radio.

* Lorsque vous installez plusieurs contrôleurs les uns à côté des autres, ne réglez pas les canaux adjacents.



Éléments de réglage

Firmware

La version du micrologiciel du contrôleur est affichée.

Cliquez sur [Update firmware] pour mettre à jour le micrologiciel.

Pour savoir comment mettre à jour, voir « Mise à jour du micrologiciel ».

Se reporter à P87

Controller name

Vous pouvez enregistrer le nom du contrôleur.

Utilisez un maximum de 32 caractères alphanumériques.

[Plage de réglage] Jusqu'à 32 caractères alphanumériques

* Pour les symboles, seul «-» (tiret), «_» (tiret du bas), et « » (espace demi-largeur) peuvent être utilisés.

Running mode

Sélectionnez le mode de fonctionnement du contrôleur.

[Par défaut] Free mode

[Plage de réglage] Free mode / Repeat mode (Basic mode / Sequence mode) / External control mode

Wireless frequency

Sélectionnez le canal de fréquence à utiliser pour la communication sans fil.

[Par défaut] 2.4GHz

[Plage de réglage] 2.4GHz (Auto / Channel 1 à 13) / 5GHz (Auto / Channel 36, 40, 44, 48)

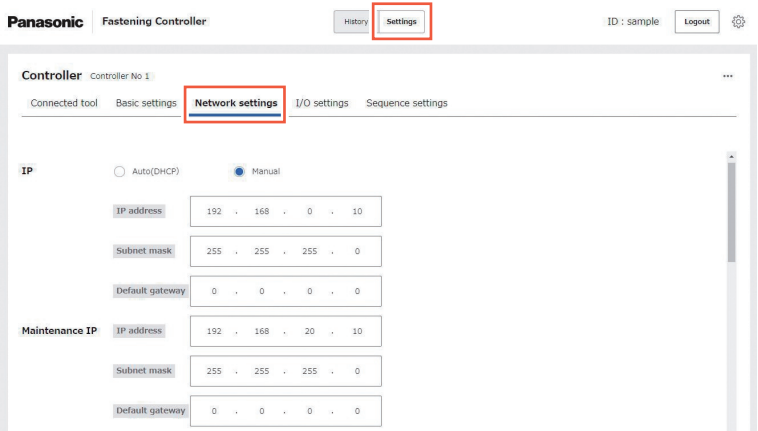
External access point
Vous pouvez activer la communication via un point d'accès externe. Se reporter à P69 [Par défaut] OFF (désactivé) [Plage de réglage] OFF (désactivé)/ON (activé) * WLAN mode : Ce réglage permet un fonctionnement sans utiliser de point d'accès externe. Mode normal : Sans gérer les adresses IP de l'outil (attribution automatique) Mode pont : En gérant (spécifiant) les adresses IP de l'outil
Pairing key
Vous pouvez activer la touche d'appariement. [Par défaut] ON (activé) [Plage de réglage] OFF (désactivé)/ON (activé)
Reset key
Vous pouvez activer la touche de réinitialisation. [Par défaut] ON (activé) [Plage de réglage] OFF (désactivé)/ON (activé)
Controller's clock
Réglez l'horloge du contrôleur. Cliquez sur [Adjust clock] pour actualiser l'heure.
Timezone
Vous pouvez régler un fuseau horaire souhaité lors du réglage de l'horloge du contrôleur.
NTP server
Définissez un serveur NTP si vous utilisez le réglage automatique de l'horloge.
Tool keep alive
Réglez la fréquence à laquelle le contrôleur vérifie la disponibilité des outils en mode de communication sans fil. Les outils qui ne répondent pas sont détectés comme étant hors ligne, puis sont déconnectés. [Par défaut] 30 s [Plage de réglage] 10 s à 3600 s

Storage capacity
Activez ou désactivez la notification de faible capacité d'entreposage et réglez le comportement en cas de manque de capacité. [Par défaut] Notification - OFF, Fonctionnement lorsque la capacité est insuffisante - Automatically delete data [Plage de réglage] Notification - OFF/ON (capacité restante 10/20/30/40/50 %), Fonctionnement lorsque la capacité est insuffisante - Suspend operation / Automatically delete data Le réglage par défaut est « Automatically delete data ». Réfléchissez bien à la manière de traiter les données avant de sélectionner « Suspend operation » si nécessaire.
NOK results
Sélectionnez comment gérer les résultats d'échec de fixation. [Par défaut] Store data only [Plage de réglage] Report to system / Store data only / Ignore
Operation when WLAN disconnected
Sélectionnez le comportement en cas d'interruption temporaire de la communication sans fil. [Par défaut] Suspend tool [Plage de réglage] Suspend tool / Enable fastening (Until batch size or 20 rundowns) Pour plus de détails, voir « COMPORTEMENT DE L'OUTIL AVEC LA COMMUNICATION SANS FIL DÉCONNECTÉE ». Se reporter à P76
Buzzer
Sélectionnez le volume et la signification du signal sonore. [Par défaut] Volume - LOW, Beep - Tous cochés [Plage de réglage] Volume - OFF/LOW/HIGH, Beep - Cochez ou décochez chaque élément
Barcode reader settings
Vous pouvez connecter un lecteur de codes-barres pour ajouter des informations de lecture aux données d'historique des fixations. [Reading Test] Affiche les informations lues par le lecteur de codes-barres. [Bluetooth settings] Ces paramètres sont utilisés lorsque vous connectez un lecteur de codes-barres de type Bluetooth. Le bouton « Search » permet d'afficher les périphériques connectables. Utilisez « Pairing » pour sélectionner un périphérique à connecter. S'il est déjà connecté, l'adresse MAC/le nom du périphériques s'affiche. Vous pouvez le déconnecter en sélectionnant « Cancel registration ».

Paramètres réseau

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Paramètres] en haut et sélectionnez l'onglet « Paramètres réseau ».

Vous pouvez régler les paramètres réseau du contrôleur.



Éléments de réglage

IP
Configurez l'adresse IP du port Ethernet (pour le réseau).
[Par défaut] Manual
[Plage de réglage] Auto (DHCP) / Manual
* Pour « Manual »
[Par défaut] IP address - 192.168.0.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0
Maintenance IP
Configurez l'adresse IP du port Ethernet (pour la maintenance).
[Par défaut] IP address - 192.168.20.10
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0
WLAN
Configurez l'adresse IP (du côté du contrôleur) pour la communication sans fil avec les outils.
[Par défaut] IP address - 192.168.100.1
Subnet mask - 255.255.255.0
Default gateway - 0.0.0.0

Atlas Open Protocol
Définissez les paramètres relatifs au protocole Atlas Open. Pour plus de détails, voir « Connexion via la communication Open Protocol ».
Se reporter à P57
RS232C
Ceci est un réglage spécifique à TOYOTA MOTOR CORPORATION. Le contrôle à partir de périphériques externes est possible.
[Par défaut] Disable
[Plage de réglage] Disable / Enable
Step flow after tightening NG
Ce paramètre détermine si vous pouvez passer au serrage suivant en cas de résultat de serrage NG.
[Par défaut] Keep
[Plage de réglage] Next (Le serrage suivant peut être effectué.) / Keep (Le serrage suivant ne peut pas être effectué.)
Access point
Définissez le point d'accès interne pour la communication sans fil avec les outils.
[Par défaut] SSID - Numéro de modèle du contrôleur-adresse MAC
Security-WPA2
[Plage de réglage] SSID - Un maximum de 32 caractères alphanumériques
Security-WPA2
External access point
Configurez le point d'accès externe à utiliser.
[Par défaut] SSID - Vide
Security - Vide
Password - Vide
[Plage de réglage] SSID - Un maximum de 32 caractères alphanumériques
Security - Open/WPA2
Password - 8 à 63 caractères alphanumériques
* Pour les symboles, uniquement «"», «¥», «,», et «' (apostrophe)» peuvent être utilisés.
* L'option est activée uniquement lorsque le « External access point » a été réglé sur « ON » dans le réglage basique.

- Pour les adresses IP pour « IP » et « Maintenance IP », n'utilisez pas le même sous-réseau.
(Lorsque vous définissez une valeur par défaut (255.255.255.0) dans« Subnet mask », définissez des valeurs différentes dans la partie correspondante à « 192.168.0 » ou « 192.168.20 ».)
- Seul « Atlas Open Protocol » ou « RS232C » peut être activé, l'un ou l'autre. Ils ne peuvent pas être utilisés simultanément.

Démarrage du mode d'appariement sur le contrôleur

Vous pouvez mettre le contrôleur en mode d'appariement avec « Utilisation de la touche sur l'unité » ou « Réglage dans l'écran de configuration ».

Pendant 2 minutes en mode d'appariement, démarrez le mode d'appariement sur un outil dans la zone de couverture pour établir l'appariement.

Si l'appariement n'est pas établi dans le délai, le mode d'appariement se termine.

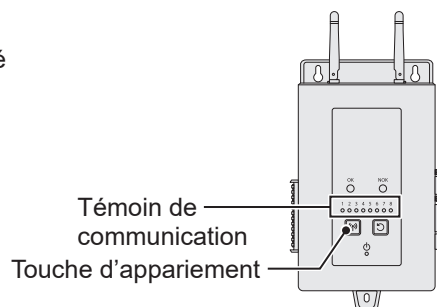
* Après avoir tenté de démarrer l'appariement, cela peut prendre un certain temps pour que le contrôleur entre en mode d'appariement.

Utilisation de la touche sur l'unité

Utilisez la touche d'appariement sur l'unité du contrôleur.

Sélectionnez le témoin de communication du numéro sans enregistrement (témoin éteint) et maintenez la touche d'appariement enfoncée pour entrer en mode d'appariement.

Voir la procédure suivante pour plus de détails.



(Pour enregistrer l'outil N° 4)

1 Appuyez sur la touche d'appariement sur le contrôleur 4 fois pour sélectionner l'outil N° 4.

Le témoin de communication N° 4 clignote.



2 Lorsque le N° 4 est sélectionné, maintenez la touche d'appariement enfoncée sur le contrôleur pour entrer en mode d'appariement de l'outil N° 4.

En mode d'appariement, le témoin de communication N° 4 commence à clignoter rapidement.

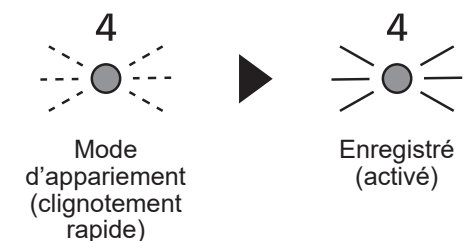


3 Actionnez l'outil N° 4 pour établir l'appariement.

Le témoin de communication N° 4 reste allumé.

Pour savoir comment utiliser l'outil, voir « Démarrage du mode d'appariement sur un outil ».

Se reporter à P30

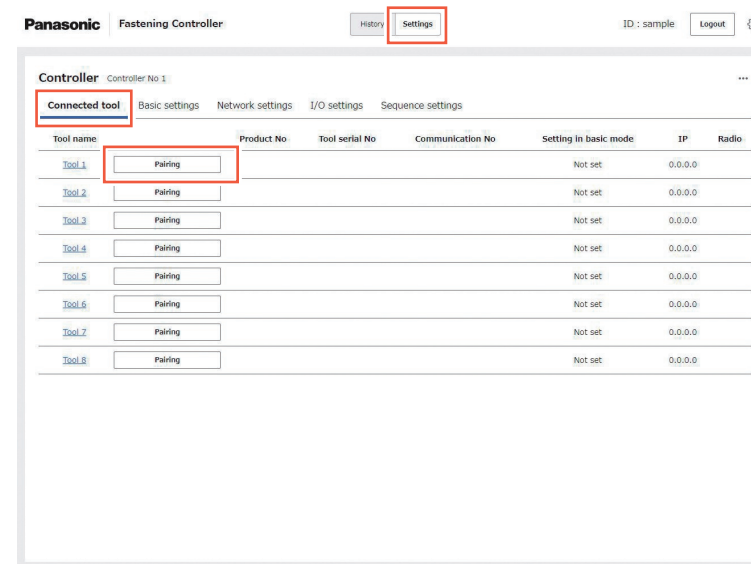


Réglage dans l'écran de configuration

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

Dans l'écran « Connected tool », cliquez sur [Pairing] du numéro d'outil souhaité.

Une fois que le contrôleur entre en mode d'appariement, effectuez la procédure dans « Démarrage du mode d'appariement sur un outil ». **Se reporter à P30**



<Pour référence> Remplacement par un outil de rechange

Lors du remplacement d'un outil apparié défectueux par un nouvel outil du même modèle, annulez l'appariement **Se reporter à P30** puis effectuez l'appariement

Se reporter à P28 afin que les paramètres de fixation et les autres réglages puissent être automatiquement transférés.

* Pour appairer avec un outil ayant un numéro de produit différent, annulez l'appariement pour supprimer les informations d'appariement actuelles avant de l'appairer avec. **Se reporter à P34**

Affichage lorsque l'appariement est terminé

Une fois l'appariement terminé, si l'écran de configuration n'affiche pas les informations de l'outil apparié, procédez à la mise à jour de l'affichage dans l'écran de configuration.

* En « Bridge mode » ou lorsque « External access point » est activé, réglez l'adresse IP de l'outil avant de commencer l'enregistrement de l'appariement.

Démarrage du mode d'appariement sur un outil

Mettez le contrôleur en mode d'appariement avant de démarrer le mode d'appariement sur un outil.

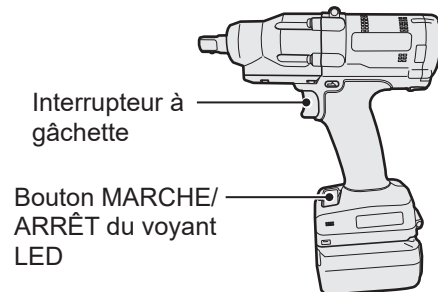
■ Procédure

1 Réglez le bloc-batterie. Tout en maintenant enfoncé le bouton MARCHE/ARRÊT du voyant LED, appuyez sur le bouton de déclenchement.

L'outil entre en mode d'appariement. La communication sans fil est automatiquement établie et l'enregistrement de l'appariement est terminé.

* Pour plus de détails, voir les Instructions d'utilisation de l'outil.

* Si l'appariement échoue, annulez l'appariement sur le contrôleur puis réessayez.

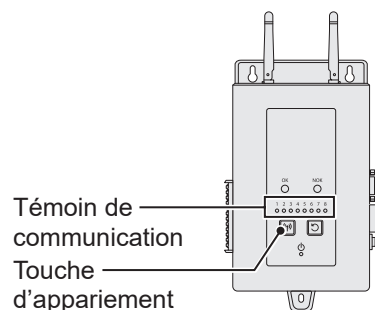


Annulation de l'appariement

Vous pouvez annuler l'enregistrement de l'appariement sur le contrôleur avec « Utilisation de la touche sur l'unité » ou « Réglage dans l'écran de configuration ».

■ Utilisation de la touche sur l'unité

Utilisez la touche d'appariement sur l'unité du contrôleur. Sélectionnez le témoin de communication du numéro d'outil dont vous souhaitez annuler l'enregistrement (témoin allumé) et maintenez la touche d'appariement enfoncée pour annuler l'enregistrement d'appariement. Voir la procédure suivante pour plus de détails.



(Pour annuler l'outil N° 4)

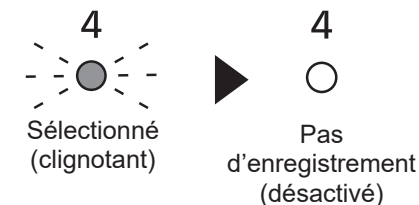
1 Appuyez sur la touche d'appariement sur le contrôleur 4 fois pour sélectionner l'outil N° 4.

Le témoin de communication N° 4 clignote.



2 Lorsque le N° 4 est sélectionné, maintenez la touche d'appariement enfoncée sur le contrôleur pour annuler l'enregistrement de l'appariement de l'outil N° 4.

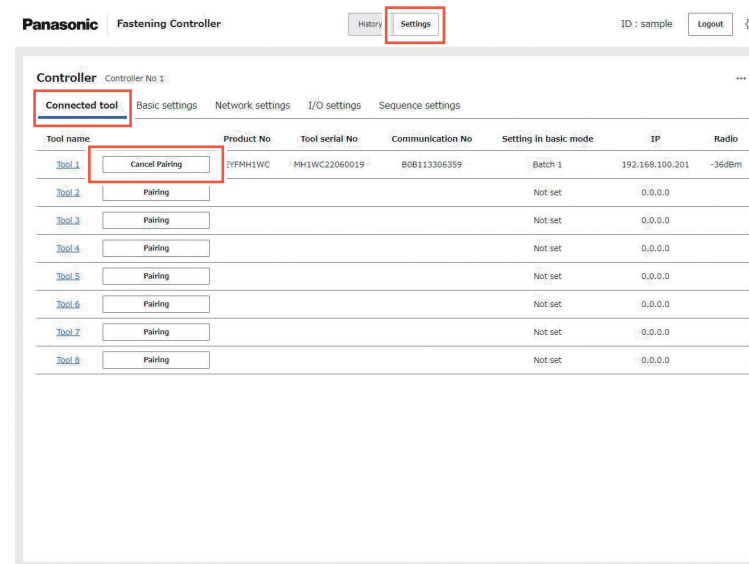
Lorsque l'appariement est annulé, le témoin de communication N° 4 arrête de clignoter et s'éteint.



■ Réglage dans l'écran de configuration

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

Dans l'écran « Connected tool », cliquez sur [Cancel Pairing] du numéro d'outil souhaité.

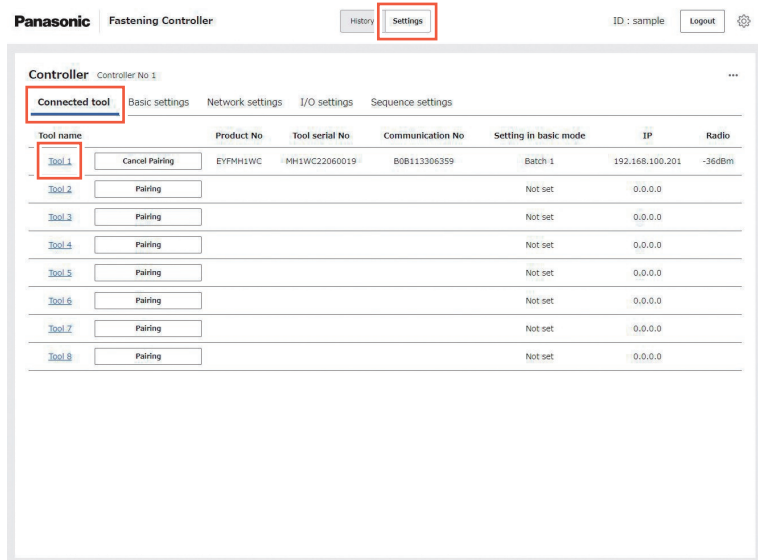


* Si le contrôleur ne peut pas communiquer avec l'outil en raison de l'arrêt de l'outil ou d'une autre raison, vérifiez [Force to unpair] dans la boîte de dialogue de confirmation d'annulation de l'appariement.

Affichage de l'écran Outil

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

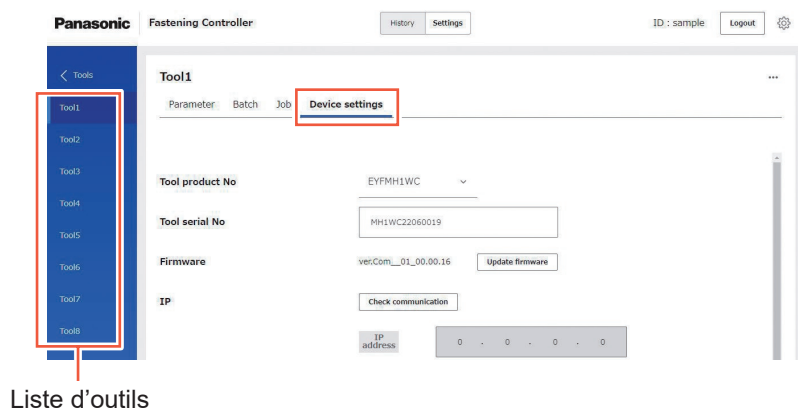
Dans l'écran « Connected tool », cliquez sur le numéro d'outilsouhaité. L'écran correspondant au numéro d'outil s'affiche.



Affichage de l'écran de configuration de l'outil

Dans l'onglet « Device settings » sur l'écran du numéro d'outil, vous pouvez effectuer les réglages de base de l'outil et entrer les paramètres communs.

* Pour changer l'outil, sélectionnez celui souhaité dans la liste d'outils.



Liste d'outils

Éléments de réglage de l'outil

Tool product No

Sélectionnez le numéro de produit d'outil.

[Par défaut] Vide

[Plage de réglage] Sélectionnable dans le menu déroulant

* Automatiquement sélectionné si vous établissez l'appariement au préalable.

* Le numéro de produit de l'outil ne peut pas être modifié après l'appariement. Annulez l'appariement, puis modifiez-le.

Tool serial No

Vous pouvez régler et afficher l'identification de l'unité de l'outil.

[Par défaut] ID de modèle à 5 chiffres + numéro de série à 8 chiffres (année de fabrication à 2 chiffres + mois à 2 chiffres + lot de production à 4 chiffres)

[Plage de réglage] 13 à 16 caractères alphanumériques

* Le numéro de modèle peut ne pas être reconnu correctement si les informations sont modifiées.

Ne le modifiez pas sauf si cela est nécessaire par la règle de gestion.

Firmware

La version du micrologiciel de la pièce de communication de l'outil est affichée.

Cliquez sur [Update firmware] pour mettre à jour le micrologiciel.

Pour savoir comment mettre à jour, voir « Mise à jour du micrologiciel ».

Se reporter à P87

IP

Définissez l'adresse IP (du côté de l'outil) pour la communication sans fil avec les outils.

[Par défaut] IP address - 192.168.100.201 (Outil 1) à 208 (Outil 8)

Subnet mask - 255.255.255.0

Default gateway - 0.0.0.0

* Ils deviennent tous « 0.0.0.0 » en Bridge mode ou lorsque « External access point » est activé.

Tool's clock

L'horloge de l'outil s'affiche. Cliquez sur [Adjust to controller] pour ajuster l'heure.

• Pour les autres éléments de réglage, voir les Instructions d'utilisation de l'outil.

Suppression des informations d'enregistrement

Pour arrêter l'utilisation d'un outil ou apparier un outil avec un numéro de produit différent, supprimez les informations d'appariement.

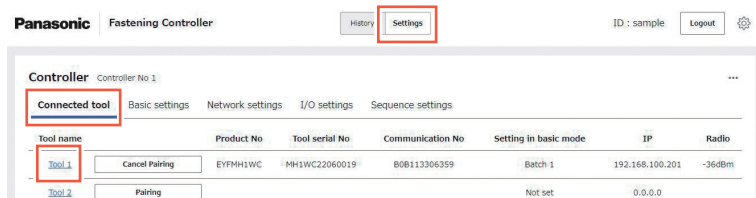
* Annulez l'appariement au préalable.

- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

L'écran « Connected tool » s'affiche.

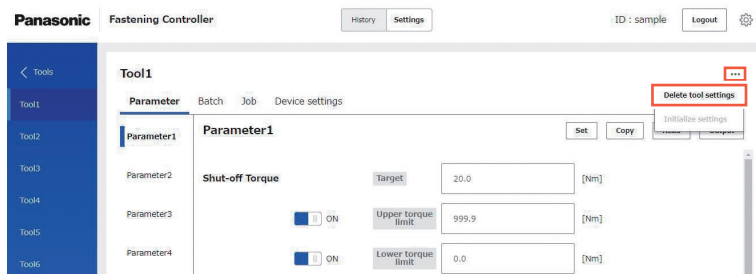
- 2 Dans l'écran « Connected tool », cliquez sur le numéro d'outil souhaité.

L'écran correspondant au numéro d'outil s'affiche.

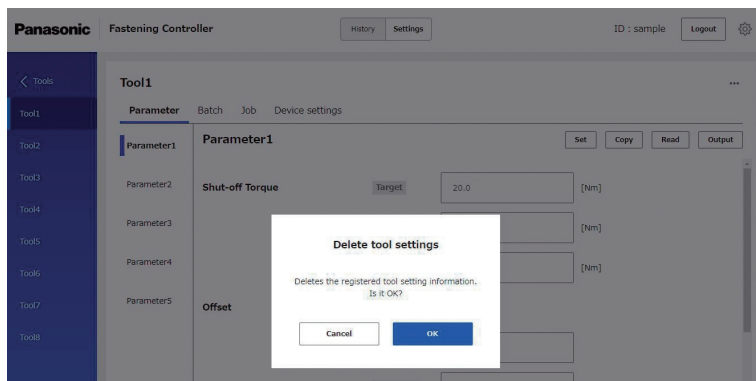


- 3 Cliquez sur ... (touche d'option d'outil) puis [Delete tool settings].

L'écran « Delete tool settings » s'affiche.



- 4 Dans l'écran « Delete tool settings », cliquez sur [OK].



Réinitialisation aux réglages d'usine

Vous pouvez réinitialiser un outil à ses réglages d'usine.

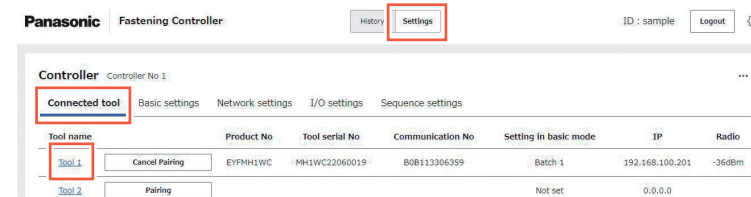
* La réinitialisation annule l'appariement.

- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

L'écran « Connected tool » s'affiche.

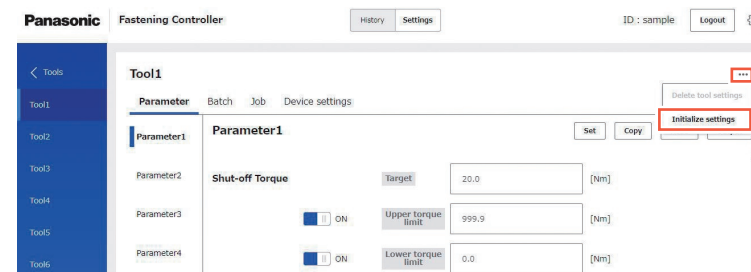
- 2 Dans l'écran « Connected tool », cliquez sur le numéro d'outilsouhaité.

L'écran correspondant au numéro d'outil s'affiche.

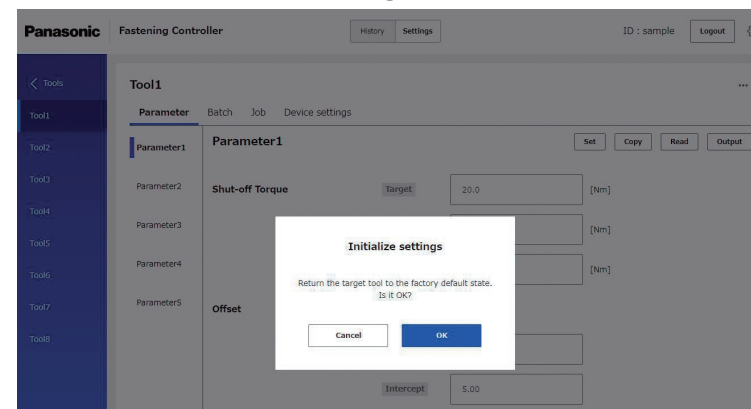


- 3 Cliquez sur ... (touche d'option d'outil) puis [Initialize settings].

L'écran « Initialize settings » s'affiche.



- 4 Dans l'écran « Initialize settings », cliquez sur [OK].



RÉGLAGE DES PARAMÈTRES DE FIXATION DES OUTILS

Réglage des paramètres

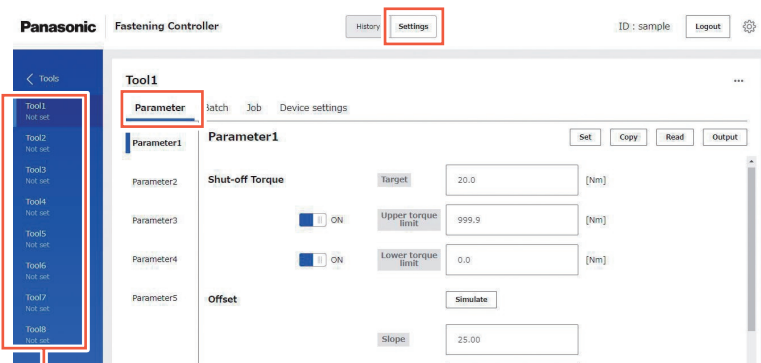
Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

Dans l'écran « Connected tool », cliquez sur le numéro d'outil souhaité.

Dans l'écran pour le numéro d'outil, sélectionnez l'onglet « Parameter » pour effectuer les réglages.

Vous pouvez définir cinq paramètres (paramètres 1 à 5) pour chaque outil.

* Pour changer l'outil, sélectionnez celui souhaité dans la liste d'outils.

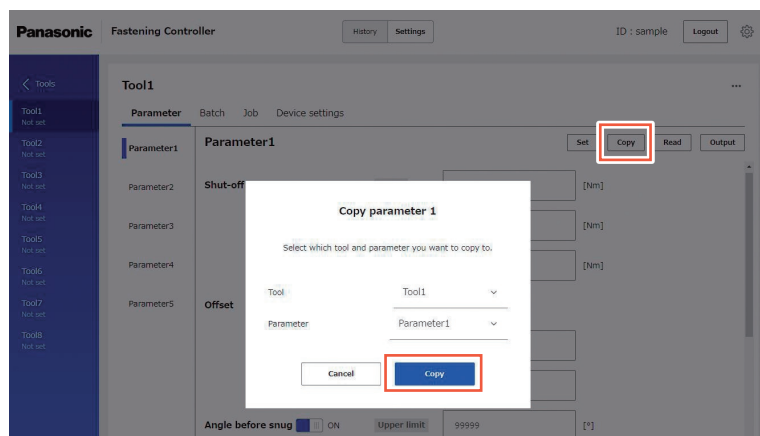


Liste d'outils

Copie des paramètres

Vous pouvez copier le paramètre défini pour créer un nouveau paramètre ou l'utiliser sur un autre outil.

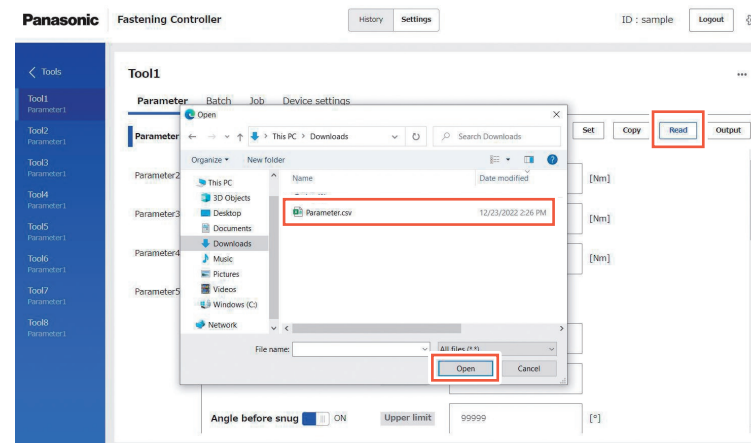
Dans l'onglet « Parameter » de l'écran du numéro d'outil, cliquez sur [Copy] pour afficher l'écran de copie du paramètre. Dans l'écran, sélectionnez la destination et cliquez sur [Copy].



Chargement des paramètres

Vous pouvez enregistrer un paramètre en chargeant un fichier de paramètre enregistré dans le PC de configuration dans le contrôleur.

Vous pouvez également charger un fichier de paramètres créé avec « Tool Manager ». Dans l'onglet « Parameter » de l'écran du numéro d'outil, cliquez sur [Read] et ouvrez le fichier de paramètres.



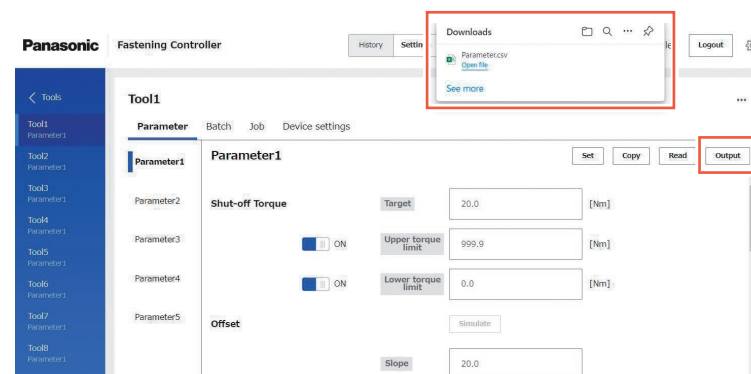
Exportation des paramètres

Vous pouvez exporter le paramètre créé vers le PC de configuration.

Vous pouvez utiliser le fichier exporté comme sauvegarde pour le copier vers un autre contrôleur, ou le déplacer vers un autre PC de configuration.

Dans l'onglet « Parameter » de l'écran du numéro d'outil, cliquez sur [Output] et enregistrez le fichier de paramètres.

Ne modifiez pas le fichier de paramètres exporté.
Sinon, il risque de ne pas être lu correctement.



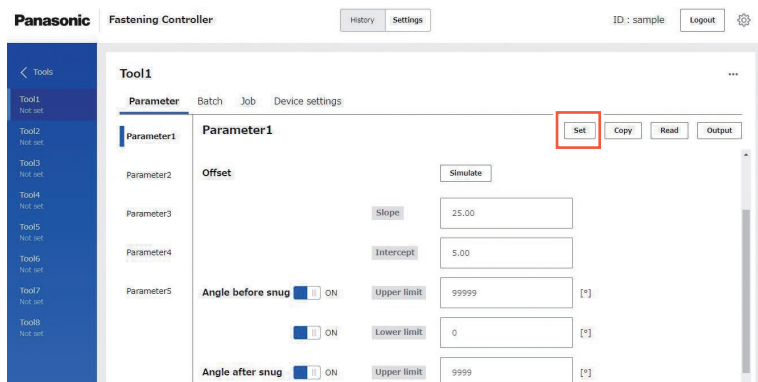
Enregistrement des paramètres

Enregistrez un paramètre pour l'utiliser afin de contrôler un outil en « Free mode » du mode de fonctionnement du contrôleur.

* Il n'est pas utilisé en « Repeat mode » et en « External control mode ».

(Pour le « Free mode », le « Repeat mode », et le « External control mode », voir « Configuration du mode de fonctionnement ». **Se reporter à P45**)

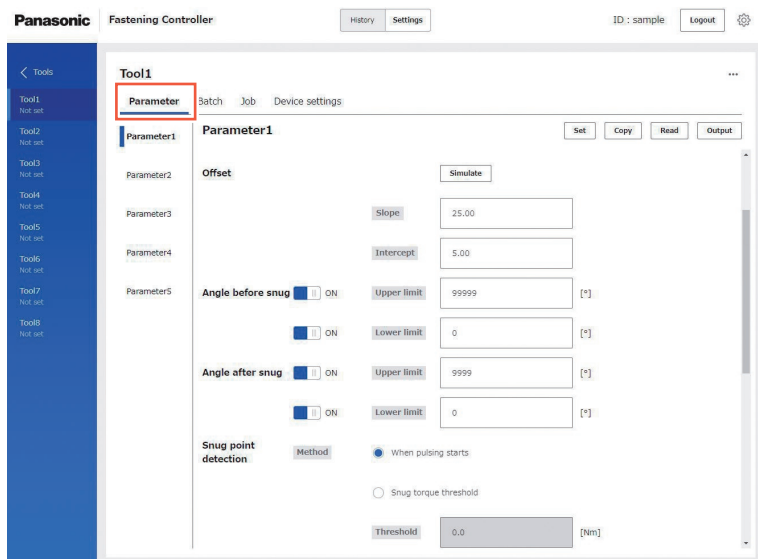
Dans l'onglet « Parameter » de l'écran du numéro d'outil, cliquez sur [Set].



Éléments de paramètres

Réglez les éléments de paramètre de fixation.

Pour plus de détails, voir les Instructions d'utilisation de l'outil.

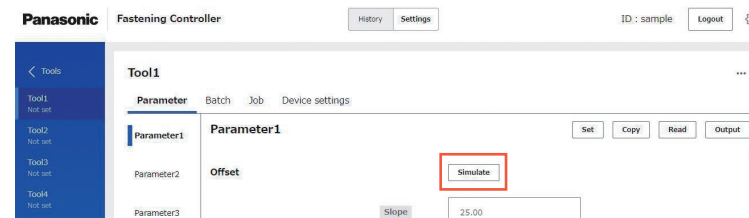


Réglage d'un décalage (paramètre, référence ①)

Définissez un décalage pour qu'il corresponde à la valeur de sortie du couple avec la valeur mesurée réelle.

1 Dans l'onglet « Parameter » de l'écran du numéro d'outil, cliquez sur [Simulate] dans « Offset ».

La page « Offset » s'affiche.



2 Entrez une valeur à définir et cliquez sur [Apply].

Entrez « Socket length » et « Shut-off Torque ». Cliquez sur [Apply] pour envoyer les valeurs d'entrée à l'outil. L'outil entre en mode de décalage (indiqué par T2).

3 Effectuez le travail réel à l'aide de l'outil puis cliquez sur [Get data].

Un journal d'historique de fixation est ajouté à la liste de l'historique dans la page « Offset ».

* Même si l'outil est prêt pour la fixation (« mode C ») après avoir cliqué sur [Get data], ne démarrez pas la fixation normale tant que le réglage du décalage n'est pas terminé.

4 Lorsque le journal de l'historique de fixation obtenu est sélectionné, saisissez une valeur de couple mesurée réelle (re-fixation) et cliquez sur [Calculer].

Un décalage correspondant au couple de sortie avec le couple mesuré réel de l'outil est calculé automatiquement.

5 Confirmez que le décalage est actualisé et cliquez sur [Apply].

La valeur réglée est envoyée à l'outil.

6 Répétez les étapes 3 à 5 jusqu'à ce que la différence devienne suffisamment minime.

* Conservez les valeurs dans la colonne « % » entre 95% et 105%.



[À propos du T1 mode]

Si [T1 mode] est coché dans l'écran de réglage de décalage, le contrôleur est en mode de sortie minimum.

(Si [T1 mode] est décoché le contrôleur revient en « Offset Mode ».)



T1 mode

[Description]

Vous pouvez vérifier si le contrôle de couple fonctionne correctement lorsque le couple cible est proche de la limite inférieure de la plage de contrôle du couple du contrôleur. Dans ce mode, le contrôleur est coupé aux décomptes minimum par minute (sortie minimale).

À ce stade, le journal de l'historique des travaux n'est pas enregistré.

Après avoir utilisé ce mode, utilisez une jauge de couple ou une clé dynamométrique pour vérifier que le couple de sortie du contrôleur n'a pas dépassé le couple cible.

L'unité de contrôleur peut ne pas être utilisable pour certaines opérations si son couple de sortie dépasse le couple cible dans ce mode.

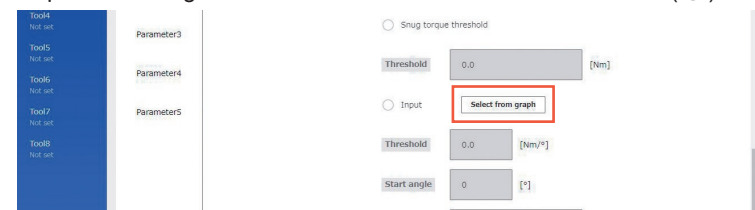
* La fixation avec d'autres outils est suspendue lorsque vous définissez un décalage.

■ Réglage d'un point d'adaptation (paramètre, référence ②)

Vous pouvez régler un point de visée en fonction d'une forme d'onde.

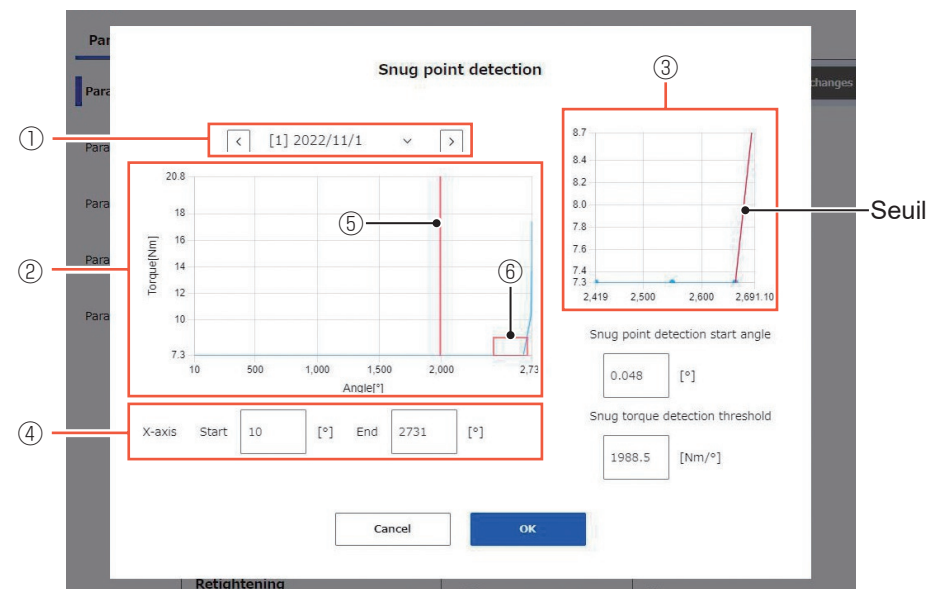
1 Dans l'onglet « Parameter » de l'écran de numéro d'outil, cliquez sur [Select from graph] dans « Snug point detection ».

- L'écran « Snug point detection » s'affiche avec la forme d'onde actuelle de l'outil.
- Les données d'historique de fixation sont nécessaires pour référence. Effectuez ce réglage après effectué au moins une fixation.
- Vous pouvez changer la forme d'onde à utiliser avec les flèches (①).



2 Définissez un seuil dans le graphique.

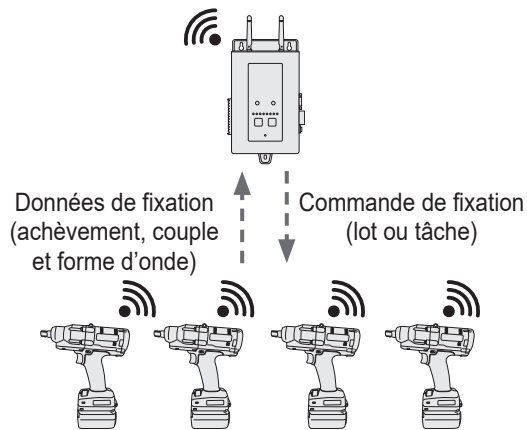
- La fenêtre principale (②) affiche une forme d'onde entière et la sous-fenêtre (③) agrandit une partie spécifique de la forme d'onde.
- Vous pouvez modifier l'étendue de la forme d'onde affichée dans la fenêtre principale en entrant les angles de début et de fin dans « X-axis » (④) sous le graphique.
- Vous pouvez régler l'angle de début de détection du point de visée (⑤) en déplaçant la barre verticale.
- Ajustez la position du cadre de sélection (⑥) dans la fenêtre principale pour modifier la taille d'affichage de la sous-fenêtre.
- Sélectionnez un seuil à régler dans la sous-fenêtre (③).



Contrôle de la fixation avec les outils

Le contrôleur peut contrôler jusqu'à 8 outils connectés pour la fixation. Il reçoit les données de fixation de chaque tâche de fixation et compte la quantité fixée.

Nombre maximum d'appareils connectés : 8



Combinaisons de commande de fixation typiques

Vous pouvez créer différentes combinaisons de paramètres de commande de fixation. Voir les combinaisons typiques ci-dessous.

Mode	[Free mode]	[Repeat mode]																							
		[Basic mode]	[Sequence mode]																						
Critère de réussite	— (La quantité n'est pas spécifiée)	La fixation de la quantité cible est terminée	Les outils effectuent la fixation des quantités ciblées respectives dans l'ordre spécifié																						
[Batch] « Valeur définie unique » (Fixation dans la même condition) * Type de pièce à usiner unique	A  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>10 Nm</td><td>∞</td></tr></table> Parameter	Valeur définie	Quantité ciblée	10 Nm	∞	A  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>10 Nm</td><td>10</td></tr></table> Batch	Valeur définie	Quantité ciblée	10 Nm	10	A ①  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>10 Nm</td><td>10</td></tr></table> B ②  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>20 Nm</td><td>5</td></tr></table> Batch et Sequence	Valeur définie	Quantité ciblée	10 Nm	10	Valeur définie	Quantité ciblée	20 Nm	5						
Valeur définie	Quantité ciblée																								
10 Nm	∞																								
Valeur définie	Quantité ciblée																								
10 Nm	10																								
Valeur définie	Quantité ciblée																								
10 Nm	10																								
Valeur définie	Quantité ciblée																								
20 Nm	5																								
[Job] Plusieurs valeurs définies (Fixation dans des conditions différentes) * Plusieurs types de pièces à usiner		A  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>10 Nm</td><td>2</td></tr><tr><td>20 Nm</td><td>3</td></tr><tr><td>30 Nm</td><td>5</td></tr></table> Job	Valeur définie	Quantité ciblée	10 Nm	2	20 Nm	3	30 Nm	5	A ①  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>10 Nm</td><td>2</td></tr><tr><td>20 Nm</td><td>3</td></tr><tr><td>30 Nm</td><td>5</td></tr></table> B ②  OK <table><tr><th>Valeur définie</th><th>Quantité ciblée</th></tr><tr><td>20 Nm</td><td>5</td></tr><tr><td>30 Nm</td><td>10</td></tr></table> Job et Sequence	Valeur définie	Quantité ciblée	10 Nm	2	20 Nm	3	30 Nm	5	Valeur définie	Quantité ciblée	20 Nm	5	30 Nm	10
Valeur définie	Quantité ciblée																								
10 Nm	2																								
20 Nm	3																								
30 Nm	5																								
Valeur définie	Quantité ciblée																								
10 Nm	2																								
20 Nm	3																								
30 Nm	5																								
Valeur définie	Quantité ciblée																								
20 Nm	5																								
30 Nm	10																								
Remarque	—	* Une tâche peut contenir jusqu'à 10 étapes.	* Une séquence peut contenir jusqu'à 10 étapes.																						

Nombre de combinaisons pouvant être enregistrées

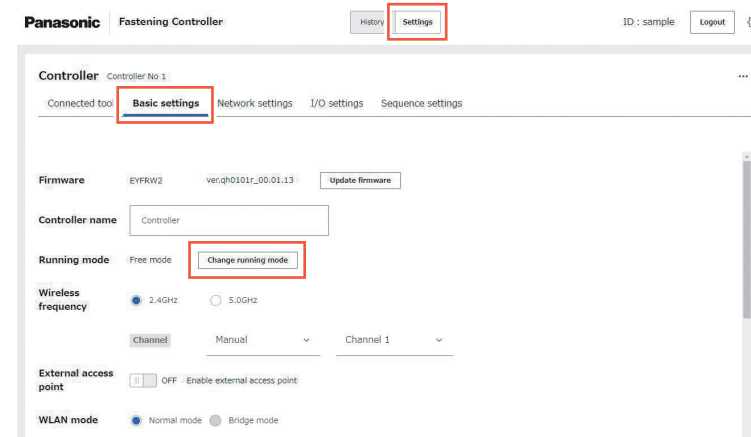
Voir le nombre de combinaisons qui peuvent être enregistrées dans le contrôleur comme indiqué ci-dessous.

Mode du contrôleur		Réglage de l'outil	Nombre de combinaisons pouvant être enregistrées
Free mode		Parameter	5 combinaisons par outil
Repeat mode	Basic mode (commande indépendante)	Batch	5 combinaisons par outil
		Job	5 combinaisons par outil
	Sequence mode (Contrôle séquentiel)	Batch/Job	5 combinaisons
External control mode		—	—

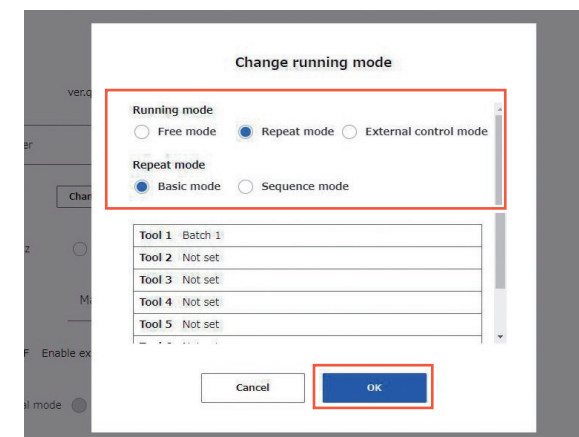
Configuration du mode de fonctionnement

Configurez le mode de fonctionnement du contrôleur comme indiqué ci-dessous.

- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Basic settings ».
- 2 Dans l'onglet « Basic settings », cliquez sur [Change running mode]. L'écran « Change running mode » s'affiche.



- 3 Sélectionnez un « Running mode » et cliquez sur [OK]. Le mode de fonctionnement est réglé. Sélectionnez un mode de fonctionnement entre « Free mode », « Repeat mode », et « External control mode ». Pour le « Repeat mode », sélectionnez « Basic mode » ou « Sequence mode ». **Se reporter à P46 à 49**



- * Enregistrez le « Parameter » avant de régler sur « Free mode ».
- * Enregistrez un « Batch/Job » avant de régler sur « Repeat mode ».

RÉGLAGE DU MODE DE COMMANDE DE FIXATION (suite)

■ Free mode

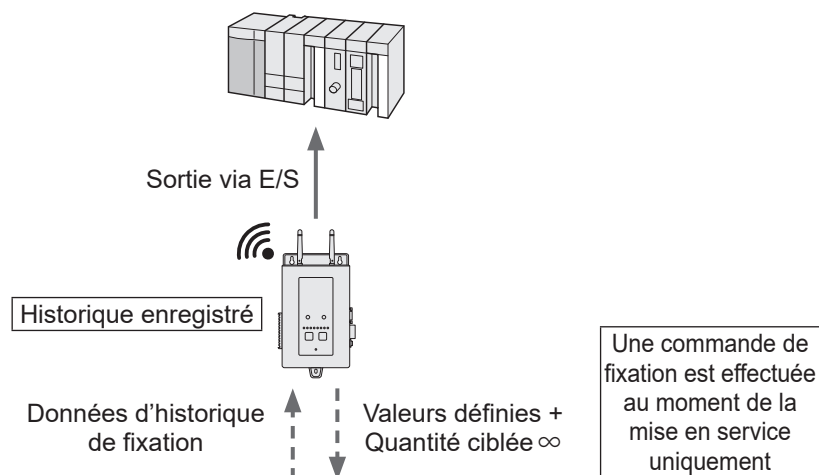
Ce mode permet une fixation inconditionnelle sans spécifier la quantité à fixer.

Les outils utilisent des paramètres pré-enregistrés pour la fixation.

Jusqu'à 8 outils peuvent effectuer une opération indépendante.

Les paramètres de sortie E/S sont activés.

* Utilisez le mode lorsque la quantité fixée est comptée par un appareil externe.








			
Valeur définie	Quantité ciblée	Valeur définie	Quantité ciblée
10 Nm	∞	20 Nm	∞
30 Nm	∞	40 Nm	∞

Jusqu'à 8 outils peuvent être commandés en même temps






			
Valeur définie	Quantité ciblée	Valeur définie	Quantité ciblée
50 Nm	∞	60 Nm	∞
70 Nm	∞	80 Nm	∞

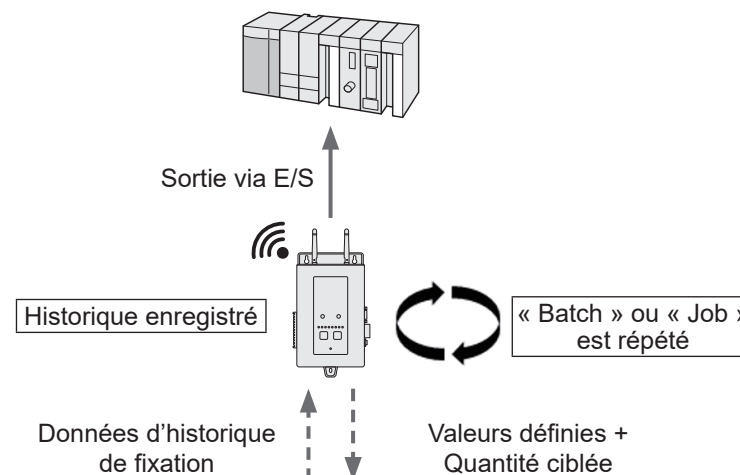
■ Repeat mode (Basic mode)

Ce mode répète un processus de « Batch » ou de « Job ».

Les outils utilisent des réglages de « Batch » ou de « Job » pour la fixation.

Jusqu'à 8 outils peuvent effectuer une opération indépendante.

Les paramètres de sortie E/S sont activés.








			
Valeur définie	Quantité ciblée	Valeur définie	Quantité ciblée
10 Nm	10	20 Nm	10
Valeur définie	Quantité ciblée	Valeur définie	Quantité ciblée
30 Nm	10	40 Nm	10

Jusqu'à 8 outils peuvent être commandés en même temps






			
Valeur définie	Quantité ciblée	Valeur définie	Quantité ciblée
50 Nm	10	60 Nm	10
60 Nm	5	70 Nm	5
70 Nm	5	80 Nm	5
		90 Nm	5
		10 Nm	5

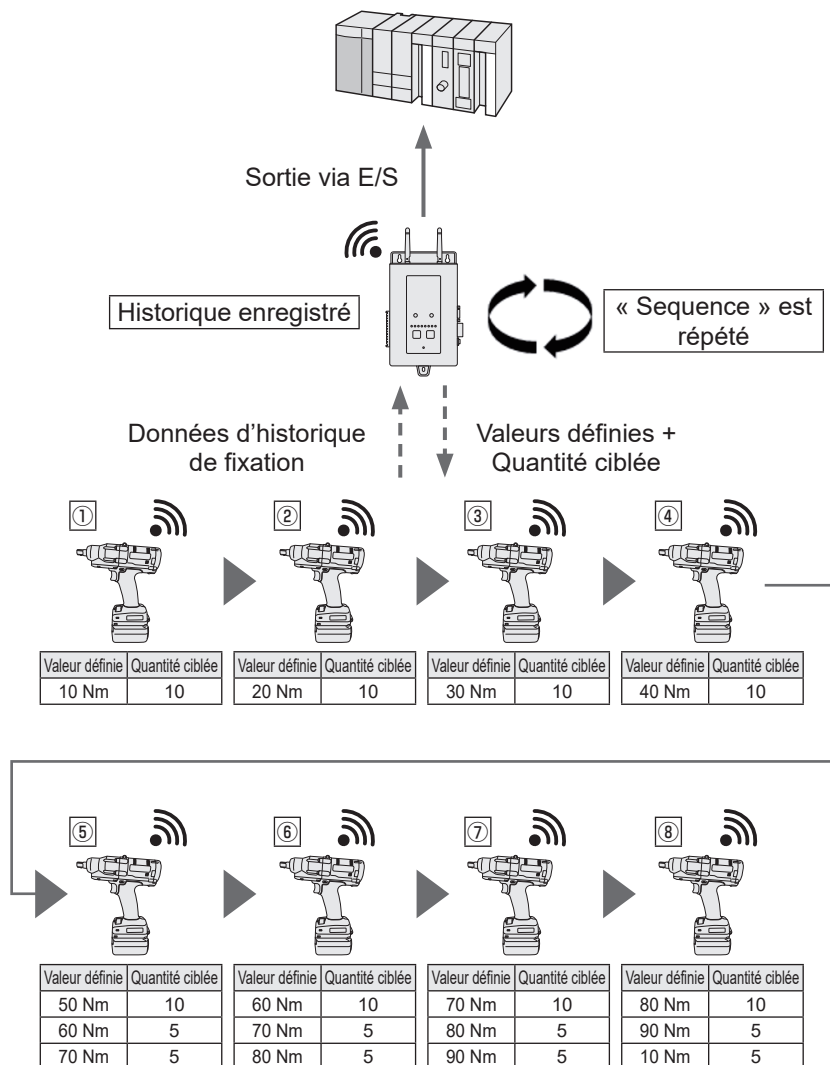
■ Repeat mode (Sequence mode)

Ce mode répète un processus de « Sequence » dans lequel les outils disponibles sont contrôlés dans l'ordre.

Les outils utilisent des réglages de « Sequence » pré-enregistrés pour la fixation séquentielle.

Jusqu'à 10 étapes peuvent être réglées. Une séquence prend en charge jusqu'à 8 outils, mais permet à un seul outil de fonctionner à la fois.

Les paramètres de sortie E/S sont activés.



■ External control mode

Ce mode permet le contrôle de la fixation commandé par un appareil externe (système hôte). Les 2 types de contrôle suivants sont pris en charge.

● Commande via Open Protocol (avec Open Protocol activé)

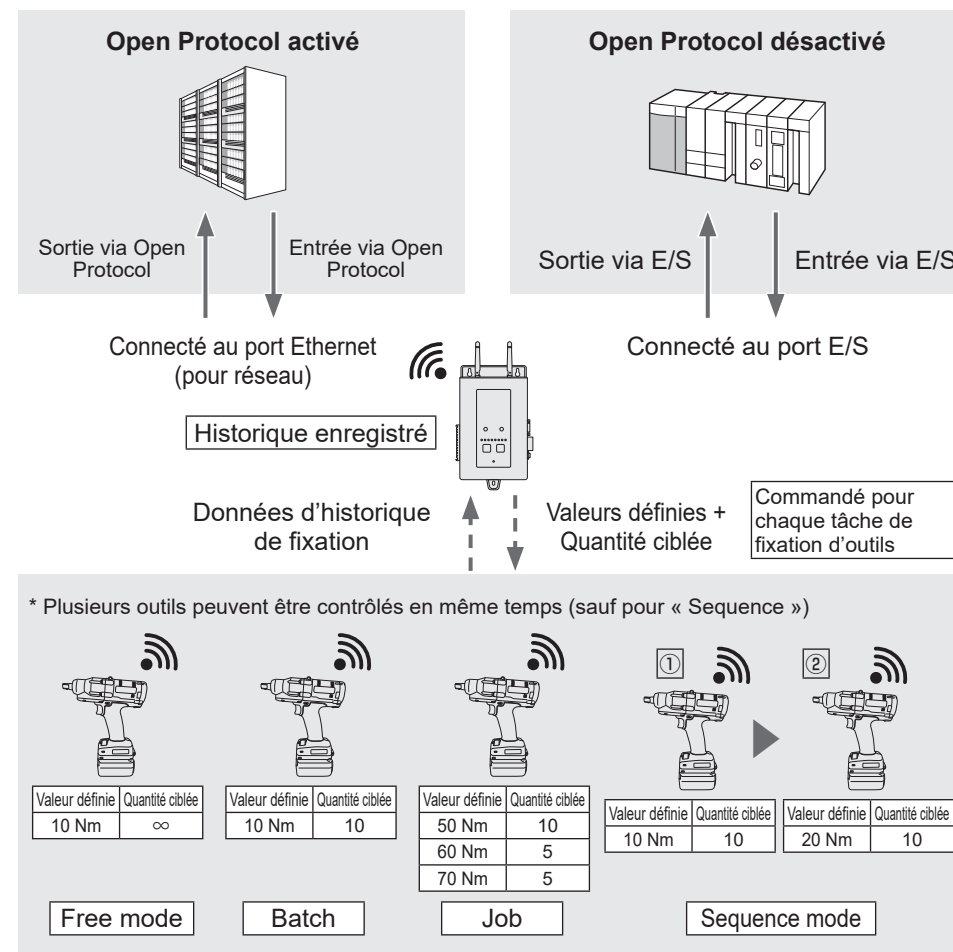
La fixation est contrôlée via Open Protocol par un système hôte.

Jusqu'à 8 outils peuvent être contrôlés indépendamment.

* Les contrôles de tâche et de séquence ne sont pas pris en charge.

● Contrôle via E/S (avec Open Protocol activé)

La fixation est commandée par les entrées via le port E/S d'un périphérique externe. Jusqu'à 8 outils peuvent être contrôlés indépendamment ou séquentiellement.



* Si le contrôleur s'éteint pendant la fixation, celle-ci ne reprend pas après l'activation du contrôleur. La fixation recommence lorsqu'elle est commandée par un périphérique externe.

* Les paramètres de sortie E/S sont activés.

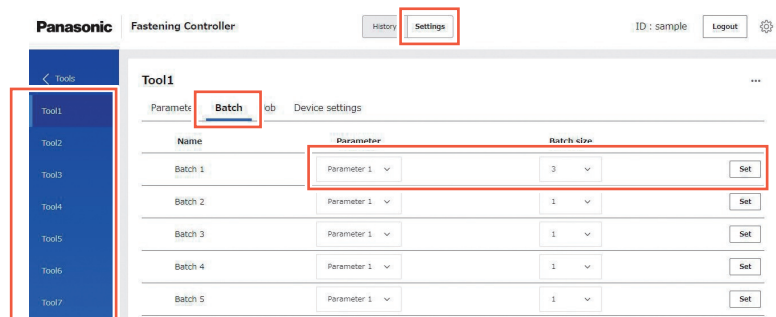
Création (configuration) d'un lot

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ». Dans l'écran « Connected tool », cliquez sur le numéro d'outilsouhaité.

Dans l'écran du numéro d'outil, sélectionnez l'onglet « Batch » et effectuez les réglages. Sélectionnez un paramètre dans le menu déroulant « Parameter » et configurez « Batch size » (quantité à fixer, jusqu'à 99). Cliquez sur [Set] pour définir les valeurs pour « Repeat mode (Basic mode) ».

* Pour changer l'outil, sélectionnez celui souhaité dans la liste d'outils.

* Jusqu'à 5 lots peuvent être enregistrés.



Liste d'outils

Création (configuration) d'une tâche

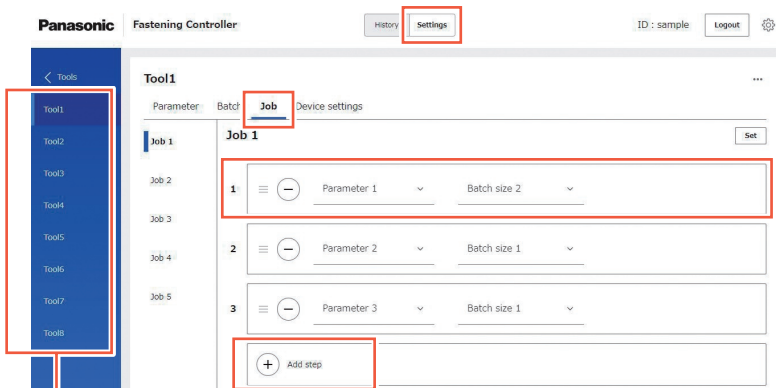
Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ». Dans l'écran « Connected tool », cliquez sur le numéro d'outilsouhaité.

Dans l'écran du numéro d'outil, sélectionnez l'onglet « Job » et effectuez les réglages. Sélectionnez un paramètre dans le menu déroulant « Parameter » et configurez « Batch size » (quantité à fixer, jusqu'à 99). Cliquez sur [Set] pour définir les valeurs pour « Repeat mode (Basic mode) ».

* Jusqu'à 10 étapes peuvent être enregistrées.

* Pour changer l'outil, sélectionnez celui souhaité dans la liste d'outils.

* Jusqu'à 5 tâches peuvent être enregistrées.



Liste d'outils

Création (configuration) d'une séquence

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Sequence settings ».

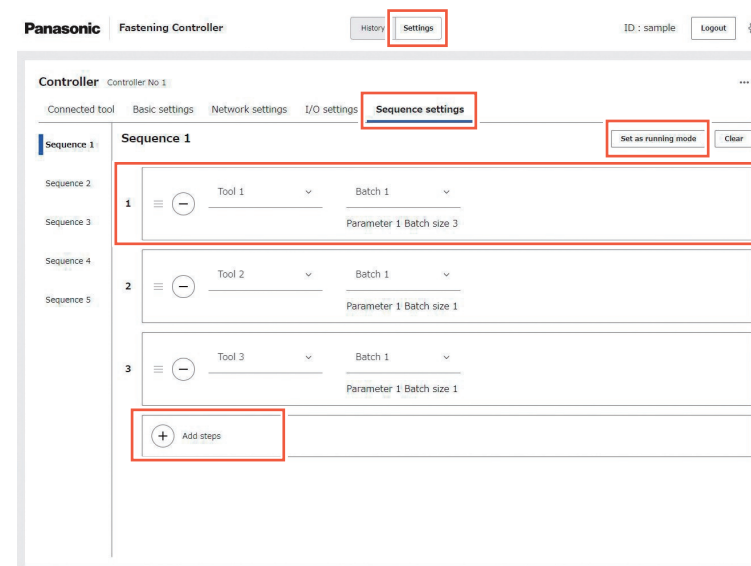
Dans l'écran « Sequence settings », sélectionnez un outil dans le menu déroulant « Tool » et configurez « Batch » ou « Job ».

Cliquez sur [Set as running mode] pour régler les valeurs pour « Repeat mode (Sequence mode) ».

* Jusqu'à 5 séquences peuvent être enregistrées.

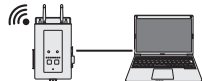
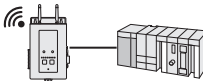
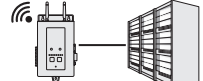
* Jusqu'à 10 étapes peuvent être enregistrées.

* Le même outil peut être utilisé plus d'une fois dans une séquence.



Types d'appareils externes pris en charge

Le contrôleur prend en charge les types de périphériques externes suivants.

Fonction	PC de configuration	API	Système hôte du client
Illustration			
Méthode de communication	Ethernet	E/S	Ethernet
Protocole de communication	http/https	— (Signal MARCHÉ/ARRÊT seulement)	Protocole ouvert
Utilisation principale	- Affichage et stockage de l'historique de fixation - Modification des paramètres	- Signaux de sortie terminée et de défaillance - Changement de l'ordre de fixation	- Exportation de l'historique de fixation - Changement de l'ordre de fixation
Données pouvant être exportées	- Numéros de série d'outils - Temps - Résultats d'exécution et d'échec - Valeurs de couple, angles, délais de fixation - Données de forme d'onde	- Résultats d'exécution et d'échec - Batch/job/sequence terminer - Batch/job/sequence sélectionné - Outil actif	- Numéros de série d'outils - Temps - Résultats d'exécution et d'échec - Valeurs de couple, angles, délais de fixation - Données de forme d'onde
Commutation de l'ordre de fixation	—	Batch/job/sequence sélectionné	Parameter/batch sélectionné
Autre	S'affiche dans un navigateur Web. Microsoft Edge est recommandé.	8 ports chacun pour l'entrée et la sortie	Pour les commandes prises en charge, voir « Commandes compatibles avec Open Protocol ». Se reporter à P61 Les séquences de contrôle doivent être examinées respectivement.

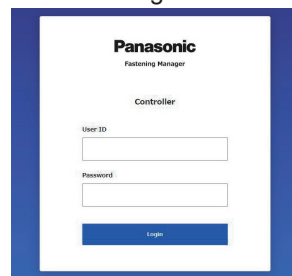
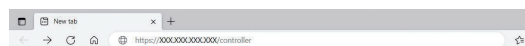
Connexion au PC de configuration dans un emplacement distant

Le PC de configuration avec le certificat installé peut se connecter à distance à des contrôleurs.

Notez qu'un seul accès à la fonction de configuration est accepté à la fois.

Pour vous connecter, saisissez l'adresse IP du contrôleur dans un navigateur Web.

Se reporter à P21



Connexion via E/S

Vous pouvez attribuer des commandes prises en charge à 8 ports d'entrée et 8 ports de sortie comme vous le souhaitez.

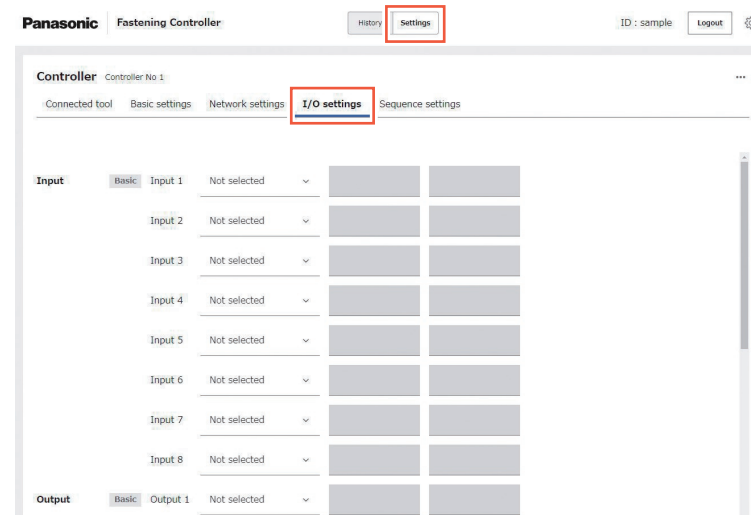
Attribuez-les dans l'écran « I/O settings ».

Vous trouverez ci-dessous les commandes qui peuvent être attribuées aux ports.

Entrée	Commande prise en charge	Sortie	Commande prise en charge
1	Batch (Outil 1 à 5) Job (Outil 1 à 5) Sequence (1 à 5) Batch reset (1 à 8) Reset Suspend tool (1 à 8) Suspend controller	1	OK (Outil 1 à 8) NOK (Outil 1 à 8) Batch complete (Outil 1 à 5) Job complete (Outil 1 à 5) Sequence complete (1 à 5) Tool active (Outil 1 à 8) Batch selected (Outil 1 à 5) Job selected (Outil 1 à 5) Sequence selected (1 à 5)
2		2	
3		3	
4		4	
5		5	
6		6	
7		7	
8		8	

Configuration E/S

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « I/O settings ».



* Il est possible d'attribuer un comportement ou un événement non encore enregistré. (Excepté pour la sélection de tâche et la sélection de séquence)

Commandes attribuées aux ports d'entrée

Vous trouverez ci-dessous les commandes qui peuvent être attribuées aux ports d'entrée. Lorsqu'un signal d'un appareil externe est entré dans l'un des ports, la commande attribuée est exécutée.

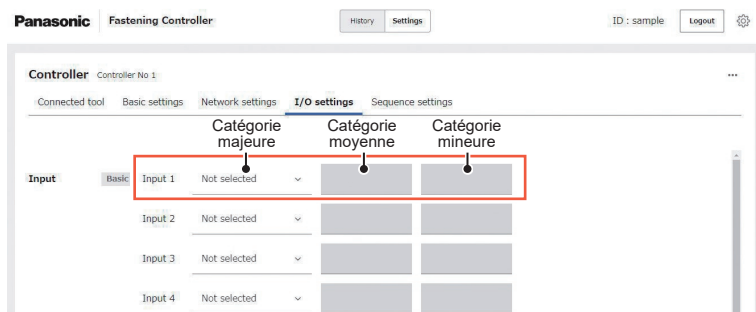
Catégorie majeure (comportement)	Catégorie moyenne (Outil)	Catégorie mineure (N° de lot, etc.)
Batch	Outil 1 à 8	1-5
Job	Outil 1 à 8	1-5
Sequence	—	1-5
Suspend tool*1	Outil 1 à 8	—
Suspend controller*1	—	—
Batch reset	Outil 1 à 8	—
Reset	—	—

*1 Activé uniquement lorsque le signal d'entrée est maintenu.

Remarques lorsque la commande « Suspend tool » ou « Suspend controller » est entrée

- Lorsque la commande « Suspend controller » est activée, aucun ordre de fixation n'est accepté.
 - Pour le numéro d'outil avec la commande « Suspend tool » activée, aucune commande de fixation « Batch » ou « Job » n'est acceptée.
 - Pour les numéros d'outil autres qu'avec la commande « Suspend tool » activée, une commande de fixation « Batch » ou « Job » est acceptée.
 - Lorsque la commande « Suspend tool » est activée, aucune commande de fixation « Sequence » n'est acceptée.
- À ce stade, le processus continue jusqu'à ce qu'il atteigne l'outil avec la commande « Suspend tool » activée.
- « Batch reset » et « Reset » sont traités de la même manière qu'une commande de fixation.

Après avoir sélectionné un comportement dans la catégorie majeure, sélectionnez un outil puis un numéro (par exemple, numéro de lot) si nécessaire.



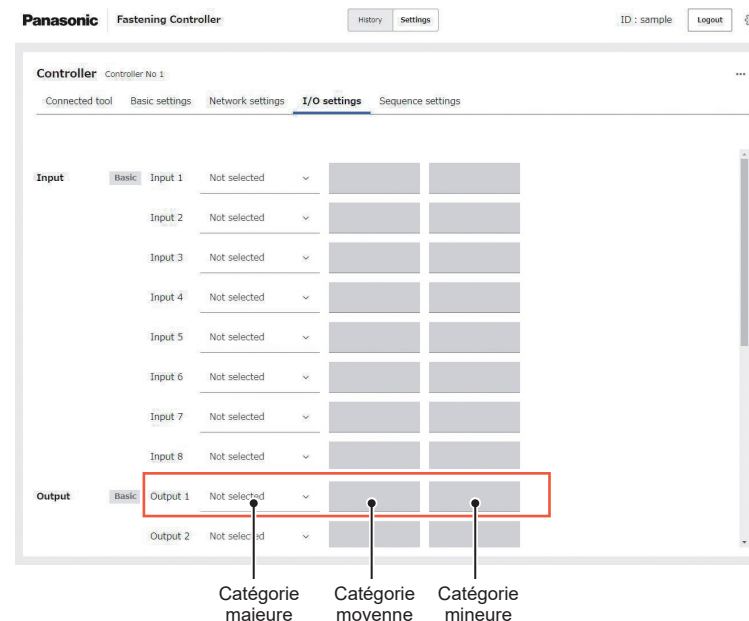
* Aucune action n'est effectuée si un signal non attribué est entré. (Aucune erreur ne se produit)

Commandes attribuées aux ports de sortie

Vous trouverez ci-dessous les commandes qui peuvent être attribuées aux ports de sortie. Lorsqu'un événement pertinent est survenu, le contrôleur émet un signal du port correspondant à un périphérique externe tel que spécifié par la commande attribuée.

Catégorie majeure (Événement)	Catégorie moyenne (Outil)	Catégorie mineure (N° de lot, etc.)
OK	Outil 1 à 8	—
NOK	Outil 1 à 8	—
Batch complete	Outil 1 à 8	1-5
Job complete	Outil 1 à 8	1-5
Sequence complete	—	1-5
Tool active	Outil 1 à 8	—
Batch selected	Outil 1 à 8	1-5
Job selected	Outil 1 à 8	1-5
Sequence selected	—	1-5

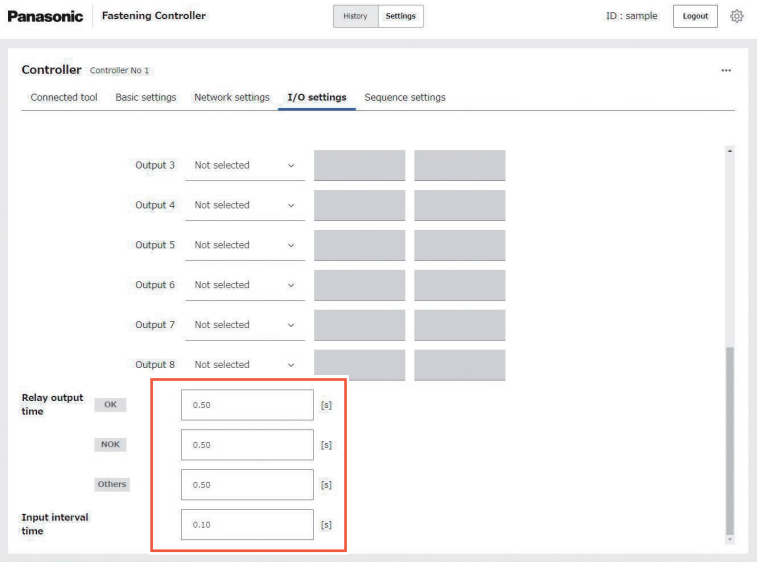
Après avoir sélectionné un événement dans la catégorie majeure, sélectionnez un outil puis un numéro (par exemple, numéro de lot) si nécessaire.



* Si le contrôleur s'éteint pendant l'exécution d'une commande de sortie, le processus ne reprend pas après la mise sous tension du contrôleur. (Veuillez noter que les données d'historique de fixation sont enregistrées.)

Autres paramètres

Vous pouvez définir d'autres paramètres associés à l'E/S comme indiqué ci-dessous.

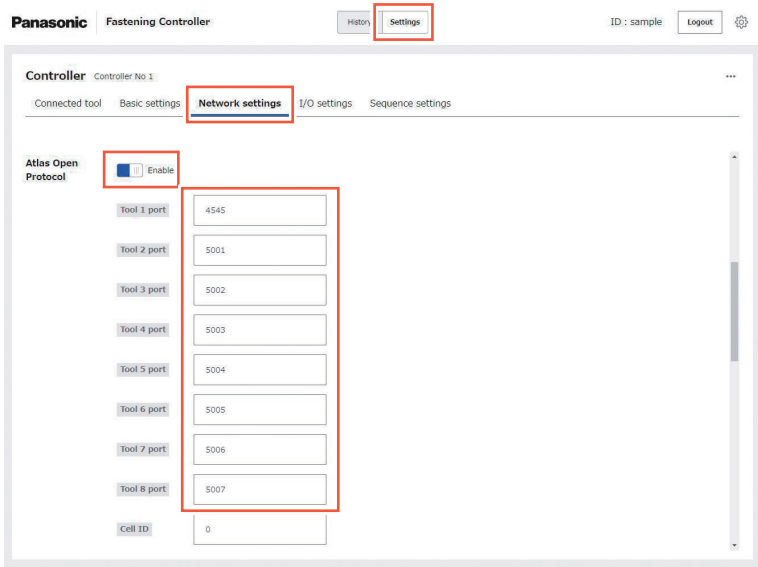


Relay output time (OK)
Sélectionnez le délai d'émission par le relais du signal d'exécution de fixation. [Par défaut] 0.5 s [Plage de réglage] 0.01 s à 10 s
Relay output time (NOK)
Sélectionnez le délai d'émission par le relais du signal d'échec de fixation. [Par défaut] 0.5 s [Plage de réglage] 0.01 s à 10 s
Relay output time (Others)
Sélectionnez le délai d'émission par le relais de tout signal autre que ceux d'exécution et d'échec de fixation. [Par défaut] 0.5 s [Plage de réglage] 0.01 s à 10 s
Input interval time
Sélectionnez le délai pendant lequel les signaux d'entrée successifs ne sont pas comptés (acceptés). Configurez de manière à éviter un double comptage causé par le bruit, etc. [Par défaut] 0.1 s [Plage de réglage] 0.01 s à 10 s

Connexion via la communication Open Protocol

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Network settings ».

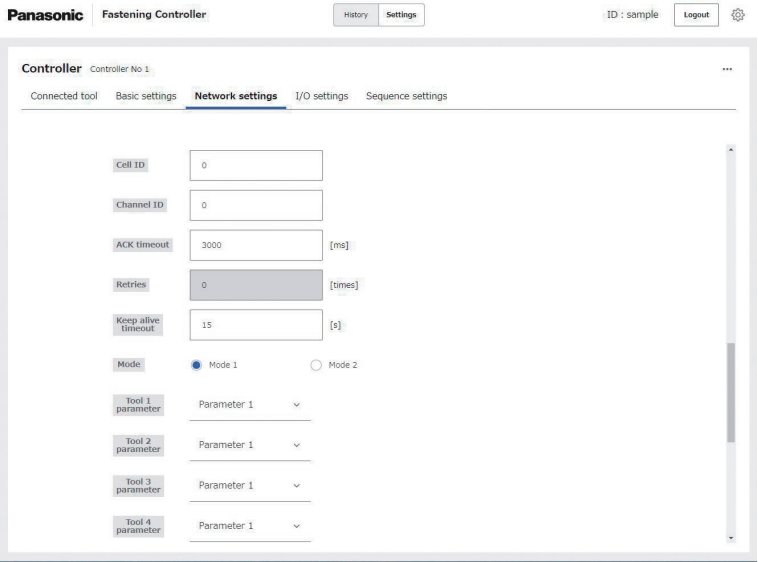
Activez « Atlas Open Protocol ».
Configurez les numéros de port des outils utilisés respectivement.



Tool port
Attribuez un numéro de port pour la communication Open Protocol à chaque outil. [Par défaut] Outil 1 - 4545, Outil 2 à 8 - 5001 à 5007 [Plage de réglage] Outil 1 à 8 - 1024 à 49151

Autres paramètres

Configurez d’autres éléments si nécessaire.

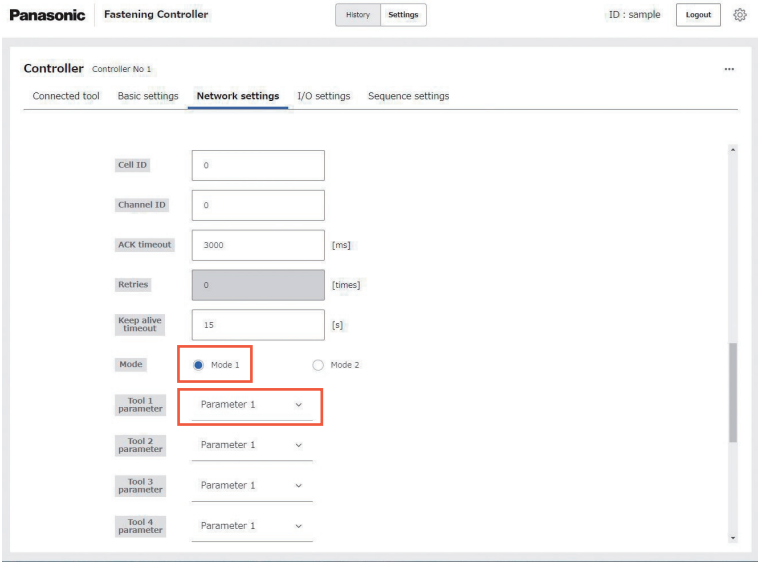


Cell ID
Définissez l'ID de la cellule. [Par défaut] 0 [Plage de réglage] 0 à 9999
Channel ID
Définissez l'ID du canal. [Par défaut] 0 [Plage de réglage] 0 à 99
ACK timeout
Définissez le délai d'attente d'une réponse à un message de requête émise par le contrôleur. [Par défaut] 3000 ms [Plage de réglage] 100 ms à 30000 ms
Retries
Définissez le nombre d'envois répétés d'un message de requête par le contrôleur. [Par défaut] 0 times [Plage de réglage] Non sélectionnable (Fixe)

Keep alive timeout
Définissez le délai pour déterminer l'occurrence de la déconnexion après la dernière communication avec un système hôte. [Par défaut] 15 s [Plage de réglage] 1 s à 60 s
Mode
Configurez le mode de fonctionnement. Mode 1 : Fixation inconditionnelle avec paramètres pré-enregistrés Mode 2 : Fixation avec paramètres commandés par un système hôte [Par défaut] Mode 1 [Plage de réglage] Mode 1/Mode 2

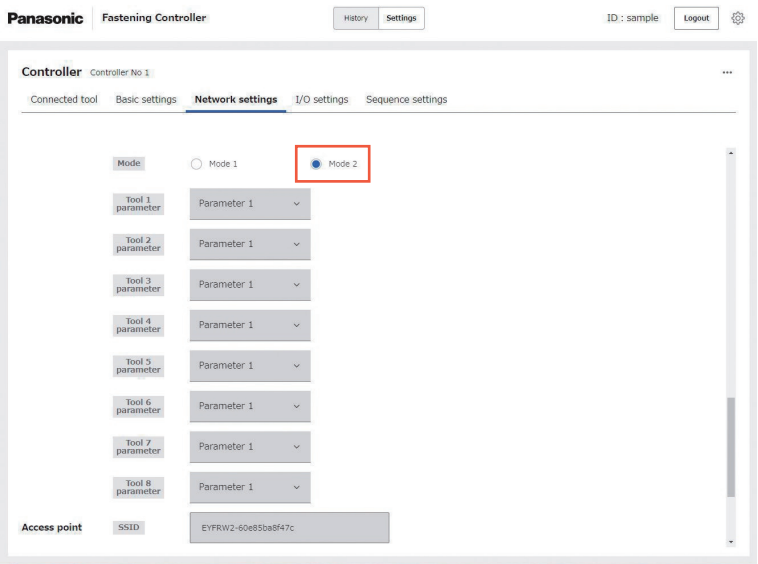
Attribution des paramètres de fixation (Mode 1)

Le « Mode 1 » (sans paramètres commandés) nécessite de pré-enregistrer les paramètres de fixation sur les outils.
Sélectionnez un paramètre dans le menu déroulant comme indiqué ci-dessous.



Attribution des paramètres de fixation (Mode 2)

La fixation peut être commandée avec une commande MID 0018 par un périphérique externe.
Vous pouvez spécifier « Parameter » ou « Batch » dans une commande de fixation.



Pour spécifier « Parameter » dans une commande de fixation
Mettez « 0 » dans le chiffre des centaines de l'identifiant.
Les chiffres des dizaines et des unités indiquent un numéro de paramètre.
Exemple : ID du paramètre 1 : 001
ID du paramètre 5 : 005

Pour spécifier « Batch » dans une commande de fixation
Mettez « 1 » dans le chiffre des centaines de l'identifiant.
Les chiffres des dizaines et des unités indiquent un numéro de lot.
Exemple : ID du lot 1 : 101
ID du lot 5 : 105

* « Job » et « Sequence » ne sont pas pris en charge.

Commandes compatibles avec Open Protocol
Le contrôleur prend en charge les commandes suivantes.
Pour plus de détails sur les commandes, voir la Spécification Open Protocol.

MID 0001 Application communication start
La révision 1 est prise en charge. [Contenu] Début de la communication
MID 0002 Application communication start acknowledge
La révision 1 est prise en charge. [Contenu] Reconnaissance de la communication
MID 0004 Application command error
La révision 1 est prise en charge. [Contenu] Erreur de commande
MID 0005 Application command accepted
La révision 1 est prise en charge. [Contenu] Acceptation de la commande
MID 0018 Select parameter set, Dynamic Job included
La révision 1 est prise en charge. Pour savoir comment attribuer, voir « Attribution des paramètres de fixation (Mode 2) ». Se reporter à P60 [Contenu] Ordre de configuration des paramètres
MID 0042 Disable tool
La révision 1 est prise en charge. [Contenu] Outil désactivé
MID 0043 Enable tool
La révision 1 est prise en charge. [Contenu] Outil activé
MID 0050 Vehicle ID number download request
La révision 1 est prise en charge. [Contenu] Demande d'acquisition de l'ID du véhicule

MID 0060 Last tightening result data subscribe

Les révisions 1 et 2 sont prises en charge.

[Contenu] Enregistrement final des données de résultat de fixation

MID 0061 Last tightening result data

Les révisions 1 et 2 sont prises en charge.

[Contenu] Téléchargement du résultat de fixation

MID 0062 Last tightening result data acknowledge

Les révisions 1 et 2 sont prises en charge.

[Contenu] Accusé de réception du téléchargement de résultat de fixation

MID 9999 Keep alive message

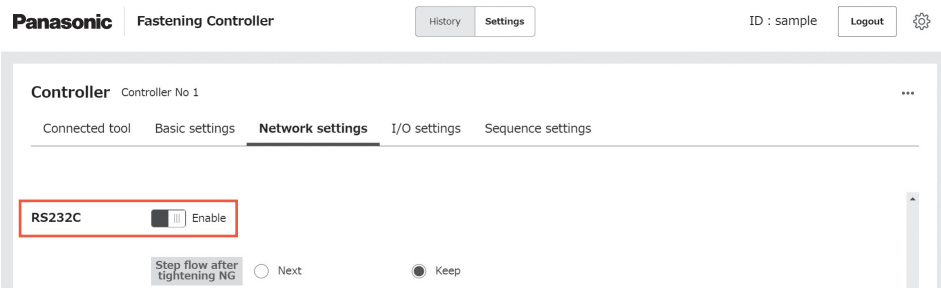
La révision 1 est prise en charge.

[Contenu] Vérification de disponibilité

Connexion à des périphériques externes avec les spécifications spécifiques à TOYOTA MOTOR CORPORATION

Contrôlez à partir de périphériques externes est prise en charge.

Activez « RS232C » à partir de l'onglet « Network settings » dans [Settings].



RS232C

Ceci est un réglage spécifique à TOYOTA MOTOR CORPORATION. Le contrôle à partir de périphériques externes est possible.

[Par défaut] Disable

[Plage de réglage] Disable / Enable

Step flow after tightening NG

Ce paramètre détermine si vous pouvez passer au serrage suivant en cas de résultat de serrage NG.

[Par défaut] Keep

[Plage de réglage] Next (Le serrage suivant peut être effectué.) / Keep (Le serrage suivant ne peut pas être effectué.)

Ceci est pris en charge uniquement par la version de micrologiciel 2.03.00 ou ultérieure. Pour savoir comment mettre à jour le micrologiciel, consultez « Mise à jour du micrologiciel ». **Se reporter à P87**

Configuration

Vous pouvez connecter un lecteur de codes-barres disponible dans le commerce pour enregistrer les informations lues tout en les reliant aux données d'historique des fixations. Cela peut être utilisé pour lier des produits à l'historique des fixations.

Connexion	Mode de communication	Remarque
Lecteur de code-barres Récepteur sans fil Contrôleur Panasonic	Sans fil 2,4 GHz ou Bluetooth	Lit les informations sur le produit (telles que les numéros de série de fabrication) et les reflète dans les données d'historique.

N'utilisez de lecteurs de codes-barres câblés de type USB.

Appareils applicables

Les lecteurs de codes-barres suivants sont compatibles avec le contrôleur.

Élément	Description	
Interface de communication	USB-HID	
Disposition du clavier	U.S.A.	
Caractères pris en charge	Caractères alphanumériques, symboles	
	Codes pris en charge	Description du code (informations anticipées)
	Nombres	0-9
	Caractères alphabétiques	A-Z, a-z
	Symboles	!"#\$%&'()*+,-./:;<=>?@[¥]^_`{ }~
Codes 1D acceptables	JAN, EAN, UPC, CODE39, ITF	
Codes 2D acceptables	Code QR Modèle 1/2, Micro QR	
Nombre acceptable de caractères	100 caractères (maximum)	

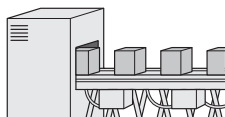
Modèles recommandés

Bluetooth: Honeywell Xenon XP 1952g, ZEBRA DS2278

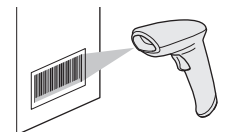
Processus de travail

En suivant la procédure ci-dessous, vous pouvez enregistrer les informations sur le produit tout en les liant aux données d'historique des fixations.

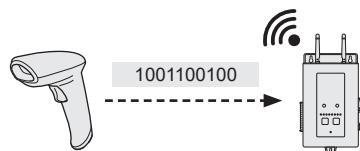
1 Les produits circulent par la ligne.



2 Lisez les informations sur le produit avec un lecteur de codes-barres.



3 Les informations lues par le lecteur de codes-barres sont envoyées au contrôleur.



4 Un ordre de fixation est envoyé du contrôleur aux outils.

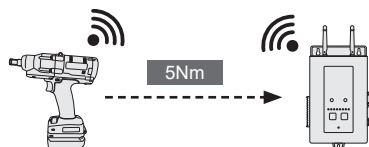
* Cette étape peut précéder ou suivre l'étape 3.



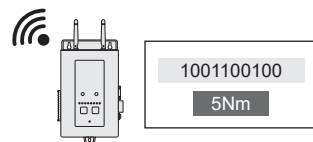
5 Effectuez le travail de fixation à l'aide des outils.



6 Le résultat du travail de fixation (comme le couple) est envoyé au contrôleur.



7 Les informations lues conservées dans le contrôleur et le résultat du travail de fixation sont liés les uns aux autres et enregistrés dans la mémoire.



8 Répétez les étapes 5 à 7 jusqu'à ce que les informations de lecture du code-barres soient mises à jour (ou que le travail soit terminé).

Procédure de réglage

La procédure de réglage varie en fonction des spécifications du lecteur de codes-barres.

■ Méthode sans fil 2,4 GHz (avec récepteur sans fil dédié)

Connectez-le en suivant la procédure ci-dessous.

(Les étapes 2 à 3 ne sont pas nécessaires.)

■ Méthode Bluetooth (sans récepteur sans fil dédié)

Préparez séparément un récepteur sans fil Bluetooth et connectez-le en suivant la procédure ci-dessous.

Récepteurs sans fil Bluetooth disponibles

- Version Bluetooth : Compatible avec Ver4.0
- Compatible avec les systèmes d'exploitation Linux (uniquement ceux qui ne nécessitent pas de pilotes dédiés)

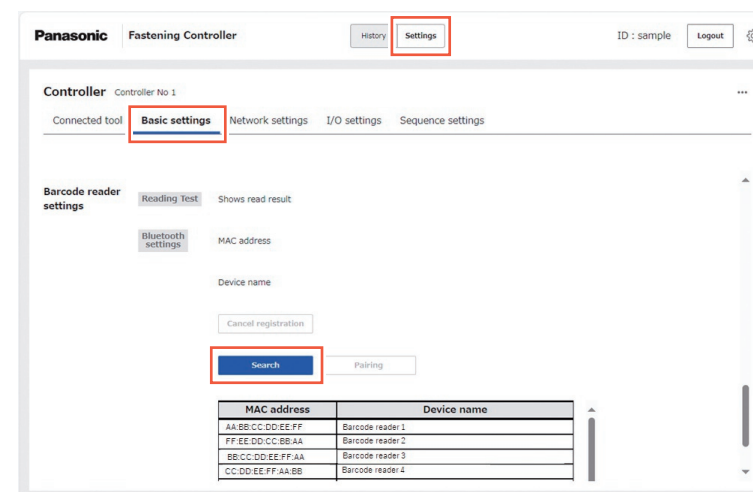
Modèles recommandés

EDIMAX BT-8500

1 Connectez le récepteur sans fil du lecteur de codes-barres au port USB-A du contrôleur.

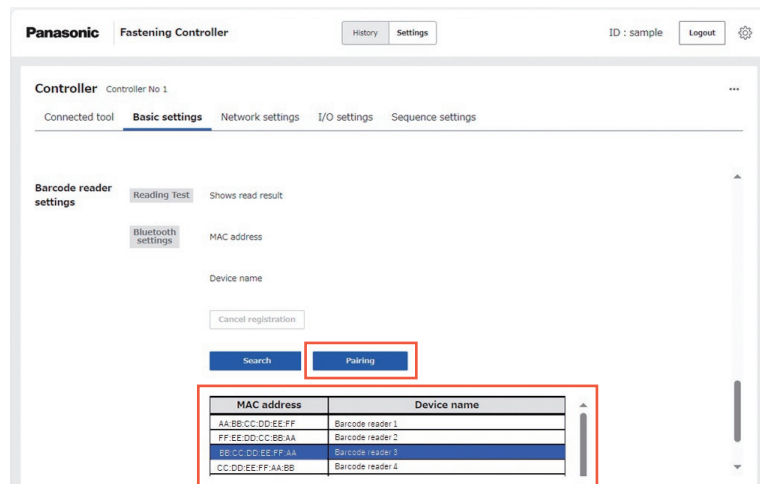
2 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut, sélectionnez l'onglet « Basic settings » et cliquez sur « Search » à partir de « Barcode reader settings ».

* Mettez également le lecteur de codes-barres en mode appairage conformément à ses spécifications.



3 Sélectionnez le lecteur de codes-barres à connecter dans la liste des noms de périphériques et appuyez sur « Pairing ».

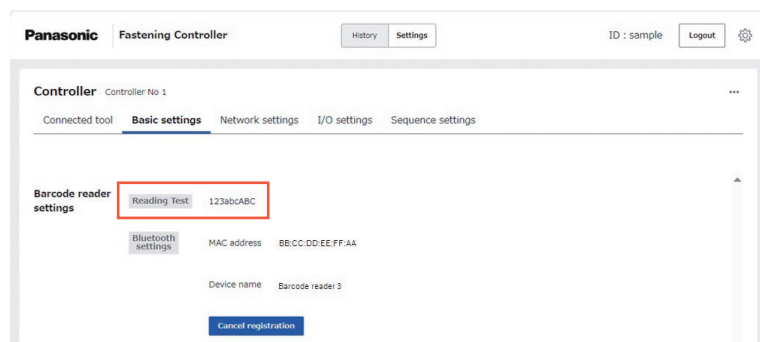
Il sera apparié au lecteur de codes-barres.



Liste des noms d'appareils

- L'état de la recherche est conservé pendant environ 10 secondes.
- Une fois l'appairage enregistré, il est automatiquement reconnecté la deuxième fois et les fois suivantes.
- * Selon les spécifications du lecteur de codes-barres, un nouvel appairage peut être nécessaire.
- * Si l'appairage échoue, annulez l'appairage sur le contrôleur puis réessayez.

4 Lisez les informations du code-barres et vérifiez que les informations s'affichent correctement dans « Reading Test ».

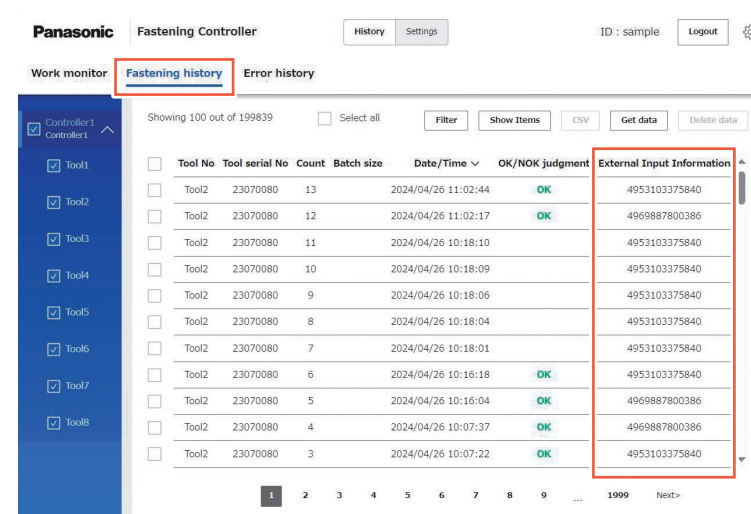


5 Effectuez le travail de fixation avec le lecteur de codes-barres après avoir lu les informations.

Les données lues seront affichées dans « External Input Information » des données d'historique des fixations.

Remarques pendant le fonctionnement

- Le « Témoin de fixation OK » clignote lors de la réception de la lecture du code-barres.
- Pendant le fonctionnement, vérifiez que l'état de réception de lecture de code-barres est actif avant de travailler.



Remarques sur les valeurs de lecture

Les valeurs lues sont :

- Représentées dans les résultats de travail de tous les outils enregistrés par le contrôleur après la lecture.
- Non conservées lorsque le contrôleur est désactivé.
- Remplacé par des informations nouvellement lues.
- Conservées jusqu'à ce que les conditions suivantes soient remplies.

Running mode	Conditions de conservation des données
Free mode	Les données sont conservées jusqu'à leur mise à jour.
Repeat mode (Basic mode)	Jusqu'à la fin du « Batch »/« Job ». Ou les données sont conservées jusqu'à leur mise à jour.
Repeat mode (Sequence mode)	Jusqu'à la fin de la « Sequence ». Ou les données sont conservées jusqu'à leur mise à jour.
External control mode * Commande via Open Protocol	Les informations VIN sont prioritaires et ne sont pas ajoutées.
External control mode * Contrôle via E/S	Jusqu'à la fin du « Batch »/« Job »/« Sequence ». Ou les données sont conservées jusqu'à leur mise à jour.

- Selon les spécifications du lecteur de codes-barres que vous utilisez, des paramètres détaillés peuvent être nécessaires pour la connexion avec le contrôleur. Avant d'utiliser cette fonction, lisez attentivement les Instructions d'utilisation et les paramètres de votre appareil.
- Si les données sont lues en continu dans un délai de 0,5 seconde, les informations seront consolidées ; par conséquent, espacez les lectures.
- Un seul lecteur de codes-barres peut être utilisé simultanément avec le contrôleur. La connexion de plusieurs lecteurs peut entraîner un dysfonctionnement.

Licences

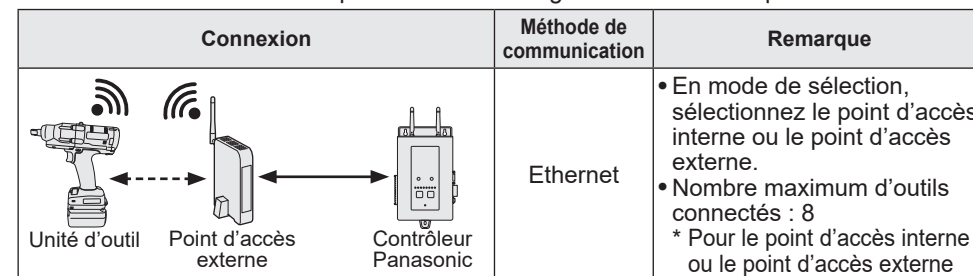
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Configuration

Le contrôleur peut se connecter aux outils via la communication sans fil à l'aide d'un point d'accès externe au lieu du point d'accès intégré.
Le contrôleur peut contrôler les outils quelque soit l'endroit où il est installé.
Connectez le point d'accès et le contrôleur au réseau local câblé.

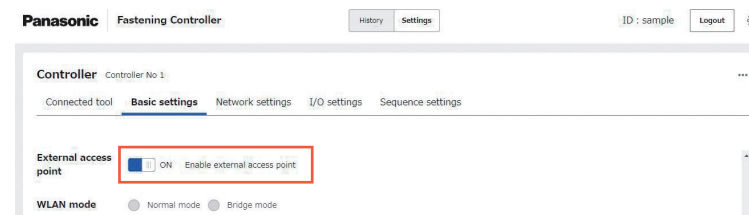
* La couverture sans fil et les performances changent en fonction du point d'accès utilisé.



Procédure de réglage

- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut, sélectionnez l'onglet « Basic settings » et réglez « External access point » sur « ON ».

* « WLAN mode » est désactivé lorsque « External access point » est activé.



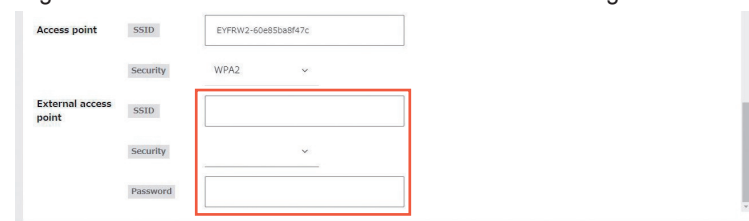
- 2 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Network settings ». Dans « External access point », configurez « SSID », « Security » et « Password ».

* Vous ne pouvez enregistrer qu'un seul SSID dans le contrôleur. (Vous ne pouvez pas enregistrer différents SSID pour différents outils)

* Voir les Instructions d'utilisation de votre point d'accès externe.

* Effectuez ce réglage avant de commencer l'enregistrement d'appariement avec les outils.

* Configurez l'adresse IP de l'outil avant de commencer l'enregistrement d'appariement.

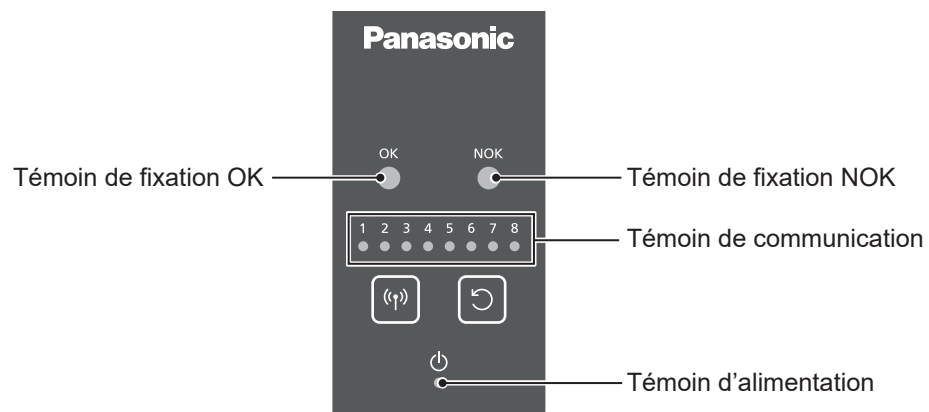


Témoins lumineux et un signal sonore

Les témoins lumineux et l'avertisseur sonore indiquent l'état du contrôleur.

⚠ MISE EN GARDE

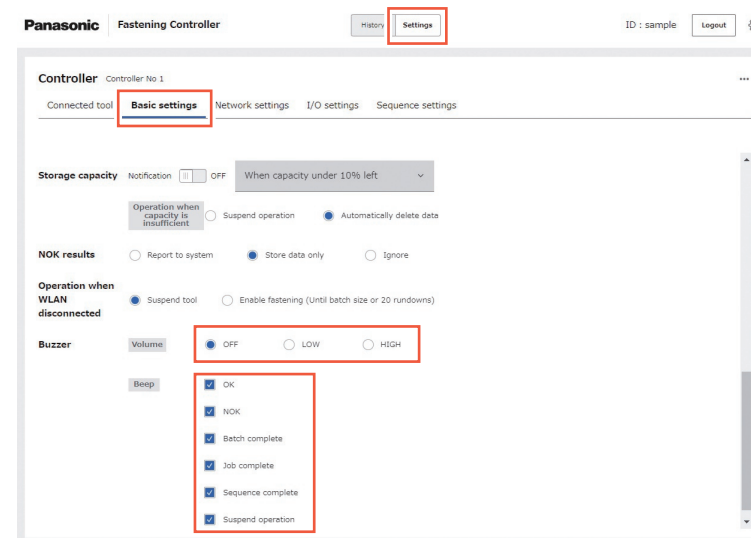
N'éteignez pas l'interrupteur d'alimentation lorsque le témoin clignote pendant le démarrage.
Une initialisation peut être nécessaire.



État	Témoin lumineux	Alarme sonore
Mise sous tension	Témoin d'alimentation (jaune) Reste allumé	—
Un outil à appairer sélectionné	Témoin de communication (bleu) Clignote lentement	—
Appariement établi	Témoin de communication (bleu) Clignote rapidement	—
Appariement terminé	Témoin de communication (bleu) Reste allumé	Un bip court ■
Appariement non établi	Témoin de communication (bleu) Clignote très lentement	—
Appariement déconnecté	Témoin de communication (bleu) Éteint	—
Exécution de la fixation	Témoin OK (vert) Reste allumé	Un bip court ■
Échec de la fixation	Témoin NOK (rouge) Reste allumé	Un bip long ■■
Exécution de Batch/job	Témoin OK (vert) Clignote deux fois	Deux bips courts ■■
Séquence terminée	Témoin OK (vert) Clignote trois fois	Trois bips courts ■■■
Erreur	Témoin d'alimentation (jaune) Clignote	Deux bips longs ■■ ■■

Configuration du signal sonore

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Basic settings ».
Dans « Buzzer », réglez « Volume » et « Beep ».

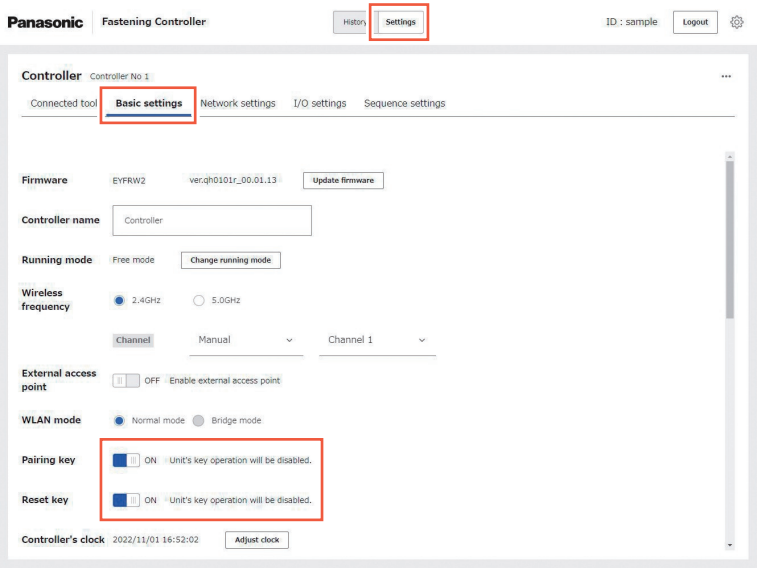


Élément	Description
Volume	3 niveaux (OFF / LOW / HIGH) (LOW : 75 dB, HIGH : 85 dB)
Beep	Sélectionné sur le PC de configuration (OK / NOK / Batch complete / Job complete / Sequence complete / Suspend operation)

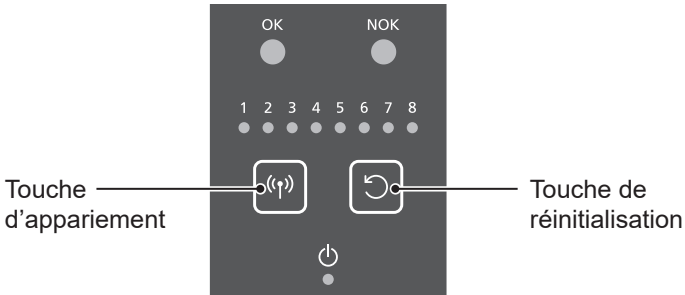
RÉGLAGE DES TOUCHES DE COMMANDE

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Basic settings ».

Dans « Pairing key » et « Reset key », vous pouvez désactiver la touche d'appariement et la touche de réinitialisation sur le boîtier de commande.



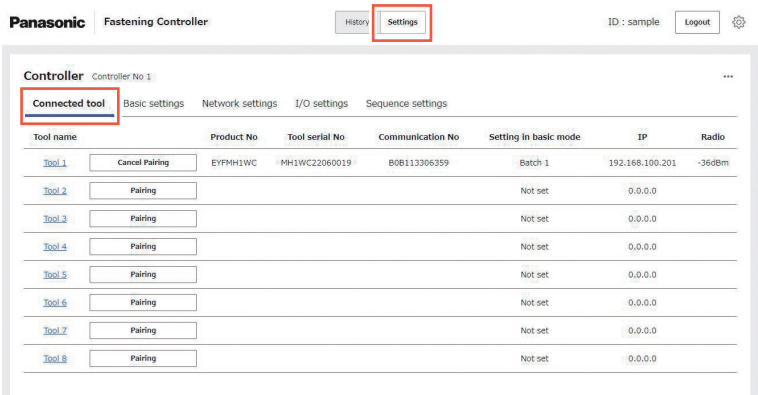
Pairing key
Activez ou désactivez la touche d'appariement sur le boîtier de commande. [Par défaut] ON [Plage de réglage] ON (activé)/OFF (désactivé)
Reset key
Activez ou désactivez la touche de réinitialisation sur le boîtier de commande. [Par défaut] ON [Plage de réglage] ON (activé)/OFF (désactivé)



VÉRIFICATION DES INFORMATIONS DES OUTILS CONNECTÉS

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

Vous pouvez voir les informations et l'état des outils connectés au contrôleur.



Les éléments ci-dessous sont affichés.

Tool name
Le numéro d'outil enregistré (1 à 8) s'affiche.
Tool serial No
Vous pouvez régler et afficher l'identification de l'unité de l'outil. Par défaut : ID de modèle à 5 chiffres + numéro de série à 8 chiffres (année de fabrication à 2 chiffres + mois à 2 chiffres + lot de production à 4 chiffres)
Product No
Le numéro de produit d'outil s'affiche.
Communication No
L'identification de l'unité (adresse MAC) de la pièce de communication de l'outil est affichée.
Setting in basic mode
Un comportement lorsque le Running mode réglé sur « Repeat mode (Basic mode) » est affiché.
IP
L'adresse IP de l'outil est affichée.
Radio
La puissance d'un signal radio (RSSI) reçu de l'outil est affichée. * La puissance de la dernière communication est affichée. * Elle ne peut pas être mesurée et « 0dBm » apparaît lorsqu'un point d'accès externe est utilisé.

MONITEUR DE TRAVAIL

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Work monitor ».

Les derniers journaux de l'historique de fixation par outil sont affichés. Vous pouvez les utiliser pour travailler en vous référant aux résultats du travail.

* Plusieurs PC de configuration peuvent les afficher en même temps. (Jusqu'à 8 accès. Les accès multiples depuis le même compte sont acceptés.)

* Pour se connecter avec plus d'un compte, l'utilisation de différents PC est recommandée.

* Pour utiliser plusieurs comptes sur le même ordinateur, il est recommandé d'utiliser des navigateurs Web différents.

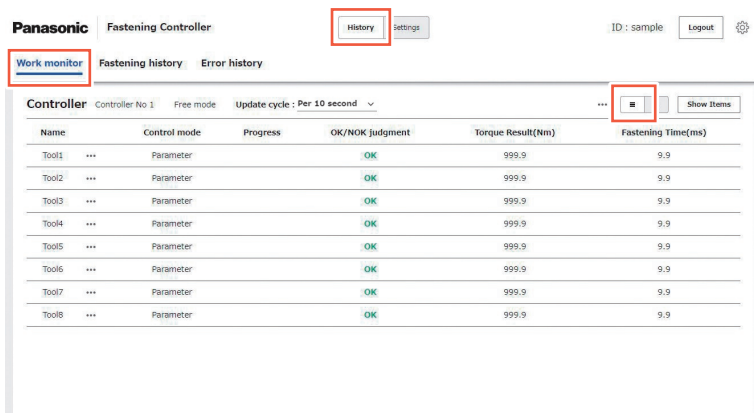
* Un seul accès à la fonction de configuration est accepté à la fois.

Changer le format d'affichage

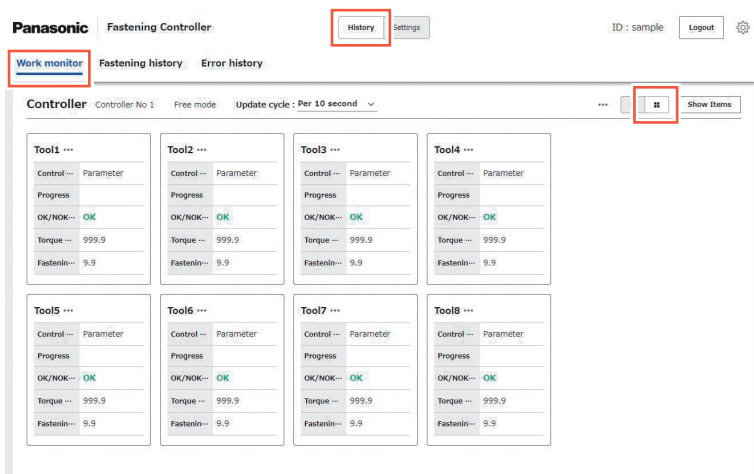
Vous pouvez choisir entre « Affichage de liste » et « Affichage de grille ».

Utilisez l'icône de vue en haut à droite de l'écran.

Affichage de liste

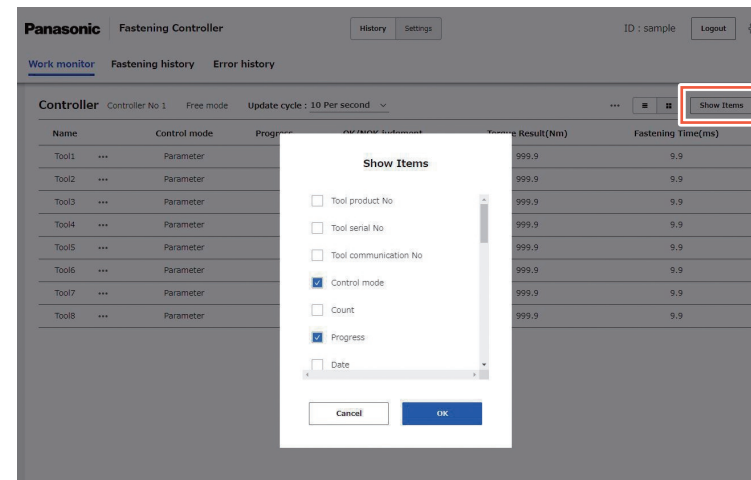


Affichage de grille



Sélection des éléments à afficher

Sélectionnez les éléments à afficher à l'aide de « Show Items ».



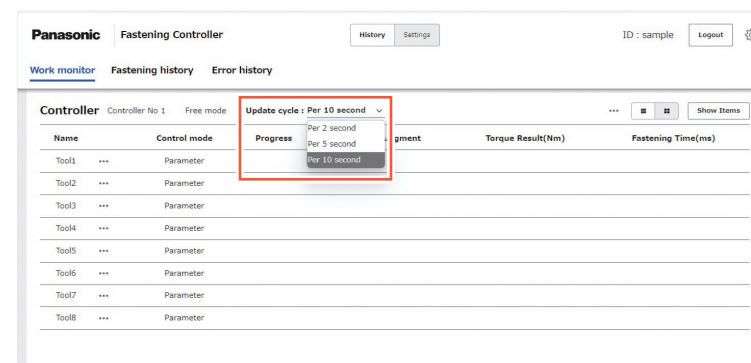
* Dans « Affichage de liste », vous pouvez faire défiler vers le bas et sélectionner de nombreux éléments à afficher.

* Dans « Affichage de grille », vous pouvez afficher jusqu'à 5 éléments.

Sélection du cycle d'actualisation d'affichage

Vous pouvez configurer la mise à jour automatique de l'affichage.

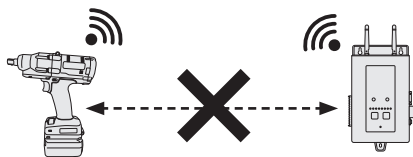
Sélectionnez le cycle de mise à jour entre « per 2 second », « per 5 second », et « per 10 second » comme ci-dessous.



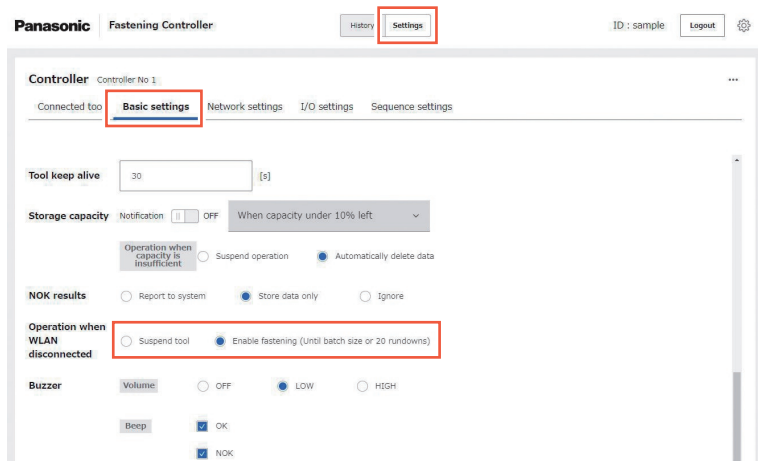
* Si un grand nombre d'outils ou de PC de configuration sont connectés, le cycle de mise à jour de « per 10 second » est recommandé. (Cela peut prendre un certain temps pour traiter les données).

COMPORTEMENT DE L'OUTIL AVEC LA COMMUNICATION SANS FIL DÉCONNECTÉE

Vous pouvez continuer la fixation avec les mêmes paramètres en cas d'interruption temporaire de la communication sans fil entre un outil et le contrôleur. Les résultats du travail des outils lors de la déconnexion de la communication sans fil sont notifiés au contrôleur « Lorsque l'outil est reconnecté » ou « Lors de la première fixation après le rétablissement de la connexion de l'outil ».



Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Basic settings ». Si vous configurez « Operation when WLAN disconnected » sur « Suspend tool », la fixation en cours se termine après l'interruption, mais aucune autre fixation n'est effectuée. Si vous réglez « Enable fastening », aucune autre fixation n'est effectuée une fois que la quantité fixée a atteint la limite supérieure.



Avec « Enable fastening », les quantités limites supérieures par mode sont les suivantes.

Mode		Comportement
Free mode		Continue la fixation jusqu'à 20 vis
Repeat mode	Basic mode	Continue la fixation jusqu'à la fin du lot ou jusqu'à 20 vis
	Sequence mode	Continue la fixation jusqu'à la fin du lot ou jusqu'à 20 vis * Les outils autres que ceux concernés continuent de fonctionner normalement.
External control mode		Continue la fixation jusqu'à la fin du lot ou jusqu'à 20 vis

RÉINITIALISATION DU COMPTAGE PENDANT LE FONCTIONNEMENT

Pour modifier les réglages, arrêtez la commande de fixation avec le contrôleur s'il est en cours de fonctionnement. Une boîte de dialogue de confirmation apparaît lorsque vous appliquez la modification.

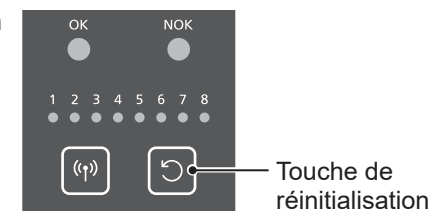
Vous pouvez réinitialiser les quantités comptées avec « Utilisation de la touche sur l'unité » ou « Réglage dans l'écran de configuration ».

* Ceci ne s'applique pas au « Free mode ».

Utilisation de la touche sur l'unité

Maintenez enfoncée la touche de réinitialisation sur le contrôleur pendant 3 secondes ou plus.

* Les quantités de tous les outils sont réinitialisées.

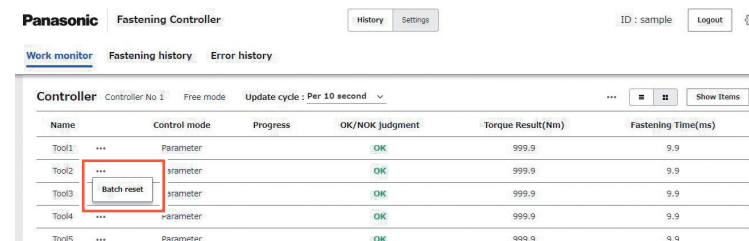


Réglage dans l'écran de configuration

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Work monitor ».

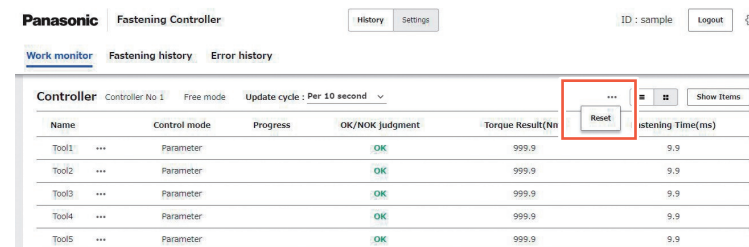
Pour réinitialiser les quantités par outil

Dans l'écran « Work monitor », cliquez sur ... (touche d'option outil) puis sur [Batch reset] du numéro d'outil souhaité.



Pour réinitialiser les quantités de tous les outils collectivement

Dans l'écran « Work monitor », cliquez sur ... (touche d'option contrôleur), puis sur [Reset] en haut à droite.



* En Sequence mode, les quantités sont réinitialisées jusqu'au premier outil.

Affichage des données d'historique de fixation

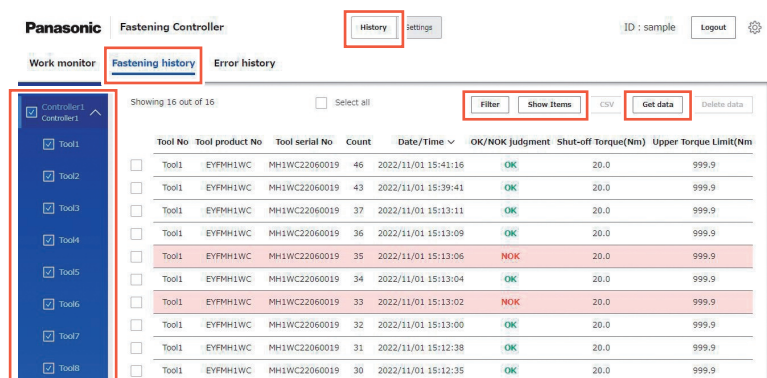
Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Fastening history ».

Vous pouvez visualiser les données d'historique de fixation envoyées par les outils au contrôleur.

Pour afficher les données, sélectionnez le contrôleur souhaité et les outils dans la liste d'outils sur la gauche et cliquez sur [Get data] en haut à droite.

Les journaux d'historique de fixation s'affichent de la plus récente à la plus ancienne.

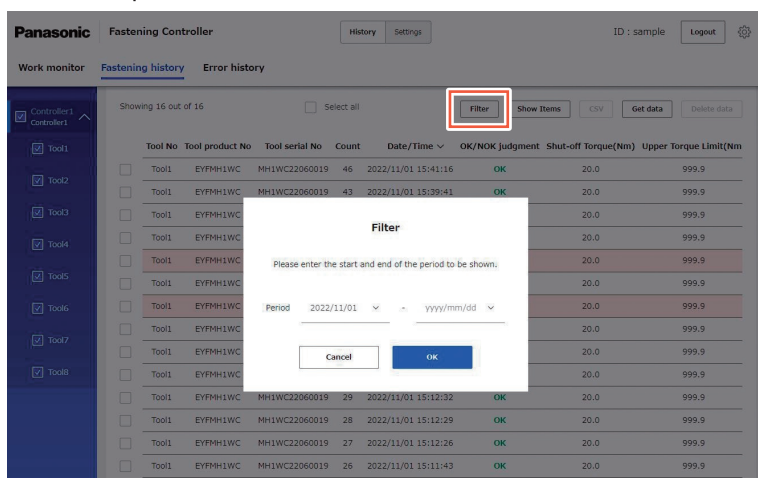
* Pour le contenu des éléments de l'historique de fixation, voir les Instructions d'utilisation de l'outil.



Liste d'outils

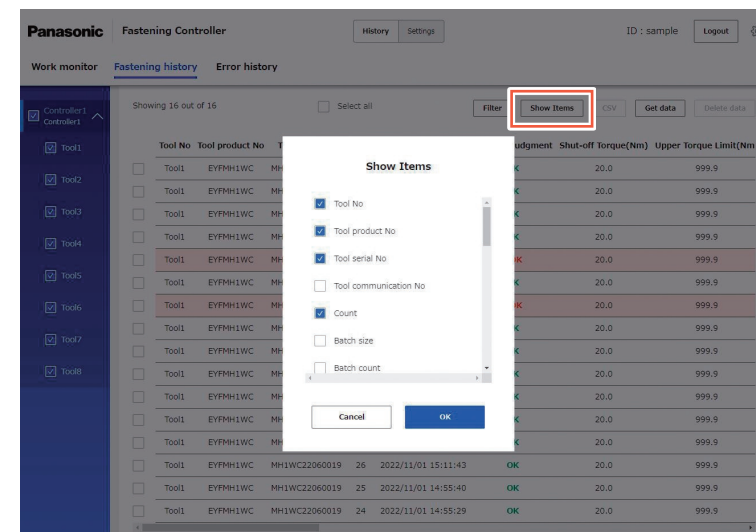
Extraction des journaux de l'historique de fixation par période

Cliquez sur [Filter] et spécifiez la période de temps pour réduire l'affichage des journaux d'historique de fixation.



Configuration des éléments à afficher

Pour modifier les éléments affichés, cliquez sur [Show Items] et sélectionnez les éléments souhaités.



Capacité des données d'historique de fixation

Le contrôleur peut stocker un maximum d'environ 200,000 journaux d'historique de fixation (y compris les données de forme d'onde).

Il suspend le fonctionnement ou supprime automatiquement les journaux (par écrasement) s'il reçoit plus de journaux.

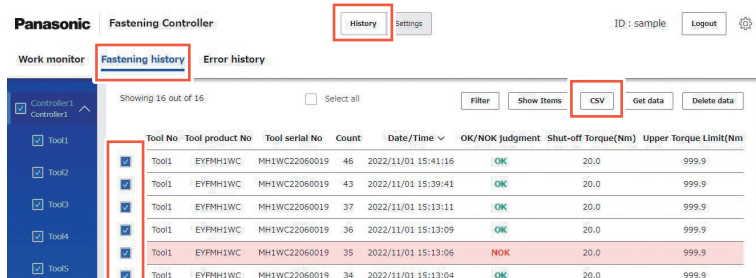
Il est recommandé d'exporter périodiquement les journaux au format CSV si nécessaire en vous référant au guide ci-dessous.

Temps estimé pour atteindre la capacité de stockage totale

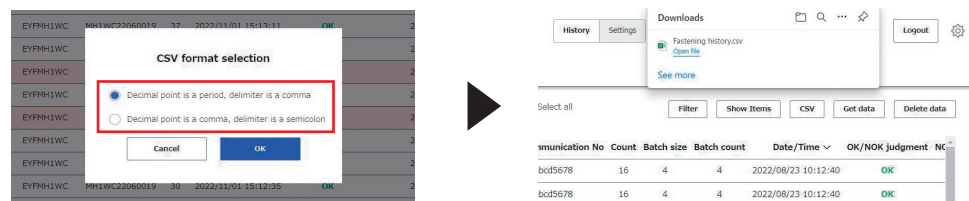
	Quantité par jour par outil		
Nombre d'outils	1,000	3,000	5,000
2	Environ 100 jours	Environ 33 jours	Environ 20 jours
4	Environ 50 jours	Environ 16 jours	Environ 10 jours
8	Environ 25 jours	Environ 8 jours	Environ 5 jours

Exportation des données d'historique de fixation au format CSV

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Fastening history ».
Sélectionnez les journaux souhaités et cliquez sur [CSV].
Les journaux d'historique de fixation sont exportés au format CSV.

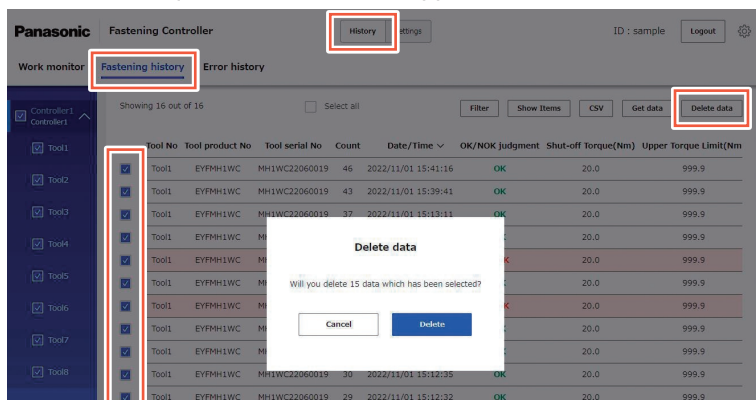


Vous pouvez choisir entre « Decimal point is a period, delimiter is a comma » et « Decimal point is a comma, delimiter is a semicolon ».



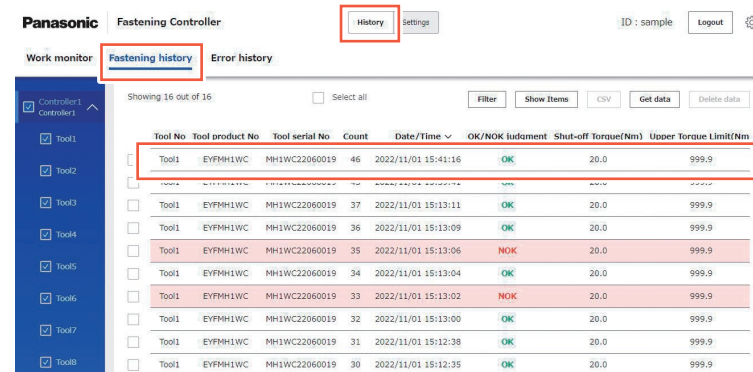
Suppression des données d'historique de fixation

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Fastening history ».
Sélectionnez les journaux souhaités et cliquez sur [Delete data].
Les journaux de l'historique de fixation sont supprimés.

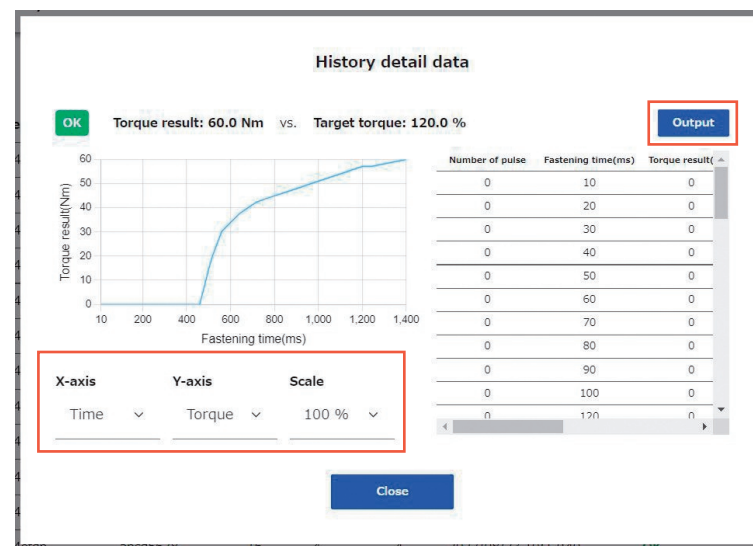


Affichage des données de forme d'onde

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Fastening history ».
Si vous avez activé pour enregistrer les données de forme d'onde, vous pouvez faire un double-clic sur la ligne du journal d'historique de fixation souhaité pour afficher une fenêtre contextuelle de données de forme d'onde.



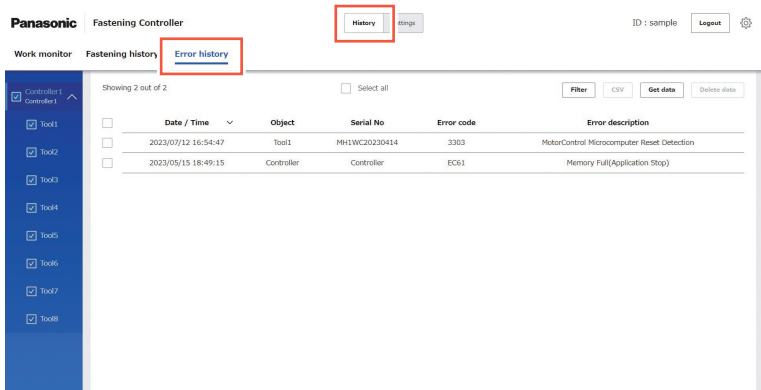
Vous pouvez ajuster l'affichage en sélectionnant « X-axis », « Y-axis », et « Scale ».
Cliquez sur [Output] pour exporter les données au format CSV.



* Veuillez à configurer « Graph sending timing » dans « Device settings » sur « After every fastening ».

Affichage de l'historique des erreurs

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [History] en haut et sélectionnez l'onglet « Error history ».
L'historique des erreurs qui se sont produites s'affiche.



Les éléments ci-dessous sont affichés.

* Pour le contenu de l'erreur, voir « CODE D'ERREUR ». **Se reporter à P96**

Date / Time
La date et l'heure d'occurrence de l'erreur s'affichent.
Object
Le dispositif (le contrôleur ou l'un des outils de 1 à 8) provoquant une erreur est affiché.
Serial No
Le numéro de série de l'appareil (le contrôleur ou l'un des outils 1 à 8) à l'origine d'une erreur s'affiche.
Error code
Un code d'erreur qui s'est produite s'affiche.
Error description
Le contenu d'une erreur qui s'est produite s'affiche.

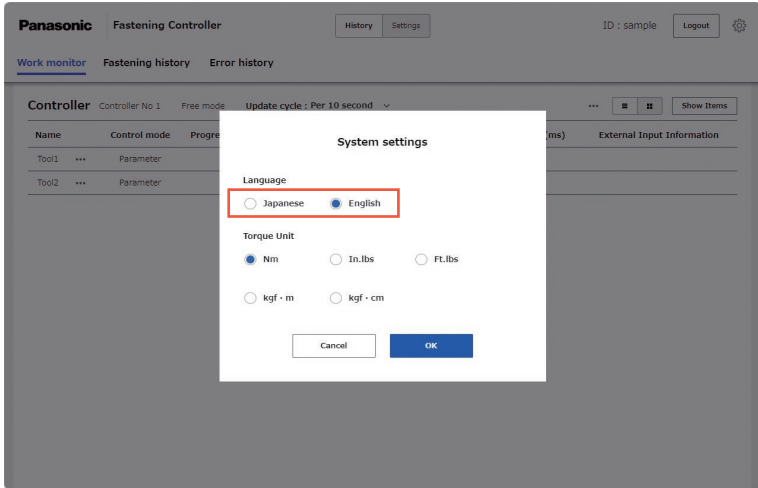
Changement de langue

Vous pouvez sélectionner « Japanese » ou « English ».

- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur la touche d'option dans le coin supérieur droit et sélectionnez « System Settings ».
L'écran « System Settings » s'affiche.



- 2 Sélectionnez la langue dans l'écran « System settings ».
Vous pouvez sélectionner « Japanese » ou « English ».

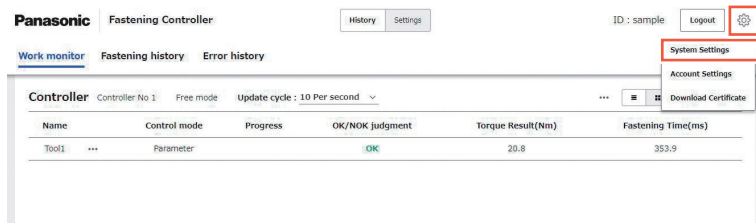


Changement de l'unité de couple pour l'affichage

Vous pouvez sélectionner « Nm », « In.lbs », « Ft.lbs », « kgf·m » ou « kgf·cm ».

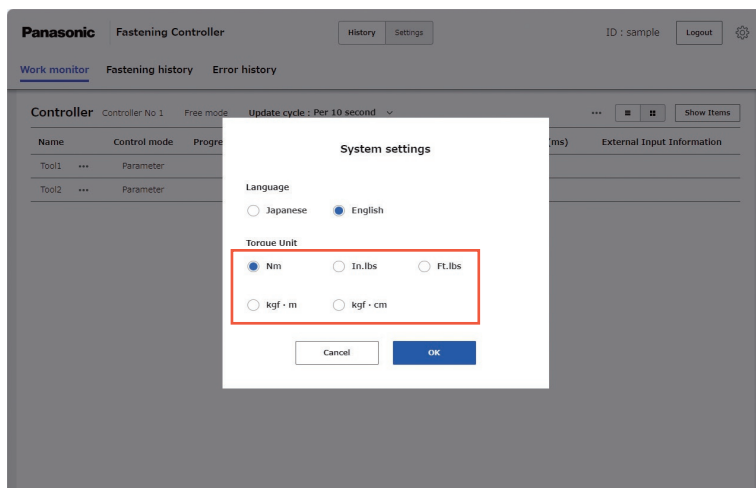
- 1 Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur la touche d'option dans le coin supérieur droit et sélectionnez « System Settings ».

L'écran « System settings » s'affiche.



- 2 Sélectionnez l'unité de couple dans l'écran « System settings ».

Vous pouvez sélectionner l'unité de couple entre « Nm », « In.lbs », « Ft.lbs », « kgf·m », et « kgf·cm ».

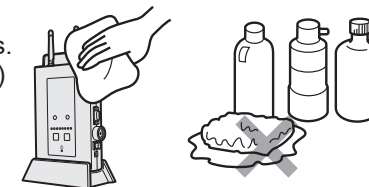


* Certains affichages d'unité peuvent subir des corrections numériques.

Comment nettoyer

Essuyage avec un chiffon doux

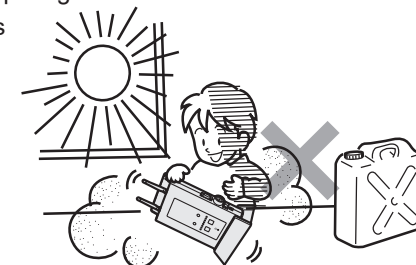
N'utilisez pas de chiffon humide, de diluant, d'alcool, de benzine ou d'autres liquides volatils. (Cause de décoloration, déformation ou fissures)



Comment entreposer

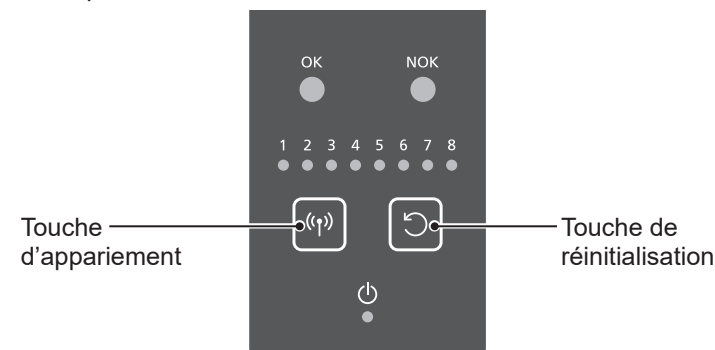
Évitez les conditions suivantes pendant l'entreposage.

- Habitable de voiture ou autres endroits chauds
- Endroits exposés aux rayons directs du soleil
- Endroits exposés à l'eau ou à l'humidité
- Endroits contenant beaucoup de corps étrangers ou de poussière
- Endroits à portée des enfants
- Endroits contenant de l'essence ou d'autres produits inflammables
- Endroits présentant un risque de chute



Initialisation du contrôleur

Pour initialiser (réinitialisation des réglages usine) le contrôleur, maintenez la touche d'appariement et la touche de réinitialisation enfoncées simultanément pendant 10 secondes ou plus.



* Cela peut prendre plus de 5 minutes en fonction de l'utilisation de l'entreposage.

* Vous ne pouvez pas effectuer cette opération lorsque les touches sur l'appareil sont désactivées. **Se reporter à P72**

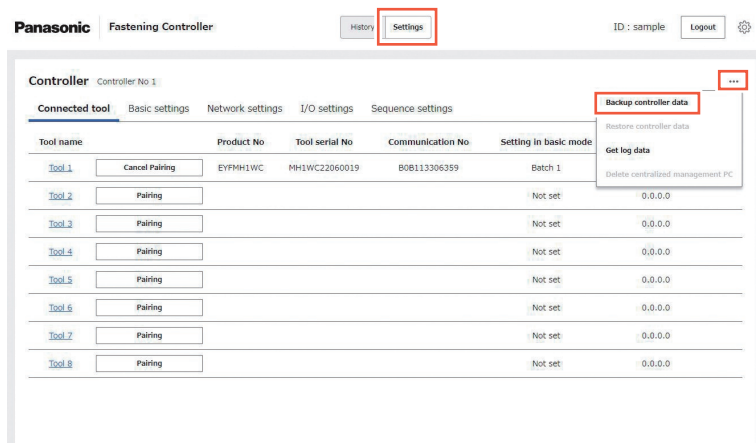
Effectuer une sauvegarde des paramètres

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut.

Cliquez sur ... (touche d'option contrôleur), puis sur [Backup controller data].

Vous pouvez sauvegarder les réglages du contrôleur et des outils.

* Les données d'historique de fixation ne sont pas sauvegardées. Exportez-les au format CSV si nécessaire.



Restauration des paramètres

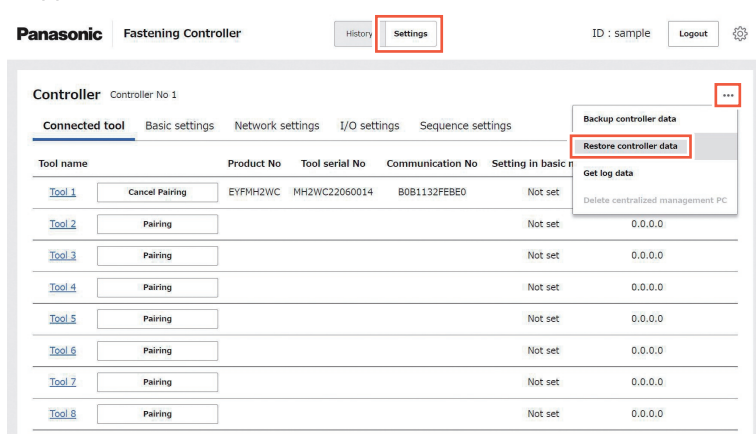
Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut.

Cliquez sur ... (touche d'option contrôleur), puis sur [Restore controller data].

Vous pouvez restaurer les paramètres du contrôleur et des outils à partir de leur sauvegarde.

* Vous ne pouvez pas le faire pendant le contrôle de fixation.

* Vous ne pouvez pas l'effectuer lorsque l'appariement avec les outils est enregistré. Annulez l'appariement.



Mise à jour du micrologiciel

Vous pouvez mettre à jour le micrologiciel du contrôleur et la pièce de communication de l'outil.

Utilisez l'une des méthodes suivantes pour mettre à jour le micrologiciel.

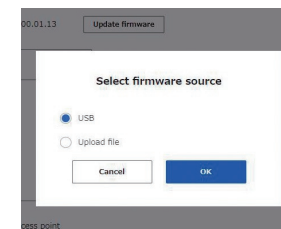
① Utilisation du port USB du contrôleur.

* Une clé USB verrouillée par mot de passe ne peut pas être utilisée.

* Sauvegardez un seul fichier de données de micrologiciel directement sur une clé USB sans créer de dossier.

② Écriture à partir du PC de configuration.

* Lors de la sélection de « Upload file », sélectionnez le fichier de données de micrologiciel enregistré sur le PC dans l'écran de sélection.

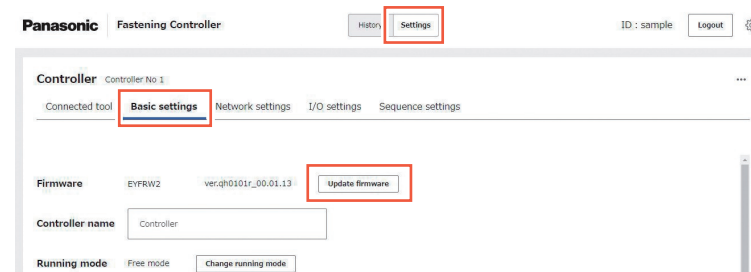


Pour la version actuelle du micrologiciel, accédez à notre site Web. Ou contactez notre commercial.

Se reporter à P2

Pour le contrôleur

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut, sélectionnez l'onglet « Basic settings » et cliquez sur [Update firmware].

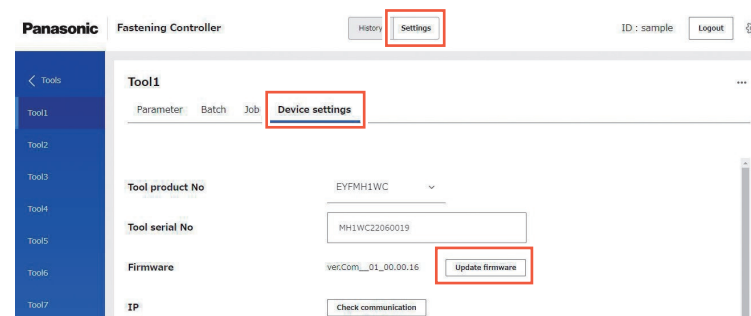


Pour la pièce de communication de l'outil

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut et sélectionnez l'onglet « Connected tool ».

Dans l'écran « Connected tool », cliquez sur le numéro d'outilsouhaité.

Dans l'onglet « Device settings » dans l'écran du numéro d'outil, cliquez sur [Update firmware].



Remplacement de la pile bouton

Pour maintenir l'horloge (RTC) du contrôleur en marche, remplacez la pile bouton en vous référant au guide de remplacement ci-dessous.

Type de batterie



CR2450

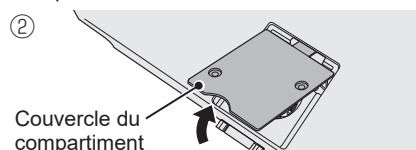
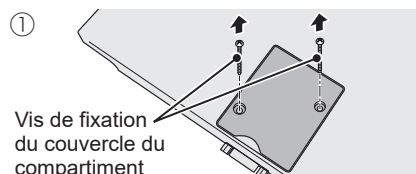
Guide de remplacement

La pile bouton est utilisée pour maintenir l'horloge en marche lorsque le contrôleur est éteint. Pour réduire sa consommation, en principe, ne désactivez pas le contrôleur.

L'alimentation est activée 12 heures par jour (jours ouvrables uniquement)	L'alimentation est toujours activée
Environ 3 ans	Environ 8 ans

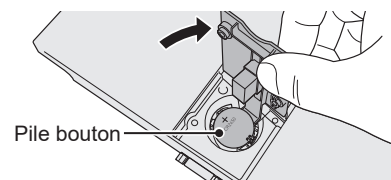
Remplacez-la par la procédure suivante ou contactez votre revendeur. Il est recommandé de faire effectuer ce travail par une personne compétente en électricité.

1 Retirez les 2 vis de fixation du couvercle du compartiment puis retirez le couvercle du compartiment.

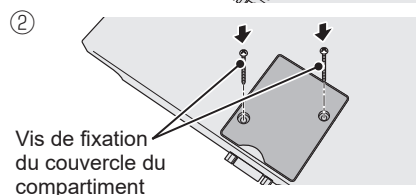
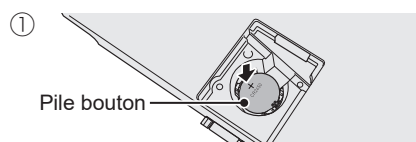


2 À l'aide du couvercle du compartiment, retirez la pile bouton.

Soulevez la pile bouton avec le crochet du couvercle du compartiment.

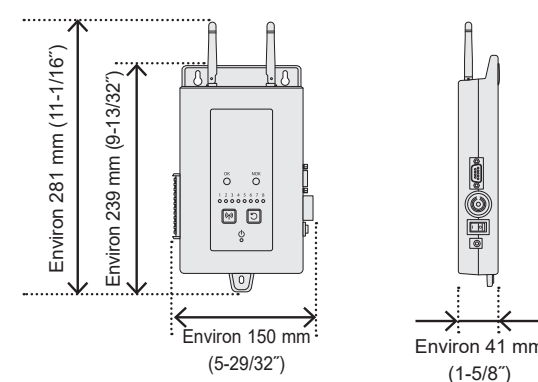


3 Placez une pile bouton neuve et fixez le couvercle du compartiment avec les 2 vis de fixation du couvercle du compartiment.



Spécifications du contrôleur

Réception des signaux d'exécution et d'échec de fixation pendant le travail de montage du produit intérieur

N° de modèle	EYFRW2
Alimentation électrique	100 V-240 V CA, 50/60 Hz
Norme de communication sans fil	Réseau local sans fil (IEEE.802.11 a/b/g/n)
Bande de fréquence	2,4 GHz : 2,412 GHz à 2,462 GHz 5 GHz : 5,180 GHz à 5,240 GHz
Canal	2,4 GHz : 1 à 11 canaux 5 GHz : 36, 40, 44, 48 canaux
Couverture	2,4 GHz : environ 16 m (52,5 ft) 5 GHz : environ 10 m (32,8 ft)
Nombre d'outils pouvant être enregistrées	8 (maximum)
Bornes d'entrée/sortie (E/S)	8 entrées et 8 sorties
Tension nominale de la borne d'entrée	24 V CC, 50 mA
Tension nominale de la borne de sortie	30 V CC, 3 A
Consommation électrique	Environ 30 W
Plages de température et d'humidité de fonctionnement	0 °C (32 °F) à 45 °C (113 °F), 20 % à 90 %
Taille (dimensions estimées) Longueur totale × Hauteur totale × Largeur	Environ 150 × 239 × 41 mm (5-29/32" × 9-13/32" × 1-5/8") (hauteur y compris les antennes : 281 mm (11-1/16")) 
Masse (Poids)	Environ 550 g (1,1 lbs) (unité principale uniquement)
Interface de communication	Ethernet × 2, RS232C × 1, USB-A × 1
Nombre de données pouvant être stockées	Environ 200 000 journaux d'historique de fixation (y compris les données de forme d'onde)
Modèles d'outils compatibles	EYFNH1WC/WP*, EYFMH1WC/WP, EYFMH2WC/WP

*1 Ceci est pris en charge uniquement par la version de micrologiciel 2.02.00 ou ultérieure.

Spécifications sans fil

Fréquences par canal

Bande de fréquence	Canal	Fréquence
2,4 GHz	Canal 1	2,412 GHz
	Canal 2	2,417 GHz
	Canal 3	2,422 GHz
	Canal 4	2,427 GHz
	Canal 5	2,432 GHz
	Canal 6	2,437 GHz
	Canal 7	2,442 GHz
	Canal 8	2,447 GHz
	Canal 9	2,452 GHz
	Canal 10	2,457 GHz
	Canal 11	2,462 GHz
5 GHz	Canal 36	5,180 GHz
	Canal 40	5,200 GHz
	Canal 44	5,220 GHz
	Canal 48	5,240 GHz

Spécifications d'interface utilisateur Web

Système d'exploitation compatible	Windows 10 ou version ultérieure (supportant l'un des navigateurs Web ci-dessous)
Navigateur Web pris en charge	Microsoft Edge version 102 ou ultérieure ou Google Chrome version 102 ou ultérieure
Langue prise en charge	Anglais, japonais
Résolution d'écran recommandée	1024 × 768 ou plus

MISE EN GARDE

- Certains ordinateurs ne sont pas disponibles même s'ils sont conformes à l'environnement d'exploitation.
- Selon l'environnement d'utilisation, etc. de votre PC, les descriptions et les écrans de ces Instructions d'utilisation peuvent être différents des descriptions et écrans réels. Soyez avertis.
- Le contenu de ces Instructions d'utilisation peut faire l'objet de modifications sans préavis.
- Toute reproduction totale ou partielle du contenu de ces Instructions d'utilisation est interdite sans autorisation.
- Les descriptions sur le fonctionnement de Windows dans ces Instructions d'utilisation utilisent les procédures et les écrans de Windows 10.
- WebUI ne fonctionne pas avec un système d'exploitation autre que le système d'exploitation compatible.
- Le fonctionnement n'est pas garanti pour tous les PC répondant à l'environnement recommandé.

■ Conditions d'utilisation (Lire avant utilisation)

<Limitations>

WebUI est un logiciel de configuration pour EYFRW2.

MISE EN GARDE

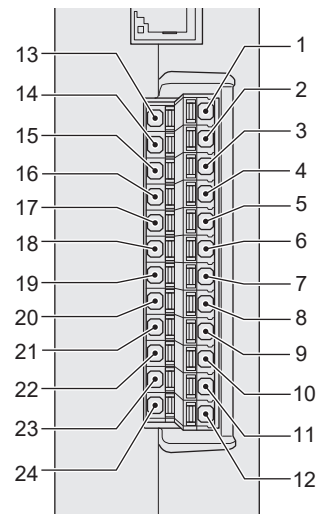
- Respectez les consignes suivantes lors de l'utilisation de la fonction.
Il est entendu que vous acceptez les conditions d'utilisation suivantes en utilisant la fonction.

[Conditions d'utilisation]

Panasonic n'offre aucune garantie concernant la fonctionnalité.
Panasonic ne peut être tenu responsable de tout dommage, incluant sans s'y limiter la perte directe, la perte indirecte, l'étendue de perte, la perte consécutive et la perte spéciale provoquée par l'utilisation ou l'activation de la fonction.
La reproduction et la distribution non autorisées de la fonction sont interdites.

Spécifications de l'E/S de contact

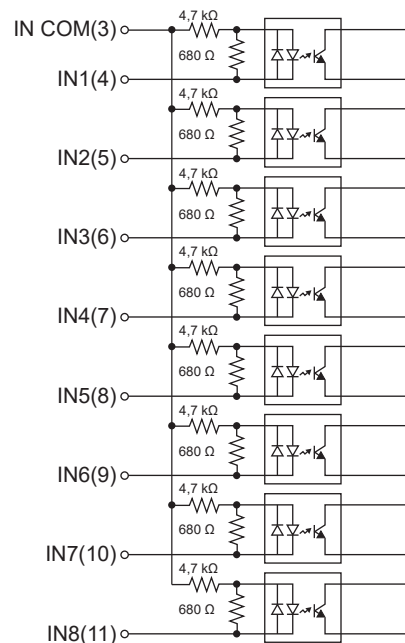
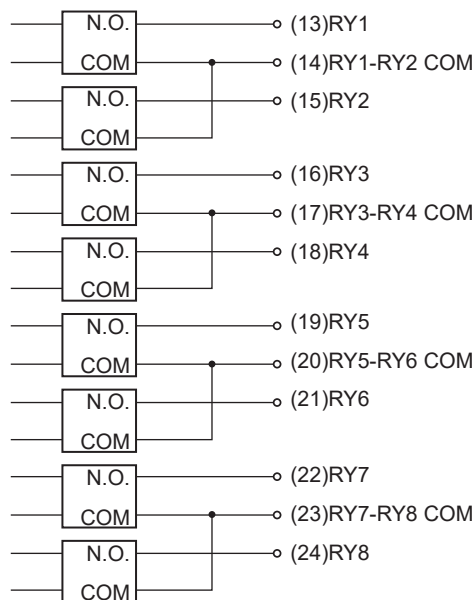
■ Attribution entre les bornes de relais de sortie et les bornes d'entrée



N°	Attribution des broches
1	+24 V
2	+24 V
3	IN COM
4	IN 1
5	IN 2
6	IN 3
7	IN 4
8	IN 5
9	IN 6
10	IN 7
11	IN 8
12	24 V return

N°	Attribution des broches
13	RY1
14	RY1-RY2 COM
15	RY2
16	RY3
17	RY3-RY4 COM
18	RY4
19	RY5
20	RY5-RY6 COM
21	RY6
22	RY7
23	RY7-RY8 COM
24	RY8

■ Schéma de connexion du bornier



■ Déclaration du texte explicatif pour diverses exigences

Cet appareil est conforme au chapitre 15 du règlement de la FCC. Le fonctionnement est soumis aux deux conditions suivantes: (1) cet appareil ne peut pas provoquer de brouillage préjudiciable et (2) cet appareil doit pouvoir accepter n'importe quel brouillage reçu incluant ceux qui pourraient provoquer un fonctionnement non désiré.

Avertissement de la FCC : afin d'assurer la continuité de la conformité, installez et utilisez selon les instructions données. Tout changement ou modification non expressément approuvé par les parties responsables de la conformité pourraient faire perdre à l'utilisateur le droit de faire fonctionner cet équipement.

Cet équipement a été testé et déclaré conforme aux limites des appareils numériques de classe B, conformément à la chapitre 15 du règlement de la FCC. Ces limites ont été définies pour fournir une protection raisonnable contre les brouillages préjudiciables dans une installation résidentielle. Cet équipement produit, utilise et peut émettre des énergies de fréquence radio et s'il n'est pas installé et utilisé conformément aux instructions, il pourra provoquer des brouillages préjudiciables aux communications radio. Il n'y a toutefois aucune garantie que ces brouillages ne se produisent pas lors d'une installation particulière. Si cet équipement provoque des brouillages préjudiciables à la réception de la radio ou de la télévision, ce qui peut être vérifié en mettant en marche puis en arrêtant l'équipement, l'utilisateur est encouragé à essayer d'éliminer le brouillage selon l'une des mesures suivantes :

- Réorienter ou déplacer l'antenne réceptrice.
- Augmenter l'espacement entre l'équipement et le récepteur.
- Brancher l'équipement à une prise d'un circuit différent de celui auquel le récepteur est branché.
- Consulter le distributeur ou un technicien de radio/télévision expérimenté pour obtenir une aide.

Contient l'ID FCC : Z64-WL18DBMOD Contient IC : 4511-WL18DBMOD

Cet émetteur ne doit pas être installé ou utilisé en conjonction avec une autre antenne ou un autre émetteur.

Cet appareil est conforme aux limites d'exposition aux radiations fixées par la FCC pour un environnement non contrôlé. Cet équipement a été approuvé pour un fonctionnement mobile nécessitant un espacement minimum de 20 cm (7-7/8") entre la ou les antennes et le corps de toute personne (à l'exclusion des extrémités des mains, des poignets et des pieds) pendant les modes de fonctionnement sans fil. Cet équipement ne peut être colocalisé ou utilisé avec une autre antenne ou un autre émetteur.

Cet équipement est conforme aux limites d'exposition aux rayonnements énoncées pour un environnement non contrôlé et respecte les règles d'exposition aux fréquences radioélectriques (RF) CNR-102 de l'ISDE. Cet équipement doit être installé et utilisé en gardant une distance de 20 cm (7-7/8") ou plus entre le radiateur et le corps humain.

Cet appareil contient un (des) émetteur(s)/récepteur(s) exempté(s) de licence qui est (sont) conforme(s) au(x) CNR exempté(s) de licence du ministère de l'Innovation, des Sciences et du Développement économique du Canada. L'utilisation est soumise aux deux conditions suivantes :

1. Ce dispositif ne doit pas causer d'interférences.
2. Ce dispositif doit accepter toute interférence, y compris les interférences qui peuvent causer un fonctionnement indésirable de l'appareil.

Pour une utilisation en intérieur uniquement.

PRÉCAUTIONS POUR LA COMMUNICATION SANS FIL

Mises en garde pour l'utilisation d'un périphérique WLAN

L'appareil utilise une bande de fréquence partagée avec d'autres types d'équipement incluant des appareils industriels, scientifiques et médicaux (par ex. un four à micro-ondes) et des stations de radio telles qu'une station de radio amateur (sous licence) et une station radio de faible puissance (sans licence) pour l'identification mobile utilisée dans les lignes de fabrication d'usine et une station de radio amateur (sous licence).

1. Avant d'utiliser l'appareil, vérifiez qu'il n'y a aucune station de radio à faible puissance pour l'identification mobile ou qu'aucune station de radio amateur ne fonctionne à proximité.
2. Si l'appareil provoque des interférences nuisibles avec une station de radio locale pour l'identification mobile, cessez immédiatement d'utiliser la bande et consultez le centre d'assistance ci-dessous pour résoudre le problème d'interférence (par exemple, en installant une cloison).
3. Si l'appareil cause des interférences nuisibles avec une station de radio à faible puissance ou à proximité pour l'identification mobile ou une station de radio amateur ou d'autres problèmes, consultez le centre d'assistance.

■ Il se peut qu'il y ait du bruit, une couverture radio plus courte ou un dysfonctionnement dans les conditions environnementales suivantes.

- Il y a une obstruction (par exemple un objet en métal ou en béton armé) qui empêche la propagation radio régulière entre l'unité d'outils sans fil et le contrôleur.
- Les antennes du contrôleur sont recouvertes de métal.
- Le corps d'un opérateur interfère avec la propagation radio entre un opérateur (l'unité d'outil sans fil) et le contrôleur.
- Un appareil micro-ondes, un PC ou tout autre appareil causant du bruit se trouve à proximité.
- Un téléphone portable ou un téléphone PHS est utilisé à proximité de l'outil sans fil et du contrôleur.

Conditions de licence logicielle

Ce produit intègre le logiciel suivant :

- (1) le logiciel développé indépendamment par ou pour Panasonic Corporation,
- (2) le logiciel détenu par un tiers et sous licence de Panasonic Corporation,
- (3) le logiciel sous licence en vertu de la GNU General Public License, Version 1.0 (GPL V1.0),
- (4) le logiciel sous licence en vertu de la GNU General Public License, Version 2.0 (GPL V2.0),
- (5) le logiciel sous licence en vertu de la GNU General Public License, Version 3.0 (GPL V3.0),
- (6) le logiciel sous licence en vertu de la GNU LESSER General Public License, Version 2.1 (LGPL V2.1),
- (7) le logiciel sous licence en vertu de la GNU LESSER General Public License, Version 3.1 (LGPL V3.1),
- (8) le logiciel sous licence en vertu de la SMAIL General Public License(SMAIL),
- (9) le logiciel sous licence en vertu de la Mozilla Public License Version 1.1 (MPL V1.1),
- (10) le logiciel sous licence en vertu de la Mozilla Public License Version 2.0 (MPL V2.0), et/ou
- (11) un logiciel libre autre que le logiciel sous licence en vertu de GPL V1.0, GPL V2.0, GPL V3.0, LGPL V2.1, LGPL V3.1, SMAIL, MPL V1.1 et/ou MPL V2.0.

Les logiciels de la catégorie (3) - (11) sont distribués dans l'espoir qu'ils seront utiles mais SANS AUCUNE GARANTIE, sans même la garantie implicite de QUALITÉ MARCHANDE ou d'ADÉQUATION POUR UN USAGE PARTICULIER.

Pour plus de détails sur les détenteurs des droits d'auteur et les licences, reportez-vous à la page 99 et aux pages suivantes.

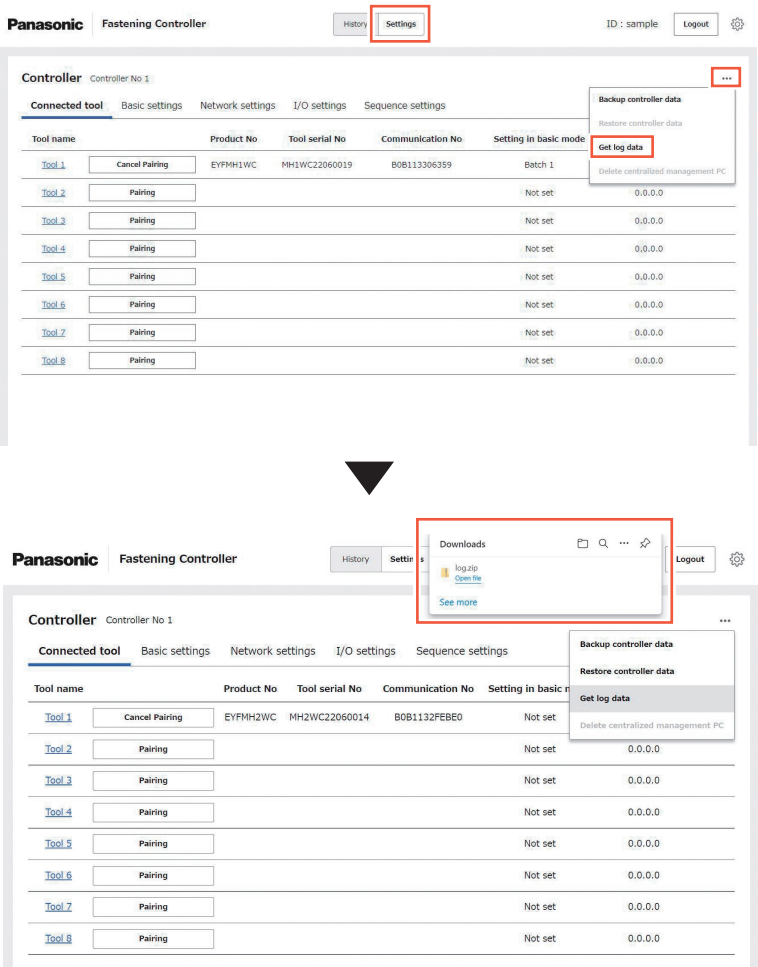
Au moins 3 ans à partir de la livraison de ce produit, Panasonic transmettra à tout tiers qui nous contacte via les informations de contact fournies ci-dessous, pour un coût inférieur à celui de l'exécution physique d'une distribution de code source, une copie complète lisible par une machine du code source correspondant, couvert par une licence GPL V1.0, GPL V2.0, GPL V3.0, LGPL V2.1, LGPL V3.1, SMAIL ou d'autres licences avec l'obligation de le faire, ainsi que l'avis de droit d'auteur respectif.

Informations de contact : oss-cd-powertools-gl@ml.jp.panasonic.com

Appareil	Code d'erreur	Type	Catégorie	Événement	Action
Contrôleur	0xEF21	Avertissement	Défaillance du matériel	Erreur de CPU secondaire (défaillance)	Redémarrez le contrôleur. Si le problème persiste, il se peut que l'appareil soit cassé. Contactez votre revendeur.
	0xEF51	Avertissement	Défaillance du matériel	Erreur Ether0	L'appareil est peut-être cassé. Contactez votre revendeur.
	0xEF52	Avertissement	Défaillance du matériel	Erreur Ether1	L'appareil est peut-être cassé. Contactez votre revendeur.
	0xEF61	Avertissement	Défaillance du matériel	Erreur du module WLAN (défaillance)	Redémarrez le contrôleur. Si le problème persiste, il se peut que l'appareil soit cassé. Contactez votre revendeur.
	0xCE42	Erreur	Défaillance du logiciel	Erreur de contenu de réglage	Réinitialisez les paramètres d'usine du contrôleur et effectuez à nouveau les réglages.
	0xCE43	Erreur	Défaillance du logiciel	Erreur d'information de rétraction	Maintenez enfoncée la touche de réinitialisation du contrôleur pendant 3 secondes ou plus.
	0xEC61	Avertissement	Défaillance du logiciel	La capacité de stockage de l'historique de fixation est pleine (opération suspendue)	Supprimez les journaux de l'historique de fixation sur l'écran de l'historique de fixation pour libérer de l'espace. Exportez-les avant de les supprimer si nécessaire.
Outil	0x4301	Mise en garde	Défaillance du logiciel	La capacité de stockage est pleine	Accédez au logiciel de réglage de l'outil (logiciel Tool manager) et supprimez les journaux de l'historique des tâches.
	0x4302	Mise en garde	Défaillance du logiciel	Le nombre de résultats envoyés dans une file d'attente a atteint la limite supérieure.	L'outil ne peut pas communiquer avec le contrôleur. Changez le lieu de travail. Si le problème persiste, il se peut que l'appareil soit cassé. Contactez votre revendeur.
	0x3303	Erreur	Défaillance du logiciel	Détection de réinitialisation du microcontrôleur de commande	Une erreur qui s'est produite a été résolue.
	0x3304	Erreur	Défaillance du logiciel	Détection de réinitialisation du microcontrôleur de calcul de couple	Une erreur qui s'est produite a été résolue.

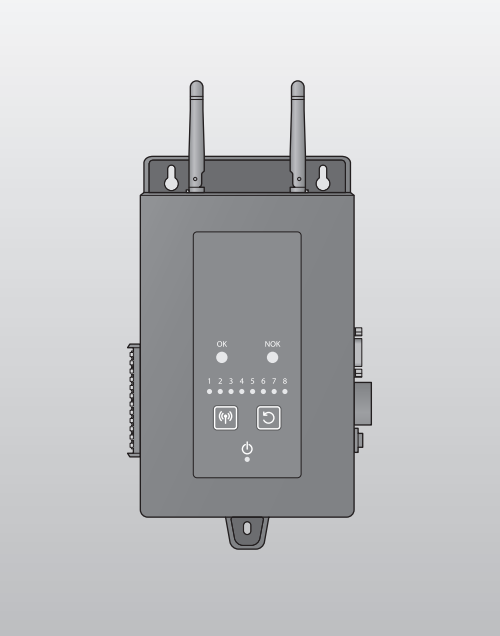
Appareil	Code d'erreur	Type	Catégorie	Événement	Action
Outil	0x4305	Mise en garde	Défaillance du logiciel	Batterie RTC faible	Remplacez la pile bouton à l'intérieur de l'unité d'outil.
	0x4306	Mise en garde	Défaillance du logiciel	Erreur de mise à jour du micrologiciel	Vérifiez que le fichier du micrologiciel est correct.
	0x4315	Mise en garde	Défaillance du logiciel	Erreur de communication USB	Une erreur qui s'est produite a été résolue.
	0x4316	Mise en garde	Défaillance du logiciel	Module WLAN redémarré	Une erreur qui s'est produite a été résolue.
	0x1401	Avertissement	Défaillance du matériel	Erreur de module WLAN	Une erreur qui s'est produite a été résolue.
	0x1402	Avertissement	Défaillance du matériel	Erreur de microcontrôleur de commande du moteur	Une erreur qui s'est produite a été résolue.
	0x1403	Avertissement	Défaillance du matériel	Erreur du microcontrôleur de calcul de couple	Une erreur qui s'est produite a été résolue.
	0x1404	Avertissement	Défaillance du matériel	Erreur de clé USB externe	Une erreur qui s'est produite a été résolue.
	0x1405	Avertissement	Défaillance du matériel	Erreur RTC	Une erreur qui s'est produite a été résolue.
	0x1406	Avertissement	Défaillance du matériel	Erreur d'identification du circuit	Une erreur qui s'est produite a été résolue.
	0x1407	Avertissement	Défaillance du matériel	Pas d'espace d'échange restant	Une erreur qui s'est produite a été résolue.
	0x1408	Avertissement	Défaillance du matériel	Espace de paramètre endommagé	Une erreur qui s'est produite a été résolue.

Dans la page du haut (la page initiale de l'écran de configuration), cliquez sur [Settings] en haut.
Cliquez sur ... (touche d'option contrôleur), puis sur [Get log data].
Vous pouvez obtenir les journaux de fonctionnement du contrôleur.



Manual de instrucciones
Controlador de Montaje

Núm. de modelo:
EYFRW2



IMPORTANTE
Lea y siga las instrucciones de seguridad y operación antes de usar este aparato.
No utilice la función inalámbrica fuera del país donde adquirió el producto.
Hacerlo podría infringir las leyes y normativas locales.

Manual de instrucciones original: Inglés
Traducción del manual de instrucciones original: Otros idiomas

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Entorno de funcionamiento

Debe utilizar un navegador web para configurar el controlador.
Prepare un PC que cumpla con los siguientes requisitos.

SO compatible	Windows 10 o posterior (compatible con cualquiera de los siguientes navegadores web)
Navegador web	Microsoft Edge versión 102 o posterior o Google Chrome versión 102 o posterior

- Algunos PC no están disponibles incluso si cumplen con el entorno operativo.
- En función del entorno de uso, etc., de su PC, las descripciones y pantallas de este Manual de instrucciones podrían ser diferentes de las descripciones y pantallas reales. Por favor, téngalo en cuenta.
- El contenido de este Manual de instrucciones está sujeto a cambios sin previo aviso.
- Cualquier reproducción del contenido de este Manual de instrucciones, en su totalidad o en parte, está prohibida sin permiso.
- Las cifras en este Manual de instrucciones son solo como referencia.

[Nota]
Mantenga siempre actualizado el firmware.
Encontrará los datos más recientes sobre el firmware en la siguiente página web, que proporciona acceso al Manual de instrucciones.
Para saber cómo actualizar el firmware, consulte “Actualización del firmware”.
Consulte P87

Cómo acceder al Manual de instrucciones

La versión actual del Manual de instrucciones del controlador y otros recursos se pueden descargar desde el siguiente sitio web.

<https://panasonic.net/electricworks/ecm/powerelctrictools/download/>



Marca comercial

- Microsoft y Windows son marcas registradas o marcas comerciales de Microsoft Corporation en EE. UU. y/o en otros países.
- Las capturas de pantalla se utilizan de acuerdo con las directrices de Microsoft Corporation.

Otros nombres, incluyendo nombres de empresas y productos en este Manual de instrucciones, son marcas comerciales o marcas comerciales registradas de sus respectivas compañías.
™ y ® pueden omitirse en estas Manual de instrucciones.

Uso previsto

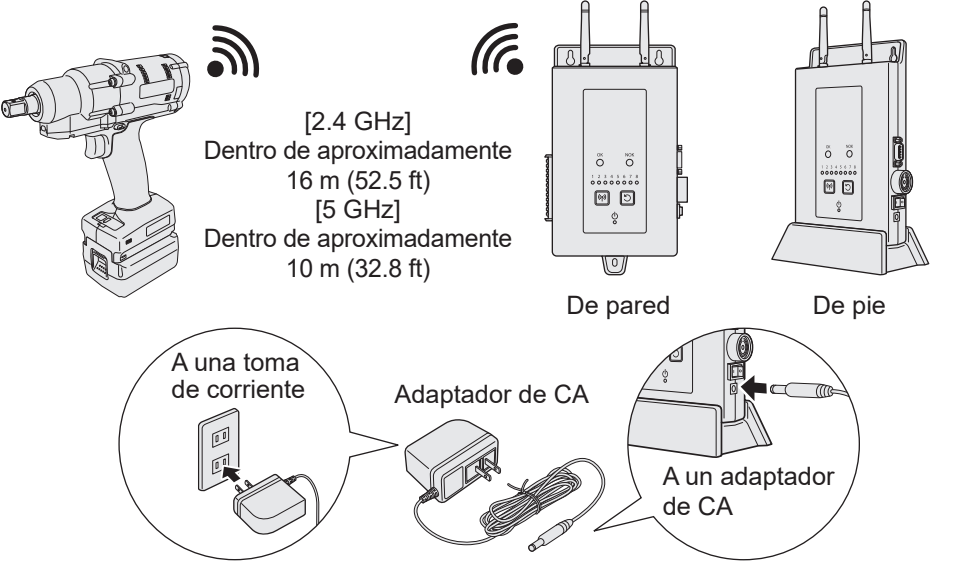
Este producto es un controlador que se comunica inalámbricamente con herramientas. Puede recibir datos del historial de sujeción de las herramientas, realizar ajustes en las herramientas y controlar la cantidad a fijar.



- 01** Conecte hasta 8 herramientas
- 02** Compatibilidad con bandas de 2.4 GHz y 5 GHz
- 03** Admite una función de control de la fijación y una función de almacenamiento del historial

Configuración

Instale el controlador en un rango en el que la comunicación inalámbrica con las herramientas sea posible.
Suministre alimentación a través de una toma de CA y conéctela a dispositivos externos a través de interfaces de comunicación según sea necesario.



- El controlador contiene una pila de botón para mantener la función del reloj (RTC) en funcionamiento. Se recomienda mantener la alimentación encendida para reducir el consumo de la pila de botón interna.
- La cobertura inalámbrica puede cambiar según el entorno.

A continuación se indican las instrucciones que debe seguir siempre para evitar daños personales y materiales.

■ A continuación se presenta la gravedad de los daños causados por un uso incorrecto.

 ADVERTENCIA	Puede provocar la muerte o lesiones graves.
 PRECAUCIÓN	Puede causar lesiones menores o daños a la propiedad.

■ El contenido que se debe observar se presenta con los siguientes símbolos. (Lo siguiente son ejemplos)

 NO DEBE realizar la acción.	
 DEBE realizar la acción.	

 ADVERTENCIA	
 Obligatorio	● Asegúrese de que no haya objetos enterrados, como conductos, tuberías de agua y tuberías de gas, en el lugar de instalación. Tocar estos objetos enterrados puede causar una descarga eléctrica o causar fugas eléctricas o de gas.
	● Inserte el enchufe de alimentación hasta el fondo. La inserción incompleta puede causar descargas eléctricas o generación de calor y provocar un incendio. No utilice un enchufe dañado o un enchufe suelto.
	● Limpie el polvo del enchufe de alimentación de forma habitual. El polvo acumulado en el enchufe puede absorber la humedad y provocar un aislamiento deficiente con el consiguiente riesgo de incendio. Desconecte el enchufe de alimentación y límpielo con un paño seco.
	● Utilice únicamente el cable de alimentación especificado. El uso de cualquier otro enchufe puede causar descargas eléctricas, cortocircuitos o incendios.
	● Mantenga el lugar de trabajo suficientemente iluminado. Una mala visibilidad en un lugar de trabajo oscuro puede provocar un accidente o lesiones.

 ADVERTENCIA	
 Prohibido	● No utilice enchufes o dispositivos de cableado que superen el valor nominal. Utilice solo 100 V-240 V CA. Si se sobrepasa el valor nominal debido a una sobrecarga de la toma de corriente, se puede generar calor y provocar un incendio.
	● No dañe el cable de alimentación ni el enchufe. (Evite dañarlo, romperlo, modificarlo, acercarlo a una fuente de calor, doblarlo con fuerza, retorcerlo, tirar de él, colocarle una carga pesada, pellizcarlo o atarlo) El uso de un cable o enchufe dañado puede provocar una descarga eléctrica, un cortocircuito o un incendio. Compruebe el cable y el enchufe periódicamente y si presentan daños, consulte a su distribuidor.
	● No utilice el controlador con una fuente de alimentación de CC, generador de motor o transformador. ● No utilice el controlador en un lugar con líquido o gas inflamable. Hacerlo puede causar la generación de calor, humo, fuego o explosión.
	● No instale el controlador en una pared de mortero. Atornillarlo en una pared de mortero puede provocar la generación de calor de la malla metálica del interior, con el consiguiente riesgo de incendio en caso de fuga eléctrica.
	● Desconecte el enchufe de alimentación entre usos. Mantenerlo conectado puede causar un aislamiento deficiente que provoque descargas eléctricas o incendios por fugas eléctricas.
 No desmontar	● No modifique el controlador. No desmonte ni repare el controlador. De lo contrario, podrían producirse incendios, descargas eléctricas o lesiones. Para la reparación, consulte a su distribuidor o a nuestro Centro de Atención al Cliente.
 Mantener seco	Evite el siguiente uso de las herramientas cargadas. ● No las utilice ni las deje expuestas a la lluvia o a la humedad. ● No las utilice sumergidas bajo el agua. De lo contrario, podría provocar humo, incendios o explosiones.
 Sin manos húmedas	● No conecte ni desconecte el enchufe de la toma de corriente con las manos mojadas. Si lo hace, podría provocar una descarga eléctrica.



Prohibido



Obligatorio



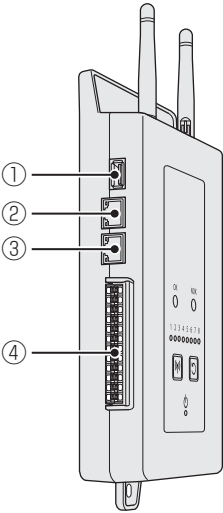
PRECAUCIÓN

- **No utilice el controlador para ningún otro propósito que no sea el previsto.**
De lo contrario, podrían producirse lesiones.
- **No coloque el controlador en un lugar accesible para los niños.**
De lo contrario, podría provocar un accidente o problemas.
- **No utilice el controlador con aceite u otro material extraño adherido al mismo.**
Dicho aceite u otro material extraño puede penetrar en el interior, provocando calor, fuego o explosión.
- **No guarde el cuerpo principal en un lugar donde la temperatura pueda subir a 45 °C (113 °F) o más.**
Si lo hace, podría provocar un funcionamiento anómalo.
- **No trabaje en una posición inusual.**
De lo contrario, podría caerse y sufrir lesiones.
Siempre colóquese sobre una base estable y mantenga un buen equilibrio.
- **No utilice el controlador cuando esté cansado.**
Si lo hace, podría provocar un accidente o lesiones.
- **No permita que un niño ni cualquier otra persona que no sea un operador se acerquen al lugar de trabajo o toque el controlador.**
De lo contrario, podrían producirse lesiones.
- **No utilice el controlador con dispositivos incompatibles.**
De lo contrario, podría provocar un funcionamiento incorrecto y provocar un accidente.

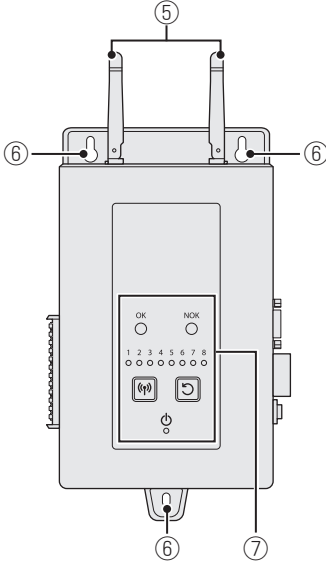
- **Para instalar el controlador en una pared, asegúrelo con los tornillos para evitar que se caiga.**
Podría sufrir lesiones si se cae.
- **Para desconectar el enchufe de alimentación, sujete siempre la clavija de alimentación sin tirar del cable.**
Si tira del cable, podría provocar una descarga eléctrica o un cortocircuito.
- **Antes de su uso, compruebe si el controlador y otras piezas están dañadas y confirme su funcionamiento normal.**
De lo contrario, podría producirse una rotura, con el consiguiente riesgo de lesiones.
- **Mantenga el lugar de trabajo limpio.**
Un lugar o una mesa de trabajo desordenados pueden provocar un accidente.
- **Piense bien cómo manejar y trabajar, preste atención al entorno que le rodea y utilice el sentido común durante el trabajo.**
De lo contrario, podría provocar un accidente o lesiones.

Cuerpo principal

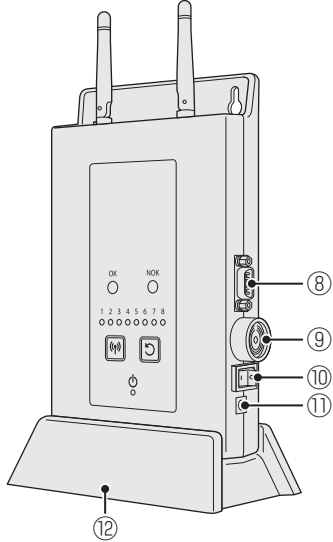
Lado izquierdo



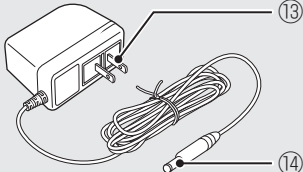
Lado delantero



Lado derecho



Adaptador de CA



①	● Puerto USB (USB-A)
②	■ Puerto Ethernet (para el mantenimiento)
③	■ Puerto Ethernet (para la red)
④	1~24 Puerto de E/S
⑤	Antena de diversidad
⑥	Orificio para colgar en la pared
⑦	Panel de control

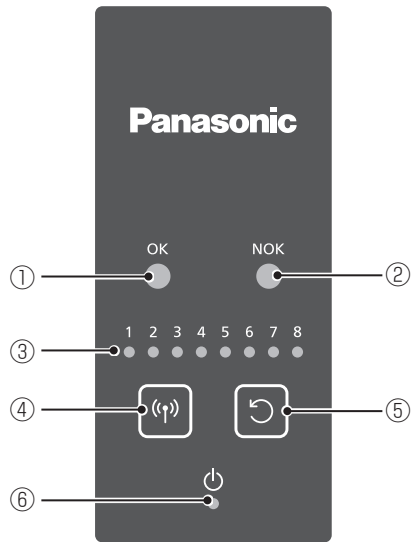
⑧	IOIOI Puerto de serie (RS232C)
⑨	Zumbador
⑩	Interruptor de alimentación
⑪	● Toma del adaptador de CA
⑫	Soporte del controlador
⑬	Enchufe de alimentación
⑭	Conector de alimentación

ANTES DEL USO

ES 6

7 ES

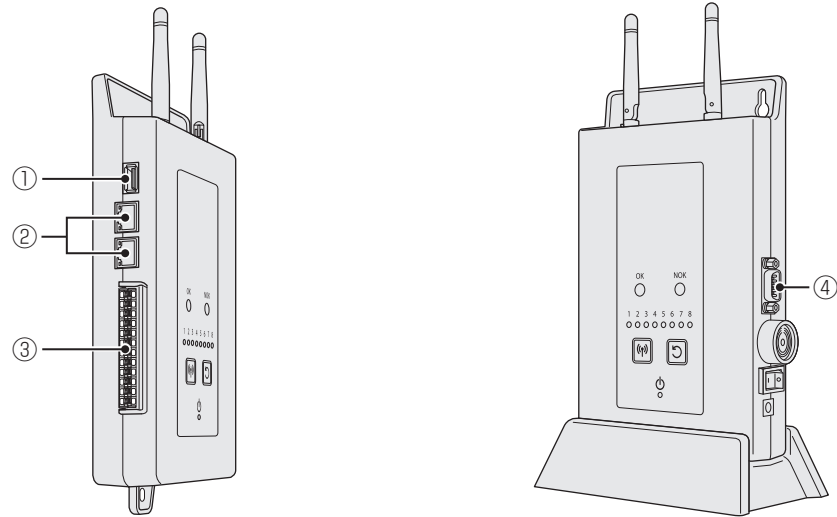
■ Panel de control



①	Lámpara de fijación OK Parpadea en verde: Estado de recepción de lectura del código de barras. Verde sólido: Se ha recibido una señal de finalización de fijación. Apagado: Todavía no se ha recibido una señal de finalización de fijación.
---	---

③	Lámpara de comunicación (N.º 1 a N.º 8) Azul sólido: Se ha registrado una herramienta. Azul parpadeante: Una herramienta se está registrando o está fuera de cobertura. Apagado: Aún no se ha registrado ninguna herramienta.
④	Tecla de emparejamiento
⑤	Tecla de reinicio
⑥	Lámpara de alimentación Amarillo sólido: Encendido (modo de recepción) Apagado: Apagado Amarillo parpadeante: Error

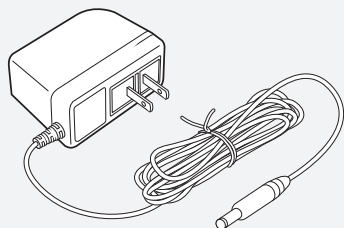
■ Interfaz de comunicación



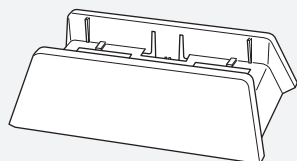
Interfaz		Detalles
①	USB	Utilice este puerto para conectar una unidad flash USB para actualizar el firmware. * Conecte directamente una unidad flash USB (sin extensión) Un receptor inalámbrico está conectado a este puerto para conectar un lector de códigos de barras. * Sólo hay disponibles lectores de códigos barras inalámbricos. • USB2.0 USB-A × 1
②	Ethernet (para mantenimiento y red)	Utilice este puerto para conectarse a un PC para la configuración o un sistema anfitrión. * Conecte el puerto Ethernet (para mantenimiento) directamente a un PC para la configuración. (No utilice un concentrador) • 10Base-T/100Base-TX × 2 • Longitud del cable: menos de 30 m (98.4 ft)
③	Terminal de entrada/salida (E/S)	Utilice este puerto para conectar a un dispositivo externo (p. ej., un PLC). • 8 entradas y 8 salidas • Longitud del cable: 10 m (32.8 ft) o menos • Clasificación del terminal de entrada: 24 V CC, 50 mA • Clasificación del terminal de salida: 30 V CC, 3 A
④	Puerto de serie (RS232C)	Utilice este puerto para conectar a un dispositivo externo (p. ej., un PLC). • RS232C × 1 • Longitud del cable: 10 m (32.8 ft) o menos

Accesorio

■ **Adaptador de CA × 1**
(WEYFRW1K7651)



■ **Soporte del controlador × 1**
(EYFRW1F7001)



Consumibles

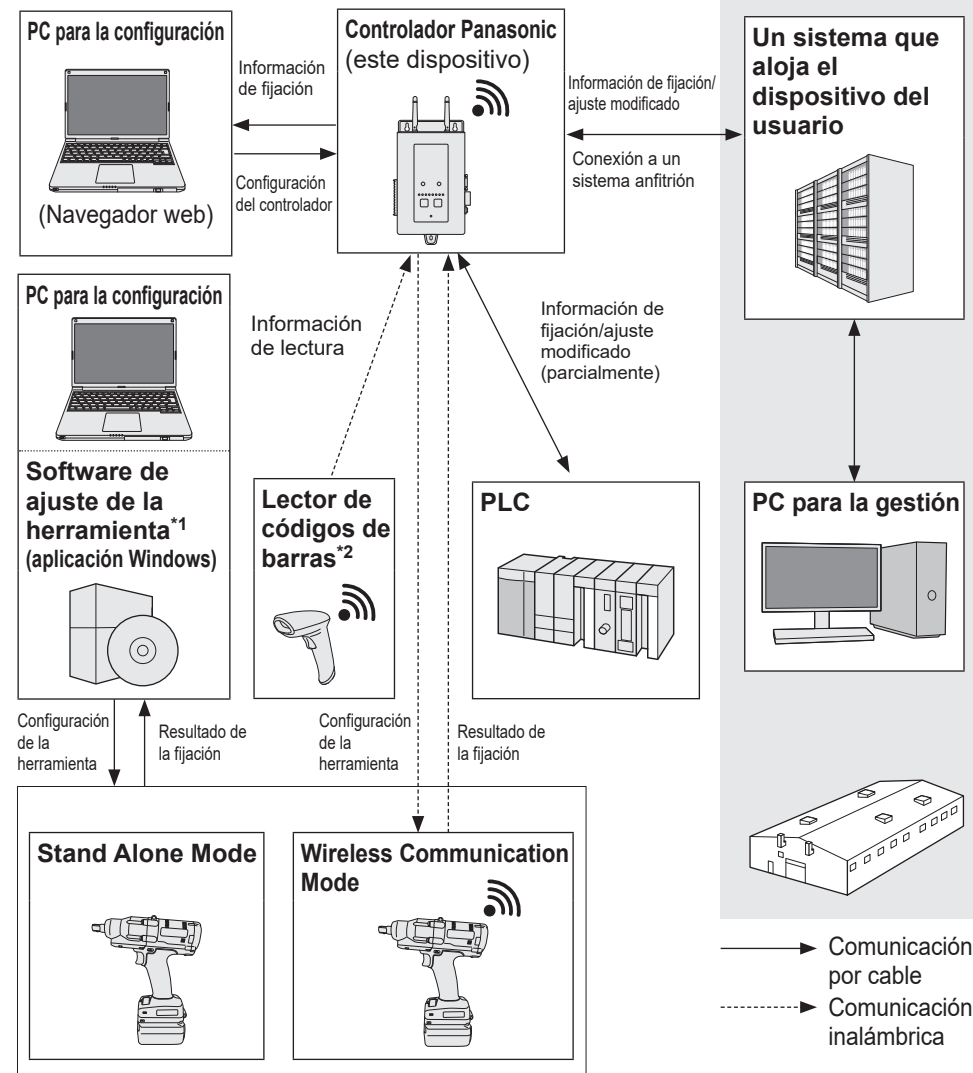
■ **Pila de botón (CR2450) × 1**

Para saber cómo sustituirla, consulte “Sustitución de la pila de botón”.

Consulte P88



Configuración del sistema



*1 El “software de ajuste de la herramienta” puede descargarse de nuestro sitio web.

Consulte P2

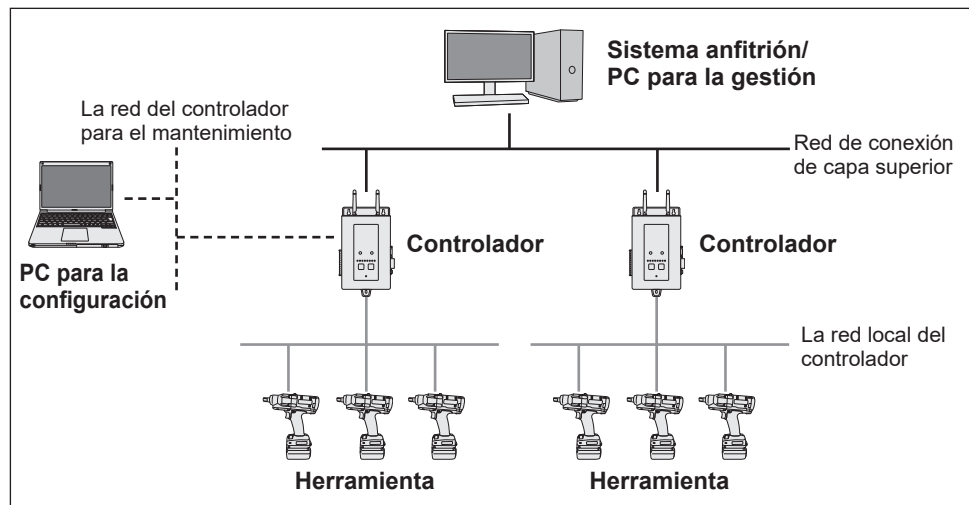
*2 Esto solo es compatible con la versión de firmware 2.03.00 o posterior.

Configuraciones de red típicas

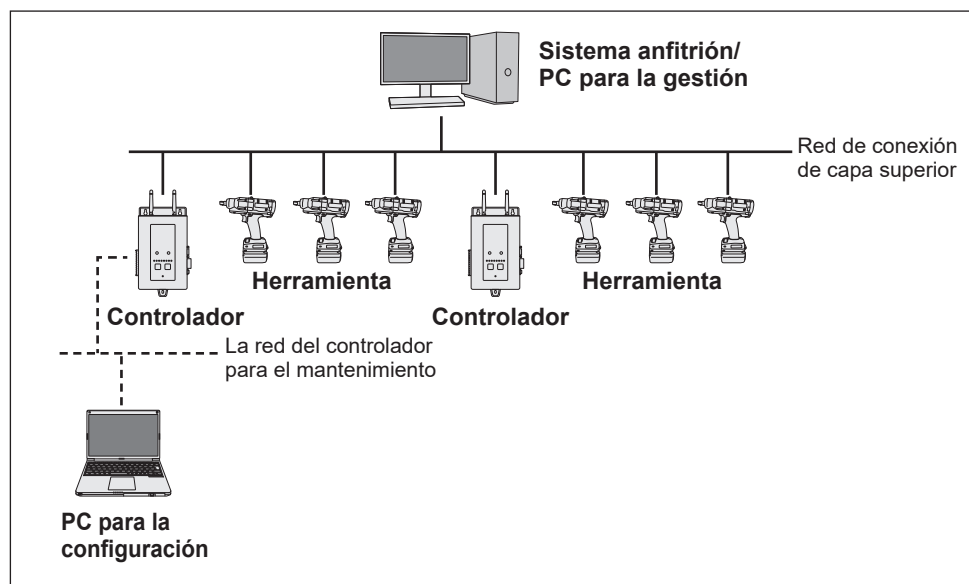
El controlador se puede utilizar en las 3 configuraciones siguientes.

■ No gestionar las direcciones IP de las herramientas

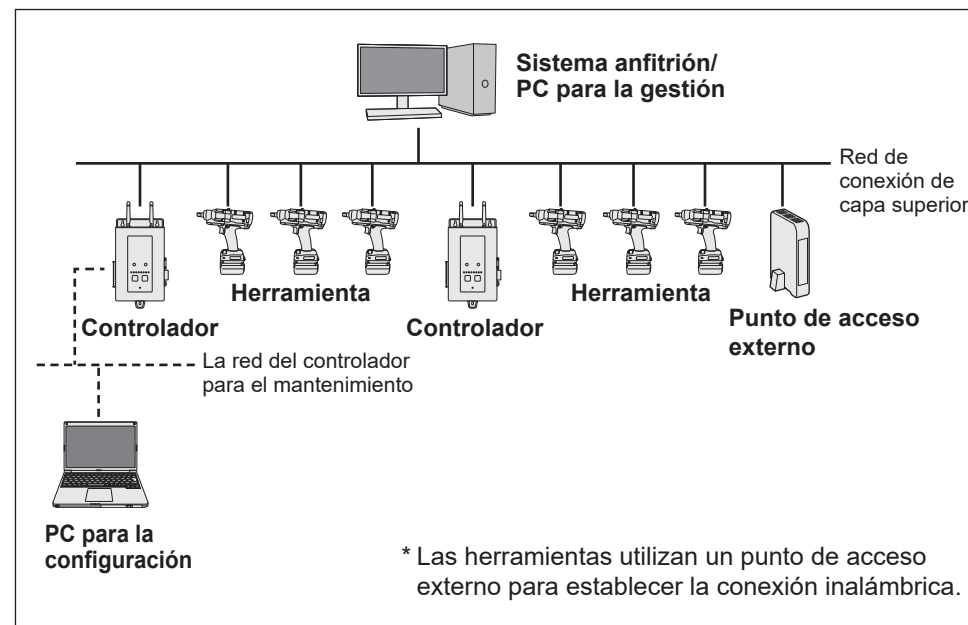
* Asignación automática (utilizando el punto de acceso incorporado en el controlador)



■ Gestión de las direcciones IP de las herramientas (utilizando el punto de acceso integrado en el controlador)



■ Reconocimiento de las direcciones IP de las herramientas (mediante puntos de acceso externos)



* Utilice el sistema dentro de su red local (sin conexión a Internet).

* Asegúrese de comprobar la configuración de la dirección IP para la red del controlador antes de empezar a utilizarlo. (Cambie el valor predeterminado si es necesario)

HERRAMIENTAS CONECTABLES/PRECAUCIONES PARA LA INSTALACIÓN

Lista de modelos de herramienta aplicables

Modelos que pueden registrarse	EYFNH1WC/WP*1 EYFMH1WC/WP EYFMH2WC/WP
--------------------------------	---

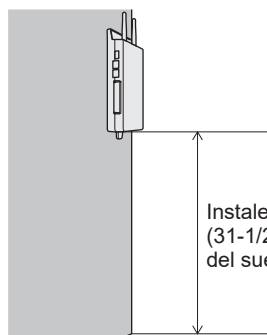
*1 Esto solo es compatible con la versión de firmware 2.02.00 o posterior.

Precauciones para la instalación

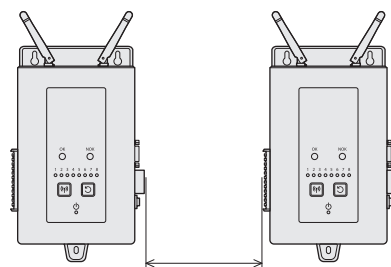
Instale el controlador 80 cm (31-1/2") o más por encima del suelo. Mantenga 10 cm (3-15/16") o más entre los controladores instalados. (1 m (39-3/8") o más recomendado) Mantenga los obstáculos alejados de las antenas del controlador instalado. El controlador posee 2 antenas de diversidad. Mantenga los obstáculos alejados de ambas antenas.

⚠ PRECAUCIÓN

Para una instalación segura, utilice tornillos de madera con un diámetro nominal de 3.5 mm (1/8") a 4.1 mm (5/32").



Instale el controlador 80 cm (31-1/2") o más por encima del suelo.

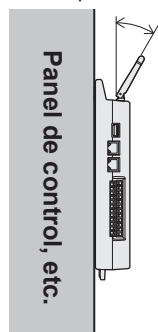


Mantenga 10 cm (3-15/16") o más entre los controladores instalados.

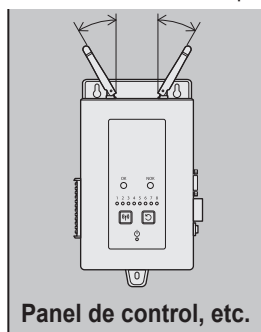
Ajuste los ángulos de las antenas si la comunicación es inestable.

* Especialmente en el caso del controlador instalado en un panel metálico, el ajuste de los ángulos de las antenas puede mejorar la estabilidad de la comunicación.

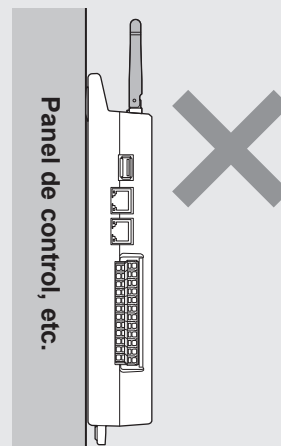
Incline las antenas de 30 a 45° con respecto a la pared.



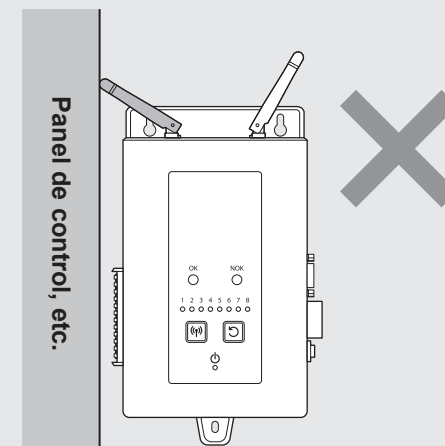
Incline las antenas de 30 a 45° hacia afuera, vistas desde la parte delantera.



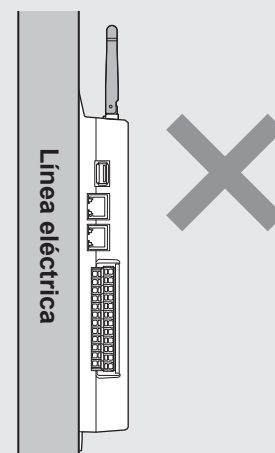
■ Evite la siguiente instalación.



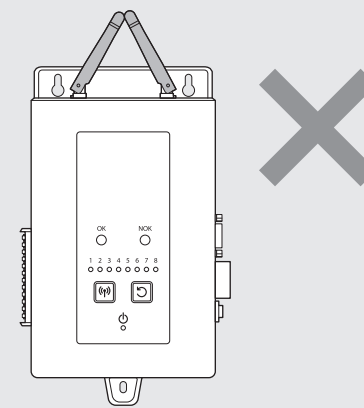
La antena está en paralelo con el panel de control (panel metálico) en la parte trasera.



La antena está en contacto con el panel de control (panel metálico).



El controlador se instala muy cerca de una línea eléctrica.



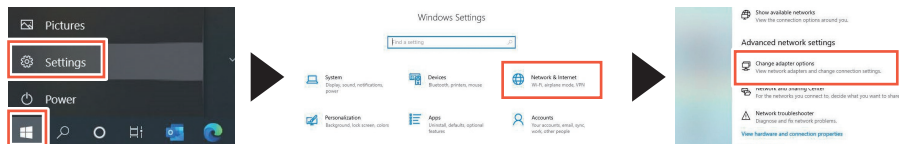
Las antenas están en contacto entre sí.

PREPARACIÓN ANTES DEL USO

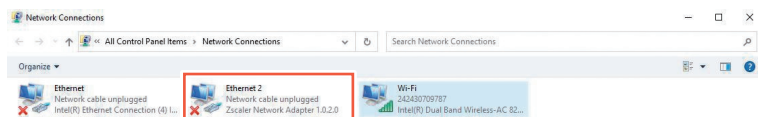
Ajustes de red en el PC para la configuración

Establezca los ajustes de red en el PC para la configuración como se indica a continuación cuando lo conecte y el controlador por primera vez.

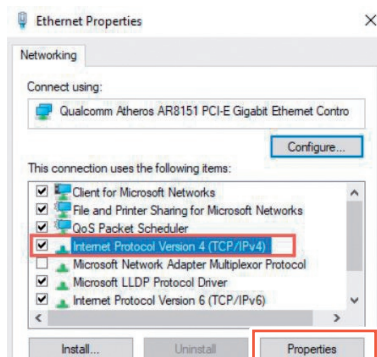
- 1 Haga clic en  en la parte inferior izquierda de la pantalla y haga clic en  (Settings) - [Network & Internet] - [Change adapter options].



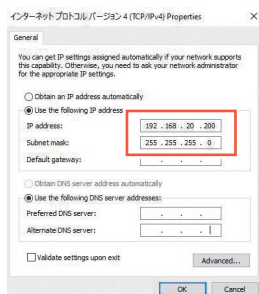
- 2 Haga clic con el botón derecho en el dispositivo a conectar y haga clic en [Properties].



- 3 Seleccione "Internet Protocol Version 4" y haga clic en [Properties].



- 4 Ajuste la "IP address" y la "Subnet mask" como se indica a continuación.



IP address	192 . 168 . 20 . 200
Subnet mask	255 . 255 . 255 . 0

- * Si ha cambiado la dirección IP del controlador tras la conexión inicial, habilite la conexión devolviendo los ajustes de red (dirección IP y máscara de subred) a su estado inicial en el PC para la configuración. En ese momento, configure la dirección IP de modo que el controlador y el PC para la configuración pertenezcan a la misma red.
- * Anote y conserve los ajustes de red del PC para la configuración (dirección IP y máscara de subred) antes de modificarlos.
- * Se recomienda dejar la puerta de enlace predeterminada sin especificar (en blanco).

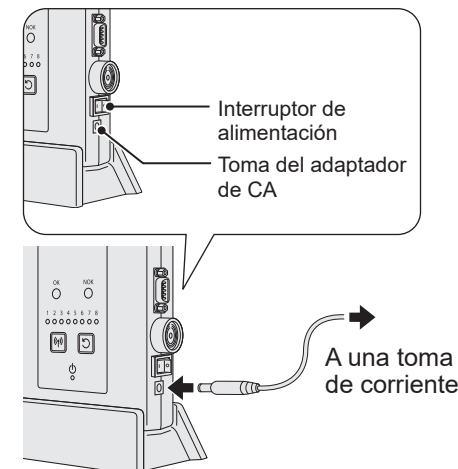
Visualización de la pantalla de ajustes

Para configurar el controlador, acceda a él a través de un navegador web. Visualice la pantalla de ajuste del controlador tal como se indica a continuación.

Cuando utilice el controlador por primera vez, retire la película protectora de la pila de botón.

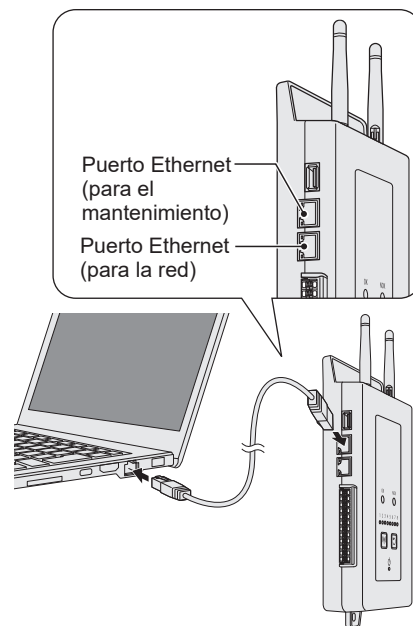
- 1 Encienda el controlador.

- 1 Conecte el adaptador de CA al controlador y conecte el enchufe de alimentación a una toma de corriente.
- 2 Encienda el Interruptor de alimentación del controlador.
 - * Tarda unas decenas de segundos en iniciarse.
 - * Durante la puesta en marcha, la lámpara de fijación OK, la lámpara de fijación NOK y las lámparas de comunicación (del N.º 1 al N.º 8) parpadean simultáneamente.
 - * No conecte cables LAN.



- 2 Conecte el controlador al PC para la configuración con un cable LAN.

- 1 Conecte un cable LAN al puerto Ethernet del controlador.
 - * El controlador tiene 2 puertos Ethernet: uno para el mantenimiento y uno para las redes. Utilice el de mantenimiento para la primera conexión.
- 2 Conéctese al PC para la configuración con el cable LAN.



3 Inicie un navegador web en el PC para la configuración y acceda al controlador.

- 1 Inicie un navegador web en el PC para la configuración. (Se recomienda Microsoft Edge)
- 2 Introduzca la dirección IP del controlador en la barra de direcciones del navegador web.

* La dirección IP predeterminada para el puerto Ethernet (para mantenimiento) es "192.168.20.10".

En la barra de direcciones del navegador web, introduzca

"http://192.168.20.10/controller"

* Introducir solo "192.168.20.10/controller" también permite el acceso.

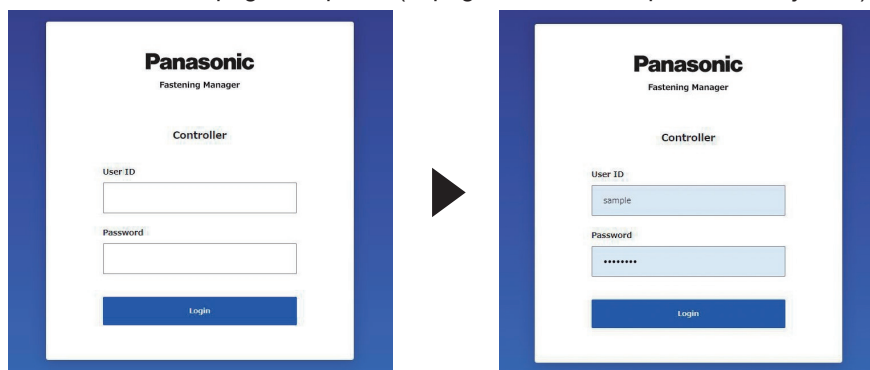
* Para obtener información sobre cómo acceder a través del puerto Ethernet (para la red), consulte "Conexión a través de la red". **Consulte P21**

* La dirección IP también debe ajustarse en el PC para la configuración.

- 3 En la pantalla de inicio de sesión que aparece, introduzca la ID de usuario y la contraseña.

* La ID de usuario y la contraseña para el inicio de sesión inicial se muestran a continuación.

- 4 Se muestra la página superior (la página inicial de la pantalla de ajustes).



ID de usuario y contraseña para el inicio de sesión inicial

Inicie sesión con la ID de usuario y la contraseña siguientes.

■ ID de usuario: **root**

■ Contraseña: **abcABC123**

* El tipo de cuenta para el inicio de sesión inicial es "default".

Para los tipos de cuenta, consulte "Tipos de cuenta (Autoridades)". **Consulte P19**

* Solamente es posible la creación de la cuenta cuando inicia sesión con la ID de usuario y la contraseña anteriores. Cree una nueva cuenta antes de iniciar el uso.

* Por seguridad, se recomienda cambiar la contraseña anterior después del inicio de sesión inicial.

Tipos de cuenta (Autoridades)

A continuación se indican los tipos de cuenta. Utilícelas de acuerdo con las aplicaciones.

Tipo de cuenta	Función
Predeterminado	• Para el inicio de sesión inicial. Consulte P18 • Añadir o cambiar una cuenta de usuario.
Administrator	• Visualización del historial de fijación. • Configuración del controlador. • Configuración de herramientas. • Añadir o cambiar una cuenta de usuario. * Cree al menos una cuenta de administrador.
General	• Visualización del historial de fijación (incluyendo la visualización del monitor de trabajo).

Se pueden registrar hasta 10 cuentas.

De este modo, más de un operador puede iniciar sesión simultáneamente.

* Solo una cuenta puede iniciar sesión como administrador al mismo tiempo.

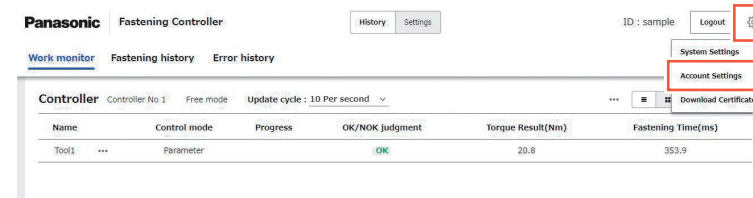
Cuando se intentan realizar múltiples accesos, la última sesión tiene prioridad.

Creación de una cuenta de usuario

Cree una nueva cuenta antes de iniciar el uso.

- 1 En la página superior (la página inicial de la pantalla de ajustes), haga clic en la tecla de opción de la parte superior derecha y seleccione "Account Settings".

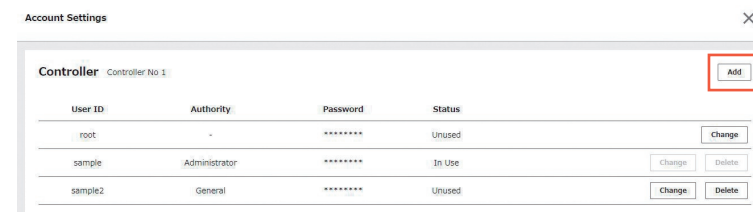
Se visualiza la pantalla "Account Settings".



- 2 En la pantalla "Account Settings", haga clic en [Add].

Se visualiza la pantalla "Add account".

• Haga clic en [Change] para cambiar la cuenta y [Delete] para eliminarla.



3 Introduzca la “User ID” y la “Password”, seleccione “Authority” y haga clic en [Add].

- * Cree una cuenta de administrador para configurar las herramientas.
- * Para una contraseña, utilice siempre una combinación de 3 o más tipos: mayúsculas, minúsculas, números y símbolos.

[Referencia] Si pierde la ID de usuario o la contraseña

■ Cuenta general

- [Método 1] Inicie sesión como administrador y realice cambios en la cuenta correspondiente.
- * Un usuario general no puede cambiar la ID del usuario y la contraseña y debe solicitar a un administrador que los cambie.
- [Método 2] Inicie sesión con una cuenta de administrador recién creada y realice cambios en la cuenta en cuestión.
- * Inicie sesión con la ID del usuario y la contraseña del inicio de sesión inicial y cree una nueva cuenta de administrador. **Consulte P18**

■ Cuenta de administrador

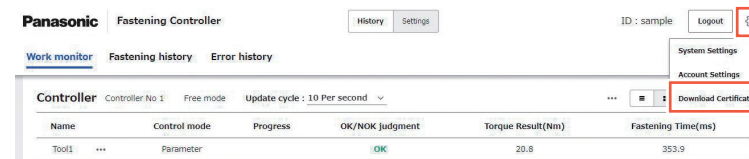
- A) Cuando se han creado varias cuentas de administrador
- [Método 1] Inicie sesión con otra cuenta de administrador y realice cambios en la cuenta en cuestión.
- [Método 2] Inicie sesión con una cuenta de administrador recién creada y realice cambios en la cuenta en cuestión.
- * Inicie sesión con la ID del usuario y la contraseña del inicio de sesión inicial y cree una nueva cuenta de administrador. **Consulte P18**
- [Método 3] Inicialice los ajustes si ha perdido las ID y las contraseñas de todas las cuentas de administrador. **Consulte P85**
- B) Cuando solo se ha creado una cuenta de administrador
- [Método 1] Inicie sesión con una cuenta de administrador recién creada y realice cambios en la cuenta en cuestión.
- * Inicie sesión con la ID del usuario y la contraseña del inicio de sesión inicial y cree una nueva cuenta de administrador. **Consulte P18**
- [Método 2] Inicialice los ajustes si ha perdido las ID y las contraseñas de todas las cuentas de administrador. **Consulte P85**

Obtener un certificado

Es necesario un certificado para acceder al controlador a través del puerto Ethernet (para la red). Puede obtener un certificado como se indica a continuación.

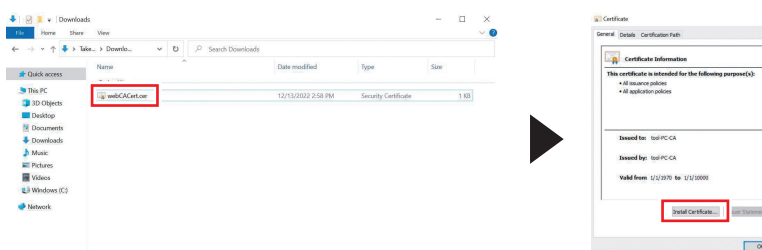
1 En la página superior (la página inicial de la pantalla de ajustes), haga clic en la tecla de opción de la parte superior derecha y seleccione “Download Certificate”.

Se ha descargado un dato de certificado en el PC para la configuración.

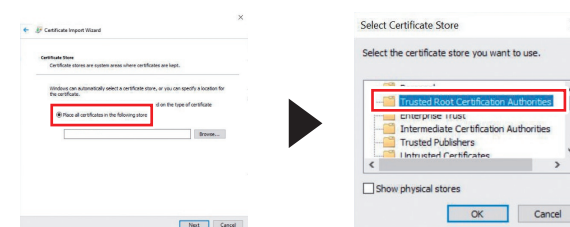


2 Instale el certificado en el “PC para la configuración utilizado para acceder al controlador a través de la red”.

- ① Haga doble clic en el dato del certificado descargado y seleccione “Install Certificate”.



- ② Seleccione “Place all certificates in the following store” y luego seleccione “Trusted Root Certification Authorities”.



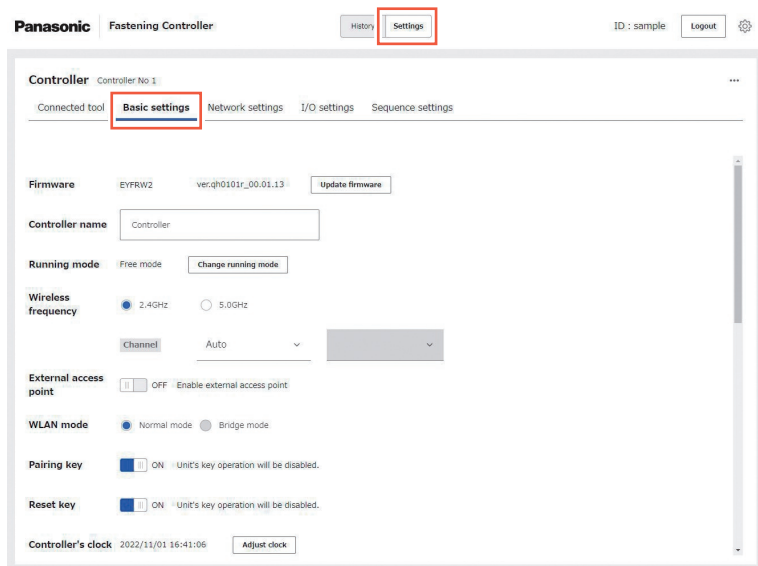
Conexión a través de la red

En la barra de direcciones del navegador web, introduzca “https://XXX.XXX.XXX.XXX/controller” para conectar el controlador a través del puerto Ethernet (para red).

- * “XXX.XXX.XXX.XXX” es una dirección IP.
- * La dirección IP predeterminada es “192.168.0.10”. Si ha cambiado la dirección predeterminada, introduzca la que ha cambiado. **Consulte P26**

Ajustes básicos

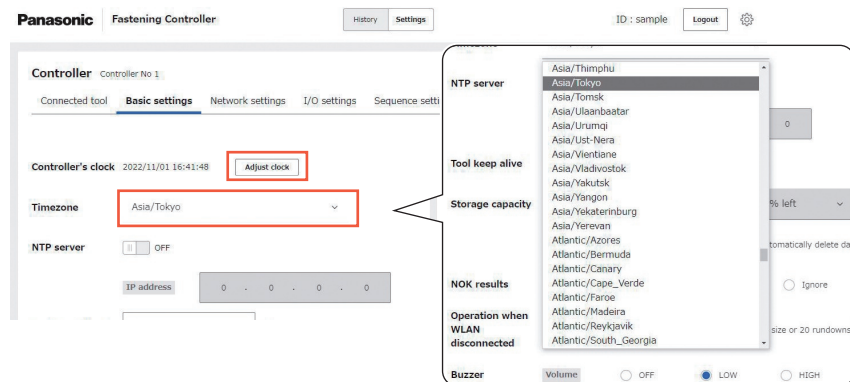
En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Basic settings”.
Puede configurar el controlador.



Ajuste de la hora

Seleccione “Timezone” y haga clic en [Adjust clock].
La hora se actualiza.

- La hora no está ajustada todavía en el momento del envío. Asegúrese de ajustar la hora cuando utilice el controlador por primera vez.

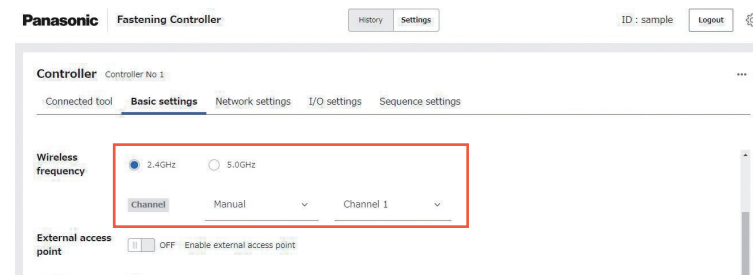


* Si utiliza un servidor NTP, introduzca la dirección IP.

Ajuste de la frecuencia de radio y del canal

Puede establecer la frecuencia a utilizar.
Seleccione “2.4GHz” o “5GHz” y, a continuación, el canal que desea utilizar.

- * Los canales seleccionables difieren entre “2.4GHz” y “5GHz”.
- * Puede ajustar “Auto Channel”.
El controlador selecciona automáticamente los canales disponibles en el entorno circundante cuando se activa.
El ajuste puede ser efectivo contra interferencias de radio.
- * Cuando instale múltiples controladores uno cerca de otro, no establezca canales adyacentes.



Elementos de ajuste

Firmware

Se muestra la versión de firmware del controlador.
Haga clic en [Update firmware] para actualizar el firmware.
Para saber cómo actualizar, consulte “Actualización del firmware”. **Consulte P87**

Controller name

Puede registrar el nombre del controlador.
Use un máximo de 32 caracteres alfanuméricos.
[Predeterminado] Controller
[Rango de ajuste] Hasta 32 caracteres alfanuméricos
* Para los símbolos, solo se pueden utilizar “-” (guión), “_” (guión bajo) y “ ” (espacio de media anchura).

Running mode

Seleccione el modo de funcionamiento del controlador.
[Predeterminado] Free mode
[Rango de ajuste] Free mode / Repeat mode (Basic mode / Sequence mode) / External control mode

Wireless frequency

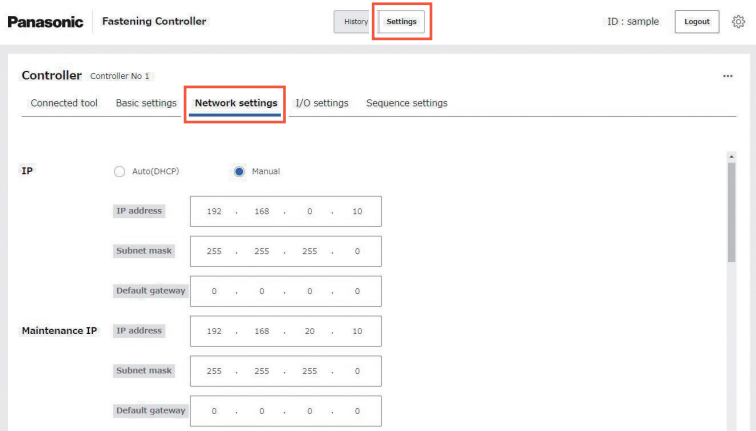
Seleccione el canal de frecuencia que se utilizará para la comunicación inalámbrica.
[Predeterminado] 2.4GHz
[Rango de ajuste] 2.4GHz (Auto / Channel 1 a 13) / 5GHz (Auto / Channel 36, 40, 44, 48)

External access point
Puede habilitar la comunicación a través de un punto de acceso externo. Consulte P69
[Predeterminado] OFF (deshabilitado)
[Rango de ajuste] OFF (deshabilitado)/ON (habilitado)
* WLAN mode: Este ajuste es para el funcionamiento sin utilizar un punto de acceso externo.
Normal mode: cuando no se gestionan las direcciones IP de la herramienta (asignación automática)
Bridge mode: cuando se gestionan (especifican) las direcciones IP de la herramienta.
Pairing key
Puede habilitar la tecla Emparejamiento.
[Predeterminado] ON (habilitado)
[Rango de ajuste] OFF (deshabilitado)/ON (habilitado)
Reset key
Puede habilitar la tecla Reiniciar.
[Predeterminado] ON (habilitado)
[Rango de ajuste] OFF (deshabilitado)/ON (habilitado)
Controller's clock
Ajuste el reloj del controlador.
Haga clic en [Adjust clock] para actualizar la hora.
Timezone
Puede ajustar la zona horaria deseada al ajustar el reloj del controlador.
NTP server
Establezca un servidor NTP si utiliza el ajuste automático del reloj.
Tool keep alive
Establezca el intervalo de tiempo en el que el controlador comprueba la disponibilidad de las herramientas en el modo de comunicación inalámbrica.
Las herramientas que no responden se detectan como fuera de línea y se desconectan.
[Predeterminado] 30 s
[Rango de ajuste] de 10 s a 3600 s

Storage capacity
Habilita o deshabilita la notificación de baja capacidad de almacenamiento y ajusta el comportamiento en caso de escasez de capacidad.
[Predeterminado] Notificación -OFF,
Funcionamiento cuando la capacidad es insuficiente -Automatically delete data
[Rango de ajuste] Notificación -OFF/ON (capacidad restante 10/20/30/40/50%)
Funcionamiento cuando la capacidad es insuficiente -Suspend operation / Automatically delete data
El ajuste predeterminado es "Automatically delete data".
Piense bien cómo manejar los datos antes de seleccionar "Suspend operation" según sea necesario.
NOK results
Seleccione cómo manejar los resultados de los fallos de fijación.
[Predeterminado] Store data only
[Rango de ajuste] Report to system / Store data only / Ignore
Operation when WLAN disconnected
Seleccione el comportamiento en caso de interrupción temporal de la comunicación inalámbrica.
[Predeterminado] Suspend tool
[Rango de ajuste] Suspend tool / Enable fastening (Until batch size or 20 rundowns)
Para más información, consulte "COMPORTAMIENTO DE LAS HERRAMIENTAS CON LA COMUNICACIÓN INALÁMBRICA DESCONECTADA". Consulte P76
Buzzer
Seleccione el volumen y el significado del zumbador.
[Predeterminado] Volume - LOW,
Beep - Todo marcado
[Rango de ajuste] Volume - OFF/LOW/HIGH,
Beep - Marque o desmarque cada elemento
Barcode reader settings
Puede conectar un lector de códigos barras para añadir información de lectura a los datos del historial de fijación.
[Reading Test] Muestra la información leída por el lector de códigos de barras.
[Bluetooth settings] Estos ajustes se utilizan al conectar un lector de códigos de barras tipo Bluetooth.
El botón "Search" muestra los dispositivos conectables.
Utilice "Pairing" para seleccionar un dispositivo a conectar.
Si ya está conectado, se mostrará la dirección MAC/nombre del dispositivo.
Puede desconectarlo seleccionando "Cancel registration".

Ajustes de red

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Network settings”. Puede realizar los ajustes de red del controlador.



Elementos de ajuste

IP
Establezca la dirección IP del Puerto Ethernet (para la red).
[Predeterminado] Manual
[Rango de ajuste] Auto (DHCP) / Manual
* Para “Manual”
[Predeterminado] IP address - 192.168.0.10 Subnet mask - 255.255.255.0 Default gateway - 0.0.0.0
Maintenance IP
Establezca la dirección IP del Puerto Ethernet (para el mantenimiento).
[Predeterminado] IP address - 192.168.20.10 Subnet mask - 255.255.255.0 Default gateway - 0.0.0.0
WLAN
Ajuste la dirección IP (en el lado del controlador) para la comunicación inalámbrica con las herramientas.
[Predeterminado] IP address - 192.168.100.1 Subnet mask - 255.255.255.0 Default gateway - 0.0.0.0

Atlas Open Protocol
Configure los parámetros relacionados con el Protocolo Abierto Atlas. Para más detalles, consulte “Conexión a través de la Comunicación de Protocolo Abierto”. Consulte P57
RS232C
Este es un ajuste específico de TOYOTA MOTOR CORPORATION. Es posible el control desde dispositivos externos. [Predeterminado] Disable [Rango de ajuste] Disable / Enable
Step flow after tightening NG
Este ajuste determina si se puede pasar al siguiente apriete en caso de que se produzca un resultado NG de apriete. [Predeterminado] Keep [Rango de ajuste] Next (El siguiente apriete puede realizarse). / Keep (No se puede realizar el siguiente apriete).
Access point
Establezca el punto de acceso interno para la comunicación inalámbrica con las herramientas. [Predeterminado] SSID - Número de modelo del controlador-Dirección MAC Security - WPA2 [Rango de ajuste] SSID - Un máximo de 32 caracteres alfanuméricos Security - WPA2
External access point
Establezca el punto de acceso externo que desea utilizar. [Predeterminado] SSID - En blanco Security - En blanco Password - En blanco [Rango de ajuste] SSID - Un máximo de 32 caracteres alfanuméricos Security - Abierto/WPA2 Password - De 8 a 63 caracteres alfanuméricos * Para los símbolos, solo pueden utilizarse “””, “¥”, “,” y “” (comillas inversas). * La opción sólo está habilitada cuando “External access point” se ha ajustado en “ON” en el ajuste básico.

- Para las direcciones IP para “IP” y “Maintenance IP”, no utilice la misma subred. (Cuando configure un valor predeterminado (255.255.255.0) en “Subnet mask”, ajuste valores diferentes en la parte correspondiente a “192.168.0” o “192.168.20”).
- Solo se pueden activar “Atlas Open Protocol” y “RS232C”. No se pueden utilizar simultáneamente.

Inicio del modo Emparejamiento en el controlador

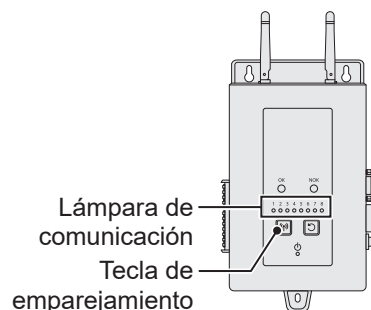
Puede poner el controlador en el modo de emparejamiento mediante “Uso de la tecla en la unidad” o “Ajuste en la pantalla de ajustes”. Durante 2 minutos del modo de emparejamiento, inicie el modo de emparejamiento en una herramienta dentro de la cobertura para establecer automáticamente el emparejamiento. Si el emparejamiento no se establece dentro del tiempo, el modo de emparejamiento finalizará.

* Después de intentar iniciar el emparejamiento, puede pasar algún tiempo hasta que el controlador entre en el modo de emparejamiento.

Uso de la tecla en la unidad

Utilice la tecla Emparejamiento en la unidad del controlador.

Seleccione la lámpara de comunicación del número sin registro (luz apagada) y mantenga pulsada la tecla de emparejamiento para acceder al modo de emparejamiento. Consulte el siguiente procedimiento para obtener más detalles.



(Para registrar la herramienta N.º 4)

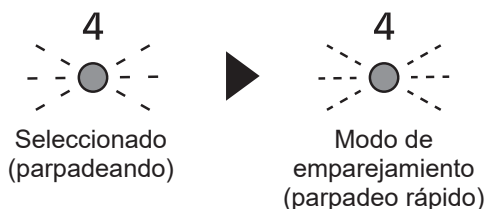
1 Pulse la tecla Emparejamiento en el controlador 4 veces para seleccionar la herramienta N.º 4.

La lámpara de comunicación N.º 4 parpadea.



2 Mientras el N.º 4 está seleccionado, mantenga pulsada la tecla Emparejamiento en el controlador para entrar en el modo de emparejamiento de la herramienta N.º 4.

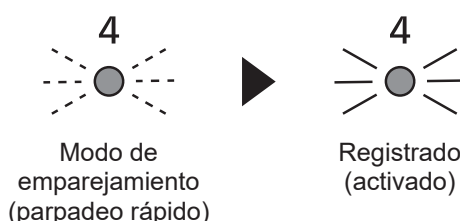
En el modo de emparejamiento, la Lámpara de comunicación N.º 4 comienza a parpadear rápidamente.



3 Opere la herramienta N.º 4 para establecer el emparejamiento.

La lámpara de comunicación N.º 4 permanece encendida.

Para saber cómo operar la herramienta, consulte “Inicio del modo de emparejamiento en una herramienta”. **Consulte P30**



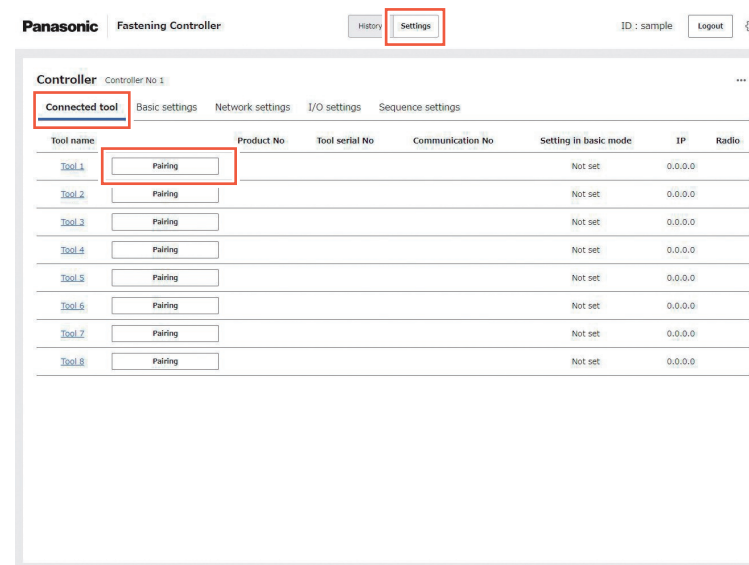
Ajuste en la pantalla de ajustes

En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”.

En la pantalla “Connected tool”, haga clic en [Pairing] del número de herramienta deseado.

Después de que el controlador entre en el modo de emparejamiento, realice el procedimiento descrito en “Inicio del modo de emparejamiento en una herramienta”.

Consulte P30



<Para referencia> Sustituir con una herramienta de recambio

Cuando sustituya una herramienta emparejada defectuosa por una nueva con el mismo número de modelo, cancele el emparejamiento **Consulte P30** y, a continuación, realice el emparejamiento **Consulte P28** para que los parámetros de fijación y otros ajustes puedan transferirse automáticamente.

* Para emparejar con una herramienta con un número de producto diferente, cancele el emparejamiento para borrar la información de emparejamiento actual antes de emparejar con ella. **Consulte P34**

Pantalla después de completar el emparejamiento

Después de completar el emparejamiento, si la pantalla de ajuste no muestra la información de la herramienta emparejada, realice la actualización de la visualización en la pantalla de ajuste.

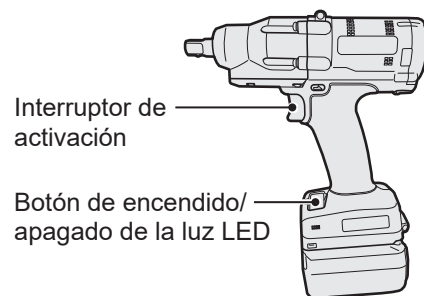
* En el “Bridge mode” o cuando “External access point” está habilitado, ajuste la dirección IP de la herramienta antes de iniciar el registro de emparejamiento.

Inicio del modo de emparejamiento en una herramienta

Ponga el controlador en el modo de emparejamiento antes de iniciar el modo de emparejamiento en una herramienta.

Procedimiento

- Coloque la batería. Mientras mantiene pulsado el botón de activación/desactivación de la luz LED, tire del interruptor de activación.**
La herramienta entra en el modo de emparejamiento.
La comunicación inalámbrica se establece automáticamente y se completa el registro de emparejamiento.
* Para más información, consulte el Manual de instrucciones de la herramienta.
* Si el emparejamiento falla, cancele el emparejamiento en el controlador y, a continuación, vuelva a intentarlo.

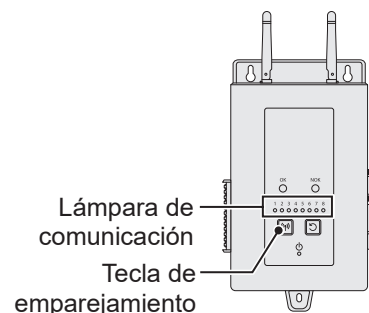


Cancelación del emparejamiento

Puede cancelar el registro de emparejamiento en el controlador mediante "Uso de la tecla en la unidad" o "Ajuste en la pantalla de ajustes".

Uso de la tecla en la unidad

Utilice la tecla Emparejamiento en la unidad del controlador.
Seleccione la lámpara de comunicación del número de herramienta con la que desea cancelar el registro (luz encendida) y mantenga pulsada la tecla de emparejamiento para cancelar el registro.
Consulte el siguiente procedimiento para obtener más detalles.



(Para cancelar la herramienta N.º 4)

- Pulse la tecla Emparejamiento en el controlador 4 veces para seleccionar la herramienta N.º 4.**
La lámpara de comunicación N.º 4 parpadea.



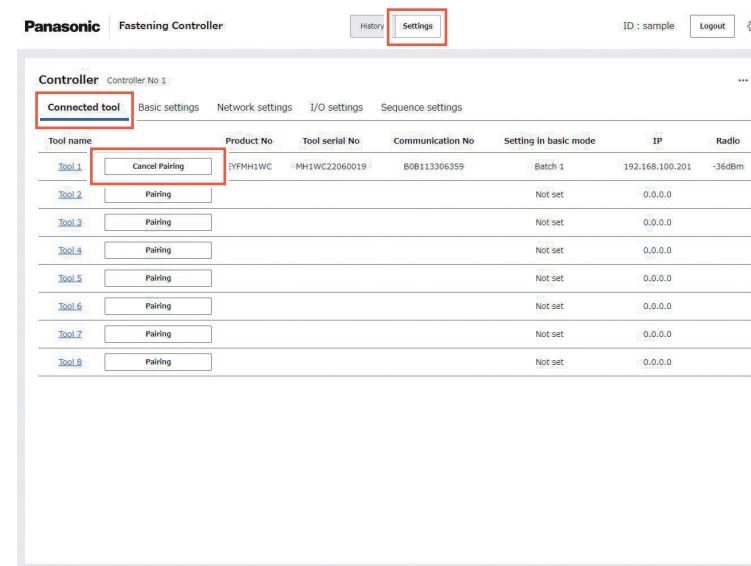
- Mientras el N.º 4 está seleccionado, mantenga pulsada la tecla Emparejamiento en el controlador para cancelar el registro de emparejamiento de la herramienta N.º 4.**

Cuando se cancela el emparejamiento, la lámpara de comunicación N.º 4 deja de parpadear y se apaga.



Ajuste en la pantalla de ajustes

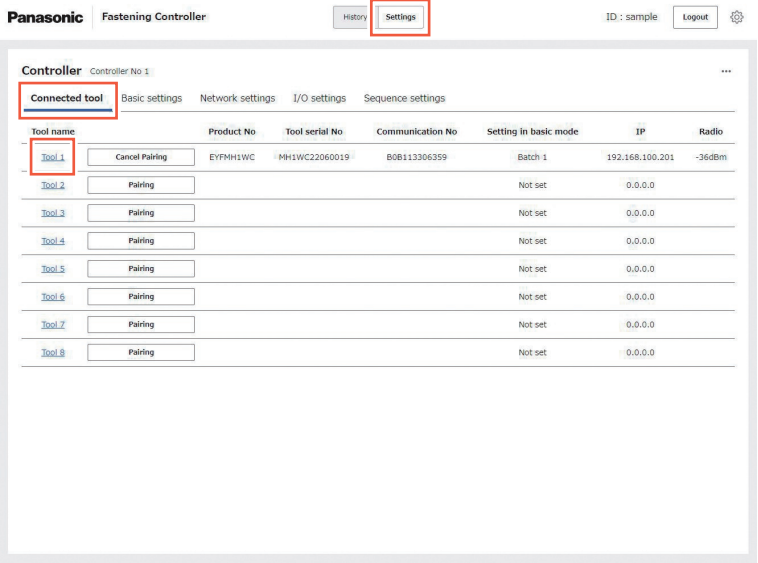
En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña "Connected tool".
En la pantalla "Connected tool", haga clic en [Cancel Pairing] del número de herramienta deseado.



* Si el controlador no puede comunicarse con la herramienta debido a que la herramienta está apagada o a cualquier otro motivo, marque [Force to unpair] en el cuadro de diálogo de confirmación de cancelación del emparejamiento.

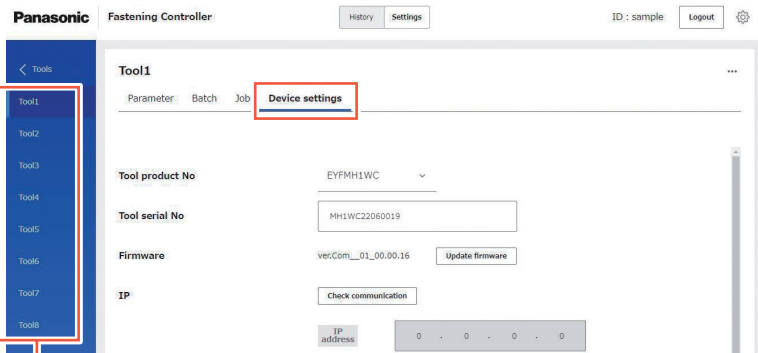
Visualización de la pantalla Herramienta

En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”.
En la pantalla “Connected tool”, haga clic en el número de herramienta deseado.
Se visualiza la pantalla para el número de herramienta.



Visualización de la pantalla de ajustes de la herramienta

Desde la pestaña “Device settings” de la pantalla correspondiente al número de herramienta, puede realizar los ajustes básicos de la herramienta e introducir parámetros comunes.
* Para cambiar la herramienta, seleccione la deseada en la lista de herramientas.



Lista de herramientas

Elementos de ajuste de la herramienta

Tool product No
Seleccione el número de producto de la herramienta. [Predeterminado] En blanco [Rango de ajuste] Seleccionable desde el menú desplegable * Se selecciona automáticamente si se establece el emparejamiento de antemano. * El número de producto de la herramienta no se puede cambiar después del emparejamiento. Cancele el emparejamiento y, a continuación, cámbielo.
Tool serial No
Puede ajustar y visualizar la identificación de la unidad de la herramienta. [Predeterminado] 5 dígitos de identificación del modelo + 8 dígitos del número de serie (2 dígitos del año de fabricación + 2 dígitos del mes + 4 dígitos del lote de producción) [Rango de ajuste] De 13 a 16 caracteres alfanuméricos * Es posible que el número de modelo no se reconozca correctamente si se cambia la información. No la cambie a menos que lo requiera la regla de administración.
Firmware
Se muestra la versión de firmware de la parte de comunicación de la herramienta. Haga clic en [Update firmware] para actualizar el firmware. Para saber cómo actualizar, consulte “Actualización del firmware”. Consulte P87
IP
Ajuste la dirección IP (en el lado de la herramienta) para la comunicación inalámbrica con las herramientas. [Predeterminado] IP address - 192.168.100.201 (Herramienta 1) a 208 (Herramienta 8) Subnet mask - 255.255.255.0 Default gateway - 0.0.0.0 * Todos se convierten en “0.0.0.0” en el Bridge mode o cuando “External access point” está habilitado.
Tool’s clock
Se visualiza el reloj de la herramienta. Haga clic en [Adjust to controller] para ajustar la hora.

• Para otros elementos de ajuste, consulte el Manual de instrucciones de la herramienta.

Eliminación de la información de registro

Para detener el uso de la herramienta o emparejar una herramienta con un número de producto diferente, borre la información de emparejamiento.

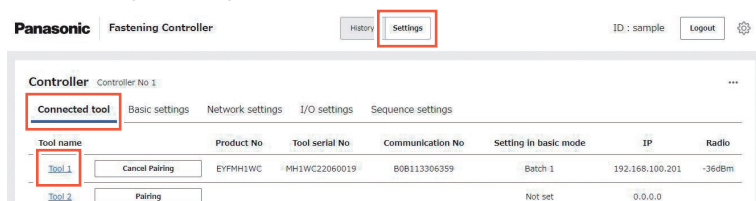
* Cancele el emparejamiento de antemano.

- 1 En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”.

Aparece la pantalla “Connected tool”.

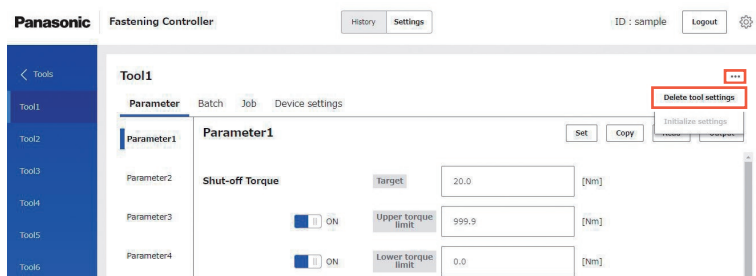
- 2 En la pantalla “Connected tool”, haga clic en el número de herramienta deseado.

Se visualiza la pantalla para el número de herramienta.

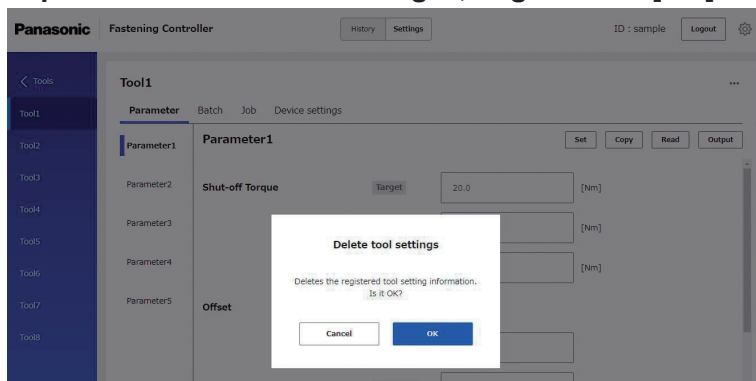


- 3 Haga clic en ... (tecla de opción de la herramienta) y, a continuación, [Delete tool settings].

Se visualiza la pantalla “Delete tool settings”.



- 4 En la pantalla “Delete tool settings”, haga clic en [OK].



Restablecer los ajustes de fábrica

Puede restaurar una herramienta a sus ajustes de fábrica.

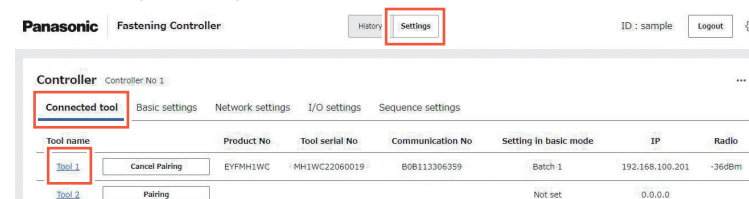
* Al restablecer se cancela el emparejamiento.

- 1 En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”.

Aparece la pantalla “Connected tool”.

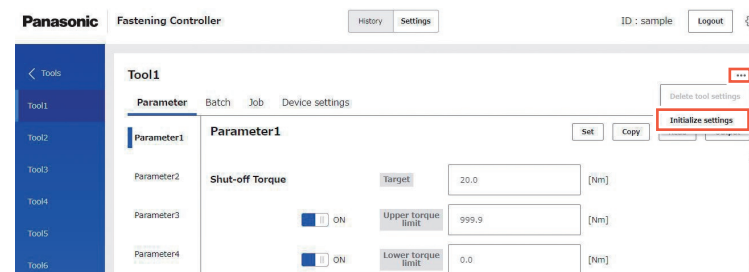
- 2 En la pantalla “Connected tool”, haga clic en el número de herramienta deseado.

Se visualiza la pantalla para el número de herramienta.

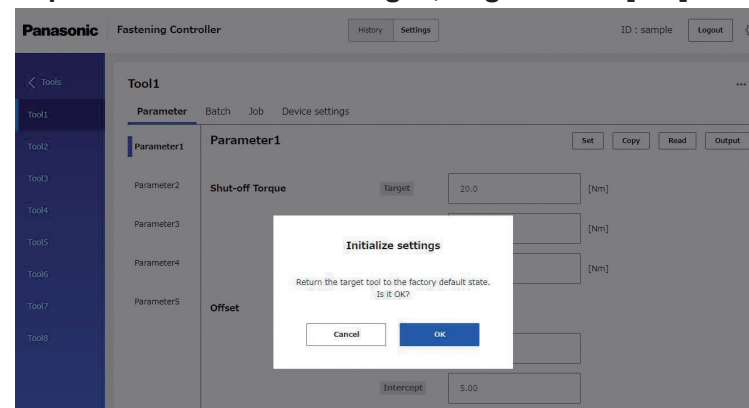


- 3 Haga clic en ... (tecla de opción de la herramienta) y, a continuación, [Initialize settings].

Se visualiza la pantalla “Initialize settings”.



- 4 En la pantalla “Initialize settings”, haga clic en [OK].



Ajuste de parámetros

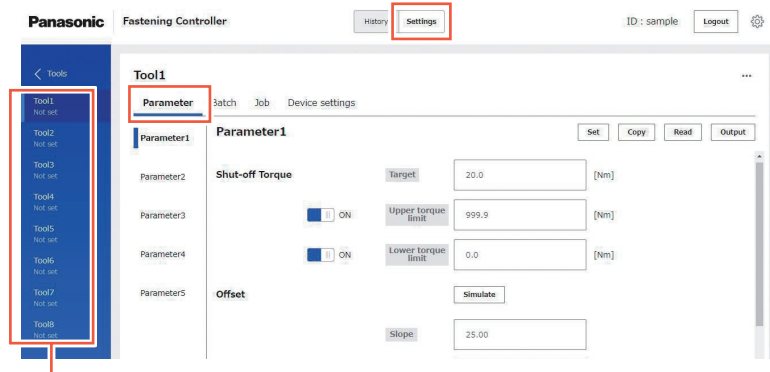
En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”.

En la pantalla “Connected tool”, haga clic en el número de herramienta deseado.

En la pantalla del número de herramienta, seleccione “Parameter” para realizar los ajustes.

Puede ajustar cinco parámetros (parámetros del 1 a 5) para cada herramienta.

* Para cambiar la herramienta, seleccione la deseada en la lista de herramientas.

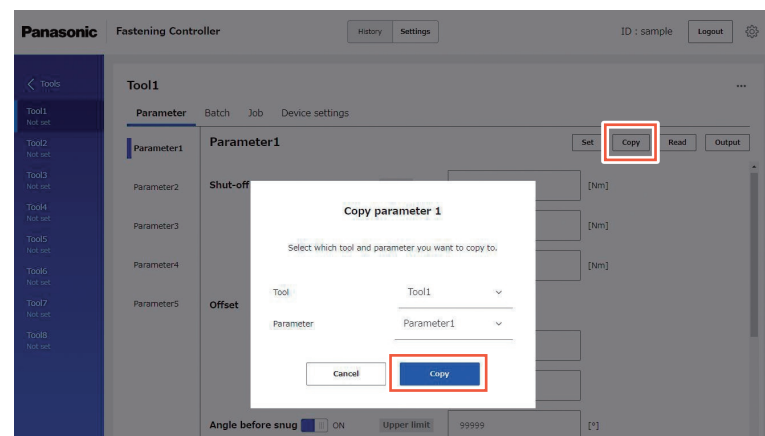


Lista de herramientas

Copia de parámetros

Puede copiar el parámetro establecido para crear un nuevo parámetro a partir de él o utilizarlo en otra herramienta.

En la pestaña “Parameter” de la pantalla para el número de herramienta, haga clic en [Copy] para visualizar la pantalla para copiar el parámetro. En la pantalla, seleccione el destino y haga clic en [Copy].

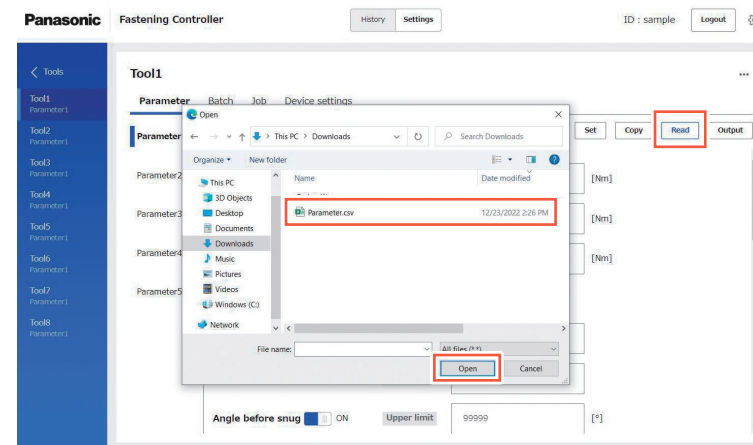


Carga de parámetros

Puede registrar un parámetro cargando un archivo de parámetro guardado en el PC para la configuración en el controlador.

También puede cargar un archivo de parámetro creado con “Tool Manager”.

Desde la pestaña “Parameter” en la pantalla para el número de herramienta, haga clic en [Read] y abra el archivo del parámetro.



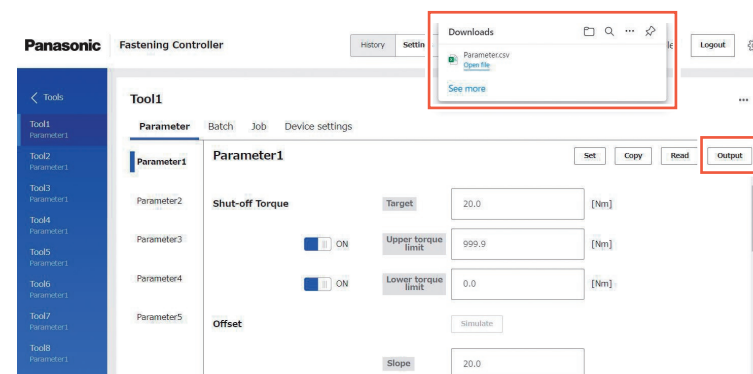
Exportar parámetros

Puede exportar el parámetro creado al PC para la configuración.

Puede utilizar el archivo exportado como copia de seguridad, para copiarlo a otro controlador o moverlo a otro PC para la configuración.

Desde la pestaña “Parameter” en la pantalla para el número de herramienta, haga clic en [Output] y guarde el archivo del parámetro.

No edite el archivo del parámetro exportado.
De lo contrario, es posible que no se lea correctamente.



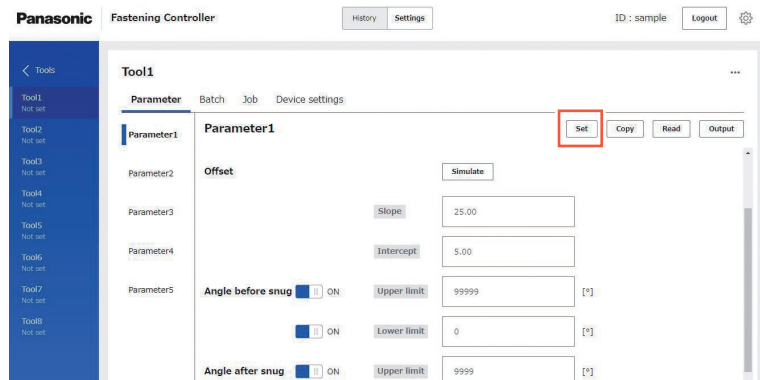
Registro de parámetros

Registre un parámetro para utilizarlo para controlar una herramienta en el “Free mode” del modo de funcionamiento de controlador.

* No se utiliza en “Repeat mode” y “External control mode”.

(Para “Free mode”, “Repeat mode” y “External control mode”, consulte “Ajuste del modo de funcionamiento”. **Consulte P45**)

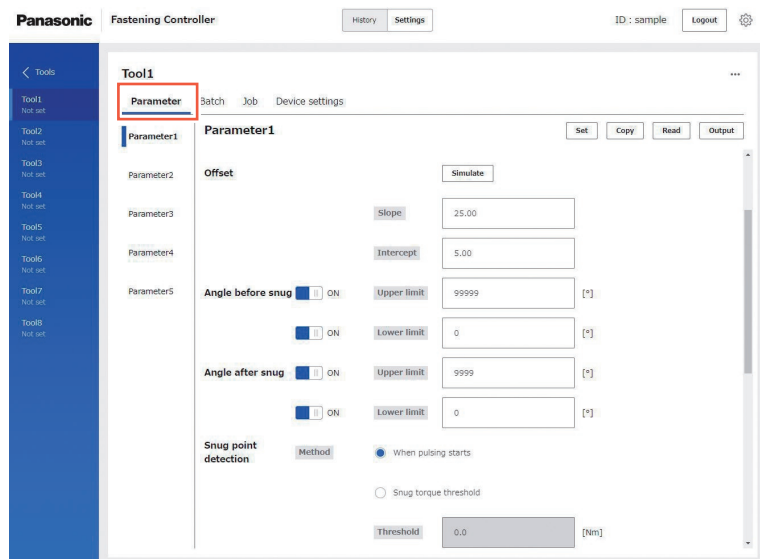
Desde la pestaña “Parameter” en la pantalla para el número de herramienta, haga clic en [Set].



Elementos del parámetro

Ajuste los elementos de los parámetros de fijación.

Para más información, consulte el Manual de instrucciones de la herramienta.

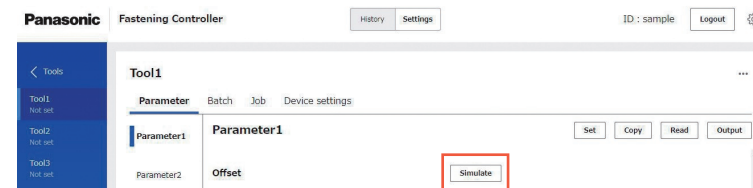


Ajuste de un desplazamiento (Parámetro, referencia ①)

Ajuste un desplazamiento para que coincida con el valor de salida del par con el valor medido real.

1 Desde la pestaña “Parameter” en la pantalla para el número de herramienta, haga clic en [Simulate] en “Offset”.

Se visualiza la página “Offset”.



2 Introduzca un valor a ajustar y haga clic en [Apply].

Introduzca “Socket length” y “Shut-off Torque”. Haga clic en [Apply] para enviar los valores introducidos a la herramienta. La herramienta entra en el modo de corrección (indicado como T2).

3 Lleve a cabo el trabajo real utilizando la herramienta y luego haga clic en [Get data].

Se añade un registro de historial de fijación a la lista del historial en la página “Offset”.

* Aunque la herramienta se prepara para la fijación (“modo C”) después de hacer clic en [Get data], no inicie la fijación normal hasta que se haya completado el ajuste del desplazamiento.

4 Mientras está seleccionado el registros del historial de fijación obtenido, introduzca un valor de par medido real (refijación) y haga clic en [Calculate].

Se calcula automáticamente una desviación para hacer coincidir el par de salida con el par real medido de la herramienta.

5 Confirme que el desplazamiento está actualizado y haga clic en [Apply].

El valor ajustado se envía a la herramienta.

6 Repita los pasos 3 a 5 hasta que la diferencia sea lo suficientemente pequeña.

* Mantenga los valores en la columna “%” dentro del intervalo del 95 % al 105 %.



[Acerca del T1 mode]

Comprobar [T1 mode] en la pantalla de ajuste del desplazamiento pone el controlador en el modo de salida mínimo.

(Anular la selección de [T1 mode] devuelve el controlador al “Offset Mode”).



T1 mode

[Descripción]

Puede comprobar si el control de par funciona correctamente cuando el par objetivo está cerca del límite inferior del rango de control de par del controlador. En este modo, el controlador se apaga en los recuentos mínimos por minuto (salida mínima).

En ese momento, el registro del historial de trabajo no se almacena.

Después de trabajar en este modo, utilice un medidor de par o una llave dinamométrica para confirmar que el par de salida del controlador no ha excedido el par de torsión objetivo.

La unidad del controlador puede no ser utilizable para algún trabajo si su par de salida excede el par objetivo en este modo.

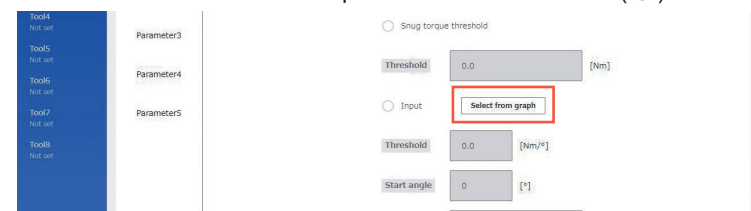
* La fijación por otras herramientas se suspende mientras se ajusta un desplazamiento.

■ Ajuste de un punto de ajuste (Parámetro, referencia ②)

Puede establecer un punto de ajuste basado en una forma de onda.

1 En la pestaña “Parameter” en la pantalla para el número de herramienta, haga clic en [Select from graph] en “Snug point detection”.

- Se visualiza la pantalla “Snug point detection” que muestra la forma de onda actual de la herramienta.
- Los datos del historial de fijación son necesarios a modo de referencia. Realice este ajuste al menos una vez después de la fijación.
- Puede cambiar la forma de onda para utilizarla con flechas (①).



2 Establezca un umbral en el gráfico.

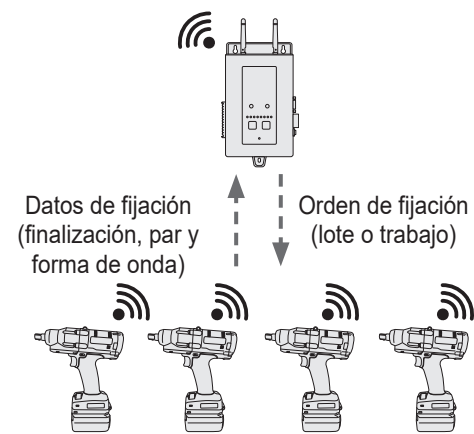
- La ventana principal (②) muestra una forma de onda completa y la ventana secundaria (③) amplía una parte específica desde toda la forma de onda.
- Puede cambiar el rango de la forma de onda mostrada en la ventana principal introduciendo los ángulos inicial y final en el “X-axis” (④) debajo del gráfico.
- Puede ajustar el ángulo de inicio de la detección del punto de ajuste (⑤) moviendo la barra vertical.
- Ajuste la posición del marco de selección (⑥) en la ventana principal para cambiar el rango de visualización de la subventana.
- Seleccione un umbral a ajustar en la ventana secundaria (③).



Control de la fijación mediante herramientas

El controlador puede controlar hasta 8 herramientas conectadas para la fijación. Recibe datos de fijación de cada tarea de sujeción y cuenta la cantidad fijada.

Número máximo de dispositivos conectados: 8



Combinaciones de control de fijación típicas

Puede crear distintas combinaciones de ajustes de control de fijación. Consulte las combinaciones típicas a continuación.

Modo	[Free mode]	[Repeat mode]																							
		[Basic mode]	[Sequence mode]																						
Criterio de aprobado	— (La cantidad no se especifica)	Se completa la fijación de la cantidad objetivo	Las herramientas completan la fijación de las cantidades objetivo respectivas en el orden especificado																						
[Batch] “Valor de ajuste único” (Fijación en la misma condición) * Un solo tipo de pieza de trabajo	A OK <table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>10 Nm</td><td>∞</td></tr></table> Parameter	Valor de ajuste	Cantidad objetivo	10 Nm	∞	A OK <table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>10 Nm</td><td>10</td></tr></table> Batch	Valor de ajuste	Cantidad objetivo	10 Nm	10	<div><div><div><div>A ①</div><div></div><div>OK</div></div><div>▶</div><div><div>B ②</div><div></div><div>OK</div></div></div><div><table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>10 Nm</td><td>10</td></tr></table><div data-kind="parent" data-rs="2">Batch y Sequence</div><table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>20 Nm</td><td>5</td></tr></table><div data-kind="ghost"></div></div></div>	Valor de ajuste	Cantidad objetivo	10 Nm	10	Valor de ajuste	Cantidad objetivo	20 Nm	5						
Valor de ajuste	Cantidad objetivo																								
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Valor de ajuste	Cantidad objetivo																								
20 Nm	5																								
[Job] Múltiples valores de ajuste (Fijación en diferentes condiciones) * Múltiples tipos de piezas de trabajo		A OK <table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>10 Nm</td><td>2</td></tr><tr><td>20 Nm</td><td>3</td></tr><tr><td>30 Nm</td><td>5</td></tr></table> Job	Valor de ajuste	Cantidad objetivo	10 Nm	2	20 Nm	3	30 Nm	5	<div><div><div><div>A ①</div><div></div><div>OK</div></div><div>▶</div><div><div>B ②</div><div></div><div>OK</div></div></div><div><table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>10 Nm</td><td>2</td></tr><tr><td>20 Nm</td><td>3</td></tr><tr><td>30 Nm</td><td>5</td></tr></table><div data-kind="parent" data-rs="2">Job y Sequence</div><table><tr><td>Valor de ajuste</td><td>Cantidad objetivo</td></tr><tr><td>20 Nm</td><td>5</td></tr><tr><td>30 Nm</td><td>10</td></tr></table><div data-kind="ghost"></div></div></div>	Valor de ajuste	Cantidad objetivo	10 Nm	2	20 Nm	3	30 Nm	5	Valor de ajuste	Cantidad objetivo	20 Nm	5	30 Nm	10
Valor de ajuste	Cantidad objetivo																								
10 Nm	2																								
20 Nm	3																								
30 Nm	5																								
Valor de ajuste	Cantidad objetivo																								
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20 Nm	3																								
30 Nm	5																								
Valor de ajuste	Cantidad objetivo																								
20 Nm	5																								
30 Nm	10																								
Observación	—	* Un trabajo puede contener hasta 10 pasos.	* Una secuencia puede contener hasta 10 pasos.																						

Número de combinaciones que se pueden registrar

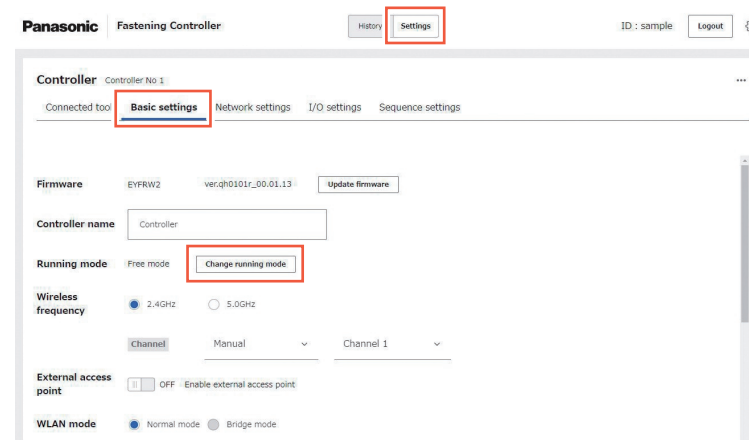
Consulte el número de combinaciones que se pueden registrar en el controlador tal como se indica a continuación.

Modo del controlador		Ajuste de la herramienta	Número de combinaciones que se pueden registrar
Free mode		Parameter	5 combinaciones por herramienta
Repeat mode	Basic mode (control independiente)	Batch	5 combinaciones por herramienta
		Job	5 combinaciones por herramienta
	Sequence mode (control secuencial)	Batch/Job	5 combinaciones
External control mode		—	

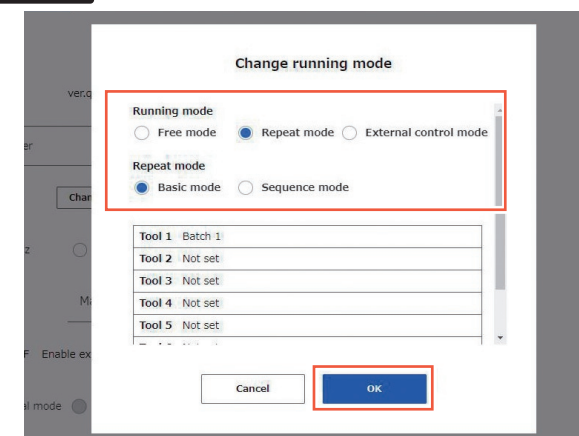
Ajuste del modo de funcionamiento

Ajuste el modo de funcionamiento del controlador como se indica a continuación.

- 1 En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Basic settings”.
- 2 En la pestaña “Basic settings”, haga clic en [Change running mode]. Se visualiza la pantalla “Change running mode”.



- 3 Seleccione un “Running mode” y haga clic en [OK]. Se establece el modo de funcionamiento. Seleccione un modo de funcionamiento de entre “Free mode”, “Repeat mode” y “External control mode”. Para “Repeat mode”, seleccione “Basic mode” o “Sequence mode”.
Consulte P46 a 49

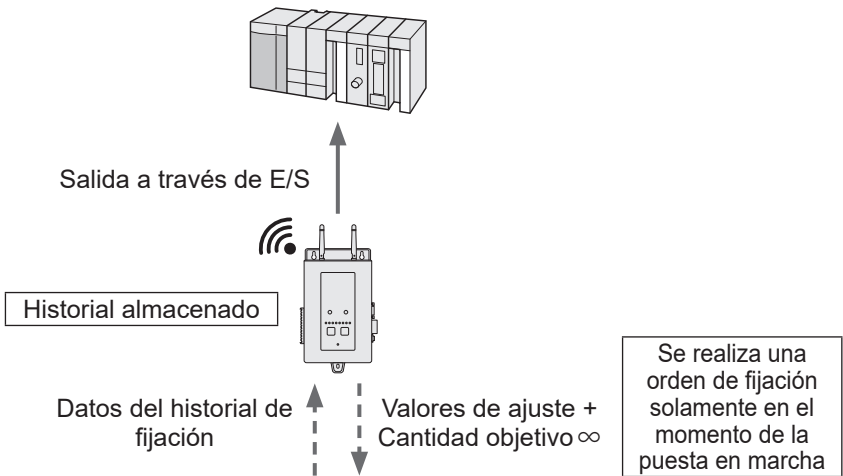


- * Registre el “Parameter” antes de ajustarlo en el “Free mode”.
- * Registre un “Batch/Job” antes de ajustarlo en el “Repeat mode”.

Free mode

Este modo permite una fijación incondicional sin especificar la cantidad a fijar. Las herramientas usan parámetros preregistrados para la fijación. Hasta 8 herramientas pueden llevar a cabo una operación independiente. Se activan los ajustes de salida de E/S.

* Utilice el modo cuando la cantidad fijada sea contada por un dispositivo externo.













Valor de ajuste	Cantidad objetivo
10 Nm	∞

Valor de ajuste	Cantidad objetivo
20 Nm	∞

Valor de ajuste	Cantidad objetivo
30 Nm	∞

Valor de ajuste	Cantidad objetivo
40 Nm	∞

Se pueden controlar hasta 8 herramientas al mismo tiempo











Valor de ajuste	Cantidad objetivo
50 Nm	∞

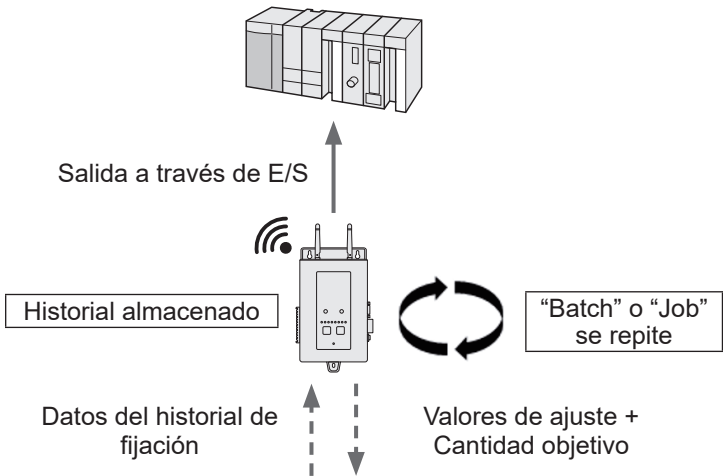
Valor de ajuste	Cantidad objetivo
60 Nm	∞

Valor de ajuste	Cantidad objetivo
70 Nm	∞

Valor de ajuste	Cantidad objetivo
80 Nm	∞

Repeat mode (Basic mode)

Este modo repite un proceso “Batch” o “Job”. Las herramientas utilizan los ajustes preregistrados “Batch” o “Job” para la fijación. Hasta 8 herramientas pueden llevar a cabo una operación independiente. Se activan los ajustes de salida de E/S.













Valor de ajuste	Cantidad objetivo
10 Nm	10

Valor de ajuste	Cantidad objetivo
20 Nm	10

Valor de ajuste	Cantidad objetivo
30 Nm	10

Valor de ajuste	Cantidad objetivo
40 Nm	10

Se pueden controlar hasta 8 herramientas al mismo tiempo











Valor de ajuste	Cantidad objetivo	Valor de ajuste	Cantidad objetivo	Valor de ajuste	Cantidad objetivo	Valor de ajuste	Cantidad objetivo
50 Nm	10	60 Nm	10	70 Nm	10	80 Nm	10
60 Nm	5	70 Nm	5	80 Nm	5	90 Nm	5
70 Nm	5	80 Nm	5	90 Nm	5	10 Nm	5

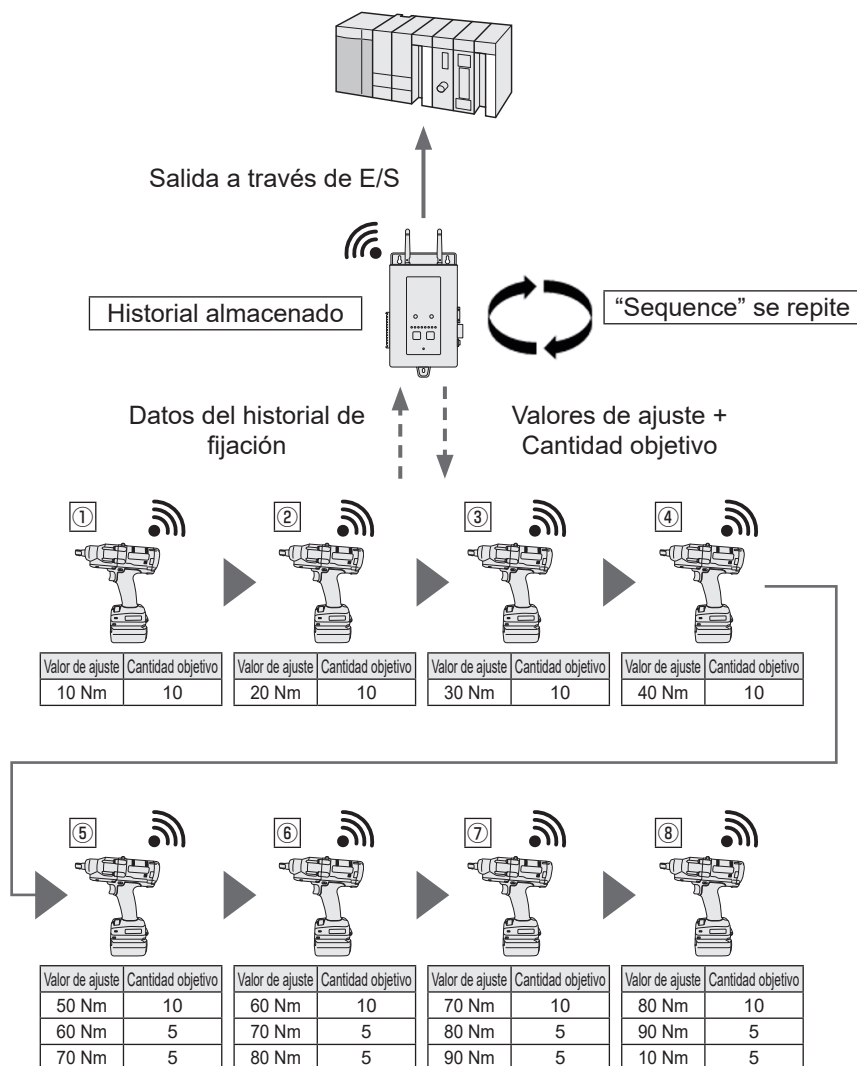
■ Repeat mode (Sequence mode)

Este modo repite un proceso "Sequence" donde las herramientas disponibles se controlan en orden.

Las herramientas utilizan ajustes "Sequence" preregistrados para la fijación secuencial.

Se pueden ajustar hasta 10 pasos. Una secuencia soporta hasta 8 herramientas pero solo permite que una herramienta funcione a la vez.

Se activan los ajustes de salida de E/S.



■ External control mode

Este modo permite fijar el control según lo solicitado por un dispositivo externo (sistema anfitrión).

Los siguientes 2 tipos de control son compatibles.

● Control mediante Protocolo Abierto (con Protocolo Abierto habilitado)

La fijación se controla a través de un Protocolo Abierto mediante un sistema anfitrión.

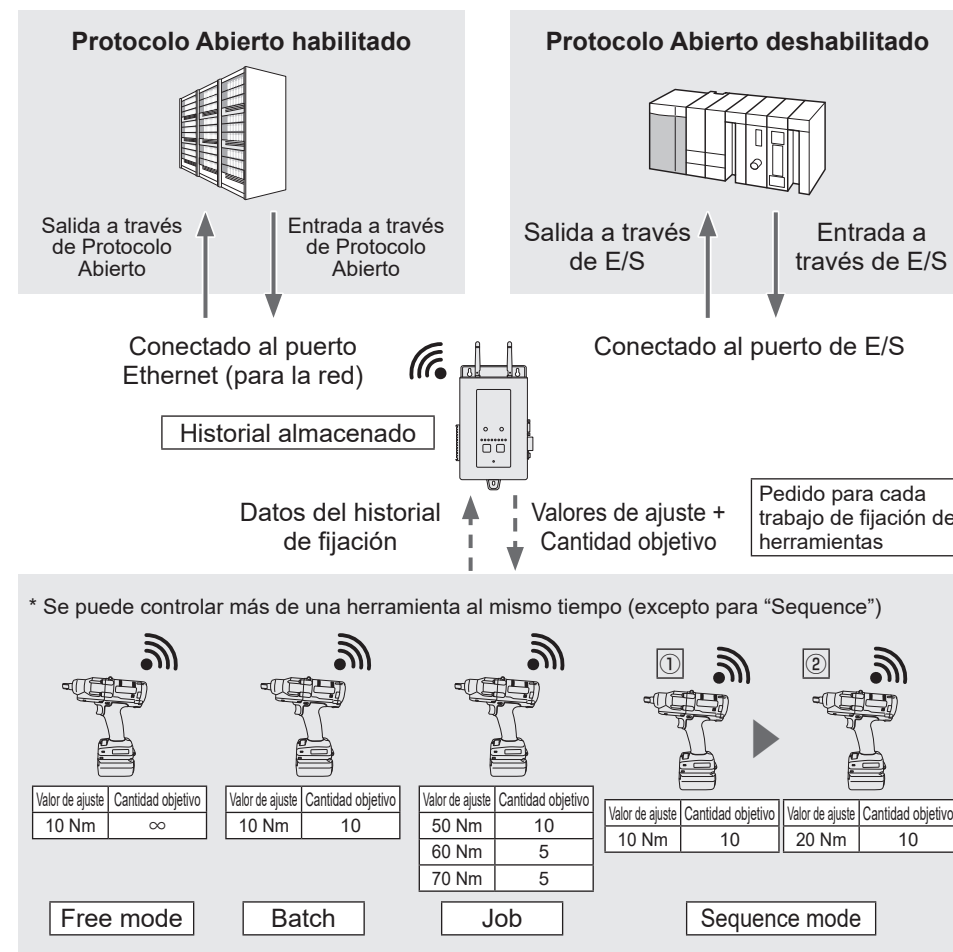
Se pueden controlar hasta 8 herramientas de forma independiente.

* Los controles de trabajos y secuencias no son compatibles.

● Control mediante E/S (con Protocolo abierto deshabilitado)

La fijación se controla mediante entradas a través del puerto de E/S desde un dispositivo externo.

Se pueden controlar hasta 8 herramientas independiente o secuencialmente.



* Si el controlador se apaga durante la fijación, ésta no se reanuda tras encender el controlador. La fijación vuelve a comenzar cuando se solicita por un dispositivo externo.

* Se activan los ajustes de salida de E/S.

Creación (ajuste) de un lote

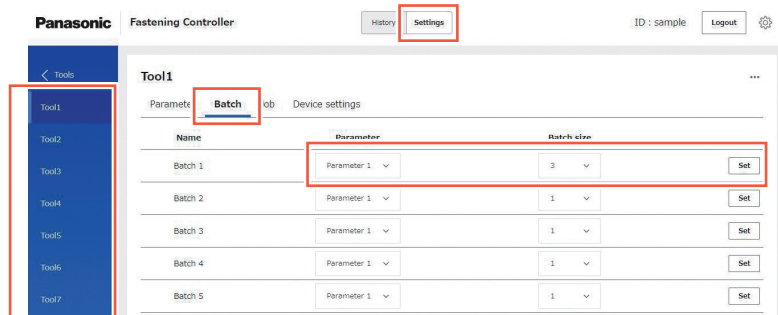
En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña "Connected tool". En la pantalla "Connected tool", haga clic en el número de herramienta deseado.

En la pantalla del número de herramienta, seleccione la pestaña "Batch" para realizar los ajustes.

Seleccione un parámetro desde el menú desplegable "Parameter" y ajuste "Batch size" (cantidad a fijar, hasta 99). Haga clic en [Set] para ajustar los valores para "Repeat mode (Basic mode)".

* Para cambiar la herramienta, seleccione la deseada en la lista de herramientas.

* Se pueden registrar hasta 5 lotes.



Lista de herramientas

Creación (ajuste) de un trabajo

En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña "Connected tool". En la pantalla "Connected tool", haga clic en el número de herramienta deseado.

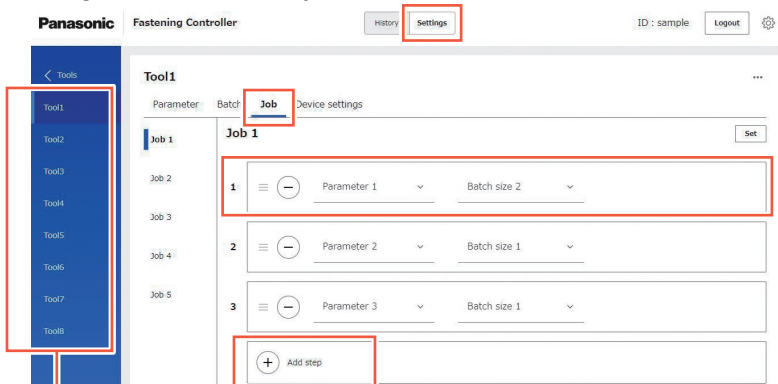
En la pantalla del número de herramienta, seleccione la pestaña "Job" para realizar los ajustes.

Seleccione un parámetro desde el menú desplegable "Parameter" y ajuste "Batch size" (cantidad a fijar, hasta 99). Haga clic en [Set] para ajustar los valores para "Repeat mode (Basic mode)".

* Se pueden registrar hasta 10 pasos.

* Para cambiar la herramienta, seleccione la deseada en la lista de herramientas.

* Se pueden registrar hasta 5 trabajos.



Lista de herramientas

Creación (ajuste) de una secuencia

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña "Sequence settings".

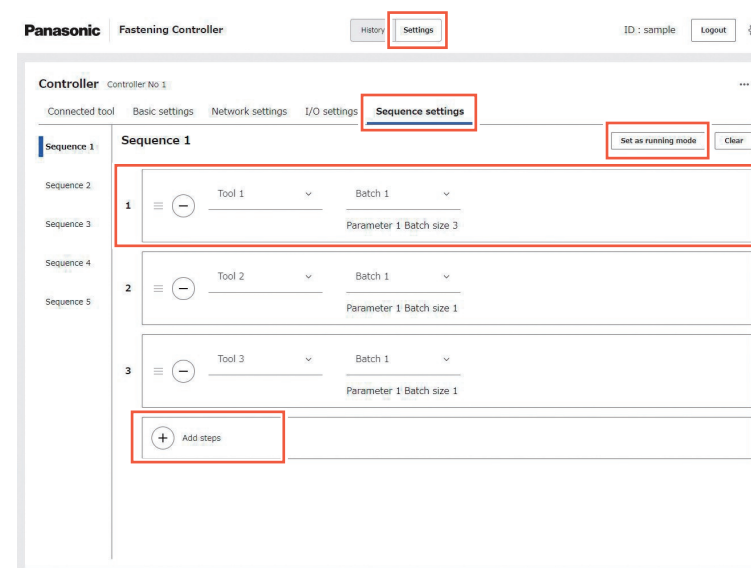
En la pantalla "Sequence settings", seleccione una herramienta del menú desplegable "Tool" y ajuste "Batch" o "Job".

Haga clic en [Set as running mode] para ajustar los valores de "Repeat mode (Sequence mode)".

* Se pueden registrar hasta 5 secuencias.

* Se pueden registrar hasta 10 pasos.

* Se puede utilizar la misma herramienta más de una vez en una secuencia.



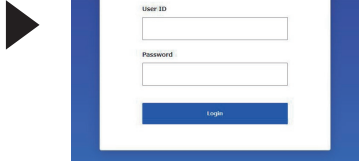
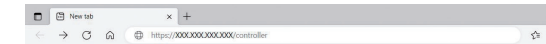
Tipos de dispositivos externos compatibles

El controlador es compatible con los siguientes tipos de dispositivos externos.

Función	PC para la configuración	PLC	Sistema anfitrión del cliente
Ilustración			
Método de comunicación	Ethernet	E/S	Ethernet
Protocolo de comunicación	http/https	— (Solo señal ON/OFF)	Protocolo Abierto
Uso principal	• Visualización y almacenamiento del historial de fijación • Cambio de los ajustes	• Emisión de las señales de finalización y fallo • Conmutación del orden de fijación	• Exportación del historial de fijación • Conmutación del orden de fijación
Datos que se pueden exportar	• Números de serie de las herramientas • Hora • Resultados de finalización y fallos • Valores de par, ángulos, longitudes de tiempo de fijación • Datos de forma de onda	• Resultados de finalización y fallos • Batch/job/sequence completa • Batch/job/sequence seleccionado • Herramienta activa	• Números de serie de las herramientas • Hora • Resultados de finalización y fallos • Valores de par, ángulos, longitudes de tiempo de fijación • Datos de forma de onda
Cambio del orden de fijación	—	• Batch/job/sequence seleccionado	• Parameter/batch seleccionado
Otros	Se muestra en un navegador web. Se recomienda Microsoft Edge.	8 puertos para cada entrada y salida	Para más información sobre los comandos compatibles, consulte “Comandos compatibles con Protocolo Abierto”. Consulte P61 Las secuencias de control deben ser revisadas respectivamente.

Conexión al PC para configuración en una ubicación remota

El PC para la configuración con el certificado instalado puede conectarse remotamente a los controladores. Tenga en cuenta que solo se acepta un acceso a la función de configuración a la vez. Para conectarse, introduzca la dirección IP del controlador deseado en un navegador web. **Consulte P21**



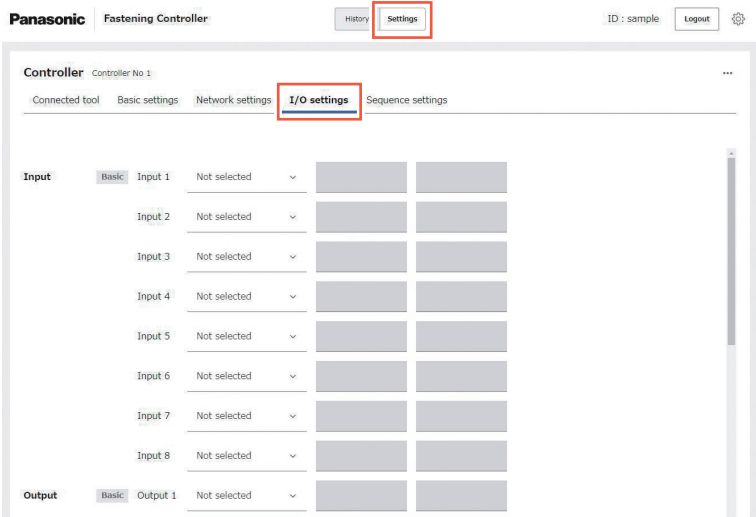
Conexión a través de la E/S

Puede asignar comandos compatibles a 8 puertos de entrada y 8 puertos de salida como desee. Asígnelos en la pantalla “I/O settings”. A continuación se indican los comandos que se pueden asignar a los puertos.

Entrada	Comando compatible	Salida	Comando compatible
1	Batch (Herramienta 1 a 5) Job (Herramienta 1 a 5) Sequence (1 a 5) Batch reset (1 a 8) Reset Suspend tool (1 a 8) Suspend controller	1	OK (Herramienta 1 a 8) NOK (Herramienta 1 a 8) Batch complete (Herramienta 1 a 5) Job complete (Herramienta 1 a 5) Sequence complete (1 a 5) Tool active (Herramienta 1 a 8) Batch selected (Herramienta 1 a 5) Job selected (Herramienta 1 a 5) Sequence selected (1 a 5)
2		2	
3		3	
4		4	
5		5	
6		6	
7		7	
8		8	

Ajuste de E/S

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “I/O settings”.



* Es posible asignar un comportamiento o un evento aún no registrado. (Excepto para la selección de trabajo y la selección de secuencia)

Comandos asignados a los puertos de entrada

A continuación se indican los comandos que se pueden asignar a los puertos de entrada. Se ejecuta el comando asignado cuando una señal de un dispositivo externo se introduce en uno de los puertos.

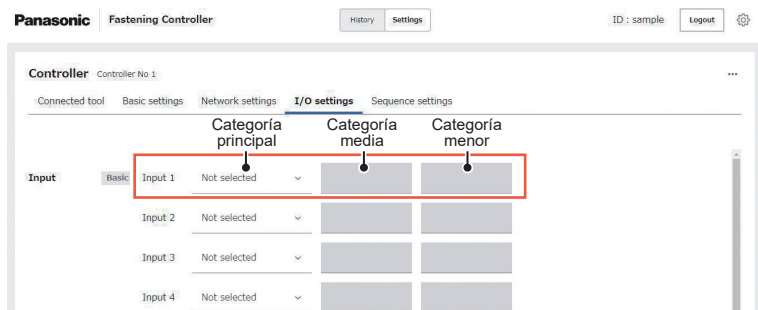
Categoría principal (comportamiento)	Categoría media (herramienta)	Categoría menor (N.º de lote, etc.)
Batch	Herramienta del 1 al 8	1-5
Job	Herramienta del 1 al 8	1-5
Sequence	—	1-5
Suspend tool*1	Herramienta del 1 al 8	—
Suspend controller*1	—	—
Batch reset	Herramienta del 1 al 8	—
Reset	—	—

*1 Habilitado solo mientras se mantiene la señal de entrada.

Notas cuando se introduce el comando “Suspend tool” o “Suspend controller”

- Mientras “Suspend controller” está activo, no se acepta ninguna orden de fijación.
- Para el número de herramienta con “Suspend tool” activo, no se acepta ninguna orden de fijación “Batch” o “Job”.
- Para otros números de herramienta con “Suspend tool” activo, se acepta una orden de fijación “Batch” o “Job”.
- Mientras “Suspend tool” está activo, no se acepta ninguna orden de fijación “Sequence”. En ese momento, el proceso continúa hasta llegar a la herramienta con “Suspend tool” activo.
- “Batch reset” y “Reset” son tratados de la misma forma que en una orden de sujeción.

Después de seleccionar un comportamiento en la categoría principal, seleccione una herramienta y, a continuación, un número (por ejemplo, número de lote) según sea necesario.



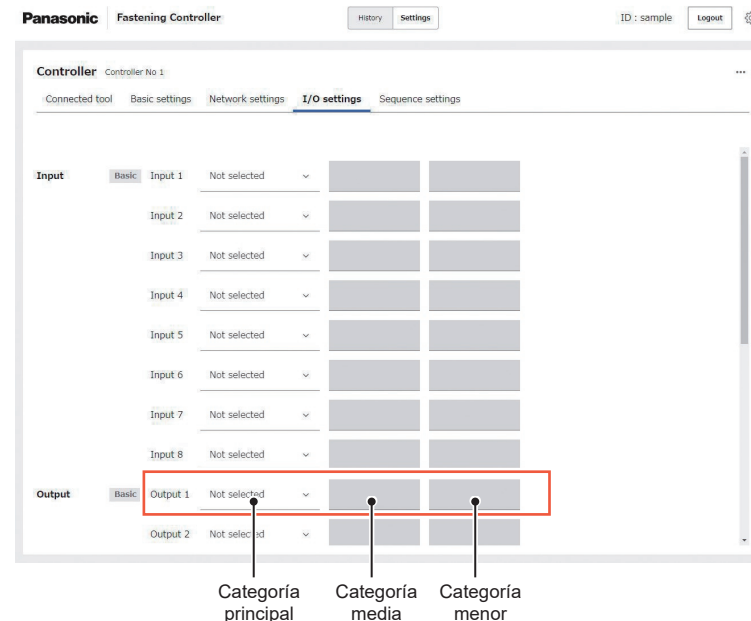
* No se realiza ninguna acción si se introduce una señal no asignada. (No ocurre ningún error)

Comandos asignados a los puertos de salida

A continuación se indican los comandos que se pueden asignar a los puertos de salida. Cuando se ha producido un evento relevante, el controlador envía una señal desde el puerto correspondiente a un dispositivo externo según lo especificado por el comando asignado.

Categoría principal (evento)	Categoría media (herramienta)	Categoría menor (N.º de lote, etc.)
OK	Herramienta del 1 al 8	—
NOK	Herramienta del 1 al 8	—
Batch complete	Herramienta del 1 al 8	1-5
Job complete	Herramienta del 1 al 8	1-5
Sequence complete	—	1-5
Tool active	Herramienta del 1 al 8	—
Batch selected	Herramienta del 1 al 8	1-5
Job selected	Herramienta del 1 al 8	1-5
Sequence selected	—	1-5

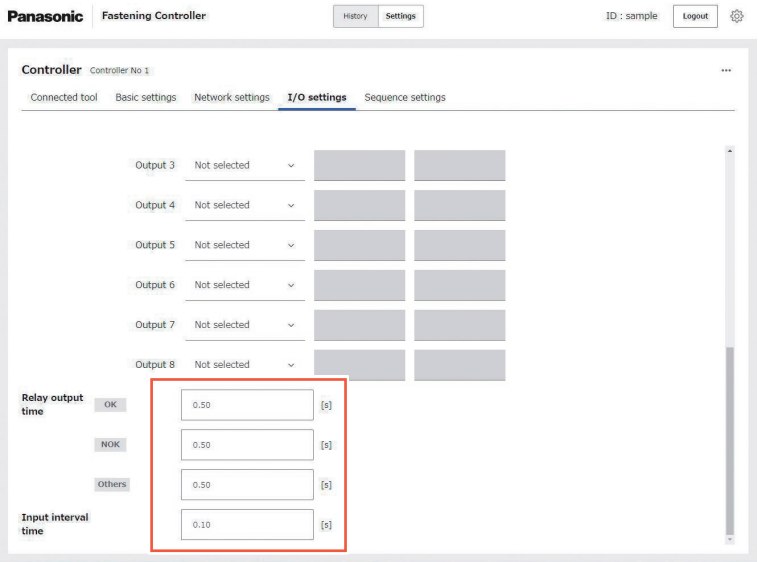
Después de seleccionar un evento en la categoría principal, seleccione una herramienta y, a continuación, un número (por ejemplo, número de lote) según sea necesario.



* Si el controlador se apaga mientras se ejecuta un comando de salida, el proceso no se reanuda una vez que el controlador se encienda. (Tenga en cuenta que se guardan los datos del historial de fijación).

Otros ajustes

Puede establecer otros ajustes relacionados con la E/S como se indica a continuación.

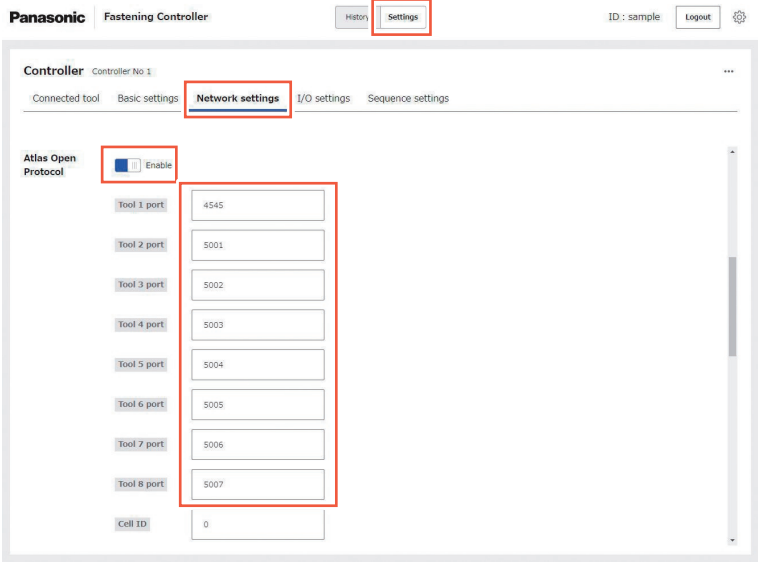


Relay output time (OK)
Seleccione el tiempo que debe transcurrir hasta que el relé emita una señal de finalización de la fijación. [Predeterminado] 0.5 s [Rango de ajuste] de 0.01 s a 10 s
Relay output time (NOK)
Seleccione el tiempo que debe transcurrir hasta que el relé emita una señal de fallo de fijación. [Predeterminado] 0.5 s [Rango de ajuste] de 0.01 s a 10 s
Relay output time (Others)
Seleccione el tiempo que debe transcurrir hasta que el relé emita una señal distinta de las de finalización de la fijación y fallo. [Predeterminado] 0.5 s [Rango de ajuste] de 0.01 s a 10 s
Input interval time
Seleccione el tiempo durante el cual no se cuentan (aceptan) las señales de entrada sucesivas. Ajústelo para evitar el doble recuento causado por el ruido, etc. [Predeterminado] 0.1 s [Rango de ajuste] de 0.01 s a 10 s

Conexión a través de la Comunicación de Protocolo Abierto

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Network settings”.

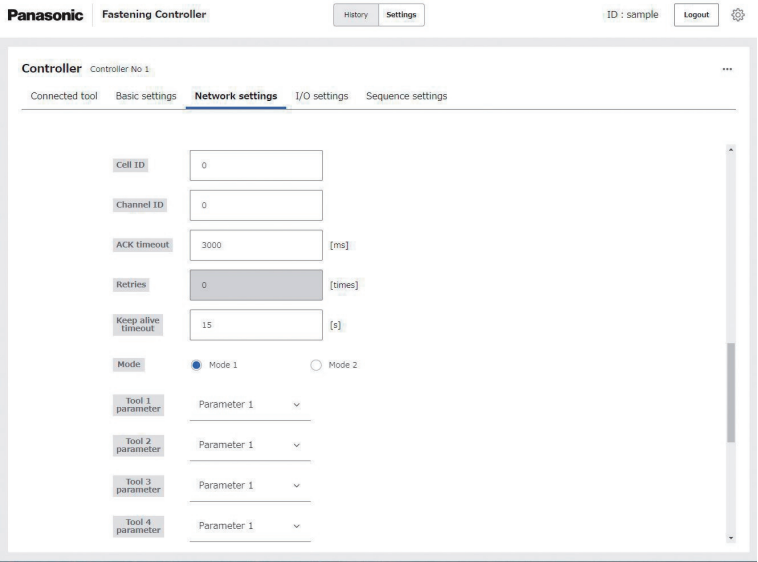
Enable “Atlas Open Protocol”.
Ajuste los números de puerto a las herramientas utilizadas respectivamente.



Tool port
Asigne un número de puerto para la comunicación de Protocolo Abierto a cada herramienta. [Predeterminado] Herramienta 1 - 4545, Herramienta 2 a 8 - 5001 a 5007 [Rango de ajuste] Herramienta 1 a 8 - 1024 a 49151

Otros ajustes

Ajuste otros elementos según sea necesario.

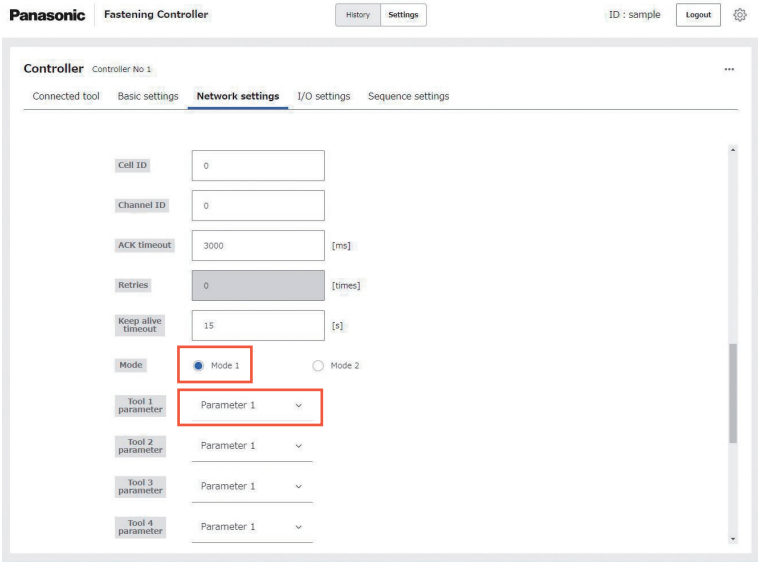


Cell ID
Ajuste la ID de la celda. [Predeterminado] 0 [Rango de ajuste] de 0 a 9999
Channel ID
Ajuste la ID del canal. [Predeterminado] 0 [Rango de ajuste] de 0 a 99
ACK timeout
Establezca el tiempo de espera de una respuesta a un mensaje de solicitud del controlador. [Predeterminado] 3000 ms [Rango de ajuste] de 100 ms a 30000 ms
Retries
Establezca el número de veces que desea repetir el envío de un mensaje de solicitud desde el controlador. [Predeterminado] 0 times [Rango de ajuste] No seleccionable (Fijo)

Keep alive timeout
Ajuste la duración de tiempo para determinar la ocurrencia de desconexión después de la última comunicación con un sistema anfitrión. [Predeterminado] 15 s [Rango de ajuste] de 1 s a 60 s
Mode
Ajuste el modo de funcionamiento. Mode 1: Fijación incondicional con parámetros prerregistrados Mode 2: Fijación con parámetros ordenados por un sistema anfitrión [Predeterminado] Mode 1 [Rango de ajuste] Mode 1 / Mode 2

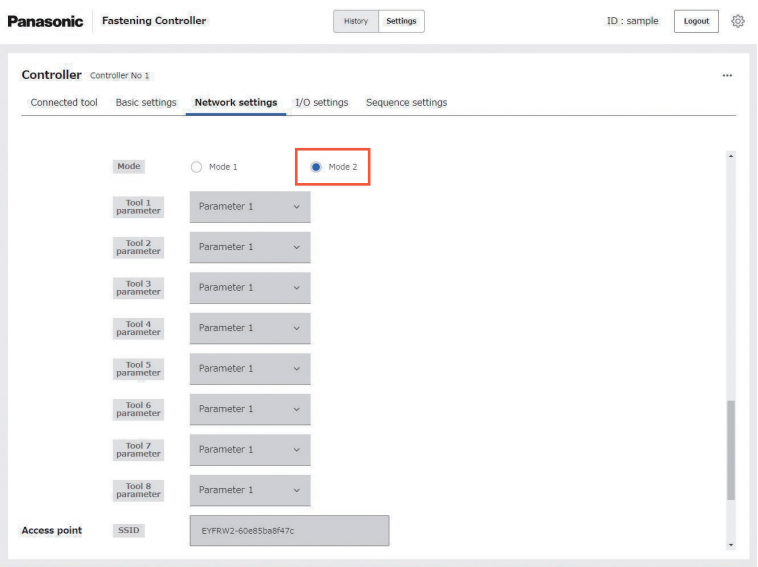
Asignación de los parámetros de fijación (Mode 1)

“Mode 1” (sin parámetros solicitados) requiere parámetros de fijación prerregistrados en las herramientas.
Seleccione un parámetro del menú desplegable como se indica a continuación.



Asignación de los parámetros de fijación (Mode 2)

La fijación puede solicitarse con un comando MID 0018 mediante un dispositivo externo.
Puede especificar “Parameter” o “Batch” en una orden de fijación.



■ Para especificar “Parameter” en una orden de fijación
Ponga “0” en el dígito de las centenas de la ID.
Los dígitos de las decenas y de las unidades muestran un número de parámetro.
Ejemplo: ID del parámetro 1: 001
ID del parámetro 5: 005

■ Para especificar “Batch” en una orden de fijación
Ponga “1” en el dígito de las centenas de la ID.
Los dígitos de las decenas y de las unidades muestran un número de lote.
Ejemplo: ID del lote 1: 101
ID del lote 5: 105

* “Job” y “Sequence” no son compatibles.

■ Comandos compatibles con Protocolo Abierto

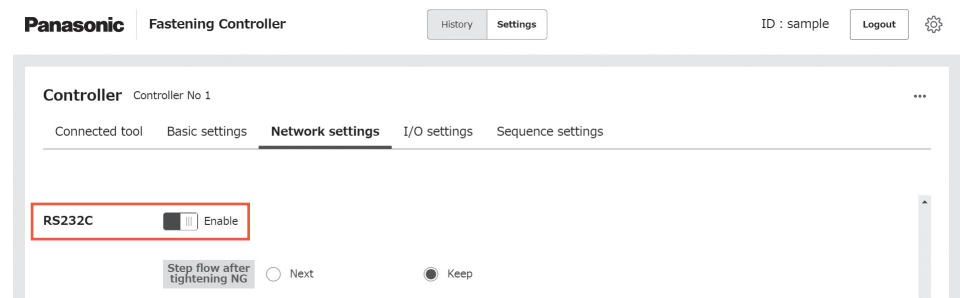
El controlador es compatible con los siguientes comandos.
Para obtener más detalles sobre los comandos, consulte Especificación de Protocolo Abierto.

MID 0001 Application communication start
La revisión 1 es compatible. [Contenido] Inicio de la comunicación
MID 0002 Application communication start acknowledge
La revisión 1 es compatible. [Contenido] Reconocimiento de la comunicación
MID 0004 Application command error
La revisión 1 es compatible. [Contenido] Error de comando
MID 0005 Application command accepted
La revisión 1 es compatible. [Contenido] Aceptación de comandos
MID 0018 Select parameter set, Dynamic Job included
La revisión 1 es compatible. Para más información sobre cómo asignar, consulte “Asignación de los parámetros de fijación (Mode 2)”. Consulte P60 [Contenido] Orden de los parámetros
MID 0042 Disable tool
La revisión 1 es compatible. [Contenido] Herramienta deshabilitada
MID 0043 Enable tool
La revisión 1 es compatible. [Contenido] Herramienta habilitada
MID 0050 Vehicle ID number download request
La revisión 1 es compatible. [Contenido] Solicitud de adquisición de la ID del vehículo

MID 0060 Last tightening result data subscribe
Las revisiones 1 y 2 son compatibles. [Contenido] Registro de datos del resultado final de la fijación
MID 0061 Last tightening result data
Las revisiones 1 y 2 son compatibles. [Contenido] Carga del resultado de la fijación
MID 0062 Last tightening result data acknowledge
Las revisiones 1 y 2 son compatibles. [Contenido] Confirmación de la carga del resultado de la fijación
MID 9999 Keep alive message
La revisión 1 es compatible. [Contenido] Comprobación de disponibilidad

Conexión a dispositivos externos con las especificaciones propias de TOYOTA MOTOR CORPORATION

Se admite el control desde dispositivos externos.
Habilite “RS232C” desde la pestaña “Network settings” en [Settings].



RS232C
Este es un ajuste específico de TOYOTA MOTOR CORPORATION. Es posible el control desde dispositivos externos. [Predeterminado] Disable [Rango de ajuste] Disable / Enable
Step flow after tightening NG
Este ajuste determina si se puede pasar al siguiente apriete en caso de que se produzca un resultado NG de apriete. [Predeterminado] Keep [Rango de ajuste] Next (El siguiente apriete puede realizarse). / Keep (No se puede realizar el siguiente apriete).

Esto solo es compatible con la versión de firmware 2.03.00 o posterior.
Para saber cómo actualizar el firmware, consulte “Actualización del firmware”.
Consulte P87

Configuración

Puede conectar un lector de códigos de barras comercial para guardar la información de lectura y vincularla a los datos del historial de fijación.
Puede utilizarse para vincular productos al historial de fijaciones.

Conexión	Método de comunicación	Nota
 Lector de códigos de barras Receptor inalámbrico Controlador Panasonic	Inalámbrico de 2.4 GHz o Bluetooth	• Lee la información del producto (como los números de serie de fabricación) y la refleja en los datos del historial.

No utilice lectores de códigos de barras USB con cable.

Dispositivos aplicables

Los siguientes lectores de códigos barras son compatibles con el controlador.

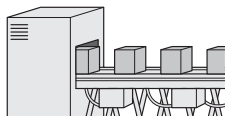
Elemento	Descripción	
Interfaz de comunicación	USB-HID	
Disposición del teclado	EE. UU.	
Caracteres compatibles	Caracteres alfanuméricos, símbolos	
	Códigos compatibles	Descripción del código (información anticipada)
	Números	0-9
	Caracteres alfabéticos	A-Z, a-z
Códigos 1D aceptables	Símbolos	!"#\$%&'()*+,-./:;<=>?@[¥]^_`{ }~
	Códigos 2D aceptables	Código QR Modelo 1/2, Micro QR
	Número aceptable de caracteres	100 caracteres (máximo)

Modelos recomendados
Bluetooth: Honeywell Xenon XP 1952g, ZEBRA DS2278

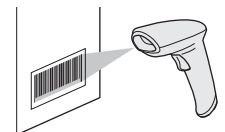
Flujo del proceso de trabajo

Siguiendo el procedimiento que se indica a continuación, puede guardar la información del producto y vincularla a los datos del historial de fijación.

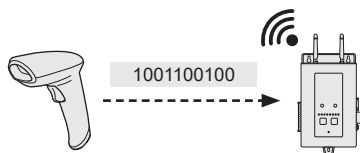
1 Los productos fluyen a través de la línea.



2 Lea la información del producto con un lector de códigos de barras.

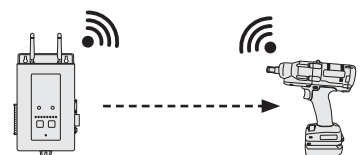


3 La información leída por el lector de códigos de barras se envía al controlador.

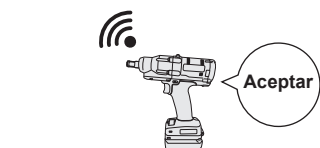


4 Se envía una orden de fijación desde el controlador a las herramientas.

* Este paso puede suceder antes o después del paso 3.



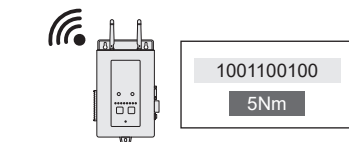
5 Realice los trabajos de fijación utilizando las herramientas.



6 El resultado del trabajo de fijación (como el par de apriete) se envía al controlador.



7 La información de lectura conservada en el controlador y el resultado del trabajo de fijación se vinculan entre sí y se guardan en la memoria.



8 Repita los pasos 5 a 7 hasta que se actualice la información de lectura del código de barras (o hasta que finalice el trabajo).

Procedimiento de ajuste

El procedimiento de ajuste varía en función de las especificaciones del lector de códigos de barras.

■ Método inalámbrico de 2.4 GHz (con receptor inalámbrico dedicado)

Conéctelo siguiendo el procedimiento que se indica a continuación. (Los pasos 2 a 3 no son necesarios).

■ Método Bluetooth (sin receptor inalámbrico dedicado)

Prepare un receptor inalámbrico Bluetooth por separado y conéctelo siguiendo el procedimiento que se indica a continuación.

Receptores inalámbricos Bluetooth disponibles

- Versión de Bluetooth: Compatible con la versión 4.0
- Compatible con el SO Linux (solo aquellos que no requieren controladores dedicados)

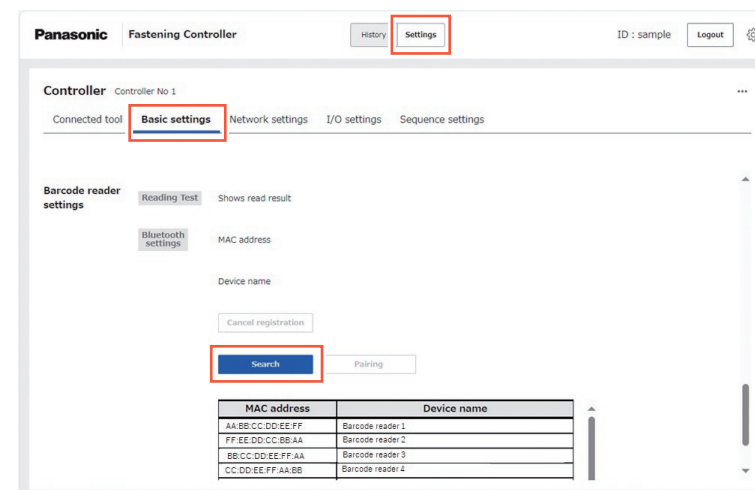
Modelos recomendados

EDIMAX BT-8500

1 Conecte el receptor inalámbrico del lector de códigos de barras al puerto USB-A del controlador.

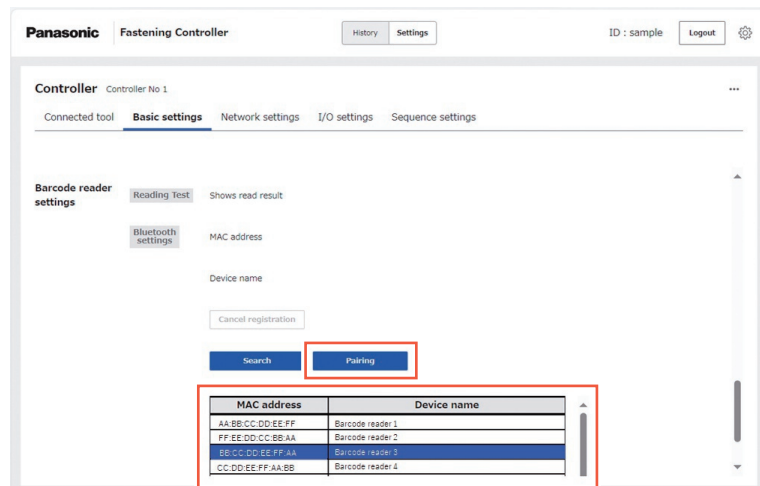
2 En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior, seleccione la pestaña "Basic settings" y haga clic en "Search" desde "Barcode reader settings".

* Ponga también el lector de código de barras en el modo de emparejamiento según sus especificaciones.



3 Seleccione el lector de códigos de barras a conectar desde la lista de nombres de dispositivos y pulse “Pairing”.

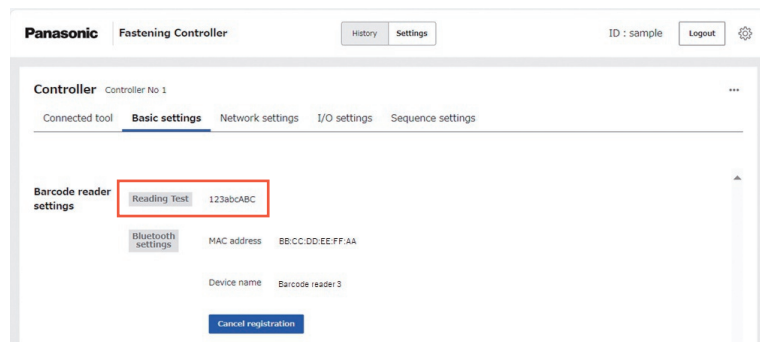
Se emparejará con el lector de códigos de barras.



Lista de nombres de dispositivos

- El estado de búsqueda se mantiene durante unos 10 segundos.
- Una vez registrado el emparejamiento, se volverá a conectar automáticamente la segunda y siguientes veces.
- * En función de las especificaciones del lector de códigos de barras, podría ser necesario volver a realizar el emparejamiento.
- * Si el emparejamiento falla, cancele el emparejamiento en el controlador y, a continuación, vuelva a intentarlo.

4 Lea la información del código de barras y compruebe que la información se muestra correctamente en “Reading Test”.

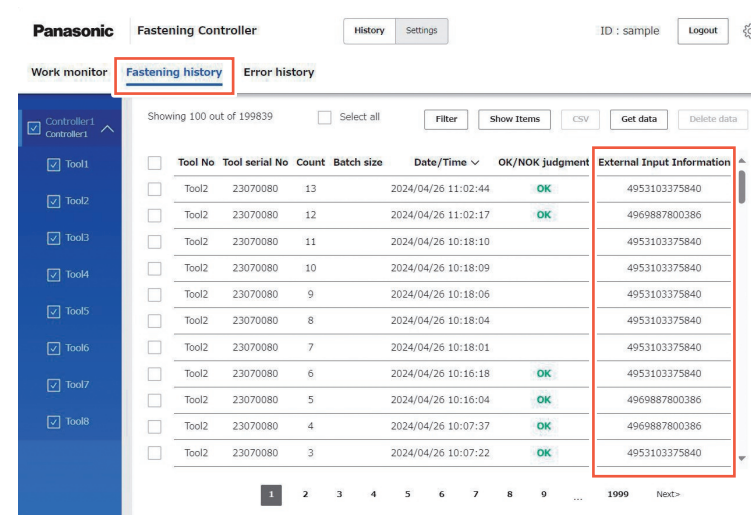


5 Realice los trabajos de fijación con el lector de códigos de barras que ha leído la información.

Los datos leídos se mostrarán en “External Input Information” de los datos del historial de fijación.

Notas durante el funcionamiento

- La “Lámpara de fijación OK” parpadeará en el estado de recepción de la lectura del código de barras.
- Durante el funcionamiento, compruebe que el estado de recepción de la lectura del código de barras está activo antes de trabajar.



Notas sobre los valores de lectura

Los valores leídos son:

- Reflejado en los resultados de trabajo de todas las herramientas registradas por el controlador tras la lectura.
- No se retienen cuando el controlador está desactivado.
- Sobrescritos por la nueva información leída.
- Retenidos hasta que se cumplan las siguientes condiciones.

Running mode	Condiciones de retención de datos
Free mode	Los datos se conservan hasta que se actualizan.
Repeat mode (Basic mode)	Hasta la finalización de "Batch"/"Job". O los datos se conservan hasta que se actualizan.
Repeat mode (Sequence mode)	Hasta la finalización de "Sequence". O los datos se conservan hasta que se actualizan.
External control mode * Control mediante Protocolo Abierto	La información VIN tiene prioridad y no se añaden.
External control mode * Control mediante E/S	Hasta la finalización de "Batch"/"Job"/"Sequence". O los datos se conservan hasta que se actualizan.

- Dependiendo de las especificaciones del dispositivo del lector de códigos de barras que esté utilizando, es posible que se requieran ajustes detallados para la conexión con el controlador. Antes de utilizar esta función, lea atentamente el Manual de instrucciones y los ajustes de su dispositivo.
- Si los datos se leen de forma continua en 0.5 segundos, la información se consolidará; por lo tanto, espacie las lecturas.
- Solo un lector de códigos de barras puede funcionar simultáneamente con el controlador. La conexión de varios lectores puede provocar un mal funcionamiento.

Licencias

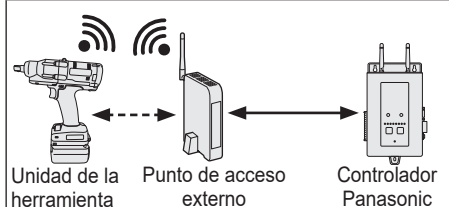
La marca Bluetooth® y sus logos son marcas comerciales registradas propiedad de Bluetooth SIG, Inc. y cualquier uso de dichas marcas por parte de Panasonic Corporation se realiza bajo licencia. Otros nombres de marcas y marcas comerciales son propiedad de sus respectivos propietarios.

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Configuración

El controlador puede conectarse a las herramientas mediante comunicación inalámbrica utilizando un punto de acceso externo en lugar del punto de acceso integrado. El controlador puede controlar las herramientas allí donde esté instalado. Conecte el punto de acceso y el controlador a la LAN por cable.

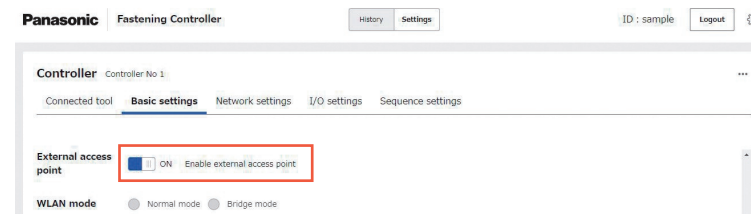
* La cobertura inalámbrica y el rendimiento cambian en función del punto de acceso utilizado.

Conexión	Método de comunicación	Nota
 Unidad de la herramienta Punto de acceso externo Controlador Panasonic	Ethernet	• En la selección de modo, seleccione el punto de acceso interno o el punto de acceso externo. • Número máximo de herramientas conectadas: 8 * Tanto para el punto de acceso interno como para el punto de acceso externo

Procedimiento de ajuste

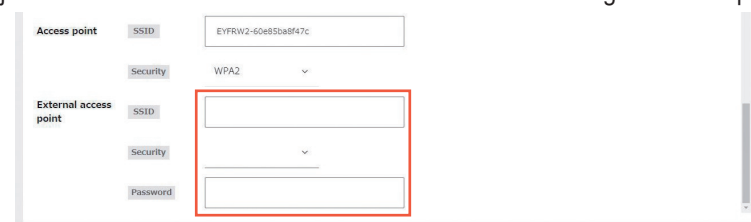
- 1 En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior, seleccione la pestaña "Basic settings" y coloque "External access point" en "ON".

* "WLAN mode" se deshabilita cuando "External access point" está habilitado.



- 2 En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña "Network settings". En "External access point", ajuste "SSID", "Security" y "Password".

- * Solo puede registrar un SSID en el controlador. (No puede registrar diferentes SSID para diferentes herramientas)
- * Consulte el Manual de instrucciones de su punto de acceso externo.
- * Realice este ajuste antes de iniciar el registro del emparejamiento con las herramientas.
- * Ajuste la dirección IP de la herramienta antes de iniciar el registro del emparejamiento.

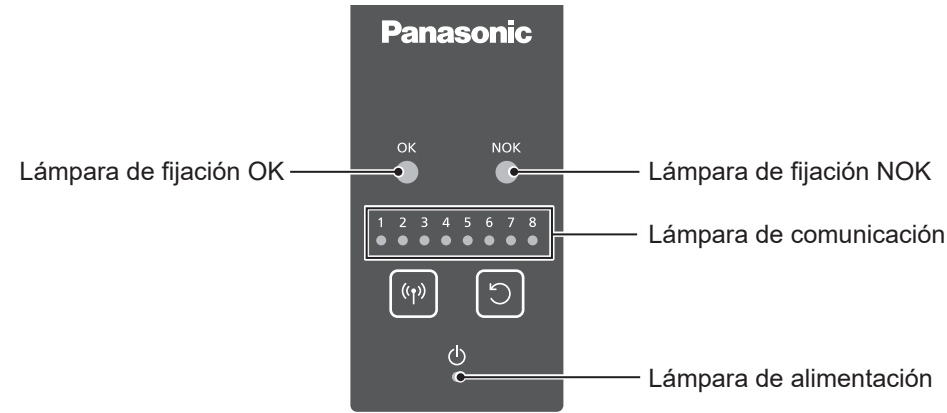


Lámparas indicadoras y un zumbador

Las lámparas indicadoras y el zumbador muestran el estado del controlador.

PRECAUCIÓN

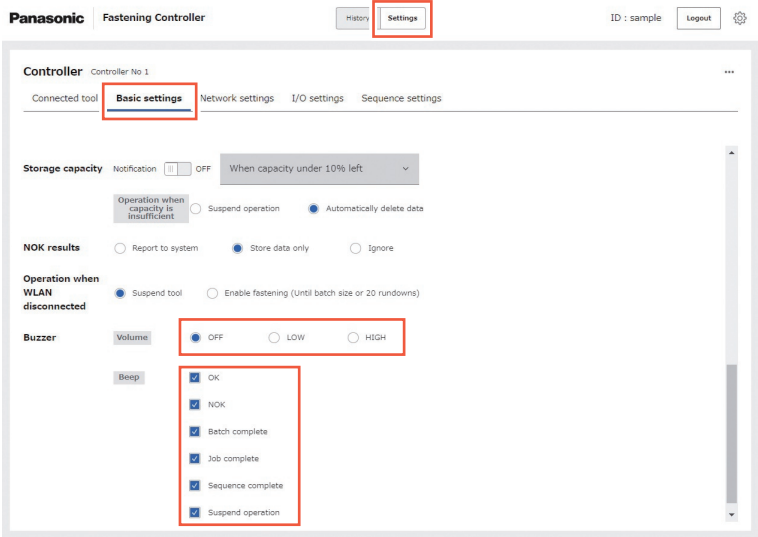
No apague el interruptor de alimentación mientras la lámpara esté parpadeando. Es posible que se requiera la inicialización.



Estado	Lámpara indicadora	Zumbador
Alimentación encendida	Lámpara de alimentación (amarilla) Permanece encendida	—
Una herramienta a emparejar seleccionada	Lámpara de comunicación (azul) Parpadea lentamente	—
Emparejamiento establecido	Lámpara de comunicación (azul) Parpadea rápidamente	—
Emparejamiento completado	Lámpara de comunicación (azul) Permanece encendida	Un pitido corto ■
Emparejamiento no establecido	Lámpara de comunicación (azul) Parpadea muy lentamente	—
Emparejamiento desconectado	Lámpara de comunicación (azul) Apagada	—
Finalización de la fijación	Lámpara OK (verde) Permanece encendida	Un pitido corto ■
Fallo de fijación	Lámpara NOK (roja) Permanece encendida	Un pitido largo ■■
Finalización del Batch/job	Lámpara OK (verde) Parpadea dos veces	Dos pitidos cortos ■■
Secuencia completa	Lámpara OK (verde) Parpadea tres veces	Tres pitidos cortos ■■■
Error	Lámpara de alimentación (amarilla) Parpadea	Dos pitidos largos ■■ ■■

Ajuste del zumbador

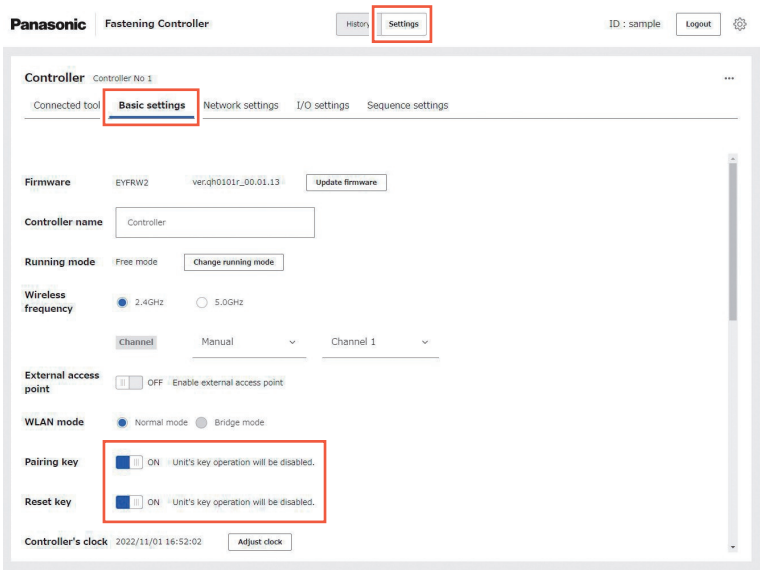
En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Basic settings”. En “Buzzer”, ajuste “Volume” y “Beep”.



Elemento	Descripción
Volume	3 niveles (OFF / LOW / HIGH) (LOW: 75 dB, HIGH: 85 dB)
Beep	Seleccionado en PC para la configuración (OK / NOK / Batch complete / Job complete / Sequence complete / Suspend operation)

AJUSTE DE LAS TECLAS DE FUNCIONAMIENTO

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Basic settings”. En “Pairing key” y “Reset key”, puede deshabilitar Pairing key y Reset key en el panel de control.



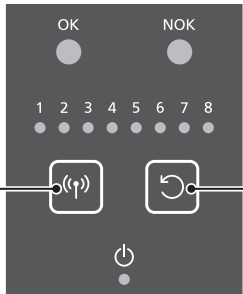
Pairing key

Active o desactive la tecla Emparejamiento en el panel de control.
[Predeterminado] ON
[Rango de ajuste] ON (habilitado)/OFF (deshabilitado)

Reset key

Active o desactive la tecla Reiniciar en el panel de control.
[Predeterminado] ON
[Rango de ajuste] ON (habilitado)/OFF (deshabilitado)

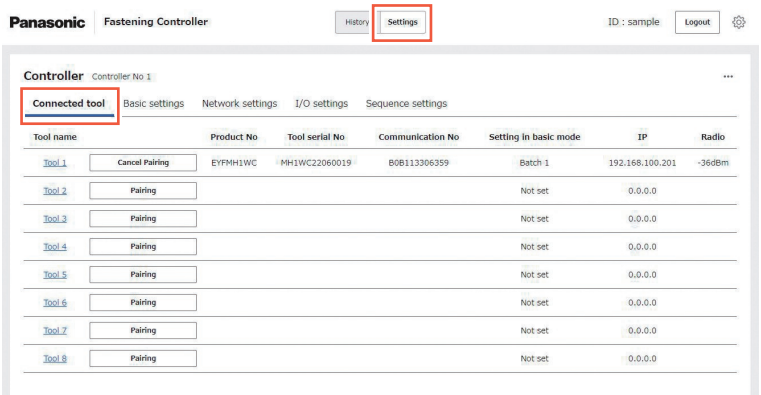
Tecla de emparejamiento



Tecla de reinicio

COMPROBACIÓN DE LA INFORMACIÓN DE LAS HERRAMIENTAS CONECTADAS

En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña “Connected tool”. Puede ver la información y el estado de las herramientas conectadas al controlador.



A continuación se muestran los elementos visualizados.

Tool name
Se visualiza el número de la herramienta registrada (del 1 al 8).
Tool serial No
Puede ajustar y visualizar la identificación de la unidad de la herramienta. Predeterminado: 5 dígitos de identificación del modelo + 8 dígitos del número de serie (2 dígitos del año de fabricación + 2 dígitos del mes + 4 dígitos del lote de producción)
Product No
Se muestra el número de producto de la herramienta.
Communication No
Se muestra la identificación de la unidad (dirección MAC) de la parte de comunicación de la herramienta.
Setting in basic mode
Se muestra un comportamiento cuando Running mode está ajustado en “Repeat mode (Basic mode)”.
IP
Se muestra la dirección IP de la herramienta.
Radio
Se muestra la intensidad de la señal de radio (RSSI) recibida de la herramienta. * Se muestra la fuerza en la última comunicación. * No se puede medir y aparece “0dBm” cuando se utiliza un punto de acceso externo.

MONITOR DE TRABAJO

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña "Work monitor".

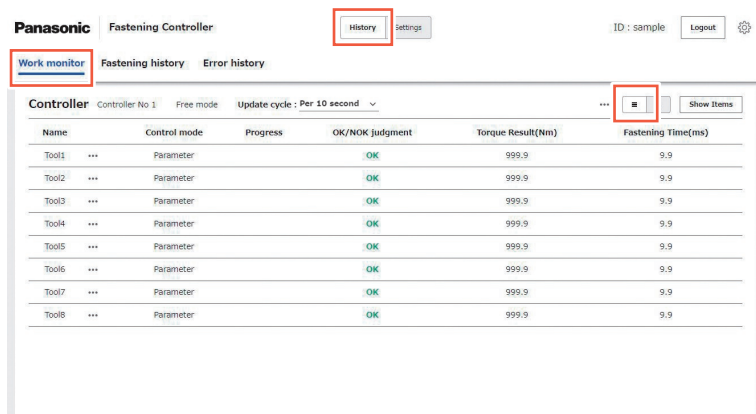
Se muestran los últimos registros del historial por herramienta. Puede utilizarlos para trabajar consultando los resultados del trabajo.

- * Más de un PC para la configuración puede mostrarlos al mismo tiempo. (Hasta 8 accesos. Se aceptan múltiples accesos desde la misma cuenta).
- * Para iniciar sesión con más de una cuenta, se recomienda el uso de diferentes PC.
- * Para usar más de una cuenta en el mismo PC, se recomienda el uso de diferentes navegadores web.
- * Solo se acepta un acceso a la función de configuración a la vez.

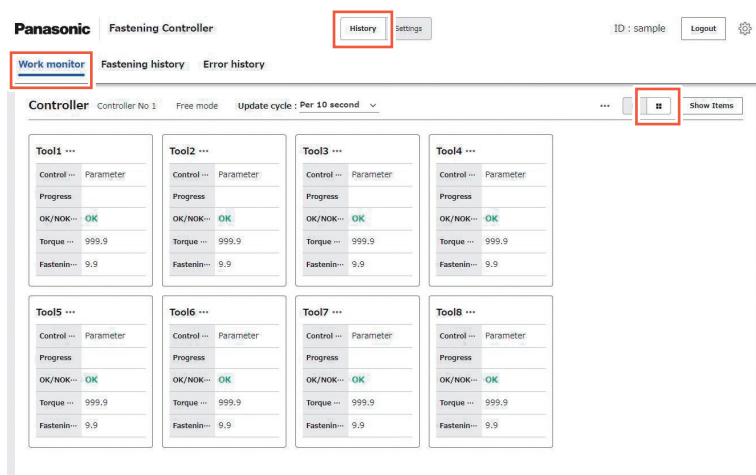
Cambio del formato de visualización

Puede seleccionar "Vista de lista" y "Vista de cuadrícula".
Use el icono de vista en la parte superior derecha de la pantalla.

Vista de lista

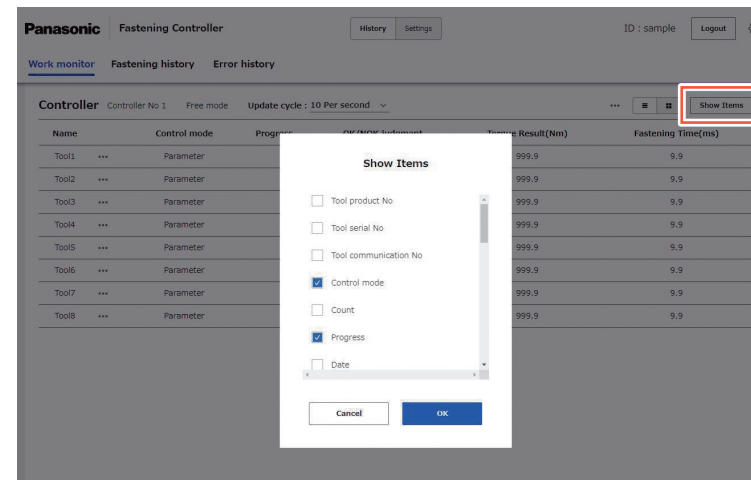


Vista de cuadrícula



Selección de elementos a mostrar

Seleccione los elementos que desea mostrar utilizando "Show Items".



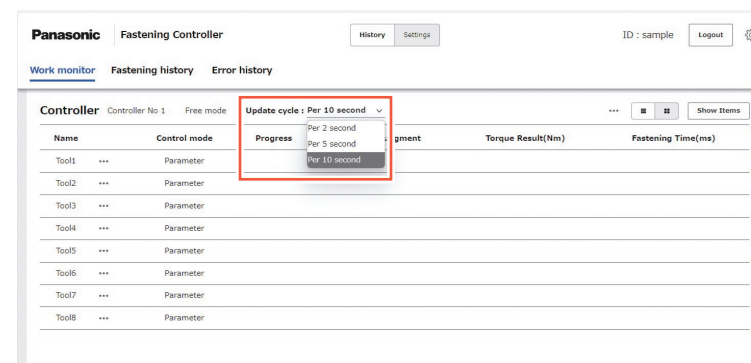
* En "Vista de lista", puede desplazarse hacia abajo y seleccionar muchos elementos para mostrarlos.

* En "Vista de cuadrícula", puede mostrar hasta 5 elementos.

Selección del ciclo de actualización de la pantalla

Puede establecer la actualización automática de la pantalla.

Seleccione el ciclo de actualización de "Per 2 second", "Per 5 second" y "Per 10 second" como se indica a continuación.



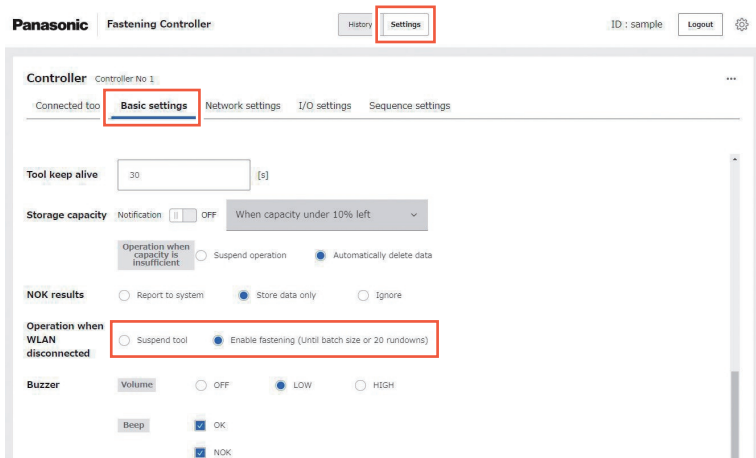
* Si se conecta un gran número de herramientas o PC para la configuración, se recomienda el ciclo de actualización de "Per 10 second". (Puede tardar algún tiempo en procesar los datos).

COMPORTAMIENTO DE LAS HERRAMIENTAS CON LA COMUNICACIÓN INALÁMBRICA DESCONECTADA

Puede continuar la fijación con los mismos parámetros en caso de interrupción temporal de la comunicación inalámbrica entre una herramienta y el controlador. Los resultados del trabajo de las herramientas durante la desconexión de la comunicación inalámbrica se notifican al controlador “Cuando la herramienta se vuelve a conectar” o “En la primera fijación tras recuperar la conexión de la herramienta”.



En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior y seleccione la pestaña “Basic settings”. Si ajusta “Operation when WLAN disconnected” en “Suspend tool”, la fijación en curso finaliza tras la interrupción, pero no se realiza ninguna otra fijación. Si ajusta “Enable fastening”, no se realizan más fijaciones una vez que la cantidad fijada ha alcanzado el límite superior.



Con “Enable fastening”, las cantidades del límite superior por modo son las siguientes.

Modo		Comportamiento
Free mode		Continúa fijando hasta 20 tornillos
Repeat mode	Basic mode	Continúa apretando hasta el final del lote o hasta 20 tornillos
	Sequence mode	Continúa fijando hasta el final del lote o hasta 20 tornillos * Herramientas distintas de las afectadas siguen funcionando con normalidad.
External control mode		Continúa apretando hasta el final del lote o hasta 20 tornillos

REINICIO DEL RECUENTO DURANTE EL FUNCIONAMIENTO

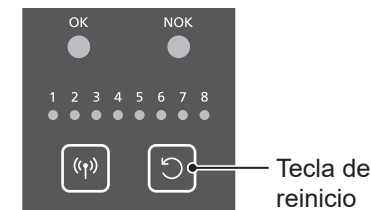
Para cambiar los ajustes, detenga el control de fijación mediante el controlador si está en curso. Aparece un cuadro de diálogo de confirmación cuando se aplica el cambio. Puede reiniciar las cantidades contadas por “Uso de la tecla en la unidad” o “Ajuste en la pantalla de ajustes”.

* Esto no se aplica a “Free mode”.

Uso de la tecla en la unidad

Mantenga pulsada la tecla Reiniciar en el controlador 3 segundos o más.

* Se reinician las cantidades de todas las herramientas activas.

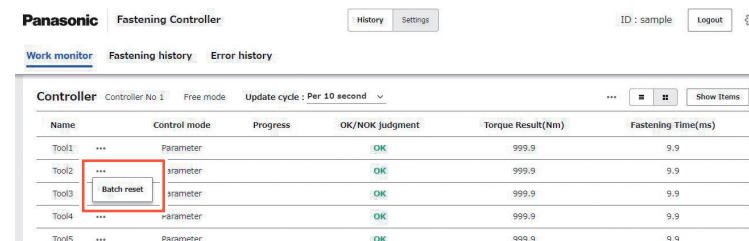


Ajuste en la pantalla de ajustes

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Work monitor”.

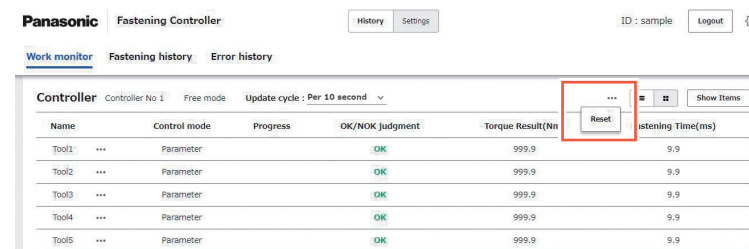
■ Para restablecer las cantidades por herramienta

En la pantalla “Work monitor”, haga clic en ... (tecla de opción de la herramienta) y luego en [Batch reset] del número de herramienta deseado.



■ Para restablecer las cantidades de todas las herramientas de forma colectiva

En la pantalla “Work monitor”, haga clic en ... (tecla de opción del controlador) y luego en [Reset] en la parte superior derecha.



* En el Sequence mode, las cantidades se restablecen hasta la primera herramienta.

Visualización de los datos del historial de fijación

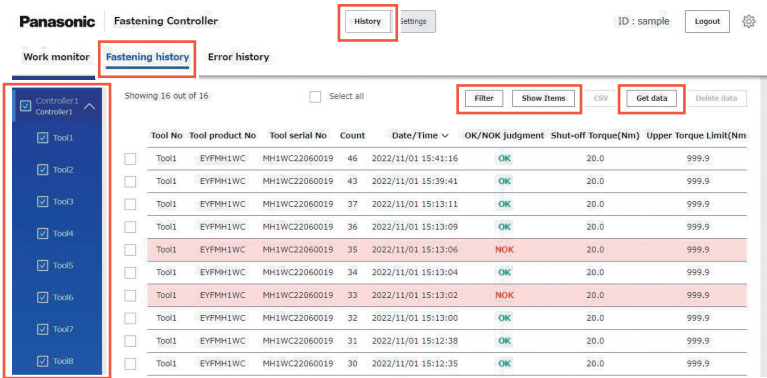
En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Fastening history”.

Puede ver los datos del historial de fijación enviados desde las herramientas al controlador.

Para visualizar los datos, seleccione el controlador y las herramientas deseados en la lista de herramientas a la izquierda y haga clic en [Get data] en la parte superior derecha.

Los registros del historial de fijación se muestran del más reciente al más antiguo.

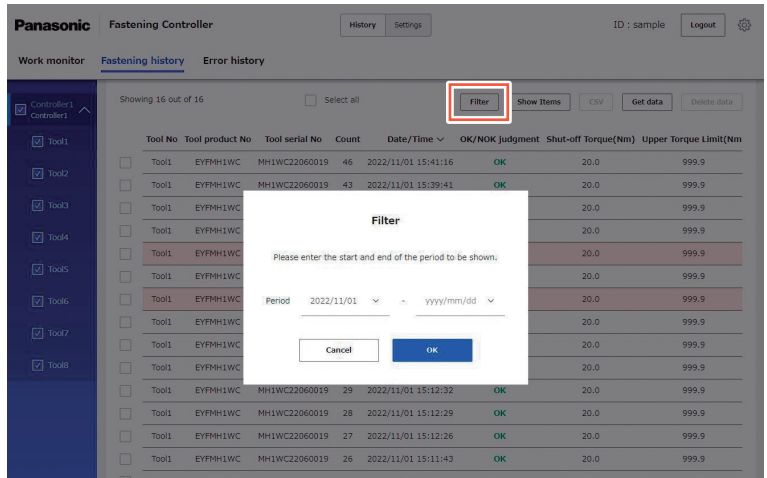
* Para el contenido de los elementos del historial de fijación, consulte el Manual de instrucciones de la herramienta.



Lista de herramientas

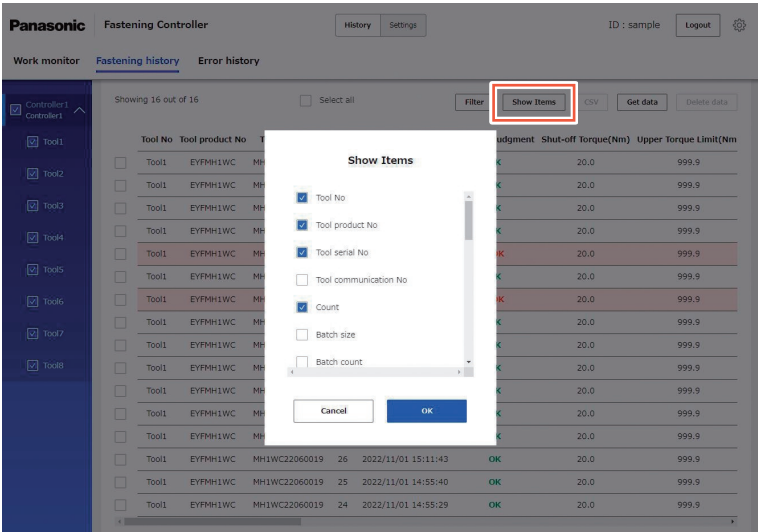
Extracción de los registros del historial de fijación por período de tiempo

Haga clic en [Filter] y especifique el período de tiempo para limitar los registros del historial de fijación a visualizar.



Elementos de ajuste a visualizar

Para cambiar los elementos visualizados, haga clic en [Show Items] y seleccione los elementos deseados.



Capacidad para los datos del historial de fijación

El controlador puede almacenar un máximo de unos 200,000 registros del historial de fijación (incluidos los datos de forma de onda).

Suspende el funcionamiento o borra automáticamente los registros (sobrescribiéndolos) si recibe más registros.

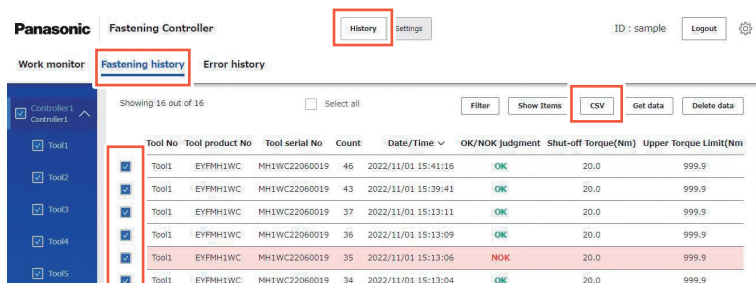
Se recomienda exportar periódicamente los registros en formato CSV según sea necesario consultando la guía que figura a continuación.

Tiempo estimado para alcanzar la plena capacidad de almacenamiento

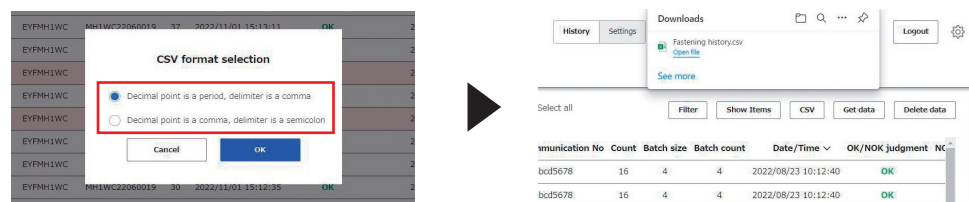
Número de herramientas	Cantidad por día por herramienta		
	1,000	3,000	5,000
2	Aproximadamente 100 días	Aproximadamente 33 días	Aproximadamente 20 días
4	Aproximadamente 50 días	Aproximadamente 16 días	Aproximadamente 10 días
8	Aproximadamente 25 días	Aproximadamente 8 días	Aproximadamente 5 días

Exportación de los datos del historial de fijación en formato CSV

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Fastening history”.
 Seleccione los registros deseados y haga clic en [CSV].
 Los registros del historial de fijación se exportan en formato CSV.

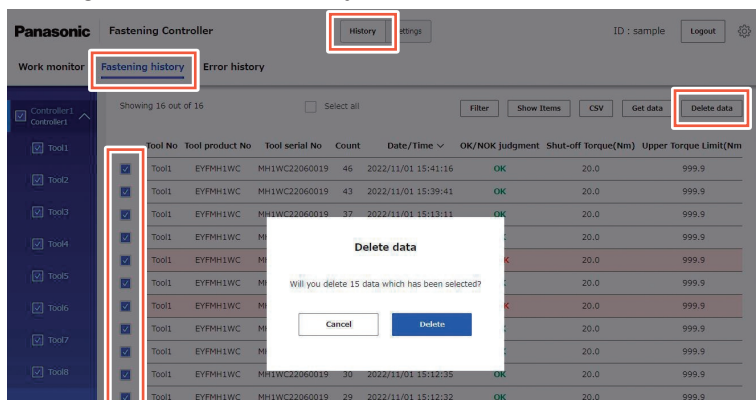


Puede seleccionar entre “Decimal point is a period, delimiter is a comma” y “Decimal point is a comma, delimiter is a semicolon”.



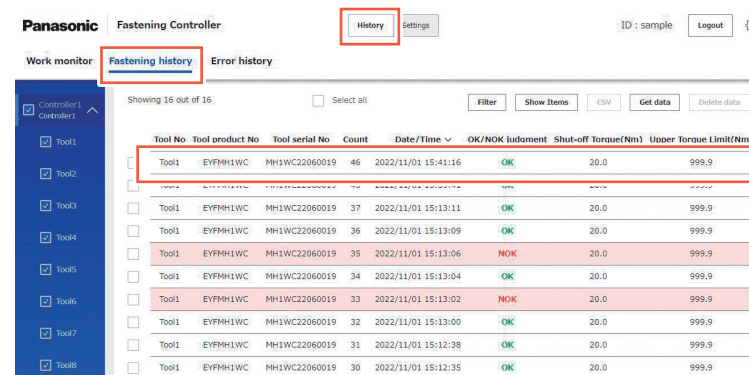
Borrado de los datos del historial de fijación

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Fastening history”.
 Seleccione los registros deseados y haga clic en [Delete data].
 Se borran los registros del historial de fijación.

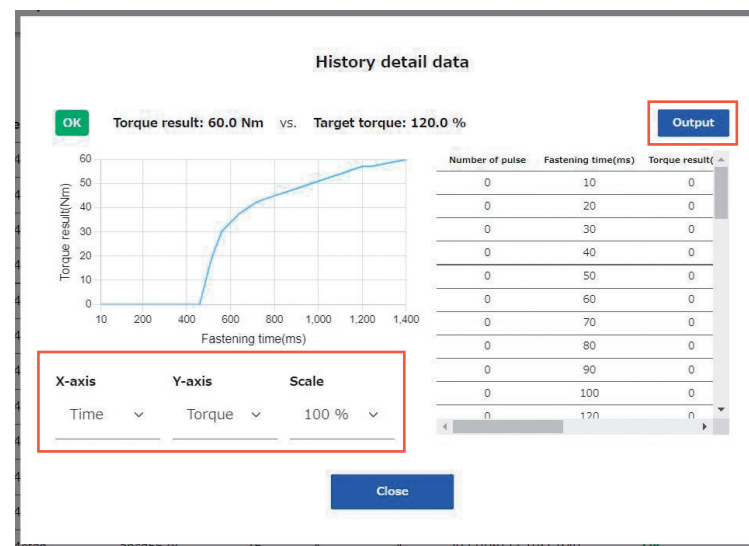


Visualización de los datos de forma de onda

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Fastening history”.
 Si ha habilitado la opción de guardar datos de forma de onda, puede hacer doble clic en la fila del registro histórico de fijaciones deseado para mostrar una ventana emergente de datos de forma de onda.



Puede ajustar la visualización seleccionando “X-axis”, “Y-axis” y “Scale”.
 Hacer clic en [Output] exporta los datos en formato CSV.

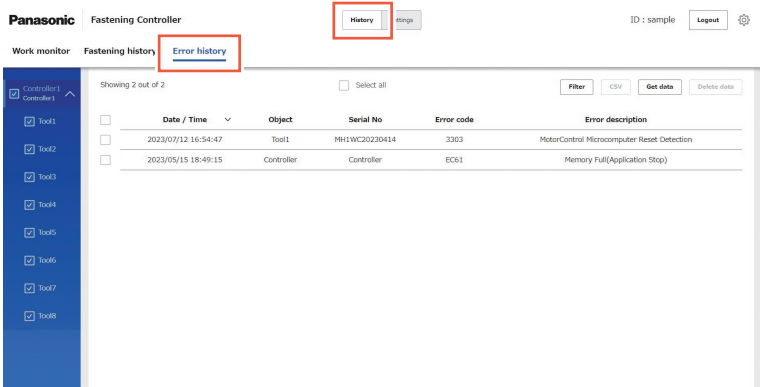


* Ajuste “Graph sending timing” en “Device settings” a “After every fastening”.

Visualización del historial de errores

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [History] en la parte superior y seleccione la pestaña “Error history”.

Se muestra el historial de errores que se han producido.



A continuación se muestran los elementos visualizados.

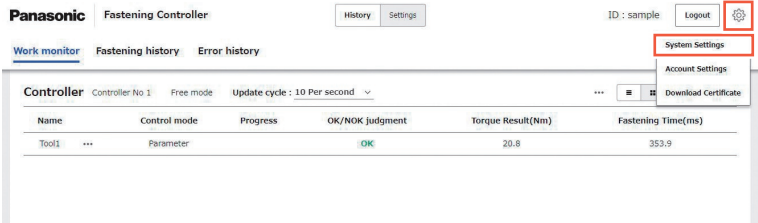
* Para el contenido del error, consulte “CÓDIGO DE ERROR”. **Consulte P96**

Date / Time
Se muestran la fecha y la hora de la ocurrencia del error.
Object
Se muestra el dispositivo (e controlador o cualquiera de las herramientas del 1 al 8) que causa un error.
Serial No
Se muestra el número de serie del dispositivo (el controlador o cualquiera de las herramientas 1 a 8) que causa un error.
Error code
Se visualiza un código de error que ha ocurrido.
Error description
Se muestra el contenido de un error que se ha producido.

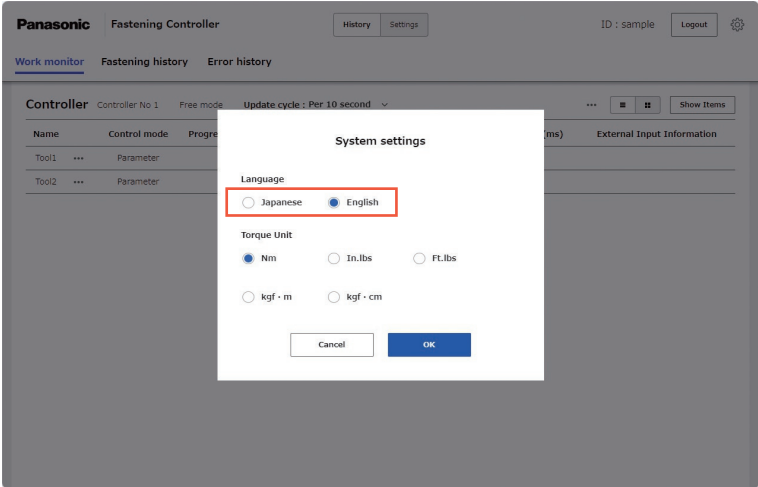
Cambio del idioma

Puede seleccionar “Japanese” o “English”.

- 1
- En la página superior (la página inicial de la pantalla de ajustes), haga clic en la tecla de opción de la parte superior derecha y seleccione “System Settings”.
Se visualiza la pantalla “System settings”.



- 2
- Seleccione el idioma en la pantalla “System settings”.
Puede seleccionar “Japanese” o “English”.

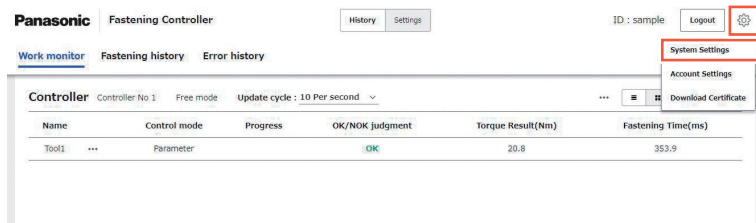


Cambio de la unidad de par de torsión a visualizar

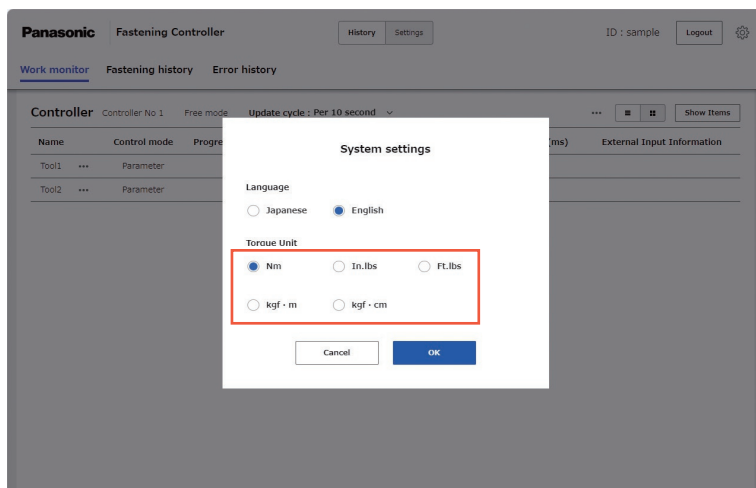
Puede seleccionar “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m” o “kgf·cm”.

- 1 En la página superior (la página inicial de la pantalla de ajustes), haga clic en la tecla de opción de la parte superior derecha y seleccione “System Settings”.

Se visualiza la pantalla “System settings”.



- 2 Seleccione la unidad del par en la pantalla “System settings”. Puede seleccionar la unidad de par de entre “Nm”, “In.lbs”, “Ft.lbs”, “kgf·m” y “kgf·cm”.

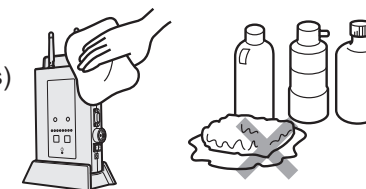


* Las pantallas de algunas unidades pueden experimentar correcciones numéricas.

Cómo limpiar

Limpieza con un paño suave

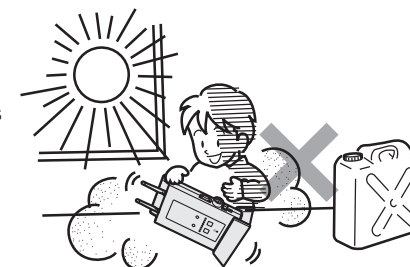
No utilice paños húmedos, diluyente, alcohol, bencina u otros líquidos volátiles.
(Causa de decoloración, deformación o grietas)



Cómo almacenar

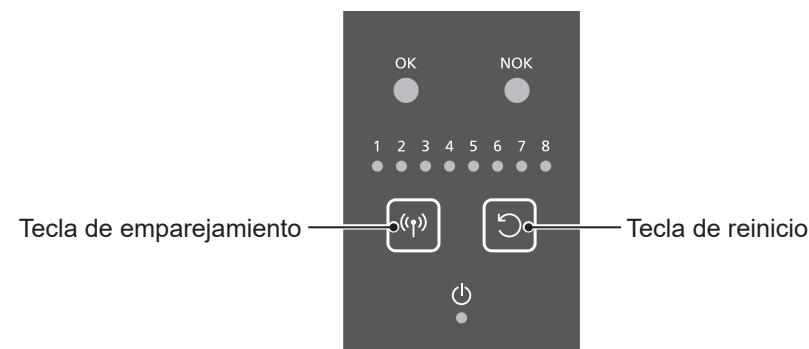
Evite las siguientes condiciones durante el almacenamiento.

- Cabina del coche u otros lugares calientes
- Lugares expuestos a la luz solar directa
- Lugares expuestos al agua o a la humedad
- Lugares con mucho polvo o cuerpos extraños
- Lugares al alcance de los niños
- Lugares con gasolina u otros productos inflamables
- Lugares con riesgo de caída



Inicialización del controlador

Para inicializar (restablecimiento de fábrica) el controlador, mantenga pulsadas simultáneamente la tecla Emparejamiento y la tecla Reiniciar 10 segundos o más.



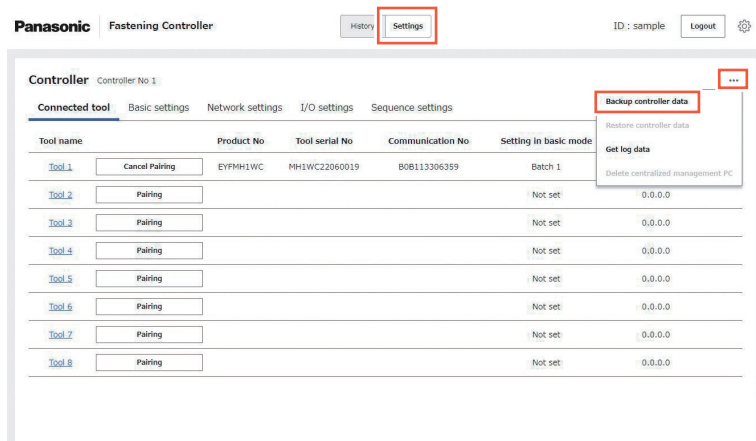
* Puede tardar más de 5 minutos dependiendo del uso de almacenamiento.

* No puede realizarla cuando las teclas de la unidad están deshabilitadas.

Consulte P72

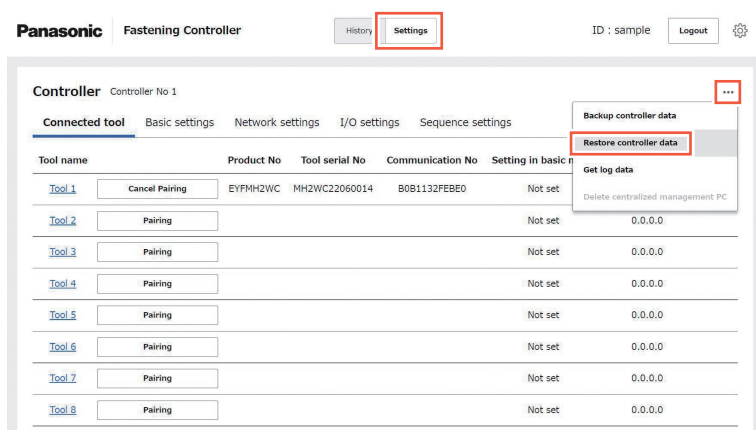
Realización de una copia de seguridad de los ajustes

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior.
Haga clic en ... (tecla de opción del controlador) y luego en [Backup controller data].
Puede realizar una copia de seguridad de los ajustes del controlador y de las herramientas.
* No se realiza una copia de seguridad de los datos del historial de fijación. Expórtelos en formato CSV si es necesario.



Restauración de los ajustes

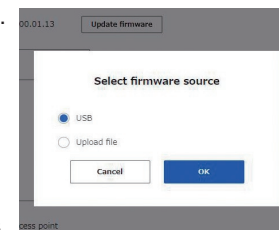
En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior.
Haga clic en ... (tecla de opción del controlador) y luego en [Restore controller data].
Puede restaurar los ajustes del controlador y las herramientas desde su copia de seguridad.
* No puede realizarlo durante el control de fijación.
* No puede realizarlo al registrar el emparejamiento con herramientas. Cancele el emparejamiento.



Actualización del firmware

Puede actualizar el firmware del controlador y la parte de comunicación de la herramienta.

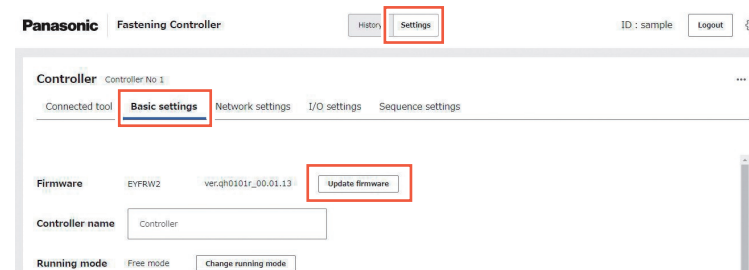
- ① Uso del puerto USB del controlador.
 - * No se puede utilizar una memoria USB con bloqueo por contraseña.
 - * Guarde solo archivo de datos de firmware directamente en una unidad flash USB sin crear una carpeta.
- ② Escritura desde el PC para la configuración.
 - * Al seleccionar "Upload file", seleccione el archivo de datos de firmware guardado en el PC en la pantalla de selección.



Para obtener la versión actual del firmware, visite nuestro sitio web. **Consulte P2**
O póngase en contacto con nuestra persona de ventas.

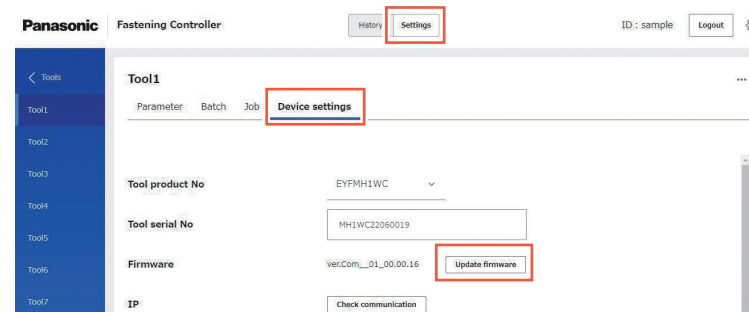
■ Para el controlador

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior, seleccione la pestaña "Basic settings" y haga clic en [Update firmware].



■ Para la parte de comunicación de la herramienta

En la página superior (la página inicial de la pantalla de configuración), haga clic en [Settings] en la parte superior y seleccione la pestaña "Connected tool".
En la pantalla "Connected tool", haga clic en el número de herramienta deseado.
Desde la pestaña "Device settings" en la pantalla para el número de herramienta, haga clic en [Update firmware].



Sustitución de la pila de botón

Para mantener en funcionamiento el reloj (RTC) del controlador, sustituya la pila de botón consultando la siguiente guía de sustitución.

■ Tipo de pila



CR2450

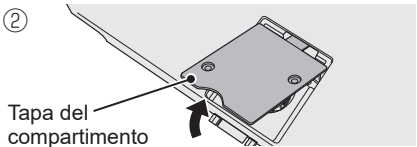
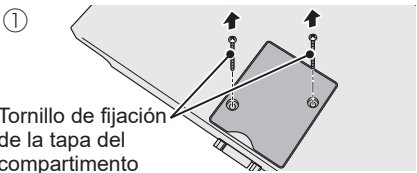
■ Guía de sustitución

La pila de botón se utiliza para mantener el reloj en funcionamiento cuando el controlador está apagado. Para minimizar su consumo, en principio, no apague el control.

La alimentación está encendida 12 horas al día (solo los días laborales)	La alimentación está siempre encendida
Aproximadamente 3 años	Aproximadamente 8 años

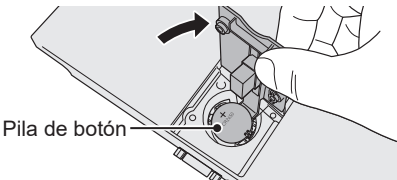
Sustitúyala con el siguiente procedimiento o póngase en contacto con su distribuidor. Se recomienda que una persona que tenga conocimientos eléctricos realice el trabajo.

1 Extraiga los 2 tornillos de fijación de la tapa del compartimento y, a continuación, retire la tapa del compartimento.

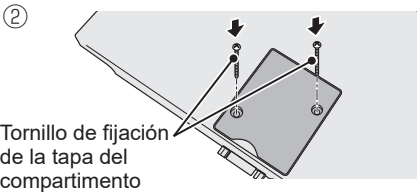
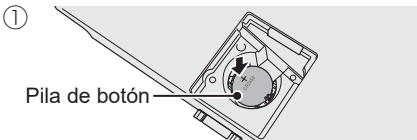


2 Usando la tapa del compartimento, saque la pila de botón.

Coja la pila de botón con el gancho de la tapa del compartimento.

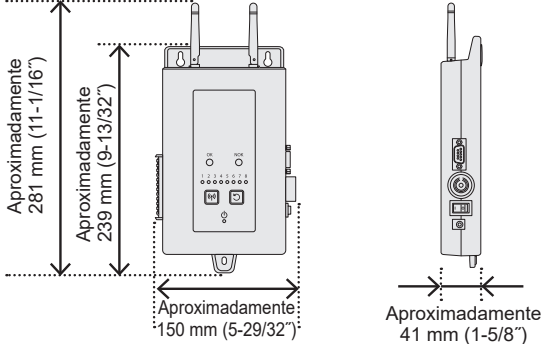


3 Coloque una nueva pila de botón y coloque la tapa del compartimento con los 2 tornillos de fijación de la tapa del compartimento.



Especificaciones del controlador

Recepción de señales de finalización y fallo de fijación durante los trabajos de montaje de productos de interior

Núm. de modelo	EYFRW2
Fuente de alimentación	100 V-240 V CA, 50/60 Hz
Estándar de comunicación inalámbrica	LAN inalámbrica (IEEE.802.11 a/b/g/n)
Banda de frecuencia	2.4 GHz: de 2.412 GHz a 2.462 GHz 5 GHz: de 5.180 GHz a 5.240 GHz
Canal	2.4 GHz: de 1 a 11 canales 5 GHz: 36, 40, 44, 48 canales
Cobertura	2.4 GHz: aproximadamente 16 m (52.5 ft) 5 GHz: aproximadamente 10 m (32.8 ft)
Número de herramientas que se pueden registrar	8 (máximo)
Terminales de entrada/salida (E/S)	8 entradas y 8 salidas
Clasificación del terminal de entrada	24 V CC, 50 mA
Clasificación del terminal de salida	30 V CC, 3 A
Consumo de energía	Aproximadamente 30 W
Intervalos de temperatura y humedad de funcionamiento	De 0 °C (32 °F) a 45 °C (113 °F), del 20 % al 90 %
Tamaño (dimensiones estimadas) Longitud total × Altura total × Anchura	Aproximadamente 150 × 239 × 41 mm (5-29/32" × 9-13/32" × 1-5/8") (altura incluyendo las antenas: 281 mm (11-1/16")) 
Masa (Peso)	Alrededor de 550 g (1.1 lbs) (unidad principal solamente)
Interfaz de comunicación	Ethernet × 2, RS232C × 1, USB-A × 1
Número de datos que se pueden almacenar	Aproximadamente 200 000 registros del historial de fijación (incluyendo datos de forma de onda)
Modelos de herramientas compatibles	EYFNH1WC/WP*, EYFMH1WC/WP, EYFMH2WC/WP

*1 Esto solo es compatible con la versión de firmware 2.02.00 o posterior.

Especificaciones inalámbricas

Frecuencias por canal

Banda de frecuencia	Canal	Frecuencia
2.4 GHz	Canal 1	2.412 GHz
	Canal 2	2.417 GHz
	Canal 3	2.422 GHz
	Canal 4	2.427 GHz
	Canal 5	2.432 GHz
	Canal 6	2.437 GHz
	Canal 7	2.442 GHz
	Canal 8	2.447 GHz
	Canal 9	2.452 GHz
	Canal 10	2.457 GHz
	Canal 11	2.462 GHz
5 GHz	Canal 36	5.180 GHz
	Canal 40	5.200 GHz
	Canal 44	5.220 GHz
	Canal 48	5.240 GHz

Especificaciones WebUI

SO compatible	Windows 10 o posterior (compatible con cualquiera de los siguientes navegadores web)
Navegador web compatible	Microsoft Edge versión 102 o posterior o Google Chrome versión 102 o posterior
Idioma compatible	Español, Japonés
Resolución de pantalla recomendada	1024 × 768 o superior

PRECAUCIÓN

- Algunos PC no están disponibles incluso si cumplen con el entorno operativo.
- En función del entorno de uso, etc., de su PC, las descripciones y pantallas de este Manual de instrucciones podrían ser diferentes de las descripciones y pantallas reales.
Por favor, téngalo en cuenta.
- El contenido de este Manual de instrucciones está sujeto a cambios sin previo aviso.
- Cualquier reproducción del contenido de este Manual de instrucciones, en su totalidad o en parte, está prohibida sin permiso.
- Las descripciones sobre cómo operar Windows en este Manual de instrucciones usan los procedimientos y pantallas de Windows 10.
- WebUI no funciona en un SO distinto al SO compatible.
- No se garantiza el funcionamiento para todos los PC que cumplan con el entorno recomendado.

■ Condiciones de uso (lea antes del uso)

<Limitaciones>

WebUI es el software de configuración para EYFRW2.

PRECAUCIÓN

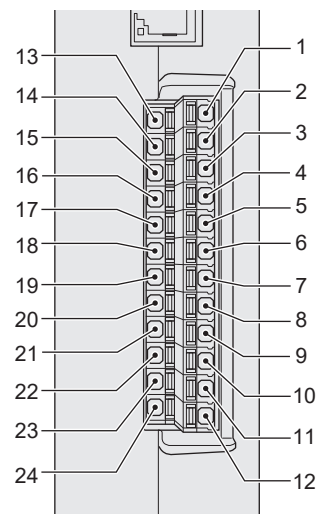
- Tenga en cuenta lo siguiente cuando utilice la función.
Se considera que está de acuerdo con los siguientes términos de uso usando la función.

[Condiciones de uso]

Panasonic no ofrece ninguna garantía de ningún tipo con respecto a la función. Panasonic no se hace responsable de ningún daño, incluidos, aunque sin limitarse a ellos, los daños directos, indirectos, por propagación, consecuentes y especiales causados por el uso o funcionamiento de la función. La reproducción y distribución no autorizadas de la función está prohibida.

Especificaciones de E/S de contacto

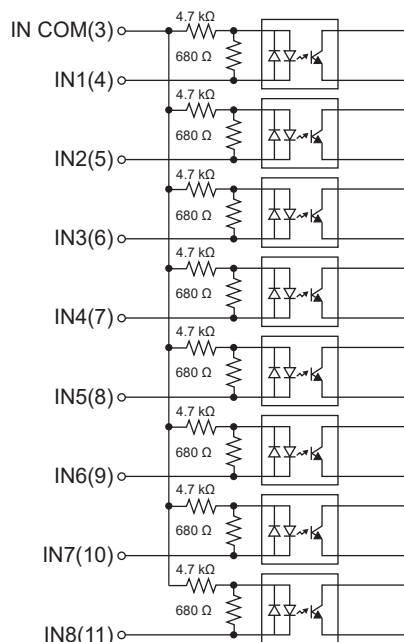
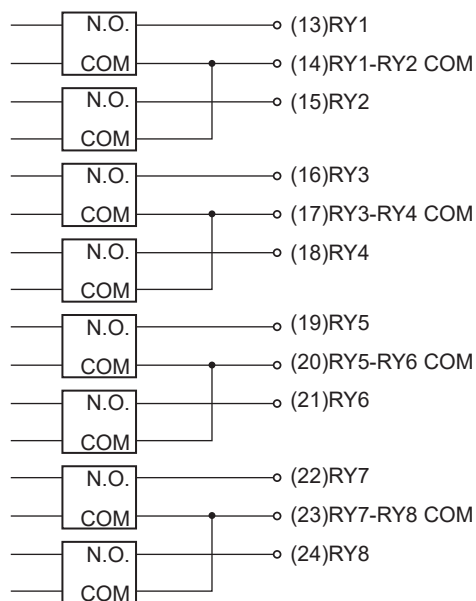
Asignación entre terminales de relé de salida y terminales de entrada



Núm.	Asignación de contactos
1	+24 V
2	+24 V
3	IN COM
4	IN 1
5	IN 2
6	IN 3
7	IN 4
8	IN 5
9	IN 6
10	IN 7
11	IN 8
12	24 V return

Núm.	Asignación de contactos
13	RY1
14	RY1-RY2 COM
15	RY2
16	RY3
17	RY3-RY4 COM
18	RY4
19	RY5
20	RY5-RY6 COM
21	RY6
22	RY7
23	RY7-RY8 COM
24	RY8

Diagrama de conexión del bloque de terminales



Declaración de texto explicativo para varios requisitos

Este dispositivo cumple con el Apartado 15 de las regulaciones de FCC. La operación está sujeta a las siguientes dos condiciones (1) Este dispositivo no puede ocasionar interferencias que ocasionen daños y (2) este dispositivo debe aceptar cualquier interferencia, incluida una interferencia que pueda ocasionar una operación no deseada.

Precaución de FCC: Para asegurar un cumplimiento continuo, instale y use el equipo según las instrucciones provistas. Cualquier cambio o modificación no aprobada expresamente por el grupo responsable de su certificación puede anular el derecho del usuario sobre el uso del equipo.

Este equipo ha sido probado y se ha determinado que cumple con las limitaciones de un dispositivo digital de Clase B, de conformidad con el Apartado 15 de las regulaciones de FCC. Estas limitaciones están diseñadas para brindar protección razonable contra las interferencias perjudiciales en un entorno residencial. Este equipo genera, utiliza y puede irradiar energía de radiofrecuencia y, si no se instala y utiliza de acuerdo a las instrucciones, puede provocar interferencias perjudiciales en las comunicaciones de radio. Sin embargo, no existe ninguna garantía de que no se produzcan interferencias en una instalación concreta. Si este equipo provoca interferencias perjudiciales en la recepción de radio o televisión, lo que se puede determinar apagando y encendiendo el equipo, se recomienda al usuario intentar corregir la interferencia adoptando una de las siguientes medidas:

- Cambie la orientación o posición de la antena receptora.
- Aumente la separación entre el equipo y el receptor.
- Conecte el equipo en una toma de corriente de un circuito que no sea el mismo en el que está conectado el receptor.
- Consulte por ayuda a un proveedor o un técnico de radio/televisión con experiencia.

Contiene el ID de la FCC: Z64-WL18DBMOD Contiene el IC: 4511-WL18DBMOD

Este transmisor no debe colocarse ni utilizarse junto con ninguna otra antena o transmisor.

Este equipo cumple con los límites de exposición a la radiación de la FCC establecidos para un entorno no controlado. Este equipo ha sido aprobado para el uso móvil que requiere un espacio mínimo de 20 cm (7-7/8") entre la(s) antena(s) y el cuerpo de la persona (excluyendo las extremidades de manos, muñecas y pies) durante los modos inalámbricos de funcionamiento. Este equipo no debe colocarse ni utilizarse con ninguna otra antena o transmisor.

Este equipo cumple con los límites de exposición a la radiación de ISED establecidos para un entorno no controlado y cumple con RSS-102 de las reglas de exposición a radiofrecuencia (RF) de ISED. Este equipo debe ser instalado y operado manteniendo el radiador al menos a 20 cm (7-7/8") o más alejado del cuerpo de la persona.

Este dispositivo contiene transmisor(es)/receptor(es) exentos de licencia que cumplen con los RSS exentos de licencia de Innovación, Ciencia y Desarrollo Económico de Canadá. Su funcionamiento está sujeto a las dos condiciones siguientes:

1. Este dispositivo no puede causar interferencias.
2. Este dispositivo debe aceptar cualquier interferencia, incluidas las que puedan causar un funcionamiento no deseado del dispositivo.

Solo para uso en interiores.

PRECAUCIONES PARA LA COMUNICACIÓN INALÁMBRICA

Precauciones al utilizar un dispositivo WLAN

El dispositivo utiliza una banda de frecuencia compartida con otros tipos de equipos, incluidos dispositivos industriales, científicos y médicos (por ejemplo, un microondas) y estaciones de radio como una estación de radio local (con licencia) y una estación de radio de baja potencia (con licencia) para la identificación móvil utilizada en las líneas de fabricación de fábrica y una estación de radio de aficionados (con licencia).

1. Antes de usar el dispositivo, confirme que no haya instalaciones o estaciones de radio de baja potencia para la identificación móvil o que no haya emisoras de radioaficionados en las cercanías.
2. Si el dispositivo causa interferencias perjudiciales con una estación de radio local para la identificación móvil, detenga inmediatamente el uso de la banda y consulte el centro de asistencia siguiente para la solución del problema de interferencia (por ejemplo, instalación de una partición).
3. Si el dispositivo causa interferencias dañinas con un local o estación de radio de baja potencia para la identificación móvil o una estación de radioaficionados u otros problemas, consulte con el centro de asistencia.

■ Puede haber ruido, menor cobertura de radio o mal funcionamiento en las siguientes condiciones ambientales.

- Hay una obstrucción (por ejemplo, un objeto metálico o de concreto reforzado) que impide la propagación uniforme de la radio entre la unidad de herramienta con conexión inalámbrica y el controlador.
- Las antenas del controlador están cubiertas de metal.
- El cuerpo de un operador está interfiriendo con la propagación de la radio entre un operador (la unidad de herramienta con conexión inalámbrica) y el controlador.
- Hay cerca un microondas, un PC o cualquier otro dispositivo que genere ruido.
- Se utiliza un teléfono móvil o un teléfono PHS cerca de la unidad de herramienta con conexión inalámbrica y el controlador.

Términos de la licencia del software

Este producto incorpora el siguiente software:

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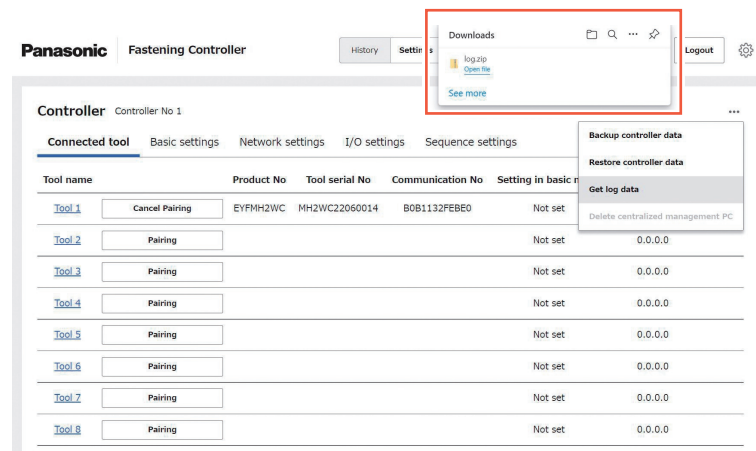
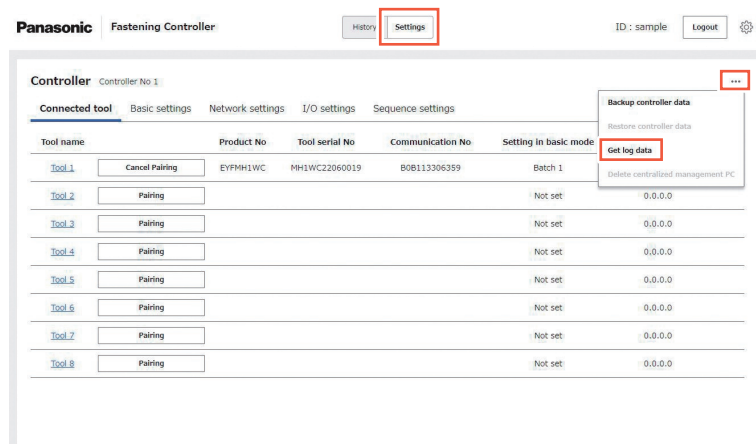
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Dispositivo	Código de error	Tipo	Categoría	Evento	Acción
Controlador	0xEF21	Advertencia	Fallo de hardware	Error de la CPU secundaria (fallo)	Reinicie el controlador. Si el problema persiste, es posible que el dispositivo esté roto. Póngase en contacto con su distribuidor.
	0xEF51	Advertencia	Fallo de hardware	Error Ether0	El dispositivo podría estar roto. Póngase en contacto con su distribuidor.
	0xEF52	Advertencia	Fallo de hardware	Error Ether1	El dispositivo podría estar roto. Póngase en contacto con su distribuidor.
	0xEF61	Advertencia	Fallo de hardware	Error del módulo WLAN (fallo)	Reinicie el controlador. Si el problema persiste, es posible que el dispositivo esté roto. Póngase en contacto con su distribuidor.
	0xCE42	Error	Fallo de software	Error de contenido del ajuste	Restablezca los ajustes de fábrica del controlador y vuelva a realizar los ajustes.
	0xCE43	Error	Fallo de software	Error de información de retracción	Mantenga pulsada la tecla de reinicio en el controlador 3 segundos o más.
	0xEC61	Advertencia	Fallo de software	La capacidad para almacenar el historial de fijación está llena (funcionamiento suspendido)	Borre los registros del historial de fijación en la pantalla del historial de fijación para liberar cierta capacidad. Expórtelos antes de borrarlos si es necesario.
Herramienta	0x4301	Precaución	Fallo de software	La capacidad de almacenamiento está llena	Acceda al software de configuración de la herramienta (software Tool Manager) y borre los registros del historial de trabajo.
	0x4302	Precaución	Fallo de software	El número de resultados de envío en una cola ha alcanzado el límite superior.	La herramienta no se puede comunicar con el controlador. Cambie el lugar de trabajo. Si el problema persiste, es posible que el dispositivo esté roto. Póngase en contacto con su distribuidor.
	0x3303	Error	Fallo de software	Restablecimiento del microcontrolador de control del motor detectado	Se ha resuelto un error.
	0x3304	Error	Fallo de software	Restablecimiento del microcontrolador de cálculo de par detectado	Se ha resuelto un error.

Dispositivo	Código de error	Tipo	Categoría	Evento	Acción
Herramienta	0x4305	Precaución	Fallo de software	Pila RTC baja	Sustituya la pila de botón dentro de la unidad de la herramienta.
	0x4306	Precaución	Fallo de software	Error de actualización del firmware	Confirme que el archivo de firmware es correcto.
	0x4315	Precaución	Fallo de software	Error de comunicación USB	Se ha resuelto un error.
	0x4316	Precaución	Fallo de software	Módulo WLAN reiniciado	Se ha resuelto un error.
	0x1401	Advertencia	Fallo de hardware	Error del módulo WLAN	Se ha resuelto un error.
	0x1402	Advertencia	Fallo de hardware	Error del microcontrolador de control del motor	Se ha resuelto un error.
	0x1403	Advertencia	Fallo de hardware	Error del microcontrolador de cálculo de par	Se ha resuelto un error.
	0x1404	Advertencia	Fallo de hardware	Error de la unidad flash externa	Se ha resuelto un error.
	0x1405	Advertencia	Fallo de hardware	Error RTC	Se ha resuelto un error.
	0x1406	Advertencia	Fallo de hardware	Error de identificación del circuito	Se ha resuelto un error.
	0x1407	Advertencia	Fallo de hardware	No queda espacio de intercambio	Se ha resuelto un error.
	0x1408	Advertencia	Fallo de hardware	Espacio del parámetro dañado	Se ha resuelto un error.

En la página superior (la página inicial de la pantalla de ajustes), haga clic en [Settings] en la parte superior.
Haga clic en ... (tecla de opción del controlador) y luego en [Get log data].
Puede obtener los registros de funcionamiento del controlador.



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27.5.2.4.5 Consume some sequence of the characters in the pending sequence. virtual int_type overflow(int_type __c = _Traits::eof());
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```

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```
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```

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```
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program `Gnomovision' (a program to direct compilers to make passes
at assemblers) written by James Hacker.
```

```
<signature of Ty Coon>, 1 April 1989
Ty Coon, President of Vice
```

That's all there is to it!

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```

```
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When a program is linked with a library, whether statically or using a shared library, the combination of the two is legally speaking a combined work, a derivative of the original library. The ordinary General Public License therefore permits such linking only if the entire combination fits its criteria of freedom. The Lesser General Public License permits more lax criteria for linking other code with the library.

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For example, on rare occasions, there may be a special need to encourage the widest possible use of a certain library, so that it becomes a de-facto standard. To achieve this, non-free programs must

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Although the Lesser General Public License is Less protective of the users' freedom, it does ensure that the user of a program that is linked with the Library has the freedom and the wherewithal to run that program using a modified version of the Library.

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""Source code"" for a work means the preferred form of the work for making modifications to it. For a library, complete source code means all the source code for all modules it contains, plus any associated interface definition files, plus the scripts used to control compilation and installation of the library.

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This option is useful when you wish to copy part of the code of the Library into a program that is not a library.

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LICENSE TERMS (cont.)

Library will still fall under Section 6.)

Otherwise, if the work is a derivative of the Library, you may distribute the object code for the work under the terms of Section 6. Any executables containing that work also fall under Section 6, whether or not they are linked directly with the Library itself.

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You must give prominent notice with each copy of the work that the Library is used in it and that the Library and its use are covered by this License. You must supply a copy of this License. If the work during execution displays copyright notices, you must include the copyright notice for the Library among them, as well as a reference directing the user to the copy of this License. Also, you must do one of these things:

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Finally, every program is threatened constantly by software patents. States should not allow patents to restrict development and use of software on general-purpose computers, but in those that do, we wish to avoid the special danger that patents applied to a free program could make it effectively proprietary. To prevent this, the GPL assures that patents cannot be used to render the program non-free.

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b) Convey the object code in, or embodied in, a physical product (including a physical distribution medium), accompanied by a written offer, valid for at least three years and valid for as long as you offer spare parts or customer support for that product model, to give anyone who possesses the object code either (1) a copy of the Corresponding Source for all the software in the product that is covered by this License, on a durable physical medium customarily used for software interchange, for a price no more than your reasonable cost of physically performing this conveying of source, or (2) access to copy the Corresponding Source from a network server at no charge.

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Version 3.1, 31 March 2009

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5. [6]Michael Barone <michael.barone@lmco.com> GPSVME fixes
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7. [8]Greg Brackley <greg.brackley@bigfoot.com> Major rework of WINNT port. Clean up rcvbuf and iosignal code into separate modules.
8. [9]Marc Brett <Marc.Brett@westgeo.com> Magnavox GPS clock driver
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iconv (Charset Conversion Library) v2.0

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agere_sta_fw.bin -- 9.48 Hermes I
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Firmware provided by Patrick Boettcher <pboettcher@dibcom.fr> to Devin Heitmueller <dheitmuelle@kernellabs.com> on October 8, 2009.

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The following XC4000 firmware file "dvb-fe-xc4000-1.4.1.fw" was created based on version 1.4 of "xc4000_firmwares.h".

Firmware provided as part of an XC4000 Linux developers kit by Brian Mathews <bmathews@xceive.com> to Devin Heitmueller <dheitmueller@kernellabs.org> on July 1, 2009.

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Firmware provided as part of an XC5000C Linux developers kit by Ramon Cazares <Ramon.Cazares@CrestaTech.com> to Devin Heitmueller <dheitmueller@linuxtv.org> on July 25, 2012.

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Fast discrete Fourier and cosine transforms and inverses
author: Monty <xiphmont@mit.edu>
modifications by: Monty
last modification date: Jul 1 1996

/* These Fourier routines were originally based on the Fourier routines of the same names from the NETLIB bihar and fftpack fortran libraries developed by Paul N. Swarztrauber at the National Center for Atmospheric Research in Boulder, CO USA. They have been reimplemented in C and optimized in a few ways for OggSquish. */

/* As the original fortran libraries are public domain, the C Fourier routines in this file are hereby released to the public domain as well. The C routines here produce output exactly equivalent to the original fortran routines. Of particular interest are the facts that (like the original fortran), these routines can work on arbitrary length vectors that need not be powers of two in length. */

* WHENCE *

This file attempts to document the origin and licensing information, if known, for each piece of firmware distributed for use with the Linux kernel.

Driver: BCM-0bb4-0306 Cypress Bluetooth firmware for HTC Vive

File: brcm/BCM-0bb4-0306.hcd

Licence: Redistributable. See LICENCE.cypress for details.

Driver: ambassador -- Madge Ambassador (Collage PCI 155 Server) ATM NIC.

File: atmsar11.fw

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Driver: snd-korg1212 -- Korg 1212 IO audio device

File: korg/k1212.dsp

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Driver: snd-maestro3 -- ESS Allegro Maestro3 audio device

File: ess/maestro3_assp_kernel.fw
File: ess/maestro3_assp_minisc.fw

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Driver: snd-ymfpici -- Yamaha YMF724/740/744/754 audio devices

File: yamaha/ds1_ctrl.fw
File: yamaha/ds1_dsp.fw
File: yamaha/ds1e_ctrl.fw

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Driver: advansys - AdvanSys SCSI

File: advansys/mcode.bin
File: advansys/3550.bin
File: advansys/38C0800.bin
File: advansys/38C1600.bin

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Found in hex form in kernel source.

Driver: qla1280 - Qlogic QLA 1240/1x80/1x160 SCSI support

File: qllogic/1040.bin
File: qllogic/1280.bin
File: qllogic/12160.bin

Licence: Redistributable. See LICENCE.qla1280 for details

Driver: smctr -- SMC ISA/MCA Token Ring adapter

File: tr_smctr.bin
Version: 6.3C1
Info: MCT.BIN v6.3C1 03/01/95

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Driver: kaweth -- USB KLSI KL5USB101-based Ethernet device

File: kaweth/new_code.bin
File: kaweth/new_code_fix.bin
File: kaweth/trigger_code.bin
File: kaweth/trigger_code_fix.bin

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Driver: dvb-ttusb-budget -- Technotrend/Hauppauge Nova-USB devices

File: ttusb-budget/dspbootcode.bin

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Driver: keyspan -- USB Keyspan USA-xxx serial device

File: keyspan/mpr.fw
File: keyspan/usa18x.fw
File: keyspan/usa19.fw
File: keyspan/usa19qi.fw
File: keyspan/usa19qw.fw
File: keyspan/usa19w.fw
File: keyspan/usa28.fw
File: keyspan/usa28xa.fw
File: keyspan/usa28xb.fw
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File: keyspan/usa49w.fw
File: keyspan/usa49wlc.fw

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Driver: keyspan_pda -- USB Keyspan PDA single-port serial device

File: keyspan_pda/keyspan_pda.fw
Source: keyspan_pda/keyspan_pda.S

File: keyspan_pda/xircom_pgs.fw
Source: keyspan_pda/xircom_pgs.S

Source: keyspan_pda/Makefile

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Compiled from original 8051 source into Intel HEX, used in our binary ihex form.

Driver: emi26 -- EMI 2|6 USB Audio interface

File: emi26/bitstream.fw
Version: 1.1.1.131
Info: DATE=2001dec06

File: emi26/firmware.fw
Version: 1.0.2.916
Info: DATE=12.02.2002

File: emi26/loader.fw

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 */
```

Driver: emi62 -- EMI 6|2m USB Audio interface

File: emi62/bitstream.fw
Version: 1.0.0.191
Info: DATE= 2002oct28

File: emi62/loader.fw
Version: 1.0.2.002
Info: DATE=10.01.2002

File: emi62/midi.fw
Version: 1.04.062
Info: DATE=16.10.2002

File: emi62/spdif.fw
Version: 1.04.062
Info: DATE=16.10.2002

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Original licence information: None

Driver: ti_usb_3410_5052 -- USB TI 3410/5052 serial device

File: ti_3410.fw
Info: firmware 9/10/04 FW3410_Special_StartWdogOnStartPort

File: ti_5052.fw
Info: firmware 9/18/04

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Driver: ti_usb_3410_5052 -- Multi-Tech USB cell modems

File: mts_cdma.fw
File: mts_gsm.fw
File: mts_edge.fw

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Found in hex form in ftp://ftp.multitech.com/wireless/wireless_linux.zip

Driver: ti_usb_3410_5052 -- Multi-Tech USB fax modems

File: mts_mt9234mu.fw
File: mts_mt9234zba.fw

Licence: Unknown

Driver: whiteheat -- USB ConnectTech WhiteHEAT serial device

File: whiteheat.fw
Version: 4.06

File: whiteheat_loader.fw

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Debug loader claims the following behaviour:
Port 1 LED flashes when the vend_ax program is running
Port 2 LED flashes when any SETUP command arrives

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Port 3 LED flashes when any valid VENDOR request occurs
Port 4 LED flashes when the EXTERNAL RAM DOWNLOAD request occurs

Converted from Intel HEX files, used in our binary representation of ihex.

Driver: ip2 -- Computone IntelliPort Plus serial device

File: intelliport2.bin

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Driver: cpia2 -- cameras based on Vision's CPiA2

File: cpia2/stv0672_vp4.bin

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Contact: steve.miller@st.com
Description: This file contains patch data for the CPiA2 (stv0672) VP4.

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Driver: dabusb -- Digital Audio Broadcasting (DAB) Receiver for USB and Linux

File: dabusb/firmware.fw
File: dabusb/bitstream.bin

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Driver: vicam -- USB 3com HomeConnect (aka vicam)

File: vicam/firmware.fw

Licence: Unknown

Found in hex form in kernel source.

Driver: io_edgeport - USB Inside Out Edgeport Serial Driver

File: edgeport/boot.fw
File: edgeport/boot2.fw
File: edgeport/down.fw
File: edgeport/down2.fw

Licence: Allegedly GPLv2+, but no source visible. Marked:
/*
/* Edgeport/4 Binary Image
/* Generated by HEX2C v1.06
/* Copyright (C) 1998 Inside Out Networks, All rights reserved.
/*

Found in hex form in kernel source.

Driver: io_ti - USB Inside Out Edgeport Serial Driver
(TI Devices)

File: edgeport/down3.bin

Licence:
/*
/* Edgeport Binary Image (for TI based products)
/* Generated by TIBin2C v2.00 (watchport)
/* Copyright (C) 2001 Inside Out Networks, All rights reserved.
/*

Found in hex form in kernel source.

Driver: dsp56k - Atari DSP56k support

File: dsp56k/bootstrap.bin
Source: dsp56k/bootstrap.asm
Source: dsp56k/Makefile
Source: dsp56k/concat-bootstrap.pl

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

DSP56001 assembler, buildable with a56 from
<http://www.zdomain.com/a56.html>

Driver: snd-sb16-csp - Sound Blaster 16/AWE CSP support

File: sb16/mulaw_main.csp
File: sb16/alaw_main.csp
File: sb16/ima_adpcm_init.csp
File: sb16/ima_adpcm_playback.csp
File: sb16/ima_adpcm_capture.csp

LICENSE TERMS (cont.)

Licence: Allegedly GPLv2+, but no source visible. Marked:

```
/*  
 * Copyright (c) 1994 Creative Technology Ltd.  
 * Microcode files for SB16 Advanced Signal Processor  
 */
```

Found in hex form in kernel source.

Driver: qla2xxx - QLogic QLA2XXX Fibre Channel

File: ql2100_fw.bin
Version: 1.19.38 TP
File: ql2200_fw.bin
Version: 2.02.08 TP
File: ql2300_fw.bin
Version: 3.03.28 IPX
File: ql2322_fw.bin
Version: 3.03.28 IPX
File: ql2400_fw.bin
Version: 8.07.00 MID
File: ql2500_fw.bin
Version: 8.07.00 MIDQ

Licence: Redistributable. See LICENCE.qla2xxx for details

Available from <http://ldriver.qlogic.com/firmware/>

Driver: orinoco - Agere/Prism/Symbol Orinoco support

File: agere_sta_fw.bin
Version: 9.48 Hermes I
File: agere_ap_fw.bin
Version: 9.48 Hermes I

Licence: Redistributable. See LICENCE.agere for details

Driver: ar9170 - Atheros 802.11n "otus" USB

File: ar9170-1.fw
File: ar9170-2.fw

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: ath9k_htc - Atheros HTC devices (USB)

File: ar9271.fw
File: ar7010.fw
File: ar7010_1_1.fw
File: htc_9271.fw

Version: 1.3.1
File: htc_7010.fw
Version: 1.3.1

Licence: Redistributable. See LICENCE.atheros_firmware for details

File: ath9k_htc/htc_7010-1.4.0.fw
Version: 1.4.0
File: ath9k_htc/htc_9271-1.4.0.fw
Version: 1.4.0

Licence: Free software. See LICENCE.open-ath9k-htc-firmware for details

Driver: cassini - Sun Cassini

File: sun/cassini.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: slicoss - Alacritech IS-NIC products

File: slicoss/gbdownload.sys
File: slicoss/gbrvcuocode.sys
File: slicoss/oasisdbgdownload.sys
File: slicoss/oasisdownload.sys
File: slicoss/oasisrcvucode.sys

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Found in hex form in kernel source.

Driver: sxg - Alacritech IS-NIC products

File: sxg/saharadownloadB.sys
File: sxg/saharadbdownloadB.sys

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Found in hex form in kernel source.

Driver: cxgb3 - Chelsio Terminator 3 1G/10G Ethernet adapter

File: cxgb3/t3b_psram-1.1.0.bin
File: cxgb3/t3c_psram-1.1.0.bin
File: cxgb3/t3fw-7.0.0.bin
File: cxgb3/t3fw-7.1.0.bin
File: cxgb3/t3fw-7.4.0.bin
File: cxgb3/t3fw-7.10.0.bin
File: cxgb3/t3fw-7.12.0.bin

Licence: GPLv2 or OpenIB.org BSD license, no source visible

Driver: cxgb3 - Chelsio Terminator 3 1G/10G Ethernet adapter

File: cxgb3/acl2005_opt_edc.bin
File: cxgb3/acl2005_twx_edc.bin
File: cxgb3/acl2020_twx_edc.bin

Licence:

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Found in hex form in kernel source.

Driver: cxgb4 - Chelsio Terminator 4/5/6 1/10/25/40/100G Ethernet adapter

File: cxgb4/t4fw-1.14.4.0.bin
File: cxgb4/t4fw-1.15.37.0.bin
File: cxgb4/t4fw-1.24.3.0.bin
Link: cxgb4/t4fw.bin -> t4fw-1.24.3.0.bin
File: cxgb4/t5fw-1.14.4.0.bin

File: cxgb4/t5fw-1.15.37.0.bin
File: cxgb4/t5fw-1.24.3.0.bin
Link: cxgb4/t5fw.bin -> t5fw-1.24.3.0.bin
File: cxgb4/t6fw-1.24.3.0.bin
Link: cxgb4/t6fw.bin -> t6fw-1.24.3.0.bin
File: cxgb4/aq1202_fw.cld
File: cxgb4/bcm8483.bin

Licence: Redistributable. See LICENCE.chelsio_firmware for details

Driver: e100 -- Intel PRO/100 Ethernet NIC

File: e100/d101m_ucose.bin
File: e100/d101s_ucose.bin
File: e100/d102e_ucose.bin

Licence: Redistributable. See LICENCE.e100 for details

Driver: acenic -- Alteon AceNIC Gigabit Ethernet card

File: acenic/tg1.bin
File: acenic/tg2.bin

Licence: Unknown

Found in hex form in kernel source, but source allegedly available at <http://alteon.shareable.org/>

Driver: tg3 -- Broadcom Tigon3 based gigabit Ethernet cards

File: tigon/tg3.bin
File: tigon/tg3_tso.bin
File: tigon/tg3_tso5.bin
File: tigon/tg357766.bin

Licence:

* Firmware is:

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*

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Found in hex form in kernel source.

Driver: starfire - Adaptec Starfire/DuraLAN support

File: adaptec/starfire_rx.bin

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File: adaptec/starfire_tx.bin

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Driver: i2400m-usb - Intel 2400 Wireless WiMAX Connection over USB

File: i2400m-fw-usb-1.4.sbcf
File: i2400m-fw-usb-1.5.sbcf
File: i6050-fw-usb-1.5.sbcf

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Also available from <http://linuxwimax.org/Download>

Driver: libertas - Marvell Libertas fullmac-type 802.11b/g cards

File: libertas/cf8381.bin
File: libertas/cf8381_helper.bin
File: libertas/cf8385.bin
File: libertas/cf8385_helper.bin
File: libertas/gspi8682.bin
File: libertas/gspi8682_helper.bin
File: libertas/gspi8686_v9.bin
File: libertas/gspi8686_v9_helper.bin
File: libertas/gspi8688.bin
File: libertas/gspi8688_helper.bin
File: libertas/sd8385.bin
File: libertas/sd8385_helper.bin
File: libertas/sd8682.bin
File: libertas/sd8682_helper.bin
File: libertas/sd8686_v8.bin
File: libertas/sd8686_v8_helper.bin
File: libertas/sd8686_v9.bin
File: libertas/sd8686_v9_helper.bin
File: libertas/usb8388_v5.bin
File: libertas/usb8388_v9.bin
File: libertas/usb8682.bin
File: mrvl/sd8688.bin
Link: libertas/sd8688.bin -> ../mrvl/sd8688.bin
File: mrvl/sd8688_helper.bin
Link: libertas/sd8688_helper.bin -> ../mrvl/sd8688_helper.bin

Licence: Redistributable. See LICENCE.Marvell for details. Extracted from

Linux driver tarballs downloaded from Marvell's "Extranet" with permission.

Driver: libertas - Marvell Libertas 802.11b/g cards, OLPC firmware

File: libertas/lbtf_sdio.bin
Version: 9.0.7.p4

File: lbtf_usb.bin
Version: 5.132.3.p1

File: libertas/usb8388_olpc.bin
Version: 5.110.22.p23

Licence: Redistributable. See LICENCE.OLPC for details.

Available from <http://dev.laptop.org/pub/firmware/libertas/>

Driver: mwl8k - Marvell Libertas softmac-type 802.11b/g/n cards

File: mwl8k/fmimage_8687.fw
File: mwl8k/helper_8687.fw
File: mwl8k/fmimage_8366.fw
File: mwl8k/fmimage_8366_ap-1.fw
File: mwl8k/fmimage_8366_ap-2.fw
File: mwl8k/fmimage_8366_ap-3.fw
Version: 5.2.8.16
File: mwl8k/helper_8366.fw

File: mwl8k/fmimage_8764_ap-1.fw
Version: 7.4.0.9

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Driver: mwifiex - Marvell Wi-Fi fullmac-type 802.11n/ac cards

File: mrvl/sd8787_uapsta.bin
Version: W14.68.35.p66

File: mrvl/usb8766_uapsta.bin
Version: 14.68.22.p16

File: mrvl/sd8797_uapsta.bin
Version: W14.68.29.p59

File: mrvl/usb8797_uapsta.bin
Version: W14.68.29.p60

File: mrvl/sd8897_uapsta.bin
Version: W15.68.19.17

File: mrvl/usb8897_uapsta.bin
Version: 15.68.4.p103

File: mrvl/pcie8897_uapsta.bin
Version: W15.68.19.p21

File: mrvl/sd8887_uapsta.bin
Version: W15.68.7.p189

File: mrvl/sd8801_uapsta.bin
Version: W14.68.36.p204

File: mrvl/usb8801_uapsta.bin
Version: W14.68.36.p138

File: mrvl/pcieuart8997_combo_v4.bin
Version: W16.68.1.p179

File: mrvl/pcieusb8997_combo_v4.bin
Version: W16.68.1.p195

File: mrvl/pcie8997_wlan_v4.bin
Version: W16.68.1.p195

File: mrvl/usbusb8997_combo_v4.bin
Version: W16.68.1.p183

File: mrvl/sdsd8997_combo_v4.bin
Version: W16.68.1.p179

File: mrvl/sdsd8977_combo_v2.bin
Version: W16.68.1.p195

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<http://git.marvell.com/?p=mwiflex-firmware.git>

Driver: iwlwifi - Intel Wireless Wifi

File: iwlwifi-3945-2.ucode
Version: 15.32.2.9

File: iwlwifi-4965-2.ucode
Version: 228.61.2.24

File: iwlwifi-5000-1.ucode
Version: 5.4.A.11 (aka 5.4.1.16)

File: iwlwifi-5000-2.ucode
Version: 8.24.2.12

File: iwlwifi-5000-5.ucode
Version: 8.83.5.1

File: iwlwifi-5150-2.ucode

Version: 8.24.2.2

File: iwlwifi-1000-3.ucode
Version: 128.50.3.1

File: iwlwifi-1000-5.ucode
Version: 39.31.5.1

File: iwlwifi-6000-4.ucode
Version: 9.221.4.1

File: iwlwifi-6050-4.ucode
Version: 9.201.4.1

File: iwlwifi-6050-5.ucode
Version: 41.28.5.1

File: iwlwifi-6000g2a-5.ucode
Version: 17.168.5.3

File: iwlwifi-6000g2a-6.ucode
Version: 18.168.6.1

File: iwlwifi-6000g2b-5.ucode
Version: 17.168.5.1

File: iwlwifi-6000g2b-6.ucode
Version: 18.168.6.1

File: iwlwifi-135-6.ucode
Version: 18.168.6.1

File: iwlwifi-100-5.ucode
Version: 39.31.5.1

File: iwlwifi-105-6.ucode
Version: 18.168.6.1

File: iwlwifi-2030-6.ucode
Version: 18.168.6.1

File: iwlwifi-2000-6.ucode
Version: 18.168.6.1

File: iwlwifi-7260-7.ucode
Version: 22.1.7.0

File: iwlwifi-7260-8.ucode
Version: 22.24.8.0

File: iwlwifi-7260-9.ucode
Version: 25.228.9.0

File: iwlwifi-7260-10.ucode
Version: 23.15.10.0

File: iwlwifi-7260-12.ucode

Version: 25.17.12.0

File: iwlwifi-7260-13.ucode
Version: 25.30.13.0

File: iwlwifi-7260-16.ucode
Version: 16.242414.0

File: iwlwifi-7260-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-3160-7.ucode
Version: 22.1.7.0

File: iwlwifi-3160-8.ucode
Version: 22.24.8.0

File: iwlwifi-3160-9.ucode
Version: 25.228.9.0

File: iwlwifi-3160-10.ucode
Version: 23.15.10.0

File: iwlwifi-3160-12.ucode
Version: 25.17.12.0

File: iwlwifi-3160-13.ucode
Version: 25.30.13.0

File: iwlwifi-3160-16.ucode
Version: 16.242414.0

File: iwlwifi-3160-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-7265-8.ucode
Version: 22.24.8.0

File: iwlwifi-7265-9.ucode
Version: 25.228.9.0

File: iwlwifi-7265-10.ucode
Version: 23.15.10.0

File: iwlwifi-7265-12.ucode
Version: 25.17.12.0

File: iwlwifi-7265-13.ucode
Version: 25.30.13.0

File: iwlwifi-7265-16.ucode
Version: 16.242414.0

File: iwlwifi-7265-17.ucode
Version: 17.bfb58538.0

File: iwlwifi-7265D-10.ucode

Version: 23.15.10.0

File: iwlwifi-7265D-12.ucode
Version: 25.17.12.0

File: iwlwifi-7265D-13.ucode
Version: 25.30.13.0

File: iwlwifi-7265D-16.ucode
Version: 16.242414.0

File: iwlwifi-7265D-17.ucode
Version: 17.352738.0

File: iwlwifi-7265D-21.ucode
Version: 21.302800.0

File: iwlwifi-7265D-22.ucode
Version: 22.391740.0

File: iwlwifi-7265D-27.ucode
Version: 27.541033.0

File: iwlwifi-7265D-29.ucode
Version: 29.3e3b4de5.0

File: iwlwifi-3168-21.ucode
Version: 21.302800.0

File: iwlwifi-3168-22.ucode
Version: 22.391740.0

File: iwlwifi-3168-27.ucode
Version: 27.541033.0

File: iwlwifi-3168-29.ucode
Version: 29.3e3b4de5.0

File: iwlwifi-8000C-13.ucode
Version: 25.30.13.0

File: iwlwifi-8000C-16.ucode
Version: 16.242414.0

File: iwlwifi-8000C-21.ucode
Version: 21.302800.0

File: iwlwifi-8000C-22.ucode
Version: 22.391740.0

File: iwlwifi-8000C-27.ucode
Version: 27.541033.0

File: iwlwifi-8000C-31.ucode
Version: 31.560484.0

File: iwlwifi-8000C-34.ucode

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Version: 34.610288.0

File: iwlwifi-8000C-36.ucode
Version: 36.8fd77bb3.0

File: iwlwifi-8265-21.ucode
Version: 21.302800.0

File: iwlwifi-8265-22.ucode
Version: 22.391740.0

File: iwlwifi-8265-27.ucode
Version: 27.541033.0

File: iwlwifi-8265-31.ucode
Version: 31.560484.0

File: iwlwifi-8265-34.ucode
Version: 34.610288.0

File: iwlwifi-8265-36.ucode
Version: 36.8fd77bb3.0

File: iwlwifi-9000-pu-b0-jf-b0-33.ucode
Version: 33.610294.0

File: iwlwifi-9000-pu-b0-jf-b0-34.ucode
Version: 34.ba501b11.0

File: iwlwifi-9000-pu-b0-jf-b0-38.ucode
Version: 38.755cfdd8.0

File: iwlwifi-9000-pu-b0-jf-b0-41.ucode
Version: 41.fc1a7aea.0

File: iwlwifi-9000-pu-b0-jf-b0-43.ucode
Version: 43.95eb4e97.0

File: iwlwifi-9000-pu-b0-jf-b0-46.ucode
Version: 46.a41adfe7.0

File: iwlwifi-9260-th-b0-jf-b0-33.ucode
Version: 33.610294.0

File: iwlwifi-9260-th-b0-jf-b0-34.ucode
Version: 34.ba501b11.0

File: iwlwifi-9260-th-b0-jf-b0-38.ucode
Version: 38.755cfdd8.0

File: iwlwifi-9260-th-b0-jf-b0-41.ucode
Version: 41.fc1a7aea.0

File: iwlwifi-9260-th-b0-jf-b0-43.ucode
Version: 43.95eb4e97.0

File: iwlwifi-9260-th-b0-jf-b0-46.ucode

Version: 46.a41adfe7.0

File: iwlwifi-cc-a0-46.ucode
Version: 46.3cfab8da.0

File: iwlwifi-cc-a0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-b0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-b0-jf-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-c0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-Qu-c0-jf-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-QuZ-a0-hr-b0-48.ucode
Version: 48.13675109.0

File: iwlwifi-QuZ-a0-jf-b0-48.ucode
Version: 48.13675109.0

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Also available from <http://wireless.kernel.org/en/users/Drivers/iwlwifi#Firmware>

Driver: ipu3-ingu - Intel IPU3 (3rd Gen Image Processing Unit) driver

File: intel/irci_irci_ecr-master_20161208_0213_20170112_1500.bin
Version: irci_irci_ecr-master_20161208_0213_20170112_1500
md5sum: 59abc311fce49c5a180b5a8a3917912d
Link: intel/ipu3-fw.bin -> irci_irci_ecr-master_20161208_0213_20170112_1500.bin

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Driver: cx231xx - Conexant Cx23100/101/102 USB broadcast A/V decoder

File: v4l-cx231xx-avcore-01.fw

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Driver: tehuti - Tehuti Networks 10G Ethernet

File: tehuti/bdx.bin

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Found in hex form in kernel source.

Driver: typhoon - 3cr990 series Typhoon

File: 3com/typhoon.bin

Licence:

/*
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*/

Found in hex form in kernel source.

Driver: yam - YAM driver for AX.25

File: yam/1200.bin

File: yam/9600.bin

Licence:

* (C) F6FBB 1998

Found in hex form in kernel source.

Driver: 3c359 - 3Com 3C359 Token Link Velocity XL adapter

File: 3com/3C359.bin

Licence:

/*
* The firmware this driver downloads into the tokenring card is a
* separate program and is not GPL'd source code, even though the Linux
* side driver and the routine that loads this data into the card are.
*
* This firmware is licensed to you strictly for use in conjunction
* with the use of 3Com 3C359 TokenRing adapters. There is no
* warranty expressed or implied about its fitness for any purpose.
*/
/* 3c359_microcode.mac: 3Com 3C359 Tokenring microcode.
*
* Notes:
* - Loaded from xl_init upon adapter initialization.
*
* Available from 3Com as part of their standard 3C359 driver.
*/

Found in hex form in kernel source.

Driver: pcnet_cs - NE2000 compatible PCMCIA adapter

File: cis/LA-PCM.cis

File: cis/PCMLM28.cis

File: cis/DP83903.cis

File: cis/NE2K.cis

File: cis/tamarack.cis

File: cis/PE-200.cis

File: cis/PE520.cis

Source: cis/

Licence: Dual GPLv2/MPL

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Driver: 3c589_cs - 3Com PCMCIA adapter

File: cis/3CXEM556.cis
Source: cis/src/3CXEM556.cis

Licence: Dual GPLv2/MPL

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Driver: 3c574_cs - 3Com PCMCIA adapter

File: cis/3CCFEM556.cis
Source: cis/src/3CCFEM556.cis

Licence: Dual GPLv2/MPL

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Driver: serial_cs - Serial PCMCIA adapter

File: cis/MT5634ZLX.cis
File: cis/RS-COM-2P.cis
File: cis/COMpad2.cis
File: cis/COMpad4.cis
Source: cis/src/MT5634ZLX.cis
Source: cis/src/RS-COM-2P.cis
Source: cis/src/COMpad2.cis
Source: cis/src/COMpad4.cis

Licence: Dual GPLv2/MPL

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Driver: serial_cs - Serial PCMCIA adapter

File: cis/SW_555_SER.cis
File: cis/SW_7xx_SER.cis
File: cis/SW_8xx_SER.cis

Licence: GPLv3. See GPL-3 for details.

Copyright Sierra Wireless

Driver: smc91c92_cs - SMC 91Cxx PCMCIA

File: ositech/Xilinx7OD.bin

Licence: Allegedly GPL, but no source visible. Marked:
This file contains the firmware of Seven of Diamonds from OSITECH.
(Special thanks to Kevin MacPherson of OSITECH)

Found in hex form in kernel source.

Driver: cx23418 - Conexant PCI Broadcast A/V with MPEG encoder

File: v4l-cx23418-apu.fw
File: v4l-cx23418-cpu.fw
File: v4l-cx23418-dig.fw

Licence: Redistributable.

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Driver: cx23885 - Conexant PCI Express Broadcast A/V decoder

File: v4l-cx23885-avcore-01.fw

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Driver: cx23840 - Conexant sideport Broadcast A/V decoder

File: v4l-cx25840.fw

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Driver: qllogicpti - PTI Qlogic, ISP Driver

File: qllogic/isp1000.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: myri_sbus - MyriCOM Gigabit Ethernet

File: myricom/lanai.bin

Licence: Unknown

Found in hex form in kernel source.

Driver: bnx2x: Broadcom Everest

File: bnx2x-e1-4.8.53.0.fw
File: bnx2x-e1h-4.8.53.0.fw
File: bnx2x-e1-5.2.7.0.fw
File: bnx2x-e1h-5.2.7.0.fw
File: bnx2x-e1-5.2.13.0.fw
File: bnx2x-e1h-5.2.13.0.fw
File: bnx2x/bnx2x-e1-6.0.34.0.fw
File: bnx2x/bnx2x-e1h-6.0.34.0.fw
File: bnx2x/bnx2x-e2-6.0.34.0.fw
File: bnx2x/bnx2x-e1-6.2.5.0.fw
File: bnx2x/bnx2x-e1h-6.2.5.0.fw
File: bnx2x/bnx2x-e2-6.2.5.0.fw
File: bnx2x/bnx2x-e1-6.2.9.0.fw
File: bnx2x/bnx2x-e1h-6.2.9.0.fw
File: bnx2x/bnx2x-e2-6.2.9.0.fw
File: bnx2x/bnx2x-e2-7.0.20.0.fw
File: bnx2x/bnx2x-e1-7.0.20.0.fw
File: bnx2x/bnx2x-e1h-7.0.20.0.fw
File: bnx2x/bnx2x-e2-7.0.23.0.fw
File: bnx2x/bnx2x-e1-7.0.23.0.fw
File: bnx2x/bnx2x-e1h-7.0.23.0.fw
File: bnx2x/bnx2x-e2-7.0.29.0.fw
File: bnx2x/bnx2x-e1-7.0.29.0.fw
File: bnx2x/bnx2x-e1h-7.0.29.0.fw
File: bnx2x/bnx2x-e2-7.2.16.0.fw
File: bnx2x/bnx2x-e1-7.2.16.0.fw
File: bnx2x/bnx2x-e1h-7.2.16.0.fw
File: bnx2x/bnx2x-e2-7.2.51.0.fw

File: bnx2x/bnx2x-e1-7.2.51.0.fw
File: bnx2x/bnx2x-e1h-7.2.51.0.fw
File: bnx2x/bnx2x-e1-7.8.2.0.fw
File: bnx2x/bnx2x-e1h-7.8.2.0.fw
File: bnx2x/bnx2x-e2-7.8.2.0.fw
File: bnx2x/bnx2x-e1-7.8.17.0.fw
File: bnx2x/bnx2x-e1h-7.8.17.0.fw
File: bnx2x/bnx2x-e2-7.8.17.0.fw
File: bnx2x/bnx2x-e1-7.8.19.0.fw
File: bnx2x/bnx2x-e1h-7.8.19.0.fw
File: bnx2x/bnx2x-e2-7.8.19.0.fw
File: bnx2x/bnx2x-e1-7.10.51.0.fw
File: bnx2x/bnx2x-e1h-7.10.51.0.fw
File: bnx2x/bnx2x-e2-7.10.51.0.fw
File: bnx2x/bnx2x-e1-7.12.30.0.fw
File: bnx2x/bnx2x-e1h-7.12.30.0.fw
File: bnx2x/bnx2x-e2-7.12.30.0.fw
File: bnx2x/bnx2x-e1-7.13.1.0.fw
File: bnx2x/bnx2x-e1h-7.13.1.0.fw
File: bnx2x/bnx2x-e2-7.13.1.0.fw
File: bnx2x/bnx2x-e1-7.13.11.0.fw
File: bnx2x/bnx2x-e1h-7.13.11.0.fw
File: bnx2x/bnx2x-e2-7.13.11.0.fw

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Found in hex form in kernel source.

Driver: bnx2 - Broadcom NetXtremII

File: bnx2/bnx2-mips-06-4.6.16.fw
File: bnx2/bnx2-mips-06-5.0.0.j3.fw
File: bnx2/bnx2-mips-06-5.0.0.j6.fw
File: bnx2/bnx2-mips-06-6.0.15.fw
File: bnx2/bnx2-mips-06-6.2.1.fw
File: bnx2/bnx2-mips-06-6.2.3.fw
File: bnx2/bnx2-mips-09-4.6.17.fw
File: bnx2/bnx2-mips-09-5.0.0.j3.fw
File: bnx2/bnx2-mips-09-5.0.0.j9.fw
File: bnx2/bnx2-mips-09-5.0.0.j15.fw
File: bnx2/bnx2-mips-09-6.0.17.fw
File: bnx2/bnx2-mips-09-6.2.1.fw
File: bnx2/bnx2-mips-09-6.2.1a.fw
File: bnx2/bnx2-mips-09-6.2.1b.fw
File: bnx2/bnx2-rv2p-06-4.6.16.fw

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File: bnx2/bnx2-rv2p-06-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-06-6.0.15.fw
File: bnx2/bnx2-rv2p-09-4.6.15.fw
File: bnx2/bnx2-rv2p-09-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-09-5.0.0.j10.fw
File: bnx2/bnx2-rv2p-09-6.0.17.fw
File: bnx2/bnx2-rv2p-09ax-5.0.0.j3.fw
File: bnx2/bnx2-rv2p-09ax-5.0.0.j10.fw
File: bnx2/bnx2-rv2p-09ax-6.0.17.fw

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Driver: netxen_nic - NetXen Multi port (1/10) Gigabit Ethernet NIC

File: phanfw.bin
Version: 4.0.590

Licence: Redistributable. See LICENCE.phanfw for details.

Available from http://ldriver.qlogic.com/firmware/netxen_nic/new/

Driver: dvb-ttpci -- AV7110 cards

File: av7110/bootcode.bin
Source: av7110/Boot.S
Source: av7110/Makefile

Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

ARM assembly source code from <https://linuxtv.org/downloads/firmware/Boot.S>

Driver: snd-wavefront - ISA WaveFront sound card

File: yamaha/yss225_registers.bin

Licence: Allegedly GPLv2+, but no source visible.

Found in hex form in kernel source, with the following comment:
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Driver: rt61pci - Ralink RT2561, RT2561S, RT2661 wireless MACs

File: rt2561.bin
File: rt2561s.bin
File: rt2661.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Downloaded from <http://www.ralinktech.com/ralink/Home/Support/Linux.html>

Driver: rt73usb - Ralink RT2571W, RT2671 wireless MACs

File: rt73.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Downloaded from <http://www.ralinktech.com/ralink/Home/Support/Linux.html>

Driver: mt7601u - MediaTek MT7601U Wireless MACs

File: mt7601u.bin
Version: 34

Licence: Redistributable. See LICENCE.ralink_a_mediatek_company_firmware for details

Downloaded from <http://www.mediatek.com/en/downloads/>

Driver: rt2800pci - Ralink RT2860, RT2890, RT3090, RT3290, RT5390 wireless MACs

File: rt2860.bin
Version: 40

File: rt3290.bin
Version: 37

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

Binary file supplied originally by Shiang Tu <shiang_tu@ralinktech.com>, latest from <http://www.mediatek.com/en/downloads1/downloads/>

Driver: rt2860sta - Ralink RT3090 wireless MACs

Link: rt3090.bin -> rt2860.bin

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Driver: rt2800usb - Ralink RT2870, RT3070, RT3071, RT3072, RT5370 wireless MACs

File: rt2870.bin
Version: 36

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Binary file supplied originally by Shiang Tu <shiang_tu@ralinktech.com>, latest from <http://www.mediatek.com/en/downloads1/downloads/>

Driver: rt2870sta - Ralink RT2870, RT3070, RT3071 wireless MACs

Link: rt3070.bin -> rt2870.bin
File: rt3071.bin

Licence: Redistributable. See LICENCE.ralink-firmware.txt for details

rt3071.bin is a copy of bytes 4096-8191 of rt2870.bin for compatibility.

Driver: usbdx/usbduxfast/usbduxsigma - usbdx data acquisition cards

File: usbdx_firmware.bin
File: usbduxfast_firmware.bin
File: usbduxsigma_firmware.bin
Source: usbdx/

Licence: GPLv2. See GPL-2 for details.

Provided from the author, Bernd Porr <BerndPorr@f2s.com>

Driver: xc4000 - Xceive 4000 Tuner driver

File: dvb-fe-xc4000-1.4.1.fw
Version: 1.4.1

Licence: Redistributable. See LICENCE.xc4000 for details

Driver: xc5000 - Xceive 5000 Tuner driver

File: dvb-fe-xc5000-1.6.114.fw
Version: 1.6.114

File: dvb-fe-xc5000c-4.1.30.7.fw
Version: 4.1.30.7

Licence: Redistributable. See LICENCE.xc5000 and LICENCE.xc5000c for details

Driver: dib0700 - DiBcom dib0700 USB DVB bridge driver

File: dvb-usb-dib0700-1.20.fw
Version: 1.20

Licence: Redistributable. See LICENSE.dib0700 for details

Driver: ath3k - DFU Driver for Atheros bluetooth chipset AR3011

File: ath3k-1.fw
Version: 1.0

Fix EEPROM radio table issue and change PID to 3005

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: mga - Matrox G200/G400/G550

File: matrox/g200_warp.fw
File: matrox/g400_warp.fw

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Found in hex form in kernel source.

Driver: r128 - ATI Rage 128

File: r128/r128_cce.bin

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Found in decimal form in kernel source.

Driver: radeon - ATI Radeon

File: radeon/R100_cp.bin
File: radeon/R200_cp.bin
File: radeon/R300_cp.bin
File: radeon/R420_cp.bin
File: radeon/RS600_cp.bin
File: radeon/RS690_cp.bin
File: radeon/R520_cp.bin
File: radeon/R600_pfp.bin
File: radeon/R600_me.bin
File: radeon/RV610_pfp.bin
File: radeon/RV610_me.bin
File: radeon/RV630_pfp.bin
File: radeon/RV630_me.bin
File: radeon/RV620_pfp.bin
File: radeon/RV620_me.bin
File: radeon/RV635_pfp.bin
File: radeon/RV635_me.bin
File: radeon/RV670_pfp.bin
File: radeon/RV670_me.bin
File: radeon/RS780_pfp.bin
File: radeon/RS780_me.bin
File: radeon/RV770_pfp.bin
File: radeon/RV770_me.bin
File: radeon/RV730_pfp.bin
File: radeon/RV730_me.bin
File: radeon/RV710_pfp.bin
File: radeon/RV710_me.bin

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Found in hex form in kernel source.

Driver: radeon - ATI Radeon

File: radeon/R600_rlc.bin
File: radeon/R600_uvd.bin
File: radeon/RS780_uvd.bin
File: radeon/R700_rlc.bin
File: radeon/RV710_uvd.bin
File: radeon/RV710_smc.bin
File: radeon/RV730_smc.bin
File: radeon/RV740_smc.bin
File: radeon/RV770_smc.bin
File: radeon/RV770_uvd.bin
File: radeon/CEDAR_me.bin
File: radeon/CEDAR_pfp.bin
File: radeon/CEDAR_rlc.bin
File: radeon/CEDAR_smc.bin
File: radeon/CYPRESS_me.bin
File: radeon/CYPRESS_pfp.bin
File: radeon/CYPRESS_rlc.bin
File: radeon/CYPRESS_uvd.bin
File: radeon/CYPRESS_smc.bin
File: radeon/JUNIPER_me.bin
File: radeon/JUNIPER_pfp.bin
File: radeon/JUNIPER_rlc.bin
File: radeon/JUNIPER_smc.bin
File: radeon/REDWOOD_me.bin
File: radeon/REDWOOD_pfp.bin
File: radeon/REDWOOD_rlc.bin
File: radeon/REDWOOD_smc.bin

File: radeon/PALM_me.bin
File: radeon/PALM_pfp.bin
File: radeon/SUMO_rlc.bin
File: radeon/SUMO_uvd.bin
File: radeon/BARTS_mc.bin
File: radeon/BARTS_me.bin
File: radeon/BARTS_pfp.bin
File: radeon/BARTS_smc.bin
File: radeon/BTC_rlc.bin
File: radeon/CAICOS_mc.bin
File: radeon/CAICOS_me.bin
File: radeon/CAICOS_pfp.bin
File: radeon/CAICOS_smc.bin
File: radeon/TURKS_mc.bin
File: radeon/TURKS_me.bin
File: radeon/TURKS_pfp.bin
File: radeon/TURKS_smc.bin
File: radeon/CAYMAN_mc.bin
File: radeon/CAYMAN_me.bin
File: radeon/CAYMAN_pfp.bin
File: radeon/CAYMAN_rlc.bin
File: radeon/CAYMAN_smc.bin
File: radeon/SUMO_pfp.bin
File: radeon/SUMO_me.bin
File: radeon/SUMO2_pfp.bin
File: radeon/SUMO2_me.bin
File: radeon/ARUBA_me.bin
File: radeon/ARUBA_pfp.bin
File: radeon/ARUBA_rlc.bin
File: radeon/PITCAIRN_ce.bin
File: radeon/PITCAIRN_mc.bin
File: radeon/PITCAIRN_mc2.bin
File: radeon/PITCAIRN_me.bin
File: radeon/PITCAIRN_pfp.bin
File: radeon/PITCAIRN_rlc.bin
File: radeon/PITCAIRN_smc.bin
File: radeon/TAHITI_ce.bin
File: radeon/TAHITI_mc.bin
File: radeon/TAHITI_mc2.bin
File: radeon/TAHITI_me.bin
File: radeon/TAHITI_pfp.bin
File: radeon/TAHITI_rlc.bin
File: radeon/TAHITI_uvd.bin
File: radeon/TAHITI_smc.bin
File: radeon/TAHITI_vce.bin
File: radeon/VERDE_ce.bin
File: radeon/VERDE_mc.bin
File: radeon/VERDE_mc2.bin
File: radeon/VERDE_me.bin
File: radeon/VERDE_pfp.bin
File: radeon/VERDE_rlc.bin
File: radeon/VERDE_smc.bin
File: radeon/OLAND_ce.bin
File: radeon/OLAND_mc.bin
File: radeon/OLAND_mc2.bin
File: radeon/OLAND_me.bin
File: radeon/OLAND_pfp.bin

File: radeon/OLAND_rlc.bin
File: radeon/OLAND_smc.bin
File: radeon/HAINAN_ce.bin
File: radeon/HAINAN_mc.bin
File: radeon/HAINAN_mc2.bin
File: radeon/HAINAN_me.bin
File: radeon/HAINAN_pfp.bin
File: radeon/HAINAN_rlc.bin
File: radeon/HAINAN_smc.bin
File: radeon/BONAIRE_ce.bin
File: radeon/BONAIRE_mc.bin
File: radeon/BONAIRE_mc2.bin
File: radeon/BONAIRE_me.bin
File: radeon/BONAIRE_mec.bin
File: radeon/BONAIRE_pfp.bin
File: radeon/BONAIRE_rlc.bin
File: radeon/BONAIRE_sdma.bin
File: radeon/BONAIRE_uvd.bin
File: radeon/BONAIRE_smc.bin
File: radeon/BONAIRE_vce.bin
File: radeon/KABINI_ce.bin
File: radeon/KABINI_me.bin
File: radeon/KABINI_mec.bin
File: radeon/KABINI_pfp.bin
File: radeon/KABINI_rlc.bin
File: radeon/KABINI_sdma.bin
File: radeon/KAVERI_ce.bin
File: radeon/KAVERI_me.bin
File: radeon/KAVERI_mec.bin
File: radeon/KAVERI_pfp.bin
File: radeon/KAVERI_rlc.bin
File: radeon/KAVERI_sdma.bin
File: radeon/HAWAII_ce.bin
File: radeon/HAWAII_mc.bin
File: radeon/HAWAII_mc2.bin
File: radeon/HAWAII_me.bin
File: radeon/HAWAII_mec.bin
File: radeon/HAWAII_pfp.bin
File: radeon/HAWAII_rlc.bin
File: radeon/HAWAII_sdma.bin
File: radeon/HAWAII_smc.bin
File: radeon/MULLINS_ce.bin
File: radeon/MULLINS_me.bin
File: radeon/MULLINS_mec.bin
File: radeon/MULLINS_pfp.bin
File: radeon/MULLINS_rlc.bin
File: radeon/MULLINS_sdma.bin
File: radeon/pitcairn_ce.bin
File: radeon/pitcairn_k_smc.bin
File: radeon/pitcairn_mc.bin
File: radeon/pitcairn_me.bin
File: radeon/pitcairn_pfp.bin
File: radeon/pitcairn_rlc.bin
File: radeon/pitcairn_smc.bin
File: radeon/tahiti_ce.bin
File: radeon/tahiti_k_smc.bin
File: radeon/tahiti_mc.bin

File: radeon/tahiti_me.bin
File: radeon/tahiti_pfp.bin
File: radeon/tahiti_rlc.bin
File: radeon/tahiti_smc.bin
File: radeon/verde_ce.bin
File: radeon/verde_k_smc.bin
File: radeon/verde_mc.bin
File: radeon/verde_me.bin
File: radeon/verde_pfp.bin
File: radeon/verde_rlc.bin
File: radeon/verde_smc.bin
File: radeon/oland_ce.bin
File: radeon/oland_k_smc.bin
File: radeon/oland_mc.bin
File: radeon/oland_me.bin
File: radeon/oland_pfp.bin
File: radeon/oland_rlc.bin
File: radeon/oland_smc.bin
File: radeon/hainan_ce.bin
File: radeon/hainan_k_smc.bin
File: radeon/hainan_mc.bin
File: radeon/hainan_me.bin
File: radeon/hainan_pfp.bin
File: radeon/hainan_rlc.bin
File: radeon/hainan_smc.bin
File: radeon/bonaire_ce.bin
File: radeon/bonaire_k_smc.bin
File: radeon/bonaire_mc.bin
File: radeon/bonaire_me.bin
File: radeon/bonaire_mec.bin
File: radeon/bonaire_pfp.bin
File: radeon/bonaire_rlc.bin
File: radeon/bonaire_sdma.bin
File: radeon/bonaire_sdma1.bin
File: radeon/bonaire_smc.bin
File: radeon/bonaire_uvd.bin
File: radeon/bonaire_vce.bin
File: radeon/kabini_ce.bin
File: radeon/kabini_me.bin
File: radeon/kabini_mec.bin
File: radeon/kabini_pfp.bin
File: radeon/kabini_rlc.bin
File: radeon/kabini_sdma.bin
File: radeon/kabini_sdma1.bin
File: radeon/kabini_uvd.bin
File: radeon/kabini_vce.bin
File: radeon/kaveri_ce.bin
File: radeon/kaveri_me.bin
File: radeon/kaveri_mec.bin
File: radeon/kaveri_mec2.bin
File: radeon/kaveri_pfp.bin
File: radeon/kaveri_rlc.bin
File: radeon/kaveri_sdma.bin
File: radeon/kaveri_sdma1.bin
File: radeon/kaveri_uvd.bin
File: radeon/kaveri_vce.bin
File: radeon/hawaii_ce.bin

File: radeon/hawaii_k_smc.bin
File: radeon/hawaii_mc.bin
File: radeon/hawaii_me.bin
File: radeon/hawaii_mec.bin
File: radeon/hawaii_pfp.bin
File: radeon/hawaii_rlc.bin
File: radeon/hawaii_sdma.bin
File: radeon/hawaii_sdma1.bin
File: radeon/hawaii_smc.bin
File: radeon/hawaii_uvd.bin
File: radeon/hawaii_vce.bin
File: radeon/mullins_ce.bin
File: radeon/mullins_me.bin
File: radeon/mullins_mec.bin
File: radeon/mullins_pfp.bin
File: radeon/mullins_rlc.bin
File: radeon/mullins_sdma.bin
File: radeon/mullins_sdma1.bin
File: radeon/mullins_uvd.bin
File: radeon/mullins_vce.bin
File: radeon/banks_k_2_smc.bin
File: radeon/si58_mc.bin

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Driver: amdgpu - AMD Radeon

File: amdgpu/tahiti_ce.bin
File: amdgpu/tahiti_k_smc.bin
File: amdgpu/tahiti_mc.bin
File: amdgpu/tahiti_me.bin
File: amdgpu/tahiti_pfp.bin
File: amdgpu/tahiti_rlc.bin
File: amdgpu/tahiti_smc.bin
File: amdgpu/pitcairn_ce.bin
File: amdgpu/pitcairn_k_smc.bin
File: amdgpu/pitcairn_mc.bin
File: amdgpu/pitcairn_me.bin
File: amdgpu/pitcairn_pfp.bin
File: amdgpu/pitcairn_rlc.bin
File: amdgpu/pitcairn_smc.bin
File: amdgpu/verde_ce.bin
File: amdgpu/verde_k_smc.bin
File: amdgpu/verde_mc.bin
File: amdgpu/verde_me.bin
File: amdgpu/verde_pfp.bin
File: amdgpu/verde_rlc.bin
File: amdgpu/verde_smc.bin
File: amdgpu/hainan_ce.bin
File: amdgpu/hainan_k_smc.bin
File: amdgpu/hainan_mc.bin
File: amdgpu/hainan_me.bin
File: amdgpu/hainan_pfp.bin
File: amdgpu/hainan_rlc.bin
File: amdgpu/hainan_smc.bin

File: amdgpu/oland_ce.bin
File: amdgpu/oland_k_smc.bin
File: amdgpu/oland_mc.bin
File: amdgpu/oland_me.bin
File: amdgpu/oland_pfp.bin
File: amdgpu/oland_rlc.bin
File: amdgpu/oland_smc.bin
File: amdgpu/si58_mc.bin
File: amdgpu/banks_k_2_smc.bin
File: amdgpu/bonaire_ce.bin
File: amdgpu/bonaire_k_smc.bin
File: amdgpu/bonaire_mc.bin
File: amdgpu/bonaire_me.bin
File: amdgpu/bonaire_mec.bin
File: amdgpu/bonaire_pfp.bin
File: amdgpu/bonaire_rlc.bin
File: amdgpu/bonaire_sdma.bin
File: amdgpu/bonaire_sdma1.bin
File: amdgpu/bonaire_smc.bin
File: amdgpu/bonaire_uvd.bin
File: amdgpu/bonaire_vce.bin
File: amdgpu/hawaii_ce.bin
File: amdgpu/hawaii_k_smc.bin
File: amdgpu/hawaii_mc.bin
File: amdgpu/hawaii_me.bin
File: amdgpu/hawaii_mec.bin
File: amdgpu/hawaii_pfp.bin
File: amdgpu/hawaii_rlc.bin
File: amdgpu/hawaii_sdma.bin
File: amdgpu/hawaii_sdma1.bin
File: amdgpu/hawaii_smc.bin
File: amdgpu/hawaii_uvd.bin
File: amdgpu/hawaii_vce.bin
File: amdgpu/kabini_ce.bin
File: amdgpu/kabini_me.bin
File: amdgpu/kabini_mec.bin
File: amdgpu/kabini_pfp.bin
File: amdgpu/kabini_rlc.bin
File: amdgpu/kabini_sdma.bin
File: amdgpu/kabini_sdma1.bin
File: amdgpu/kabini_uvd.bin
File: amdgpu/kabini_vce.bin
File: amdgpu/mullins_ce.bin
File: amdgpu/mullins_me.bin
File: amdgpu/mullins_mec.bin
File: amdgpu/mullins_pfp.bin
File: amdgpu/mullins_rlc.bin
File: amdgpu/mullins_sdma.bin
File: amdgpu/mullins_sdma1.bin
File: amdgpu/mullins_uvd.bin
File: amdgpu/mullins_vce.bin
File: amdgpu/kaveri_ce.bin
File: amdgpu/kaveri_me.bin
File: amdgpu/kaveri_mec.bin
File: amdgpu/kaveri_mec2.bin
File: amdgpu/kaveri_pfp.bin
File: amdgpu/kaveri_rlc.bin

File: amdgpu/kaveri_sdma.bin
File: amdgpu/kaveri_sdma1.bin
File: amdgpu/kaveri_uvd.bin
File: amdgpu/kaveri_vce.bin
File: amdgpu/topaz_ce.bin
File: amdgpu/topaz_k_smc.bin
File: amdgpu/topaz_mc.bin
File: amdgpu/topaz_me.bin
File: amdgpu/topaz_mec2.bin
File: amdgpu/topaz_mec.bin
File: amdgpu/topaz_pfp.bin
File: amdgpu/topaz_rlc.bin
File: amdgpu/topaz_sdma1.bin
File: amdgpu/topaz_sdma.bin
File: amdgpu/topaz_smc.bin
File: amdgpu/tonga_ce.bin
File: amdgpu/tonga_k_smc.bin
File: amdgpu/tonga_mc.bin
File: amdgpu/tonga_me.bin
File: amdgpu/tonga_mec2.bin
File: amdgpu/tonga_mec.bin
File: amdgpu/tonga_pfp.bin
File: amdgpu/tonga_rlc.bin
File: amdgpu/tonga_sdma1.bin
File: amdgpu/tonga_sdma.bin
File: amdgpu/tonga_smc.bin
File: amdgpu/tonga_uvd.bin
File: amdgpu/tonga_vce.bin
File: amdgpu/carrizo_ce.bin
File: amdgpu/carrizo_me.bin
File: amdgpu/carrizo_mec2.bin
File: amdgpu/carrizo_mec.bin
File: amdgpu/carrizo_pfp.bin
File: amdgpu/carrizo_rlc.bin
File: amdgpu/carrizo_sdma1.bin
File: amdgpu/carrizo_sdma.bin
File: amdgpu/carrizo_uvd.bin
File: amdgpu/carrizo_vce.bin
File: amdgpu/fiji_ce.bin
File: amdgpu/fiji_mc.bin
File: amdgpu/fiji_me.bin
File: amdgpu/fiji_mec2.bin
File: amdgpu/fiji_mec.bin
File: amdgpu/fiji_pfp.bin
File: amdgpu/fiji_rlc.bin
File: amdgpu/fiji_sdma1.bin
File: amdgpu/fiji_sdma.bin
File: amdgpu/fiji_smc.bin
File: amdgpu/fiji_uvd.bin
File: amdgpu/fiji_vce.bin
File: amdgpu/stoney_ce.bin
File: amdgpu/stoney_me.bin
File: amdgpu/stoney_mec.bin
File: amdgpu/stoney_pfp.bin
File: amdgpu/stoney_rlc.bin
File: amdgpu/stoney_sdma.bin
File: amdgpu/stoney_uvd.bin

File: amdgpu/stoney_vce.bin
File: amdgpu/polaris10_ce.bin
File: amdgpu/polaris10_ce_2.bin
File: amdgpu/polaris10_mc.bin
File: amdgpu/polaris10_k_mc.bin
File: amdgpu/polaris10_me.bin
File: amdgpu/polaris10_me_2.bin
File: amdgpu/polaris10_mec2.bin
File: amdgpu/polaris10_mec2_2.bin
File: amdgpu/polaris10_mec.bin
File: amdgpu/polaris10_mec_2.bin
File: amdgpu/polaris10_pfp.bin
File: amdgpu/polaris10_pfp_2.bin
File: amdgpu/polaris10_rlc.bin
File: amdgpu/polaris10_sdma1.bin
File: amdgpu/polaris10_sdma.bin
File: amdgpu/polaris10_smc.bin
File: amdgpu/polaris10_k_smc.bin
File: amdgpu/polaris10_k2_smc.bin
File: amdgpu/polaris10_smc_sk.bin
File: amdgpu/polaris10_uvd.bin
File: amdgpu/polaris10_vce.bin
File: amdgpu/polaris11_ce.bin
File: amdgpu/polaris11_ce_2.bin
File: amdgpu/polaris11_mc.bin
File: amdgpu/polaris11_k_mc.bin
File: amdgpu/polaris11_me.bin
File: amdgpu/polaris11_me_2.bin
File: amdgpu/polaris11_mec2.bin
File: amdgpu/polaris11_mec2_2.bin
File: amdgpu/polaris11_mec.bin
File: amdgpu/polaris11_mec_2.bin
File: amdgpu/polaris11_pfp.bin
File: amdgpu/polaris11_pfp_2.bin
File: amdgpu/polaris11_rlc.bin
File: amdgpu/polaris11_sdma1.bin
File: amdgpu/polaris11_sdma.bin
File: amdgpu/polaris11_smc.bin
File: amdgpu/polaris11_k_smc.bin
File: amdgpu/polaris11_k2_smc.bin
File: amdgpu/polaris11_smc_sk.bin
File: amdgpu/polaris11_uvd.bin
File: amdgpu/polaris11_vce.bin
File: amdgpu/polaris12_ce.bin
File: amdgpu/polaris12_ce_2.bin
File: amdgpu/polaris12_mc.bin
File: amdgpu/polaris12_k_mc.bin
File: amdgpu/polaris12_me.bin
File: amdgpu/polaris12_me_2.bin
File: amdgpu/polaris12_mec.bin
File: amdgpu/polaris12_mec_2.bin
File: amdgpu/polaris12_mec2.bin
File: amdgpu/polaris12_mec2_2.bin
File: amdgpu/polaris12_pfp.bin
File: amdgpu/polaris12_pfp_2.bin
File: amdgpu/polaris12_rlc.bin
File: amdgpu/polaris12_sdma.bin

File: amdgpu/polaris12_sdma1.bin
File: amdgpu/polaris12_smc.bin
File: amdgpu/polaris12_k_smc.bin
File: amdgpu/polaris12_uvd.bin
File: amdgpu/polaris12_vce.bin
File: amdgpu/vegam_ce.bin
File: amdgpu/vegam_me.bin
File: amdgpu/vegam_mec.bin
File: amdgpu/vegam_mec2.bin
File: amdgpu/vegam_pfp.bin
File: amdgpu/vegam_rlc.bin
File: amdgpu/vegam_sdma.bin
File: amdgpu/vegam_sdma1.bin
File: amdgpu/vegam_smc.bin
File: amdgpu/vegam_uvd.bin
File: amdgpu/vegam_vce.bin
File: amdgpu/vega10_acg_smc.bin
File: amdgpu/vega10_asd.bin
File: amdgpu/vega10_ce.bin
File: amdgpu/vega10_gpu_info.bin
File: amdgpu/vega10_me.bin
File: amdgpu/vega10_mec.bin
File: amdgpu/vega10_mec2.bin
File: amdgpu/vega10_pfp.bin
File: amdgpu/vega10_rlc.bin
File: amdgpu/vega10_sdma.bin
File: amdgpu/vega10_sdma1.bin
File: amdgpu/vega10_smc.bin
File: amdgpu/vega10_sos.bin
File: amdgpu/vega10_uvd.bin
File: amdgpu/vega10_vce.bin
File: amdgpu/vega12_asd.bin
File: amdgpu/vega12_ce.bin
File: amdgpu/vega12_gpu_info.bin
File: amdgpu/vega12_me.bin
File: amdgpu/vega12_mec.bin
File: amdgpu/vega12_mec2.bin
File: amdgpu/vega12_pfp.bin
File: amdgpu/vega12_rlc.bin
File: amdgpu/vega12_sdma.bin
File: amdgpu/vega12_sdma1.bin
File: amdgpu/vega12_smc.bin
File: amdgpu/vega12_sos.bin
File: amdgpu/vega12_uvd.bin
File: amdgpu/vega12_vce.bin
File: amdgpu/vega20_asd.bin
File: amdgpu/vega20_ce.bin
File: amdgpu/vega20_me.bin
File: amdgpu/vega20_mec.bin
File: amdgpu/vega20_mec2.bin
File: amdgpu/vega20_pfp.bin
File: amdgpu/vega20_rlc.bin
File: amdgpu/vega20_sdma.bin
File: amdgpu/vega20_sdma1.bin
File: amdgpu/vega20_smc.bin
File: amdgpu/vega20_sos.bin
File: amdgpu/vega20_uvd.bin

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File: amdgpu/vega20_vce.bin
File: amdgpu/raven_asd.bin
File: amdgpu/raven_ce.bin
File: amdgpu/raven_gpu_info.bin
File: amdgpu/raven_me.bin
File: amdgpu/raven_mec.bin
File: amdgpu/raven_mec2.bin
File: amdgpu/raven_pfp.bin
File: amdgpu/raven_rlc.bin
File: amdgpu/raven_sdma.bin
File: amdgpu/raven_vcn.bin
File: amdgpu/raven_dmcu.bin
File: amdgpu/picasso_asd.bin
File: amdgpu/picasso_ce.bin
File: amdgpu/picasso_gpu_info.bin
File: amdgpu/picasso_me.bin
File: amdgpu/picasso_mec.bin
File: amdgpu/picasso_mec2.bin
File: amdgpu/picasso_pfp.bin
File: amdgpu/picasso_rlc.bin
File: amdgpu/picasso_rlc_am4.bin
File: amdgpu/picasso_sdma.bin
File: amdgpu/picasso_vcn.bin
File: amdgpu/raven2_asd.bin
File: amdgpu/raven2_ce.bin
File: amdgpu/raven2_gpu_info.bin
File: amdgpu/raven2_me.bin
File: amdgpu/raven2_mec.bin
File: amdgpu/raven2_mec2.bin
File: amdgpu/raven2_pfp.bin
File: amdgpu/raven2_rlc.bin
File: amdgpu/raven2_sdma.bin
File: amdgpu/raven2_vcn.bin

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Driver: s2255drv

File: f2255usb.bin
Version: 1.2.8

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Driver: rtl8192e - Realtek 8192 PCI wireless driver

File: RTL8192E/boot.img
File: RTL8192E/data.img
File: RTL8192E/main.img

Licence: Redistributable, provided by Realtek in their driver source download.

Driver: lgs8gxx - Legend Silicon GB20600 demodulator driver

File: lgs8g75.fw

Licence: Unknown

Driver: ib_qib - QLogic Infiniband

File: qllogic/sd7220.fw

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Found in hex form in kernel source.

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Driver: qed - QLogic 4xxxx Ethernet Driver Core Module.

File: qed/qed_init_values_zipped-8.4.2.0.bin
File: qed/qed_init_values_zipped-8.7.3.0.bin
File: qed/qed_init_values_zipped-8.10.5.0.bin
File: qed/qed_init_values-8.10.9.0.bin
File: qed/qed_init_values_zipped-8.10.10.0.bin
File: qed/qed_init_values-8.14.6.0.bin
File: qed/qed_init_values_zipped-8.15.3.0.bin
File: qed/qed_init_values-8.18.9.0.bin
File: qed/qed_init_values_zipped-8.20.0.0.bin
File: qed/qed_init_values-8.20.0.0.bin
File: qed/qed_init_values-8.30.12.0.bin
File: qed/qed_init_values_zipped-8.33.1.0.bin
File: qed/qed_init_values_zipped-8.33.11.0.bin
File: qed/qed_init_values-8.33.12.0.bin
File: qed/qed_init_values_zipped-8.37.2.0.bin
File: qed/qed_init_values_zipped-8.37.7.0.bin
File: qed/qed_init_values-8.37.7.0.bin

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Driver: ueagle-atm - Driver for USB ADSL Modems based on Eagle IV Chipset

File: ueagle-atm/CMV4p.bin.v2
File: ueagle-atm/DSP4p.bin
File: ueagle-atm/eagleIV.fw
Version: 1.0

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Driver: ueagle-atm - Driver for USB ADSL Modems based on Eagle I,II,III

File: ueagle-atm/930-fpga.bin
File: ueagle-atm/CMVeiWO.bin
File: ueagle-atm/CMVepFR10.bin
File: ueagle-atm/DSP9p.bin
File: ueagle-atm/eagleIII.fw
File: ueagle-atm/adi930.fw
File: ueagle-atm/CMVep.bin
File: ueagle-atm/CMVepFR.bin
File: ueagle-atm/DSPei.bin
File: ueagle-atm/CMV9i.bin
File: ueagle-atm/CMVepES03.bin
File: ueagle-atm/CMVepIT.bin
File: ueagle-atm/DSPep.bin

File: ueagle-atm/CMV9p.bin
File: ueagle-atm/CMVepES.bin
File: ueagle-atm/CMVepWO.bin
File: ueagle-atm/eagleI.fw
File: ueagle-atm/CMVei.bin
File: ueagle-atm/CMVepFR04.bin
File: ueagle-atm/DSP9i.bin
File: ueagle-atm/eagleII.fw
Version: 1.1

Licence: Redistributable. Based on

<https://mail.gna.org/public/eagleusb-dev/2004-11/msg00172.html>

Driver: vxge - Exar X3100 Series 10GbE PCIe I/O Virtualized Server Adapter

File: vxge/X3fw.ncf
File: vxge/X3fw-pxe.ncf
Version: 1.8.1

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Driver: brcmsmac - Broadcom 802.11n softmac wireless LAN driver.

File: brcm/bcm43xx-0.fw
File: brcm/bcm43xx_hdr-0.fw
Version: 610.812

Licence: Redistributable. See LICENCE.broadcom_bcm43xx for details.

Driver: brcmfmac - Broadcom 802.11n fullmac wireless LAN driver.

File: brcm/bcm4329-fullmac-4.bin
File: brcm/brcmfmac43236b.bin
File: brcm/brcmfmac4329-sdio.bin
File: brcm/brcmfmac4330-sdio.bin
File: brcm/brcmfmac4334-sdio.bin
File: brcm/brcmfmac4335-sdio.bin
File: brcm/brcmfmac4339-sdio.bin
File: brcm/brcmfmac43241b0-sdio.bin
File: brcm/brcmfmac43241b4-sdio.bin
File: brcm/brcmfmac43241b5-sdio.bin
File: brcm/brcmfmac43242a.bin
File: brcm/brcmfmac43143.bin
File: brcm/brcmfmac43143-sdio.bin

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File: brcm/brcmfmac43430a0-sdio.bin
File: brcm/brcmfmac43455-sdio.bin
File: brcm/brcmfmac4350c2-pcie.bin
File: brcm/brcmfmac4350-pcie.bin
File: brcm/brcmfmac4356-sdio.bin
File: brcm/brcmfmac43569.bin
File: brcm/brcmfmac43570-pcie.bin
File: brcm/brcmfmac4358-pcie.bin
File: brcm/brcmfmac43602-pcie.bin
File: brcm/brcmfmac43602-pcie.ap.bin
File: brcm/brcmfmac4366b-pcie.bin
File: brcm/brcmfmac4366c-pcie.bin
File: brcm/brcmfmac4371-pcie.bin

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File: brcm/brcmfmac43340-sdio.bin
File: brcm/brcmfmac43362-sdio.bin
File: brcm/brcmfmac43430-sdio.bin
File: brcm/brcmfmac4354-sdio.bin
File: brcm/brcmfmac4356-pcie.bin
File: brcm/brcmfmac4373-sdio.bin
File: brcm/brcmfmac4373.bin

Licence: Redistributable. See LICENCE.cypress for details.

File: "brcm/brcmfmac4330-sdio.Prowise-PT301.txt"
File: "brcm/brcmfmac43340-sdio.meegopad-t08.txt"
File: "brcm/brcmfmac43362-sdio.cubietech,cubietruck.txt"
File: "brcm/brcmfmac43362-sdio.lemaker,bananapro.txt"
File: "brcm/brcmfmac43430a0-sdio.jumper-ezpad-mini3.txt"
File: "brcm/brcmfmac43430a0-sdio.ONDA-V80 PLUS.txt"
File: "brcm/brcmfmac43430-sdio.AP6212.txt"
File: "brcm/brcmfmac43430-sdio.Hampoo-D2D3_Vi8A1.txt"
File: "brcm/brcmfmac43430-sdio.MUR1DX.txt"
File: "brcm/brcmfmac43430-sdio.raspberrypi,3-model-b.txt"
File: "brcm/brcmfmac43455-sdio.raspberrypi,3-model-b-plus.txt"
File: "brcm/brcmfmac4356-pcie.gpd-win-pocket.txt"

Licence: GPLv2. See GPL-2 for details.

Driver: tda7706 - FM radio Highly integrated tuner for AM/FM car-radio

File: TDA7706_OM_v2.5.1_boot.txt
File: TDA7706_OM_v3.0.2_boot.txt

Licence: Redistributable. See LICENCE.tda7706-firmware.txt for details.
Copyright © 2010 STMicroelectronics

Driver: wl1251 - Texas Instruments 802.11 WLAN driver for WiLink4 chips

File: ti-connectivity/wl1251-fw.bin
Version: 4.0.4.3.7

File: ti-connectivity/wl1251-nvs.bin

Licence: Redistributable. See LICENCE.wl1251 for details.

The published NVS files are for testing only. Every device needs to have a unique NVS which is properly calibrated for best results.

The driver expects to find the firmwares under a ti-connectivity subdirectory. So if your system looks for firmwares in /lib/firmware, the firmwares for wl12xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: wl12xx - Texas Instruments 802.11 WLAN driver for WiLink6/7 chips

File: ti-connectivity/wl1271-fw.bin
Version: 6.1.0.50.350 (STA-only)
File: ti-connectivity/wl1271-fw-2.bin
Version: 6.1.5.50.74 (STA-only)
File: ti-connectivity/wl1271-fw-ap.bin
Version: 6.2.1.0.54 (AP-only)
File: ti-connectivity/wl127x-fw-3.bin
Version: 6.3.0.0.77
File: ti-connectivity/wl127x-fw-plt-3.bin
Version: 6.3.0.0.77 (PLT-only)
File: ti-connectivity/wl127x-fw-4-sr.bin
Version: 6.3.5.0.98 (Single-role)
File: ti-connectivity/wl127x-fw-4-mr.bin
Version: 6.5.2.0.15 (Multi-role)
File: ti-connectivity/wl127x-fw-4-plt.bin
Version: 6.3.5.0.98 (PLT-only)
File: ti-connectivity/wl127x-fw-5-sr.bin
Version: 6.3.10.0.142 (Single-role)
File: ti-connectivity/wl127x-fw-5-mr.bin
Version: 6.5.7.0.50 (Multi-role)
File: ti-connectivity/wl127x-fw-5-plt.bin
Version: 6.3.10.0.142 (PLT-only)

File: ti-connectivity/wl128x-fw.bin
Version: 7.1.5.50.74 (STA-only)
File: ti-connectivity/wl128x-fw-ap.bin
Version: 7.2.1.0.54 (AP-only)
File: ti-connectivity/wl128x-fw-3.bin
Version: 7.3.0.0.77
File: ti-connectivity/wl128x-fw-plt-3.bin
Version: 7.3.0.0.77
File: ti-connectivity/wl128x-fw-4-sr.bin
Version: 7.3.5.0.98 (Single-role)
File: ti-connectivity/wl128x-fw-4-mr.bin
Version: 7.5.2.0.15 (Multi-role)
File: ti-connectivity/wl128x-fw-4-plt.bin
Version: 7.3.5.0.98 (PLT)
File: ti-connectivity/wl128x-fw-5-sr.bin
Version: 7.3.10.0.142 (Single-role)

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File: ti-connectivity/wl128x-fw-5-mr.bin
Version: 7.5.7.0.50 (Multi-role)
File: ti-connectivity/wl128x-fw-5-plt.bin
Version: 7.3.10.2.142 (PLT-only)

File: ti-connectivity/wl127x-nvs.bin
File: ti-connectivity/wl128x-nvs.bin
Link: ti-connectivity/wl12xx-nvs.bin -> wl127x-nvs.bin
Link: ti-connectivity/wl1271-nvs.bin -> wl127x-nvs.bin

Licence: Redistributable. See LICENCE.ti-connectivity for details.

The NVS file includes two parts:

- radio calibration
- HW configuration parameters (aka. INI values)

The published NVS files are for testing only. Every device needs to have a unique NVS which is properly calibrated for best results. You can find more information about NVS generation for your device here:

<http://wireless.kernel.org/en/users/Drivers/wl12xx/calibrator>

If you're using a wl127x based device, use a symbolic link called wl1271-nvs.bin that links to the wl127x-nvs.bin file. If you are using wl128x, link to wl128x-nvs.bin instead.

The driver expects to find the firmwares under a ti-connectivity subdirectory. So if your system looks for firmwares in /lib/firmware, the firmwares for wl12xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: wl18xx - Texas Instruments 802.11 WLAN driver for WiLink8 chips

File: ti-connectivity/wl18xx-fw.bin
Version: 8.2.0.0.100
File: ti-connectivity/wl18xx-fw-2.bin
Version: 8.5.0.0.55
File: ti-connectivity/wl18xx-fw-3.bin
Version: 8.8.0.0.13
File: ti-connectivity/wl18xx-fw-4.bin
Version: 8.9.0.0.79

Licence: Redistributable. See LICENCE.ti-connectivity for details.

The driver expects to find the firmwares under a ti-connectivity subdirectory. So if your system looks for firmwares in /lib/firmware, the firmwares for wl18xx chips must be located in /lib/firmware/ti-connectivity/.

Driver: TI_ST - Texas Instruments bluetooth driver

File: ti-connectivity/TIInit_6.2.31.bts
Version: 2.44 (TI_P31.123)

File: ti-connectivity/TIInit_6.6.15.bts
Version: 2.14 (TI_P6_15.93)
File: ti-connectivity/TIInit_7.2.31.bts

Licence: Redistributable. See LICENCE.ti-connectivity for details.

TIInit_7.2.31.bts version 7.2.31

In order to use that file copy it to /lib/firmware/ti-connectivity.

Driver: tlg2300 - Telgent 2300 V4L/DVB driver.

File: tlg2300_firmware.bin

Licence: Redistributable.

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Driver: r8712u - Realtek 802.11n WLAN driver for RTL8712U

File: rtlwifi/rtl8712u.bin
Info: From Vendor's rtl8712_8188_8191_8192SU_usb_linux_v7_0.20100831
Reverted rtl8188C_8192C_8192D_usb_linux_v3.4.2_3727.20120404

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192ce - Realtek 802.11n WLAN driver for RTL8192CE

File: rtlwifi/rtl8192cfw.bin
File: rtlwifi/rtl8192cfwU.bin
File: rtlwifi/rtl8192cfwU_B.bin
Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192cu - Realtek 802.11n WLAN driver for RTL8192CU

File: rtlwifi/rtl8192cufw.bin
File: rtlwifi/rtl8192cufw_A.bin
File: rtlwifi/rtl8192cufw_B.bin
File: rtlwifi/rtl8192cufw_TMSC.bin

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Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192se - Realtek 802.11n WLAN driver for RTL8192SE

Info: updated from rtl_92ce_92se_92de_linux_mac80211_0004.0816.2011 driver version
File: rtlwifi/rtl8192sefw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192de - Realtek 802.11n WLAN driver for RTL8192DE

Info: Updated from Realtek version rtl_92ce_92se_92de_8723ae_linux_mac80211_0007.0809.2012
File: rtlwifi/rtl8192defw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723e - Realtek 802.11n WLAN driver for RTL8723E

Info: Taken from Realtek version rtl_92ce_92se_92de_8723ae_linux_mac80211_0007.0809.2012
File: rtlwifi/rtl8723fw.bin
File: rtlwifi/rtl8723fw_B.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723be - Realtek 802.11n WLAN driver for RTL8723BE

Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver
File: rtlwifi/rtl8723befw.bin
Info: Update to version 36 - Sent by Realtek
File: rtlwifi/rtl8723befw_36.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723de - Realtek 802.11ac WLAN driver for RTL8723DE

Info: Supplied by Vendor at https://github.com/pkshih/rtlwifi_rtl8723de
File: rtlwifi/rtl8723defw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: r8723au - Realtek 802.11n WLAN driver for RTL8723AU

Info: Taken from Realtek driver rtl8723A_WiFi_linux_v4.1.3_6044.20121224
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.

File: rtlwifi/rtl8723aufw_A.bin
File: rtlwifi/rtl8723aufw_B.bin
File: rtlwifi/rtl8723aufw_B_NoBT.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8188ee - Realtek 802.11n WLAN driver for RTL8188EE

Info: Taken from Realtek version rtl_92ce_92se_92de_8723ae_88ee_linux_mac80211_0010.0109.2013
File: rtlwifi/rtl8188efw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8188eu - Realtek 802.11n WLAN driver for RTL8188EU

Info: Taken from Realtek version RTL8188EUS_linux_v4.1.4_6773.20130222
File: rtlwifi/rtl8188eufw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8821ae - Realtek 802.11n WLAN driver for RTL8821AE

Info: From Vendor's realtek/rtlwifi_linux_mac80211_0019.0320.2014V628 driver
File: rtlwifi/rtl8821aefw.bin
File: rtlwifi/rtl8821aefw_wowlan.bin
Info: Update to version 29 - Sent by Realtek
File: rtlwifi/rtl8821aefw_29.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8822be - Realtek 802.11n WLAN driver for RTL8822BE

Info: Sent to Larry Finger by Realtek engineer Ping-Ke Shih <pkshih@realtek.com>
File: rtlwifi/rtl8822befw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtw88 - Realtek 802.11ac WLAN driver for RTL8822BE and RTL8822CE

Info: Sent to Larry Finger by Realtek engineer Yan-Hsuan Chuang <yhchuang@realtek.com>
File: rtw88/rtw8822b_fw.bin
File: rtw88/rtw8822c_fw.bin
File: rtw88/rtw8822c_wow_fw.bin
File: rtw88/README

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8192ee - Realtek 802.11n WLAN driver for RTL8192EE

Info: Initial version taken from Realtek version
rtl_92ce_92se_92de_8723ae_88ee_8723be_92ee_linux_mac80211_0017.1224.2013
Updated Jan. 14, 2015 with file added by Realtek to
http://github.com/lwfinger/rtlwifi_new.git.
File: rtlwifi/rtl8192eefw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8723bs - Realtek 802.11n WLAN driver for RTL8723BS

Info: Firmware files extracted from data statements in Realtek driver
v4.3.5.5_12290.20140916_BTCOEX20140507-4E40.
File: rtlwifi/rtl8723bs_bt.bin
File: rtlwifi/rtl8723bs_nic.bin
File: rtlwifi/rtl8723bs_ap_wowlan.bin
File: rtlwifi/rtl8723bs_wowlan.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: rtl8xxxu - Realtek 802.11n WLAN driver for RTL8XXX USB devices

Info: rtl8723au taken from Realtek driver
rtl8723A_WiFi_linux_v4.1.3_6044.20121224
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8723aufw_A.bin
File: rtlwifi/rtl8723aufw_B.bin
File: rtlwifi/rtl8723aufw_B_NoBT.bin

Info: rtl8723bu taken from Realtek driver
rtl8723BU_WiFi_linux_v4.3.16_14189.20150519_BTCOEX20150119-5844
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8723bu_nic.bin
File: rtlwifi/rtl8723bu_wowlan.bin
File: rtlwifi/rtl8723bu_ap_wowlan.bin

Info: rtl8192eu taken from Realtek driver
rtl8192EU_linux_v4.3.1.1_11320.20140505
Firmware is embedded in the driver as data statements. This info
has been extracted into a binary file.
File: rtlwifi/rtl8192eu_nic.bin
File: rtlwifi/rtl8192eu_wowlan.bin
File: rtlwifi/rtl8192eu_ap_wowlan.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Driver: r8169 - RealTek 8169/8168/8101 ethernet driver.

File: rtl_nic/rtl8168d-1.fw
File: rtl_nic/rtl8168d-2.fw
File: rtl_nic/rtl8105e-1.fw
File: rtl_nic/rtl8168e-1.fw
File: rtl_nic/rtl8168e-2.fw

File: rtl_nic/rtl8168e-3.fw
Version: 0.0.4

File: rtl_nic/rtl8168f-1.fw
Version: 0.0.5

File: rtl_nic/rtl8168f-2.fw
Version: 0.0.4

File: rtl_nic/rtl8411-1.fw
Version: 0.0.3

File: rtl_nic/rtl8411-2.fw
Version: 0.0.1

File: rtl_nic/rtl8402-1.fw
Version: 0.0.1

File: rtl_nic/rtl8106e-1.fw
Version: 0.0.1

File: rtl_nic/rtl8106e-2.fw
Version: 0.0.1

File: rtl_nic/rtl8168g-1.fw
Version: 0.0.3

File: rtl_nic/rtl8168g-2.fw
Version: 0.0.1

File: rtl_nic/rtl8168g-3.fw
Version: 0.0.1

File: rtl_nic/rtl8168h-1.fw
Version: 0.0.2

File: rtl_nic/rtl8168h-2.fw
Version: 0.0.2

File: rtl_nic/rtl8107e-1.fw
Version: 0.0.2

File: rtl_nic/rtl8107e-2.fw
Version: 0.0.2

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* notice is accompanying it.

Driver: vt6656 - VIA VT6656 USB wireless driver

File: vntwusb.fw

Licence: Redistributable. See LICENCE.via_vt6656 for details.

Driver: DFU Driver for Atheros bluetooth chipset AR3012

File: ar3k/AthrBT_0x01020001.dfu
File: ar3k/ramps_0x01020001_26.dfu
File: ar3k/AthrBT_0x01020200.dfu
File: ar3k/ramps_0x01020200_26.dfu
File: ar3k/ramps_0x01020200_40.dfu
File: ar3k/AthrBT_0x31010000.dfu
File: ar3k/ramps_0x31010000_40.dfu
File: ar3k/AthrBT_0x11020000.dfu
File: ar3k/ramps_0x11020000_40.dfu
File: ar3k/ramps_0x01020201_26.dfu
File: ar3k/ramps_0x01020201_40.dfu
File: ar3k/AthrBT_0x41020000.dfu
File: ar3k/ramps_0x41020000_40.dfu
File: ar3k/AthrBT_0x11020100.dfu
File: ar3k/ramps_0x11020100_40.dfu
File: ar3k/AthrBT_0x31010100.dfu
File: ar3k/ramps_0x31010100_40.dfu

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: DFU Driver for Atheros bluetooth chipset AR3012

File: ar3k/AthrBT_0x01020201.dfu
File: ar3k/1020201coex/ramps_0x01020201_26_HighPriority.dfu

Licence: Redistributable. See LICENCE.QualcommAtheros_ar3k for details

Driver:Atheros AR300x UART HCI Bluetooth Chip driver

File: ar3k/1020201/PS_ASIC.pst
File: ar3k/1020201/RamPatch.txt
File: ar3k/1020200/ar3kbdaddr.pst
File: ar3k/1020200/PS_ASIC.pst
File: ar3k/1020200/RamPatch.txt
File: ar3k/30101/ar3kbdaddr.pst
File: ar3k/30101/PS_ASIC.pst
File: ar3k/30101/RamPatch.txt
File: ar3k/30000/ar3kbdaddr.pst

File: ar3k/30000/PS_ASIC.pst
File: ar3k/30000/RamPatch.txt

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: ath6kl - Atheros support for AR6003

File: ath6k/AR6004/hw1.3/fw-3.bin
File: ath6k/AR6004/hw1.3/bdata.bin
File: ath6k/AR6004/hw1.2/fw-2.bin
File: ath6k/AR6004/hw1.2/bdata.bin
File: ath6k/AR6003/hw1.0/otp.bin.z77
File: ath6k/AR6003/hw1.0/bdata.SD31.bin
File: ath6k/AR6003/hw1.0/bdata.SD32.bin
File: ath6k/AR6003/hw1.0/data.patch.bin
File: ath6k/AR6003/hw1.0/bdata.WB31.bin
File: ath6k/AR6003/hw1.0/athwlan.bin.z77
File: ath6k/AR6003/hw2.1.1/fw-2.bin
File: ath6k/AR6003/hw2.1.1/fw-3.bin
File: ath6k/AR6003/hw2.1.1/otp.bin
File: ath6k/AR6003/hw2.1.1/athwlan.bin
File: ath6k/AR6003/hw2.1.1/endpointping.bin
File: ath6k/AR6003/hw2.1.1/bdata.SD31.bin
File: ath6k/AR6003/hw2.1.1/bdata.SD32.bin
File: ath6k/AR6003/hw2.1.1/data.patch.bin
File: ath6k/AR6003/hw2.1.1/bdata.WB31.bin
File: ath6k/AR6003/hw2.0/otp.bin.z77
File: ath6k/AR6003/hw2.0/bdata.SD31.bin
File: ath6k/AR6003/hw2.0/bdata.SD32.bin
File: ath6k/AR6003/hw2.0/data.patch.bin
File: ath6k/AR6003/hw2.0/bdata.WB31.bin
File: ath6k/AR6003/hw2.0/athwlan.bin.z77
File: ath6k/AR6002/eeprom.data
File: ath6k/AR6002/eeprom.bin
File: ath6k/AR6002/athwlan.bin.z77
File: ath6k/AR6002/data.patch.hw2_0.bin

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: ath10k - Qualcomm Atheros support for QCA988x family of chips

File: ath10k/QCA988X/hw2.0/board.bin
File: ath10k/QCA988X/hw2.0/firmware-4.bin
Version: 10.2.4.45
Licence: ath10k/QCA988X/hw2.0/notice_ath10k_firmware-4.txt
File: ath10k/QCA988X/hw2.0/firmware-5.bin
Version: 10.2.4-1.0-00045
Licence: ath10k/QCA988X/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA6174/hw2.1/board.bin
File: ath10k/QCA6174/hw2.1/board-2.bin
File: ath10k/QCA6174/hw2.1/firmware-5.bin
Version: SW_RM.1.1.1-00157-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw2.1/notice_ath10k_firmware-5.txt

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File: ath10k/QCA6174/hw3.0/board.bin
File: ath10k/QCA6174/hw3.0/board-2.bin
File: ath10k/QCA6174/hw3.0/firmware-4.bin
Version: WLAN.RM.2.0-00180-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw3.0/notice_ath10k_firmware-4.txt
File: ath10k/QCA6174/hw3.0/firmware-6.bin
Version: WLAN.RM.4.4.1-00140-QCARMSWPZ-1
Licence: ath10k/QCA6174/hw3.0/notice_ath10k_firmware-6.txt
File: ath10k/QCA9377/hw1.0/board.bin
File: ath10k/QCA9377/hw1.0/board-2.bin
File: ath10k/QCA9377/hw1.0/firmware-5.bin
Version: WLAN.TF.1.0-00002-QCATFSWPZ-5
Licence: ath10k/QCA9377/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA99X0/hw2.0/board.bin
File: ath10k/QCA99X0/hw2.0/firmware-5.bin
Version: 10.4.1.00030-1
Licence: ath10k/QCA99X0/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA4019/hw1.0/board-2.bin
File: ath10k/QCA4019/hw1.0/firmware-5.bin
Version: 10.4-3.6-00140
Licence: ath10k/QCA4019/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9887/hw1.0/board.bin
File: ath10k/QCA9887/hw1.0/firmware-5.bin
Version: 10.2.4-1.0-00045
Licence: ath10k/QCA9887/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9888/hw2.0/board-2.bin
File: ath10k/QCA9888/hw2.0/firmware-5.bin
Version: 10.4-3.9.0.2-00040
Licence: ath10k/QCA9888/hw2.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9984/hw1.0/board-2.bin
File: ath10k/QCA9984/hw1.0/firmware-5.bin
Version: 10.4-3.9.0.2-00046
Licence: ath10k/QCA9984/hw1.0/notice_ath10k_firmware-5.txt
File: ath10k/QCA9377/hw1.0/firmware-6.bin
Version: WLAN.TF.2.1-00021-QCARMSWP-1
Licence: ath10k/QCA9377/hw1.0/notice_ath10k_firmware-6.txt

Licence: Redistributable. See LICENSE.QualcommAtheros_ath10k for details

Driver: myri10ge - Myri10GE 10GbE NIC driver

File: myri10ge_eth_z8e.dat
File: myri10ge_ethp_z8e.dat
File: myri10ge_rss_eth_z8e.dat
File: myri10ge_rss_ethp_z8e.dat
File: myri10ge_eth_big_z8e.dat
File: myri10ge_ethp_big_z8e.dat
File: myri10ge_rss_eth_big_z8e.dat
File: myri10ge_rss_ethp_big_z8e.dat
Version: 1.4.57

Licence: Redistributable. See LICENCE.myri10ge_firmware for details.

Driver: ath6kl - Atheros support for AR6003 WiFi-Bluetooth combo module

File: ath6k/AR6003.1/hw2.1.1/athwlan.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.SD31.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.SD32.bin
File: ath6k/AR6003.1/hw2.1.1/bdata.WB31.bin
File: ath6k/AR6003.1/hw2.1.1/data.patch.bin
File: ath6k/AR6003.1/hw2.1.1/endpointping.bin
File: ath6k/AR6003.1/hw2.1.1/otp.bin

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: ath6kl - Atheros support for AR3001 WiFi-Bluetooth combo module

File: ar3k/30101coex/ar3kbdaddr.pst
File: ar3k/30101coex/PS_ASIC_aclLowPri.pst
File: ar3k/30101coex/PS_ASIC_aclHighPri.pst
File: ar3k/30101coex/PS_ASIC.pst
File: ar3k/30101coex/RamPatch.txt

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: drxk - Micronas DRX-K demodulator driver

File: dvb-usb-terratec-h5-drxk.fw

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Driver: ene-ub6250 -- ENE UB6250 SD card reader driver

File: ene-ub6250/sd_init1.bin
File: ene-ub6250/sd_init2.bin
File: ene-ub6250/sd_rdw.bin
File: ene-ub6250/ms_init.bin
File: ene-ub6250/msp_rdw.bin
File: ene-ub6250/ms_rdw.bin

Licence: Redistributable. See LICENCE.ene_firmware for details.

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Driver: isci -- Intel C600 SAS controller driver

File: isci/isci_firmware.bin
Source: isci/

Licence: GPLv2. See GPL-2 for details.

Driver: ar5523 -- Atheros AR5523 based USB Wifi dongles

File: ar5523.bin

Licence: Redistributable. See LICENCE.atheros_firmware for details

Driver: s5p-mfc - Samsung MFC video encoder/decoder driver

File: s5p-mfc.fw
File: s5p-mfc-v6.fw
File: s5p-mfc-v6-v2.fw
File: s5p-mfc-v7.fw
File: s5p-mfc-v8.fw

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Driver: carl9170 -- Atheros AR9170 802.11 draft-n USB driver

File: carl9170-1.fw
Version: 1.9.6
Source: carl9170fw/

Downloaded from <http://linuxwireless.org/en/users/Drivers/carl9170>

Licence: GPLv2. Some build scripts use the New BSD (3-clause) licence.. See GPL-2 for details.

Driver: snd-hda-codec-ca0132 - Creative Sound Core3D codec

File: ctefx.bin
File: ctspeq.bin

Licence: Redistributable. See LICENCE.ca0132 for details

Found also in alsa-firmware package.

Driver: btusb - Bluetooth USB driver

File: intel/ibt-hw-37.7.bseq
Version: 1316.02.00
File: intel/ibt-hw-37.7.10-fw-1.80.2.3.d.bseq
Version: BT_WilkinsPeak_B3_REL_87_0001
File: intel/ibt-hw-37.7.10-fw-1.0.2.3.d.bseq
Version: BT_WilkinsPeak_B3_REL_87_0001
File: intel/ibt-hw-37.7.10-fw-1.80.1.2d.d.bseq
Version: BT_WilkinsPeak_B5_REL_42_0001
File: intel/ibt-hw-37.7.10-fw-1.0.1.2d.d.bseq
Version: BT_WilkinsPeak_B5_REL_42_0001
File: intel/ibt-hw-37.8.bseq
Version: 1339_02.00
File: intel/ibt-hw-37.8.10-fw-1.10.2.27.d.bseq
Version: BT_StonePeak_C0_REL_59_0001
File: intel/ibt-hw-37.8.10-fw-1.10.3.11.e.bseq
Version: BT_StonePeak_D0_REL_50_0002
File: intel/ibt-hw-37.8.10-fw-22.50.19.14.f.bseq
Version: BT_StonePeak_D1_REL_52_00005
File: intel/ibt-11-5.ddc
Version: LnP/SfP_REL0522
File: intel/ibt-11-5.sfi
Version: BT_LightningPeak_REL0487
File: intel/ibt-12-16.ddc
Version: BT_WindStormPeak_REL0306
File: intel/ibt-12-16.sfi
Version: BT_WindStormPeak_REL0306
File: intel/ibt-17-16-1.sfi
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-16-1.ddc
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-2.sfi
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-2.ddc
Version: BT_JeffersonPeak_B0_B0_REL0472
File: intel/ibt-17-0-1.sfi
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-0-1.ddc
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-1.sfi
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-17-1.ddc
Version: BT_JeffersonPeak_A0_B0_REL0201
File: intel/ibt-18-16-1.sfi
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-16-1.ddc
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-2.sfi
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-2.ddc
Version: BT_ThunderPeak_B0_B0_REL0472
File: intel/ibt-18-0-1.sfi

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Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-0-1.ddc
Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-1.sfi
Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-18-1.ddc
Version: BT_ThunderPeak_A0_B0_REL0201
File: intel/ibt-20-0-3.sfi
Version: BT_CyclonePeak_A0_REL0310
File: intel/ibt-20-0-3.ddc
Version: BT_CyclonePeak_A0_REL0310
File: intel/ibt-20-1-3.sfi
Version: BT_CyclonePeak_A0_REL0310
File: intel/ibt-20-1-3.ddc
Version: BT_CyclonePeak_A0_REL_0310
File: intel/ibt-20-1-4.sfi
Version: BT_CyclonePeak_A0_REL0310
File: intel/ibt-20-1-4.ddc
Version: BT_CyclonePeak_A0_REL0310
File: intel/ibt-19-0-0.sfi
Version: BT_Quasar_REL0310
File: intel/ibt-19-0-0.ddc
Version: BT_Quasar_REL0310
File: intel/ibt-19-0-1.sfi
Version: BT_Quasar_REL0310
File: intel/ibt-19-0-1.ddc
Version: BT_Quasar_REL0310
File: intel/ibt-19-0-4.sfi
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-0-4.ddc
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-16-4.sfi
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-16-4.ddc
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-32-1.sfi
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-32-1.ddc
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-32-0.sfi
Version: BT_HarrisonPeak_REL0310
File: intel/ibt-19-32-0.ddc
Version: BT_HarrisonPeak_REL0310

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File: rtl_bt/rtl8192ee_fw.bin
File: rtl_bt/rtl8192eu_fw.bin
File: rtl_bt/rtl8723a_fw.bin
File: rtl_bt/rtl8723b_fw.bin
File: rtl_bt/rtl8723bs_fw.bin
File: rtl_bt/rtl8723bs_config-OBDA8723.bin
File: rtl_bt/rtl8761a_fw.bin
File: rtl_bt/rtl8812ae_fw.bin
File: rtl_bt/rtl8821a_fw.bin
File: rtl_bt/rtl8822b_fw.bin

File: rtl_bt/rtl8822b_config.bin
File: rtl_bt/rtl8723d_fw.bin
File: rtl_bt/rtl8723d_config.bin
File: rtl_bt/rtl8821c_fw.bin
File: rtl_bt/rtl8821c_config.bin
File: rtl_bt/rtl8822cu_fw.bin

Licence: Redistributable. See LICENCE.rtlwifi_firmware.txt for details.

Found in vendor driver, linux_bt_usb_2.11.20140423_8723be.rar
From https://github.com/troy-tan/driver_store
Files rtl_bt/rtl8822b_* came directly from Realtek. These files are updated on April 14, 2017.
Files rtl_bt/rtl8821c_* and rtl_bt/rtl8723d_* came directly from Realtek.
File rtl_bt/rtl8822cu_fw.bin came directly from Realtek.
updated on February 24, 2019
File rtl_bt/rtl8822cu_fw.bin came directly from Realtek.

Driver: btmk_usb - Bluetooth USB driver

File: mt7650.bin

Licence: Redistributable. See LICENCE.ralink_a_mEDIATEK_company_firmware for details

Driver: rp2 -- Comtrol RocketPort 2 serial driver

File: rp2.fw

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Driver: go7007

File: go7007/s2250-1.fw
File: go7007/s2250-2.fw
Link: s2250.fw -> go7007/s2250-2.fw
Link: s2250_loader.fw -> go7007/s2250-1.fw

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File: go7007/go7007fw.bin
File: go7007/go7007tv.bin
File: go7007/lr192.fw
File: go7007/px-m402u.fw
File: go7007/px-tv402u.fw
File: go7007/wis-startrek.fw

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Driver: ccp - Platform Security Processor (PSP) device

File: amd/amd_sev_fam17h_model0xh.sbin
Version: 2019-02-13

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Driver: microcode_amd - AMD CPU Microcode Update Driver for Linux

File: amd-ucode/microcode_amd.bin
Version: 2013-07-10
File: amd-ucode/microcode_amd_fam15h.bin
Version: 2018-05-24
File: amd-ucode/microcode_amd_fam16h.bin
Version: 2014-10-28
File: amd-ucode/microcode_amd_fam17h.bin
Version: 2018-11-28

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Driver: mxu11x0 - MOXA UPort 11x0 USB Serial hub driver

File: moxa/moxa-1110.fw
File: moxa/moxa-1130.fw
File: moxa/moxa-1131.fw
File: moxa/moxa-1150.fw
File: moxa/moxa-1151.fw

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Driver: mxuport - MOXA UPort USB Serial hub driver

File: moxa/moxa-1250.fw
File: moxa/moxa-1251.fw

File: moxa/moxa-1410.fw
File: moxa/moxa-1450.fw
File: moxa/moxa-1451.fw
File: moxa/moxa-1613.fw
File: moxa/moxa-1618.fw
File: moxa/moxa-1653.fw
File: moxa/moxa-1658.fw

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Driver: cw1200 - ST-E CW1100/CW1200 WLAN driver

File: wsm_22.bin
Version: WSM395
Licence: Redistributable. See LICENCE.cw1200 for details.

File: sdd_sagrad_1091_1098.bin

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(Please note that the actual device firmware is separately licensed)

Driver: BFA/BNA - QLogic BR-series Adapter FC/FCOE drivers

File: cbfw-3.2.1.1.bin
File: ctfw-3.2.1.1.bin
File: ct2fw-3.2.1.1.bin
File: cbfw-3.2.3.0.bin
File: ctfw-3.2.3.0.bin
File: ct2fw-3.2.3.0.bin
File: cbfw-3.2.5.1.bin
File: ctfw-3.2.5.1.bin
File: ct2fw-3.2.5.1.bin

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Driver: qat - Intel(R) QAT crypto accelerator

File: qat_895xcc.bin
File: qat_895xcc_mmp.bin
File: qat_c3xxx.bin
File: qat_c3xxx_mmp.bin
File: qat_c62x.bin
File: qat_c62x_mmp.bin
Link: qat_mmp.bin -> qat_895xcc_mmp.bin

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Driver: rsi -- Redpine Signals Inc 91x driver

File: rsi_91x.fw

File: rsi/rs9113_wlan_qsps.rps
Version: 1.6.1

File: rsi/rs9113_wlan_bt_dual_mode.rps
Version: 1.6.1

File: rsi/rs9113_ap_bt_dual_mode.rps
Version: 1.6.1

File: rsi/rs9116_wlan.rps
Version: 1.0.5b

File: rsi/rs9116_wlan_bt_classic.rps
Version: 1.0.5b

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Driver: xhci-rcar -- Renesas R-Car Gen2/3 USB 3.0 host controller driver

File: r8a779x_usb3_v1.dlmem
File: r8a779x_usb3_v2.dlmem
File: r8a779x_usb3_v3.dlmem

Licence: Redistributable. See LICENCE.r8a779x_usb3 for details.

Driver: snd_soc_sst_acpi

File: intel/fw_sst_0f28.bin-48kHz_i2s_master

License: Redistributable. See LICENCE.fw_sst_0f28 for details

Driver: as102 - Abilis Systems Single DVB-T Receiver

File: as102_data1_st.hex
File: as102_data2_st.hex

License: Redistributable. See LICENCE.Abilis for details

Driver: it9135 -- ITEtech IT913x DVB-T USB driver

File: dvb-usb-it9135-01.fw
File: dvb-usb-it9135-02.fw

Licence: Redistributable. See LICENCE.it913x for details

Driver: snd_soc_sst_acpi

File: intel/IntcSST2.bin
Version: 8.4.1.77

License: Redistributable. See LICENCE.IntcSST2 for details

Driver: snd_intel_sst_core

File: intel/fw_sst_0f28.bin
File: intel/fw_sst_0f28_ssp0.bin

License: Redistributable. See LICENCE.fw_sst_0f28 for details

Driver: snd_intel_sst_core

File: intel/fw_sst_22a8.bin
Version: 01.0B.02.02

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License: Redistributable. See LICENCE.fw_sst_0f28 for details

Driver: snd-soc-skl

File: intel/dsp_fw_release_v969.bin
Version: 8.20.00.969
File: intel/dsp_fw_release_v3402.bin
Version: 9.21.00.3402_161
Link: intel/dsp_fw_release.bin -> intel/dsp_fw_release_v3402.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_bxt_n_v2219.bin
Version: 9.22.01.2219_64
File: intel/dsp_fw_bxt_n_v3366.bin
Version: 9.22.01.3366_157
Link: intel/dsp_fw_bxt_n.bin -> intel/dsp_fw_bxt_n_v3366.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_kbl_v701.bin
Version: 9.21.00.701
File: intel/dsp_fw_kbl_v1037.bin
Version: 09.21.00.1037
File: intel/dsp_fw_kbl_v2042.bin
Version: 9.21.00.2042_46
File: intel/dsp_fw_kbl_v2630.bin
Version: 9.21.00.2630_97
File: intel/dsp_fw_kbl_v3266.bin
Version: 9.21.00.3266_144
File: intel/dsp_fw_kbl_v3420.bin
Version: 9.21.00.3420_163
File: intel/dsp_fw_kbl_v3402.bin
Version: 9.21.00.3402_161
Link: intel/dsp_fw_kbl.bin -> dsp_fw_kbl_v3402.bin

License: Redistributable. See LICENCE.adsp_sst for details

File: intel/dsp_fw_glk_v1814.bin
Version: 9.92.01.1814
File: intel/dsp_fw_glk_v2880.bin
Version: 9.22.00.2880
File: intel/dsp_fw_glk_v2768.bin
Version: 9.22.01.2768
File: intel/dsp_fw_glk_v3366.bin
Version: 9.22.01.3366_157
Link: intel/dsp_fw_glk.bin -> dsp_fw_glk_v3366.bin

File: intel/dsp_fw_cnl_v1191.bin
Version: 10.00.00.1191
File: intel/dsp_fw_cnl_v1858.bin
Version: 10.23.00.1858
File: intel/dsp_fw_cnl.bin
Link: intel/dsp_fw_cnl.bin -> intel/dsp_fw_cnl_v1858.bin

License: Redistributable. See LICENCE.adsp_sst for details

Driver: smsmdtv - Siano MDTV Core module

File: cmmmb_vega_12mhz.inp
File: cmmmb_venice_12mhz.inp
File: dvb_nova_12mhz.inp
File: dvb_nova_12mhz_b0.inp
File: isdbt_nova_12mhz.inp
File: isdbt_nova_12mhz_b0.inp
File: isdbt_rio.inp
File: sms1xxx-hcw-55xxx-dvbt-02.fw
File: sms1xxx-hcw-55xxx-isdbt-02.fw
File: sms1xxx-nova-a-dvbt-01.fw
File: sms1xxx-nova-b-dvbt-01.fw
File: sms1xxx-stellar-dvbt-01.fw
File: tdm_b_nova_12mhz.inp

Licence: Redistributable. See LICENCE.siano for details

Driver: xhci-tegra -- NVIDIA Tegra XHCI driver

File: nvidia/tegra124/xusb.bin
Version: v45.46

File: nvidia/tegra210/xusb.bin
Version: v50.10

Licence: Redistributable. See LICENCE.nvidia for details

Driver: tegra-vic -- NVIDIA Tegra VIC driver

File: nvidia/tegra124/vic03_ucose.bin
File: nvidia/tegra210/vic04_ucose.bin
File: nvidia/tegra186/vic04_ucose.bin

Licence: Redistributable. See LICENCE.nvidia for details

Driver: atusb - ATUSB IEEE 802.15.4 transceiver driver

File: atusb/atusb-0.2.dfu
Version: 0.2
File: atusb/atusb-0.3.dfu
Version: 0.3
File: atusb/rzusb-0.3.bin
Version: 0.3
Info: atusb/ChangeLog

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Licence: GPLv2 or later. See GPL-2 and GPL-3 for details.

Driver: qca - Qualcomm Atheros Bluetooth support for QCA61x4 chips

File: qca/nvm_usb_00000201.bin
File: qca/nvm_usb_00000200.bin
File: qca/nvm_usb_00000300.bin
File: qca/nvm_usb_00000302.bin
File: qca/nvm_00130300.bin
File: qca/nvm_00130302.bin
File: qca/rampatch_usb_00000200.bin
File: qca/rampatch_usb_00000201.bin
File: qca/rampatch_usb_00000300.bin
File: qca/rampatch_usb_00000302.bin
File: qca/rampatch_00130300.bin
File: qca/rampatch_00130302.bin
File: qca/crbtfw21.tlv
File: qca/crnv21.bin
File: qca/nvm_00440302.bin
File: qca/rampatch_00440302.bin

Licence: Redistributable. See LICENSE.QualcommAtheros_ath10k and qca/NOTICE.txt for details

Driver: liquidio -- Cavium LiquidIO driver

File: liquidio/lío_23xx_nic.bin
Version: v1.7.2

File: liquidio/lío_23xx_vsw.bin
Version: v1.7.2

File: liquidio/lío_210nv_nic.bin
Version: v1.7.2

File: liquidio/lío_210sv_nic.bin
Version: v1.7.2

File: liquidio/lío_410nv_nic.bin
Version: v1.7.2

Licence: Redistributable. See LICENCE.cavium_liquidio for details

Driver: nitrox -- Cavium CNN55XX crypto driver

File: cavium/cnn55xx_ae.fw
Version: v01

File: cavium/cnn55xx_se.fw
Version: v10

Licence: Redistributable. See LICENCE.cavium for details

Driver: i915 -- Intel Integrated Graphics driver

File: i915/skl_dmc_ver1_23.bin
File: i915/skl_dmc_ver1_26.bin
File: i915/skl_dmc_ver1_27.bin
File: i915/skl_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 27 for Skylake

File: i915/bxt_dmc_ver1_07.bin
File: i915/bxt_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 07 for Broxton

File: i915/kbl_dmc_ver1_01.bin
File: i915/kbl_dmc_ver1.bin
Version: DMC API/ABI ver 1 - release 01 for Kabylake

File: i915/kbl_dmc_ver1_04.bin
File: i915/kbl_dmc_ver1_04.bin
Version: DMC API/ABI ver 1 - release 04 for Kabylake

File: i915/skl_guc_ver1.bin
Version: Guc API/ABI ver 1 - release 1059 for Skylake

File: i915/skl_guc_ver4.bin
Version: Guc API/ABI ver 4 - release 3 for Skylake

File: i915/skl_guc_ver6_1.bin
File: i915/skl_guc_ver6.bin
Version: Guc API/ABI ver 6 - release 1 for Skylake

File: i915/skl_guc_ver9_33.bin
Version: Guc API/ABI ver 9 - release 33 for Skylake

File: i915/skl_guc_32.0.3.bin
Version: Guc API/ABI ver 32 - release 0 for Skylake

File: i915/skl_guc_33.0.0.bin
Version: Guc API/ABI ver 33 - release 0 for Skylake

File: i915/skl_huc_ver01_07_1398.bin
Version: HuC API/ABI ver 1 - release 7 for Skylake

File: i915/bxt_huc_ver01_07_1398.bin
Version: HuC API/APB ver 1 - release 7 for Broxton

File: i915/bxt_huc_ver01_8_2893.bin
Version: HuC API/APB ver 1 - release 8 for Broxton

File: i915/kbl_huc_ver02_00_1810.bin
Version: HuC API/APB ver 2 - for Kabylake

File: i915/bxt_guc_ver8_7.bin
Version: Guc API/APB ver 8 - release 7 for Broxton

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File: i915/bxt_guc_ver9_29.bin
Version: Guc API/APB ver 9 - release 29 for Broxton

File: i915/bxt_guc_32.0.3.bin
Version: Guc API/APB ver 32 - release 0 for Broxton

File: i915/bxt_guc_33.0.0.bin
Version: Guc API/APB ver 33 - release 0 for Broxton

File: i915/kbl_guc_ver9_14.bin
Version: Guc API/APB ver 9 release 14 for Kabylake

File: i915/kbl_guc_ver9_39.bin
Version: Guc API/APB ver 9 release 39 for Kabylake

File: i915/kbl_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Kabylake

File: i915/kbl_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Kabylake

File: i915/glk_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Geminilake

File: i915/glk_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Geminilake

File: i915/glk_huc_ver03_01_2893.bin
Version: Huc API/APB ver 3 release 1 for Geminilake

File: i915/glk_dmc_ver1_04.bin
Version: DMC API/ABI ver 1 - release 04 for Geminilake

File: i915/cnl_dmc_ver1_06.bin
Version: DMC API/ABI ver 1 - release 06 for Cannonlake

File: i915/cnl_dmc_ver1_07.bin
Version: DMC API/ABI ver 1 - release 07 for Cannonlake

File: i915/icl_dmc_ver1_07.bin
Version: DMC API/ABI ver 1 - release 07 for icelake

File: i915/icl_guc_32.0.3.bin
Version: Guc API/APB ver 32 release 0 for Icelake

File: i915/icl_guc_33.0.0.bin
Version: Guc API/APB ver 33 release 0 for Icelake

File: i915/icl_huc_ver8_4_3238.bin
Version: Huc API/APB ver 8 release 4 for Icelake
License: Redistributable. See LICENSE.i915 for details

Driver: nouveau - NVIDIA GPU driver

File: nvidia/gk20a/fecs_data.bin

File: nvidia/gk20a/fecs_inst.bin
File: nvidia/gk20a/gpccs_data.bin
File: nvidia/gk20a/gpccs_inst.bin
File: nvidia/gk20a/sw_bundle_init.bin
File: nvidia/gk20a/sw_ctx.bin
File: nvidia/gk20a/sw_method_init.bin
File: nvidia/gk20a/sw_nonctx.bin
File: nvidia/gm200/acr/bl.bin
File: nvidia/gm200/acr/ucode_load.bin
File: nvidia/gm200/acr/ucode_unload.bin
File: nvidia/gm200/gr/fecs_bl.bin
File: nvidia/gm200/gr/fecs_data.bin
File: nvidia/gm200/gr/fecs_inst.bin
File: nvidia/gm200/gr/fecs_sig.bin
File: nvidia/gm200/gr/gpccs_bl.bin
File: nvidia/gm200/gr/gpccs_data.bin
File: nvidia/gm200/gr/gpccs_inst.bin
File: nvidia/gm200/gr/gpccs_sig.bin
File: nvidia/gm200/gr/sw_bundle_init.bin
File: nvidia/gm200/gr/sw_ctx.bin
File: nvidia/gm200/gr/sw_method_init.bin
File: nvidia/gm200/gr/sw_nonctx.bin
File: nvidia/gm204/acr/bl.bin
File: nvidia/gm204/acr/ucode_load.bin
File: nvidia/gm204/acr/ucode_unload.bin
File: nvidia/gm204/gr/fecs_bl.bin
File: nvidia/gm204/gr/fecs_data.bin
File: nvidia/gm204/gr/fecs_inst.bin
File: nvidia/gm204/gr/fecs_sig.bin
File: nvidia/gm204/gr/gpccs_bl.bin
File: nvidia/gm204/gr/gpccs_data.bin
File: nvidia/gm204/gr/gpccs_inst.bin
File: nvidia/gm204/gr/gpccs_sig.bin
File: nvidia/gm204/gr/sw_bundle_init.bin
File: nvidia/gm204/gr/sw_ctx.bin
File: nvidia/gm204/gr/sw_method_init.bin
File: nvidia/gm204/gr/sw_nonctx.bin
File: nvidia/gm206/acr/bl.bin
File: nvidia/gm206/acr/ucode_load.bin
File: nvidia/gm206/acr/ucode_unload.bin
File: nvidia/gm206/gr/fecs_bl.bin
File: nvidia/gm206/gr/fecs_data.bin
File: nvidia/gm206/gr/fecs_inst.bin
File: nvidia/gm206/gr/fecs_sig.bin
File: nvidia/gm206/gr/gpccs_bl.bin
File: nvidia/gm206/gr/gpccs_data.bin
File: nvidia/gm206/gr/gpccs_inst.bin
File: nvidia/gm206/gr/gpccs_sig.bin
File: nvidia/gm206/gr/sw_bundle_init.bin
File: nvidia/gm206/gr/sw_ctx.bin
File: nvidia/gm206/gr/sw_method_init.bin
File: nvidia/gm206/gr/sw_nonctx.bin
File: nvidia/gm20b/acr/bl.bin
File: nvidia/gm20b/acr/ucode_load.bin
File: nvidia/gm20b/gr/fecs_bl.bin
File: nvidia/gm20b/gr/fecs_data.bin
File: nvidia/gm20b/gr/fecs_inst.bin

File: nvidia/gm20b/gr/fecs_sig.bin
 File: nvidia/gm20b/gr/gpccs_data.bin
 File: nvidia/gm20b/gr/gpccs_inst.bin
 File: nvidia/gm20b/gr/sw_bundle_init.bin
 File: nvidia/gm20b/gr/sw_ctx.bin
 File: nvidia/gm20b/gr/sw_method_init.bin
 File: nvidia/gm20b/gr/sw_nonctx.bin
 File: nvidia/gm20b/pmu/desc.bin
 File: nvidia/gm20b/pmu/image.bin
 File: nvidia/gm20b/pmu/sig.bin
 File: nvidia/gp100/acr/bl.bin
 File: nvidia/gp100/acr/ucode_load.bin
 File: nvidia/gp100/acr/ucode_unload.bin
 File: nvidia/gp100/gr/fecs_bl.bin
 File: nvidia/gp100/gr/fecs_data.bin
 File: nvidia/gp100/gr/fecs_inst.bin
 File: nvidia/gp100/gr/fecs_sig.bin
 File: nvidia/gp100/gr/gpccs_bl.bin
 File: nvidia/gp100/gr/gpccs_data.bin
 File: nvidia/gp100/gr/gpccs_inst.bin
 File: nvidia/gp100/gr/gpccs_sig.bin
 File: nvidia/gp100/gr/sw_bundle_init.bin
 File: nvidia/gp100/gr/sw_ctx.bin
 File: nvidia/gp100/gr/sw_method_init.bin
 File: nvidia/gp100/gr/sw_nonctx.bin
 File: nvidia/gp102/acr/bl.bin
 File: nvidia/gp102/acr/ucode_load.bin
 File: nvidia/gp102/acr/ucode_unload.bin
 File: nvidia/gp102/acr/unload_bl.bin
 File: nvidia/gp102/gr/fecs_bl.bin
 File: nvidia/gp102/gr/fecs_data.bin
 File: nvidia/gp102/gr/fecs_inst.bin
 File: nvidia/gp102/gr/fecs_sig.bin
 File: nvidia/gp102/gr/gpccs_bl.bin
 File: nvidia/gp102/gr/gpccs_data.bin
 File: nvidia/gp102/gr/gpccs_inst.bin
 File: nvidia/gp102/gr/gpccs_sig.bin
 File: nvidia/gp102/gr/sw_bundle_init.bin
 File: nvidia/gp102/gr/sw_ctx.bin
 File: nvidia/gp102/gr/sw_method_init.bin
 File: nvidia/gp102/gr/sw_nonctx.bin
 File: nvidia/gp102/nvdec/scrubber.bin
 File: nvidia/gp102/sec2/desc.bin
 File: nvidia/gp102/sec2/image.bin
 File: nvidia/gp102/sec2/sig.bin
 File: nvidia/gp102/sec2/desc-1.bin
 File: nvidia/gp102/sec2/image-1.bin
 File: nvidia/gp102/sec2/sig-1.bin
 File: nvidia/gp104/acr/bl.bin
 File: nvidia/gp104/acr/ucode_load.bin
 File: nvidia/gp104/acr/ucode_unload.bin
 File: nvidia/gp104/acr/unload_bl.bin
 File: nvidia/gp104/gr/fecs_bl.bin
 File: nvidia/gp104/gr/fecs_data.bin
 File: nvidia/gp104/gr/fecs_inst.bin
 File: nvidia/gp104/gr/fecs_sig.bin
 File: nvidia/gp104/gr/gpccs_bl.bin

File: nvidia/gp104/gr/gpccs_data.bin
 File: nvidia/gp104/gr/gpccs_inst.bin
 File: nvidia/gp104/gr/gpccs_sig.bin
 File: nvidia/gp104/gr/sw_bundle_init.bin
 File: nvidia/gp104/gr/sw_ctx.bin
 File: nvidia/gp104/gr/sw_method_init.bin
 File: nvidia/gp104/gr/sw_nonctx.bin
 File: nvidia/gp104/nvdec/scrubber.bin
 File: nvidia/gp104/sec2/desc.bin
 File: nvidia/gp104/sec2/image.bin
 File: nvidia/gp104/sec2/sig.bin
 File: nvidia/gp104/sec2/desc-1.bin
 File: nvidia/gp104/sec2/image-1.bin
 File: nvidia/gp104/sec2/sig-1.bin
 File: nvidia/gp106/acr/bl.bin
 File: nvidia/gp106/acr/ucode_load.bin
 File: nvidia/gp106/acr/ucode_unload.bin
 File: nvidia/gp106/acr/unload_bl.bin
 File: nvidia/gp106/gr/fecs_bl.bin
 File: nvidia/gp106/gr/fecs_data.bin
 File: nvidia/gp106/gr/fecs_inst.bin
 File: nvidia/gp106/gr/fecs_sig.bin
 File: nvidia/gp106/gr/gpccs_bl.bin
 File: nvidia/gp106/gr/gpccs_data.bin
 File: nvidia/gp106/gr/gpccs_inst.bin
 File: nvidia/gp106/gr/gpccs_sig.bin
 File: nvidia/gp106/gr/sw_bundle_init.bin
 File: nvidia/gp106/gr/sw_ctx.bin
 File: nvidia/gp106/gr/sw_method_init.bin
 File: nvidia/gp106/gr/sw_nonctx.bin
 File: nvidia/gp106/nvdec/scrubber.bin
 File: nvidia/gp106/sec2/desc.bin
 File: nvidia/gp106/sec2/image.bin
 File: nvidia/gp106/sec2/sig.bin
 File: nvidia/gp106/sec2/desc-1.bin
 File: nvidia/gp106/sec2/image-1.bin
 File: nvidia/gp106/sec2/sig-1.bin
 File: nvidia/gp107/acr/bl.bin
 File: nvidia/gp107/acr/ucode_load.bin
 File: nvidia/gp107/acr/ucode_unload.bin
 File: nvidia/gp107/acr/unload_bl.bin
 File: nvidia/gp107/gr/fecs_bl.bin
 File: nvidia/gp107/gr/fecs_data.bin
 File: nvidia/gp107/gr/fecs_inst.bin
 File: nvidia/gp107/gr/fecs_sig.bin
 File: nvidia/gp107/gr/gpccs_bl.bin
 File: nvidia/gp107/gr/gpccs_data.bin
 File: nvidia/gp107/gr/gpccs_inst.bin
 File: nvidia/gp107/gr/gpccs_sig.bin
 File: nvidia/gp107/gr/sw_bundle_init.bin
 File: nvidia/gp107/gr/sw_ctx.bin
 File: nvidia/gp107/gr/sw_method_init.bin
 File: nvidia/gp107/gr/sw_nonctx.bin
 File: nvidia/gp107/nvdec/scrubber.bin
 File: nvidia/gp107/sec2/desc.bin
 File: nvidia/gp107/sec2/image.bin
 File: nvidia/gp107/sec2/sig.bin

File: nvidia/gp107/sec2/desc-1.bin
File: nvidia/gp107/sec2/image-1.bin
File: nvidia/gp107/sec2/sig-1.bin
File: nvidia/gp10b/acr/bl.bin
File: nvidia/gp10b/acr/ucode_load.bin
File: nvidia/gp10b/gr/fecs_bl.bin
File: nvidia/gp10b/gr/fecs_data.bin
File: nvidia/gp10b/gr/fecs_inst.bin
File: nvidia/gp10b/gr/fecs_sig.bin
File: nvidia/gp10b/gr/gpccs_bl.bin
File: nvidia/gp10b/gr/gpccs_data.bin
File: nvidia/gp10b/gr/gpccs_inst.bin
File: nvidia/gp10b/gr/gpccs_sig.bin
File: nvidia/gp10b/gr/sw_bundle_init.bin
File: nvidia/gp10b/gr/sw_ctx.bin
File: nvidia/gp10b/gr/sw_method_init.bin
File: nvidia/gp10b/gr/sw_nonctx.bin
File: nvidia/gp10b/pmu/desc.bin
File: nvidia/gp10b/pmu/image.bin
File: nvidia/gp10b/pmu/sig.bin
File: nvidia/gp108/acr/bl.bin
File: nvidia/gp108/acr/ucode_load.bin
File: nvidia/gp108/acr/ucode_unload.bin
File: nvidia/gp108/acr/unload_bl.bin
File: nvidia/gp108/gr/fecs_bl.bin
File: nvidia/gp108/gr/fecs_data.bin
File: nvidia/gp108/gr/fecs_inst.bin
File: nvidia/gp108/gr/fecs_sig.bin
File: nvidia/gp108/gr/gpccs_bl.bin
File: nvidia/gp108/gr/gpccs_data.bin
File: nvidia/gp108/gr/gpccs_inst.bin
File: nvidia/gp108/gr/gpccs_sig.bin
File: nvidia/gp108/gr/sw_bundle_init.bin
File: nvidia/gp108/gr/sw_ctx.bin
File: nvidia/gp108/gr/sw_method_init.bin
File: nvidia/gp108/gr/sw_nonctx.bin
File: nvidia/gp108/nvdec/scrubber.bin
File: nvidia/gp108/sec2/desc.bin
File: nvidia/gp108/sec2/image.bin
File: nvidia/gp108/sec2/sig.bin
File: nvidia/gv100/acr/bl.bin
File: nvidia/gv100/acr/ucode_load.bin
File: nvidia/gv100/acr/ucode_unload.bin
File: nvidia/gv100/acr/unload_bl.bin
File: nvidia/gv100/gr/fecs_bl.bin
File: nvidia/gv100/gr/fecs_data.bin
File: nvidia/gv100/gr/fecs_inst.bin
File: nvidia/gv100/gr/fecs_sig.bin
File: nvidia/gv100/gr/gpccs_bl.bin
File: nvidia/gv100/gr/gpccs_data.bin
File: nvidia/gv100/gr/gpccs_inst.bin
File: nvidia/gv100/gr/gpccs_sig.bin
File: nvidia/gv100/gr/sw_bundle_init.bin
File: nvidia/gv100/gr/sw_ctx.bin
File: nvidia/gv100/gr/sw_method_init.bin
File: nvidia/gv100/gr/sw_nonctx.bin
File: nvidia/gv100/nvdec/scrubber.bin

File: nvidia/gv100/sec2/desc.bin
File: nvidia/gv100/sec2/image.bin
File: nvidia/gv100/sec2/sig.bin

File: nvidia/tu10x/typec/ccg_primary.cyacd
File: nvidia/tu10x/typec/ccg_secondary.cyacd
File: nvidia/tu10x/typec/ccg_boot.cyacd

Licence: Redistributable. See LICENCE.nvidia for details

Driver: wilc1000 - Atmel 802.11n WLAN driver for WILC1000

File: atmel/wilc1000_fw.bin
File: atmel/wilc1000_ap_fw.bin
File: atmel/wilc1000_p2p_fw.bin
File: atmel/wilc1000_wifi_firmware.bin

License: Redistributable. See LICENSE.atmel for details

Driver: hfi1 - Intel OPA Gen 1 adapter

File: hfi1_dc8051.fw
Version: 1.27.0
File: hfi1_fabric.fw
Version: 0x1055
File: hfi1_pcie.fw
Version: 0x4755
File: hfi1_sbus.fw
Version: 0x10130001

Licence: Redistributable. See LICENSE.hfi1_firmware for details

Driver: knav_qmss_queue - TI Keystone 2 QMSS driver

File: ti-keystone/ks2_qmss_pdsp_acc48_k2_le_1_0_0_9.bin

Licence: Redistributable. See LICENCE.ti-keystone for details.

Driver: mwlfwifi - Marvell mac80211 driver for 80211ac cards.

File: mwlfwifi/88W8864.bin
Version: 7.2.8.6

File: mwlfwifi/88W8897.bin
Version: 8.2.0.10

Licence: Redistributable. See LICENCE.Marvell for details.

Driver: mtk-vpu - Mediatek VPU video processing unit driver

File: vpu_d.bin
File: vpu_p.bin

Licence: Redistributable.

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Driver: btmtnk - MediaTek Bluetooth Driver

File: mediatek/mt7622pr2h.bin
Version: 20180621204904
File: mediatek/mt7668pr2h.bin
Version: 20180517181834

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: rk3399-dptx - ROCKCHIP rk3399 dptx firmware

File: rockchip/dptx.bin
Version: 3.1

Licence: Redistributable. See LICENCE.rockchip for details.

Driver: mt76x0 - MediaTek MT76x0 Wireless MACs

File: mediatek/mt7610u.bin
File: mediatek/mt7610e.bin
Version: 2.6
File: mediatek/mt7650e.bin
Version: 1.0.07-b370

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: mt76x2e - MediaTek MT76x2 Wireless MACs

File: mt7662.bin
Version: 1.9

File: mt7662_rom_patch.bin

Version: 0.0.2_P69

Licence: Redistributable. See LICENCE.ralink_a_mEDIATEK_company_firmware for details

Driver: mt76x2u - MediaTek MT76x2u Wireless MACs

File: mediatek/mt7662u.bin
Version: 1.5

File: mediatek/mt7662u_rom_patch.bin
Version: 0.0.2_P48

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: mt7615e - MediaTek MT7615e Wireless MACs

File: mediatek/mt7615_n9.bin
Version: 20190114
File: mediatek/mt7615_cr4.bin
Version: 20190114
File: mediatek/mt7615_rom_patch.bin
Version: 20190114

Licence: Redistributable. See LICENCE.mediatek for details.

Driver: nfp - Netronome Flow Processor

Link: netronome/nic_AMDA0081-0001_1x40.nffw -> nic/nic_AMDA0081-0001_1x40.nffw
Link: netronome/nic_AMDA0097-0001_2x40.nffw -> nic/nic_AMDA0097-0001_2x40.nffw
Link: netronome/nic_AMDA0099-0001_2x10.nffw -> nic/nic_AMDA0099-0001_2x10.nffw
Link: netronome/nic_AMDA0081-0001_4x10.nffw -> nic/nic_AMDA0081-0001_4x10.nffw
Link: netronome/nic_AMDA0097-0001_4x10_1x40.nffw -> nic/nic_AMDA0097-0001_4x10_1x40.nffw
Link: netronome/nic_AMDA0099-0001_1x10_1x25.nffw -> nic/nic_AMDA0099-0001_1x10_1x25.nffw
Link: netronome/nic_AMDA0099-0001_2x25.nffw -> nic/nic_AMDA0099-0001_2x25.nffw
Link: netronome/nic_AMDA0096-0001_2x10.nffw -> nic/nic_AMDA0096-0001_2x10.nffw
Link: netronome/nic_AMDA0097-0001_8x10.nffw -> nic/nic_AMDA0097-0001_8x10.nffw
Link: netronome/nic_AMDA0058-0011_2x40.nffw -> nic/nic_AMDA0058-0011_2x40.nffw
Link: netronome/nic_AMDA0058-0012_2x40.nffw -> nic/nic_AMDA0058-0012_2x40.nffw
Link: netronome/nic_AMDA0078-0011_1x100.nffw -> nic/nic_AMDA0078-0011_1x100.nffw
File: netronome/nic/nic_AMDA0081-0001_1x40.nffw
File: netronome/nic/nic_AMDA0097-0001_2x40.nffw
File: netronome/nic/nic_AMDA0099-0001_2x10.nffw
File: netronome/nic/nic_AMDA0081-0001_4x10.nffw
File: netronome/nic/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/nic/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/nic/nic_AMDA0099-0001_2x25.nffw
File: netronome/nic/nic_AMDA0096-0001_2x10.nffw
File: netronome/nic/nic_AMDA0097-0001_8x10.nffw
File: netronome/nic/nic_AMDA0058-0011_2x40.nffw
File: netronome/nic/nic_AMDA0058-0012_2x40.nffw
File: netronome/nic/nic_AMDA0078-0011_1x100.nffw

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File: netronome/nic-sriov/nic_AMDA0081-0001_1x40.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_2x10.nffw
File: netronome/nic-sriov/nic_AMDA0081-0001_4x10.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/nic-sriov/nic_AMDA0099-0001_2x25.nffw
File: netronome/nic-sriov/nic_AMDA0096-0001_2x10.nffw
File: netronome/nic-sriov/nic_AMDA0097-0001_8x10.nffw
File: netronome/nic-sriov/nic_AMDA0058-0011_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0058-0012_2x40.nffw
File: netronome/nic-sriov/nic_AMDA0078-0011_1x100.nffw

Version: v2.1.16.1

File: netronome/flower/nic_AMDA0099.nffw
File: netronome/flower/nic_AMDA0096.nffw
File: netronome/flower/nic_AMDA0097.nffw
File: netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0081.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0081-0001_1x40.nffw -> netronome/flower/nic_AMDA0081.nffw
Link: netronome/flower/nic_AMDA0097-0001_2x40.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_2x10.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0081-0001_4x10.nffw -> netronome/flower/nic_AMDA0081.nffw
Link: netronome/flower/nic_AMDA0097-0001_4x10_1x40.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_2x25.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0096-0001_2x10.nffw -> netronome/flower/nic_AMDA0096.nffw
Link: netronome/flower/nic_AMDA0097-0001_8x10.nffw -> netronome/flower/nic_AMDA0097.nffw
Link: netronome/flower/nic_AMDA0099-0001_1x10_1x25.nffw -> netronome/flower/nic_AMDA0099.nffw
Link: netronome/flower/nic_AMDA0058-0011_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0011_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0058-0012_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0011_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_1x100.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_2x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_4x10_1x40.nffw -> netronome/flower/nic_AMDA0058.nffw
Link: netronome/flower/nic_AMDA0078-0012_8x10.nffw -> netronome/flower/nic_AMDA0058.nffw

Version: AOTC-2.10.A.38

File: netronome/bpf/nic_AMDA0081-0001_1x40.nffw
File: netronome/bpf/nic_AMDA0097-0001_2x40.nffw
File: netronome/bpf/nic_AMDA0099-0001_2x10.nffw
File: netronome/bpf/nic_AMDA0081-0001_4x10.nffw
File: netronome/bpf/nic_AMDA0097-0001_4x10_1x40.nffw
File: netronome/bpf/nic_AMDA0099-0001_1x10_1x25.nffw
File: netronome/bpf/nic_AMDA0099-0001_2x25.nffw

File: netronome/bpf/nic_AMDA0096-0001_2x10.nffw
File: netronome/bpf/nic_AMDA0097-0001_8x10.nffw
File: netronome/bpf/nic_AMDA0058-0011_2x40.nffw
File: netronome/bpf/nic_AMDA0058-0012_2x40.nffw
File: netronome/bpf/nic_AMDA0078-0011_1x100.nffw

Version: v2.0.6.124

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Driver: wil6210 - Qualcomm Atheros support for 11ad family of chips

File: wil6210.fw
File: wil6210.brd
Version: 5.2.0.18

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Driver: venus - Qualcomm Venus video codec accelerator

File: qcom/venus-1.8/venus.mdt
File: qcom/venus-1.8/venus.b00
File: qcom/venus-1.8/venus.b01
File: qcom/venus-1.8/venus.b02
File: qcom/venus-1.8/venus.b03
File: qcom/venus-1.8/venus.b04

Version: 1.8-00109

File: qcom/venus-4.2/venus.mdt
File: qcom/venus-4.2/venus.b00
File: qcom/venus-4.2/venus.b01
File: qcom/venus-4.2/venus.b02
File: qcom/venus-4.2/venus.b03
File: qcom/venus-4.2/venus.b04

Version: 4.2

File: qcom/venus-5.2/venus.mdt
File: qcom/venus-5.2/venus.b00
File: qcom/venus-5.2/venus.b01
File: qcom/venus-5.2/venus.b02
File: qcom/venus-5.2/venus.b03
File: qcom/venus-5.2/venus.b04
File: qcom/venus-5.2/venus.mbn

Version: 5.2-00023

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<https://developer.qualcomm.com/hardware/dragonboard-410c/tools>

Driver: imx-sdma - support for i.MX SDMA driver

File: imx/sdma/sdma-imx6q.bin
Version: 3.3
File: imx/sdma/sdma-imx7d.bin
Version: 4.2

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Driver: adreno - Qualcomm Adreno GPU firmware

File: qcom/a300_pfp.fw
Link: a300_pfp.fw -> qcom/a300_pfp.fw
File: qcom/a300_pm4.fw
Link: a300_pm4.fw -> qcom/a300_pm4.fw
File: qcom/a530_pfp.fw
File: qcom/a530_pm4.fw
File: qcom/a530v3_gpmu.fw2
File: qcom/a530_zap.b00
File: qcom/a530_zap.b01
File: qcom/a530_zap.b02
File: qcom/a530_zap.mdt

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Binary files supplied originally from
<https://developer.qualcomm.com/hardware/dragonboard-410c/tools>

Driver: mlxsw_spectrum - Mellanox Spectrum switch

File: mellanox/mlxsw_spectrum-13.1420.122.mfa2
File: mellanox/mlxsw_spectrum-13.1530.152.mfa2
File: mellanox/mlxsw_spectrum-13.1620.192.mfa2
File: mellanox/mlxsw_spectrum-13.1702.6.mfa2
File: mellanox/mlxsw_spectrum-13.1703.4.mfa2
File: mellanox/mlxsw_spectrum-13.1910.622.mfa2
File: mellanox/mlxsw_spectrum-13.2000.1122.mfa2

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Driver: cdns-mhdp - Cadence MHDP DP bridge

File: cadence/mhdp8546.bin
Version: 1.2.15

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Driver: fsl-mc bus - NXP Management Complex Bus Driver

File: dpaa2/mc/mc_10.10.0_is1088a.itb
File: dpaa2/mc/mc_10.10.0_is2088a.itb
File: dpaa2/mc/mc_10.10.0_lx2160a.itb
File: dpaa2/mc/mc_10.14.3_is1088a.itb
File: dpaa2/mc/mc_10.14.3_is2088a.itb
File: dpaa2/mc/mc_10.14.3_lx2160a.itb
File: dpaa2/mc/mc_10.16.2_is1088a.itb
File: dpaa2/mc/mc_10.16.2_is2088a.itb
File: dpaa2/mc/mc_10.16.2_lx2160a.itb

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Driver: msc-phy - Microchip PHY drivers

File: microchip/mscc_vsc8574_revb_int8051_29e8.bin
File: microchip/mscc_vsc8584_revb_int8051_fb48.bin

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Driver: meson-vdec - Amlogic video decoder

File: meson/vdec/g12a_h264.bin
File: meson/vdec/g12a_vp9.bin
File: meson/vdec/gxbb_h264.bin
File: meson/vdec/gxl_h263.bin
File: meson/vdec/gxl_h264.bin
File: meson/vdec/gxl_hevc.bin
File: meson/vdec/gxl_hevc_mmu.bin
File: meson/vdec/gxl_mjpeg.bin
File: meson/vdec/gxl_mpeg12.bin
File: meson/vdec/gxl_mpeg4_5.bin
File: meson/vdec/gxm_h264.bin

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This quote is just too good to not pass on:

""BTW, I would have rejected the name Story Server because its initials are SS, the name of the secret police in Nazi Germany, probably the most despised pair of letters in western culture."" --- <http://scriptingnewsarchive.userland.com/1999/12/13>

Let no one say political correctness isn't dead....

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stdio.c
by Mark Gates <mgates@nlanr.net>
and Ajay Tirumalla <tirumala@ncsa.uiuc.edu>

input and output numbers, converting with kilo, mega, giga

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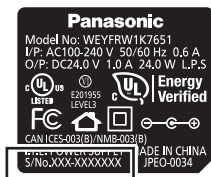
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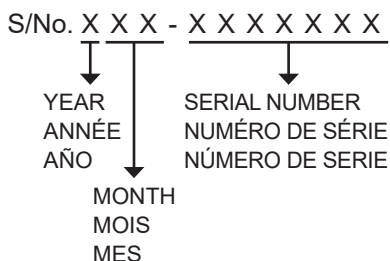
Explanation of AC adapter manufacturing date
Explication de la date de fabrication de l'adaptateur CA
Explicación de la fecha de fabricación del adaptador de CA



About S/No. From the year of 2010, notation of year will be as below;
À propos du numéro de série. À partir de 2010, l'indication de l'année se fera comme ci-dessous :
Acerca del N/S. Desde el año 2010, la notación del año será la siguiente;
ex: /ex. : /ej.:

2022/11	N11-XXXXXXX
2023/06	P06-XXXXXXX
2024/01	Q01-XXXXXXX
2025/01	R01-XXXXXXX
2026/01	S01-XXXXXXX

(A, B, C-Z) the letters of "I" and "O" will not be used.
(In order not to make confusion of 1 and 0.)
(A, B, C-Z) les lettres « I » et « O » ne seront pas
utilisées.
(Afin de ne pas faire de confusion avec 1 et 0.)
No se utilizarán las letras (A, B, C-Z) "I" y "O".
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